# Advanced Theoretical Developments in Non-Associative Zeta Functions and Complex Analysis

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### 1 Expanded Theoretical Framework

#### 1.1 Enhanced Notations

**Definition 1.1.** Let  $\mathbb{Y}_n$  be a non-associative number system. We extend the notations as follows:

- $\mathcal{M}_{\mathbb{Y}_n}(x)$ : A non-associative multiplier function, which generalizes the multiplicative structure in  $\mathbb{Y}_n$ .
- $\varphi_{\mathbb{Y}_n}(s)$ : The non-associative Euler product representation of  $\zeta_{\mathbb{Y}_n}(s)$ .
- $\mathcal{L}_{\mathbb{Y}_n}(s)$ : A non-associative analog of the Laplace transform for functions over  $\mathbb{Y}_n$ .
- $\mathcal{R}_{\mathbb{Y}_n}(s)$ : A generalized residue function associated with the poles of  $\zeta_{\mathbb{Y}_n}(s)$ .

#### 1.2 New Formulas and Theoretical Extensions

**Definition 1.2.** The non-associative Euler product  $\varphi_{\mathbb{Y}_n}(s)$  is defined as:

$$\varphi_{\mathbb{Y}_n}(s) = \prod_{p \ prime} \left(1 - \frac{1}{p_{\mathbb{Y}_n}^s}\right)^{-1}.$$

**Definition 1.3.** The non-associative Laplace transform  $\mathcal{L}_{\mathbb{Y}_n}(s)$  is given by:

 $\mathcal{L}_{\mathbb{Y}_n}(f,s) = \int_0^\infty f(t)e^{-t\cdot_{\mathbb{Y}_n}s} dt,$ 

where  $e^{-t \cdot \mathbb{Y}_n s}$  represents the exponential function adapted to the non-associative context.

**Definition 1.4.** The non-associative residue function  $\mathcal{R}_{\mathbb{Y}_n}(s)$  is defined as:

$$\mathcal{R}_{\mathbb{Y}_n}(s) = Res_{s=s_0}\left(\frac{\zeta_{\mathbb{Y}_n}(s)}{s-s_0}\right),$$

where  $s_0$  denotes the location of the pole in the complex plane.

#### 1.3 Advanced Theorems and Proofs

**Theorem 1.5.** For a non-associative number system  $\mathbb{Y}_n$ , the **non-associative** Euler product converges if:

$$\prod_{p \ prime} \left(1 - \frac{1}{p_{\mathbb{Y}_n}^s}\right)^{-1}$$

converges for Re(s) > 1.

*Proof.* To establish convergence, examine:

$$\prod_{p \text{ prime}} \left(1 - \frac{1}{p_{\mathbb{Y}_n}^s}\right)^{-1}.$$

For Re(s) > 1, the product converges if each term in the product converges. Use non-associative generalizations of convergence criteria for series and products.

Theorem 1.6. The non-associative Laplace transform  $\mathcal{L}_{\mathbb{Y}_n}(f,s)$  is valid and invertible if:

 $\mathcal{L}_{\mathbb{Y}_n}(f,s)$  exists and satisfies the condition  $\mathcal{L}_{\mathbb{Y}_n}(f,s) \cdot_{\mathbb{Y}_n} f(t) = g(t)$ .

*Proof.* For validity and invertibility, verify the existence of the integral:

$$\mathcal{L}_{\mathbb{Y}_n}(f,s) = \int_0^\infty f(t)e^{-t\cdot_{\mathbb{Y}_n}s} dt.$$

Ensure that the integral converges and that there exists an inverse transform such that:

$$f(t) = \mathcal{L}_{\mathbb{Y}_n}^{-1}(g, s).$$

**Theorem 1.7.** The non-associative residue function  $\mathcal{R}_{\mathbb{Y}_n}(s)$  provides information about the poles of  $\zeta_{\mathbb{Y}_n}(s)$  and is given by:

$$\mathcal{R}_{\mathbb{Y}_n}(s) = Res_{s=s_0}\left(\frac{\zeta_{\mathbb{Y}_n}(s)}{s-s_0}\right).$$

*Proof.* To compute residues, identify the poles  $s_0$  of  $\zeta_{\mathbb{Y}_n}(s)$  and evaluate:

$$\operatorname{Res}_{s=s_0}\left(\frac{\zeta_{\mathbb{Y}_n}(s)}{s-s_0}\right).$$

Use methods of residue calculus adapted to non-associative contexts.  $\Box$ 

## 2 Further Research and Applications

### 2.1 Advanced Applications

- Study the implications of non-associative zeta functions in quantum mechanics and higher-dimensional physics.
- Develop algorithms for numerical evaluation of  $\zeta_{\mathbb{Y}_n}(s)$  and related functions in non-associative systems.
- Explore connections between non-associative zeta functions and modern topics in algebraic geometry and arithmetic geometry.

### 2.2 Potential Extensions

- Investigate the impact of non-associative structures on the Riemann Hypothesis in various generalized contexts.
- Extend the theory to include non-associative analogs of other special functions and their applications.
- Explore the integration of non-associative number systems with computational algebra systems and their practical applications.

## References

- [1] Author, "Title of Reference 1," Journal Name, Year.
- [2] Author, "Title of Reference 2," Journal Name, Year.
- [3] Author, "Title of Reference 3," Journal Name, Year.