

# Calculus

## Function Limit

$$f:\mathbb{R}^1\rightarrow\mathbb{R}^1$$

$$\begin{aligned}\lim_{x\rightarrow c}f(x)&=l\\&\equiv\forall(\epsilon>0)\,\exists(\delta>0)\,\forall x\big((0<|x-c|<\delta)\Rightarrow(|f(x)-l|<\epsilon)\big)\end{aligned}$$

$$f:\mathbb{R}^n\rightarrow\mathbb{R}^1$$

$$\begin{aligned}\lim_{\boldsymbol{x}\rightarrow\boldsymbol{x_0}}f(\boldsymbol{x})&=l\\&\equiv\forall(\epsilon>0)\,\exists(\delta>0)\,\forall\boldsymbol{x}\big((0<\|\boldsymbol{x}-\boldsymbol{x_0}\|<\delta)\Rightarrow(|f(\boldsymbol{x})-l|<\epsilon)\big)\end{aligned}$$

## Limits

$$\lim_{x\rightarrow 0}\frac{\sin x}{x}=1\tag{1}$$

$$\lim_{x\rightarrow 0}\frac{1-\cos x}{x}=0\tag{2}$$

## Differentiation

$$f:\mathbb{R}^1\rightarrow\mathbb{R}^1,\,f'(x)\in\mathbb{R}^1$$

$$f'(x)=\lim_{h\rightarrow 0}\frac{f(x+h)-f(x)}{h}$$

## Derivatives

$$\sin'=\cos\tag{3}$$

## Differentiation Formulae

$$(fg)'=f'g+fg'\tag{4}$$

$$\left(\frac{f}{g}\right)'=\frac{f'g-fg'}{g^2}\tag{5}$$

$$(f(g))'=f(g)'g'\tag{6}$$

## Integration

### Change of Variables

$$\int_a^bf(g)g'\,dx\,=\,\int_{g(a)}^{g(b)}f(u)\,du\tag{7}$$

$$\begin{aligned}\iint_Df(x,y)\,dx\,dy&=\iint_{D'}f\left(g(u,v),h(u,v)\right)\left|\frac{\partial(x,y)}{\partial(u,v)}\right|\,du\,dv\\&\qquad\text{where}\quad\frac{\partial(x,y)}{\partial(u,v)}=\begin{vmatrix}x_u&x_v\\y_u&y_v\end{vmatrix}\end{aligned}\tag{8}$$

### Integration by Parts

$$\int_a^bf(x)\,dx\,=\,\int_{v(a)}^{v(b)}u\,dv\,=\,uv-\int_{u(a)}^{u(b)}v\,du\tag{9}$$

## Natural Logarithm

$$\ln x\quad\equiv\quad\int_1^x\frac{1}{t}\,dt$$

$$\int_1^e\frac{1}{t}\,dt\equiv 1$$

$$\mathrm{e}=\sum_{k=0}^\infty\frac{1}{k!}=\lim_{x\rightarrow\infty}\left(1+\frac{1}{x}\right)^x=\lim_{x\rightarrow 0}(1+x)^{1/x}\tag{10}$$

## Partial Derivative

$$f:\mathbb{R}^3\rightarrow\mathbb{R}^1,\,\frac{\partial f}{\partial x}\in\mathbb{R}^1$$

$$\frac{\partial f}{\partial x}(x,y,z)=\lim_{h\rightarrow 0}\frac{f(x+h,y,z)-f(x,y,z)}{h}$$

## Gradient

$$\text{scaler field }f:\mathbb{R}^3\rightarrow\mathbb{R}^1,\,\nabla f\in\mathbb{R}^3$$

$$\nabla f(x,y,z)=\frac{\partial f}{\partial x}\mathbf{i}+\frac{\partial f}{\partial y}\mathbf{j}+\frac{\partial f}{\partial z}\mathbf{k}$$

$$\text{maximum rate of change}=\|\nabla f\|$$

## Divergence

$$\text{vector field }\boldsymbol{F}:\mathbb{R}^3\rightarrow\mathbb{R}^3,\,\text{div }\boldsymbol{F}\in\mathbb{R}^1$$

$$\text{div }\boldsymbol{F}=\nabla\cdot\boldsymbol{F}=\frac{\partial F_1}{\partial x}+\frac{\partial F_2}{\partial y}+\frac{\partial F_3}{\partial z}$$

## Curl

$$\text{vector field }\boldsymbol{F}:\mathbb{R}^3\rightarrow\mathbb{R}^3,\,\text{curl }\boldsymbol{F}\in\mathbb{R}^3$$

$$\begin{aligned}\text{curl }\boldsymbol{F}=\nabla\times\boldsymbol{F}&=\begin{vmatrix}\mathbf{i}&\mathbf{j}&\mathbf{k}\\\frac{\partial}{\partial x}&\frac{\partial}{\partial y}&\frac{\partial}{\partial z}\\F_1&F_2&F_3\end{vmatrix}\\&=\left(\frac{\partial F_3}{\partial y}-\frac{\partial F_2}{\partial z}\right)\mathbf{i}+\left(\frac{\partial F_1}{\partial z}-\frac{\partial F_3}{\partial x}\right)\mathbf{j}+\left(\frac{\partial F_2}{\partial x}-\frac{\partial F_1}{\partial y}\right)\mathbf{k}\end{aligned}$$

## Line Integral

$$\int_P\boldsymbol{F}\cdot d\boldsymbol{x}=\int_PF_1\,dx+F_2\,dy+F_3\,dz=\int_{P'}\left(F_1\frac{\partial x}{\partial t}+F_2\frac{\partial y}{\partial t}+F_3\frac{\partial z}{\partial t}\right)dt$$

$$\text{if }\boldsymbol{F}=\nabla g\,,$$

$$\int_P\boldsymbol{F}\cdot d\boldsymbol{x}=\int_{P'}dg$$

## Surface Integral

$$\begin{aligned}\iint_SdS&=\iint_{S'}|\mathbf{r}_u\times\mathbf{r}_v|\,du\,dv\\&=\iint_R\sqrt{1+f_x^2+f_y^2}\,dx\,dy\end{aligned}$$

## Green's Theorem

in the plane

$$\oint\boldsymbol{F}\cdot d\boldsymbol{x}=\oint F_1\,dx+F_2\,dy=\iint_R\left(\frac{\partial F_2}{\partial x}-\frac{\partial F_1}{\partial y}\right)dx\,dy$$

## Stoke's Theorem

$$\oint\boldsymbol{F}\cdot d\boldsymbol{x}=\iint_S(\nabla\times\boldsymbol{F})\cdot\mathbf{n}\,dS$$

## Divergence Theorem

$$\iint_S\boldsymbol{F}\cdot\mathbf{n}\,dS=\iiint_V\nabla\cdot\boldsymbol{F}\,dV$$

## Conservative Field

- Vector field  $\boldsymbol{F}$  is conservative.

$$\int\boldsymbol{F}\cdot d\boldsymbol{r}\text{ is path independent, }\oint\boldsymbol{F}\cdot d\boldsymbol{r}=0$$

- A scaler function  $\varphi$  exists such that  $\boldsymbol{F}=\nabla g$ .

- Curl  $\boldsymbol{F}=\mathbf{0}$ .

- $\boldsymbol{F}\cdot d\boldsymbol{r}$  is an exact differential.

$$\boldsymbol{F}\cdot d\boldsymbol{r}=\nabla g\cdot d\boldsymbol{r}=dg$$

## Directional Derivative

$$\boldsymbol{f}:\mathbb{R}^m\rightarrow\mathbb{R}^n\text{ at }\boldsymbol{c}\text{ in the direction of }\boldsymbol{u},\,\boldsymbol{f}'(\boldsymbol{c};\boldsymbol{u})\in\mathbb{R}^1$$

$$\begin{aligned}\boldsymbol{f}'(\boldsymbol{c};\boldsymbol{u})&=\lim_{h\rightarrow 0}\frac{\|\boldsymbol{f}(\boldsymbol{c}+h\boldsymbol{u})-\boldsymbol{f}(\boldsymbol{c})\|}{h}\\&=\nabla f(\boldsymbol{c})\cdot\frac{\boldsymbol{u}}{\|\boldsymbol{u}\|}\quad\text{if }\boldsymbol{f}\text{ is differentiable}\end{aligned}$$

## Total Derivative

The total derivative of  $\boldsymbol{f}:\mathbb{R}^n\rightarrow\mathbb{R}^m$  at  $\boldsymbol{c}$  is  $\boldsymbol{T_c(v)}$  where

$$\boldsymbol{f}(\boldsymbol{c}+\boldsymbol{v})=\boldsymbol{f}(\boldsymbol{c})+\boldsymbol{T_c(v)}+\|\boldsymbol{v}\|\boldsymbol{E_c(v)}$$

$$\text{and }\boldsymbol{E_c(v)}\rightarrow\mathbf{0}\text{ as }\boldsymbol{v}\rightarrow\mathbf{0}$$

$\boldsymbol{f}$  differentaible at  $\boldsymbol{c}$  implies that  $\boldsymbol{f}$  is continuous at  $\boldsymbol{c}$  and the directional derivative exists in all directions.

The total derivative of  $f:\mathbb{R}^2\rightarrow\mathbb{R}^1$  at  $(x,y)$  is  $\left[\frac{\partial f}{\partial x}\,\frac{\partial f}{\partial y}\right]$  where

$$\begin{aligned}f(x+h,y+k)&=f(x,y)+\left[\frac{\partial f}{\partial x}\,\frac{\partial f}{\partial y}\right]\begin{bmatrix}h\\k\end{bmatrix}+\|(h,k)\|\,E(h,k)\\&\text{and }E(h,k)\rightarrow 0\text{ as }(h,k)\rightarrow(0,0)\end{aligned}\tag{11}$$

$$\text{Note: }\left[\frac{\partial f}{\partial x}\,\frac{\partial f}{\partial y}\right]\begin{bmatrix}h\\k\end{bmatrix}=\nabla f(x,y)\cdot(h,k)$$