

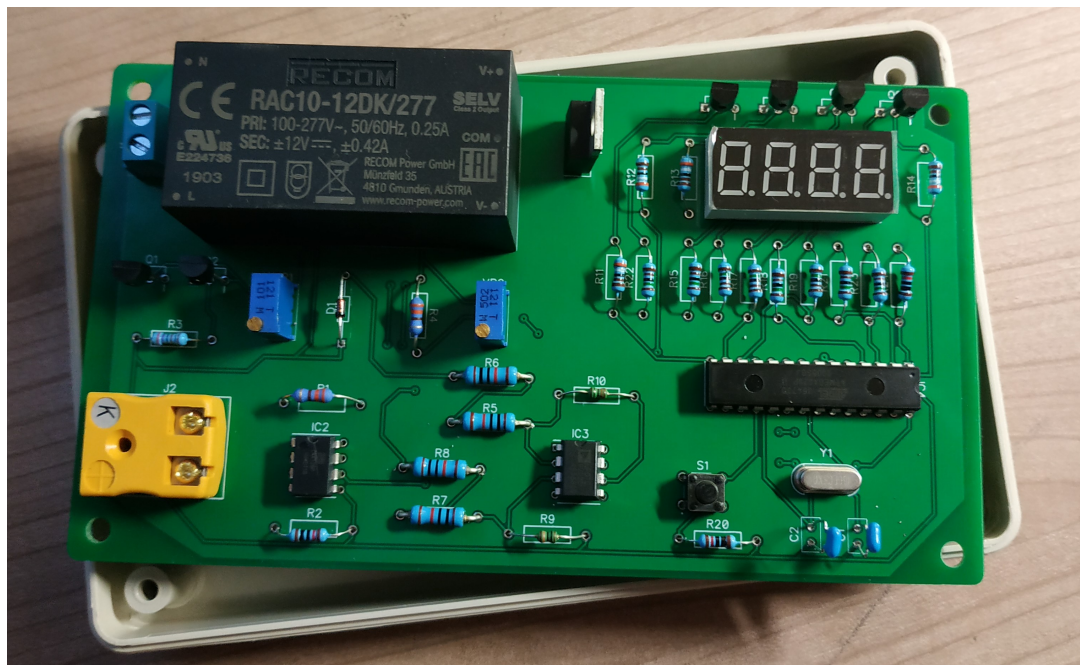
## Digital Multi-Functional Thermometer

This thermometer provides instant digital readout of the temperature sensed by a K type thermocouple. It can measure temperatures precisely between 20 and 250 °C (68 °F and 482 °F). This appliance is useful for both beginners and professional cooks to monitor the internal temperature of foods like steaks, chicken, fish and liquids like water or cooking oil.

It can also measure the ambience temperature through a diode, which is also used to make a temperature compensation in the thermocouple.

Specifications:

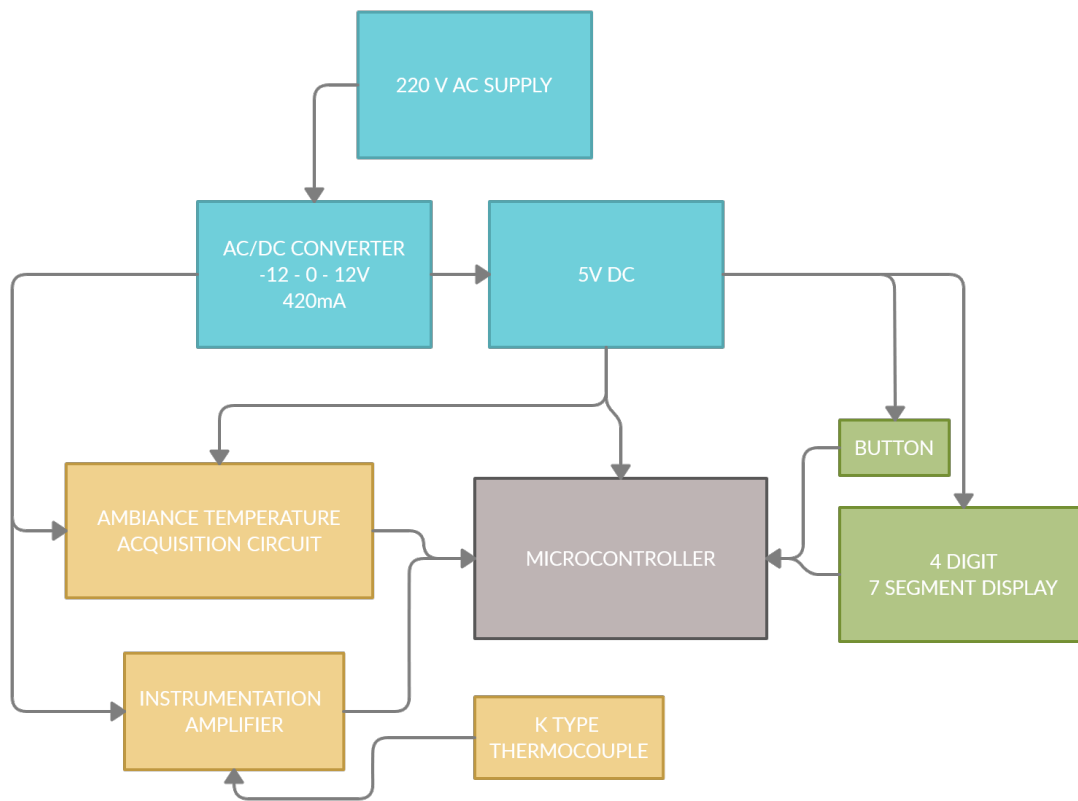
- Power supply: 220V AC
- Temperature display units: °C
- Resolution: 0.5 °C
- Temperature range: 0°C ~ 250°C
- Temperature accuracy:  $\pm 2$  °C



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System block diagram:



The voltage that provides the k thermocouple is amplified with a gain of 243 to provide a signal of 10mv per degree to an adc channel in the microcontroller.

The ambience temperature it's acquired with an 1N4148 diode and his temperature dependency, which is about -2mV/°C the circuit uses an op-amp in differential mode to amplify this signal with a gain of five and then is send to an adc channel in the microcontroller.

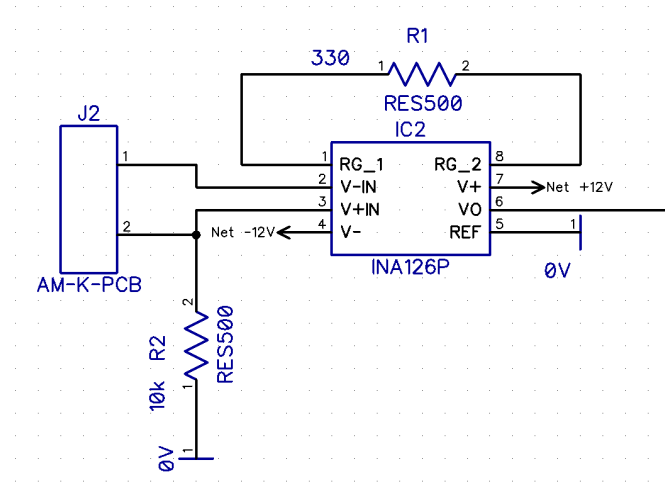
The four-digit seven segment display utilises a circuit to multiplex the displays, 12 digital pins of the microcontroller are used.

The voltage comes from and ac to dc converter which provides 12, -12 and 0 volts along with an LM7805 which provides 5 volts.

The microcontroller is an Atmega328P with an arduino IDE.

## Selection of components.

### Thermocouple.



The type k thermocouple provides a linear seebeck coefficient in the range between our range of application (0 – 250°C) of about 41  $\mu\text{V}/^\circ\text{C}$ , therefore.

$$V_{in} = 41 \cdot 10^{-6}(T - T_{amb})$$

Our microcontroller has a resolution of 4.9 mV, so we need to amplify our signal to about 10mV/°C

$$V_{out} = 10 \cdot 10^{-3}(T - T_{amb})$$

To do that an ina126p instrumentation amplifier is used, it has low quiescent current, low offset voltage, low offset drift, low noise which is ideal for the application.

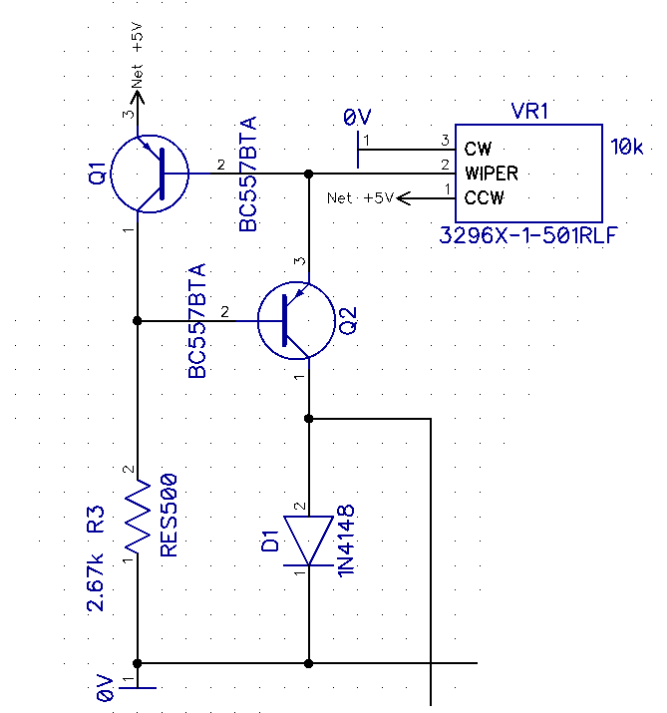
$$G = \frac{10^{-3}}{41 \cdot 10^{-6}} = 243$$

With the gain equation of the ina126p:

$$G = 5 + \frac{80K}{R_g} \rightarrow R_g = R1 = \frac{80k}{G - 5} = 330\Omega$$

**R2 = 10K** -> To provide a path for the input bias current of both inputs.

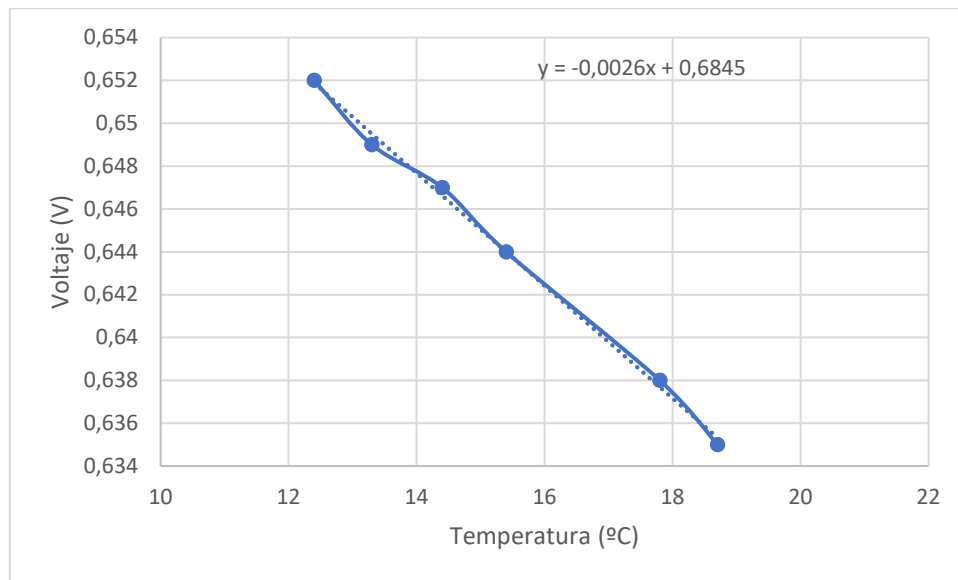
Temperature acquisition circuit.



First, we provide a constant current thru the diode to delete this dependency and obtain the following output. (For the tested diode)

$$V_{out} = 0.6849 - 0.0026 \cdot T$$

Which was obtained with a linear trendline.



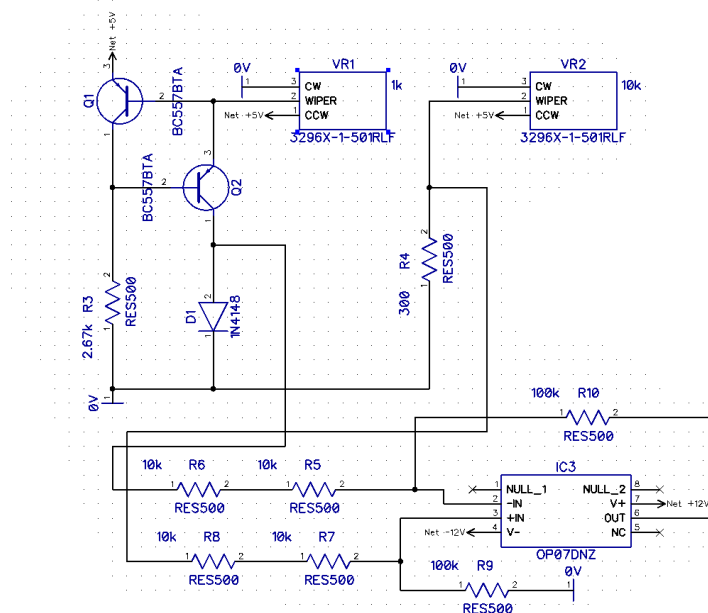
$$I_{e,q2} = 2mA \rightarrow R2 = VR1 = \frac{V_{be,q1}}{I_{e,q2}} \cong 350\Omega \rightarrow \text{VR1 potentiometer of } 1K$$

$$R3 = \frac{V_{cc} - V_{be,q1} - V_{be,q2}}{I_{e,q1}} \rightarrow R3 \text{ min} = 1800\Omega, R3 \text{ max} = 1950\Omega$$

**R3 = 2.67KΩ** to provide enough current to saturate transistors.

## Temperature amplification circuit

A differential operational circuit will be used in this part, first to get rid of the 0.6849 V constant voltage of the diode and then amplify the temperature dependant voltage to get a 10 mV per degree signal.



First with VR2 and R4 we obtain 0.6849V, if we choose  $R4 = 330 \Omega$

$$V_{pot} = V_{in} \cdot \frac{330}{330 + Pot} \rightarrow Pot = \frac{330 \cdot V_{in}}{V_{pot}} - 330 = 2079 \Omega$$

A 10K potentiometer is used for VR2

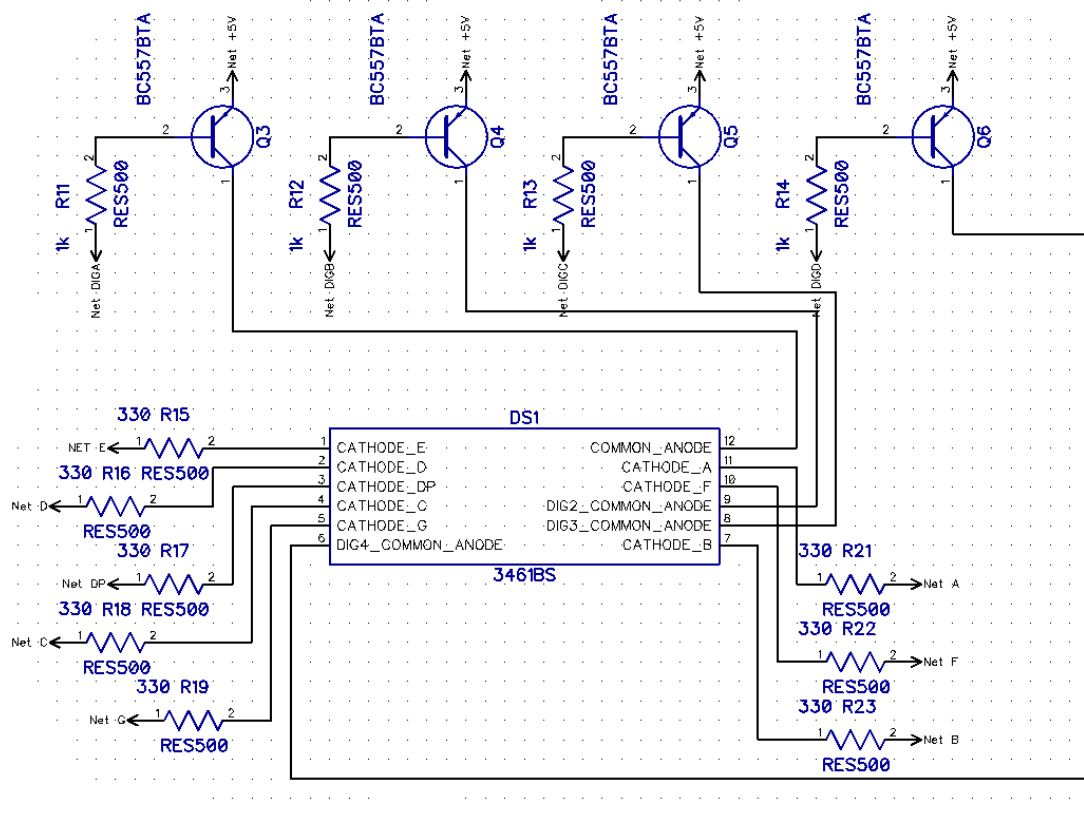
Then an OP07 is used in differential mode to obtain the output signal dependant with the temperature.

$$V_{temp} = \frac{R10}{(R6 + R5)} \cdot (V_{pot} - V_{diode}) = 5 \cdot (0.6849 - 0.6849 + 0.0023 \cdot T) = 0.0115 \cdot T$$

**$R10 = 100k$  (<5 Tolerance);  $R5=R6=R8=R7 = 10K$**

#### 4 Digit 7 segment display driver.

To control which segment will be in it's on state and to supply the same current to each segment (diode) and to reduce the current sink of the microcontroller four transistor's working as switches will be used.



6.5 mA will be enough to light each diode, therefore **R15 to R19 and R21 to R23 = 330  $\Omega$**  ( $V_r = V_{cc} - V_{ce|sat} - V_{diode}$ ), now we need to provide the enough current to the base to saturate the transistors in the worst condition. (All leds on)

$$I_{c, \max} = 6.5 \cdot 8 = 52 \text{ mA}$$

$$I_b > \frac{I_c}{\beta} > 0.52 \text{ mA}$$

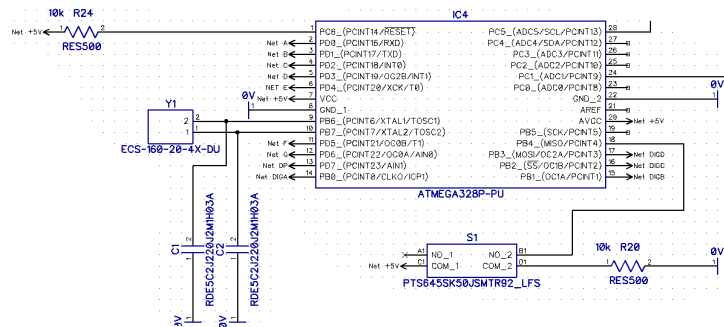
$$R_b > \frac{V_{uc} - (V_{cc} - V_{be|sat})}{I_b} > 576 \Omega$$

**R11 = R12 = R13 = R14 = 1K $\Omega$** , to ensure saturation.

When the digital pin out its zero then the transistor is in cut off,  $I_c = 0$

## Microcontroller

The microcontroller is an Atmega328P, the operating voltage is 5V. To work with the Arduino IDE a 16Mhz crystal is needed along with two 22pF ceramic capacitors, also a 10K resistor is used to bypass the reset pin.



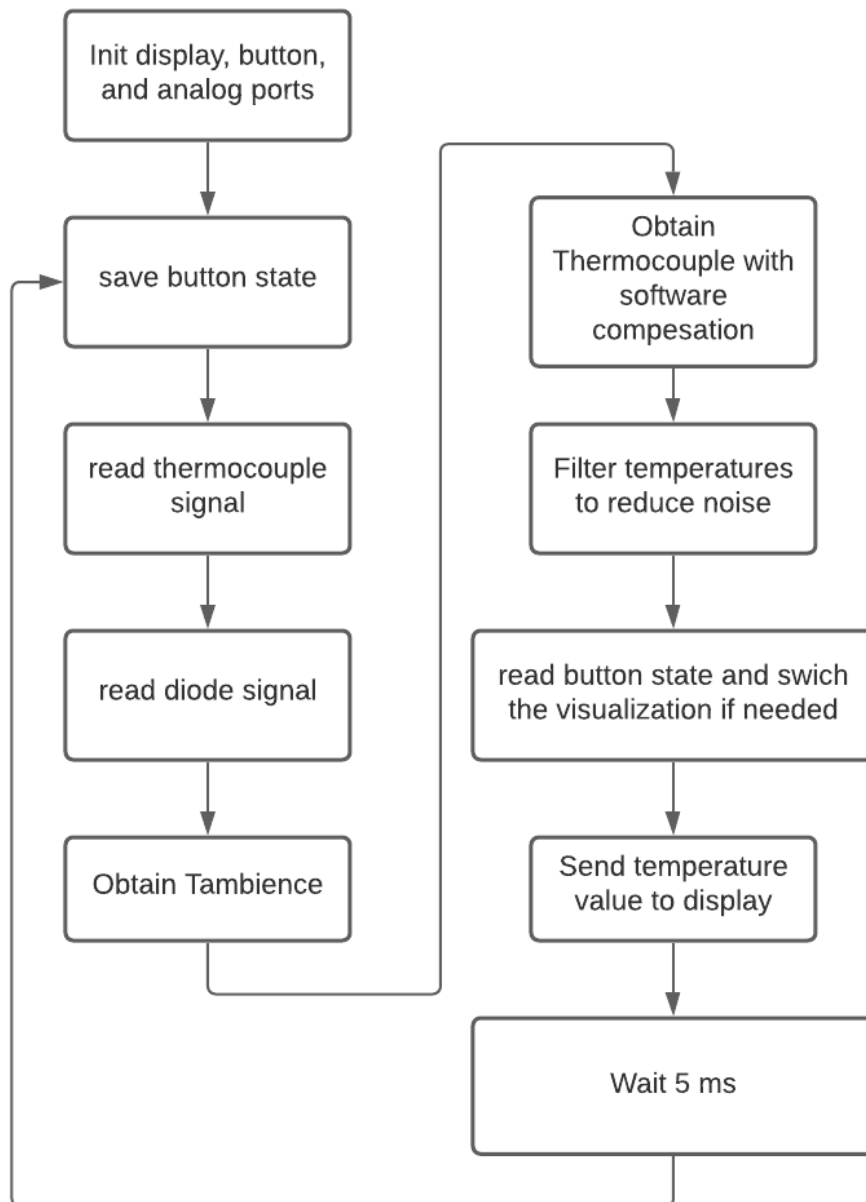
A button (S1) is added so the user can change between the thermocouple temperature and the ambience temperature.



## Software

In this section the code is presented. It contains the display driver, the function to obtain both temperatures (thermocouple, and diode) from the A/D converters and the cold-junction software compensation.

Flow diagram:



Code:

Main:

```
#include "four7Seg.h"
```

```
//VARIABLES
float value = 32;
const long interval = 5;
const int buttonPin = 12;
unsigned long counter = 0;
int a,b,c,d = 0; //To select values to num7seg
int anDiode = A1;
int anK = A5;
int anValue = 0;
float Temperatureamb = 0, FilterTempamb = 0, SumTempamb = 0;
float Temperaturek = 0, FilterTempk = 0, SumTempk = 0;
float T_Thermocouple = 0;
int n = 0;
int buttonState = 0;    // current state of the button
int lastButtonState = 0; // previous state of the button
int i = 0;              // to change between T_k, T_amb;

void setup() {
  initDisplay();
  pinMode(buttonPin, INPUT); //Set digital pin 13 as input
}

void loop() {
  buttonState = digitalRead(buttonPin);
  anValue = analogRead(anK);
  Temperaturek = Ttermocouple(anValue);
  anValue = analogRead(anDiode);
  Temperatureamb = Tambience(anValue);
  SumTempk = SumTempk + Temperaturek;
  SumTempamb = SumTempamb + Temperatureamb;
  T_Thermocouple = FilterTempk + FilterTempamb;
  //Filter temperature over one second.
  if(n >= 200){
    FilterTempk = SumTempk/n;
    FilterTempamb = SumTempamb/n;
    SumTempamb = 0;
    SumTempk = 0;
    n = -1;
  }

  // compare the buttonState
  if (buttonState != lastButtonState) {
    // if the state has changed, increment the counter
    if (buttonState == HIGH) {
      i = i + 1;
    }
  }
}
```

```

n = n + 1;
if (i == 1)
{
    splitnumber(T_Thermocouple, &a, &b, &c, &d);
    multiplexDisplay(T_Thermocouple, a, b, c, 0);
}
else
{
    splitnumber(Temperatureamb, &a, &b, &c, &d);
    multiplexDisplay(Temperatureamb, a, b, c, d);
    i = 0;
}
lastButtonState = buttonState;
delay_milis(interval);
}

float Tambience(int analogValue)
{
    //Obtains the temperature from a 1N4148 diode
    //The equation for the one is used:  $V_{diode} = 5 * 0.0026 * T$ 
    //Aux variables
    float vdiode = 0;
    vdiode = (5 * (float)analogValue)/1024;
    return vdiode*76.923 + 4; //where 4 is the offset
}

float Ttermocouple(int analogValue)
{
    //Obtains the temperature from a 1N4148 diode
    //The equation for the one is used:  $V_{diode} = 5 * 0.0026 * T$ 
    //Aux variables
    float vdiode = 0;
    vdiode = (5 * (float)analogValue)/1024;
    return vdiode*100 + 2.5; //(T-Tamb) offset error
}

void delay_milis(unsigned long period)
{
    counter = millis() + period;
    while(millis() < counter)
    {
    }
}

```

## 7 segment Driver

```
/* ****
/* file name : four7Seg.c
/* ****
/* description : Driver for four seven segment displays
/* common anode and multiplexed.
/* programmer : Joaquin Sopena
/* language : ANSI C
/* date : October 25, 2020
/* ****/

#include "Arduino.h"

/* ****
**/
/* Local variables */
/* ****
**/

int num7seg[] = { B11000000, B11111001, B10100100, B10110000,
                  B10011001, B10010010, B10000010, B11111000,
                  B10000000, B10011000};

//Display is connected to pins 0 to 7 of the Arduino, this array contains
//the combinations for numbers 0 to 9.

int count_seg = 4; //Value to manage multiplexing

/* ****
**/
/* Functions */
/* ****
**/
```

```
//Converts a decimal number to its equivalent for seven segment displays
```

```
//Values from 0 to 999 with one decimal.
```

```
void splitnumber(float value, int *h, int *t, int *u, int *th)
```

```
{  
    int tens, units, tenths;  
    int temp = (int)value;  
    float tempth;  
    if(value < 1000) //If not, error.  
    {  
        *h = temp / 100;  
        *th = (int)((value - temp)*10);  
        temp = temp % 100;  
        *t = temp / 10;  
        *u = temp % 10;  
    }  
}
```

```
void multiplexDisplay(float value, int a, int b, int c, int d)
```

```
{  
    if(count_seg == 4 & value > 99){  
        PORTB = B11111110;  
        PORTD = num7seg[a];  
    }  
    if(count_seg == 3 & value > 9){  
        PORTB = B11111101;  
        PORTD = num7seg[b];  
    }  
    if(count_seg == 2){  
        PORTB = B11111011;
```

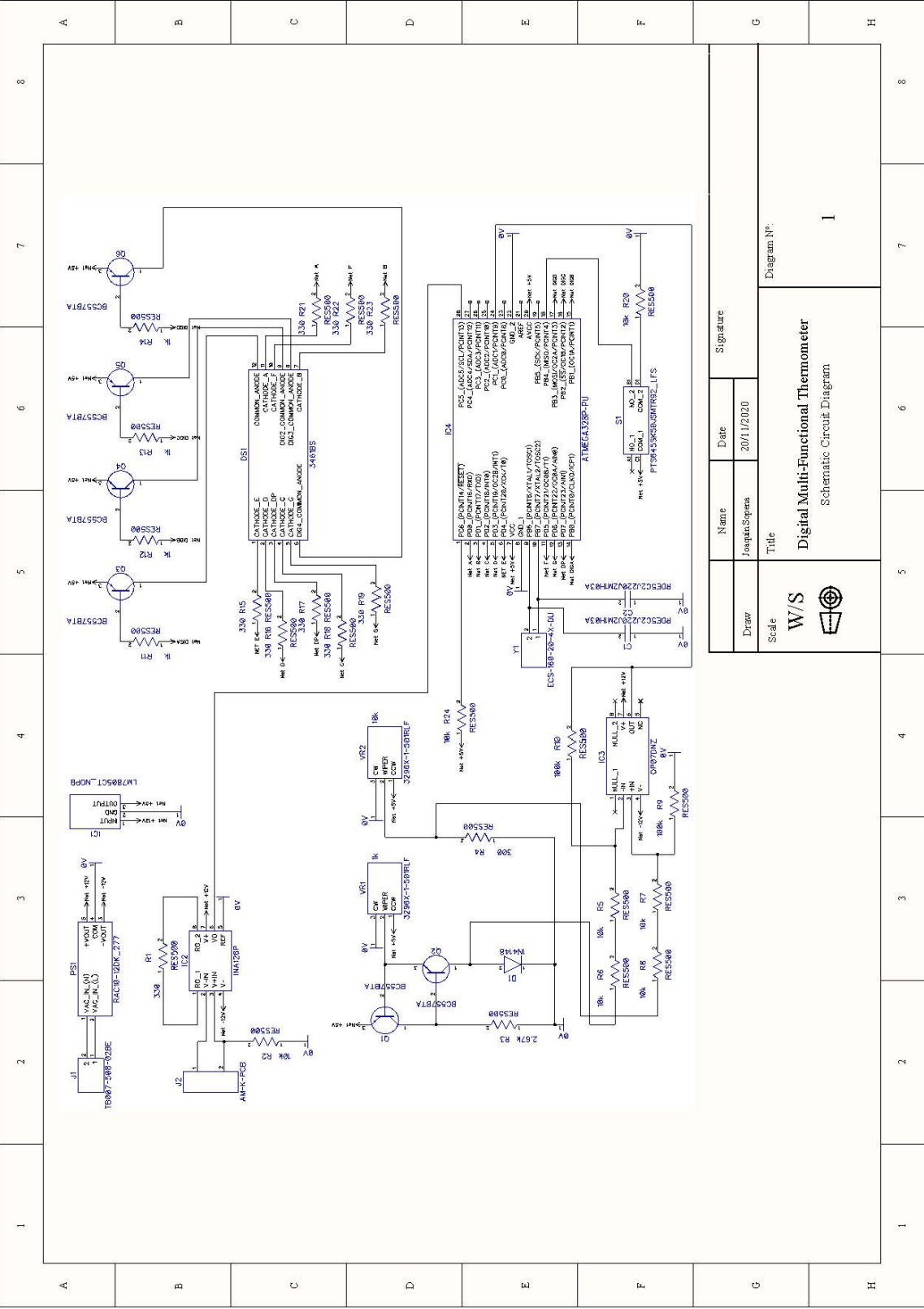
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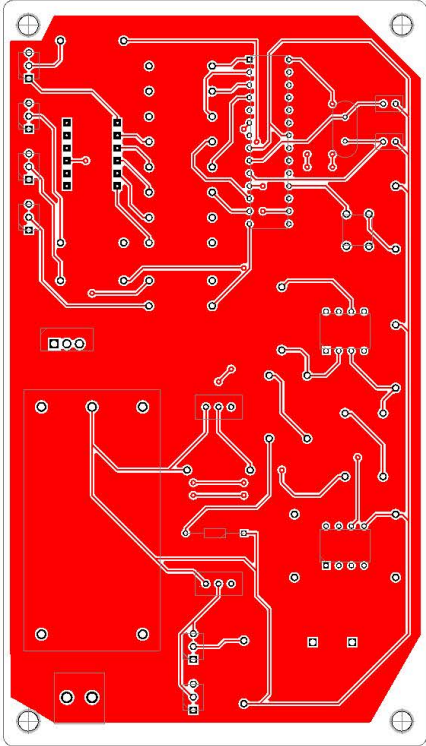
        PORTD = num7seg[c] & B01111111;
    }
    if(count_seg == 1){
        PORTB = B11110111;
        PORTD = num7seg[d];
        count_seg = 5;
    }
    count_seg -=1;
}

void initDisplay()
{
    DDRD = B11111111; //Set Arduino digital pins 0 to 7 as output
    DDRB = B00001111; //Set Arduino digital pin 8-11 as output
}

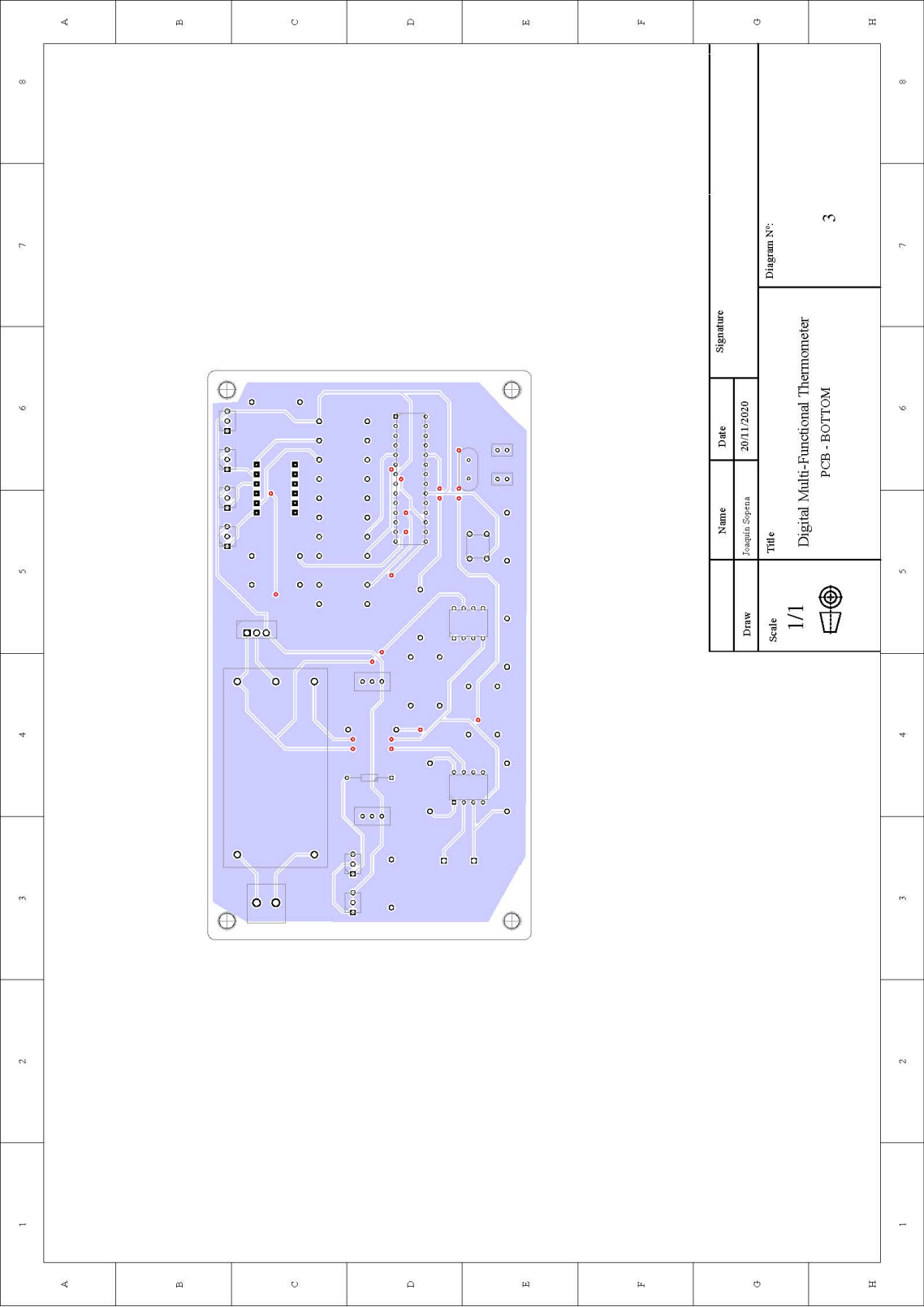
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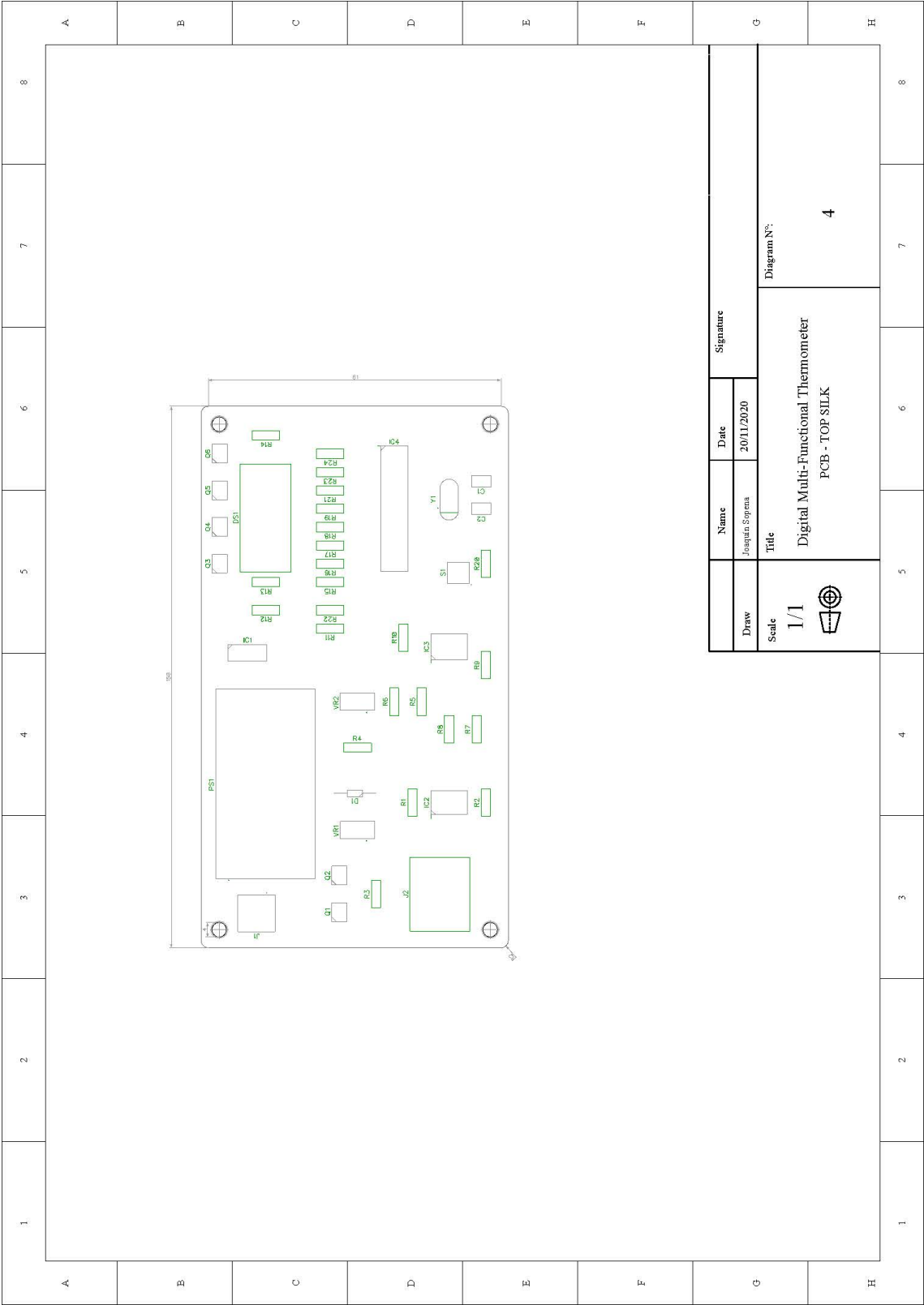
PCB and circuit diagrams:



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C								
D								
E								
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G	Draw		Name		Date		Signature	
H	Scale		Title		Diagram N°:		2	
	1/1		Digital Multi-Functional Thermometer PCB - TOP					







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