

Racecar 101

James Wright

September 8, 2022

Outline

- 1 What makes a car fast?
- 2 Vehicle Basics
- 3 Vehicle Balance and Control
- 4 Three Tenants of Racecar Design

Note

This first part is a very simplified breakdown

- It's not the most accurate
- It's not to insult anyone's intelligence

It's simply to not distract from the things that can be easily forgotten or muddled.

Also, I like audience participation. Ask questions. I'll be asking y'all questions.

Table of Contents

- 1 What makes a car fast?
- 2 Vehicle Basics
- 3 Vehicle Balance and Control
- 4 Three Tenants of Racecar Design

What makes a car go fast?

$$\text{Time} = \frac{\text{Distance}}{\text{Velocity}}$$

¹Assuming distance is constant

What makes a car go fast?

$$\text{Time} = \frac{\text{Distance}}{\text{Velocity}}$$

- To lower time, we need to increase velocity¹

¹Assuming distance is constant

What makes a car go fast?

$$\text{Time} = \frac{\text{Distance}}{\text{Velocity}}$$

- To lower time, we need to increase velocity¹
- All motorsports have velocity changes during a race
 - Excluding top-speed records of course

¹Assuming distance is constant

What makes a car go fast?

$$\text{Time} = \frac{\text{Distance}}{\text{Velocity}}$$

- To lower time, we need to increase velocity¹
- All motorsports have velocity changes during a race
 - Excluding top-speed records of course
- Change in velocity is...

¹Assuming distance is constant

What makes a car go fast?

$$\text{Time} = \frac{\text{Distance}}{\text{Velocity}}$$

- To lower time, we need to increase velocity¹
- All motorsports have velocity changes during a race
 - Excluding top-speed records of course
- Change in velocity is... **Acceleration**

¹Assuming distance is constant

What makes a car go fast?

$$\text{Time} = \frac{\text{Distance}}{\text{Velocity}}$$

- To lower time, we need to increase velocity¹
- All motorsports have velocity changes during a race
 - Excluding top-speed records of course
- Change in velocity is... **Acceleration**
- To maximize velocity, you must maximize acceleration
 - ie. Whatever changes in velocity you make, do them as quickly as possible

¹Assuming distance is constant

What makes a car go fast?

$$\text{Time} = \frac{\text{Distance}}{\text{Velocity}}$$

- To lower time, we need to increase velocity¹
- All motorsports have velocity changes during a race
 - Excluding top-speed records of course
- Change in velocity is... **Acceleration**
- To maximize velocity, you must maximize acceleration
 - ie. Whatever changes in velocity you make, do them as quickly as possible

To make a car **faster**, you must make the car **accelerate more**

¹Assuming distance is constant

What famous equation involves acceleration?

What famous equation involves acceleration?

Newton's 2nd law!

$$F = ma$$

What famous equation involves acceleration?

Newton's 2nd law!

$$F = ma$$

We care about acceleration, so rearrange:

$$a = \frac{F}{m}$$

How do we maximize acceleration?

$$a = \frac{F}{m}$$

Decrease Mass

- Make things lighter

How do we maximize acceleration?

$$a = \frac{F}{m}$$

Decrease Mass

- Make things lighter

Increase Force

How do we maximize acceleration?

$$a = \frac{F}{m}$$

Decrease Mass

- Make things lighter

Increase Force

- Increase the force the tires can apply to the ground

How do we maximize acceleration?

$$a = \frac{F}{m}$$

Decrease Mass

- Make things lighter

Increase Force

- Increase the force the tires can apply to the ground
- Increase power output

How do we maximize acceleration?

$$a = \frac{F}{m}$$

Decrease Mass

- Make things lighter

Increase Force

- Increase the force the tires can apply to the ground
- Increase power output
- Increase braking torque

How do we maximize acceleration?

$$a = \frac{F}{m}$$

Decrease Mass

- Make things lighter

Increase Force

- Increase the force the tires can apply to the ground
- Increase power output
- Increase braking torque

The latter two hold **only if the tires can transfer the torque**

Balancing \uparrow Force vs \downarrow Mass

Balancing \uparrow Force vs \downarrow Mass

Sometimes \uparrow mass + \uparrow force = \uparrow acceleration

Balancing \uparrow Force vs \downarrow Mass

Sometimes \uparrow mass + \uparrow force = \uparrow acceleration

Bigger Engine

Increases the total vehicle mass, but increases power output
Depending on the ratio, can lead to better acceleration.

Balancing \uparrow Force vs \downarrow Mass

Sometimes \uparrow mass + \uparrow force = \uparrow acceleration

Bigger Engine

Increases the total vehicle mass, but increases power output
Depending on the ratio, can lead to better acceleration.

Sometimes \downarrow mass + \downarrow force = \uparrow acceleration

Balancing \uparrow Force vs \downarrow Mass

Sometimes \uparrow mass + \uparrow force = \uparrow acceleration

Bigger Engine

Increases the total vehicle mass, but increases power output
Depending on the ratio, can lead to better acceleration.

Sometimes \downarrow mass + \downarrow force = \uparrow acceleration

Smaller/Narrower Tires

Decreases total vehicle mass, but decreases total acceleration potential
Also reduces unsprung mass (improves vehicle handling and response)

Longitudinal Acceleration

Simplest acceleration to model:

$$a = \frac{F}{m}$$

Tire traction capacity sets upper limit of the acceleration.

Longitudinal Acceleration

Simplest acceleration to model:

$$a = \frac{F}{m}$$

Tire traction capacity sets upper limit of the acceleration.

Divided into 2 components:

Longitudinal Acceleration

Simplest acceleration to model:

$$a = \frac{F}{m}$$

Tire traction capacity sets upper limit of the acceleration.

Divided into 2 components:

- 1 Braking (negative)

Longitudinal Acceleration

Simplest acceleration to model:

$$a = \frac{F}{m}$$

Tire traction capacity sets upper limit of the acceleration.

Divided into 2 components:

- 1 Braking (negative)

Braking should **ALWAYS** be limited by tire traction

Longitudinal Acceleration

Simplest acceleration to model:

$$a = \frac{F}{m}$$

Tire traction capacity sets upper limit of the acceleration.

Divided into 2 components:

- 1 Braking (negative)

Braking should **ALWAYS** be limited by tire traction

- This is as much for safety as it is performance
- Ensure that car is capable of absolute maximum braking acceleration

Longitudinal Acceleration

Simplest acceleration to model:

$$a = \frac{F}{m}$$

Tire traction capacity sets upper limit of the acceleration.

Divided into 2 components:

① Braking (negative)

Braking should **ALWAYS** be limited by tire traction

- This is as much for safety as it is performance
- Ensure that car is capable of absolute maximum braking acceleration

② Power (positive)

Longitudinal Acceleration

Simplest acceleration to model:

$$a = \frac{F}{m}$$

Tire traction capacity sets upper limit of the acceleration.

Divided into 2 components:

① Braking (negative)

Braking should **ALWAYS** be limited by tire traction

- This is as much for safety as it is performance
- Ensure that car is capable of absolute maximum braking acceleration

② Power (positive)

- Almost always limited by the power unit (ICE, electric motor, rubber band windup, etc.)

Lateral Acceleration

Turning causes *Lateral Acceleration*, which is not a change in speed, but of direction:

$$a_{\text{lat}} = \frac{V^2}{r}$$

where V is velocity, and r is the turning radius.

Lateral Acceleration

Turning causes *Lateral Acceleration*, which is not a change in speed, but of direction:

$$a_{\text{lat}} = \frac{V^2}{r}$$

where V is velocity, and r is the turning radius.

Plugging back into momentum balance yields:

$$F = m \frac{V^2}{r} \Rightarrow V = \sqrt{\frac{Fr}{m}}$$

Lateral Acceleration

Turning causes *Lateral Acceleration*, which is not a change in speed, but of direction:

$$a_{\text{lat}} = \frac{V^2}{r}$$

where V is velocity, and r is the turning radius.

Plugging back into momentum balance yields:

$$F = m \frac{V^2}{r} \Rightarrow V = \sqrt{\frac{Fr}{m}}$$

Therefore given:

- a force, F (tire traction)
- a mass, m (the car)
- and a radius, r (the track/racing line)

there is a **limit to the maximum velocity**

Lateral Acceleration cont.

How do we maximize the velocity? $V = \sqrt{\frac{Fr}{m}}$

Lateral Acceleration cont.

How do we maximize the velocity? $V = \sqrt{\frac{Fr}{m}}$

- 1 Decrease mass m

Lateral Acceleration cont.

How do we maximize the velocity? $V = \sqrt{\frac{Fr}{m}}$

- ① Decrease mass m
 - Add lightness
 - Has compounding affect due to load transfer (discussed later)

Lateral Acceleration cont.

How do we maximize the velocity? $V = \sqrt{\frac{Fr}{m}}$

- ① Decrease mass m
 - Add lightness
 - Has compounding affect due to load transfer (discussed later)
- ② Increase force F

Lateral Acceleration cont.

How do we maximize the velocity? $V = \sqrt{\frac{Fr}{m}}$

- ① Decrease mass m
 - Add lightness
 - Has compounding affect due to load transfer (discussed later)
- ② Increase force F
 - Increase the maximum force the tires can exert

Lateral Acceleration cont.

How do we maximize the velocity? $V = \sqrt{\frac{Fr}{m}}$

- ① Decrease mass m
 - Add lightness
 - Has compounding affect due to load transfer (discussed later)
- ② Increase force F
 - Increase the maximum force the tires can exert
 - How?

Lateral Acceleration cont.

How do we maximize the velocity? $V = \sqrt{\frac{Fr}{m}}$

① Decrease mass m

- Add lightness
- Has compounding affect due to load transfer (discussed later)

② Increase force F

- Increase the maximum force the tires can exert
- How?
 - Aero downforce
 - Different tires
 - Suspension design, etc....

Quick Review

Higher Acceleration = Faster Car

	Limited by	How to make better?
Longitudinal Acceleration	Force (Braking and Power)	Bigger Engine/Brakes
	Mass	Reduce it
Lateral Acceleration	Force (Tire Traction)	Increase Grip
	Mass	Reduce it

Table of Contents

- 1 What makes a car fast?
- 2 Vehicle Basics**
- 3 Vehicle Balance and Control
- 4 Three Tenants of Racecar Design

G-G Curve

What about lateral and longitudinal acceleration at the same time?

G-G Curve

What about lateral and longitudinal acceleration at the same time? Answer: look at a G-G curve for the car

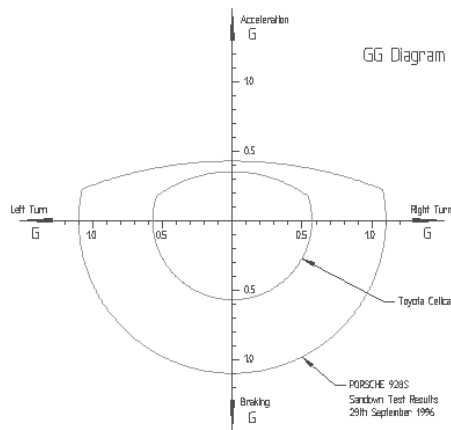


Figure 2

G-G Curve

What about lateral and longitudinal acceleration at the same time? Answer: look at a G-G curve for the car

G-G Curve (or Traction Circle)

- Plots **maximum steady-state acceleration** that a vehicle can have in **any direction**

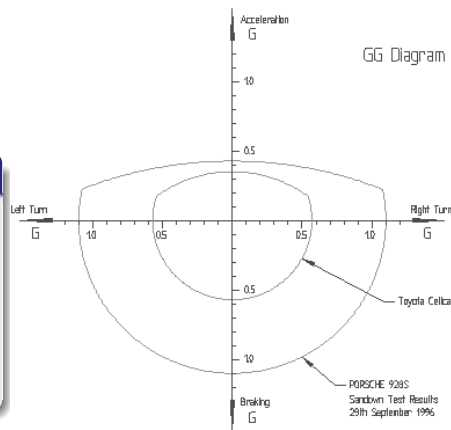


Figure 2

G-G Curve

What about lateral and longitudinal acceleration at the same time? Answer: look at a G-G curve for the car

G-G Curve (or Traction Circle)

- Plots **maximum steady-state acceleration** that a vehicle can have in **any direction**
- Outside circle = lost traction, locked wheels, etc

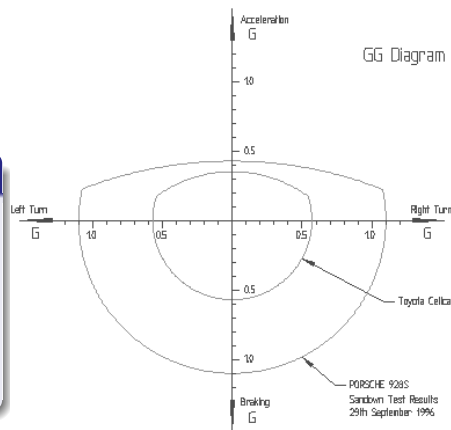


Figure 2

G-G Curve

What about lateral and longitudinal acceleration at the same time? Answer: look at a G-G curve for the car

G-G Curve (or Traction Circle)

- Plots **maximum steady-state acceleration** that a vehicle can have in **any direction**
- Outside circle = lost traction, locked wheels, etc
- Inside circle = within limits of the vehicle

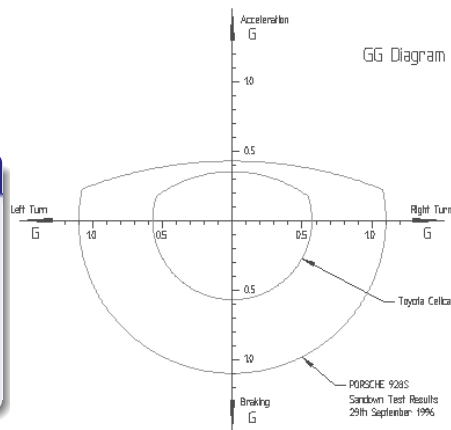


Figure 2

G-G Curve

What about lateral and longitudinal acceleration at the same time? Answer: look at a G-G curve for the car

G-G Curve (or Traction Circle)

- Plots **maximum steady-state acceleration** that a vehicle can have in **any direction**
- Outside circle = lost traction, locked wheels, etc
- Inside circle = within limits of the vehicle
- On the circle = driving at the edge

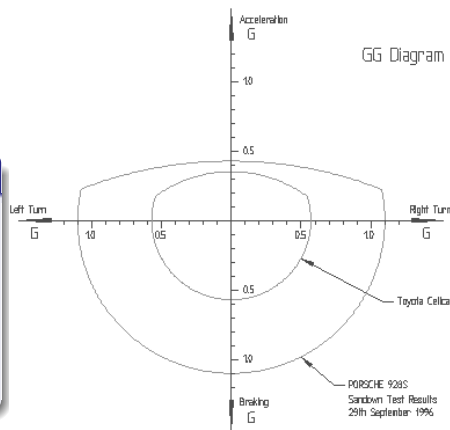


Figure 2

G-G Curve: Misc Remarks

- Circles

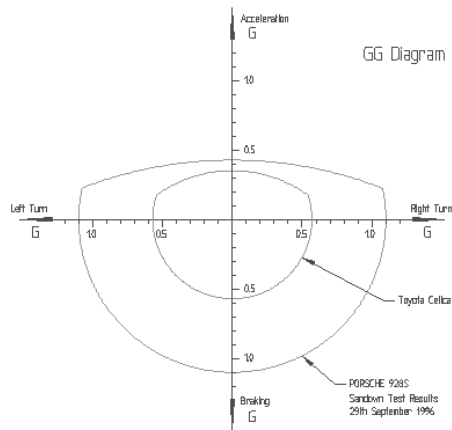


Figure 2

G-G Curve: Misc Remarks

- Circles
 - Shape of the curve is circular, due to tires

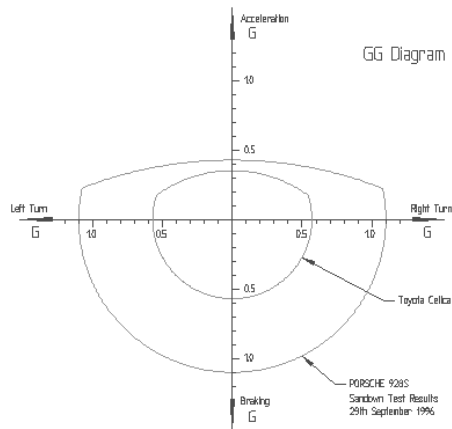


Figure 2

G-G Curve: Misc Remarks

- Circles
 - Shape of the curve is circular, due to tires
 - Tires can be assumed to have a maximum **force vector** which can be applied in **any direction**

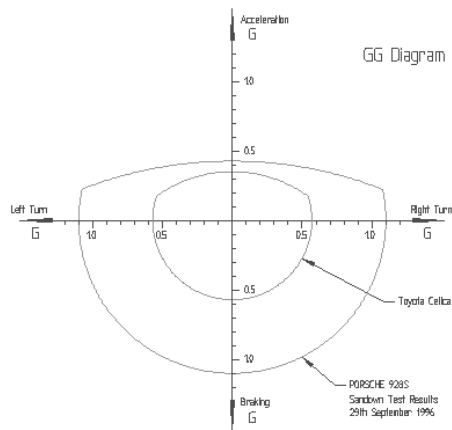


Figure 2

G-G Curve: Misc Remarks

- Circles
 - Shape of the curve is circular, due to tires
 - Tires can be assumed to have a maximum **force vector** which can be applied in **any direction**
- Positive Acceleration shape

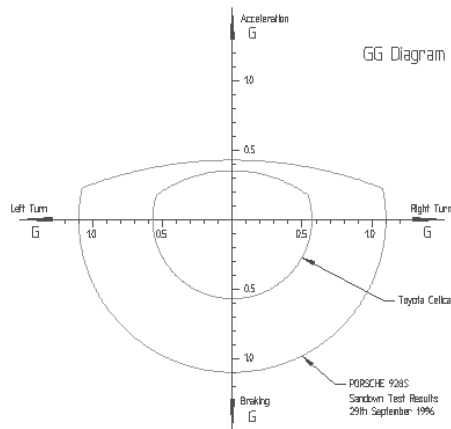


Figure 2

G-G Curve: Misc Remarks

- Circles
 - Shape of the curve is circular, due to tires
 - Tires can be assumed to have a maximum **force vector** which can be applied in **any direction**
- Positive Acceleration shape
 - Top part of curve isn't *quite* circular

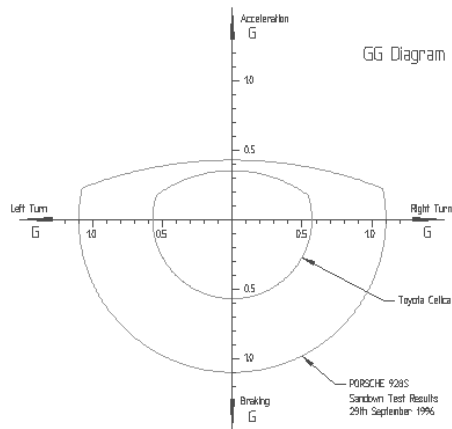


Figure 2

G-G Curve: Misc Remarks

- Circles
 - Shape of the curve is circular, due to tires
 - Tires can be assumed to have a maximum **force vector** which can be applied in **any direction**
- Positive Acceleration shape
 - Top part of curve isn't *quite* circular
 - **Positive acceleration is nearly always limited by the power unit, not the tires**
 - For (nearly) all cars, the power unit is the most severe acceleration limitation.

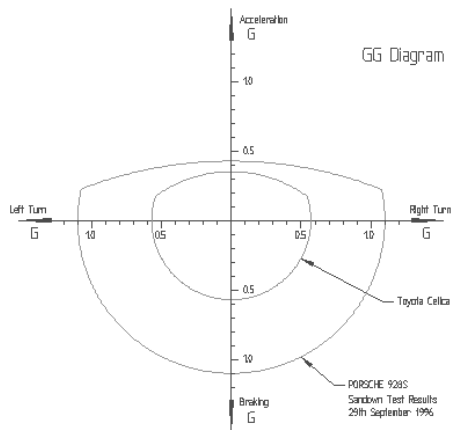


Figure 2

How do tires generate force?

How do tires generate force?

Via friction with the ground

Tires and Friction

Newton's Law of Friction

$$F = N\mu$$

where F is the max static friction force, N is the normal force, and μ is the static friction coefficient

Tires and Friction

Newton's Law of Friction

$$F = N\mu$$

where F is the max static friction force, N is the normal force, and μ is the static friction coefficient

- Tires create force via **static friction**
 - A tire is in *kinetic* friction if it's locked up or doing a burnout

Tires and Friction

Newton's Law of Friction

$$F = N\mu$$

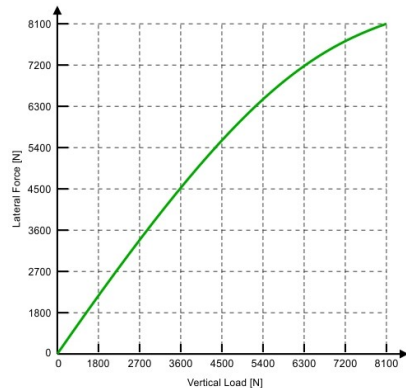
where F is the max static friction force, N is the normal force, and μ is the static friction coefficient

- Tires create force via **static friction**
 - A tire is in *kinetic* friction if it's locked up or doing a burnout
- μ is generally assumed to be constant
 - So F is linearly dependent on N

Tires and Load Sensitivity

- Tires **do not** have a constant μ :

$$F = N\mu(N)$$

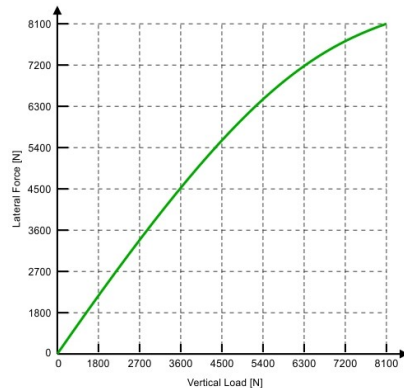


Tires and Load Sensitivity

- Tires **do not** have a constant μ :

$$F = N\mu(N)$$

- This phenomena is known as **Load Sensitivity**

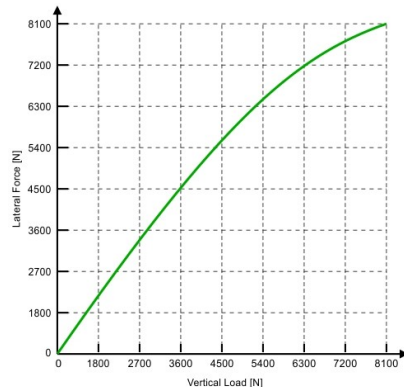


Tires and Load Sensitivity

- Tires **do not** have a constant μ :

$$F = N\mu(N)$$

- This phenomena is known as **Load Sensitivity**
- Generally, μ and N are inversely proportional
 - As $\uparrow N$, $\downarrow \mu$

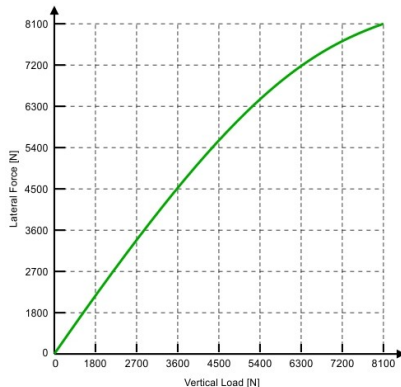


Tires and Load Sensitivity

- Tires **do not** have a constant μ :

$$F = N\mu(N)$$

- This phenomena is known as **Load Sensitivity**
- Generally, μ and N are inversely proportional
 - As $\uparrow N$, $\downarrow \mu$



Load Sensitivity is the singular most impactful thing in racecar design

It alters practically every single decision

Load Transfer

Load Transfer

Load Transfer

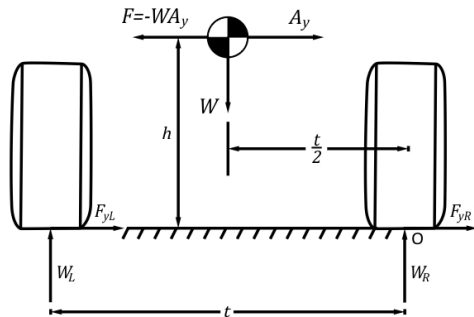
Load Transfer

- Weight of vehicle shifting due to acceleration

Load Transfer

Load Transfer

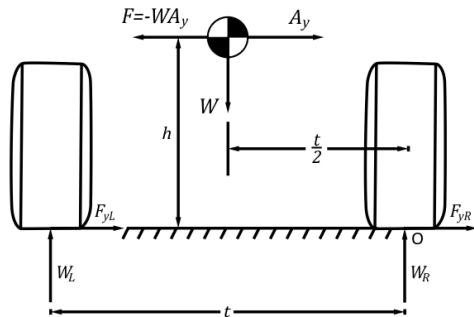
- Weight of vehicle shifting due to acceleration
- Caused by torque of tires against CG, *not* by body roll



Load Transfer

Load Transfer

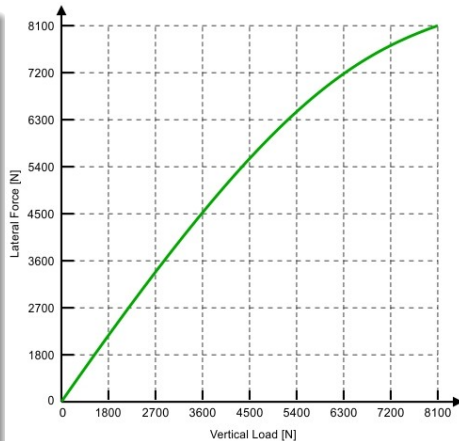
- Weight of vehicle shifting due to acceleration
- Caused by torque of tires against CG, *not by body roll*
- **Reduces global vehicle grip due to load sensitivity**



Load Transfer Example

No load transfer vs 50% load transfer

Assume 4.5kN of static vertical load on each tire.

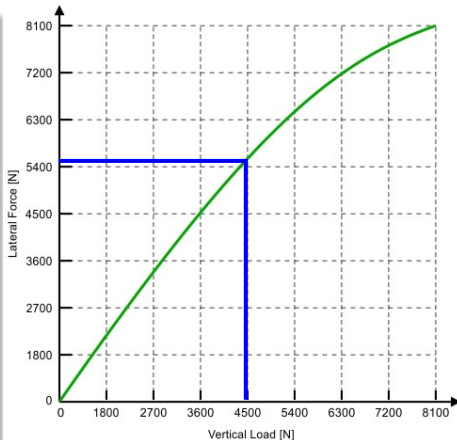


Load Transfer Example

No load transfer vs 50% load transfer

Assume 4.5kN of static vertical load on each tire.
Static traction:

$$F(4.5\text{kN}) = 5.55\text{kN} \Rightarrow F_{\text{tot}}^{\text{static}} = 5.55 \cdot 4 = 22.2\text{kN}$$



Load Transfer Example

No load transfer vs 50% load transfer

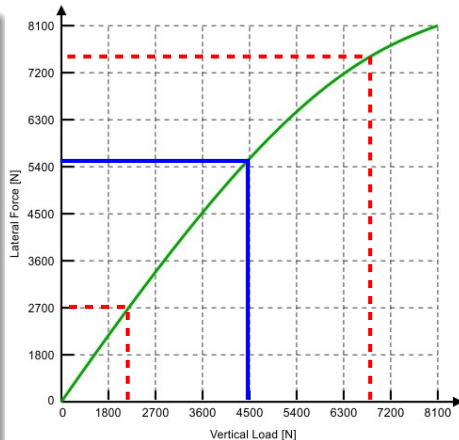
Assume 4.5kN of static vertical load on each tire.
Static traction:

$$F(4.5\text{kN}) = 5.55\text{kN} \Rightarrow F_{\text{tot}}^{\text{static}} = 5.55 \cdot 4 = 22.2\text{kN}$$

With load transfer:

$$F(0.5 \cdot 4.5\text{kN} = 2.25\text{kN}) = 2.7\text{kN}$$

$$F(1.5 \cdot 4.5\text{kN} = 6.75\text{kN}) = 7.5\text{kN}$$



Load Transfer Example

No load transfer vs 50% load transfer

Assume 4.5kN of static vertical load on each tire.
Static traction:

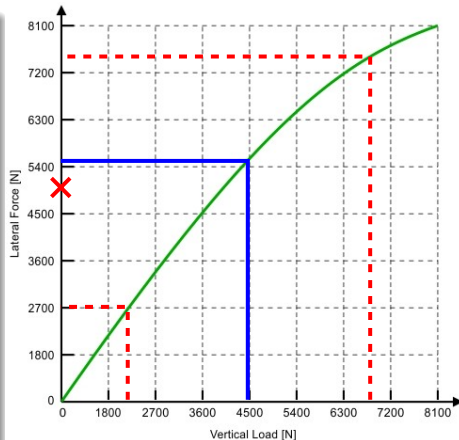
$$F(4.5\text{kN}) = 5.55\text{kN} \Rightarrow F_{\text{tot}}^{\text{static}} = 5.55 \cdot 4 = 22.2\text{kN}$$

With load transfer:

$$F(0.5 \cdot 4.5\text{kN} = 2.25\text{kN}) = 2.7\text{kN}$$

$$F(1.5 \cdot 4.5\text{kN} = 6.75\text{kN}) = 7.5\text{kN}$$

$$\therefore F_{\text{tot}}^{\text{transfer}} = 2(2.7\text{kN} + 7.5\text{kN}) = 20.4\text{kN}$$



Load Transfer Example

No load transfer vs 50% load transfer

Assume 4.5kN of static vertical load on each tire.
Static traction:

$$F(4.5\text{kN}) = 5.55\text{kN} \Rightarrow F_{\text{tot}}^{\text{static}} = 5.55 \cdot 4 = 22.2\text{kN}$$

With load transfer:

$$F(0.5 \cdot 4.5\text{kN} = 2.25\text{kN}) = 2.7\text{kN}$$

$$F(1.5 \cdot 4.5\text{kN} = 6.75\text{kN}) = 7.5\text{kN}$$

$$\therefore F_{\text{tot}}^{\text{transfer}} = 2(2.7\text{kN} + 7.5\text{kN}) = 20.4\text{kN}$$

8% Drop in total traction!

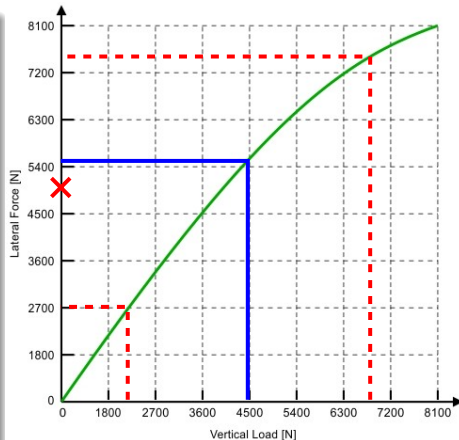


Table of Contents

- 1 What makes a car fast?
- 2 Vehicle Basics
- 3 Vehicle Balance and Control**
- 4 Three Tenants of Racecar Design

How does a car turn?

How does a car turn?

The car uses the tires to generate a **lateral force to redirect the car** and a **torque to rotate the car**

How does a car turn?

The car uses the tires to generate a **lateral force to redirect the car** and a **torque to rotate the car**

Corners represent a change in two different things:

How does a car turn?

The car uses the tires to generate a **lateral force to redirect the car** and a **torque to rotate the car**

Corners represent a change in two different things:

① Change in **position**

- The path the car takes on track
- Governed by Conservation of (linear) Momentum ($F = ma$)

How does a car turn?

The car uses the tires to generate a **lateral force to redirect the car** and a **torque to rotate the car**

Corners represent a change in two different things:

① Change in **position**

- The path the car takes on track
- Governed by Conservation of (linear) Momentum ($F = ma$)

② Change in **orientation**

- The direction of the car along the taken path
- Governed by Conservation of Angular Momentum ($M = I\alpha$)

How does a car turn?

The car uses the tires to generate a **lateral force to redirect the car** and a **torque to rotate the car**

Corners represent a change in two different things:

① Change in **position**

- The path the car takes on track
- Governed by Conservation of (linear) Momentum ($F = ma$)

② Change in **orientation**

- The direction of the car along the taken path
- Governed by Conservation of Angular Momentum ($M = I\alpha$)
- Previous topics primarily cover vehicle dynamics for translation

How does a car turn?

The car uses the tires to generate a **lateral force to redirect the car** and a **torque to rotate the car**

Corners represent a change in two different things:

① Change in **position**

- The path the car takes on track
- Governed by Conservation of (linear) Momentum ($F = ma$)

② Change in **orientation**

- The direction of the car along the taken path
- Governed by Conservation of *Angular* Momentum ($M = I\alpha$)
- Previous topics primarily cover vehicle dynamics for translation
- Now we'll cover orientation/rotation

Angular Momentum

Conservation of Angular Momentum

$$M = I\alpha$$

where M is the moments (torque) acted on the car, I is the moment of inertia, and α is the angular acceleration

Angular Momentum

Conservation of Angular Momentum

$$M = I\alpha$$

where M is the moments (torque) acted on the car, I is the moment of inertia, and α is the angular acceleration

- Analogous to conservation of linear momentum:

	Linear	Angular
External Action	F	M
Object's resistance to change	m	I
Rate of Change	a	α
State Variable	V	ω

Angular Momentum

Conservation of Angular Momentum

$$M = I\alpha$$

where M is the moments (torque) acted on the car, I is the moment of inertia, and α is the angular acceleration

- Analogous to conservation of linear momentum:

	Linear	Angular
External Action	F	M
Object's resistance to change	m	I
Rate of Change	a	α
State Variable	V	ω

- Moments can be calculated from a force F and distance r via $M = F \times r$

Angular Acceleration for Racecars

- Reminder: Angular momentum governs **car orientation**

Angular Acceleration for Racecars

- Reminder: Angular momentum governs **car orientation**
- Angular velocity ω has no direct impact on lap time

Angular Acceleration for Racecars

- Reminder: Angular momentum governs **car orientation**
- Angular velocity ω has no direct impact on lap time
- Therefore, we *do not* want to maximize angular acceleration.

Angular Acceleration for Racecars

- Reminder: Angular momentum governs **car orientation**
- Angular velocity ω has no direct impact on lap time
- Therefore, we *do not* want to maximize angular acceleration.
- We only want to **control it such that we can maximize linear acceleration.**

Angular Acceleration for Racecars

- Reminder: Angular momentum governs **car orientation**
- Angular velocity ω has no direct impact on lap time
- Therefore, we *do not* want to maximize angular acceleration.
- We only want to **control it such that we can maximize linear acceleration**.

This is where balance and control comes into play

Ensure that the car is oriented such that we can achieve maximum linear acceleration

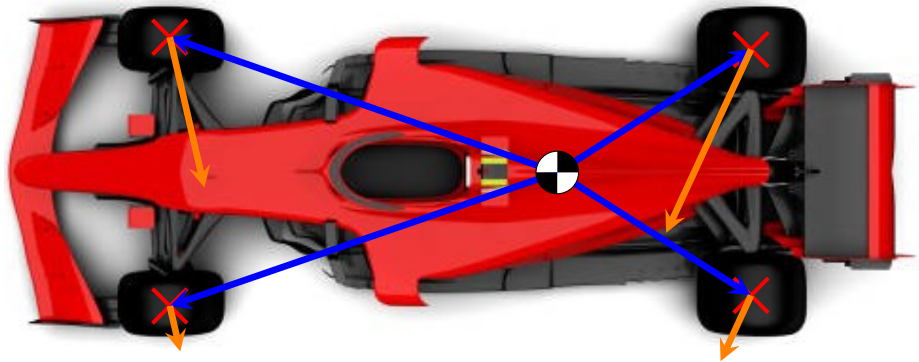
Vehicle Balance

Why do Formula 1 and Indy cars have larger tires at the rear than the front?

Vehicle Balance - Formula 1 Car

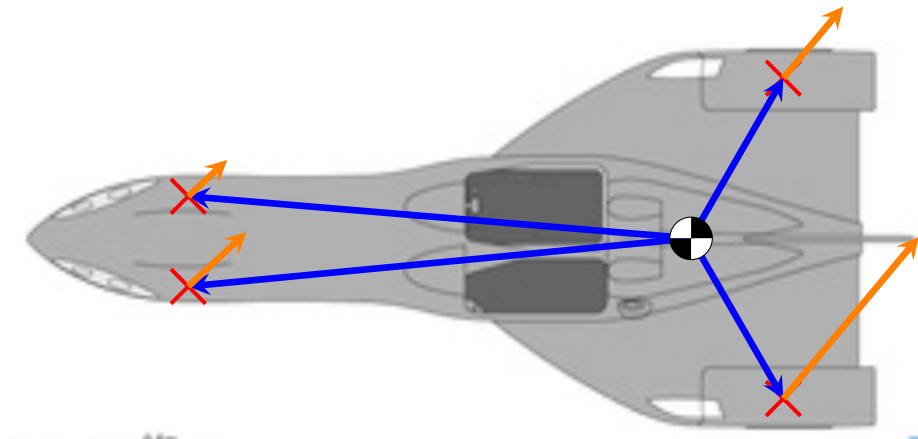
Balance the moments of the car

$$M = F \times r$$



Vehicle Balance - Delta Wing

Balance the moments of the car $M = F \times r$



Oversteer vs Understeer

Neutral Steer

Moments in perfect *imbalance*

Oversteer vs Understeer

Neutral Steer

Moments in perfect *imbalance*

Under Steer

Unbalanced moments cause under-rotation

Oversteer vs Understeer

Neutral Steer

Moments in perfect *imbalance*

Under Steer

Unbalanced moments cause under-rotation

Over Steer

Unbalanced moments cause over-rotation

Oversteer vs Understeer

Neutral Steer

Moments in perfect *imbalance*

Under Steer

Unbalanced moments cause under-rotation

Over Steer

Unbalanced moments cause over-rotation

- The latter two prevent achieving maximum linear acceleration

Oversteer vs Understeer

Neutral Steer

Moments in perfect *imbalance*

Under Steer

Unbalanced moments cause under-rotation

Over Steer

Unbalanced moments cause over-rotation

- The latter two prevent achieving maximum linear acceleration
- A car can dynamically change between all three states

Oversteer vs Understeer

Neutral Steer

Moments in perfect *imbalance*

Under Steer

Unbalanced moments cause under-rotation

Over Steer

Unbalanced moments cause over-rotation

- The latter two prevent achieving maximum linear acceleration
- A car can dynamically change between all three states
- Changes occur due to differences in load transfer, suspension magic, and through dynamic movement

Table of Contents

- 1 What makes a car fast?
- 2 Vehicle Basics
- 3 Vehicle Balance and Control
- 4 Three Tenants of Racecar Design

Three Tenants of Racecar Design

In order of importance:

- 1 Make it Lighter
 - Improves acceleration, load transfer, responsiveness, etc.

Three Tenants of Racecar Design

In order of importance:

- ① Make it Lighter
 - Improves acceleration, load transfer, responsiveness, etc.
- ② Make it Lower
 - Lowering a component lowers CG \Rightarrow reduces load transfer

Three Tenants of Racecar Design

In order of importance:

- ① Make it Lighter
 - Improves acceleration, load transfer, responsiveness, etc.
- ② Make it Lower
 - Lowering a component lowers CG \Rightarrow reduces load transfer
- ③ Make it more Central
 - Reduces $I \Rightarrow$ makes the car more responsive

Three Tenants of Racecar Design

In order of importance:

- ① Make it Lighter
 - Improves acceleration, load transfer, responsiveness, etc.
- ② Make it Lower
 - Lowering a component lowers CG \Rightarrow reduces load transfer
- ③ Make it more Central
 - Reduces $I \Rightarrow$ makes the car more responsive

The car that is lighter, has a lower CG, or has a lower inertia will be faster

Recommended Resources

- *Tune to Win* by Carroll Smith
 - Vehicle dynamics for normal people
 - Covers the gamut of racecar design topics (aero, cooling, VD, powertrain, etc.)
- *Racecar Vehicle Dynamics* by Milliken & Milliken
 - "The Bible"
 - It's a textbook, but incredibly useful
 - More specialized to vehicle dynamics (shocking given the name)

Questions