

GENERATION OF SPACETIME METRIC WAVES

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Einstein field equations (EFE)
$$G_{\mu\nu} = \frac{8\pi G_N}{c^4} T_{\mu\nu}$$

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Weak field regime EFE (outside source)
$$\Box \bar{h}_{\mu\nu} = 0$$

(EFE)

WAVE EQUATION WITH

PROPAGATION VELOCITY c

Newton's law of universal gravitation

(outside source)

$$=G\frac{m_1 \times m_2}{d^2}$$

GENERATION OF SPACETIME METRIC WAVES

...whose solution is a superposition of plane waves:
$$\bar{h}_{\mu\nu}(t, \mathbf{x}) = \int d^3\mathbf{k} \, A_{\mu\nu}(\mathbf{k}) \cos(c|\mathbf{k}|t - \mathbf{k} \cdot \mathbf{x})$$

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PROPAGATION VELOCITY c

GENERATION OF SPACETIME METRIC WAVES

Newton's law of universal gravitation

$$T = G \frac{m_1 \times m_2}{d^2}$$

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Einstein field equations (EFE)
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By imposing gauge conditions its 10 components reduce to two degrees of freedom, thus for a plane wave along the *z* axis:

$$h_{\mu\nu}^{TT} = egin{bmatrix} 0 & 0 & 0 & 0 \ 0 & h_{+} & h_{ imes} & 0 \ 0 & h_{ imes} & -h_{+} & 0 \ 0 & 0 & 0 & 0 \end{bmatrix} \cos\omega(t-z/c)$$

 h_+ and h_\times are the two GW polarisations perpendicular to the direction of propagation

GRAVITATIONAL PERTURBATION ON MATTER

A GW generates periodic distortions in flat spacetime, which can be described in terms of the Riemann tensor:

$$R^{\mu}_{\nu\rho\sigma} = \frac{1}{2} (\partial_{\rho}\partial_{\nu}h^{\mu}_{\nu\rho} + \partial_{\sigma}\partial^{\mu}h^{\nu\rho} - \partial_{\rho}\partial^{\mu}h^{\nu\sigma} - \partial_{\sigma}\partial_{\nu}h^{\mu}_{\rho})$$

- Measures the curvature of spacetime.
- Embodies the tidal force field and describes the relative acceleration between two particles in free fall.

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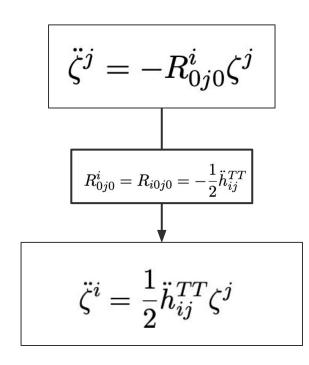
How does the curvature of spacetime affect the motion of matter?

Geodesic deviation: relative motion of nearby particles in terms of a tidal force determined by the Riemann tensor.

$$\frac{D^2 \zeta^{\mu}}{D\tau^2} = -R^{\mu}_{\nu\rho\sigma} \zeta^{\rho} \frac{dx^{\nu}}{d\tau} \frac{dx^{\sigma}}{d\tau}$$

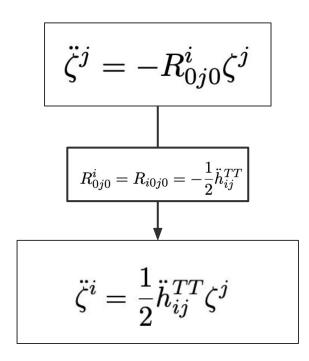
GRAVITATIONAL PERTURBATION ON MATTER

Geodesic deviation for two test masses in a near local-Lorentz frame, moving non-relativistically:



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GW travelling in the z-direction towards a ring of test masses:

- The plus polarisation is

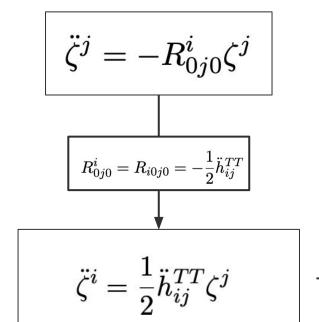
$$h_{ab}^{TT} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} h_{+} \cos \omega t$$

- The displacement between geodesic is

$$\zeta_a(t) = (x_0 + \delta x(t), y_0 + \delta y(t))$$

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$$\delta \ddot{x} = -\frac{h_{+}}{2}(x_{0} + \delta x)\omega^{2} \sin \omega t$$

$$\delta \ddot{y} = \frac{h_{+}}{2}(y_{0} + \delta y)\omega^{2} \sin \omega t$$

$$(\omega^2 \sin \omega t)$$

GRAVITATIONAL PERTURBATION ON MATTER

Integrating for the plus and cross polarisation leads to two set of equations:

$$\delta x(t) = \frac{h_{+}}{2} x_{0} \sin \omega t$$

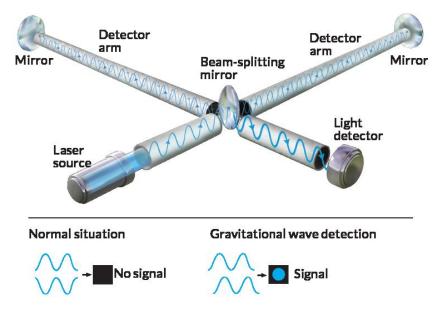
$$\delta y(t) = -\frac{h_{+}}{2} y_{0} \sin \omega t$$

$$h_{+} \left(\begin{array}{c} \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \end{array} \right)$$

$$\omega(t) \quad 0 \quad \frac{\pi}{2} \quad \pi \quad \frac{3\pi}{2} \quad 2\pi$$

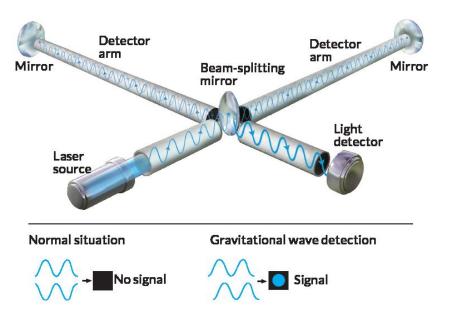
INTERFEROMETRIC DETECTORS

- Laser beam is sent through a beam splitter and ends up in two resonant cavities, in which luminosity is built up.
- The light is allowed to interfere where the arms join together.



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No GW

Interference is destructive, no light hits the photodetector at the output.

GW 🔀

Light path periodically shorten in one direction and lengthen it in the other.

INTERACTION WITH TEST MASSES

The distance of a mirror with respect to the beam splitter is described by the geodesic deviation equation:

$$\ddot{L}^i = \frac{1}{2} \ddot{h}_{ij}^{TT} L^j$$



The proper distance along the *x* axis expands and shrinks periodically, with a fractional length change

$$rac{\delta L}{L_c} \simeq rac{1}{2} h_{xx}^{TT}(t,z=0)$$

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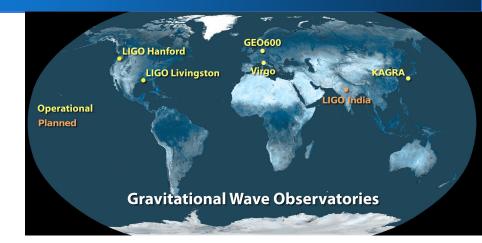


Since h(t) is linear in h_+ and h_\times , it can be written through the *beam pattern functions*

$$h(t) = F_+ h_+(t) + F_\times h_\times(t)$$

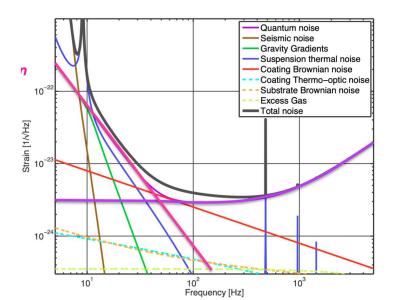
Network of detector is necessary to

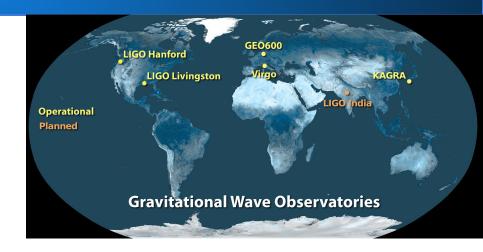
- provide directional information about the source
- separate a signal from noise confidently



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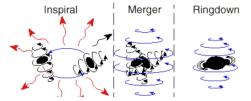
If there is a signal: measured strain is a sum of noise and signal:

$$s(t) = n(t) + h(t)$$

instrumental noise arising from naturally occurring random processes

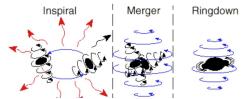
INSPIRALLING BINARY SYSTEMS:

- Compact objects: neutron stars and/or black holes.
- Three stages evolution that leads to coalescence.
- Inspiral needs to be in its final stages in order for the GWs to be detectable by Earth-based interferometers.



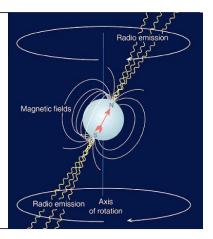
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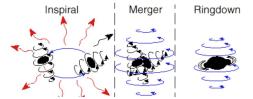
PERIODIC SOURCES:

- Continuous sources of GWs such as pulsars with a non-trivial quadrupole moment.
- Evolution time is longer, GW emission weaker
- GW signal almost constant in amplitude and frequency



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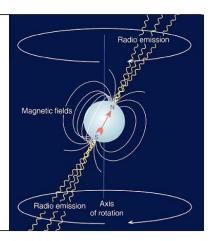
UNMODELED BURST

- Short-duration unknown or unanticipated sources.
- Potential progenitors: systems such as supernovae or gamma ray bursts
- Little is known about the details of these systems to anticipate an accurate waveform



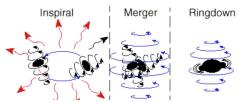
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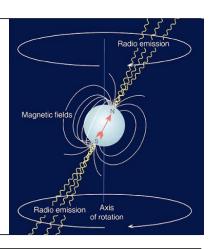
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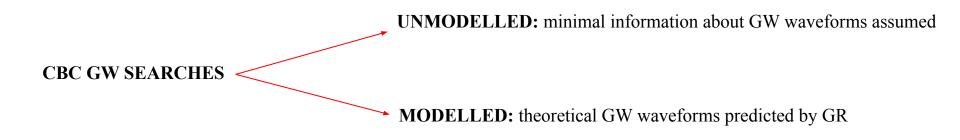
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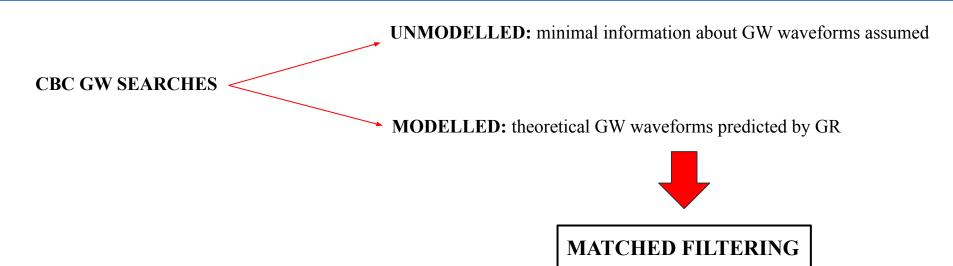
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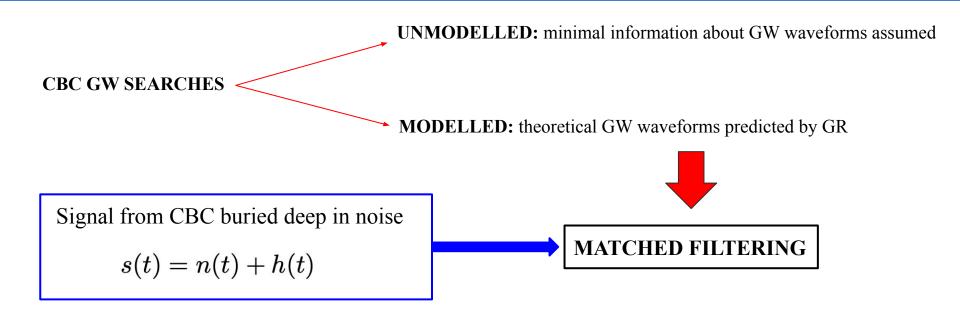


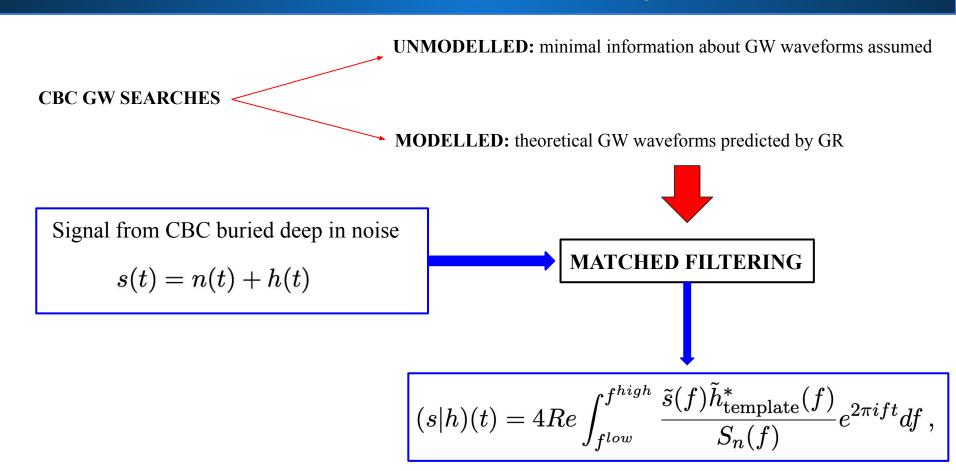
STOCHASTIC GWs

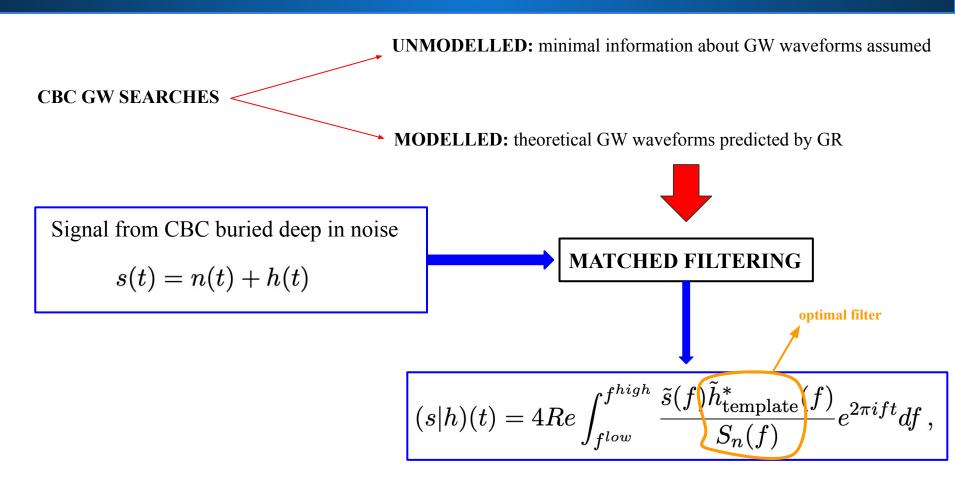
- Remnant GWs from the early evolution of the universe.
- Superposition of GWs produced by many simultaneous inspirals, bursts, or continuous signals from throughout the Universe.
- cosmic GW background

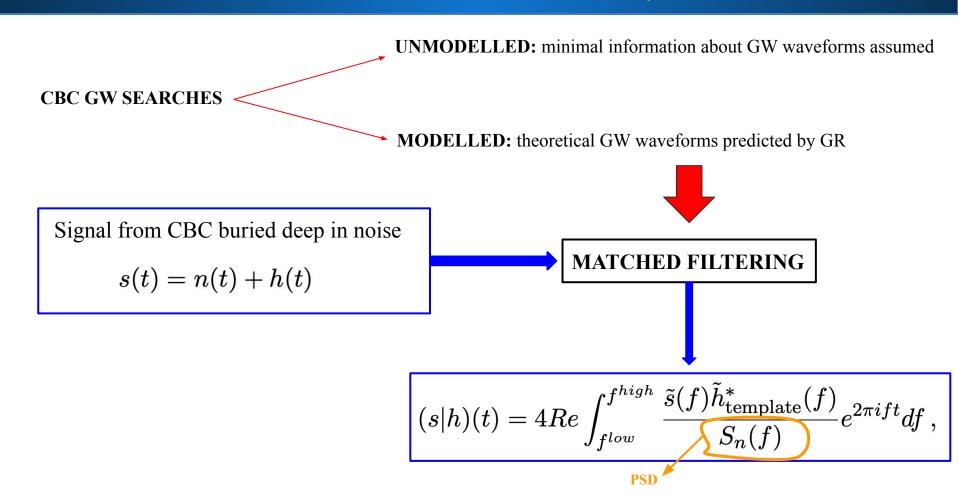


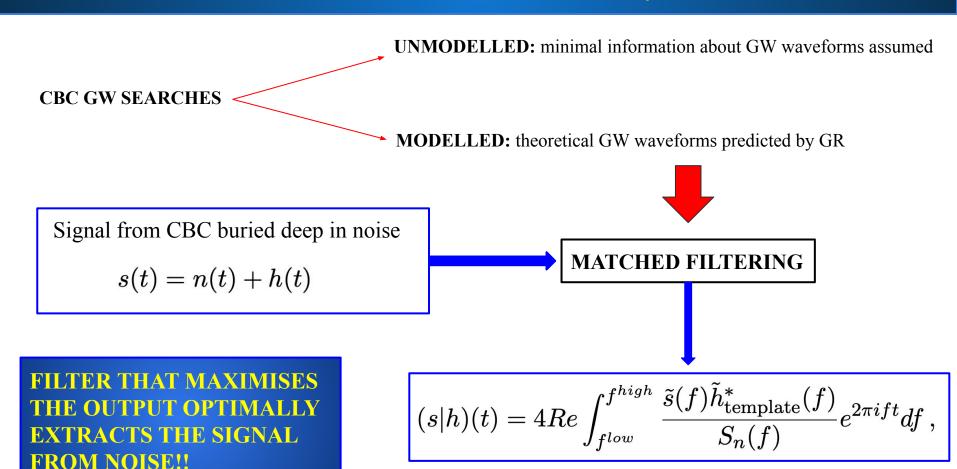












Signal candidate or not?



$$\rho(t) = \frac{|(s|h)|}{\sigma_h}$$

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$$\rho(t) = \frac{|(s|h)|}{\sigma_h}$$
 root-mean-square fluctuations of the optimal filter

Signal candidate or not?



$$\rho(t) = \frac{|(s|h)|}{\sigma_h}$$

- Proportional to the amplitude of the signal buried in the noise.
- Threshold needs to be accurately chosen to avoid high FAR while detecting signals

- Parameters of astrophysical systems will not be known a-priori.
- We know approximate *waveforms* of various sources (BBH, BNS and NSBH).
- To cover the full parameter space is computationally prohibitive.
 - o maximise over an overall amplitude and phase of the signal.
 - use inverse Fourier transform to evaluate the statistic as a function of time.
 - Only intrinsic parameters masses and spins remain.



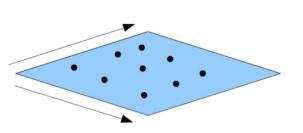
Match-filter data against a predetermined collection of waveform models: the template bank.

TEMPLATE BANKS

Waveforms manifold: continuous space in the component masses and spins.

Lay out template banks over parameter space: points $\lambda = \{\lambda_{intr}, \lambda_{extr}\}$ waveforms

NORMALIZED
$$(\hat{h}_i|\hat{h}_j) = \frac{(h_i|h_j)}{\sqrt{(h_i|h_i)(h_j|h_j)}}$$
 .



 $h(f;\lambda)$

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OVERLAP

 $h(f;\lambda)$

$$(\hat{h}_i|\hat{h}_j) = rac{(h_i|h_j)}{\sqrt{(h_i|h_i)(h_j|h_j)}} \,.$$

MATCH BETWEEN NEARBY TEMPLATES
$$\mathcal{M}(\lambda, \Delta \lambda) \equiv \max_{\Delta \lambda_{extr}} (\hat{h}(f; \lambda), \hat{h}(f; \lambda + \Delta \lambda))$$

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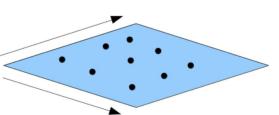
$$\mathcal{M}(\lambda, \Delta \lambda) \simeq 1 - g_{ij} \Delta \lambda^i \Delta \lambda^j$$
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Lay out template banks over parameter space: points
$$\lambda = \{\lambda_{intr}, \lambda_{extr}\}$$
 waveforms $h(f; \lambda)$

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MATCH BETWEEN **NEARBY TEMPLATES**

$$\mathcal{M}(\lambda, \Delta \lambda) \equiv \max_{\Delta \lambda_{extr}} (\hat{h}(f; \lambda), \hat{h}(f; \lambda + \Delta \lambda))$$

MANIFOLD

$$\mathcal{M}(\lambda,\Delta\lambda)\simeq 1-g_{ij}\dot{\Delta}\lambda^i\Delta\lambda^j\,,$$
 $g_{ij}\equiv -rac{1}{2}rac{\partial^2\mathcal{M}}{\partial\Delta\lambda^i\partial\Delta\lambda^j}|_{\Delta}$

$$g_{ij} \equiv -rac{1}{2} rac{\partial^2 \mathcal{M}}{\partial \Delta \lambda^i \partial \Delta \lambda^j} |_{\Delta \lambda = 0}$$

TEMPLATE BANKS

Templates placement in parameter space such that metric distance is never larger than a preset mismatch:

$$1 - \mathcal{M} = g_{ij} \Delta \lambda^i \Delta \lambda^j$$

Choice of the set of waveform models based on *Fitting Factor*:

$$FF(h_*) = \max_{\Lambda} \mathcal{M}(\tilde{h}_*, \tilde{h}(\Lambda))$$
 .

Template discrete placement — Fractional loss of SNR in capturing the signal with the template bank.

$$1-FF(h_*)$$

TEMPLATE BANKS

Effectualness: template bank is built such that no putative signal anywhere in the parameter space has

FF < the minimal match

- Reasonable FF value for effectual bank~97%
- FF distribution as indicator of parameter space regions with poor sensitivity.
- Systems whose GW is weaker corresponds to lowest FF:

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 $FF_{\text{eff}} = \alpha^{1/3}$

★ Poorly aligned and intrinsically low GW luminosity disfavoured.

$$\alpha = \frac{\int d\vec{x} F F^3(\vec{x}) \sigma^3(\vec{x})}{\int d\vec{x} \sigma^3(\vec{x})}$$

CANDIDATE RANKING STATISTIC

Detector calibrated strain data contains both Gaussian and non-Gaussian noise.



Background under control

- Data quality investigations and vetoes
- Consistency checks
 - Mitigate the effect of noise transients.
 - Chi-square test: is signal distribution across frequency band as expected?
 - Assign an accurate statistical significance to candidate signals.

CANDIDATE RANKING STATISTIC

■ Chi-square test

CANDIDATE RANKING STATISTIC

Background estimation

- Estimate search background from the data themselves.
- Time-shift technique: repeat analysis with time offset applied between detectors.
 - Background noise sample: coincidences resulting in this time-shifted data.
 - Each coincident trigger is assigned a FAR.
- Divide search spaces into different classes to deal with non-uniform background.
 - Candidate events is measured against the background from the same class.
- Hierarchical removal of confirmed signals from background to assess significance of other events.

DETECTION STRATEGIES

COINCIDENT ANALYSIS

- Data from individual detectors are processed separately and then combined.
- Signals must be seen in both detectors within an allowed time window.
- Matched filtering done once per detector per template.
- Non-coincident triggers immediately rejected.
- Found coincidences are ranked by

$$\hat{
ho}_{
m coinc} = \sqrt{\hat{
ho}_1^2 + \hat{
ho}_2^2}.$$

• Background estimation analysis repeated, FAR computed as function of the detection statistic.

DETECTION STRATEGIES

COINCIDENT ANALYSIS

Detection is claimed

DETECTION STRATEGIES

COHERENT ANALYSIS

- Data from the individual detectors are combined coherently in phase and then processed.
- Computationally expensive for modelled searches.
 - Externally triggered searches: time and sky-location are known, computational cost is decreased.
- Single statistic for the full network as to construct just one more sensitive detector.
 - New ranking statistic.

DETECTION STRATEGIES

COHERENT ANALYSIS

The multi-detector log-likelihood

$$\ln \lambda = (\mathbf{s}|\mathbf{h}) - \frac{1}{2}(\mathbf{h}|\mathbf{h})$$

- Search a 7D parameter space of signals for binaries on circular orbits with and aligned spin components.

Maximising log-likelihood over the values of the 4 waveform amplitudes leads to:
$$ho_{
m coh}^2\equiv 2\ln\lambda|_{
m MAX}\equiv ({f s}|{f h}_\mu){\cal M}^{\mu
u}({f s}|{f h}_
u)$$

More sensitive search: more effective than the coincident search in removing background noise.

DETECTION STRATEGIES

COHERENT ANALYSIS

- Sensitivity increases with the number of the detectors in the network.
- Other improvements:
 - Ranking statistic.
 - Noise reduction and rejection mechanism.

Null stream consistency: stream that contains transients which do not contribute power to the two-polarisation signal space.

$$\rho_{\rm null}^2 = \rho_{\rm coinc}^2 - \rho_{\rm coh}^2$$

DETECTION STRATEGIES

COHERENT ANALYSIS

■ Chi-square test

The PyGRB pipeline