EXTRACTING COST RERCURRENCES FROM SEQUENTIAL AND PARALLEL FUNCTIONAL PROGRAMS

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Abstract

Contents

Chapter 1.	Introduction	1
1. Com	nplexity Analysis	1
2. Prev	2. Previous Work	
3. Contribution		4
Chapter 2.	Higher Order Complexity Analysis	6
1. Source Language		6
2. Com	nplexity Language	7
Chapter 3.	Fast Reverse	12
1. Tran	nslation	13
2. Synt	tactic Sugar Translation	19
3. Inte	rpretation	23
Chapter 4.	Reverse	32
1. Tran	nslation	32
2. Inte	rpretation	33
Chapter 5.	Parametric Insertion Sort	35
Chapter 6.	Insertion Sort	55
Chapter 7.	Work and Span	75
1. Work and span		75
2. Bounding Relation		77
3. Para	allel List Map	77
4. Para	allel Tree Map	82
DRAFT: Apri	1 7. 2016 iii	

Chapter 8. Mutual Recurrence	86
1. Motivation	86
2. Pure Potential Translation	87
3. Logical Relation	87
4. Proof	88
Bibliography	95

CHAPTER 1

Introduction

1. Complexity Analysis

The efficiency of programs is categorized by how the resource usage of a program increases with the input size in the limit. This is often called the asymptotic efficiency or complexity of a program. Asymptotic efficiency abstracts away the details of efficiency, allowing programs to be compared without knowledge of specific hardware architecture or the size and shape of the programs input (Cormen et al. [2001]). However, traditional complexity analysis is first-order; the asymptotic efficiency of a program is only expressed in terms of its input. For example, traditional analysis of the function map: (a -> b) -> [b] -> [a], which applies a function to every element in a list, assumes the cost of applying its first argument is constant. map is implemented below in OCaml.

```
let rec map f xs =
  match xs with
  | [] -> []
  | (x::xs') -> f x :: map f xs'
```

Traditional complexity analysis proceeds as follows. First we write a recurrence for the cost.

$$T(n) = c + T(n-1)$$

Then we solve this recurrence using the substitution method in Cormen et al. [2001]. We guess the solution is T(n) = cn. We check it by proving T(n) = cn by induction on n.

$$T(n) = c + T(n - 1)$$

$$= c + c(n - 1)$$

$$= c + cn - c$$

$$= cn$$

The result is the asymptotic efficiency of map is linear in the length of the list.

If the cost function is has a constant cost, such as fixed width integer addition, then this first-order analysis is sufficient. The cost of mapping a constant cost function over a list will increase linearly in the size of the list. However, first-order complexity analysis will not accurately describe the cost of mapping a nontrivial function over a list. Consider insertion sort, which is quadratic in the size of its argument. The cost of mapping this function over a list of lists depends not only on the length of the list, but also on the length of the sublists. A more accurate prediction of the cost of this function can be obtained by taking into account the cost of insertion sort.

For an example such map, it is simple enough to change our analysis to reflect that applying the functions f and :: does not have constant cost c, but instead has cost $c_f + c_{::}$. Using the same substitution method as before, our guess becomes $T(n) = (c_f + c_{::})n$. We prove our guess by induction on n.

$$T(n) = c_f + c_{::} + T(n-1)$$

$$= c_f + c_{::} + (c_f + c_{::})(n-1)$$

$$= c_f + c_{::} + (c_f + c_{::})n - c_f - c_{::}$$

$$= (c_f + c_{::})n$$

Our analysis of the cost of map is now parameterized by the cost f and ::.

Although this is sufficient for a function such as map, where the cost at each recursive call of map does not depend on the result of the recursive call on the tail of the argument since, in OCaml, :: is a constant time operation. If the cost of :: was not constant, DRAFT: April 7, 2016

then our analysis would break down because we would need to know the size of the result of the recursive call in order to know the cost of ::.

To address this, we can consider the complexity of an expression to be a pair of a cost and a potential. This is the approach taken by Danner and Royer [2007]. The cost of an expression an upper bound on the time required to evaluate an expression. The cost can be a natural number or, for parallel analysis, a cost graph representing the dependencies between sub-computations. The potential is a measure of the cost of future use of the expression.

2. Previous Work

Danner and Royer [2007], building on the work of others, introduced the idea that the complexity of an expression consists of a cost, representing an upper bound on the time it takes to evaluate the expression, and a potential, representing the cost of future uses of the expression. The notion of a potential is key because it allows the analysis of higher-order expressions. The complexity of a higher-order function such as map depends on the potential of its argument function. They developed a type system for ATR, a call-by-value version of System T, that consists of a part restricting the sizes of values of expressions and a part restricting the cost of evaluating a expression. Programs written in ATR are constrained by the type system as to run in less than type-2 polynomial time. Danner and Royer [2009] extended this work to express more forms of recursion, in particular those required by insertion sort and selection sort.

Danner et al. [2013] utilized the notion of thinking of the complexity of an expression as a pair of a cost and a potential to statically analyze the complexity of a higher-order functional language with structural list recursion. The expressions in the higher-order functional language with structural list recursion, referred to as the source language, are mapped to expressions in a complexity language by a translation function. The translated expression describes an upper bound on the complexity of the original programs.

DRAFT: April 7, 2016

Danner et al. [2015] built on this work to formalize the extraction of recurrences from a higher-order functional language with structural recursion on arbitrary inductive data types. Programs are written in the functional language, referred to as the source language. The programs are translated into a complexity language, which represents a bound on the complexity of the source program. A bounding relation is used to prove the translation and denotational semantics of the complexity language give an upper bound on the operational cost of running the source program. The paper also presents a syntactic bounding theorem, where the abstraction of values to sizes done in the semantics is instead done syntactically. Arbitrary inductive data types are handled semantically using programmer specified sizes of data types. Sizes must be programmer specified because the structure of a data type does not always determine the interpretation of the size of a data type. There also exist different reasonable interpretations of size, and some may be preferable to others depending on what is being analyzed.

3. Contribution

This thesis comes in three parts.

The first part contains a catalog of examples of the extraction of recurrences from functional programs using the approach given by Danner et al. [2015]. These examples illustrate how to apply the method to nontrivial examples. They also serve to demonstrate common techniques for solving the extracted recurrences. The examples also allow the comparison with other automated complexity methods such as those given by Avanzini et al. [2015] and Hoffmann and Hofmann [2010], highlighting their respective strengths and weaknesses. The examples include reversing a list in quadratic, reversing a list in linear time, insertion sort, parametric insertion sort, list map, and tree map.

The second part extends the analysis to parallel programs. We change costs from from natural numbers to the cost graphs described in Harper [2012]. A cost graph represents the dependencies between subcomputations in a program. The nodes of the graph are subcomputations of the program and an edge between two nodes indicates the result of one computation is an input to the other. The cost graph can be used to DRAFT: April 7, 2016

determine an optimal strategy for scheduling the computation on multiple processors. The cost graph has two properties that we are interested in, work and span. The work is the total steps required to run the program, which corresponds to the steps a single processor must execute to run the program. The span is the critical path; the longest number of steps from the start to the end of the cost graph.

The third part demonstrates the recurrence for the potential does not depend on the recurrence for the cost. Consequently, we can extract the recurrence for the potential and analyze it independently. This is useful because it is often easier to solve the cost and potential recurrences independently than it is to solve the initial recurrence. We are also sometimes only interested in just the potential or just the cost of a recurrence.

CHAPTER 2

Higher Order Complexity Analysis

Programs are written in the source language. Then the program is translated to a complexity language. The semantic interpretation of the complexity language program may be used to analyse the complexity of the original program.

1. Source Language

The source language is the simply typed lambda calculus with Unit, products, suspensions, user-defined inductive datatypes and a recursion construct. Valid signatures, types, and constructor arguments are given in figure 1. The types, expressions, and typing judgments of the source language are given in figure 1. Evaluation is call-by-value and the rules for evaluation are given in figure 1.

unit is a singleton type with only one inhabitant, the value $\langle \rangle$, also called unit.

Product types are a compound types consisting of an ordered pair of types. Products are introduced using $\langle e_0, e_1 \rangle$ Since evaluation is call-by-value, products are strict. So both expressions of in product must be evaluated before the product may be destructured. Products are eliminated using split.

A suspension is an unevaluated computation. A suspension has type $\sup \tau$ where τ is the type of the suspended computation. Suspensions are introduced using the $\mathtt{delay}(e)$ operator. Suspensions are eliminated using the $\mathtt{force}(e)$ operator, which evaluates the suspended computation.

A program using data types must have a top-level signature ψ consisting of data type declarations of the form

$$\mathtt{datatype} \delta = C_0^\delta \mathtt{of} \phi_{C_0}[\delta] \mid \ldots \mid C_{n-1}^\delta \mathtt{of} \phi_{C_{n-1}}[\delta]$$

Each datatype may only refer to datatypes declared earlier in the signature. This prevents general recursive datatypes. The argument to each constructor is given by a strictly positive functor ϕ , which is one of t, τ , $\phi_0 \times \phi_1$, and $\tau \to \phi$. The identity functor t represents recursive occurrence of the datatype. The constant functor τ represents a non-recursive type. The product functor $\phi_0 \times \phi_1$ represents a pair of arguments. The constant exponential $\tau \to \phi$ represents a function type. The introduction forms for datatypes are the constructors. The elimination form for a datatype is the rec construct.

The rec construct allows for structural recursion. rec is given an argument to recurse on and a sequence of statements corresponding to each constructor for the datatype of the first argument. The first argument to rec is evaluated to a value, and then depending on the outermost constructor of the value, rec evaluates to the appropriate branch.

map is used to lift functions from $\sigma \to \tau$ to $\phi[\sigma] \to \phi[\tau]$. map is restricted to syntactic values and is used in the operational semantics to insert recursive calls in their places. For example, if recursing on a value that does not contain a recursive occurrence of a datatype, such as a boolean or a tree leaf, then map does not insert a recursive call anywhere.

2. Complexity Language

The types, expressions, and typing judgments of the complexity language are given in figure 2. The complexity language is similar to the source language with a few exceptions.

Suspensions are no longer present.

Tuples are destructured using projections instead of split.

The translation from the source language to the complexity language is given in figure 2.

FIGURE 1. Source language syntax and types

Types

$$\tau ::= \text{unit} \mid \tau \times \tau \mid \tau \to \tau \mid \text{susp } \tau \mid \delta$$

$$\phi ::= t \mid \tau \mid \phi \times \phi \mid \tau \to \phi$$

datatype $\delta = C_0^\delta {\rm of} \phi_{C_0}[\delta] \mid \ldots \mid C_{n-1}^\delta {\rm of} \phi_{C_{n-1}}[\delta]$

Expressions

$$\begin{split} v &::= x \mid \langle \rangle \mid \langle v, v \rangle \mid \lambda x.e \mid \mathtt{delay}(e) \mid C \ v \\ e &::= x \mid \langle \rangle \mid \langle e, e \rangle \mid \mathtt{split}(e, x.x.e) \mid \lambda x.e \mid e \ e \\ & \mid \mathtt{delay}(e) \mid \mathtt{force}(e) \mid C^{\delta} \ e \mid \mathtt{rec}^{\delta}(e, \overline{C \mapsto x.e_C}) \\ & \mid \mathtt{map}^{\phi}(x.v, v) \mid \mathtt{let}(e, x.e) \end{split}$$

$$n ::= 0 \mid 1 \mid n + n$$

Typing Judgments

FIGURE 2. Source language valid signatures, types, and constructor arguments

$$\begin{array}{c} \text{Signatures: } \psi \text{ sig} \\ \hline \hline \langle \rangle \text{ sig} & \frac{\delta \notin \forall \text{C}(\psi \vdash \phi_C \text{ok})}{\psi, \text{ datatype } \delta = \overline{C} \text{ of } \phi_C[\delta] \text{ sig}} \\ \hline \\ & \text{Types: } \psi \vdash \tau \text{ type} \\ \hline \hline \psi \vdash \text{unit type} & \frac{\psi \vdash \tau_0 \text{ type } \psi \vdash \tau_1 \text{ type}}{\psi \vdash \tau_0 \times \tau_1 \text{ type}} \\ \hline \hline \psi \vdash \tau_0 \text{ type } \psi \vdash \tau_1 \text{ type} & \frac{\psi \vdash \tau \text{ type}}{\psi \vdash \text{susp } \tau \text{ type}} & \frac{\delta \in \psi}{\psi \vdash \delta \text{ type}} \\ \hline \hline & \text{Constructor arguments: } \psi \vdash \phi \text{ ok} \\ \hline \hline \hline \psi \vdash t \text{ ok} & \frac{\psi \vdash \tau \text{ type}}{\psi \vdash \tau \text{ ok}} \\ \hline \end{array}$$

FIGURE 3. Source language operational semantics

 $\frac{\psi \vdash \phi_0 \text{ ok} \qquad \psi \vdash \phi_1 \text{ ok}}{\psi \vdash \phi_0 \times \phi_1 \text{ ok}} \qquad \frac{\psi \vdash \tau \text{ type} \qquad \psi \vdash \phi \text{ ok}}{\psi \vdash \tau \to \phi \text{ ok}}$

$$\frac{e_0 \downarrow^{n_0} v_0}{\langle e_0, e_1 \rangle} \downarrow^{n_1} v_1}{\langle e_0, e_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\operatorname{split}(e_0, x_0.x_1.e_1)} \downarrow^{n_1} v}{\operatorname{split}(e_0, x_0.x_1.e_1)} \downarrow^{n_0+n_1} v}$$

$$\frac{e_0 \downarrow^{n_0} \lambda x.e_0'}{e_0 e_1 \downarrow^{1+n_0+n_1+n} v} \frac{e_1 \langle v_1/x \rangle \downarrow^n v}{\operatorname{delay}(e) \downarrow^0 \operatorname{delay}(e)}$$

$$\frac{e \downarrow^{n_0} \operatorname{delay}(e_0)}{\operatorname{force}(e) \downarrow^{n_0+n_1} v} \frac{e \downarrow^n v}{\operatorname{Ce} \downarrow^n \operatorname{C} v}$$

$$\frac{e \downarrow^{n_0} \operatorname{C} v_0}{\operatorname{map}^{\phi_C}(y.\langle y, \operatorname{delay}(\operatorname{rec}(y, \overline{C} \mapsto x.e_C))\rangle, v_0) \downarrow^{n_1} v_1} e_C[v_1/x] \downarrow^{n_2} v}{\operatorname{rec}(e, \overline{C} \mapsto x.e_C)} \downarrow^{1+n_0+n_1+n_2} v}$$

$$\frac{\operatorname{map}^t(x.v, v_0) \downarrow^0 v[v_0/x]}{\operatorname{map}^{\phi_0}(x.v, v_0) \downarrow^{n_0} v_0'} \frac{\operatorname{map}^{\phi_1}(x.v, v_1) \downarrow^{n_1} v_1'}{\operatorname{map}^{\phi_0} \langle x.v, v_0 \rangle \downarrow^{n_0} v_0'} e_1[v_0/x] \downarrow^{n_0+n_1} \langle v_0', v_1' \rangle}{\operatorname{map}^{\phi_0} \langle x.v, \lambda y.e \rangle \downarrow^0 \lambda y.\operatorname{let}(e, z.\operatorname{map}^\phi(x.v, z))} \frac{e_0 \downarrow^{n_0} v_0}{\operatorname{let}(e_0, x.e_1) \downarrow^{n_0+n_1} v}$$

DRAFT: April 7, 2016

FIGURE 4. Complexity language types, expressions, and typing judgments

$$\begin{split} T ::= \mathbf{C} \mid \mathtt{unit} \mid \Delta \mid T \times T \mid T \to T \\ \Phi ::= t \mid T \mid \Phi \times \Phi \mid T \to \Phi \\ \mathbf{C} ::= 0 \mid 1 \mid 2 \mid \dots \end{split}$$

$$\mathtt{datatype}\Delta = C_0^\Delta \mathtt{of} \Phi_{C_0}[\Delta] \ | \ \dots \ | \ C_{n-1}^\Delta \mathtt{of} \Phi_{C_{n-1}}[\Delta]$$

Expressions

$$E ::= x|0|1|E + E|\langle\rangle|\langle E, E\rangle|$$

$$\pi_0 E|\pi_1 E|\lambda x. E|E \ E|C^{\delta} \ E|\operatorname{rec}^{\Delta}(E, \overline{C \mapsto x. E_C})$$

Typing Judgments

Figure 5. Translation from source language to complexity language

$$\begin{split} \|\tau\| &= \mathbf{C} \times \langle\!\langle \tau \rangle\!\rangle \\ &\langle\!\langle \mathtt{unit} \rangle\!\rangle = \mathtt{unit} \\ &\langle\!\langle \sigma \times \tau \rangle\!\rangle = \langle\!\langle \sigma \rangle\!\rangle \times \langle\!\langle \tau \rangle\!\rangle \\ &\langle\!\langle \sigma \to \tau \rangle\!\rangle = \langle\!\langle \sigma \rangle\!\rangle \to \|\tau\| \\ &\langle\!\langle \mathtt{susp} \; \tau \rangle\!\rangle = \|\tau\| \\ &\langle\!\langle \delta \rangle\!\rangle = \delta \end{split}$$

$$\|\phi\| = \mathbf{C} \times \langle\langle \phi \rangle\rangle$$

$$\langle\langle t \rangle\rangle = t$$

$$\langle\langle \tau \rangle\rangle = \langle\langle \tau \rangle\rangle$$

$$\langle\langle \phi_0 \times \phi_1 \rangle\rangle = \langle\langle \phi_0 \rangle\rangle \times \langle\langle phi_1 \rangle\rangle$$

$$\langle\langle \tau \to \phi \rangle\rangle = \langle\langle \phi \rangle\rangle \to \|\phi\|$$

$$\langle\!\langle \psi \rangle\!\rangle = \text{ for each } \delta \in \psi, \delta = C_0^\delta \text{ of } \langle\!\langle \phi_{C_0} \rangle\!\rangle [\delta], ..., C_{n-1}^\delta \text{ of } \langle\!\langle \phi_{n-1} \rangle\!\rangle [\delta]$$

$$\begin{split} \|x\| &= \langle 0, x \rangle \\ \|\langle \rangle\| &= \langle 0, \langle \rangle \rangle \\ \|\langle e_0, e_1 \rangle\| &= \langle \|e_0\|_c + \|e_1\|_c, \langle \|e_0\|_p, \|e_1\|_p \rangle \rangle \\ \|\text{split}(e_0, x_0.x_1.e_1)\| &= \|e_0\|_c +_c \|e_1\| [\pi_0\|e_0\|_p/x_0, \pi_1\|e_0\|_p/x_1] \\ \|\lambda x.e\| &= \langle 0, \lambda x.\|e\| \rangle \\ \|e_0 \ e_1\| &= (1 + \|e_0\|_c + \|e_1\|_c) +_c \|e_0\|_p \|e_1\|_p \\ \|\text{delay}(e)\| &= \langle 0, \|e\| \rangle \\ \\ \text{DRAFT: April 7, 2016} \qquad \|\text{force}(e)\| &= \|e\|_c +_c \|e\|_p \\ \|C_i^\delta \ e\| &= \langle \|e\|_c, C_i^\delta \|e\|_p \rangle \\ \|\text{rec}^\delta(e, \overline{C \mapsto x.e_C})\| &= \|e\|_c +_c \operatorname{rec}^\delta(\|e\|_p, \overline{C \mapsto x.1 +_c \|e_C\|}) \end{split}$$

 $\|\text{map}^{\phi}(x.v_0, v_1)\| = \langle 0, \text{map}^{\langle\langle\phi\rangle\rangle}(x.\|v_0\|_p, \|v_1\|_p) \rangle$

CHAPTER 3

Fast Reverse

Fast reverse is an implementation reverse in linear time complexity. A naive implementation of reverse appends the head of the list to recursively reversed tail of the list. Fast reverse instead uses an abstraction to delay the consing. As this is the first example, we will walk through the translation and interpretation in gory detail. In following examples we will relegate the walk-through of the translation to the appendices, where the reader can peruse them, perhaps over a glass of carbenet sauvignon, as a relaxing end to a stressful day.

The definition of the list datatype holds no suprises.

$$datatype list = Nil of unit | Cons of int \times list$$

The implementation of fast reverse is not obvious. We write a function rev that applies an auxiliary function to an empty list to produce the result. The specification of reverse is rev $[x_0,\ldots,x_{n-1}]=[x_{n-1},\ldots,x_0]$. The specification of the auxiliary function $\operatorname{rec}(xs,\ldots)$ is $\operatorname{rec}([x_0,\ldots,x_{n-1}],\ldots)$ $[y_0,\ldots,y_{m-1}]=[x_{n-1},\ldots,x_0,y_0,\ldots,y_{m-1}]$. rev $xs=\lambda xs.\operatorname{rec}(xs,$ $\operatorname{Nil} \mapsto \lambda a.a,$ $\operatorname{Cons} \mapsto b.\operatorname{split}(b,x.c.\operatorname{split}(c,xs'.r.$

Notice that the implementation of rev would be much cleaner if we where able to pattern match on cases of the rec. Below is rev written with this syntactic sugar.

 λ a.force(r) Cons \langle x,a \rangle))) Nil

rev =
$$\lambda$$
xs.rec(xs, Nil $\mapsto \lambda$ a.a, Cons $\mapsto \langle y \langle ys,r \rangle \rangle . \lambda b.force(r)$ Cons $\langle x,b \rangle$) Nil DRAFT: April 7, 2016

Each recursive call creates an abstraction that applies the recursive call on the tail of the list to the list created by consing the head of the list onto the abstraction argument. The recursive calls builds nested abstractions as deep as the length of the list which is collapsed by application of the outermost abastraction to Nil. Below we show the evaluation of rev applied to a small list of just two elements.

```
rev (\operatorname{Cons}\langle 0, \operatorname{Cons}\langle 1, \operatorname{Nil}\rangle\rangle) \rightarrow
\operatorname{rec}(\operatorname{Cons}\langle 0, \operatorname{Cons}\langle 1, \operatorname{Nil}\rangle\rangle,
\operatorname{Nil} \mapsto \lambda a.a
\operatorname{Cons}\mapsto b.\operatorname{split}(b, x.c.\operatorname{split}(c, xs'.r.
\lambda a.\operatorname{force}(r) \operatorname{Cons}\langle x, a\rangle))) \operatorname{Nil}
\rightarrow^* (\lambda a 0.(\lambda a 1.(\lambda a 2.a 2) \operatorname{Cons}\langle 1, a 1\rangle) \operatorname{Cons}\langle 0, a 0\rangle) \operatorname{Nil}
\rightarrow_{\beta} (\lambda a 1.(\lambda a 2.a 2) \operatorname{Cons}\langle 1, a 1\rangle) \operatorname{Cons}\langle 0, \operatorname{Nil}\rangle
\rightarrow_{\beta} (\lambda a 2.a 2) \operatorname{Cons}\langle 1, \operatorname{Cons}\langle 0, \operatorname{Nil}\rangle\rangle
\rightarrow_{\beta} \operatorname{Cons}\langle 1, \operatorname{Cons}\langle 0, \operatorname{Nil}\rangle\rangle
```

1. Translation

We will walk through the translation from the source language to the complexity language.

```
\| \mathtt{rev} \| = \| \lambda x s. \mathtt{rec}(xs, \mathtt{Nil} \mapsto \lambda \mathtt{a.a.}, \mathtt{Cons} \mapsto b. \mathtt{split}(b, x.c. \mathtt{split}(c, xs'.r. \lambda a. \mathtt{force}(r) \ \mathtt{Cons}\langle \mathtt{x.a} \rangle))) \ \mathtt{Nil} \|
```

First we apply the rule for translating an abstraction. The rule is $\|\lambda x.e\| = \langle 0, \lambda x. \|e\| \rangle$.

$$\|\mathtt{rev}\| = \|\lambda x s.\mathtt{rec}(xs,\mathtt{Nil} \mapsto \lambda a.a,$$

$$\mathtt{Cons} \mapsto b.\mathtt{split}(b,x.c.\mathtt{split}(c,xs'.r.\lambda a.\mathtt{force}(r)\mathtt{Cons}\langle x,a\rangle))) \ \mathtt{Nil}\|$$

$$= \langle 0,\lambda x s.\|\mathtt{rec}(xs,\mathtt{Nil} \mapsto \lambda a.a,$$

$$\mathtt{Cons} \mapsto b.\mathtt{split}(b,x.c.\mathtt{split}(c,xs'.r.\lambda a.\mathtt{force}(r)\mathtt{Cons}\langle x,a\rangle))) \ \mathtt{Nil}\|\rangle$$

The next translation is an application. The rule for translating an application is $\|e_0 e_1\| = (1 + \|e_0\|_c + \|e_1\|_c) +_c (\|e_0\|_p \|e_1\|_p)$. In this case, $\operatorname{rec}(\ldots)$ is e_0 and Nil is e_1 . We translate Nil then $\operatorname{rec}(\ldots)$ seperately. The translation of a constructor applied to an expression is a tuple of the cost of the translated expression and the corresponding complexity language constructor applied to the potential of the translated expression. Since the expression inside Nil is $\langle \rangle$, and $\|\langle \rangle\| = \langle 0, \langle \rangle \rangle$, we have

$$\begin{split} |\mathrm{Nil}|| &= \langle \langle 0, \langle \rangle \rangle_c, \mathrm{Nil} \langle 0, \langle \rangle \rangle_p \rangle \\ &= \langle 0, \mathrm{Nil} \langle \rangle \rangle \end{split}$$

The rule for translating a rec expression is

$$\|\operatorname{rec}(e, \overline{C \mapsto x.e_C})\| = \|e\|_c +_c \operatorname{rec}(\|e\|_p, \overline{C \mapsto x.\|e_C\|})$$

 $\|\mathtt{rec}(xs,\mathtt{Nil}\mapsto\lambda a.a,$

$$\mathtt{Cons} \mapsto b.\mathtt{split}(b, x.c.\mathtt{split}(c, xs'.r.\lambda a.\mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle))) \|$$

$$= \|xs\|_c +_c \operatorname{rec}(\|xs\|_p, \operatorname{Nil} \mapsto 1 +_c \|\lambda a.a\|$$

$$\mathtt{Cons} \mapsto b.1 +_c \|\mathtt{split}(b, x.c.\mathtt{split}(c, xs'.r.\lambda a.\mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle))\|)$$

$$= \langle 0, xs \rangle_c +_c \operatorname{rec}(\langle 0, xs \rangle_p, \operatorname{Nil} \mapsto 1 +_c \|\lambda a.a\|$$

$$\mathtt{Cons} \mapsto b.1 +_c \|\mathtt{split}(b, x.c.\mathtt{split}(c, xs'.r.\lambda a.\mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle))\|)$$

The term xs is a variable and the rule for translating variables is $||xs|| = \langle 0, xs \rangle$.

$$= \operatorname{rec}(xs, \operatorname{Nil} \mapsto 1 +_c \|\lambda a.a\|$$

$$\mathtt{Cons} \mapsto b.1 +_c \|\mathtt{split}(b, x.c.\mathtt{split}(c, xs'.r.\lambda a.\mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle))\|)$$

DRAFT: April 7, 2016

The translation of the Nil branch is simple application of the $\|\lambda x.e\| = \langle 0, \lambda x.\|e\| \rangle$ and the variable translation rule.

$$\begin{aligned} 1 +_c \|\lambda a.a\| \\ &= 1 +_c \langle 0, \lambda a. \|a\| \rangle \\ &= \langle 1, \lambda a. \langle 0, a \rangle \rangle \end{aligned}$$

The translation of the Cons branch is a slightly more involved. The rule for translating split is

$$\|\mathtt{split}(e_0, x_0.x_1.e_1)\| = \|e_0\|_c +_c \|e_1\| [\pi_0\|e_0\|_p/x_0, \pi_1\|e_0\|_p/x_1]$$

After applying the rule to the Cons branch we get

$$\begin{split} &1 +_c \| \texttt{split}(b, x.c. \texttt{split}(c, xs'.r. \lambda a. \texttt{force}(r) \ \texttt{Cons}\langle x, a \rangle)) \| \\ &= 1 +_c \| b \|_c +_c \| \texttt{split}(c, xs'.r. \lambda a. \texttt{force}(r) \ \texttt{Cons}\langle x, a \rangle) \| [\pi_0 \| b \|_p / x, \pi_1 \| b \|_p / c] \end{split}$$

Remember that b is a variable and has type $\phi_{\texttt{Cons}}[\texttt{list} \times \texttt{susp} (\texttt{list} \to \texttt{list})]$. The translation of this type is $\mathbf{C} \times \langle\langle \phi_{\texttt{Cons}} \rangle\rangle[\texttt{list} \times \langle \texttt{list} \to \langle \mathbf{C} \times \texttt{list} \rangle\rangle]$. We can say that $\pi_0 \|\mathbf{b}\|_p$ is the head of the list \mathbf{xs} , $\pi_0 \pi_1 \|\mathbf{b}\|_p$ is the tail of the list \mathbf{xs} , and $\pi_1 \pi_1 \|\mathbf{b}\|_p$ is the DRAFT: April 7, 2016

result of the recursive call. The translation of b is (0, b).

$$1 +_c \|b\|_c +_c \|\mathrm{split}(c, xs'.r.\lambda a. \mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle) \|[\pi_0\|b\|_p/x, \pi_1\|b\|_p/c]$$

- $=1+_c\|\operatorname{split}(c,xs'.r.\lambda a.\operatorname{force}(r)\operatorname{Cons}\langle x,a\rangle)\|[\pi_0\|b\|_p/x,\pi_1\|b\|_p/c]$ We apply the rule for split again.
- $=1+_c(\|c\|_c+_c\|\lambda a.\mathtt{force}(r)\ \mathtt{Cons}\langle x,a\rangle\|[\pi_0\|c\|_p/xs',\pi_1\|c\|_p/r][\pi_0\|b\|_p/x,\pi_1\|b\|_p/c]$ c is a variable, so its translation is $\langle 0,c\rangle$.
- = 1 +_c $\|\lambda a. \mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle \| [\pi_0 \| c \|_p / x s', \pi_1 \| c \|_p / r] [\pi_0 \| b \|_p / x, \pi_1 \| b \|_p / c]$ We apply the rule for abstraction.
- $=1+_c\langle 0,\lambda a.\|\mathtt{force}(r)\ \mathtt{Cons}\langle x,a\rangle\|[\pi_0\|c\|_p/xs',\pi_1\|c\|_p/r][\pi_0\|b\|_p/x,\pi_1\|b\|_p/c]$ Recall $C+_cE$ is a macro for $\langle C+E_c,E_p\rangle$. We use this to eliminate the $+_c$. We also apply the translation rule for application.

$$= \langle 1, \lambda a. (1 + \| \mathtt{force}(r) \|_c + \| \mathtt{Cons} \langle x, a \rangle \|_c)$$

$$+_c \| \mathtt{force}(r) \|_p \| \mathtt{Cons} \langle x, a \rangle \|_p \rangle [\pi_0 \| c \|_p / xs', \pi_1 \| c \|_p / r] [\pi_0 \| b \|_p / x, \pi_1 \| b \|_p / c]$$

We will translate force(r) and Cons(x, a) individually.

First we compose the two substitutions.

let
$$\Theta = [\pi_0 ||c||_p / xs', \pi_1 ||c||_p / r] [\pi_0 ||b||_p / x, \pi_1 ||b||_p / c]$$

$$= [\pi_0 \pi_1 ||b||_p / xs', \pi_1 \pi_1 ||b||_p / r, \pi_0 ||b||_p / x]$$

Since b is a variable, the potential of its translation is b.

$$\Theta = [\pi_0 \pi_1 b / x s', \pi_1 \pi_1 b / r, \pi_0 b / x]$$

In translation of force(r) we apply the rule $\|force(e)\| = \|e\|_c +_c \|e\|_p$.

$$\|\operatorname{force}(r)\|\Theta = \|r\|_c \Theta +_c \|r\|_p \Theta$$

We apply the variable translation rule to r, then apply the substitution Θ .

$$= \langle 0, r \rangle_c \Theta +_c \langle 0, r \rangle_p \Theta$$
$$= r\Theta = \pi_1 \pi_1 b$$

Next we do the translation of Cons(x, a).

$$\|\operatorname{Cons}\langle x,a\rangle\| = \langle \|\langle x,a\rangle\|_c, \operatorname{Cons}\|\langle x,a\rangle\|_p \rangle$$

Notice the translation of $\langle x, a \rangle$ appears twice, so we will do this separately.

$$\|\langle x, a \rangle\| = \langle \|x\|_c + \|a\|_c, \langle \|x\|_p, \|a\|_p \rangle \Theta$$

Both x and a are variables, so they have 0 cost.

$$=\langle 0,\langle x,a\rangle\rangle\Theta$$

We apply the substitution Θ .

$$= \langle 0, \langle \pi_1 b, \pi_1 \pi_1 b \rangle \rangle$$

$$=\langle 0, \langle \pi_1 b, \pi_1 \pi_1 b \rangle \rangle$$

We complete the translation of $Cons\langle x, a \rangle$ using $\langle x, a \rangle$.

$$\|\operatorname{Cons}\langle x, a\rangle\| = \langle \|\langle x, a\rangle\|_c, \operatorname{Cons}\|\langle x, a\rangle\|_p \rangle$$
$$= \langle 0, \operatorname{Cons}\langle \pi_1 b, \pi_1 \pi_1 b\rangle \rangle$$

We use substitute in the translations of force(r) and Cons(x, a).

 $\|\mathbf{force}(r)\|$ has $\cot (\pi_1\pi_1b)_c$ and $\|\mathbf{Cons}\langle x,a\rangle\|$ has $\cot 0$.

$$\begin{split} &\langle 1, \lambda a. (1 + \| \mathtt{force}(r) \|_c + \| \mathtt{Cons}\langle x, a \rangle \|_c) +_c \| \mathtt{force}(r) \|_p \| \mathtt{Cons}\langle x, a \rangle \|_p \rangle \rangle \Theta \\ &= \langle 1, \lambda a. (1 + (\pi_1 \pi_1 b)_c) +_c (\pi_1 \pi_1 b)_p \, \mathtt{Cons}\langle \pi_1 b, a \rangle \rangle \end{split}$$

We can now complete the translation of the rec expression.

$$\begin{split} &\| \mathtt{rec}(xs,\mathtt{Nil} \mapsto \lambda a.a, \\ &\quad \mathtt{Cons} \mapsto b.\mathtt{split}(b,x.c.\mathtt{split}(c,xs'.r.\lambda a.\mathtt{force}(r)\ \mathtt{Cons}\langle x,a\rangle))) \| \\ &= \mathtt{rec}(xs,\mathtt{Nil} \mapsto 1 +_c \|\lambda a.a\| \\ &\quad \mathtt{Cons} \mapsto b.1 +_c \|\mathtt{split}(b,x.c.\mathtt{split}(c,xs'.r.\lambda a.\mathtt{force}(r)\ \mathtt{Cons}\langle x,a\rangle)) \|) \\ &= \mathtt{rec}(xs,\mathtt{Nil} \mapsto \langle 1,\lambda a.\langle 0,a\rangle\rangle \\ &\quad \mathtt{Cons} \mapsto b.\langle 1,\lambda a.(1 + (\pi_1\pi_1b)_c) +_c (\pi_1\pi_1b)_p\ \mathtt{Cons}\langle \pi_1b,a\rangle\rangle) \end{split}$$

We substitute the translation of rec and Nil into the translation of the application.

Let
$$R = \operatorname{rec}(xs,\operatorname{Nil} \mapsto \langle 1,\lambda a.\langle 0,a \rangle \rangle$$

$$\operatorname{Cons} \mapsto b.\langle 1,\lambda a.(1+(\pi_1\pi_1b)_c)+_c(\pi_1\pi_1b)_p \operatorname{Cons}\langle \pi_1b,a \rangle \rangle)$$
 $\|\operatorname{rec}(xs,\operatorname{Nil} \mapsto \lambda a.a,$

$$\operatorname{Cons} \mapsto b.\operatorname{split}(b,x.c.\operatorname{split}(c,xs'.r.\lambda a.\operatorname{force}(r)\operatorname{Cons}\langle x,a \rangle)))\operatorname{Nil}\|$$
Substituting R for the translation of rec and $\langle 0,\operatorname{Nil} \rangle$ for the translation of Nil .
$$=(1+R_c)+_cR_p\operatorname{Nil}\rangle$$

Recall
$$C+_cE=\langle C+E_c,E_p\rangle,$$
 so $(1+E_c)+_cE_p=1+_cE$
$$=1+_c\operatorname{rec}(xs,\operatorname{Nil}\mapsto\langle 1,\lambda a.\langle 0,a\rangle\rangle$$

$$\operatorname{Cons}\mapsto b.\langle 1,\lambda a.(1+(\pi_1\pi_1b)_c)+_c(\pi_1\pi_1b)_p\operatorname{Cons}\langle \pi_1b,a\rangle\rangle)\operatorname{Nil}$$

Finally, we substitute this into the translation of rev.

$$\begin{split} \|\text{rev}\| &= \|(\lambda \texttt{xs.rec}(\texttt{xs, Nil} \mapsto \lambda \texttt{a.a,} \\ &\quad \text{Cons} \mapsto \texttt{b.split}(\texttt{b,x.c.split}(\texttt{c,xs'.r.}\lambda \texttt{a.force}(\texttt{r}) \ \texttt{Cons}\langle \texttt{x,a}\rangle)))) \ \text{Nil}\| \\ &= \langle 0, \lambda xs.1 +_c \texttt{rec}(xs, \texttt{Nil} \mapsto \langle 1, \lambda a. \langle 0, a \rangle \rangle \\ &\quad \text{Cons} \mapsto b. \langle 1, \lambda a. (1 + (\pi_1 \pi_1 b)_c) +_c (\pi_1 \pi_1 b)_p \ \texttt{Cons}\langle \pi_1 b, a \rangle \rangle) \ \texttt{Nil} \rangle \end{split}$$

Observe that $\|\mathbf{rev}\|$ admits the same syntactic sugar as \mathbf{rev} . In the complexity language, instead of taking projections of b, we can use the same pattern matching syntactic sugar as in the source language.

$$\|\mathtt{rev}\| = \langle 0, \lambda x s. 1 +_c \mathtt{rec}(xs, \mathtt{Nil} \mapsto \langle 1, \lambda a. \langle 0, a \rangle \rangle$$

$$\mathtt{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \langle 1, \lambda a. (1 + r_c) +_c r_p \mathtt{Cons}\langle \pi_1 x, a \rangle \rangle) \mathtt{Nil} \rangle$$

2. Syntactic Sugar Translation

We walk through the same translation of fast reverse, but we use the syntactic sugar for matching introducted earlier. Recall the implementation of fast using syntactic sugar. The translation is almost identical to the translation of rev written without syntactic sugar until we translate the Cons branch of the rec.

$$\| ext{rev}\| = \|\lambda ext{xs.rec}(ext{xs}, \ ext{Nil} \mapsto \lambda ext{a.a.},$$
 $ext{Cons} \mapsto \langle x, \langle xs', r
angle
angle . \lambda a. ext{force}(r) \ ext{Cons} \langle x, a
angle) \ ext{Nil}\|$

First we apply the rule for translating an abstraction. The rule is $\|\lambda x.e\| = \langle 0, \lambda x. \|e\| \rangle$.

$$\|\mathtt{rev}\| = \langle 0, \lambda xs. \|\mathtt{rec}(xs, \mathtt{Nil} \mapsto \lambda a.a,$$

$$\mathtt{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \lambda a. \mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle) \ \mathtt{Nil}\| \rangle$$

Next we apply the rule for translating an application. The rule is $||e_0 e_1|| = (1 + ||e_0||_c + ||e_1||_c) +_c (||e_0||_p ||e_1||_p)$. In this case, rec(...) is e_0 and Nil is e_1 . We translate Nil DRAFT: April 7, 2016

then $\mathbf{rec}(...)$ separately. The translation of a constructor applied to an expression is a tuple of the cost of the translated expression and the corresponding complexity language constructor applied to the potential of the translated expression. Since the expression inside Nil is $\langle \rangle$, and $\|\langle \rangle\| = \langle 0, \langle \rangle \rangle$, we have

$$\begin{split} \|\text{Nil}\| &= \langle \langle 0, \langle \rangle \rangle_c, \text{Nil} \langle 0, \langle \rangle \rangle_p \rangle \\ &= \langle 0, \text{Nil} \langle \rangle \rangle \end{split}$$

The rule for translating a rec expression is

$$\|\mathrm{rec}(e,\overline{C\mapsto x.e_C})\| = \|e\|_c +_c \mathrm{rec}(\|e\|_p,\overline{C\mapsto x.\|e_C\|})$$

$$\begin{split} &\| \mathtt{rec}(xs,\mathtt{Nil} \mapsto \lambda a.a, \\ &\quad \mathtt{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \lambda a.\mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle) \| \\ &= \| xs\|_c +_c \mathtt{rec}(\| xs\|_p, \mathtt{Nil} \mapsto 1 +_c \| \lambda a.a \| \\ &\quad \mathtt{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. 1 +_c \| \lambda a.\mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle \|) \\ &= \langle 0, xs \rangle_c +_c \mathtt{rec}(\langle 0, xs \rangle_p, \mathtt{Nil} \mapsto 1 +_c \| \lambda a.a \| \\ &\quad \mathtt{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. 1 +_c \| \lambda a.\mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle \|) \end{split}$$

The term xs is a variable and the rule for translating variables is $||xs|| = \langle 0, xs \rangle$.

$$= \mathtt{rec}(xs, \mathtt{Nil} \mapsto 1 +_c \|\lambda a.a\|$$

$$\mathtt{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle.1 +_c \|\lambda a.\mathtt{force}(r) \ \mathtt{Cons} \langle x, a \rangle \|)$$

The translation of the Nil branch is the same as before.

$$1 +_c \|\lambda a.a\| = \langle 1, \lambda a.\langle 0, a \rangle \rangle$$

The translation of the Cons branch is much simpler without the two splits.

$$\begin{split} 1 +_c \|\lambda a. \mathsf{force}(r) \; \mathsf{Cons}\langle x, a \rangle \| \\ &= 1 +_c \langle 0, \lambda a. \| \mathsf{force}(r) \; \mathsf{Cons}\langle x, a \rangle \| \rangle \\ &= \langle 1, \lambda a. (1 + \|\mathsf{force}(r)\|_c + \|\mathsf{Cons}\langle x, a \rangle)\|_c) +_c \|\mathsf{force}(r)\|_p \; \|\mathsf{Cons}\langle x, a \rangle\|_p \rangle \end{split}$$

The translation of force(r) and $Cons\langle x, a \rangle$ are the same as before, except we do not have a substitution to apply.

$$\|\text{force}(r)\| = \|r\|_c +_c \|r\|_p = \langle 0, r \rangle_c +_c \langle 0, r \rangle_p = 0 +_c r = r$$

$$\|\mathsf{Cons}\langle x,a\rangle\| = \langle 0,\mathsf{Cons}\langle x,a\rangle \rangle$$

So the complete translation of the Cons branch is

$$\begin{split} 1 +_c \|\lambda a. \mathsf{force}(r) \ \mathsf{Cons}\langle x, a \rangle \| \\ &= 1 +_c \langle 0, \lambda a. \| \mathsf{force}(r) \ \mathsf{Cons}\langle x, a \rangle \| \rangle \\ &= \langle 1, \lambda a. (1 + \|\mathsf{force}(r)\|_c + \|\mathsf{Cons}\langle x, a \rangle)\|_c) +_c \|\mathsf{force}(r)\|_p \ \|\mathsf{Cons}\langle x, a \rangle\|_p \rangle \\ &= \langle 1, \lambda a. (1 + r_c + 0) +_c r_p \ \mathsf{Cons}\langle x, a \rangle \rangle \\ &= \langle 1, \lambda a. (1 + r_c) +_c r_p \ \mathsf{Cons}\langle x, a \rangle \rangle \end{split}$$

The complete translation of the rec becomes

$$\begin{split} \| \mathtt{rec}(xs,\mathtt{Nil} &\mapsto \lambda a.a, \\ & \mathtt{Cons} &\mapsto \langle x, \langle xs', r \rangle \rangle. \lambda a.\mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle) \| \\ &= \mathtt{rec}(xs,\mathtt{Nil} &\mapsto 1 +_c \| \lambda a.a \| \\ & \mathtt{Cons} &\mapsto \langle x, \langle xs', r \rangle \rangle. 1 +_c \| \lambda a.\mathtt{force}(r) \ \mathtt{Cons}\langle x, a \rangle \|) \\ &= \mathtt{rec}(xs,\mathtt{Nil} &\mapsto \langle 0, \lambda a. \langle 0, a \rangle \rangle \\ & \mathtt{Cons} &\mapsto \langle x, \langle xs', r \rangle \rangle. \langle 1, \lambda a. (1 + r_c) +_c r_p \ \mathtt{Cons}\langle x, a \rangle \rangle \end{split}$$

We substitute the translations of rec(...) and Nil into the application.

Let
$$R = \operatorname{rec}(xs,\operatorname{Nil} \mapsto \langle 1,\lambda a.\langle 0,a \rangle \rangle$$

$$\operatorname{Cons} \mapsto \langle x,\langle xs',r \rangle \rangle.\langle 1,\lambda a.(1+r_c)+_c r_p \operatorname{Cons}\langle x,a \rangle \rangle$$
 $\|\operatorname{rec}(xs,\operatorname{Nil} \mapsto \lambda a.a,$

$$\operatorname{Cons} \mapsto \langle x,\langle xs',r \rangle \rangle.\lambda a.\operatorname{force}(r) \operatorname{Cons}\langle x,a \rangle) \operatorname{Nil}\|$$
Substituting R for the translation of rec and $\langle 0,\operatorname{Nil} \rangle$ for the translation of Nil .
$$= (1+R_c)+_c R_p \operatorname{Nil} \rangle$$

$$= 1+_c \operatorname{rec}(xs,\operatorname{Nil} \mapsto \langle 1,\lambda a.\langle 0,a \rangle \rangle$$

$$\operatorname{Cons} \mapsto \langle x,\langle xs',r \rangle \rangle.\langle 1,\lambda a.(1+r_c)+_c r_p \operatorname{Cons}\langle x,a \rangle \rangle) \operatorname{Nil}$$

And our complete translation of rev is

$$\begin{split} \|\text{rev}\| &= \|\lambda \texttt{xs.rec}(\texttt{xs, Nil} \mapsto \lambda \texttt{a.a,} \\ &\quad \text{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \lambda a. \texttt{force}(r) \ \texttt{Cons}\langle x, a \rangle) \ \texttt{Nil}\| \\ &= \langle 0, \lambda xs. \|\text{rec}(xs, \texttt{Nil} \mapsto \lambda a.a, \\ &\quad \text{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \lambda a. \texttt{force}(r) \ \texttt{Cons}\langle x, a \rangle) \ \texttt{Nil}\| \rangle \\ &= \langle 0, \lambda xs. 1 +_c \texttt{rec}(xs, \texttt{Nil} \mapsto \langle 1, \lambda a. \langle 0, a \rangle) \rangle \\ &\quad \text{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \langle 1, \lambda a. (1 + r_c) +_c r_p \ \texttt{Cons}\langle x, a \rangle \rangle) \ \texttt{Nil} \rangle \end{split}$$

This is the same as the translation of rev without the syntactic sugar. We will use the syntactic sugar for the rest of this thesis.

3. Interpretation

The interpretation of rev is not interesting as the cost of rev is always null. Instead of interpreting rev, we will interpret rev applied to a list xs. Below is the translation of rev xs.

The cost of
$$\|\mathbf{rev}\|$$
 is 0, and we will let \mathbf{xs} be a value, which has 0 cost.
$$= (1+0+0) +_c \|\mathbf{rev}\|_p \ xs$$

$$= 1 +_c (\lambda xs.1 +_c \mathbf{rec}(xs, \mathbf{Nil} \mapsto \langle 1, \lambda a. \langle 0, a \rangle \rangle$$

$$\mathbf{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \langle 1, \lambda a. (1+r_c) +_c r_p \mathbf{Cons} \langle x, a \rangle \rangle) \ \mathbf{Nil}) \ xs$$

 $\|\text{rev xs}\| = (1 + \|\text{rev}\|_c + \|xs\|_c) +_c \|\text{rev}\|_p \|xs\|_p$

The cost of rev is driven by the auxiliary function rec(...). The cost of rev will be determined by the cost of the auxiliary function rec(...) applied to Nil plus some constant factor. We will interpret the auxiliary function in the following denotational DRAFT: April 7, 2016

semantics. We interest the size of an list to be the number of list constructors.

$$\begin{split} \llbracket \mathtt{list} \rrbracket &= \mathbb{N}^{\infty} \\ D^{list} &= \{*\} + \{1\} \times \mathbb{N}^{\infty} \\ size_{list}(\mathtt{Nil}) &= 1 \\ size_{list}(\mathtt{Cons(1,n)}) &= 1 + n \end{split}$$

We define the macro R(xs) as the translation of the auxiliary function rec(...) to avoid repeated coping of the translation.

Let
$$R(xs) = \operatorname{rec}(xs, \operatorname{Nil} \mapsto \langle 1, \lambda a. \langle 0, a \rangle \rangle$$

$$\operatorname{Cons} \mapsto b. \langle 1, \lambda a. (1 + \pi_1 \pi_1 b_c) +_c \pi_1 \pi_1 b_p \operatorname{Cons} \langle \pi_0 b, a \rangle \rangle$$

The recurrence g(n) is the interpretation of the auxiliary function R(xs), where n is the interpretation of xs.

$$\begin{split} g(n) &= [\![R(xs)]\!] \{xs \mapsto n\} \\ &= \bigvee_{size \ z \leq [\![xs]\!] \{xs \mapsto n\}} case(z, f_C, f_N) \\ \text{where} \\ f_{Nil}(x) &= [\![\langle 1, \lambda a. \langle 0, a \rangle \rangle]\!] \{xs \mapsto n\} \\ &= (1, \lambda a. (0, a)) \\ f_{Cons}(b) &= [\![\langle 1, \lambda a. (1 + \pi_1 \pi_1 b_c) +_c \pi_1 \pi_1 b_p \operatorname{Cons} \langle \pi_0 b, a \rangle \rangle]\!] \\ &= \{xs \mapsto n, b \mapsto map^{\Phi_{Cons}}(\lambda \lambda d. (d, [\![R(w)]\!] \{w \mapsto d, xs \mapsto n\}), b)\} \end{split}$$

Let us take a moment to analyze the semantic map. The definition mirrors the definition of the map macro in the complexity language. Since b is a tuple, map over a tuple is DRAFT: April 7, 2016

defined as the tuple of the map over the projections of the tuple.

The definition of map over a recursive occurrence of a

a datatype is
$$map^{T}(\lambda x. V_{0}, V_{1}) = V_{0}[V_{1}/x].$$

= $(\pi_{0}b, (\pi_{1}b, [R(w)]\{w \mapsto \pi_{1}b\}))$

Observe that we can substitute $g(\pi_1 b)$ for $[R(w)] \{ w \mapsto \pi_1 b \}$.

$$= (\pi_0 b, (\pi_1 b, g(\pi_1 b)))$$

Let us resume our interpretation of rec(...).

$$\begin{split} f_{Cons}(b) &= \left[\!\!\left[\langle 1, \lambda a.(1+\pi_1\pi_1b_c) +_c \pi_1\pi_1b_p \, \mathsf{Cons}\langle \pi_0b, a\rangle\rangle\right]\!\!\right] \\ &\qquad \left\{xs\mapsto n, b\mapsto map^{\Phi_{Cons}}(\lambda \!\!\backslash \! d.(d, \left[\!\!\left[R(w)\right]\!\!\right] \{w\mapsto d\}), b)\right\} \\ &= \left[\!\!\left[\langle 1, \lambda a.(1+\pi_1\pi_1b_c) +_c \pi_1\pi_1b_p \, \mathsf{Cons}\langle \pi_0b, a\rangle\rangle\right]\!\!\right] \\ &\qquad \left\{xs\mapsto n, b\mapsto (\pi_0b, (\pi_1b, g(\pi_1b)))\right\} \\ &= (1, \left[\!\!\left[\lambda a.(1+\pi_1\pi_1b_c) +_c \pi_1\pi_1b_p \, \mathsf{Cons}\langle \pi_0b, a\rangle\right]\!\!\right] \\ &\qquad \left\{xs\mapsto n, b\mapsto (\pi_0b, (\pi_1b, g(\pi_1b)))\right\}) \\ &= (1, \lambda \!\!\backslash \! a.[(1+\pi_1\pi_1b_c) +_c \pi_1\pi_1b_p \, \mathsf{Cons}\langle \pi_0b, a\rangle]\!\!\right] \\ &\qquad \left\{xs\mapsto n, b\mapsto (\pi_0b, (\pi_1b, g(\pi_1b))), a\mapsto a\right\}) \\ &= (1, \lambda \!\!\backslash \! a.(1+g_c(\pi_1b)) \#_c g_p(\pi_1b) \, (1+a)) \end{split}$$

So the initial extracted recurrence from rec is

$$g(n) = \bigvee_{size} case(z, f_C, f_N)$$
 where
$$f_{Nil}(x) = (1, \lambda \lambda a.(0, a))$$

$$f_{Cons}(b) = (1, \lambda \lambda a.(1 + g_c(\pi_1 b)) + g_c(\pi_1 b) (a + 1))$$

To obtain a closed form solution for the recurrence, we must eliminate the big maximum operator. To do so we break the definition of g into two cases.

case
$$n = 0$$
:
For $n = 0$, $g(0) = (1, \lambda \lambda a.(0, a))$.
case $n > 0$:

$$\begin{split} g(n+1) &= \bigvee_{size\ ys \leq n+1} case(ys, f_{Nil}, f_{Cons}) \\ &= \bigvee_{size\ ys \leq n} case(ys, f_{Nil}, f_{Cons}) \vee \bigvee_{size\ ys = n+1} case(ys, f_{Nil}, f_{Cons}) \\ &= g(n) \vee \bigvee_{size\ ys = n+1} case(ys, \lambda ().(1, \lambda (a.(0, a)), \lambda (1, m).(1, \lambda (a.(1 + g_c(m)) + g_p(m)(a + 1))) \\ &= g(n) \vee \langle 1, \lambda (a.(1 + g_c(n)) + g_p(n)(a + 1)) \rangle \end{split}$$

In order to eliminate the remaining max operator, we want to show that g is monotonically increasing; $\forall n.g(n) \leq g(n+1)$. By definition of \leq , $g(n) \leq g(n+1) \Leftrightarrow g_c(n) \leq g_c(n+1) \land g_p(n) \leq g_p(n+1)$. First we will show lemma 3.1, which states the cost of g(n) is always one.

LEMMA 3.1.
$$\forall n.g_c(n) = 1$$
.

PROOF. We prove this by induction on n.

DRAFT: April 7, 2016

Base case: n = 0:

By definition, $g_c(0) = (1, \lambda a.(0, a)) = 1.$

Induction step: n > 0:

By definition $g_c(n+1) = (g(n) \vee (1, \lambda a.(1+g_c(n)) +_c g_p(n) (a+1)))_c$. We distribute the projection over the max: $g_c(n+1) = g_c(n) \vee 1$. By the induction hypothesis, $g_c(n) = 1$, so $g_c(n+1) = 1$.

The immediate corollary of this is $g_c(n)$ is monotonically increasing.

Corollary 3.1.1. $\forall n.g_c(n) \leq g_c(n+1)$.

First we prove the lemma stating the potential of g(n) a is monotonically increasing.

LEMMA 3.2.
$$\forall n.g_p(n) \ a \leq g_p(n) \ (a+1)$$

PROOF. We prove this by induction on n.

$$n=0:$$

$$g_p(0)\ a=(\lambda\!\!\!/ a.(0,a))\ a=(0,a)$$

$$g_p(0)\ (a+1)=(\lambda\!\!\!/ a.(0.a))\ (a+1)=(0,a+1)$$

$$(0,a)\leq (0,a+1).$$

$$n>0:$$

We assume $g_p(n)$ $a \leq g_p(n)$ (a+1).

$$g_p(n) \ a \le g_p(n) \ (a+1)$$

$$g_p(n) \ a \lor (1+g_c(n)) \#_c g_p(n) \ a \le g_p(n) \ (a+1) \lor (1+g_c(n)) \#_c g_p(n) \ (a+1)$$

$$g_p(n+1) \ a \le g_p(n+1) \ (a+1)$$

Now we show $g_p(n) \leq g_p(n+1)$.

DRAFT: April 7, 2016

PROOF. By reflexivity, $g_p(n) \leq g_p(n)$. By the lemma we just proved:

$$g_p(n) \ a \le g_p(n) \ (a+1)$$

$$g_p(n) \ a \le (1+g_c(n)) \#_c g_p(n) \ (a+1)$$
 $\&a.g_p(n) \ a \le \&a.(1+g_c(n)) \#_c g_p(n) \ (a+1)$

So since for all n, $g_c(n) = 1$ and $g_p(n) \le \lambda \lambda a.(1 + g_c(n)) +_c g_p(n)$ (a+1), we conclude

$$g(n) \leq \langle 1, \lambda \lambda a.(1 + g_c(n)) +_c g_p(n) (a+1) \rangle$$

So

$$g(n+1) = \langle 1, \lambda \lambda a. (1 + g_c(n)) +_c g_p(n) (a+1) \rangle$$

To extract a recurrence from g, we apply g to the interpretation of a list a. Let $h(n, a) = g_p(n)$ a. For n = 0

$$h(0, a) = g_p(0)a$$
$$= (\lambda a.(0, a))a$$
$$= (0, a)$$

For n > 0

$$h(n,a) = g_p(n)a$$

$$= (\lambda a.(1 + g_c(n-1)) +_c g_p(n-1) (a+1)) a$$

$$= (1 + g_c(n-1)) +_c g_p(n-1)(a+1)$$

$$= (1+1) +_c h(n-1,a+1)$$

$$= (2 + h_c(n-1,a+1), h_p(n-1,a+1))$$

From this recurrence, we can extract a recurrence for the cost. For n=0

$$h_c(0,a) = (0,a)_c = 0$$

For n > 0

$$h_c(n,a) = (2 + h_c(n-1, a+1), h_p(n-1, a+1))_c = 2 + h_c(n-1, a+1)$$

We now have a recurrence for the cost of the auxiliary function rec(xs,...) when applied to some list:

(1)
$$h_c(n,a) = \begin{cases} 0 & n=0\\ 2 + h_c(n-1, a+1) & n>0 \end{cases}$$

We state the solution to the recurrence h_c is 2n.

THEOREM 3.3. $h_c(n, a) = 2n$

PROOF. We prove this by induction on n.

: case
$$n=0$$

$$h_c(0,a) = 0 = 2 \cdot 0$$

: case n > 0

We assume $h_c(n, a+1) = 2n$.

$$h_c(n+1, a) = 2 + h_c(n, a+1)$$

= 2 + 2n
= 2(n+1)

So we have proved the interpretation of applying the auxiliary function of rev xs to a list is linear in the length of xs.

We can also extract a recurrence for the potential. For n=0

$$h_p(0, a) = h_p(0, a)$$
$$= (0, a)_p$$
$$= a$$

For n > 0

$$h_p(n, a) = (2 + h_c(n - 1, a + 1), h_p(n - 1, a + 1))_p$$

= $h_p(n - 1, a + 1)$

We now have a recurrence for the potential of the auxiliary function in rev xs when applied to some list a.

(2)
$$h_p(n,a) = \begin{cases} a & n = 0 \\ h_p(n-1, a+1) & n > 0 \end{cases}$$

THEOREM 3.4. $h_p(n, a) = n + a$

PROOF. We prove this by induction on n.

: case n=0

$$h_p(0,a) = a$$

: case n > 0

$$h_p(n,a) = h_p(n-1,a+1)$$

= $n-1+a+1$ by the induction hypothesis
= $n+a$

Now that we have obtained a closed form solution for the recurrence describing the cost and potential of the auxiliary function that drives the cost of rev, we can obtain the interpretations for the cost and potential of rev xs. Recall the translation of rev xs.

$$\|\text{rev xs}\| = 1 +_c (\lambda x s.1 +_c \text{rec}(xs, \text{Nil} \mapsto \langle 1, \lambda a. \langle 0, a \rangle \rangle)$$

$$\text{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \langle 1, \lambda a. (1 + r_c) +_c r_p \text{Cons}\langle x, a \rangle \rangle) \text{ Nil}) \ xs$$

DRAFT: April 7, 2016

We can obtain an interpretation of $\|\mathbf{rev}\|$ by substituting our interpretation of the auxiliary function.

Let
$$n = [\![\| xs \|]\!]$$
.
$$[\![\| \text{rev xs} \|]\!] = [\![1 +_c (\lambda xs.1 +_c \text{rec}(xs, \text{Nil} \mapsto \langle 1, \lambda a. \langle 0, a \rangle \rangle) \\ \text{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \langle 1, \lambda a. (1 + r_c) +_c r_p \text{Cons}\langle x, a \rangle \rangle \rangle \text{Nil}) \ xs]\!] \{xs \mapsto n\}$$

$$= 1 +_c [\![\lambda xs.1 +_c \text{rec}(xs, \text{Nil} \mapsto \langle 1, \lambda a. \langle 0, a \rangle \rangle) \\ \text{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \langle 1, \lambda a. (1 + r_c) +_c r_p \text{Cons}\langle x, a \rangle \rangle \rangle \text{Nil}]\!] \{xs \mapsto n\} \ n$$

$$= 1 +_c (\![\lambda xs.]\!] +_c \text{rec}(xs, \text{Nil} \mapsto \langle 1, \lambda a. \langle 0, a \rangle \rangle) \\ \text{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \langle 1, \lambda a. (1 + r_c) +_c r_p \text{Cons}\langle x, a \rangle \rangle \rangle \text{Nil}]\!] \{xs \mapsto n\} \ n$$

$$= 1 +_c (\![\lambda xs.]\!] +_c [\![\text{rec}(xs, \text{Nil} \mapsto \langle 1, \lambda a. \langle 0, a \rangle \rangle \rangle) \\ \text{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \langle 1, \lambda a. (1 + r_c) +_c r_p \text{Cons}\langle x, a \rangle \rangle \rangle)\!] \{xs \mapsto n\} \ 0) \ n$$

$$= 1 +_c (\![\lambda xs.]\!] +_c h(xs, 0) \rangle n$$

$$= 1 +_c (1 +_c h(n, 0))$$

$$= 1 +_c (1 +_c (2n, n))$$

$$= (2 + 2n, n)$$

So we see that the cost of rev xs is linear in the length of the list, and that the potential of the result is equal to the potential of the input.

CHAPTER 4

Reverse

Here we present the naive implementation of list reverse. The naive implementation reverses a list in quadratic time as opposed to linear time.

datatype list = Nil of unit | Cons of int
$$\times$$
 list

The implementation walks down a list, appending the head of the list to the end of the result of recursively calling itself on the tail of the list. We use the syntactic sugar introduced earlier.

$$rev = \lambda x s. \mathtt{rec}(xs, \mathtt{Nil} \mapsto \mathtt{Nil},$$

$$\mathtt{Cons} \mapsto \langle x, \langle xs', r \rangle \rangle. \mathtt{rec}(\mathtt{force}(r), \mathtt{Nil} \mapsto \mathtt{Cons}\langle x, \mathtt{Nil} \rangle,$$

$$\mathtt{Cons} \mapsto \langle y, \langle ys, rys \rangle \rangle. \mathtt{Cons}\langle y, \mathtt{force}(rys) \rangle))$$

1. Translation

The translation into the complexity language is

$$\label{eq:cons} \begin{array}{lll} \texttt{rev} \; = \; \big\langle \texttt{0} \,, \lambda \texttt{xs.rec} \, (\texttt{xs} \,, \, \texttt{Nil} \; \mapsto \; \texttt{Nil} \\ & , \; \texttt{Cons} \; \mapsto \big\langle \texttt{x} \,, \big\langle \texttt{xs} \,, \, \texttt{r} \big\rangle \big\rangle \,. \\ & & \texttt{rec} \, (\texttt{r} \,, \, \, \texttt{Nil} \; \mapsto \; \texttt{Cons} \big\langle \texttt{x} \,, \, \, \texttt{Nil} \big\rangle \\ & & , \; \; \texttt{Cons} \; \mapsto \big\langle \texttt{y} \,, \big\langle \texttt{ys} \,, \, \texttt{rys} \big\rangle \big\rangle \,. \; \; \texttt{Cons} \big\langle \texttt{y} \,, \, \, \, \texttt{rys} \big\rangle \big) \big) \big\rangle \end{array}$$

It is more interesting if we consider the translation of rev applied to some xs:intlist. The translation of this function into the complexity language proceeds as follows. We begin with translating the outer rec construct.

rev xs = 1 +
$$\|\mathbf{xs}\|_c$$
 + $_c$ rec($\|\mathbf{xs}\|_p$, Nil \mapsto 1 + $_c$ $\|$ Nil $\|$ DRAFT: April 7, 2016

4. REVERSE 33

, Cons
$$\mapsto \langle x, \langle xs', r \rangle \rangle$$
. 1 $+_c \| rec(...) \| \rangle$

The cost of the translation of an intlist is zero, and the potential of the translation of an intlist is the list itself.

$$\texttt{rev xs = 1} \ +_c \ \texttt{rec(xs, Nil} \ \mapsto \ \big\langle \texttt{1,Nil} \big\rangle \ \ , \ \ \texttt{Cons} \ \mapsto \big\langle \texttt{x,\langlexs',r} \big\rangle \big\rangle \, . \ \ 1 \ +_c \ \big\| \texttt{rec(...)} \, \big\|)$$

Next we translate the inner rec.

$$\| \operatorname{rec}(\operatorname{force}(r), \operatorname{Nil} \mapsto \operatorname{Cons}(\langle x, \operatorname{Nil} \rangle)$$
, $\operatorname{Cons} \mapsto \langle y, \langle ys, rys \rangle \rangle$. $\operatorname{Cons}\langle y, \operatorname{force}(rys) \rangle)) \|$

Since x, xs', r are terms in the complexity language, they do not need to be translated. First we apply the rules for rec and force.

$$egin{aligned} \mathbf{r}_c & +_c & \mathtt{rec}(\mathbf{r}_p, \ \mathtt{Nil} & \mapsto \ 1 & +_c \ \|\mathtt{Cons}(\langle \mathtt{x}, \ \mathtt{Nil} \rangle)\| \end{aligned}$$
 , $\mathtt{Cons} & \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{rys} \rangle \rangle$. $1 & +_c \ \|\mathtt{Cons}\langle \mathtt{y}, \mathtt{force}(\mathtt{rys}) \rangle \|)$

The cost of the Cons constructor is zero, and the translation of force is just the translation of its argument.

$$\mathtt{r}_c +_c \mathtt{rec}(\mathtt{r}_p, \mathtt{Nil} \mapsto \langle \mathtt{1}, \mathtt{Cons}\langle \mathtt{x}_p, \mathtt{Nil} \rangle \rangle$$

$$, \mathtt{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{rys} \rangle \rangle. \ \langle \mathtt{1} + \mathtt{rys}_c, \mathtt{Cons}\langle \mathtt{y}_p, \mathtt{rys}_p \rangle \rangle)$$

Putting the pieces together, we get

$$\|\text{rev xs}\| = 1 +_c \text{rec}(\text{xs}_p)$$

$$, \text{ Nil } \mapsto \langle \text{1,Nil} \rangle$$

$$, \text{ Cons } \mapsto \langle \text{x,} \langle \text{xs',r} \rangle \rangle. \ 1 + \text{r}_c +_c$$

$$\text{rec}(\text{r}_p, \text{ Nil } \mapsto \langle \text{1,Cons} \langle \text{x}_p, \text{ Nil} \rangle \rangle$$

$$, \text{ Cons } \mapsto \langle \text{y,} \langle \text{ys,rys} \rangle \rangle. \ \langle \text{1 + rys}_c, \text{Cons} \langle \text{y}_p, \text{rys}_p \rangle \rangle$$

2. Interpretation

We interret the size of an intlist to be the number of constructors. \llbracket intlist \rrbracket $= \mathbb{N}^{\infty}$

$$D^{intlist} = \{*\} + \{1\} \times \mathbb{N}^{\infty}$$
 DRAFT: April 7, 2016

4. REVERSE 34

$$size_{intlist}(\mathtt{Nil}) = 0$$

$$size_{intlist}(\mathtt{Cons(1,n)}) = 1 + n$$

Then $[\![\|\mathbf{rev}\ \mathbf{xs}\|_c]\!]=1+g(\|xs\|_p),$ where

$$g(n) = [\![rec(z,Nil \mapsto 1,Cons \mapsto \langle x,\langle xs',r\rangle\rangle.1 + r_c + h(r_p))]\!]\{z \mapsto n\}$$

$$h(n) = \llbracket rec(z, Nil \mapsto 1, Cons \mapsto \langle y, \langle ys', r \rangle \rangle.1 + r_c \rrbracket \{z \mapsto n\}$$

We calculate that h(0) = 1 and for n > 0, h(n) = 1 + h(n-1). g(0) = 1 and for n > 0, g(n) = 1 + g(n-1) + h(n-1)

CHAPTER 5

Parametric Insertion Sort

Parametric insertion sort is a higher order algorithm which sorts a list using a comparison function which is passed to it as an argument. The running time of insertion sort is $\mathcal{O}(n^2)$. This characterization of the complexity of parametric insertion sort does not capture role of the comparison function in the running time. When sorting a list of integers, where comparison between any two integers takes constant time, this does not matter. However, when sorting a list of strings, where the complexity of comparison is order the length of the string, the length of the strings may influence the running time more than the length of the list when sorting small lists of large strings.

0.0.1. *Insert*. The function sort relies on the function insert to insert the head of the list into the result of recursively sorted tail of the list. We will begin with a translation and interpretation of insert.

0.0.2. Translation. The translation of insert is broken into chunks to make it more manageable. Figure 2 steps through the translation of the comparison function f applied to variables x and y. The translation true and false branches are given in figures 3 and 4 respectively. Figure 5 uses the translation of f x y and the true and false branches to construct the translation of the inner rec construct. The Nil and Cons branches of the outer rec construct are given in figures 6 and 7, respectively. We put these together to give the translation of insert. Finally we give a translation of insert f x xs in figure 9 because this is the term we will interpret in a size-based semantics. The result is:

$$\|\texttt{insert f x xs}\| = (3 + \|\texttt{f}\|_c + \|\texttt{x}\|_c + \|\texttt{xs}\|_c) \\ +_c \texttt{rec}(\|\texttt{xs}\|_p, \\ \texttt{Nil} \mapsto \langle \texttt{1,Cons}\langle \texttt{x,Nil}\rangle \rangle$$
 DRAFT: April 7, 2016 35

$$\begin{aligned} \mathsf{Cons} \mapsto \langle \mathtt{y}\,, \langle \mathtt{ys}\,, \mathtt{r} \rangle \rangle \,.\, (3 + ((\|\mathtt{f}\|_p \|\mathtt{x}\|_p)_p \ \mathtt{y})_c) +_c \mathtt{rec}\, ((\|\mathtt{f}\|_p \|\mathtt{x}\|_p)_p \ \mathtt{y})_p\,, \end{aligned}$$

$$\mathsf{True} \mapsto \langle 1, \mathsf{Cons} \langle \|\mathtt{x}\|_p\,, \mathsf{Cons} \langle \mathtt{y}\,, \mathtt{y} \rangle)$$

$$\mathsf{False} \mapsto \langle 1 + \mathtt{r}_c, \mathsf{Cons} \langle \mathtt{y}\,, \mathtt{r}_p \rangle \rangle)$$

0.0.3. Interpretation. We well use an interpretation of lists as a pair of their greatest element and their length. Figure 10 formalizes this interpretation. We use the mutual ordering on pairs. That is, $(s, n) \leq (s', n')$ if $n \leq n'$ and s < s' or n < n' and $s \leq s'$.

First we interpret the rec, which drives of the cost of insert. As in the translation, we break the interpretation up to make it more manageable. We will write map, λ and $+_c$ in the semantics, which stand for the semantic equivalents of the syntactic map, λ and $+_c$. The definitions of these semantic functions mirror the definitions of their syntactic equivalents. Figures 11 and 12 walk through the interpretation. The initial result is given in equation 8.

$$f_{Nil}(\langle \rangle) = (1, (x, 1))$$

$$f_{Cons}(j, (j, m)) = (4 + \pi_0(\pi_1(f \ x) \ j) + \pi_0 g(j, m),$$

$$(max\{x, j, \pi_0 \pi_1 g(j, m)\}, 2 + m \lor 1 + \pi_1 \pi_1 g(j, m)))$$

$$g(i, n) = \bigvee_{size(z) < (i, n)} case(z, (f_{Nil}, f_{Cons}))$$

This recurrence is difficult to work with. Specifically, we cannot apply traditional methods of solving it. We will manipulate it into a more usable form by eliminating the arbitrary maximum. We will separate the recurrence into a recurrence for the cost and a recurrence for the potential, and solve those independently.

LEMMA 0.1.
$$g_c(i, n) \le (4 + ((f x)_p i)_c n + 1)$$

PROOF. We prove this by induction on n. Recall we use the mutual ordering on pairs.

case
$$n=0$$
:
$$g_c(i,n)=(1,(x,1))_c=1 \label{eq:gc}$$
 DRAFT: April 7, 2016

casen > 0:

$$= \bigvee_{size(z) \le (i,n)} case(z, (f_{Nil}, f_{Cons}))$$

$$= \bigvee_{j < i,m \le n \text{ or } j \le i,m < n} case((j,m), (f_{Nil}, f_{Cons}))$$

$$= \bigvee_{j < i,m \le n \text{ or } j \le i,m < n} 4 + ((f \ x)_p \ j)_c + g_c(j,m')) \qquad \text{where } m' = m-1$$

$$= \bigvee_{j < i,m \le n \text{ or } j \le i,m < n} 4 + ((f \ x)_p \ j)_c + (4 + ((f \ x)_p \ j)_c)m' + 1 \quad \text{by the induction hypothesis}$$

$$= \bigvee_{j < i,m \le n \text{ or } j \le i,m < n} (4 + ((f \ x)_p \ j)_c)(m' + 1) + 1$$

$$= \bigvee_{j < i,m \le n \text{ or } j \le i,m < n} (4 + ((f \ x)_p \ j)_c)m + 1$$

$$\le \bigvee_{i < j,m \le n \text{ or } i \le j,m < n} (4 + ((f \ x)_p \ i)_c)n + 1$$

$$\le (4 + ((f \ x)_p \ i)_c)n + 1$$

As expected, we find the cost of insert is bounded by the length of the list and the largest element.

LEMMA 0.2.
$$g_p(i, n) \le (max\{x, i\}, n + 1)$$

PROOF. We prove this by induction on n.

case
$$n=0$$
:
$$g_p(i,n)=(1,(x,1))_p=(x,1). \label{eq:gp}$$
 DRAFT: April 7, 2016

case n > 0:

$$= \bigvee_{size(z) \leq (i,n)} case(z,(f_{Nil},f_{Cons}))$$

$$= \bigvee_{j < i,m \leq n \text{ or } j \leq i,m < n} (max\{x,j,\pi_0\pi_1g(j,m')\},2+m' \vee 1+\pi_1\pi_1g(j,m')) \text{ where } m' = m-1$$

$$\leq \bigvee_{j < i,m \leq n \text{ or } j \leq i,m < n} (max\{x,j\},2+m') \text{ by the induction hypothesis}$$

$$\leq \bigvee_{j < i,m \leq n \text{ or } j \leq i,m < n} (max\{x,i\},1+n)$$

$$\leq (max\{x,i\},1+n)$$

We find the length of the potential is bounded by one plus the length of the input, and the largest element in the output is bounded by the maximum of the element being inserted and the largest element in the input. This is somewhat unsatisfactory, since we would expect the relationship to be equality. What happens if we try to prove the equality?

Lemma 0.3.
$$g_p(i, n) = (max\{x, i\}, n + 1)$$

PROOF. We attempt to prove this by induction on n. The first steps proceed similarly to 0.2.

case
$$n=0$$
:
$$g_p(i,n)=(1,(x,1))_p=(x,1). \label{eq:gp}$$
 DRAFT: April 7, 2016

case n > 0:

$$= \bigvee_{size(z) \leq (i,n)} case(z, (f_{Nil}, f_{Cons}))$$

$$= \bigvee_{j < i,m \leq n \text{ or } j \leq i,m < n} (max\{x, j, \pi_0 \pi_1 g(j, m')\}, 2 + m' \vee 1 + \pi_1 \pi_1 g(j, m')) \text{ where } m' = m - 1$$

$$= \bigvee_{j < i,m \leq n \text{ or } j \leq i,m < n} (max\{x, j\}, 2 + m') \text{ by the induction hypothesis}$$

$$= \bigvee_{j < i,m \leq n} (max\{x, j\}, 1 + m) \vee \bigvee_{j \leq i,m < n} (max\{x, j\}, 1 + m)$$

We see that we get stuck. Because of the mutual ordering on pairs, our big maximum is over all z such that size(z) < (i, n). This includes (j, m) such that $j < i^m \le n$. We have no way of reasoning about the potential of $g(i-1,n) \lor g(i,n-1)$. So we cannot prove equality for 0.2. This indicates we may not have the optimal ordering on pairs.

Using lemmas 0.1 and 0.2, we can express the cost and potential of insert in terms of its arguments.

(4)
$$insert \ f \ x \ xs \leq (4 + ((f \ x)_p \ i)_c n + 1, (max\{x,i\},n+1))$$
 0.0.4. Sort.

0.0.5. Translation. The translation of sort is shown in figure 15. The translation of the Nil and Cons branches in the rec are walked through in figures 13 and 14, respectively. The translation of sort applied to its arguments is given in figure 16.

0.0.6. Interpretation. The rec construct again drives the cost and potential of sort. The walk through of the interpretation of the rec is given in figure 17. Equation 12 shows the initial recurrence extracted.

$$g(i,n) = \bigvee_{size(z) \le (i,n)} case(z, (\lambda(\langle \rangle).(1, (\neg \infty, 0), \lambda(j,m).4 + \pi_0 g(j,m)) +_c (insert \ f \ j \ \pi_1 g(j,m)))$$

Observe that in equation 12, the cost is depends on the potential of the recursive call. Therefore we must solve the recurrence for the potential first.

DRAFT: April 7, 2016

(5)

LEMMA 0.4. $\pi_1 g(n) \leq (j, n)$

PROOF. We prove this by induction on n. We use equation 4 to determine the potential of the *insert* function.

case
$$n = 0$$
: $\pi_1 g(i, n) = (i, 0)$
case $n > 0$:

$$\begin{split} \pi_1 g(i,n) &= \pi_1 \bigvee_{size(z) \leq n} case(z, (\lambda(\langle \rangle).(1, (\neg \infty, 0)), \lambda(j,m).4 + \pi_0 g(j,m)) +_c (insert \ f \ j \ \pi_1 g(j,m))) \\ &= \bigvee_{j \leq i, m < n \text{ or } j < i, m \leq n} \pi_1 (insert \ f \ j \ \pi_1 g(j',m')) \qquad j' \leq j, m' = m-1 \\ &\leq \bigvee_{j \leq i, m < n \text{ or } j < i, m \leq n} \pi_1 (insert \ f \ j \ (j',m')) \\ &\leq \bigvee_{j \leq i, m < n \text{ or } j < i, m \leq n} (max\{j,j'\}, m'+1) \\ &\leq \bigvee_{j \leq i, m < n \text{ or } j < i, m \leq n} (j,m) \\ &\leq \bigvee_{j \leq i, m < n \text{ or } j < i, m \leq n} (i,n) \\ &\leq (i,n) \end{split}$$

As in the interpretation of insert we are left with a less than satisfactory bound on the potential of sort. It would grievous mistake to write a sorting function whose output was smaller than its input. Under the current interpretation of lists, this would mean either the length of the list decreased or the size of the largest element in the list decreased. Unfortunately we are stuck with an upper bound on the size of the output because or interpretation of insert only provides an upper bound on the potential of its output. We may solve the recurrence for the cost of sort.

Lemma 0.5.
$$\pi_0 g(n) \le (4 + \pi_0(\pi_1(f \ x) \ i)n^2 + 5n + 1$$

PROOF. We prove this by induction on n.

DRAFT: April 7, 2016

case
$$n = 0$$
: $\pi_0 g(i, n) = 1$
case $n > 0$:

$$\begin{split} \pi_0 g(i,n) &= \pi_0 \bigvee_{size(z) \leq (i,n)} case(z, (\lambda(\langle \rangle).(1, (\neg \infty, 0)), \lambda(j,m).4 + \pi_0 g(j,m)) +_c (insert \ f \ j \ \pi_1 g(j,m))) \\ &= \bigvee_{j < i, m \leq n \text{ or } j \leq i, m < n} 4 + \pi_0 g(j,m-1) + \pi_0 (insert \ f \ j \ \pi_1 g(j,m-1)) \\ &\leq \bigvee_{j < i, m \leq n \text{ or } j \leq i, m < n} 4 + \pi_0 g(j,m-1) + \pi_0 (insert \ f \ j \ (j,m-1)) \\ &\leq \bigvee_{j < i, m \leq n \text{ or } j \leq i, m < n} 4 + \pi_0 g(j,m-1) + (4 + \pi_0 (\pi_1 (f \ j) \ j))(m-1) + 1 \\ &\text{ let } c_1 = (4 + \pi_0 (\pi_1 (f \ j) \ j)) \\ &\leq \bigvee_{j < i, m \leq n \text{ or } j \leq i, m < n} 4 + c_1 (m-1)^2 + 5(m-1) + 1 + c_1 (m-1) + 1 \\ &\leq \bigvee_{j < i, m \leq n \text{ or } j \leq i, m < n} 4 + c_1 m^2 - 2c_1 m + c_1 + 5m - 5 + 1 + c_1 m - c_1 + 1 \\ &\leq \bigvee_{j < i, m \leq n \text{ or } j \leq i, m < n} c_1 m^2 - c_1 m + 5m + 1 \\ &\leq \bigvee_{j < i, m \leq n \text{ or } j \leq i, m < n} (4 + \pi_0 (\pi_1 (f \ i) \ i)) n^2 + 5n + 1 \\ &\leq (4 + \pi_0 (\pi_1 (f \ i) \ i)) n^2 + 5n + 1 \end{split}$$

As expected the cost of sort is $\mathcal{O}(n^2)$ where n is the length of the list. It is clear from the analysis how the cost of the comparison function determines the running time of sort. We can see that the comparison function is called order n^2 times.

Figure 1. Parametric insertion sort in the source language

data list = Nil of unit | Cons of int \times list

insert = $\lambda f. \lambda x. \lambda xs. rec(xs, Nil \mapsto Cons(x, Nil),$

$$\mathtt{Cons} \mapsto \langle \mathtt{y} \, , \langle \mathtt{ys} \, , \mathtt{r} \rangle \rangle \, . \, \, \mathtt{rec} \, (\mathtt{f} \ \mathtt{x} \ \mathtt{y} \, , \ \mathtt{True} \ \mapsto \ \mathtt{Cons} \langle \mathtt{x} \, , \mathtt{Cons} \langle \mathtt{y} \, , \mathtt{ys} \rangle \rangle \, , \,$$

False \mapsto Cons $\langle y, force(r) \rangle$

 $\texttt{sort} \ = \ \lambda \texttt{f} . \lambda \texttt{xs.rec}(\texttt{xs}, \ \texttt{Nil} \mapsto \ \texttt{Nil}, \ \texttt{Cons} \mapsto \langle \texttt{y}, \langle \texttt{ys}, \texttt{r} \rangle \rangle . \texttt{insert} \ \texttt{f} \ \texttt{y} \ \texttt{force}(\texttt{r}))$

FIGURE 2. Translation of $(f:Int\rightarrow Int\rightarrow Bool)$ (x:Int) (y:Int). We assume f, x and y are variables, so the cost of their translation is 0. Since f is a function of two arguments, the cost of f is 0 unless f is fully applied. Notice that f in ||f|| is a source variable while plain f is a potential variable.

 $\|\mathbf{f} \times \mathbf{y}\| = (1 + \|\mathbf{f} \times \|_c + \|\mathbf{y}\|_c) +_c \|\mathbf{f} \times \|_p \|\mathbf{y}\|_p$

$$= (1 + 1 + \|\mathbf{f}\|_c + \|\mathbf{x}\|_c + (\|\mathbf{f}\|_p \|\mathbf{x}\|_p)_c + \|\mathbf{y}\|_c) +_c \|\mathbf{f}\|_p \|\mathbf{x}\|_p \|\mathbf{y}\|_p$$

$$=(2+\langle 0,f\rangle_c+\langle 0,x\rangle_c+\langle 0,y\rangle_c)+_c\langle 0,f\rangle_p\langle 0,x\rangle_p\langle 0,y\rangle_p$$

$$= (2+0+0+0)+c$$
 (f x y)

$$=\langle 2+((\mathbf{f}\ \mathbf{x})_p\ \mathbf{y})_c,((\mathbf{f}\ \mathbf{x})_p\ \mathbf{y})_p\rangle$$

FIGURE 3. Translation of True \rightarrow Cons $\langle x, Cons \langle y, ys \rangle \rangle$ in the inner rec of insert. In this case the element we are inserting into the list comes before the head of the list under the ordering given by f.

$$||\mathsf{True} \mapsto \mathsf{Cons}\langle \mathsf{x}, \mathsf{Cons}\langle \mathsf{y}, \mathsf{ys}\rangle\rangle||$$

$$=$$
 True $\mapsto 1+_c\| exttt{Cons}\langle exttt{x}, exttt{Cons}\langle exttt{y}, exttt{ys}
angle
angle\|$

$$= \; \texttt{True} \mapsto 1 +_c \langle \| \langle \texttt{x} \, , \texttt{Cons} \langle \texttt{y} \, , \texttt{ys} \rangle \rangle \|_c, \texttt{Cons} \| \langle \texttt{x} \, , \texttt{Cons} \langle \texttt{y} \, , \texttt{ys} \rangle \rangle \|_p \rangle$$

$$= \ \, {\tt True} \mapsto 1 +_c \langle \langle \| {\tt x} \|_c + \| {\tt Cons} \langle {\tt y} \, , {\tt ys} \rangle \|_c, \langle \| {\tt x} \|_p, \| {\tt Cons} \langle {\tt y} \, , {\tt ys} \rangle \|_p \rangle \rangle_c \, , \\ \\ {\tt Cons} \langle \| {\tt x} \|_c + \| {\tt Cons} \langle {\tt y} \, , {\tt ys} \rangle \|_c, \langle \| {\tt x} \|_p, \| {\tt Cons} \langle {\tt y} \, , {\tt ys} \rangle \|_p \rangle \rangle_p \rangle_c \, ,$$

$$= \texttt{True} \mapsto 1 +_c \langle \|\mathbf{x}\|_c + \|\texttt{Cons}\langle \mathbf{y}, \mathbf{ys}\rangle\|_c, \texttt{Cons}\langle \|\mathbf{x}\|_p, \|\texttt{Cons}\langle \mathbf{y}, \mathbf{ys}\rangle\|_p \rangle \rangle$$

$$= \ \, {\tt True} \mapsto 1 +_c \langle 0 + \| \langle {\tt y} \, , {\tt ys} \rangle \|_c \, , {\tt Cons} \langle {\tt x} \, , {\tt Cons} \| \langle {\tt y} \, , {\tt ys} \rangle \|_p \rangle \rangle$$

$$= \ \mathtt{True} \mapsto 1 +_c \langle \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle \rangle_c \, \mathtt{,Cons} \langle \mathtt{x} \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle \rangle_p \rangle \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle \rangle_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c, \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle_c \, \mathtt{,Cons} \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c + \|$$

$$= \ \mathtt{True} \mapsto 1 +_c \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c \, \mathtt{,Cons} \langle \mathtt{x} \, \mathtt{,Cons} \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle \rangle \rangle$$

$$= \ \mathtt{True} \mapsto 1 +_c \langle \langle \mathtt{0} \, \mathtt{,} \, \mathtt{y} \rangle_c + \langle \mathtt{0} \, \mathtt{,} \, \mathtt{ys} \rangle_c \, \mathtt{,Cons} \langle \mathtt{x} \, \mathtt{,Cons} \langle \langle \mathtt{0} \, \mathtt{,} \, \mathtt{y} \rangle_p, \langle \mathtt{0} \, \mathtt{,} \, \mathtt{ys} \rangle_p \rangle \rangle \rangle$$

$$=$$
 True $\mapsto 1+_c\langle 0,\mathtt{Cons}\langle \mathtt{x},\mathtt{Cons}\langle \mathtt{y},\mathtt{ys}
angle
angle
angle}$

DRAFT:
$$T_{AF} \rightarrow \langle f_{1} \in ons \langle x, Cons \langle y, ys \rangle \rangle \rangle$$

FIGURE 4. Translation of the False branch of the inner rec of insert. r stands for the recursive call, and has type susp list. In this case the element we are inserting into the list comes after the head of the list under the ordering given by f.

FIGURE 5. Translation of the inner rec in insert. In the True case, we have found the place of x in the list and we so stop. In the False case, x comes after the head of list under the ordering given by f and we must recurse on the tail of the list.

FIGURE 6. Translation of the Nil branch of the outer rec in insert. The insertion of an element into an empty list results in a singleton list containing only the element. This branch is also reached when the ordering given by f dictates x comes after than everything in the list, and should be placed at the back of the list.

$$\begin{split} &\|\operatorname{Nil}\mapsto\operatorname{Cons}\langle\mathbf{x}\,,\operatorname{Nil}\rangle\|\\ &= \|\operatorname{Nil}\mapsto 1+_c\|\operatorname{Cons}\langle\mathbf{x}\,,\operatorname{Nil}\rangle\|\\ &= \|\operatorname{Nil}\mapsto 1+_c\langle\|\langle\mathbf{x}\,,\operatorname{Nil}\rangle\|_c\,,\operatorname{Cons}\|\langle\mathbf{x}\,,\operatorname{Nil}\rangle\|_p\rangle\\ &= \|\operatorname{Nil}\mapsto 1+_c\langle\langle\|\mathbf{x}\|_c+\|\operatorname{Nil}\|_c,\langle\|\mathbf{x}\|_p,\|\operatorname{Nil}\|_p\rangle\rangle_c\,,\operatorname{Cons}\langle\|\mathbf{x}\|_c+\|\operatorname{Nil}\|_c,\langle\|\mathbf{x}\|_p,\|\operatorname{Nil}\|_p\rangle\rangle_p\rangle\\ &= \|\operatorname{Nil}\mapsto 1+_c\langle\|\mathbf{x}\|_c+\|\operatorname{Nil}\|_c\,,\operatorname{Cons}\langle\|\mathbf{x}\|_p,\|\operatorname{Nil}\|_p\rangle\rangle\\ &= \|\operatorname{Nil}\mapsto 1+_c\langle\langle(0\,,\mathbf{x}\rangle_c+\langle 0\,,\operatorname{Nil}\rangle_c\,,\operatorname{Cons}\langle\langle(0\,,\mathbf{x}\rangle_p,\langle 0\,,\operatorname{Nil}\rangle_p\rangle)\\ &= \|\operatorname{Nil}\mapsto 1+_c\langle(0+0\,,\operatorname{Cons}\langle\mathbf{x}\,,\operatorname{Nil}\rangle)\rangle\\ &= \|\operatorname{Nil}\mapsto\langle 1\,,\operatorname{Cons}\langle\mathbf{x}\,,\operatorname{Nil}\rangle\rangle \end{split}$$

FIGURE 7. Translation of the Cons branch of the outer rec in insert. In this branch we recurse on a nonempty list. We check if x is comes before the head of the list under the ordering given by f, in which case we are done, otherwise we recurse on the tail of the list.

$$\| \mathsf{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle \cdot \mathsf{rec}(\mathtt{f} \ \mathtt{x} \ \mathtt{y}, \ \mathsf{True} \ \mapsto \ \mathsf{Cons}\langle \mathtt{x}, \mathsf{Cons}\langle \mathtt{y}, \mathtt{ys} \rangle \rangle, \\ & \quad \mathsf{False} \ \mapsto \ \mathsf{Cons}\langle \mathtt{y}, \mathsf{force}(\mathtt{r}) \rangle) \| \\ \\ = \ \mathsf{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle \cdot 1 +_c \| \mathsf{rec}(\mathtt{f} \ \mathtt{x} \ \mathtt{y}, \ \mathsf{True} \ \mapsto \ \mathsf{Cons}\langle \mathtt{x}, \mathsf{Cons}\langle \mathtt{y}, \mathtt{ys} \rangle \rangle, \\ & \quad \mathsf{False} \ \mapsto \ \mathsf{Cons}\langle \mathtt{y}, \mathsf{force}(\mathtt{r}) \rangle) \| \\ \\ = \ \mathsf{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle \cdot 1 +_c (2 + ((\mathtt{f} \ \mathtt{x})_p \ \mathtt{y})_c) +_c \mathsf{rec}(((\mathtt{f} \ \mathtt{x})_p \ \mathtt{y})_p, \\ & \quad \mathsf{True} \mapsto \langle 1, \mathsf{Cons}\langle \mathtt{x}, \mathsf{Cons}\langle \mathtt{y}, \mathtt{ys} \rangle \rangle \rangle \\ & \quad \mathsf{False} \mapsto \langle 1 +_{c}, \mathsf{Cons}\langle \mathtt{y}, \mathsf{ys} \rangle \rangle \rangle \\ \\ = \ \mathsf{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle \cdot (3 + ((\mathtt{f} \ \mathtt{x})_p \ \mathtt{y})_c) +_c \mathsf{rec}(((\mathtt{f} \ \mathtt{x})_p \ \mathtt{y})_p, \\ & \quad \mathsf{True} \mapsto \langle 1, \mathsf{Cons}\langle \mathtt{x}, \mathsf{Cons}\langle \mathtt{y}, \mathtt{ys} \rangle \rangle \rangle \\ \\ & \quad \mathsf{False} \mapsto \langle 1 +_{c}, \mathsf{Cons}\langle \mathtt{y}, \mathtt{r}_p \rangle \rangle \rangle) \end{pmatrix}$$

FIGURE 8. Translation of insert

```
\|\text{insert}\| = \|\lambda f.\lambda x.\lambda xs.rec(xs, Nil) \rightarrow Cons(x,Nil),
                                                                                  \mathtt{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle.rec(f x y, True \mapsto \mathtt{Cons} \langle \mathtt{x}, \mathtt{Cons} \langle \mathtt{y}, \mathtt{ys} \rangle \rangle,
                                                                                                                                                                                      False \mapsto Cons\langle y, force(r) \rangle
      =\langle 0, \lambda f. \langle 0, \lambda x. \langle 0, \lambda xs. | rec(xs, Nil) \rightarrow Cons(x,Nil),
                                                                                                \mathtt{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle rec(f x y, \mathtt{True} \mapsto \mathtt{Cons} \langle \mathtt{x}, \mathtt{Cons} \langle \mathtt{y}, \mathtt{math} \rangle
                                                                                                                                                                                                     False \mapsto Cons\langle y, force \rangle
      =\langle {\tt 0} , \lambda {\tt f} . \langle {\tt 0} , \lambda {\tt x} . \langle {\tt 0}, \lambda {\tt xs} . \langle {\tt 0} , {\tt xs} \rangle_c +_c
                                     rec(\langle 0, xs \rangle_p,
                                                    Nil \mapsto \langle 1, Cons\langle x, Nil \rangle \rangle
                                                   \mathtt{Cons} \mapsto \langle \mathtt{y} \, , \langle \mathtt{ys} \, , \mathtt{r} \rangle \rangle \, . \, (3 + ((\langle \mathtt{0} \, , \mathtt{f} \rangle_p \ \mathtt{x})_p \ \mathtt{y})_c) +_c \mathtt{rec} \, (((\langle \mathtt{0} \, , \mathtt{f} \rangle_p \ \mathtt{x})_p \ \mathtt{y})_p \, ,
                                                                                                                                                                                              \mathtt{True} \mapsto \langle 1, \mathtt{Cons} \langle \mathtt{x}, \mathtt{Cons} \langle \mathtt{y}, \mathtt{y} \rangle
                                                                                                                                                                                             \mathtt{False} \mapsto \langle 1 + \mathtt{r}_c, \mathtt{Cons}\langle \mathtt{y}, \mathtt{r}_p \rangle \rangle))
      =\langle 0, \lambda f. \langle 0, \lambda x. \langle 0, \lambda xs. \rangle
                                     rec(xs,
                                                    Nil \mapsto \langle 1, Cons\langle x, Nil \rangle \rangle
                                                    Cons \mapsto \langle y, \langle ys, r \rangle \rangle . (3 + ((f x)_p y)_c) +_c rec((f x)_p y)_p,
                                                                                                                                                                                       \mathtt{True} \mapsto \langle 1, \mathtt{Cons} \langle \mathtt{x}, \mathtt{Cons} \langle \mathtt{y}, \mathtt{ys} \rangle \rangle
                                                                                                                                                                                     \mathtt{False} \mapsto \langle 1 \! + \! \mathtt{r}_c, \mathtt{Cons} \langle \mathtt{y}, \mathtt{r}_p 
angle 
angle ))
```

 $\texttt{False} {\mapsto} \left< 1 {+} \mathtt{r}_c, \mathtt{Cons} \left< \mathtt{y}, \mathtt{r}_p \right> \right>))$

FIGURE 9. The translation of insert $f \times xs$. Unlike before, we do not assume that f, x, xs are variables. They may be expressions with non-zero costs.

$$\| \text{insert f x xs} \| = (1 + \| \text{insert f x} \|_c + \| \text{xs} \|_c) +_c \| \text{insert f x} \|_p \| \text{xs} \|_p$$

$$= (1 + \| \text{insert f x} \|_c + \| \text{xs} \|_c) +_c \| \text{insert f x} \|_p \| \text{xs} \|_p$$

$$= (2 + \| \text{insert f} \|_c + \| \text{x} \|_c + (\| \text{insert f} \|_p \| \text{x} \|_p)_c + \| \text{xs} \|_c) +_c \| \text{insert f} \|_p \| \text{x} \|_p \| \text{xs} \|_p$$

$$= (2 + \| \text{insert f} \|_c + \| \text{x} \|_c + \| \text{xs} \|_c) +_c \| \text{insert f} \|_p \| \text{x} \|_p \| \text{xs} \|_p$$

$$= (3 + \| \text{insert} \|_c + \| \text{f} \|_c + (\| \text{insert} \|_p \| \text{f} \|_p \| \text{x} \|_p)_c + \| \text{xs} \|_c) +_c \| \text{insert} \|_p \| \text{f} \|_p \| \text{x} \|_p \|$$

$$= (3 + \| \text{f} \|_c + \| \text{x} \|_c + \| \text{xs} \|_c) +_c \| \text{insert} \|_p \| \text{f} \|_p \| \text{xs} \|_p$$

$$= (3 + \| \text{f} \|_c + \| \text{x} \|_c + \| \text{xs} \|_c) +_c \| \text{insert} \|_p \| \text{f} \|_p \| \text{xs} \|_p$$

$$= (3 + \| \text{f} \|_c + \| \text{x} \|_c + \| \text{xs} \|_c) +_c \| \text{cons}(\| \text{xs} \|_p , \\ \| \text{Nil} \mapsto \langle 1, \text{Cons}(\text{x}, \text{Nil}) \rangle$$

$$\text{Cons} \mapsto \langle \text{y}, \langle \text{ys}, \text{r} \rangle \rangle \cdot (3 + ((\| \text{f} \|_p \| \text{x} \|_p)_p \ \text{y})_c) +_c \text{rec}((\| \text{f} \|_p \| \text{x} \|_p)_p \ \text{y})_p ,$$

$$\text{True} \mapsto \langle 1, \text{Cons}(\| \text{x} \|_p , \text{Cons}(\text{y}, \text{y})_p)$$

FIGURE 10. Interpretation of lists as lengths

$$[list] = \mathbb{Z} \times \mathbb{N}^{\infty}$$

$$D^{list} = \{*\} + \{\mathbb{Z}\} \times \mathbb{N}^{\infty}$$

$$size_{list}(Nil) = (-\infty, 0)$$

$$size_{list}(Cons(i, (j, n))) = (max\{i, j\}, 1 + n)$$

FIGURE 11. Interpretation of the inner rec of insert with lists abstracted to sizes

$$\begin{split} & \| \mathtt{rec} \, ((\mathbf{f} - \mathbf{x})_p - \mathbf{y})_p \,, \\ & \quad \mathtt{True} \mapsto \langle 1, \mathtt{Cons} \langle \mathbf{x} \,, \mathtt{Cons} \langle \mathbf{y} \,, \mathbf{ys} \rangle \rangle \rangle \\ & \quad \mathtt{False} \mapsto \langle 1 + \mathbf{r}_c, \mathtt{Cons} \langle \mathbf{y} \,, \mathbf{r}_p \rangle \rangle) \,) \, \| \xi \{ \mathbf{f} \mapsto f, \mathbf{x} \mapsto x, \mathbf{y} \mapsto y, \mathbf{ys} \mapsto (i, n), \mathbf{r} \mapsto r \} \\ & \quad f_{True}(\langle \rangle) = \| \langle \mathbf{1} \,, \mathtt{Cons} \langle \mathbf{x} \,, \mathtt{Cons} \langle \mathbf{y} \,, \mathbf{ys} \rangle \rangle \rangle \| \xi \{ \mathbf{f} \mapsto f, \mathbf{x} \mapsto x, \mathbf{y} \mapsto y, \mathbf{ys} \mapsto (i, n), \mathbf{r} \mapsto r \} \\ & \quad = (1, (max\{x, y, i\}, 2 + n)) \\ & \quad f_{False}(\langle \rangle) = \| \langle 1 + \mathbf{r}_c, \mathtt{Cons} \langle \mathbf{y}, \mathbf{r}_p \rangle \rangle) \,) \, \| \xi \{ \mathbf{f} \mapsto f, \mathbf{x} \mapsto x, \mathbf{y} \mapsto y, \mathbf{ys} \mapsto (i, n), \mathbf{r} \mapsto r \} \\ & \quad = (1 + \pi_0 r, (max\{y, \pi_0 \pi_1 r\}, 1 + \pi_1 \pi_1 r)) \\ & \quad = \bigvee_{size(w) \leq \pi_1(\pi_1(f - x) - y)} case(w, (f_{True}, f_{False})) \end{split}$$

$$=\bigvee_{size(w)\leq \pi_{1}(\pi_{1}(f-x)-y)}case(w,(\lambda\langle\rangle.(1,(max\{x,y,i\},2+n)),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}\pi_{1}r\},1+\pi_{1}\pi_{1}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}r\},1+\pi_{0}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}r\},1+\pi_{0}r),\lambda\langle\rangle.(1+\pi_{0}r,(max\{y,\pi_{0}r\},1+\pi_{0}r),\lambda\langle\rangle))$$

$$= (1, (\max\{x,y,i\}, 2+n)) \vee (1+\pi_0 r, (\max\{y, \pi_0 \pi_1 r\}, 1+\pi_1 \pi_1 r))$$

FIGURE 12. Interpretation of rec in insert.

$$g(i,n) = [\texttt{rec}(\texttt{xs}, \\ \texttt{Nil} \mapsto \langle 1, \texttt{Cons}(\texttt{x}, \texttt{Nil}) \rangle \\ \texttt{Cons} \mapsto \langle \texttt{y}, \langle \texttt{ys}, \texttt{r} \rangle \rangle \cdot (3 + ((\texttt{f} \ \texttt{x})_p \ \texttt{y})_c) +_c \texttt{rec}((\texttt{f} \ \texttt{x})_p \ \texttt{y})_p, \\ \texttt{True} \mapsto \langle 1, \texttt{Cons}(\texttt{x}, \texttt{Cons}(\texttt{y}, \texttt{ys})) \rangle] \\ \texttt{False} \mapsto \langle 1 + \texttt{r}_c, \texttt{Cons}(\texttt{y}, \texttt{ys}) \rangle)] \\ \texttt{f} \mapsto f, \texttt{x} \mapsto (1 + \texttt{rec}(\texttt{y}, \texttt{ys})))] \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{rec}(\texttt{y}, \texttt{ys}))) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto f, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{g} \mapsto (1 + \texttt{y}, \texttt{ys})) \\ \texttt{f} \mapsto f, \texttt{g} \mapsto$$

FIGURE 13. Translation of Nil branch of sort.

$$\|\mathtt{Nil} \mapsto \mathtt{Nil}\|$$

$$=$$
Nil \mapsto 1 + $_c$ $\|$ Nil $\|$

$$=$$
Nil $\mapsto 1+_c\langle 0$,Nil \rangle

$$=$$
Nil \mapsto \langle 1,Nil \rangle

FIGURE 14. Translation of Cons branch of sort.

$$\|\mathtt{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle$$
.insert f y force(r)

$$=$$
Cons $\mapsto 1+_c\|$ insert f y force(r) $\|$

$$= \mathtt{Cons} \mapsto \langle \mathtt{y} \, , \langle \mathtt{ys} \, , \mathtt{r} \rangle \rangle . 1 +_c (\| \mathtt{force} \, (\mathtt{r}) \, \|_c) +_c \| \mathtt{insert} \ \ \mathtt{f} \ \ \mathtt{y} \|_p \| \mathtt{force} \, (\mathtt{r}) \, \|_p$$

$$= \text{Cons} \mapsto \langle \text{y}, \langle \text{ys}, \text{r} \rangle \rangle . 1 +_c \text{r}_c +_c \| \text{insert f y} \|_p \text{r}_p$$

$$= \text{Cons} \mapsto \langle \text{y}, \langle \text{ys}, \text{r} \rangle \rangle . 1 +_c \text{r}_c +_c 3 +_c \| \text{insert} \|_p \text{ f y r}_p$$

$$= Cons \mapsto \langle y, \langle ys, r \rangle \rangle . (4+r_c) +_c \|insert\|_p \text{ f } y \text{ r}_p$$

FIGURE 15. Translation of sort

$$\|\mathtt{sort}\| \ = \ \langle 0, \lambda \mathtt{f} \, . \, \langle 0, \lambda \mathtt{xs} \, . \, \|\mathtt{rec}(\mathtt{xs} \, , \, \, \mathtt{Nil} \mapsto \, \mathtt{Nil} \, ,$$

$$\mathtt{Cons} \mapsto \langle \mathtt{y} \, , \langle \mathtt{ys} \, , \mathtt{r} \rangle \rangle \, . \, \mathtt{insert} \ \ \mathtt{f} \ \ \mathtt{y} \ \ \mathtt{force}(\mathtt{r})) \, \| \rangle \rangle$$

=
$$\langle 0, \lambda {\tt f.} \langle 0, \lambda {\tt xs.rec(xs, Nil} \mapsto \langle {\tt 1,Nil} \rangle$$

 ${\tt Cons} \mapsto \langle {\tt y, \langle ys,r} \rangle \rangle.4 +_c {\tt r}_c +_c \| {\tt insert} \|_p \ {\tt f.y.r}_p \|_p$

FIGURE 16. Translation of sort applied to variables f and xs

$$\begin{split} \| \mathtt{sort} \ \ \mathbf{f} \ \ & \mathtt{xs} \| = (1 + \| \mathtt{sort} \ \ \mathbf{f} \|_c + \| \mathtt{xs} \|_c) +_c \| \mathtt{sort} \ \ \mathbf{f} \|_p \| \mathtt{xs} \|_p \\ \\ & = (1 + (1 + \| \mathtt{sort} \|_c + \| \mathbf{f} \|_c + \| \mathtt{xs} \|_c)) +_c \| \mathtt{sort} \|_p \| \mathbf{f} \|_p \| \mathtt{xs} \|_p \\ \\ & = (1 + (1 + 0 + 0 + 0)) +_c \| \mathtt{sort} \|_p \| \mathbf{f} \|_p \| \mathtt{xs} \|_p \\ \\ & = 2 +_c \| \mathtt{sort} \|_p \mathbf{f} \|_p \| \mathtt{xs} \|_p \end{split}$$

$$= 2 +_c \texttt{rec} \, (\|\texttt{xs}\|_p \,, \, \, \texttt{Nil} \mapsto \langle \texttt{1} \,, \texttt{Nil} \rangle$$

$$\texttt{Cons} \mapsto \langle \texttt{y} \,, \langle \texttt{ys} \,, \texttt{r} \rangle \rangle. (4 + \texttt{r}_c) +_c \|\texttt{insert}\|_p \ \, \texttt{f} \ \, \texttt{y} \ \, \texttt{r}_p \|$$

FIGURE 17. Interpretation of rec in sort. TO DO FIX THIS

CHAPTER 6

Insertion Sort

Insertion sort is a quadratic time sorting algorithm which sorts a list by inserting an element from an unsorted segment of a container into a sorted segment of the container. Although the asymptotic complexity of insertion sort is less than the optimal $\mathcal{O}(nlog_2n)$, insertion sort does have redeeming attributes. Insertion sort has small constant factors, making it more efficient on small datasets. The standard Python sorting algorithm, timsort, is a hybrid sorting algorithm that uses mergesort and switches to insertion sort for small datasets (?). Insertion sort may be done in-place (Cormen et al. [2001]). The running time of insertion sort is $\mathcal{O}(n^2)$.

- **0.1.** Insert. sort relies on the function insert to insert the head of the list into the result of recursively sorted tail of the list. We will begin with a translation and interpretation of insert.
- 0.1.1. Translation. The translation of insert is broken into chunks to make it more managable. Figure 2 steps through the translation of the comparison function <= applied to variables x and y.

The translation true and false branches are given in figures 3 and 4 respectively.

Figure 5 uses the translation of f x y and the true and false branches to construct the translation of the inner rec construct.

The Nil and Cons branches of the outer rec construct are given in figures 6 and 7, respectively.

We put these together to give the translation of insert.

Finally we give a translation of insert $f \times xs$ in figure 9 because this is the term we will interpret in a size-based semantics.

The result is:

$$\|\text{insert f x xs}\| = (3 + \|\mathbf{f}\|_c + \|\mathbf{x}\|_c + \|\mathbf{xs}\|_c) \\ +_c \operatorname{rec}(\|\mathbf{xs}\|_p, \\ \operatorname{Nil} \mapsto \langle 1, \operatorname{Cons}\langle \mathbf{x}, \operatorname{Nil} \rangle \rangle \\ \operatorname{Cons} \mapsto \langle \mathbf{y}, \langle \mathbf{ys}, \mathbf{r} \rangle \rangle \cdot (3 + ((\|\mathbf{f}\|_p \|\mathbf{x}\|_p)_p \ \mathbf{y})_c) +_c \operatorname{rec}((\|\mathbf{f}\|_p \|\mathbf{x}\|_p)_p \ \mathbf{y})_p, \\ \operatorname{True} \mapsto \langle 1, \operatorname{Cons}\langle \|\mathbf{x}\|_p, \operatorname{Cons}\langle \mathbf{y}, \mathbf{y}, \mathbf{y} \rangle \rangle) \right\|$$

0.1.2. *Interpretation*. We well use an interpretation of lists as their lengths. Figure 10 gives formalizes this interpretation.

First we interpret the rec, which drives of the cost of insert. As in the translation, we break the interpretation up to make it more managable. We will write map, λ and $+_c$ in the semantics, which stand for the semantic equivalents of map, λ and $+_c$ in the syntax. The definitions of these semantic functions mirror the definitions of their syntactic equivalents. Figures 11 and 12 walk through the interpretation.

The initial result is given in equation 8.

(6)
$$f_{Nil}(\langle \rangle) = (1,1)$$

(7)
$$f_{Cons}((1,m)) = (4 + \pi_0(\pi_1(f \ 1) \ 1) + \pi_0 g(m), (2+m) \lor (1+\pi_1 g(m)))$$

(8)
$$g(n) = \bigvee_{size(z) \le n} case(z, (f_{Nil}, f_{Cons}))$$

This recurrence is difficult to work with. Specifically, we cannot apply traditional methods of solving it. We will manipulate it into a more usable form by eliminating the DRAFT: April 7, 2016

arbitrary maximum. Observe that for $n=0, g(n)=f_{Nil}(\langle \rangle)=(1,1)$. For n>0,

$$\begin{split} g(n) &= \bigvee_{size(z) \leq n} case(z, (f_{Nil}, f_{Cons})) \\ &= g(n-1) \vee \bigvee_{size(z) = n} case(z, (f_{Nil}, f_{Cons})) \\ &= g(n-1) \vee f_{Cons}(n) \\ &= g(n-1) \vee (4 + \pi_0(\pi_1(f\ 1)\ 1) + \pi_0 g(n-1), (1+n) \vee (1+\pi_1 g(n-1))) \quad m = n-1 \\ &= (4 + \pi_0(\pi_1(f\ 1)\ 1) + \pi_0 g(n-1), (1+n) \vee (1+\pi_1 g(n-1))) \quad \text{lemma } 0.6 \\ &= (4 + \pi_0(\pi_1(f\ 1)\ 1) + \pi_0 g(n-1), 1+\pi_1 g(n-1)) \quad \text{lemma } 0.7 \end{split}$$

LEMMA 0.6. q(n) > q(n-1)

LEMMA 0.7. $\pi_1 g(n) > n$

PROOF. We prove this by induction on n.

case
$$n = 0$$
:: $\pi_1 g(0) = 1$
case $n > 0$::

$$\pi_1 g(n) = \pi_1 (g(n-1) \vee (4 + \pi_0(\pi_1(f \ 1) \ 1) + \pi_0 g(n-1), (1+n) \vee (1 + \pi_1 g(n-1))))$$

$$= \pi_1 g(n-1) \vee (1+n) \vee (1 + \pi_1 g(n-1))$$

$$\geq n - 1 \vee (1+n) \vee (1+n-1)$$

$$\geq 1 + n$$

$$> n$$

Equation 9 shows the extracted recurrence. Without the arbitrary maximum, it is much more obvious how to find a solution to the recurrence. The recurrence is from a potential to a complexity, consequently we can extract a recurrence for the cost, equation 10, and a recurrence for the potential, equation 11, simply by taking the projections of DRAFT: April 7, 2016

equation 9. The extracted recurrences for the cost and potential can then be solved by the substitution method.

(9)
$$g(n) = \begin{cases} (1,1) & n = 0\\ (4 + \pi_0(\pi_1(f \ 1) \ 1) + \pi_0 g(n-1), 1 + \pi_1 g(n-1)) & n > 0 \end{cases}$$

The cost recurrence is given by $\pi_0 \circ g$.

(10)
$$c(n) = \begin{cases} 1 & n = 0 \\ 4 + \pi_0(\pi_1(f \ 1) \ 1) + c(n-1) & n > 0 \end{cases}$$

This recurrence is quite simple to solve. The solution and proof of the solution are given in theorem 0.8.

THEOREM 0.8.
$$c(n) = (4 + \pi_0(\pi_1(f \ 1) \ 1))n + 1$$

PROOF. We prove this by induction on n.

case
$$n = 0$$
: $c(0) = \pi_0 g(0) = 1$

case n > 0:

$$c(n) = 4 + \pi_0(\pi_1(f \ 1) \ 1) + c(n-1)$$

$$= 4 + \pi_0(\pi_1(f \ 1) \ 1) + (4 + \pi_0(\pi_1(f \ 1) \ 1))(n-1) + 1$$

$$= (4 + \pi_0(\pi_1(f \ 1) \ 1))n + 1$$

The solution tells us the cost of the rec construct in insert is linear in the size of the list. The constant factor cannot be determined because we do not know the cost of applying f to its arguments.

The potential recurrence is given by $\pi_1 \circ g$.

(11)
$$p(n) = \begin{cases} 1 & n = 0 \\ 1 + p(n-1) & n > 0 \end{cases}$$

THEOREM 0.9. p(n) = 1 + n

PROOF. We prove this by induction on n.

DRAFT: April 7, 2016

case
$$n = 0$$
: $p(0) = 1$

case
$$n > 0$$
: $p(n) = 1 + p(n-1) = 1 + n$

The solution of this recurrence tells us the size of the output in terms of the size of the input. As one would expect of insert, the size of the output is one larger than the size of the input.

0.2. Sort.

- 0.2.1. Translation. The translation of sort is shown in figure 15. The translation of the Nil and Cons branches in the rec are walked through in figures 13 and 14, respectively. The translation of sort applied to its arguments is given in figure 16.
- 0.2.2. Interpretation. The rec construct again drives the cost and potential of sort. The walkthrough of the interpretation of the rec is given in figure 17. Equation 12 shows the initial recurrence extracted.

$$(12) \quad g(n) = \bigvee_{size(z) \le n} case(z, (\lambda(\langle \rangle).(1,0), \lambda(1,m).4 + \pi_0 g(m)) +_c insert \ f \ 1 \ \pi_1 g(m))$$

We work the recurrence into a more recognisable form using some manipulation of the big max operator and some facts about *insert*. Observe for n = 0, g(n) = (1,0)and for n > 0

$$\begin{split} g(n) &= \bigvee_{size(z) \leq n} case(z, (\lambda(\langle \rangle).(1,0), \lambda(1,m).4 + \pi_0 g(m)) +_c insert \ f \ 1 \ \pi_1 g(m)) \\ &= g(n-1) \lor \bigvee_{size(z) = n} case(z, (\lambda(\langle \rangle).(1,0), \lambda(1,m).4 + \pi_0 g(m)) +_c insert \ f \ 1 \ \pi_1 g(m)) \\ &= g(n-1) \lor (4 + \pi_0 g(n-1)) +_c insert \ f \ 1 \ \pi_1 g(n-1) \\ &= g(n-1) \lor (4 + \pi_0 g(n-1) + \pi_0 (insert \ f \ 1 \ \pi_1 g(n-1)), \pi_1 (insert \ f \ 1 \ \pi_1 g(n-1))) \\ &\text{since } \pi_0 (insert \ f \ 1 \ m) > 0 \ \text{and} \ \pi_1 (insert \ f \ 1 \ m) = 1 + m \\ &= (4 + \pi_0 g(n-1) + \pi_0 (insert \ f \ 1 \ \pi_1 g(n-1)), \pi_1 (insert \ f \ 1 \ \pi_1 g(n-1))) \end{split}$$

DRAFT: April 7, 2016

So our simplified recurrence is

(13)
$$g(n) = \begin{cases} (1,0) & n = 0\\ (4 + \pi_0 g(n-1) + \pi_0 (insert \ f \ 1 \ \pi_1 g(n-1)), \pi_1 (insert \ f \ 1 \ \pi_1 g(n-1))) & n > 0 \end{cases}$$

From this we can extract recurrences for the cost and the potential simply by taking projections from g. We begin with the potential because we will require the solution to the potential recurrence to solve the cost recurrence.

Let $p = \pi_1 \circ g$.

(14)
$$p(n) = \begin{cases} 0 & n = 0\\ \pi_1(insert \ f \ 1 \ \pi_1 g(n-1))) & n > 0 \end{cases}$$

We prove the size of the potential of the output is same as the size of the input. In other words, sort does not change the size of the list.

Theorem 0.10. p(n) = n

PROOF. We prove this by straightforward induction on n.

case
$$n = 0$$
: $p(0) = 0$

case
$$n > 0$$
: $p(n) = \pi_1(insert \ f \ 1 \ pi_g(n-1)) = \pi_1(insert \ f \ 1 \ (n-1)) = n$

Let $c = \pi_0 \circ g$.

(15)
$$c(n) = \begin{cases} 1 & n = 0 \\ 4 + \pi_0 g(n-1) + \pi_0 (insert \ f \ 1 \ \pi_1 g(n-1) & n > 0 \end{cases}$$

THEOREM 0.11.

PROOF. We prove this by straightforward induction on n.

case
$$n = 0$$
:: $c(0) = 1$

DRAFT: April 7, 2016

case n > 0::

$$c(n) = 4 + \pi_0 g(n-1) + \pi_0 (insert \ f \ 1 \ \pi_1 g(n-1))$$

$$= 4 + \pi_0 g(n-1) + \pi_0 (insert \ f \ 1 \ (n-1))$$

$$= 4 + (4 + \pi_0 (\pi_1 (f \ 1) \ 1))(n-1) + 1) + \pi_0 g(n-1)$$

TODO COMPLETE

FIGURE 1. Insertion sort in the source language

data list = Nil of unit | Cons of int \times list

insert = $\lambda x . \lambda xs. rec(xs, Nil \rightarrow Cons(x,Nil),$

False \mapsto Cons $\langle y, force(r) \rangle$

 $\texttt{sort} \ = \ \lambda \texttt{xs.rec(xs, Nil} \mapsto \ \texttt{Nil, Cons} \mapsto \langle \texttt{y, \langle ys, r \rangle} \rangle. \ \texttt{insert y force(r))}$

FIGURE 2. Translation of $x \le y$. We assume x and y are variables. Consequently the cost of the translation of both is 0. We assume \le is a function with a constant cost of 2. Since \le is a function of two arguments, the cost of \le is 0 unless \le is fully applied.

$$\begin{aligned} \|\mathbf{x} &<= \mathbf{y}\| = (2 + \|\mathbf{x}\|_c + \|\mathbf{y}\|_c) +_c \|\mathbf{x}\|_p &<= \|\mathbf{y}\|_p \\ &= \langle 2 +_c (\mathbf{x} <= \mathbf{y}) \rangle \\ &= \langle \langle 4, (\mathbf{x} <= \mathbf{y})_p \rangle \end{aligned}$$

FIGURE 3. Translation of True \rightarrow Cons $\langle x, Cons \langle y, ys \rangle \rangle$ in the inner rec of insert. In this case the element we are inserting into the list comes before the head of the list under the ordering given by f.

$$=$$
 True $\mapsto 1 +_c \| \mathtt{Cons} \langle \mathtt{x} \, , \mathtt{Cons} \langle \mathtt{y} \, , \mathtt{ys} \rangle \rangle \|$

$$= \text{True} \mapsto 1 +_c \langle \| \langle \texttt{x}, \texttt{Cons} \langle \texttt{y}, \texttt{ys} \rangle \rangle \|_c, \texttt{Cons} \| \langle \texttt{x}, \texttt{Cons} \langle \texttt{y}, \texttt{ys} \rangle \rangle \|_p \rangle$$

$$= \text{True} \mapsto 1 +_c \langle \langle \| \mathbf{x} \|_c + \| \text{Cons} \langle \mathbf{y}, \mathbf{ys} \rangle \|_c, \langle \| \mathbf{x} \|_p, \| \text{Cons} \langle \mathbf{y}, \mathbf{ys} \rangle \|_p \rangle \rangle_c,$$

$$\text{Cons} \langle \| \mathbf{x} \|_c + \| \text{Cons} \langle \mathbf{y}, \mathbf{ys} \rangle \|_c, \langle \| \mathbf{x} \|_p, \| \text{Cons} \langle \mathbf{y}, \mathbf{ys} \rangle \|_p \rangle \rangle_p \rangle$$

$$= \texttt{True} \mapsto 1 +_c \langle \|\mathbf{x}\|_c + \|\texttt{Cons}\langle \mathbf{y}, \mathbf{ys}\rangle\|_c, \texttt{Cons}\langle \|\mathbf{x}\|_p, \|\texttt{Cons}\langle \mathbf{y}, \mathbf{ys}\rangle\|_p \rangle \rangle$$

$$= \text{True} \mapsto 1 +_c \langle \langle \texttt{0}, \texttt{x} \rangle_c + \langle \| \langle \texttt{y}, \texttt{ys} \rangle \|_c, \texttt{Cons} \| \langle \texttt{y}, \texttt{ys} \rangle \|_p \rangle_c,$$

$$\texttt{Cons} \langle \langle \texttt{0}, \texttt{x} \rangle_p, \langle \| \langle \texttt{y}, \texttt{ys} \rangle \|_c, \texttt{Cons} \| \langle \texttt{y}, \texttt{ys} \rangle \|_p \rangle_p \rangle \rangle$$

$$=$$
 True $\mapsto 1+_c\langle 0+\|\langle { t y},{ t y}{ t s}
angle\|_c$, Cons $\langle { t x}$, Cons $\|\langle { t y},{ t y}{ t s}
angle\|_p
angle
angle$

$$= \ \mathtt{True} \mapsto 1 +_c \langle \| \mathtt{y} \|_c + \| \mathtt{ys} \|_c \, \mathtt{,Cons} \langle \mathtt{x} \, \mathtt{,Cons} \langle \| \mathtt{y} \|_p, \| \mathtt{ys} \|_p \rangle \rangle \rangle$$

$$= \ \, {\tt True} \mapsto 1 +_c \langle \langle {\tt 0} \, , {\tt y} \rangle_c + \langle {\tt 0} \, , {\tt ys} \rangle_c \, , {\tt Cons} \langle {\tt x} \, , {\tt Cons} \langle \langle {\tt 0} \, , {\tt y} \rangle_p, \langle {\tt 0} \, , {\tt ys} \rangle_p \rangle \rangle \rangle$$

$$=$$
 True $\mapsto 1 +_c \langle 0, \mathtt{Cons}\langle \mathtt{x}, \mathtt{Cons}\langle \mathtt{y}, \mathtt{ys} \rangle \rangle \rangle$

$$=$$
 True $\mapsto \langle 1, \mathtt{Cons}\langle \mathtt{x}, \mathtt{Cons}\langle \mathtt{y}, \mathtt{ys}\rangle\rangle\rangle$

DRAFT: April 7, 2016

FIGURE 4. Translation of the False branch of the inner rec of insert. r stands for the recursive call, and has type susp list. In this case the element we are inserting into the list comes after the head of the list under the ordering given by f.

FIGURE 5. Translation of the inner rec in insert. In the True case, we have found the place of x in the list and we so stop. In the False case, x comes after the head of list under the ordering given by f and we must recurse on the tail of the list.

FIGURE 6. Translation of the Nil branch of the outer rec in insert. The insertion of an element into an empty list results in a singleton list containing only the element. This branch is also reached when the ordering given by f dictates x comes after than everything in the list, and should be placed at the back of the list.

$$\begin{split} &\|\operatorname{Nil}\mapsto\operatorname{Cons}\langle\mathbf{x}\,,\operatorname{Nil}\rangle\|\\ &= \|\operatorname{Nil}\mapsto 1+_c\|\operatorname{Cons}\langle\mathbf{x}\,,\operatorname{Nil}\rangle\|\\ &= \|\operatorname{Nil}\mapsto 1+_c\langle\|\langle\mathbf{x}\,,\operatorname{Nil}\rangle\|_c\,,\operatorname{Cons}\|\langle\mathbf{x}\,,\operatorname{Nil}\rangle\|_p\rangle\\ &= \|\operatorname{Nil}\mapsto 1+_c\langle\langle\|\mathbf{x}\|_c+\|\operatorname{Nil}\|_c,\langle\|\mathbf{x}\|_p,\|\operatorname{Nil}\|_p\rangle\rangle_c\,,\operatorname{Cons}\langle\|\mathbf{x}\|_c+\|\operatorname{Nil}\|_c,\langle\|\mathbf{x}\|_p,\|\operatorname{Nil}\|_p\rangle\rangle_p\rangle\\ &= \|\operatorname{Nil}\mapsto 1+_c\langle\|\mathbf{x}\|_c+\|\operatorname{Nil}\|_c\,,\operatorname{Cons}\langle\|\mathbf{x}\|_p,\|\operatorname{Nil}\|_p\rangle\rangle\\ &= \|\operatorname{Nil}\mapsto 1+_c\langle\langle(0\,,\mathbf{x}\rangle_c+\langle 0\,,\operatorname{Nil}\rangle_c\,,\operatorname{Cons}\langle\langle 0\,,\mathbf{x}\rangle_p,\langle 0\,,\operatorname{Nil}\rangle_p\rangle\rangle\\ &= \|\operatorname{Nil}\mapsto 1+_c\langle(0\,+0\,,\operatorname{Cons}\langle\mathbf{x}\,,\operatorname{Nil}\rangle\rangle)\\ &= \|\operatorname{Nil}\mapsto\langle 1\,,\operatorname{Cons}\langle\mathbf{x}\,,\operatorname{Nil}\rangle\rangle \end{split}$$

FIGURE 7. Translation of the Cons branch of the outer rec in insert. In this branch we are recursing on a nonempty list. We check if x is comes before the head of the list under the ordering given by f, in which case we are done, otherwise we recurse on the tail of the list.

$$\| \mathsf{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle \cdot \mathsf{rec}(\mathtt{f} \ \mathtt{x} \ \mathtt{y}, \ \mathsf{True} \ \mapsto \ \mathsf{Cons}\langle \mathtt{x}, \mathsf{Cons}\langle \mathtt{y}, \mathtt{ys} \rangle \rangle, \\ & \quad \mathsf{False} \ \mapsto \ \mathsf{Cons}\langle \mathtt{y}, \mathsf{force}(\mathtt{r}) \rangle) \| \\ \\ = \ \mathsf{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle \cdot 1 +_c \| \mathsf{rec}(\mathtt{f} \ \mathtt{x} \ \mathtt{y}, \ \mathsf{True} \ \mapsto \ \mathsf{Cons}\langle \mathtt{x}, \mathsf{Cons}\langle \mathtt{y}, \mathtt{ys} \rangle \rangle, \\ & \quad \mathsf{False} \ \mapsto \ \mathsf{Cons}\langle \mathtt{y}, \mathsf{force}(\mathtt{r}) \rangle) \| \\ \\ = \ \mathsf{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle \cdot 1 +_c (2 + ((\mathtt{f} \ \mathtt{x})_p \ \mathtt{y})_c) +_c \mathsf{rec}(((\mathtt{f} \ \mathtt{x})_p \ \mathtt{y})_p, \\ & \quad \mathsf{True} \mapsto \langle 1, \mathsf{Cons}\langle \mathtt{x}, \mathsf{Cons}\langle \mathtt{y}, \mathtt{ys} \rangle \rangle \rangle \\ & \quad \mathsf{False} \mapsto \langle 1 +_{c}, \mathsf{Cons}\langle \mathtt{y}, \mathsf{ys} \rangle \rangle \rangle \\ \\ = \ \mathsf{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle \cdot (3 + ((\mathtt{f} \ \mathtt{x})_p \ \mathtt{y})_c) +_c \mathsf{rec}(((\mathtt{f} \ \mathtt{x})_p \ \mathtt{y})_p, \\ & \quad \mathsf{True} \mapsto \langle 1, \mathsf{Cons}\langle \mathtt{x}, \mathsf{Cons}\langle \mathtt{y}, \mathtt{ys} \rangle \rangle \rangle \\ \\ & \quad \mathsf{False} \mapsto \langle 1 +_{c}, \mathsf{Cons}\langle \mathtt{y}, \mathtt{r}_p \rangle \rangle \rangle) \end{pmatrix}$$

FIGURE 8. Translation of insert

```
\|\text{insert}\| = \|\lambda f.\lambda x.\lambda xs.rec(xs, Nil) \rightarrow Cons(x,Nil),
                                                                                   \mathtt{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle.rec(f x y, True \mapsto \mathtt{Cons} \langle \mathtt{x}, \mathtt{Cons} \langle \mathtt{y}, \mathtt{ys} \rangle \rangle,
                                                                                                                                                                                         False \mapsto Cons\langle y, force(r) \rangle
       =\langle 0, \lambda f. \langle 0, \lambda x. \langle 0, \lambda xs. | rec(xs, Nil) \rightarrow Cons(x,Nil),
                                                                                                  \mathtt{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle rec(f x y, \mathtt{True} \mapsto \mathtt{Cons} \langle \mathtt{x}, \mathtt{Cons} \langle \mathtt{y}, \mathtt{math} \rangle
                                                                                                                                                                                                        False \mapsto Cons\langle y, force \rangle
       =\langle {\tt 0} , \lambda {\tt f} . \langle {\tt 0} , \lambda {\tt x} . \langle {\tt 0}, \lambda {\tt xs} . \langle {\tt 0} , {\tt xs} \rangle_c +_c
                                     rec(\langle 0, xs \rangle_p,
                                                    Nil \mapsto \langle 1, Cons\langle x, Nil \rangle \rangle
                                                    \mathtt{Cons} \mapsto \langle \mathtt{y} \, , \langle \mathtt{ys} \, , \mathtt{r} \rangle \rangle \, . \, (3 + ((\langle \mathtt{0} \, , \mathtt{f} \rangle_p \ \mathtt{x})_p \ \mathtt{y})_c) +_c \mathtt{rec} \, (((\langle \mathtt{0} \, , \mathtt{f} \rangle_p \ \mathtt{x})_p \ \mathtt{y})_p \, ,
                                                                                                                                                                                                \mathtt{True} \mapsto \langle 1, \mathtt{Cons} \langle \mathtt{x}, \mathtt{Cons} \langle \mathtt{y}, \mathtt{y} \rangle
                                                                                                                                                                                                \mathtt{False} \mapsto \langle 1 + \mathtt{r}_c, \mathtt{Cons}\langle \mathtt{y}, \mathtt{r}_p \rangle \rangle))
       =\langle {\tt 0}\,,\lambda {\tt f}\,.\langle {\tt 0}\,,\lambda {\tt x}\,.\langle 0,\lambda {\tt xs}\,.
                                     rec(xs,
                                                     Nil \mapsto \langle 1, Cons\langle x, Nil \rangle \rangle
                                                    Cons \mapsto \langle y, \langle ys, r \rangle \rangle . (3 + ((f x)_p y)_c) +_c rec((f x)_p y)_p,
                                                                                                                                                                                         \mathtt{True} \mapsto \langle 1, \mathtt{Cons} \langle \mathtt{x}, \mathtt{Cons} \langle \mathtt{y}, \mathtt{ys} \rangle \rangle
                                                                                                                                                                                        \mathtt{False} \mapsto \langle 1 \! + \! \mathtt{r}_c, \mathtt{Cons} \langle \mathtt{y}, \mathtt{r}_p 
angle 
angle ))
```

 $\texttt{False} {\mapsto} \left< 1 {+} \mathtt{r}_c, \mathtt{Cons} \left< \mathtt{y}, \mathtt{r}_p \right> \right>))$

FIGURE 9. The translation of insert $f \times xs$. Unlike before, we do not assume that f, x, xs are variables. They may be expressions with non-zero costs.

$$\| \text{insert f x xs} \| = (1 + \| \text{insert f x} \|_c + \| \text{xs} \|_c) +_c \| \text{insert f x} \|_p \| \text{xs} \|_p$$

$$= (1 + \| \text{insert f x} \|_c + \| \text{xs} \|_c) +_c \| \text{insert f x} \|_p \| \text{xs} \|_p$$

$$= (2 + \| \text{insert f} \|_c + \| \text{x} \|_c + (\| \text{insert f} \|_p \| \text{x} \|_p)_c + \| \text{xs} \|_c) +_c \| \text{insert f} \|_p \| \text{x} \|_p \| \text{xs} \|_p$$

$$= (2 + \| \text{insert f} \|_c + \| \text{x} \|_c + \| \text{xs} \|_c) +_c \| \text{insert f} \|_p \| \text{x} \|_p \| \text{xs} \|_p$$

$$= (3 + \| \text{insert} \|_c + \| \text{f} \|_c + (\| \text{insert} \|_p \| \text{f} \|_p \| \text{x} \|_p)_c + \| \text{xs} \|_c) +_c \| \text{insert} \|_p \| \text{f} \|_p \| \text{x} \|_p \|$$

$$= (3 + \| \text{f} \|_c + \| \text{x} \|_c + \| \text{xs} \|_c) +_c \| \text{insert} \|_p \| \text{f} \|_p \| \text{xs} \|_p$$

$$= (3 + \| \text{f} \|_c + \| \text{x} \|_c + \| \text{xs} \|_c) +_c \| \text{insert} \|_p \| \text{f} \|_p \| \text{xs} \|_p$$

$$= (3 + \| \text{f} \|_c + \| \text{x} \|_c + \| \text{xs} \|_c) +_c \| \text{cons}(\| \text{xs} \|_p , \\ \| \text{Nil} \mapsto \langle 1, \text{Cons}(\text{x}, \text{Nil}) \rangle$$

$$\text{Cons} \mapsto \langle \text{y}, \langle \text{ys}, \text{r} \rangle \rangle \cdot (3 + ((\| \text{f} \|_p \| \text{x} \|_p)_p \ \text{y})_c) +_c \text{rec}((\| \text{f} \|_p \| \text{x} \|_p)_p \ \text{y})_p ,$$

$$\text{True} \mapsto \langle 1, \text{Cons}(\| \text{x} \|_p , \text{Cons}(\text{y}, \text{y})_p)$$

FIGURE 10. Interpretation of lists as lengths

$$[list] = \mathbb{N}^{\infty}$$

$$D^{list} = \{*\} + \{1\} \times \mathbb{N}^{\infty}$$

$$size_{list}(Nil) = 0$$

$$size_{list}(Cons(1, n)) = 1 + n$$

FIGURE 11. Interpretation of the inner rec of insert with lists abstracted to sizes

$$\begin{split} & \| \mathtt{rec} \, ((\mathbf{f} - \mathbf{x})_p - \mathbf{y})_p \,, \\ & \quad \mathtt{True} \mapsto \langle 1, \mathtt{Cons} \, \langle \mathbf{x} \,, \mathtt{Cons} \, \langle \mathbf{y} \,, \mathbf{ys} \rangle \rangle \rangle \\ & \quad \mathtt{False} \mapsto \langle 1 + \mathbf{r}_c, \mathtt{Cons} \, \langle \mathbf{y} \,, \mathbf{r}_p \rangle \rangle) \,) \, \| \xi \{ \mathbf{f} \mapsto f, \mathbf{x} \mapsto 1, \mathbf{y} \mapsto 1, \mathbf{ys} \mapsto n, \mathbf{r} \mapsto r \} \\ & \quad f_{True}(\langle \rangle) = \| \langle 1 \,, \mathtt{Cons} \, \langle \mathbf{x} \,, \mathtt{Cons} \, \langle \mathbf{y} \,, \, \mathbf{ys} \rangle \rangle \rangle \| \xi \{ \mathbf{f} \mapsto f, \mathbf{x} \mapsto 1, \mathbf{y} \mapsto 1, \mathbf{ys} \mapsto n, \mathbf{r} \mapsto r \} \\ & \quad = (1, 2 + n) \\ & \quad f_{False}(\langle \rangle) = \| \langle 1 + \mathbf{r}_c, \mathtt{Cons} \, \langle \mathbf{y}, \mathbf{r}_p \rangle \rangle) \,) \, \| \xi \{ \mathbf{f} \mapsto f, \mathbf{x} \mapsto 1, \mathbf{y} \mapsto 1, \mathbf{ys} \mapsto n, \mathbf{r} \mapsto r \} \\ & \quad = (1 + \pi_0 r, 1 + \pi_1 r) \\ & \quad = \langle 1 + \pi_0 r, 1 + \pi_1 r \rangle \\ & \quad = \langle 1 + \pi_0 r, 1 + \pi_1 r, r \rangle \\ & \quad = \langle 1, 2 + n, r \rangle \vee (1 + \pi_0 r, 1 + \pi_1 r) \\ & \quad = (1, 2 + n) \vee (1 + \pi_0 r, 1 + \pi_1 r) \end{split}$$

FIGURE 12. Interpretation of rec in insert.

FIGURE 13. Translation of Nil branch of sort.

$$\|\mathtt{Nil} \mapsto \mathtt{Nil}\|$$

$$=$$
Nil \mapsto 1 + $_c$ $\|$ Nil $\|$

$$=$$
Nil $\mapsto 1+_c\langle \texttt{O,NiL} \rangle$

$$=$$
Nil $\mapsto \langle 1, NiL \rangle$

FIGURE 14. Translation of Nil branch of sort.

$$\|\mathtt{Cons} \mapsto \langle \mathtt{y}, \langle \mathtt{ys}, \mathtt{r} \rangle \rangle$$
.insert f y force(r)

$$=$$
Cons $\mapsto 1+_c\|$ insert f y force(r) $\|$

$$= \mathtt{Cons} \mapsto \langle \mathtt{y}\, \mathtt{,}\, \langle \mathtt{ys}\, \mathtt{,r} \rangle \rangle.1 +_c (\|\mathtt{force}\, \mathtt{(r)}\, \|_c) +_c \|\mathtt{insert} \ \mathtt{f} \ \mathtt{y}\|_p \|\mathtt{force}\, \mathtt{(r)}\, \|_p$$

$$= \! \mathtt{Cons} \mapsto \langle \mathtt{y} \, , \langle \mathtt{ys} \, , \mathtt{r} \rangle \rangle . 1 +_{c} \mathtt{r}_{c} +_{c} \| \mathtt{insert} \ \ \mathtt{f} \ \ \mathtt{y} \|_{p} \mathtt{r}_{p}$$

$$= \texttt{Cons} \mapsto \langle \texttt{y} \texttt{,} \langle \texttt{ys}, \texttt{r} \rangle \rangle.1 +_c \texttt{r}_c +_c 3 +_c \|\texttt{insert}\|_p \texttt{ f y r}_p$$

$$= \! \mathtt{Cons} \mapsto \langle \mathtt{y} \, , \langle \mathtt{ys} \, , \mathtt{r} \rangle \rangle . 4 +_c \mathtt{r}_c +_c \| \mathtt{insert} \|_p \ \, \mathtt{f} \ \, \mathtt{y} \ \, \mathtt{r}_p$$

FIGURE 15. Translation of sort

$$\| \texttt{sort} \| \ = \ \langle 0, \lambda \texttt{f.} \langle 0, \lambda \texttt{xs.} \| \texttt{rec(xs, Nil} \mapsto \texttt{Nil,}$$

$$\texttt{Cons} \mapsto \langle \texttt{y, (ys,r)} \rangle. \texttt{insert f y force(r))} \| \rangle \rangle$$

=
$$\langle 0, \lambda \mathbf{f} . \langle 0, \lambda \mathbf{xs.rec}(\mathbf{xs}, \mathbf{Nil} \mapsto \langle \mathbf{1}, \mathbf{Nil} \rangle$$

 $\mathbf{Cons} \mapsto \langle \mathbf{y}, \langle \mathbf{ys}, \mathbf{r} \rangle \rangle . 4 +_c \mathbf{r}_c +_c \| \mathbf{insert} \|_p \ \mathbf{f} \ \mathbf{y} \ \mathbf{r}_p \|$

FIGURE 16. Translation of sort

$$\begin{split} \| \text{sort f } \mathbf{x} \mathbf{s} \| &= (1 + \| \mathbf{sort } \mathbf{f} \|_c + \| \mathbf{x} \mathbf{s} \|_c) +_c \| \mathbf{sort } \mathbf{f} \|_p \| \mathbf{x} \mathbf{s} \|_p \\ &= (1 + (1 + \| \mathbf{sort} \|_c + \| \mathbf{f} \|_c + \| \mathbf{x} \mathbf{s} \|_c)) +_c \| \mathbf{sort} \|_p \| \mathbf{f} \|_p \| \mathbf{x} \mathbf{s} \|_p \\ &= (1 + (1 + 0 + 0 + 0)) +_c \| \mathbf{sort} \|_p \| \mathbf{f} \|_p \| \mathbf{x} \mathbf{s} \|_p \\ &= 2 +_c \| \mathbf{sort} \|_p \mathbf{f} \|_p \| \mathbf{x} \mathbf{s} \|_p \\ &= 2 +_c \mathbf{rec} (\| \mathbf{x} \mathbf{s} \|_p, \| \mathbf{Nil} \mapsto \langle \mathbf{1}, \mathbf{Nil} \rangle \\ &= \mathbf{Cons} \mapsto \langle \mathbf{y}, \langle \mathbf{y} \mathbf{s}, \mathbf{r} \rangle \rangle . 4 +_c \mathbf{r}_c +_c \| \mathbf{insert} \|_p \| \mathbf{f} \| \mathbf{y} \|_p \end{split}$$

FIGURE 17. Interpretation of rec in sort.

CHAPTER 7

Work and Span

1. Work and span

Work and span is a method of calculating the cost of programs that may be run on multiple machines. The work of a program corresponds to the total number of steps needed to run. The span of a program is the steps in the critical path. The critical path is the largest number of steps that must be executed sequentially. The length of the critical path determines how much a program can be parallelized. If the span is equal to the work, than every step in the computation depends on the previous step, and the program cannot be parallelized.

Instead of calculating the cost of program, we will construct a cost graph. The cost graph represents dependencies between computations in a program and may be used to determine optimal execution strategies.

A cost graph is defined as follows.

$$\mathcal{C} ::= 0|1|\mathcal{C} \oplus \mathcal{C}|\mathcal{C} \otimes \mathcal{C}$$

The operator \oplus connects to cost graphs who must be combined sequentially. The operator \otimes connects cost graphs which may be combined in parallel.

The work of a cost graph is defined as

$$work(c) = \begin{cases} 0 & \text{if } c = 0 \\ 1 & \text{if } c = 1 \\ work(c_0) + work(c_1) & \text{if } c = c_0 \otimes c_1 \\ work(c_0) + work(c_1) & \text{if } c = c_0 \oplus c_1 \end{cases}$$

Figure 1. Source language operational semantics

$$\frac{e_0 \downarrow^{n_0} v_0}{\langle e_0, e_1 \rangle} \frac{e_1 \downarrow^{n_1} v_1}{\langle e_0, e_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0, e_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0, e_1 \rangle} \frac{e_1 [v_0 / x_0, v_1 / x_1] \downarrow^{n_1} v}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_1} v}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_1} v_1}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_1} v_1}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_1} v_1}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_1} v_1}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_1} v_1}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle} \frac{e_0 \downarrow^{n_0} \langle v_0, v_1 \rangle}{\langle e_0$$

The span of a cost graph is defined as

$$span(c) = \begin{cases} 0 & \text{if } c = 0 \\ 1 & \text{if } c = 1 \\ max(span(c_0), span(c_1)) & \text{if } c = c_0 \otimes c_1 \\ span(c_0) + span(c_1) & \text{if } c = c_0 \oplus c_1 \end{cases}$$

We alter the operational semantics of the source language slightly to reflect that the cost of evaluating an expression is a cost graph instead of an integer. Figure 1 shows the new operational semantics. For tuples, the subexpressions may be evaluated in parallel, so the cost of evaluating a tuple is the cost graphs of the subexpressions connected by \otimes . For split, the second subexpression depends on the result of the first subexpression, so the cost of evaluating the split is the cost graphs of the subexpression connected by \oplus .

FIGURE 2. Work and span translation from source language to compleity language

$$\|x\| = \langle 0, x \rangle$$

$$\|\langle \rangle\| = \langle 0, \langle \rangle \rangle$$

$$\|\langle e_0, e_1 \rangle\| = \langle \|e_0\|_c \otimes \|e_1\|_c, \langle \|e_0\|_p, \|e_1\|_p \rangle \rangle$$

$$\|split(e_0, x_0.x_1.e_1)\| = \|e_0\|_c \oplus_c \|e_1\| [\pi_0\|e_0\|_p/x_0, \pi_1\|e_1\|_p/x_1]$$

$$\|\lambda x.e\| = \langle 0, \lambda x.\|e\| \rangle$$

$$\|e_0 e_1\| = 1 \oplus (\|e_0\|_c \otimes \|e_1\|_c) \oplus_c \|e_0\|_p \|e_1\|_p$$

$$\|delay(e)\| = \langle 0, \|e\| \rangle$$

$$\|force(e)\| = \|e\|_c \oplus_c \|e\|_p$$

$$\|C_i^{\delta} e\| = \langle \|e\|_c, C_i^{\delta} \|e\|_p \rangle$$

$$\|rec^{\delta}(e, \overline{C} \mapsto x.e_{\overline{C}})\| = \|e\|_c \oplus_c rec^{\delta}(\|e\|_p, \overline{C} \mapsto x.1 \oplus_c \|e_{\overline{C}}\|)$$

$$\|map^{\phi}(x.v_0, v_1)\| = \langle 0, map^{\langle \langle \phi \rangle \rangle}(x.\|v_0\|_p, \|v_1\|_p) \rangle$$

$$\|let(e_0, x.e_1)\| = \|e_0\|_c \oplus_c \|e_1\| [\|e_0\|_p/x]$$

The complexity translation is given in figure 1. The operator $E_0 \oplus_c E_1$ is syntactic sugar for $\langle E_0 \oplus E_{1c}, E_{1p} \rangle$. The translation is similar to the original translation except we replace the use of + and $+_c$ with \oplus and \oplus_c . In the tuple case and function application case we use \otimes since the arguments do not depend on each other and may be computed in parallel.

2. Bounding Relation

TODO

3. Parallel List Map

If we revisit map using the work and span translation, we will get a different result. DRAFT: April 7, 2016

We use the same data type list and map function as in sequential list map.

datatype list = Nil of Unit | Cons of int
$$\times$$
 list

$$\mathtt{map} = \lambda f. \lambda x s. \mathtt{rec}(xs, \mathtt{Nil} \mapsto \mathtt{Nil}, \mathtt{Cons} \mapsto \langle y \langle ys, y \rangle \rangle. \mathtt{Cons} \langle f \ y, \mathtt{force}(r) \rangle)$$

The derivation of the complexity expression is given in figure 3.

The complexity language translation is

$$\begin{split} \|\text{map f xs}\| &= (3 \oplus f_c \otimes xs_c) \oplus_c \\ &\text{rec}(xs_p, \text{Nil} \mapsto \langle 1, \text{Nil} \rangle, \\ &\text{Cons} \mapsto \langle y, \langle ys, r \rangle \rangle. \langle 1 \oplus ((1 \oplus (f_p \ y)_c) \otimes r_c), \text{Cons} \langle (f_p \ y)_p, r_p \rangle \rangle) \end{split}$$

We interpret lists as a pair of their largest element and length.

$$\begin{split} \llbracket \mathtt{list} \rrbracket &= \mathbb{Z} \times \mathbb{N} \\ D^{\mathtt{list}} &= \{*\} + (\llbracket \mathbb{Z} \rrbracket \times \llbracket \mathtt{list} \rrbracket) \\ size_{\mathtt{list}}(*) &= (0,0) \\ size_{\mathtt{list}}((x,(m,n))) &= (max(x,m),1+n) \end{split}$$

The interpretation of the recurser is given in figure 3.

The result is

$$\begin{split} g(f,(m,n)) &= & \bigvee_{(m_1,n_1) \leq (m,n)} case((m_1,n_1), \mathtt{Nil} \mapsto (1,(0,0)), \\ & (m_1,n_1) \leq (m,n) \\ & \texttt{Cons} \mapsto (1 \oplus ((1 \oplus (f\ y)_c) \otimes g_c(f,(m,n-1))), ((f\ y)_p, \pi_1 g_p(f,(m,n-1))))) \end{split}$$
 DRAFT: April 7, 2016

FIGURE 3. Work and span complexity translation of map f xs.

$$\begin{split} \|\text{map f } \mathbf{x}\mathbf{s}\| &= \\ (3 \oplus f_c \otimes xs_c) \oplus_c \operatorname{rec}(xs_p, \operatorname{Nil} \mapsto 1 \oplus_c \|\operatorname{Nil}\|, \\ & \operatorname{Cons} \mapsto \langle y, \langle ys, r \rangle \rangle. 1 \oplus_c \|\operatorname{Cons}\langle f \ y, \operatorname{force}(r)\rangle\|) \\ 1 \oplus_c \|\operatorname{Nil}\| &= 1 \oplus_c \langle 0, Nil \rangle = \langle 1, Nil \rangle \\ \|\operatorname{Cons}\langle f \ y, \operatorname{force}(r) \rangle\| &= \langle \|\langle f \ y, \operatorname{force}(r) \rangle\|_c, \operatorname{Cons}\|\langle f \ y, \operatorname{force}(r) \rangle\|_p \rangle \\ \|\langle f \ y, \operatorname{force}(r) \rangle\| &= \langle \|f \ y\|_c \otimes \|\operatorname{force}(r)\|_c, \langle \|f \ y\|_p, \|\operatorname{force}(r)\|_p \rangle \rangle \\ \|f \ y\| &= (1 \oplus \|f\|_c \otimes \|y\|_c) \oplus_c \|f\|_p \|y\|_p \\ &= (1 \oplus \langle 0, f_p \rangle_c \otimes \langle 0, y \rangle_c) \oplus_c \langle 0, f_p \rangle_p \langle 0, y \rangle_p \\ &= 1 \oplus_c f_p \ y \\ &= \langle 1 \oplus (f_p y)_c, \langle f_p \ y)_p \rangle \\ \|\operatorname{force}(r)\| &= \|r\|_c \oplus_c \|r\|_p \\ &= \langle 0, r \rangle_c \oplus_c \langle 0, r \rangle_p \\ &= r \\ \|\langle f \ y, \operatorname{force}(r) \rangle\| &= \langle (1 \oplus (f_p \ y)_c) \otimes r_c, \langle (f_p \ y)_p, r_p \rangle \rangle \\ \|\operatorname{Cons}\langle f \ y, \operatorname{force}(r) \rangle\| &= \langle (1 \oplus (f_p \ y)_c) \otimes r_c, \operatorname{Cons}\langle (f_p \ y)_p, r_p \rangle \rangle \\ \|\operatorname{map f } \mathbf{x}\mathbf{s}\| &= (3 \oplus f_c \otimes xs_c) \oplus_c \\ \operatorname{rec}(xs_p, \operatorname{Nil} \mapsto \langle 1, \operatorname{Nil} \rangle, \\ \operatorname{Cons} \mapsto \langle y, \langle ys, r \rangle \rangle. \langle 1 \oplus ((1 \oplus (f_p \ y)_c) \otimes r_c), \operatorname{Cons}\langle (f_p \ y)_p, r_p \rangle \rangle) \end{split}$$

We compile the recurrence down to the work and the span to make it easier to manipulate. The costs change from cost graphs to a tuple of the work and the span.

$$\begin{split} g(f,(m,n)) &= & \bigvee_{(m_1,n_1) \leq (m,n)} case((m_1,n_1), \\ & \text{Nil} \mapsto ((1,1),(0,0)), \\ & \text{Cons} \mapsto ((2+\pi_0(f\ y)_c + \pi_0 g_c(f,(m,n-1)), \\ & 1 + max(1+\pi_1(f\ y)_c, \pi_1 g_c(f,(m,n-1)))), \\ & ((f\ y)_p, \pi_1 g_p(f,(m,n-1))))) \end{split}$$

FIGURE 4. Interpretation of recurser in map

We prove by induction bounds on the work and span of the cost of g.

THEOREM 3.1.
$$\pi_0 g_c(f, (m, n)) \le 1 + (2 + \pi_0 (f \ m)_c) n$$

PROOF. The proof is by induction on n.

case
$$n=0$$
:

$$\pi_0 g_c(f,(m,0)) = \pi_0((1,1),(0,0))_c = \pi_0(1,1) = 1$$

case n > 0:

$$\begin{split} \pi_0(g_c(f,(m,n))) &= \\ \pi_0(\bigvee_{(m_1,n_1) \leq (m,n)} case((m_1,n_1), \\ & \text{Nil} \mapsto ((1,1),(0,0)), \\ & \text{Cons} \mapsto ((2+\pi_0(f\ m_1)_c + \pi_0g_c(f,(m_1,n_1-1)), \\ & 1+max(1+\pi_1(f\ m_1)_c,\pi_1g_c(f,(m_1,n_1-1)))), \\ & ((f\ m_1)_p,\pi_1g_p(f,(m_1,n_1-1)))))_c \\ &= 1 \vee \pi_0(\bigvee_{(m_1,n_1) \leq (m,n)} ((2+\pi_0(f\ m_1)_c + \pi_0g_c(f,(m_1,n_1-1)), \\ & 1+max(1+\pi_1(f\ m_1)_c,\pi_1g_c(f,(m_1,n_1-1)))), \\ & ((f\ m_1)_p,\pi_1g_p(f,(m_1,n_1-1)))))_c \\ &= 1 \vee \bigvee_{(m_1,n_1) \leq (m,n)} 2+\pi_0(f\ m_1)_c + \pi_0g_c(f,(m_1,n_1-1)) \\ &\leq \bigvee_{(m_1,n_1) \leq (m,n)} 2+\pi_0(f\ m_1)_c + (1+(2+\pi_0(f\ m_1)_c)(n_1-1)) \\ &\leq 2+\pi_0(f\ m)_c + 1 + (2+\pi_0(f\ m)_c)(n-1) \\ &\leq 1+(2+\pi_0(f\ m)_c)n \end{split}$$

THEOREM 3.2. $\pi_1 g_c(f, (m, n)) \le 1 + \pi_1 (f \ m)_c + n$

Proof. case n = 0:

$$\pi_1 g_c(f, (m, 0)) = \pi_1((1, 1), (0, 0))_c = \pi_1(1, 1) = 1$$

case n > 0:

DRAFT: April 7, 2016

$$\begin{split} \pi_1(g_c(f,(m,n))) &= \\ \pi_1(\bigvee_{(m_1,n_1) \leq (m,n)} case((m_1,n_1), \\ & \text{Nil} \mapsto ((1,1),(0,0)), \\ & \text{Cons} \mapsto ((2+\pi_0(f\ m_1)_c + \pi_0g_c(f,(m_1,n_1-1)), \\ & 1+max(1+\pi_1(f\ m_1)_c,\pi_1g_c(f,(m_1,n_1-1)))), \\ & ((f\ m_1)_p,\pi_1g_p(f,(m_1,n_1-1)))))_c \\ &= 1 \vee \pi_1(\bigvee_{(m_1,n_1) \leq (m,n)} ((2+\pi_0(f\ m_1)_c + \pi_0g_c(f,(m_1,n_1-1))), \\ & 1+max(1+\pi_1(f\ m_1)_c,\pi_1g_c(f,(m_1,n_1-1)))), \\ & ((f\ m_1)_p,\pi_1g_p(f,(m_1,n_1-1)))))_c \\ &= 1 \vee \bigvee_{(m_1,n_1) \leq (m,n)} 1+max(1+\pi_1(f\ m_1)_c,\pi_1g_c(f,(m_1,n_1-1))) \\ &\leq \bigvee_{(m_1,n_1) \leq (m,n)} 1+max(1+\pi_1(f\ m_1)_c,1+\pi_1(f\ m_1)_c+n_1-1) \\ &\leq 1+max(1+\pi_1(f\ m)_c,1+\pi_1(f\ m)_c+n-1) \\ &\leq 1+\pi_1(f\ m)_c+n-1 \\ &\leq 1+\pi_1(f\ m)_c+n \end{split}$$

Compare these results with sequential map.

4. Parallel Tree Map

A program which is embarrasingly parallel is tree map. When a function f is mapped over a tree t, each application of f to the label at each node can be done independently. Furthermore, the tree data structure itself is dividable by construction. Dividing the work requires only destruction of the node constructor to yield the left and right subtrees.

DRAFT: April 7, 2016

We will use int labelled binary trees.

datatype tree = E of Unit | N of int
$$\times$$
tree \times tree

map simply deconstructs each node, applies the function to the label, recuses on the children, and reconstructs a node using the results.

$$\mathtt{map} = \lambda f. \lambda t. \mathtt{rec}(t, \mathtt{E} \mapsto \mathtt{E}, \mathtt{N} \mapsto \langle x, \langle t_0, r_0 \rangle, \langle t_1, r_1 \rangle \rangle. \mathtt{N} \langle f \ x, \mathtt{force}(r_0), \mathtt{force}(r_1) \rangle)$$

The translation of map f t is given in figure 4.

(16)

$$\|\mathtt{map\ f\ t}\| = 2 \oplus (f_c \otimes t_c) \oplus 1 \oplus_c$$

$$\mathtt{rec}(t_p,\mathtt{E} \mapsto \langle 1,\mathtt{E} \rangle,$$

$$\mathbb{N} \mapsto \langle y, \langle t_0, r_0 \rangle \langle t_1, r_1 \rangle \rangle \cdot \langle 2 \oplus (f_p \ x)_c \otimes r_{0c} \otimes r_{1c}, \mathbb{N} \langle (f_p \ x)_p, r_{0p}, r_{1p} \rangle \rangle$$

The result is shown in equation 16.

We interpret trees as the number of N constructors and the maximum label.

$$\llbracket tree \rrbracket = \mathbb{Z} \times \mathbb{Z}$$

$$D_{\texttt{tree}} = \{*\} + \mathbb{Z} \times \llbracket \texttt{tree} \rrbracket \times \llbracket \texttt{tree} \rrbracket$$

$$size_{\texttt{tree}}(*) = (0,0)$$

$$size_{tree}(x, (m_0, n_0), (m_1, n_1)) = (max(x, m_0, m_1), 1 + n_0 + n_1)$$

Source Language. Recall the definition of the tree data type and the function map.

FIGURE 5. Complexity translation of map f t

$$3 \oplus (f_c \otimes t_c) \oplus_c \operatorname{rec}(t_p, \mathsf{E} \mapsto 1 \oplus_c \|\mathsf{E}\|, \\ \mathsf{N} \mapsto \langle y, \langle t_0, r_0 \rangle \langle t_1, r_1 \rangle \rangle 1 \oplus_c \|\mathsf{N} \langle f| x, \operatorname{force}(r_0) \operatorname{force}(r_1) \rangle \|)$$

$$1 \oplus_c \|E\| = 1 \oplus \langle 0, E \rangle = \langle 1, E \rangle$$

$$\|\mathsf{N} \langle f| x, \operatorname{force}(r_0) \operatorname{force}(r_1) \rangle \| =$$

$$\langle \|\langle f| x, \operatorname{force}(r_0) \operatorname{force}(r_1) \rangle \|_c, \mathsf{N} \|\langle f| x, \operatorname{force}(r_0) \operatorname{force}(r_1) \rangle \|_p \rangle$$

$$\|\langle f| x, \operatorname{force}(r_0) \operatorname{force}(r_1) \rangle \|_c \otimes \|\operatorname{force}(r_1) \|_c, \langle \|f| x\|_p, \|\operatorname{force}(r_0)\|_p, \|\operatorname{force}(r_1)\|_p \rangle$$

$$\|f| x\| = 1 \oplus \|f\|_c \otimes \|x\|_c \oplus_c \|f\|_p \|x\|_p$$

$$= 1 \oplus_c \langle 0, f \rangle_c \otimes \langle 0, x \rangle_c \oplus_c \langle 0, f \rangle_p \langle 0, x \rangle_p$$

$$= 1 \oplus_c \langle f_p| x \rangle$$

$$= \langle 1 \oplus \langle f_p| x \rangle_c, \langle f_p| x \rangle_p \rangle$$

$$\|\operatorname{force}(r_0)\| = \|r_0\|_c \oplus_c \|r_0\|_p$$

$$= \langle 0, r_0 \rangle \oplus_c \langle 0, r_0 \rangle_p$$

$$= \langle 0 + r_{0c}, r_{0p} \rangle$$

$$= r_0$$

$$\|\operatorname{force}(r_1)\| = \|r_1\|_c \oplus_c \|r_1\|_p$$

$$= \langle 0, r_1 \rangle \oplus_c \langle 0, r_1 \rangle_p$$

$$= \langle 0 + r_{1c}, r_{1p} \rangle$$

$$= r_1$$

$$\|\langle f| x, \operatorname{force}(r_0) \operatorname{force}(r_1) \rangle \| =$$

$$= \langle 1 \oplus \langle f_p| x \rangle_c \otimes r_{0c} \otimes r_{1c}, \langle \langle f_p| x \rangle_p, r_{0p}, r_{1p} \rangle$$

$$\|\mathsf{N} \langle f| x, \operatorname{force}(r_0) \operatorname{force}(r_1) \rangle \| =$$

$$= \langle 1 \oplus \langle f_p| x \rangle_c \otimes r_{0c} \otimes r_{1c}, \mathsf{N} \langle \langle f_p| x \rangle_p, r_{0p}, r_{1p} \rangle$$

$$\|\mathsf{N} \langle f| x, \operatorname{force}(r_0) \operatorname{force}(r_1) \rangle \| =$$

$$= \langle 1 \oplus \langle f_p| x \rangle_c \otimes r_{0c} \otimes r_{1c}, \mathsf{N} \langle \langle f_p| x \rangle_p, r_{0p}, r_{1p} \rangle$$

$$\|\mathsf{N} \langle f| x, \operatorname{force}(r_0) \operatorname{force}(r_1) \rangle \| =$$

$$= \langle 1 \oplus \langle f_p| x \rangle_c \otimes r_{0c} \otimes r_{1c}, \mathsf{N} \langle \langle f_p| x \rangle_p, r_{0p}, r_{1p} \rangle$$

Figure 6. Deriviation of interpretation of map $\, {\tt f} \, {\tt t} \,$

CHAPTER 8

Mutual Recurrence

1. Motivation

The interpretation of a recursive function can be separated into a recurrence for the cost and a recurrence for the potential. The recurrence for the cost depends on the recurrence for the potential. However, the recurrence for the potential does not depend on the cost. We prove this by designing a pure potential translation. The pure potential translation is identical to the complexity translation except that it does not keep track of the cost.

We then show by logical relations that the potential of the complexity translation is related to the pure potential relation.

2. Pure Potential Translation

Our pure potential translation is defined below. The translation of an expression is essientially the expression itself, without suspensions.

$$|x| = x$$

$$|\langle \rangle| = \langle \rangle$$

$$|\langle e_0, e_1 \rangle| = \langle |e_0|, |e_1| \rangle$$

$$|\operatorname{split}(e_0, x_0.x_1.e_1)| = |e_1|[\pi_0|e_0|/x_0, \pi_0|e_0|/x_1]$$

$$|\lambda x.e| = \lambda x.|e|$$

$$|e_0 \ e_1| = |e_0| \ |e_1|$$

$$|delay(e)| = |e|$$

$$|force(e)| = |e|$$

$$|C_i^{\delta}e| = C_i^{\delta}|e|$$

$$|rec^{\delta}(e, \overline{C \mapsto x.e_C})| = rec^{\delta}(|e|, \overline{C \mapsto x.|e_C|})$$

$$|map^{\phi}(x.v_0, v_1)| = map^{|\phi|}(x.|v_0|, |v_1|)$$

$$|let(e_0, x.e_1)| = |e_1|[|e_0|/x]$$

3. Logical Relation

We define our logical relation below.

$$E \sim_{\text{Unit}} E' \text{always}$$

$$E \sim_{\tau_0 \times \tau_1} E' \Leftrightarrow \forall k. \langle k, \pi_0 E_p \rangle \sim_{\tau_0} \pi_0 E', \forall k. \langle k, \pi_1 E_p \rangle \sim_{\tau_1} \pi_1 E'$$

$$E \sim_{\text{susp } \tau} E' \Leftrightarrow E_p \sim_{\tau} E'$$

$$E \sim_{\sigma \to \tau} E' \Leftrightarrow \forall E_0 \sim_{\sigma} E'_0. E_p E_{0p} \sim_{\tau} E' E'_0$$

$$E \sim_{\delta} E' \Leftrightarrow \exists k, k', C, V, V'. V \sim_{\phi[\delta]} V', E \downarrow \langle k, CV_p \rangle, E' \downarrow CV'$$

The relation is defined on closed terms, but we extend it to open terms. Let Θ and Θ' be any substitutions such that $\forall x: \|\tau\|, \forall k, \langle k, \Theta(x) \rangle \sim_{\tau} \Theta'(x)$. If $E \Theta \sim_{\tau} E' \Theta'$, then $E \sim_{\tau} E'$.

4. Proof

We require some lemmas.

The first states we can always ignore the cost of related terms.

Lemma 4.1 (Ignore Cost).

$$E \sim_{\tau} E' \Leftrightarrow \forall k, \langle k, E_n \rangle \sim_{\tau} E'$$

PROOF. We proceed by induction on type.

Case $E \sim_{\mathtt{Unit}} E'$. Then $\forall k, \langle k, E_p \rangle \sim_{\mathtt{Unit}} E'$ by definition.

Case $E \sim_{\tau_0 \times \tau_1} E'$. By definition for $i \in [0, 1, \forall k_i, \langle k_i, \pi_i E_p \rangle \sim_{\tau_i} \pi_i E'$. Let k be some cost. Then $\langle k, E_p \rangle \sim_{\tau_0 \times \tau_1} E'$ by definition.

Case $E \sim_{\text{susp } \tau} E'$. By definition $E_p \sim_{\tau} E'$. Let k be some cost. Then $\langle k, E_p \rangle \sim_{\text{susp } \tau} E'$.

Case $E \sim_{\sigma \to \tau} E'$. Let E_0, E'_0 by some complexity language terms such that $E_0 \sim_{\sigma} E'_0$. Let k be some cost. Then, $E_p E_0 \sim_{\tau} E' E'_0$. So $\langle k, E_p \rangle \sim_{\sigma \to \tau} E'$.

Case $E \sim_{\delta} E'$. Then by definition there exists costs k and k', a constructor C, and complexity language values V and V' such that $V \sim_{\Phi[\delta]} V', E \downarrow \langle k, CV_p \rangle$, and $E' \downarrow CV'$. Since $E \downarrow \langle k, CV_p \rangle$, we know $\forall k_0, \exists k'_0. \langle k_0, E_p \rangle \downarrow \langle k'_0, CV_p \rangle$. So by definition we have $\forall k_0, \langle k_0, E_p \rangle \sim_{\Phi} E'$.

The next lemma states that if two terms step to related terms, then those terms are related.

LEMMA 4.2 (Related Step Back).

$$E \to F, E' \to F', F \sim_{\sigma} F' \implies E \sim_{\sigma} E'$$

PROOF. The proof proceeds by induction on type.

Case Unit. Trivial since $E \sim_{\text{Unit}} E'$ always.

Case δ . By definition $\exists C, U, U', k, k'$ such that $F \downarrow \langle k, CU_p \rangle, F' \downarrow CU', U \sim_{\phi[\delta]} U'$. Since $E \to F$ and $E' \to F'$, $E \downarrow \langle k, CU_p \rangle$ and $E' \downarrow CU'$. Therefore since $U \sim_{\phi[\delta]} U'$, we have $E \sim_{\delta} E'$.

Case $\sigma \to \tau$. Let $E_0 \sim_{\sigma} E_0'$. By definition, $F E_0 \sim_{\tau} F' E_0'$. Since $E \to F$ and $E' \to F'$, $E E_0 \to F E_0$ and $E' E_0' \to F' E_0'$. So by the induction hypothesis, $E E_0 \sim_{\tau} E' E_0'$. So by definition, $E \sim_{\sigma \to \tau} E'$.

Case $\tau_0 \times \tau_1$. Since $F \sim_{\tau_0 \times \tau_1} F'$, for $i \in \{0, 1\}$, $\forall k_i, \langle k_i, \pi_i F_p \rangle \sim_{\tau_i} \pi_i F'$, by definition. From $E \to F$, we get $\langle k_i, \pi_i E_p \rangle \to \langle k_i', \pi_i F_p \rangle$. From $E' \to F'$, we get $\pi_i E' \to \pi_i F'$. We can apply our induction hypothesis to get $\langle k_i, \pi_i E_p \rangle \sim_{\tau_i} \pi_i E'$. By 4.1, $\forall k_i, \langle k_i, \pi_i E_p \rangle \sim_{\tau_i} \pi_i E$. So by definition $E \sim_{\tau_0 \times \tau_1} E'$.

Case susp τ . Since $F \sim_{\text{susp }\tau} F'$, by definition $F_p \sim_{\tau} F'$. Since $E \to F$, $E_p \to F_p$. So by the induction hypothesis, since $E_p \to F_p$, $E' \to F'$, $F_p \sim_{\tau} F'$, $E_p \sim_{\tau} E'$. So by definition $E \sim_{\text{susp }\tau} E'$.

The next lemma states that related terms step to related terms

Lemma 4.3. [Related Step]

$$E \to F, E' \to F', E \sim_{\sigma} E' \implies F \sim_{\sigma} F'$$

PROOF. The proof is by induction on type.

Case Unit. $F \sim_{\text{Unit}} F'$ always.

Case δ . By definition, $E \sim_{\delta} E'$ implies $\exists C, V, V', k$ such that $E \downarrow \langle k, CV_p \rangle, E' \downarrow CV', V \sim_{\phi[\delta]} V'$. Since $E \to F$, $F \downarrow \langle k, CV_p \rangle$; and since $E \to F'$, $F' \downarrow CV'$. By 4.1, $\langle k, V_p \rangle \sim_{\phi[\delta]} V'$. So because $F \downarrow \langle k, CV_p \rangle, F' \downarrow CV', \langle k, V_p \rangle \sim_{\phi[\delta]} V'$, we can apply our induction hypothesis to get $F \sim_{\delta} F'$.

Case $\tau_0 \times \tau_1$. By definition $E \sim_{\tau_0 \times \tau_1} \implies \forall i \in \{0,1\}, \forall k, \langle k_i, \pi_i E_p \rangle \sim_{\tau_i} \pi_i E'$. Fix some k_i . Since $E \to F$, $\langle k_i, \pi_i E_p \rangle \to \langle k_i, \pi_i F_p \rangle$. Since $E' \to F'$, $\pi_i E' \to \pi_i F'$.

From $\langle k_i, \pi_i E_p \rangle \to \langle k_i, \pi_i F_p \rangle$, $\langle k_i, \pi_i E_p \rangle \sim_{\tau_i} \pi_i E'$, the induction hypothesis tells us $\langle k_i, \pi_i F_p \rangle \sim_{\tau_i} \pi_i F'$. So by definition $F \sim_{\tau_0 \times \tau_1} F'$.

Case susp τ . By definition $E \sim_{\text{susp } \tau} E' \implies E_p \sim_{\tau} E'$. Since $E \to F$, $E_p \to F_p$. From $E_p \to F_p$, $E' \to F'$, $E_p \sim_{\tau} E'$, the induction hypothesis gives us $F_p \sim_{\tau} F'$. So by definition $F \sim_{\text{susp } \tau} F'$.

Case $\sigma \to \tau$. Let $E_0 \sim_{\sigma} E_0'$. By definition, $E E_0 \sim_{\tau} E' E_0'$. Since $E \to F$, $E E_0 \to F E_0$. Since $E' \to F'$, $E' E_0' \to F' E_0'$. From $E E_0 \to F E_0$, $E' E_0' \to F' E_0'$, $E' E_0 \to F E_0$, the induction hypothesis tells us $F E_0 \sim_{\tau} F' E_0'$. So by definition $F \sim_{\sigma \to \tau} F'$.

The next lemma states that if the arguments to map are related, then map preserves the relatedness.

Lemma 4.4. [Related Map]

$$E \sim_{\tau_1} E', E_0 \sim_{\tau_0} E'_0 \implies \forall k. \langle k, map^{\Phi}(x, E_p, E_{0p}) \rangle \sim_{\Phi[\tau_1]} map^{\Phi}(x, E', E'_0)$$

PROOF. The proof proceeds by induction on type.

Recall the definition of the map macro.

$$map^{t}(x.E, E_{0}) = E[E_{0}/x]$$

 $map^{T}(x.E, E_{0}) = E_{0}$
 $map^{\Phi_{0} \times \Phi_{1}}(x.E, E_{0}) = \langle map^{\Phi_{0}}(x.E, \pi_{0}E_{0}), map^{\Phi_{1}}(x.E, \pi_{1}E_{0}) \rangle$
 $map^{T \to \Phi}(x.E, E_{0}) = \lambda y.map^{\Phi}(x.E, E_{0}, y)$

Case $\Phi = t$. Then $map^t(x.E_p, E_{0p}) = E_p[E_{0p}/x]$ and $map^t(x.E', E'_0) = E'[E'_0/x]$. Let k be some cost. By 4.1, $E \sim_{\tau_1} E'$ implies $\langle k, E_p \rangle \sim_{\tau_1} E'$. Since $\langle k, E_p \rangle \sim_{\tau_1} E'$ and $E_0 \sim_{\tau_0} E'_0$, $\langle k, E_p \rangle [E_{0p}/x] \sim_{\phi[\tau_0]} E'[E'_0/x]$. So $\forall k, \langle k, map^t(x.E_p, E_{0p}) \rangle \sim_{\Phi[\tau_1]} map^t(x.E', E'_0)$.

Case $\Phi = T$. Then $map^T(x.E_p, E_{0p}) = E_{0p}$ and $map^T(x.E', E'_0) = E'_0$. By 4.1 $\forall k, \langle k, E_{0p} \rangle \sim_{\tau_0} E'_0$. So $\forall k, \langle k, map^T(x.E_p, E_{0p}) \rangle \sim_{\Phi[\tau_1]} map^T(x.E', E'_0)$.

Case $\Phi = \Phi_0 \times \Phi_1$. Then $map^{\Phi_0 \times \Phi_1}(x.E_p, E_{0p}) = \langle map^{\Phi_0}(x.E_p, \pi_0 E_{0p}), map^{\Phi_1}(x.E_p, \pi_1 E_{0p}) \rangle$. Similarly $map^{\Phi_0 \times \Phi_1}(x.E', E'_0) = \langle map^{\Phi_0}(x.E', \pi_0 E'_0), map^{\Phi_1}(x.E', \pi_1 E'_0) \rangle$. By definition, $\forall k, \langle k, \pi_0 E_{0p} \rangle \sim_{\Phi_0[\tau_0]} \pi_0 E'_0$. By the induction hypothesis, $\forall k, \langle k, map^{\Phi_0}(x.E_p, \pi_0 E_{0p}) \sim_{\Phi_0[\tau_1]} \mathbb{I}$ $map^{\Phi_0[\tau_1]}(x.E', E'_0)$. By definition, $\forall k, \langle k, \pi_1 E_{0p} \rangle \sim_{\Phi_1[\tau_0]} \pi_1 E'_0$. By the induction hypothesis, $\forall k, \langle k, map^{\Phi_1}(x.E_p, \pi_1 E_{0p}) \sim_{\Phi_1[\tau_1]} map^{\Phi_1[\tau_1]}(x.E', E'_0)$. So by definition, $\forall k, \langle k, \langle map^{\Phi_0}(x.E_p, \pi_0 E_{0p}) \rangle \sim_{\Phi_0[\tau_1]} (x.E', E'_0)$.

Case $T \to \Phi$. Then $map^{T \to \Phi}(x.E_p, E_{0p}) = \lambda y.map^{\Phi}(x.E_p, E_{0p} y)$ and $map^{T \to \Phi}(x.E', E'_0) = \mathbb{I}$ $\lambda y.map^{\Phi}(x.E', E'_0 y)$. Let $E_1 : T$. Then $\lambda y.map^{\Phi}(x.E_p, E_{0p} y)$ $E_1 \to map^{\Phi}(x.E_p, E_{0p} E_1)$. Similarly, $\lambda y.map^{\Phi}(x.E', E'_0 y)$ $E'_1 \to map^{\Phi}(x.E', E'_0 E'_1)$. Since $E_0 \sim E'_0$ and $E_1 \sim E'_1$, we have E_{0p} $E_1 \sim E'_0$ E'_1 . So by our induction hypothesis, $map^{\Phi}(x.E_p, E_{0p} E_1) \sim map^{\Phi}(x.E', E'_0 E'_1)$. So by 4.2, $\lambda y.map^{\Phi}(x.E_p, E_{0p} y)$ $E_1 \sim \lambda y.map^{\Phi}(x.E', E'_0 y)$ E'_1 . So by definition, $\lambda y.map^{\Phi}(x.E_p, E_{0p} y) \sim \lambda y.map^{\Phi}(x.E', E'_0 y)$. So $map^{T \to \Phi}(x.E_p, E_{0p}) \sim map^{T \to \Phi}(x.E', E'_0)$.

Our last lemma is about the relatedness of rec terms.

Lemma 4.5 (Related Rec).

$$E \sim_{\delta} E', \forall C, E_C \sim_{\tau} E'_C \implies rec(E_p, \overline{C \mapsto x.E_c}) \sim_{\tau} rec(E', \overline{C \mapsto x.E'_c})$$

PROOF. Recall the rule for evaluating rec in the complexity language:

$$\frac{E \downarrow CV_0 \qquad map^{\Phi}(y, \langle y, rec(y, \overline{C} \mapsto x.\overline{E_C}) \rangle, V_0) \downarrow V_1 \qquad E_C[V_1/x] \downarrow V}{rec(E, \overline{C} \mapsto x.\overline{E_C}) \downarrow V}$$

By definition of \sim_{δ} , $\exists k, C, V_0, V'_0$ such that $E \downarrow \langle k, CV_{0p} \rangle, E' \downarrow CV'_0$, and $V_0 \sim_{\delta}$ V'_0 . Our proof proceeds by induction on the number of constructors in CV_{0p} . If $\Phi = T$, then $map^{\Phi}(y, \langle y, rec(y, \overline{C} \mapsto x.\overline{E_C}) \rangle, V_{0p}) = \langle y, rec(y, \overline{C} \mapsto x.\overline{E_C}) \rangle [V_{0p}/y] = \langle V_{0p}, rec(V_{0p}, \overline{C} \mapsto x.\overline{E_C}) \rangle$. Similarly for the pure potential, $map^{\Phi}(y, \langle y, rec(y, \overline{C} \mapsto x.\overline{E'_C}) \rangle, V'_{0p}) = \langle y, rec(y, \overline{C} \mapsto x.\overline{E'_C}) \rangle [V'_0/y] = \langle V'_0, rec(V'_0, \overline{C} \mapsto x.\overline{E'_C}) \rangle$. By the induction hypothesis, $rec(V_{0p}, \overline{C} \mapsto x.\overline{E_C}) \sim_{\tau} rec(V'_0, \overline{C} \mapsto x.\overline{E'_C})$. By definition of $\sim_{\text{susp }\tau}$, for any k, $\langle k, rec(V_{0p}, \overline{C} \mapsto x.\overline{E_C}) \rangle \sim_{\text{susp }\tau} rec(V'_0, \overline{C} \mapsto x.\overline{E'_C})$. So by definition of $\sim_{\tau_0 \times \tau_1}$, $\langle 0, \langle V_{0p}, rec(V_{0p}, C \mapsto x.\overline{E_C}) \rangle, V_{0p} \rangle \sim_{\phi[\delta \times \text{susp }\tau]} \langle V'_0, rec(V'_0, \overline{C} \mapsto x.\overline{E'_C}) \rangle$. So by 4.4, $\forall k. \langle k, map^{\Phi}(y, \langle y, rec(y, \overline{C} \mapsto x.\overline{E_C}) \rangle, V_{0p}) \sim_{\phi[\delta \times \text{susp }\tau]} \langle V'_0, rec(V'_0, \overline{C} \mapsto x.\overline{E'_C}) \rangle$. So by 4.4, $\forall k. \langle k, map^{\Phi}(y, \langle y, rec(y, \overline{C} \mapsto x.\overline{E_C}) \rangle, V_{0p}) \sim_{\phi[\delta \times \text{susp }\tau]} \langle V'_0, rec(V'_0, \overline{C} \mapsto x.\overline{E'_C}) \rangle$. So by 4.4, $\forall k. \langle k, map^{\Phi}(y, \langle y, rec(y, \overline{C} \mapsto x.\overline{E_C}) \rangle, V_{0p}) \sim_{\phi[\delta \times \text{susp }\tau]} \langle V'_0, rec(V'_0, \overline{C} \mapsto x.\overline{E'_C}) \rangle$. So by 4.4, $\forall k. \langle k, map^{\Phi}(y, \langle y, rec(y, \overline{C} \mapsto x.\overline{E_C}) \rangle, V_{0p}) \sim_{\phi[\delta \times \text{susp }\tau]} \langle V'_0, rec(V'_0, \overline{C} \mapsto x.\overline{E'_C}) \rangle$.

$$\begin{split} & map^{\Phi}(y,\langle y,rec(y,\overline{C\mapsto x.E_C'})\rangle,V_0'). \quad \text{Let } \langle 0, map^{\Phi}(y,\langle y,rec(y,\overline{C\mapsto x.E_C})\rangle,V_{0p}) \ \downarrow \ V_1. \end{split}$$
 Let $& map^{\Phi}(y,\langle y,rec(y,\overline{C\mapsto x.E_C'})\rangle,V_0') \downarrow V_1'. \text{ By 4.3, } V_1\sim_{\phi[\delta\times \mathtt{susp}\ \tau]} V_1'. \end{split}$

If $\Phi = t$, then $map^{\Phi}(y, \langle y, rec(y, \overline{C \mapsto x.E_C}) \rangle, V_{0p}) = V_{0p}$. Similarly, $map^{\Phi}(y, \langle y, rec(y, \overline{C \mapsto x.E'_C}) \rangle V'_0) = V'_0$. So in this case $V_0 = V_1$ and $V'_0 = V'_1$. We have already established $V_0 \sim_{\tau} V'_0$.

So in both cases $V_1 \sim_{\phi[\delta \times \text{susp } \tau]} V_1'$.

By definition of the relation $E_C[V_{1p}/x] \sim_{\tau} E'_C[V'_1/x]$. Let $E_C[V_{1p}/x] \downarrow V_2$ and $E'_C[V'_1/x] \downarrow V'_2$. By 4.3, $V_2 \sim_{\tau} V'_2$. So by 4.2, $rec(E_p, \overline{C \mapsto x.E_C}) \sim_{\tau} rec(E', \overline{C \mapsto x.E'_C})$.

Our theorem is that for all well-typed terms in the source language, the complexity translation of the term is related to the pure potential translation of that term.

Theorem 4.6 (Distinct Recurrence).

$$\gamma \vdash e : \tau \implies ||e|| \sim_{\tau} |e|$$

PROOF. Our proof is by induction on the typing derivation $\gamma \vdash e : \tau$.

Case $\overline{\gamma, x : \sigma \vdash x : \sigma}$. Then by definition of the logical relation, $\forall k, \langle k, \Theta(x) \rangle \sim_{\sigma} \Theta'(x)$. Since $||x|| = \langle 0, x \rangle$ and |x| = x, we have $\langle 0, x \rangle \sim_{\sigma} x$.

Case $\gamma \vdash e : Unit$. By definition, $||e|| \sim_{\mathtt{Unit}} |e|$ always.

Case $\frac{\gamma \vdash e_0 : \tau_0}{\gamma \vdash \langle e_0, e_1 \rangle : \tau_0 \times \tau_1} \text{ By the induction hypothesis, } \|e_0\| \sim_{\tau_0} |e_0| \text{ and } \|e_1\| \sim_{\tau_1} |e_1|. \text{ By } 4.1, \forall k, \langle k, \|e_0\|_p \rangle \sim_{\tau_0} |e_0| \text{ and } \forall k, \langle k, \|e_1\|_p \rangle \sim_{\tau_1} |e_1|. \text{ So by definition,} \|\langle e_0, e_1 \rangle\| \sim_{\tau_0 \times \tau_1} |\langle e_0, e_1 \rangle|.$

 $\begin{aligned} & \text{Case} \quad \frac{\gamma \vdash e_0 : \tau_0 \times \tau_1 \quad \gamma, x_0 : \tau_0, x_1 : \tau_1 \vdash e_1 : \tau}{\gamma \vdash split(e_0, x_0.x_1.e_1) : \tau} \quad \text{By the induction hypothesis,} \\ & \|e_0\| \sim_{\tau_0 \times \tau_1} |e_0| \text{ and } \|e_1\| \sim_{\tau} |e_1|. \quad \text{From } \|e_0\| \sim_{\tau_0 \times \tau_1} |e_0| \text{ it follows by definition that} \\ & \forall k, \langle k, \pi_0 \|e_0\|_p \rangle \sim_{\tau_0} \pi_0 |e_0| \text{ and } \forall k, \langle k, \pi_1 \|e_1\|_p \rangle \sim_{\tau_1} \pi_1 |e_1|. \quad \text{The complixity translation} \\ & \text{is } \|split(e_0, x_0.x_1.e_1)\| = \|e_0\|_c +_c \|e_1\| [\pi_0 \|e_0\|_p / x_0, \pi_1 \|e_1\|_p / x_1]. \quad \text{The pure potential} \\ & \text{translation is } |split(e_0, x_0.x_1.e_1)| = |e_1| [\pi_0 |e_0| / x_0, \pi_1 |e_0| / x_1]. \quad \text{By 4.1, it suffices to show} \\ & \|e_1\| [\pi_0 \|e_0\|_p / x_0, \pi_1 \|e_1\|_p / x_1] \sim_{\tau} |e_1| [\pi_0 |e_0| / x_0, \pi_1 |e_0| / x_1] \quad \text{By definition of the relation,} \\ & \text{the suffices to show } \|e_1\| \sim_{\tau} |e_1|, \quad \forall k, \langle k, \pi_0 \|e_0\|_p \rangle \sim_{\tau_0} \pi_0 |e_0|, \quad \text{and} \quad \forall k, \langle k, \pi_1 \|e_0\|_p \rangle \sim_{\tau_1} \\ & \text{DRAFT: April 7, 2016} \end{aligned}$

 $\pi_1|e_0|$. Since we have already establed all three conditions, we have $||split(e_0, x_0.x_1.e_1)|| \sim_{\tau} ||split(e_0, x_0.x_1.e_1)||$.

Case $\frac{\gamma, x: \sigma \vdash e: \tau}{\gamma \vdash \lambda x.e: \sigma \to \tau}$ By the induction hypothesis $\|e\| \sim_{\tau} |e|$. The complexity translation is $\|\lambda x.e\| = \langle 0, \lambda x. \|e\| \rangle$. The pure potential translation is $|\lambda x.e| = \lambda x. |e|$. Let $E_0: \|\sigma\|$ and $E_0': |\sigma|$ be complexity language terms such that $E_0 \sim_{\sigma} E_0'$. Then $\langle 0, \lambda x. \|e\| \rangle E_0 \to \langle 0 + E_{0c}, \|e\| [x \mapsto E_0] \rangle$ and $\lambda x. |e| E_0' \to |e| [x \mapsto E_0']$. Since $\|e\| \sim_{\tau} |e|$ and $E_0 \sim_{\sigma} E_0'$, $\|e\| [x \mapsto E_0] \sim_{\tau} |e| [x \mapsto E_0']$. By 4.2, $\langle 0, \lambda x. \|e\| \rangle E_0 \sim_{\tau} (\lambda x. |e|) E_0'$. So by definition $\langle 0, \lambda x. \|e\| \rangle \sim_{\sigma \to \tau} \lambda x. |e|$. So $\|\lambda x.e\| \sim_{\sigma \to \tau} |\lambda x.e|$.

Case $\frac{\gamma \vdash e_0 : \sigma \to \tau}{\gamma \vdash e_0 \; e_1 : \tau}$ The complexity translation is $\|e_0 \; e_1\| = (1 + \|e_0\|_c + \|e_1\|_c) +_c \|e_0\|_p \|e_1\|_p$. The pure potential translation is $|e_0 \; e_1| = |e_0||e_1|$. By 4.1, it suffices to show $\|e_0\|_p \|e_1\|_p \sim_\tau |e_0||e_1|$. By the induction hypothesis, $\|e_0\| \sim_{\sigma \to \tau} |e_0|$ and $\|e_1\| \sim_\sigma |e_1|$. By definition, $\|e_0\|_p \|e_1\|_p \sim_\tau |e_0||e_1|$.

Case $\frac{\gamma \vdash e : \tau}{\gamma \vdash delay(e) : susp \ \tau}$ By the induction hypothesis $\|e\| \sim_{\tau} |e|$. So $\langle 0, \|e\| \rangle \sim_{\text{susp } \tau} |e|$. The complexity translation is $\|delay(e)\| = \langle 0, \|e\| \rangle$. The pure potential translatio is |delay(e)| = |e|. So $\|delay(e)\| \sim_{\text{susp } \tau} |delay(e)|$.

Case $\frac{\gamma \vdash e : susp \ \tau}{\gamma \vdash force(e) : \tau}$ By the induction hypothesis $||e|| \sim_{susp \ \tau} |e|$. So by definition of the relation at susp type, $||e||_p \sim_\tau |e|$. By 4.1, $\forall k, \langle k, ||e||_{pp} \rangle \sim_\tau |e|$. The complexity translation is $||force(e)|| = ||e||_c +_c ||e||_p$. The pure potential translation is ||force(e)|| = ||e||. So $||e||_c +_c ||e||_p \sim_\tau |e|$. So $||force(e)|| \sim_\tau ||force(e)||$.

Case $\frac{\gamma \vdash e_0 : \sigma}{\gamma \vdash let(e_0, x.e_1) : \tau}$ By the induction hypothesis $\|e_0\| \sim_{\sigma} |e_0|$ and $\|e_1\| \sim_{\tau} |e_1|$. So $\|e_1\|[\|e_0\|_p/x] \sim_{\tau} |e_1|[|e_0|/x]$. By 4.1, $\forall k, \langle k, \|e_1\|_p[\|e_0\|_p/x] \rangle \sim_{\tau} |e_1|[|e_0|/x]$. The complexity translation is $\|let(e_0, x.e_1)\| = \|e_0\|_c +_c \|e_1\|[\|e_0\|_p/x]$. The pure potential translation is $|let(e_0, x.e_1)| = |e_1|[|e_0|/x]$. So $\|let(e_0, x.e_1)\| \sim_{\tau} |let(e_0, x.e_1)|$.

Case $\frac{\gamma, x : \tau_0 \vdash v_1 : \tau_1 \qquad \gamma \vdash v_0 : \phi[\tau_0]}{\gamma \vdash map^{\phi}(x.v_1, v_0) : \phi[\tau_1]}$ By the induction hypothesis $||v_1|| \sim_{\tau_1} |v_1|$ and $||v_0|| \sim_{\phi[\tau_0]} |v_0|$. By 4.4, $\forall k, \langle k, map^{\Phi}(x.||v_1||_p, ||v_0||_p) \rangle \sim_{\phi[\tau_1]} map^{\Phi}(x.||v_1||, ||v_0||)$. The

complexity translation is $\|map^{\phi}(x.v_1, v_0)\| = \langle 0, map^{\Phi}(x.\|v_0\|_p, \|v_1\|_p) \rangle$. The pure potential translation is $|map^{\phi}(x.v_1, v_0)| = map^{\Phi}(x, |v_0|, |v_1|)$. So we have $\|map^{\phi}(x.v_1, v_0)\| \sim_{\phi[\tau_1]} \|map^{\phi}(x.v_1, v_0)\|$.

Case $\frac{\gamma \vdash e_0 : \delta \quad \forall C(\gamma, x : \phi_C[\delta \times susp \ \tau] \vdash e_c : \tau}{\gamma \vdash rec^{\delta}(e_0, \overline{C \mapsto x.e_C}) : \tau} \text{ By the induction hypothesis}$ $\|e_0\| \sim_{\delta} |e_0| \text{ and } \forall C, \|e_c\| \sim_{\tau} |e_c|. \text{ By } 4.1, \ \forall k, \langle k \|e_C\| \sim_{\tau} |e_c, \text{ so } 1 +_c \|e_C\| \sim_{\tau} |e_c|. \text{ So}$ by 4.5, $rec(\|e_0\|_p, \overline{C \mapsto x.1 +_c \|e_C\|}) \sim_{\tau} rec(|e_0|, \overline{C \mapsto x.1 +_c |e_C|}). \text{ So by } 4.1, \ \|e_0\|_c +_c rec(\|e_0\|_p, \overline{C \mapsto x.1 +_c \|e_C\|}) \sim_{\tau} rec(|e_0|, \overline{C \mapsto x.1 +_c |e_C|})$

Case $\frac{\gamma \vdash e : \phi[\delta]}{\gamma \vdash Ce : \delta}$ By the induction hypothesis, $\|e\| \sim_{\phi[\delta]} |e|$. There exists V, V' such that $\|e\| \downarrow V$ and $|e| \downarrow V'$. By 4.3 $V \sim_{\phi[\delta]} V'$. Since $\|e\| \downarrow V$, $\langle k, C \|e\| \rangle \downarrow \langle k, C V_p$. Similarly, since $|e| \downarrow V'$, $C|e| \downarrow CV'$. So by definition we have $\langle k, C \|e\| \rangle \sim_{\delta} C|e|$. The complexity translation is $\|Ce\| = \langle \|e\|, C\|e\|_p \rangle$. The pure potential translation is |Ce| = C|e|. Therefore by 4.1, $\|Ce\| \sim_{\delta} |Ce|$.

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