

Operating Systems Tutorial 7
Jason Runzer 100520993
Albert Fung 100520898
Nicholas Gregorio 100514374
11/8/2015

Conceptual Questions

1. Signals are software interrupts that are delivered to a process. They can report errors, asynchronous events, or report other situations to an executing program. Signals can be used as a communication tool to synchronize processes, or for parent processes to terminate child processes.
2. The signal SIGINT is used to terminate a process when the user types the INTR character or can suspend a program when the user enters the SUSP character. The SIGTSTP signal is a signal that is used for job control to stop a process. This signal can be handled and ignored by the program. The SIGCONT is used to resume a program when it is called. A program can call the SIGINT with SUSP character to suspend the program. Then the program can continue if the SIGCONT to resume it, then finally it can use the SIGTSTP signal to terminate the process.
3. The kill() function allows the program to select which process to kill. The kill function can be specified to notify a process that it has finished execution as well. This is done by using kill(pid,SIGCHLD), which will notify the parent when the child has finished execution. The waitpid() function suspends the execution of the process that called it until the selected pid that refers to a process finishes its execution.
4. A linked list is a data structure where each element in the list has a pointer to the successor in the list and the data portion. Linked lists are used to implement queues, stacks, or any other data structure that grows dynamically during the time of execution of a program. This has an advantage over an array since an initial size does not need to be defined. A queue uses a linked list to satisfy the first in, first out (FIFO) condition. An item is added to the end of the list, and traversal through the items is from the first one that was added, to the last one that was added in the queue. The common operations that a linked list implementation for a queue must have is: pop() which removes the top element in the list, and push() which adds the element to the end of the list. The rest of the functions are needed if you wish to change how a queue works.
5. A linked list in C is constructed by having a node struct, and a data struct. The node contains an instance of the data struct, and also contains a pointer to the next node struct in the list. To add a value to the queue, you would iterate through the list until the node is null, then allocate memory for the node, add the data to the node, then set the next node to null. To remove a specific value from the list, you would iterate through the linked list until the data is found, then assign the previous node's pointer to the node after the one that contains the specific data. Then you would free the node that you are removing to ensure that there are no memory leaks.

Application Questions

1.

CODE

```
#include <stddef.h>
```

```
#include <stdlib.h>
```

```
#include <stdio.h>
```

```
#include <stdbool.h>
```

```
#include <unistd.h>
```

```
#include <signal.h>
```

```
#include <sys/types.h>
```

```
#include <sys/wait.h>
```

```
#include <string.h>
```

```
typedef struct {  
    char name[256];  
    int priority;  
    int pid;  
    int runtime;  
} proc;
```

```
int MAX_BUFF_SIZE = 256;
```

```
typedef struct node {  
    proc process;  
    struct node *next;  
} node_t;
```

```
node_t *queue;
```

```
void push(proc process) {  
    node_t *current = queue; //set the current node to the first one in the queue  
  
    //traverse through the linked list until it finds the next node = to NULL  
    while (current->next != NULL) {  
        current = current->next;  
    }  
    //allocate and add the process to the list  
    current->next = (node_t *) malloc(sizeof(node_t));  
  
    current->next->process = process;  
    current->next->next = NULL; //set the next node to NULL to specify the end of the list  
}
```

```

int main(void) {
    //initialize the first node with null
    queue = NULL;
    //the temp process when pushing to the list
    //proc tempProcess;

    //allocate memory for the
    queue = malloc(sizeof(node_t));
    queue->next = NULL;

    //open the file to get the processes
    FILE *fp = fopen("processes.txt", "r");

    if (!fp) {
        printf("Error opening file");
        exit(EXIT_FAILURE);
    }

    //the line for each process
    size_t len = 0;
    ssize_t read;
    char *line = NULL;

    //while ((read = getline(&line, &len, fp)) != -1) {

    //go though the text file and add each process to the list
    while ((read = getline(&line, &len, fp)) != -1) {
        //tokenize the line with , to get each entity of the process
        proc tempProcess;
        char * tokens = NULL;
        tokens = strtok(line, ",");
        strcpy(tempProcess.name, tokens);
        tokens = strtok(NULL, ",");
        tempProcess.priority = atoi(tokens); //atoi casts a char * to an integer
        tokens = strtok(NULL, ",");
        tempProcess.pid = atoi(tokens);
        tokens = strtok(NULL, ",");
        tempProcess.runtime = atoi(tokens);
        push(tempProcess); //push the process to the list

    }
    fclose(fp);
}

```

```

//traverse through and display each item in the linked list.
node_t * current = queue;
//get rid of the sentinel node
current = current->next;

//traverse through the whole linked list
while (current != NULL) {
    proc tempProcess = current->process;
    printf("Name: %s\nPriority: %d\npid: %d\nRuntime: %d\n\n",
           tempProcess.name, tempProcess.priority, tempProcess.pid,
           tempProcess.runtime);
    current = current->next; //advance the node
}
free(line);
return 0;
}

```

OUTPUT

JasonR@ubuntu:~/git-projects/Tutorial7/Q1\$./Q1

Name: systemd

Priority: 0

pid: 1

Runtime: 5

Name: bash

Priority: 0

pid: 1000

Runtime: 8

Name: vim

Priority: 1

pid: 11992

Runtime: 3

Name: emacs

Priority: 3

pid: 11993

Runtime: 1

Name: chrome

Priority: 1

pid: 11996

Runtime: 2

Name: chrome

Priority: 1

pid: 11997

Runtime: 3

Name: chrome

Priority: 1

pid: 11998

Runtime: 1

Name: gedit

Priority: 2

pid: 12235

Runtime: 4

Name: eclipse

Priority: 2

pid: 14442

Runtime: 2

Name: clang

Priority: 1

pid: 9223

Runtime: 3

JasonR@ubuntu:~/git-projects/Tutorial7/Q1\$

2.

CODE:

```
#include <stddef.h>
#include <stdlib.h>
#include <stdio.h>
#include <stdbool.h>
#include <unistd.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <string.h>
```

```
typedef struct{
    char name[256];
    int priority;
    int pid;
    int runtime;
} proc;
```

```
int MAX_BUFF_SIZE = 256;
```

```
typedef struct node{
    proc process;
    struct node *next;
} node_t;
```

```
proc tempProc;
```

```
node_t *queue;
```

```
//adds a process to the end of the list
```

```
void push (proc process){
    node_t *current = queue; //set the current node to the first one in the queue

    //traverse through the linked list until it finds the next node = to NULL
    while(current -> next != NULL){
        current = current -> next;
    }
    //allocate and add the process to the list
    current -> next = (node_t *) malloc(sizeof(node_t));
    current -> next-> process = process;
```

```
        current-> next-> next = NULL; //set the next node to NULL to specify the end of the list
    }
```

//pops the first node in the list and returns a pointer to the process that was deleted

```
proc * pop(){
    node_t * next_node = NULL;
    if(queue -> next == NULL){
        printf("in NULL");

        return NULL;
    }
```

```
    next_node = queue -> next -> next; // get the next node after the sentinal
    node_t * currentNode = queue -> next;
    tempProc = currentNode-> process;
```

```
    //strcpy(tempProc.name,currentNode -> process.name);
```

```
    free(currentNode);
    queue -> next = next_node;
```

```
    return &tempProc;
```

```
}
```

//prints the process that is given

```
void printProc(proc *pro){

    if(pro != NULL){
        printf("Name: %s\nPriority: %d\npid: %d\nRuntime: %d\n\n",
               (pro -> name),pro ->priority,pro ->pid,pro ->runtime);
    }
}
```

/* Prints the list processes that is given.*/

```
void printList(node_t *list){
    node_t * current = list;
    //get rid of the sentinal
    current = current -> next;
```

```

while(current != NULL){

    tempProc = current ->process;
    printProc(&tempProc); //print the current process
    current = current -> next; //advance the node
}

}

//deletes the node with the name specified, If not there, returns null
proc * delete_name(char *name){
    node_t *current = queue -> next;
    node_t *previous = queue;
    while(current != NULL){

        //check the current process' name
        tempProc = current -> process;
        if(strcmp(tempProc.name,name) == 0){
            node_t *deletedNode = current;
            previous -> next = current -> next;
            free(deletedNode); //free up the memory of the node
            return &tempProc;
        }
        //get the next node in the list
        previous = current;
        current = current -> next;
    }
    printf("process not found\n");
    return NULL;
}

//deletes the node with the pid specified, If not there, returns null
proc * delete_pid(int pid){
    node_t *current = queue -> next;
    node_t *previous = queue;
    while(current != NULL){
        //check the current process' pid
        tempProc = current -> process;
        if(tempProc.pid == pid){
            node_t *deletedNode = current;
            previous -> next = current -> next;
            free(deletedNode); //free up the deleted nodes memory

```



```

        return &tempProc; //return the process that was deleted
    }
    //get the next item in the list
    previous = current;
    current = current -> next;
}
printf("process not found\n");
return NULL;
}

int main(void)
{
    //inititalize the first node with null
    queue = NULL;

    //allocate memory for the
    queue = malloc(sizeof(node_t));
    queue->next = NULL;

    //open the file to get the processes
    FILE *fp = fopen("processes.txt", "r");

    if(!fp){
        printf("Error opening file");
    }

    //the line for each process

    size_t len = 0;
    ssize_t read;
    char *line = NULL;

    //go though the text file and add each process to the list
    while ((read = getline(&line, &len, fp)) != -1) {
        //tokenize the line with , to get each entity of the process
        char * tokens = NULL;
        tokens = strtok(line, ",\n");
        strcpy(tempProc.name, tokens);
        tokens = strtok(NULL, ",\n");
        tempProc.priority = atoi(tokens); //atoi casts a char * to an integer
        tokens = strtok(NULL, ",\n");
    }
}

```

```
        tempProc.pid = atoi(tokens);
        tokens = strtok(NULL, ",\n");
        tempProc.runtime = atoi(tokens);
        push(tempProc); //push the process to the list
    }
    fclose(fp);

    //traverse through and display each item in the linked list.
    printList(queue);

    printf("\n\n\n");

    //delete the processes
    delete_name("emacs");
    delete_pid(12235);

    printf("POP\n");
    while(queue -> next != NULL){
        printProc(pop());
    }

    free(line);
    return 0;

}
```

OUTPUT

```
JasonR@ubuntu:~/git-projects/Tutorial7/Q2$ ./Q2
Name: systemd
Priority: 0
pid: 1
Runtime: 5

Name: bash
Priority: 0
pid: 1000
Runtime: 8

Name: vim
Priority: 1
pid: 11992
Runtime: 3

Name: emacs
Priority: 3
pid: 11993
Runtime: 1

Name: chrome
Priority: 1
pid: 11996
Runtime: 2

Name: chrome
Priority: 1
pid: 11997
Runtime: 3

Name: chrome
Priority: 1
pid: 11998
Runtime: 1

Name: gedit
Priority: 2
pid: 12235
Runtime: 4

Name: eclipse
Priority: 2
pid: 14442
Runtime: 2

Name: clang
Priority: 1
pid: 9223
Runtime: 3
```

```
POP
Name: systemd
Priority: 0
pid: 1
Runtime: 5

Name: bash
Priority: 0
pid: 1000
Runtime: 8

Name: vim
Priority: 1
pid: 11992
Runtime: 3

Name: chrome
Priority: 1
pid: 11996
Runtime: 2

Name: chrome
Priority: 1
pid: 11997
Runtime: 3

Name: chrome
Priority: 1
pid: 11998
Runtime: 1

Name: eclipse
Priority: 2
pid: 14442
Runtime: 2

Name: clang
Priority: 1
pid: 9223
Runtime: 3

JasonR@ubuntu:~/git-projects/Tutorial7/Q2$
```

3.

Code:

```
/*
 * Q3.c
 *
 * Created on: Nov 4, 2015
 * Author: uoitstudent
 */
```

```
#include <stddef.h>
```

```
#include <stdlib.h>
```

```
#include <stdio.h>
```

```

#include <stdbool.h>
#include <unistd.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/wait.h>
#define SHELL "/bin/sh"

int main(int argc, char *argv[]) {
    int status;
    pid_t pid;
    const char *command = "./process";
    pid = fork();

    if (pid < 0) {
        //Failed
    } else if (pid == 0) {
        //Child Process
        execv(command, argv);
        exit(0);
        _exit(EXIT_FAILURE);

    } else {
        //Parent Process
        sleep(5);
        kill(pid, SIGINT);
        if(wait(&status)){
            printf("Child terminated");
        }
    }
}

```

Output:

```
JasonR@ubuntu:~/git-projects/Tutorial7/Q3$ ./Q3
54067; START
54067; tick 1
54067; tick 2
54067; tick 3
54067; tick 4
54067; tick 5
54067; SIGINT
Child terminatedJasonR@ubuntu:~/git-projects/Tutorial7/Q3$
```

4.

Code:

```
//includes
#include <stddef.h>
#include <stdlib.h>
#include <stdio.h>
#include <stdbool.h>
#include <unistd.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/wait.h>

#define SHELL "/bin/sh"

int main(int argc, char *argv[]) {
    //command to execute
    const char *command = "./process";
    int status;
    pid_t pid;

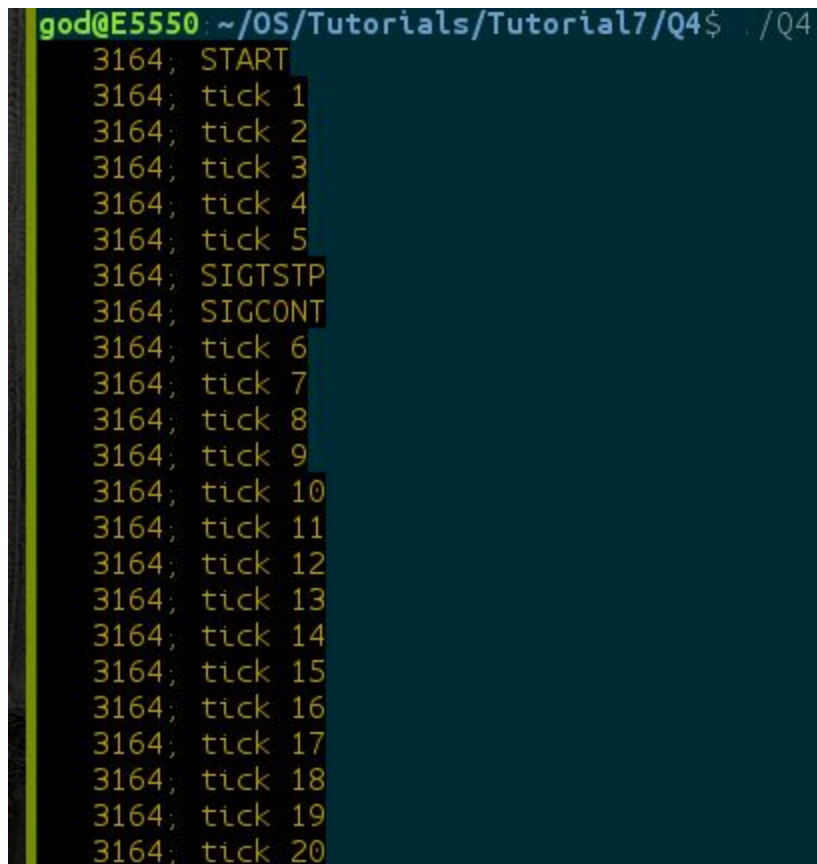
    //fork the child
    pid = fork();
    if (pid == 0) { //CHILD
        //execute command
        execv(command, argv);
        exit(0);
        _exit(EXIT_FAILURE);
    } else if (pid < 0) {
        //FORK FAILED
        status = -1;
    } else { //PARENT
        //sleep for 5 seconds
        sleep(5);
    }
}
```

```

        //send SIGTSTP to suspend the proc
        kill(pid, SIGTSTP);
        //sleep for 10 seconds
        sleep(10);
        //send SIGCONT to resume the proc
        kill(pid, SIGCONT);
        //wait for child to terminate
        waitpid(pid, &status, 0);
        //if child terminates normally
        if (status == 0) {
            exit(0);
        }
        return status;
    }
}

```

Output:



```

god@E5550: ~/OS/Tutorials/Tutorial7/Q4$ ./Q4
3164; START
3164; tick 1
3164; tick 2
3164; tick 3
3164; tick 4
3164; tick 5
3164; SIGTSTP
3164; SIGCONT
3164; tick 6
3164; tick 7
3164; tick 8
3164; tick 9
3164; tick 10
3164; tick 11
3164; tick 12
3164; tick 13
3164; tick 14
3164; tick 15
3164; tick 16
3164; tick 17
3164; tick 18
3164; tick 19
3164; tick 20

```

5.

Code:

```
#include <stddef.h>
```

```

#include <stdlib.h>
#include <stdio.h>
#include <stdbool.h>
#include <unistd.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <string.h>

#define SHELL "/bin/sh"

typedef struct {
    char name[256];
    int priority;
    int pid;
    int runtime;
} proc;

int MAX_BUFF_SIZE = 256;

typedef struct node {
    proc process;
    struct node *next;
} node_t;

node_t *queue;
proc tempProc;

//the methods below are taken from Q1 and Q2

void push(proc process) {
    node_t *current = queue; //set the current node to the first one in the queue
    //traverse through the linked list until it finds the next node = to NULL
    while (current->next != NULL) {
        current = current->next;
    }
    //allocate and add the process to the list
    current->next = (node_t *) malloc(sizeof(node_t));
    current->next->process = process;
    current->next->next = NULL; //set the next node to NULL to specify the end of the list
}

proc * delete_name(char *name) {

```



```

node_t *current = queue->next;
node_t *previous = queue;
while (current != NULL) {

    tempProc = current->process;
    if (strcmp(tempProc.name, name) == 0) {
        node_t *deletedNode = current;
        previous->next = current->next;
        free(deletedNode);
        return &tempProc;
    }
    previous = current;
    current = current->next;
}
printf("process not found\n");
return NULL;
}

//pops the first node in the list and returns a pointer to the process that was deleted
proc * pop() {
    node_t * next_node = NULL;
    if (queue->next == NULL) {
        printf("in NULL");

        return NULL;
    }

    next_node = queue->next->next; // get the next node after the sentinel
    node_t * currentNode = queue->next;
    tempProc = currentNode->process;

    //strcpy(tempProc.name,currentNode -> process.name);

    free(currentNode);
    queue->next = next_node;

    return &tempProc;
}

//prints the process that is given
void printProc(proc *pro) {
    if (pro != NULL) {
        printf("Name: %s\nPriority: %d\npid: %d\nRuntime: %d\n\n", (pro->name),

```

```

        pro->priority, pro->pid, pro->runtime);
    }
}

```

```

//prints the contents of the list given
void printList(node_t *list) {
    node_t * current = list;
    //get rid of the sentinel
    current = current->next;
    while (current != NULL) {
        tempProc = current->process;
        printProc(&tempProc); //print the current process
        current = current->next; //advance the node
    }
}

```

```

int main(int argc, char *argv[]) {
    //italize the first node with null
    queue = NULL;
    //allocate memory for the linkedlist
    queue = malloc(sizeof(node_t));
    queue->next = NULL;
    //open the file to get the processes

    proc tempProcess;

    ////////////FILE STRUCTURE//////////
    //NAME, PRIORITY, PID(0), RUNTIME IN SECONDS
    ////////////

    FILE *fp = fopen("processes_q5.txt", "r");

    if (!fp) {
        printf("Error opening file");
        exit(EXIT_FAILURE);
    }

    //the line for each process
    size_t len = 0;
    ssize_t read;
    char *line = NULL;

    //go though the text file and add each process to the list

```

```

while ((read = getline(&line, &len, fp)) != -1) {
    //tokenize the line with , to get each entity of the process
    char * tokens = NULL;
    tokens = strtok(line, ",\n");
    strcpy(tempProcess.name, tokens);
    tokens = strtok(NULL, ",\n");
    tempProcess.priority = atoi(tokens); //atoi casts a char * to an integer
    tokens = strtok(NULL, ",\n");
    tempProcess.pid = 0;
    tempProcess.runtime = atoi(tokens);
    push(tempProcess); //push the process to the list
}
//close the file
fclose(fp);
node_t * current = queue;
//get rid of the sentinel node
current = current->next;
while (current != NULL) {
    tempProcess = current->process; //advance the node
    if (tempProcess.priority == 0) { //priority zero queue
        //command to execute
        const char *command = tempProcess.name;
        int status;
        pid_t pid;
        //fork the child
        pid = fork();
        if (pid == 0) { //CHILD
            //execute command
            execv(command, argv);
            //remove from process struc
            delete_name(tempProcess.name);
            //execute the process binary
            execv("./process", argv);
            exit(0);
        } else if (pid < 0) { //FORK FAILED
            status = -1;
        } else { //PARENT
            //sleep for the runtime after exec, then kill the proc with SIGINT
            sleep(tempProcess.runtime);
            //send SIGINT to suspend the proc
            kill(pid, SIGINT);
            //wait for child to terminate
            waitpid(pid, &status, 0);
        }
    }
    current = current->next;
}

```

```

        if (status == 0) { //if child terminates normally
            //set pid returned from exec()
            tempProcess.pid = pid;
            printProc(&tempProcess);
            //iterate to next item in the linkedlist
            current = current->next;
        }
    }
} else { //rest of the queue
    //command to execute
    const char *command = tempProcess.name;
    int status;
    pid_t pid;
    //fork the child
    pid = fork();
    if (pid == 0) { //CHILD
        //execute command
        execv(command, argv);
        exit(0);
    } else if (pid < 0) { //FORK FAILED
        status = -1;
    } else { //PARENT
        //sleep for the runtime after exec, then kill the proc with SIGINT
        sleep(tempProcess.runtime);
        //send SIGINT to suspend the proc
        kill(pid, SIGINT);
        //wait for child to terminate
        waitpid(pid, &status, 0);
        if (status == 0) { //if child terminates normally
            //set pid returned from exec()
            tempProcess.pid = pid;
            //prints name, priority, pid and runtime of process
            printProc(&tempProcess);
            //iterate to next item in the linkedlist
            current = current->next;
            pop(); //pops the remaining process off the queue
        }
    }
}

}

/*
printf("Printing out rest of queue: \n");
printList(queue);

```

```

    */
    return 0;
}

```

Output:

```

god@E5550: ~/OS/Tutorials/Tutorial7/Q5$ ./Q5
3513; START
3513; tick 1
3513; tick 2
3513; tick 3
3513; tick 4
3513; tick 5
3513; SIGINT
Name: systemd
Priority: 0
pid: 3513
Runtime: 5

3521; START
3521; tick 1
3521; tick 2
3521; tick 3
3521; tick 4
3521; tick 5
3521; tick 6
3521; tick 7
3521; tick 8
3521; SIGINT
Name: bash
Priority: 0
pid: 3521
Runtime: 8

Name: vim
Priority: 1
pid: 3528
Runtime: 3

Name: emacs
Priority: 3
pid: 3532
Runtime: 1

Name: chrome
Priority: 1
pid: 3533
Runtime: 2

Name: chrome
Priority: 1
pid: 3537
Runtime: 3

Name: chrome
Priority: 1
pid: 3538
Runtime: 1

```

Name: gedit
Priority: 2
pid: 3542
Runtime: 4

Name: eclipse
Priority: 2
pid: 3547
Runtime: 2

Name: clang
Priority: 1
pid: 3550
Runtime: 3