## ELEC2202 2013/14

# **D1 Design Completion Form**

Name:	Yubo Zhi	
Username: _	y239g13	 · · · · · · · · · · · · · · · · · · ·

Sequencer simulation shows correct functionality	R.H
Whole system simulation shows correct functionality	B. H
Sequencer for 4-bit multiplication implemented on MachXO2, goes through sequence of states, stops and displays READY	145
4-bit adder implemented and shows correct functionality	ng
C,A,Q registers for 4-bit operation implemented and show correct functionality	TCIE
Whole 4-bit system implemented and shows correct functionality	12/5
ADD and SHIFT combined in a single state	18
Extension to 8 bits implemented and shows correct functionality	The

	1//		
Supervisor's signature	4		
71/11/11			
Date 21/11/19			
, ,			

Formal report to be submitted through C-Bass/ECS front desk, by 16:00, one calendar week after the scheduled laboratory session.

Include a copy of this completion form with your formal report.

## ELEC2221 D1 – Design and test of a sequential multiplier

Yubo Zhi yz39g13 BEng Electronic Engineering Professor Alun S Vaughan Group 29 November 21st 2014

**ABSTRACT:** Design an n-bit unsigned multiplier, where  $n \ge 4$ , by using SHIFT-ADD sequential algorithm with SystemVerilog, then implement on MachXO2 Pico Kit. Majority of coding and simulations are done before the lab, then finish the encapsulation modules and implement each part of the design on the CPLD during the lab. Extensions achieved are combined SHIFT and ADD states for faster operation, bi-directional shared data port for multiplier input and output, push button signal debouncing and combinational multiplier.

## 1. Adder design, simulation and synthesis

The provided adder code [1] works well for any bit, by specify the parameter n, so it is not changed.

#### 1.1 Adder simulation

endmodule

#### Adder testbench: module adder test; parameter n = 4;logic [n - 1:0] A, M, Sum; adder #(.n(n)) a0 (.\*); /a0/A initial /a0/M begin /a0/C A = b0;(0 )(1 )(2 )(3 )(4 )(5 )(6 )(7 )(8 )(9 )(a )(b )(c )(d )(e )(f )(0 )(1 )(2 )(3 )(4 )(5 )(6 )(7 )(8 )(9 )(a )(b )(c )(d )(e M = 'b0:50 ns 170 ns do 100 ns Figure 1 Modelsim 4-bit adder #5ns A++; #5ns M = A;simulation, shows all possible outputs end while (A != 'b0); end

## 2. Register design, simulation and synthesis

The code for register is modified. The signal add is changed to add\_shift, which modified to do both add and shift operations in 1 clock cycle, thus Creg register becomes unnecessary, so removed. Register modified code:

```
end else if (add_shift) // add, then shift AQ <= \{C, Sum, AQ[n-1:1]\}; else if (shift) // shift AQ AQ <= \{1'b0, AQ[n * 2 - 1:1]\}; endmodule
```

#### 2.1 Simulation of registers

#### Register testbench:

```
module register test;
parameter n = 4;
logic clock, reset, add_shift, shift, C;
logic[n - 1:0] Qin, Sum;
logic[n * 2 - 1:0] AQ;
register #(.n(n)) r0 (.*);
// Clock
initial
begin
        clock = 1'b0;
        forever #5ns clock = ~clock;
end
                              /r0/dock St0
                              /r0/re... St0
// Test sequence
                              /r0/ad... St0
initial
                              /r0/shift St0
begin
                              /r0/C
                                     St1
        reset = 'b0;
        add shift = 'b0;
                              /r0/Qin
                                     0101
                                                    0101
        shi\overline{f}t = 'b0;
                              /r0/Sum
                                     0111
                                                   0111
        C = 'b1:
                              /r0/AQ
                                     00000101
                                                           00000101
                                                                               10111001
        Oin = 'hE5;
        Sum = 'h47;
                                Now
                                                                           50 ns
        #10ns reset = 'b1;
        #10ns reset = 'b0;
                                             Figure 2 Modelsim 4-bit register simulation.
        #10ns shift = 'b1;
                                             Qin loaded at 15ns by reset signal, AQ shifted
        #10ns shift = 'b0;
        #10ns add shift = 'b1;
                                             to right 1 bit at 25ns by shift signal, C and Sum
        #10ns add shift = 'b0;
                                             loaded to highest 4 bits of AQ then shifted to right
        #10ns reset = 'b1;
        #10ns reset = 'b0;
                                             1 bit at 55ns by add shift signal.
end
endmodule
```

## 3. Sequencer design, simulation and synthesis

Instead of separate add and shift states, these two steps are combined into one shifting state, and add signal is changed to add\_shift, implemented in register. Therefore in shifting state, the sequencer check if Q0 is 1 than assert add\_shift signal, otherwise assert shift signal.

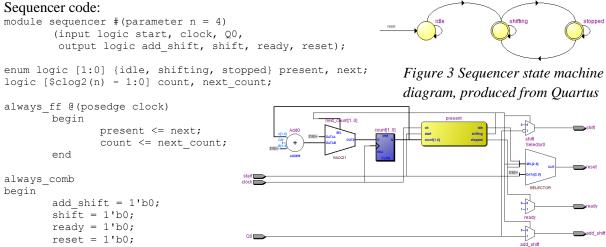


Figure 4 Sequencer RTL diagram, produced from Quartus

```
next = present;
        next_count = count;
        case (present)
                        // State after reset
        begin
                reset = 1'b1;
                next_count = n - 1;
                if (start)
                       next = shifting;
        end
        shifting:
                       // Shifting, n cycle
        begin
                next count = count - 1;
                if (\overline{Q}0)
                        add_shift = 1'b1;
                else
                        shift = 1'b1;
                if (count == 0)
                       next = stopped;
        end
        stopped:
                        // Finished
        begin
                ready = 1'b1;
                next count = n - 1;
                if (start)
                begin
                        reset = 1'b1;
                        next = shifting;
                end
        end
        default:
                next = idle;
        endcase
end
endmodule
```

#### 3.1 Simulation of sequencer

## Sequencer testbench:

#10ns start = 'b0;

end

endmodule

```
module sequencer_test;
parameter n = 4;
logic start, clock, Q0;
logic add shift, shift, ready, reset;
sequencer \#(.n(n)) s0 (.*);
// Clock
initial
begin
clock = 1'b0;
forever #5ns clock = ~clock;
                          /s0/start
                                  StO
                          /s0/Q0
                                   StO
// Test sequence
                          /s0/add_shift
initial
                          /s0/shift
begin
                          /s0/ready
start = 'b0;
                          /s0/reset
                          /s0/presen
                                   shifting
Q0 = 'b0;
                                   shifting (idle
                          /s0/next
#10ns start = 'b1;
#10ns start = 'b0;
                          /s0/next_count
#10ns Q0 = 'b0;
#20ns Q0 = 'b1;
#20ns start = 'b1;
#40ns Q0 = 'b1;
#20ns Q0 = 'b0;
```

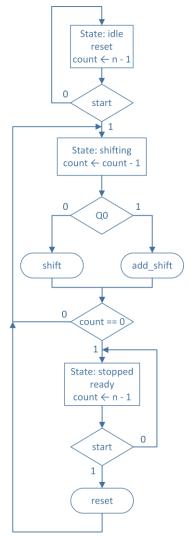


Figure 5 Sequencer ASM chart

reset signal asserted after start signal to load data in register. Then in shifting state, add\_shift signal asserted if Q0=1, otherwise shift signal asserted. After 4 shifting state, operation finished, enter stopped state, ready signal asserted.

## 4. Multiplier design, simulation and synthesis

For be able to input and output n-bit data, I designed a bi-directional data port, with 2-bit port function selection, and two n-bit register for store M and Qin. Therefore, multiplicand M will be loaded from data port at function '00', multiplier Qin will be loaded from data port at function '01', lower n-bit from result AQ will output at '10', higher n-bit from result AQ will output at '11'. For avoid bus contention, an output enable signal OE is also added.

There is a debounce module for debounce start signal, if it is signalled by a push button. Some compiler directives added to select from combinational multiplier or sequencer multiplier. Multiplier code:

```
module multiplier #(parameter n = 4, freq = 3330000)
        (input logic startPB, input logic [1:0] func,
         input logic oe, output logic ready, inout [n - 1:0] data);
//// Internal Oscillator 3.33MHz
        logic clock;
        defparam OSCH_inst.NOM_FREQ = "3.33";
        OSCH OSCH inst (
                .STDBY(1'b0),
                                        // 0=Enabled, 1=Disabled also Disabled with Bandgap=OFF
                .OSC(osc clk),
                                        \ensuremath{//} this signal is not required if not using SED
                .SEDSTDBY()
        //counter #(.n(24)) c(.*);
                                        // produces slow clock
        assign clock = osc clk;
//// Debounce
        logic start;
        debounce #(.n(freq / 1000)) d0(.clk(osc clk), .in(~startPB), .out(start));
//// Blocks
        logic C, reset, shift, add_shift;
logic [n - 1:0] Sum, M, Qin;
        logic [n * 2 - 1:0] AQ;
//`define combinational
`ifndef combinational
        adder \#(.n(n)) A(.A(AQ[n * 2 - 1:n]), .*);
        register \#(.n(n)) R(.*);
        sequencer \#(.n(n)) S(.Q0(AQ[0]), .*);
`else
        combmultiplier \#(.n(n)) c0 (.A(M), .B(Qin), .Q(AQ));
        assign ready = 'b1;
`endif
//// Port
        assign data = oe ? (func == 2'b10 ? AQ[n - 1:0] : (func == 2'b11 ? AQ[n * 2 - 1:n] :
'bz)) : 'bz;
        always ff @(posedge osc clk)
                case (func)
                2'b00:
                       M <= data;
                2'b01:
                       Qin <= data;
                endcase
endmodule
```

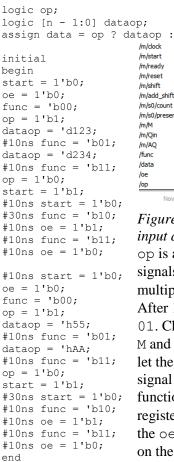
### 4.1 Simulation of multiplier

Figure 7 4-bit multiplier RTL diagram, produced from Quartus

#### Sequencer testbench:

```
module test;
parameter n = 4;

logic start;
logic [1:0] func;
logic oe, ready;
wire [n - 1:0] data;
multiplier #(.n(n)) m(.*);
```



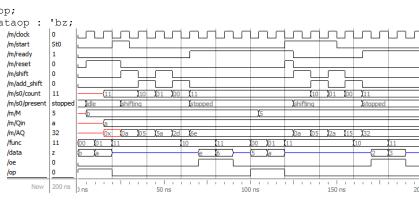


Figure 8 4-bit multiplier Modelsim simulation, bi-directional data input and output.

op is a signal in testbench to control data output from dataop setting signals to data bus, for input M and Qin. First, M loaded into the multiplier through the data bus, by selecting func at function 00. After 1 clock cycle, Qin loaded into the multiplier by using function 01. Change func to function 11, without assert oe signal to prevent M and Qin change during computation. Then assert the start signal, let the multiplier start computation. 8 clock cycles later, ready signal been asserted, means computation finished. Then, by selecting function 10 and assert the oe signal, the lower 8-bit from the AQ result register will appear on the data bus. Selecting function 11 and assert the oe signal will let the higher 8-bit from the AQ result register appear on the data bus. There is another computation cycle in the simulation.

#### 5. Extensions

endmodule

#### 5.1 Combine add and shift state

Add and shift state combination already done by modifying the register code and combine the two states into a single shifting state in the state machine.

#### 5.2 8-bit multiplier

Building an 8-bit multiplier is easy, as the parameter n to set the bit length is used in every module, so change the parameter n in the encapsulation multiplier module to 8 is the only

```
thing needed to build an 8-bit multiplier.
e.g. the first line of multiplier module defination:
```

```
module multiplier \# (parameter n = 8, freq = 3330000)
```

For simulation, change the paramter line (line 2) in testbench:

```
parameter n = 8;
```

Change following lines in testbench for 4 more computation clock cycles:

Line 27:

```
#70ns func = 'b10;
Line 43:
#50ns func = 'b10;
```

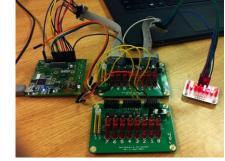


Figure 9 8-bit multiplier implemented on MachXO2 CPLD. Data bus shared for data inputs and outputs. Top switch board with high-z mode for data input, bottom switch board for control signals, LED board for data output.



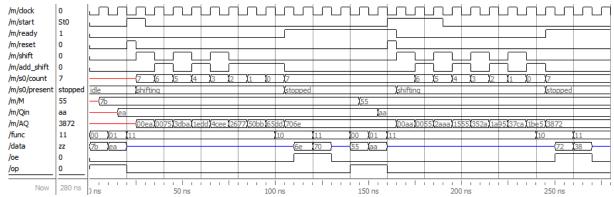


Figure 10 8-bit multiplier Modelsim simulation, bi-directional data input and output. Operations are the same as described previously in section 4.1, Figure 8.

#### 5.3 Button debouncing

Button debouncing for start signal might be needed, if the start signal is controlled by a push button. Debouncing is done by make sure the signal from push button doesn't change during a specific amount of time, basically a counter.

#### Code for debouncing a push button:

The push button featured by the MachXO2 Pico is active low, so it need to be inverted first.

Relative code in multiplier encapsulation module:

```
//// Debounce
    logic start;
    debounce #(.n(freq / 1000)) d0(.clk(osc clk), .in(~startPB), .out(start));
```

The code has been tested on the MachXO2 CPLD by change the debouncing time to a big amount, then the start button need to be push for a longer time to activate the computation.

## 5.4 Combinational multiplier

For a variable n-bit combinational multiplier, the 'generate' block will be quite useful for generate hardware using for loops.

## Combinational multiplier code:

```
module combmultiplier #(parameter n = 4)
(input logic [n - 1:0] A, B, output logic [n * 2 - 1:0] Q);
logic a[n][n];
logic c[n][n];
// Generate full adder matrix
genvar x, y;
generate
```

```
for (y = 0; y < n; y++)
                       for (x = 0; x < n; x++)
                                fulladder a0 (.A(a[y][x]), .B(A[x] & B[y]), .Cin(x == 0 ? '0 :
c[y][x - 1]), .S(s[y][x]), .Cout(c[y][x]));
       endgenerate
       // Connections
       generate
                for (x = 0; x < n; x++)
                                                                                    FΑ
                                                                                         FΑ
                                                                                              FΑ
                       assign a[0][x] = 'b0;
                for (y = 1; y < n; y++)
                       assign a[y][n-1] = c[y-1][n-1];
                for (y = 1; y < n; y++)
                                                                                    FΑ
                       for (x = 0; x < n - 1; x++)
                               assign a[y][x] = s[y - 1][x + 1];
                assign Q[n * 2 - 1] = c[n - 1][n - 1];
                for (y = 0; y < n; y++)
               assign Q[y] = s[y][0];
for (x = 0; x < n - 1; x++)
                       assign Q[n + x] = s[n - 1][x + 1];
       endgenerate
```

Figure 11 Graphical representation of unsigned combinational multiplier.

#### The full adder module used in the combinational multiplier:

```
module fulladder (input logic A, B, Cin, output logic S, Cout);
assign \{Cout,S\} = A + B + Cin;
endmodule
```

#### Relative code in multiplier encapsulation module:

```
`define combinational
`ifndef combinational
       adder \#(.n(n)) A(.A(AQ[n * 2 - 1:n]), .*);
       register \#(.n(n)) R(.*);
       sequencer \#(.n(n)) S(.Q0(AQ[0]), .*);
`else
       combmultiplier \#(.n(n)) c0 (.A(M), .B(Qin), .Q(AQ));
       assign ready = 'b1;
`endif
```

#### Modelsim testbench:

dataop = 'h55;

#10ns func = 'b01;

endmodule

```
module comb test;
parameter n = 8;
logic start, oe, ready;
logic [1:0] func;
wire [n - 1:0] data;
multiplier \#(.n(n)) m(.*);
logic [n - 1:0] dataop;
assign data = op ? dataop : 'bz;
initial
                               /m/dock
                                      0
begin
                               /m/M
                                      55
        start = 1'b1;
                               /m/Qin
                               /m/AQ
                                      3872
       oe = 1'b0;
        func = 'b00;
                               /func
                                      11
        op = 1'b1;
                               Figure 12 8-bit combinational multiplier Modelsim
        dataop = 'd123;
        #10ns func = 'b01;
                               simulation, bi-directional data input and output.
        dataop = 'd234;
                               clock is used by input data storage register M and Qin.
        #10ns func = 'b10;
                               start and ready signals are unnecessary for combinational
        op = 1'b0;
        #10ns oe = 1'b1;
                               multiplier, and they were set to always 1, so omitted from
        #10ns func = 'b11;
        #10ns oe = 1'b0;
                               simulation diagram.
                               Operations for data input and output are the same as described
        #10ns func = 'b00;
                               previously in section 4.1, Figure 8, the difference is
       op = 1'b1;
```

before getting the results.

combinational multiplier doesn't need to wait for ready signal

```
dataop = 'hAA;
#10ns func = 'b10;
op = 1'b0;
#10ns oe = 1'b1;
#10ns func = 'b11;
#10ns oe = 1'b0;
end
endmodule
```

#### 6. Conclusion

In this project, a sequential unsigned n-bit multiplier was implemented on MachXO2 Pico Dev Kit. The multiplier uses SHIFT-ADD algorithm, with the SHIFT and ADD states combined for faster operation. A debouncing module is developed for debounce the on-board push button used for signalling the start signal. For be able to input to and output from the multiplier within limited IO ports, a bi-directional data port has also been developed. Furthermore, an n-bit combinational multiplier is also developed, which is very fast compare to sequential multiplier, but will require a large amount of logic for larger n.

By finishing this project, I've learnt using SystemVerilog to design finite state machine, digital hardware design, generate block [2] for generate hardware by for loops, Synthesis and program a MachXO2 device using Lattice Diamond.

To extend it further, a signed multiplier may be a reasonable choice. There are some other combinational multiplier design available as well [3].

#### 7. References

- [1] Tom J Kazmierski (17, Oct. 13). *Suggested SystemVerilog source files* [Online]. Available: https://secure.ecs.soton.ac.uk/notes/elec2221/tjk2014/D1
- [2] Jeff Johnson (Jul 18, 2011). *Code templates: Generate for loop* [Online]. Available: http://www.fpgadeveloper.com/2011/07/code-templates-generate-for-loop.html
- [3] *Multipliers & Pipelining* [Online]. Available: http://web.mit.edu/6.111/www/f2011/handouts/L09.pdf