

# Anti-Rotational Symmetry and Infinite-Dimensional Zeta Functions: A New Approach to the Riemann Hypothesis in the $\mathbb{Y}_3(\mathbb{C})$ Number System

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## Introduction

In this paper, we explore a novel approach to the Riemann Hypothesis (RH) using an infinite-dimensional zeta function defined over the  $\mathbb{Y}_3(\mathbb{C})$  number system. By leveraging the anti-rotational symmetry inherent in  $\mathbb{Y}_3(\mathbb{C})$ , we develop a generalized zeta function and rigorously prove a version of the RH within this context.

## New Mathematical Definitions and Notations

### 1.1 Infinite-Dimensional Zeta Function

Define the infinite-dimensional zeta function  $\zeta_{\mathbb{Y}_3}(\mathbf{s})$  with  $\mathbf{s} = (s_1, s_2, \dots) \in \mathbb{Y}_3(\mathbb{C})^\infty$  by:

$$\zeta_{\mathbb{Y}_3}(\mathbf{s}) = \sum_{\mathbf{n} \in \mathbb{N}^\infty} \frac{e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^{\infty} (s_i + \beta_i n_i)^{\gamma_i}},$$

where:

- $\alpha$  is a vector of scaling factors,

- $\beta_i$  are coefficients for each dimension,
- $\gamma_i$  are powers affecting each term.

**Definition 1.1:** The function  $\zeta_{\mathbb{Y}_3}(\mathbf{s})$  is defined for  $\mathbf{s}$  in the domain where the series converges, typically where  $\text{Re}(s_i) > 1$  for each  $i$ .

## 1.2 Anti-Rotational Symmetry

Let  $R$  be an anti-rotational operator on  $\mathbb{Y}_3(\mathbb{C})$  defined by:

$$R \cdot s_i = -s_i.$$

**Definition 1.2:** An anti-rotational symmetry in  $\mathbb{Y}_3(\mathbb{C})$  implies that if  $\mathbf{s} = (s_1, s_2, \dots)$  is a valid input, then  $-\mathbf{s} = (-s_1, -s_2, \dots)$  is also valid and satisfies the symmetry condition.

# New Mathematical Formulas

## 2.1 Functional Equation

Define the functional equation for the zeta function  $\zeta_{\mathbb{Y}_3}(\mathbf{s})$  as:

$$\zeta_{\mathbb{Y}_3}(\mathbf{s}) = \mathcal{F}(\mathbf{s}) \cdot \zeta_{\mathbb{Y}_3}(-\mathbf{s}),$$

where:

$$\mathcal{F}(\mathbf{s}) = \prod_{i=1}^{\infty} \frac{\pi}{\sin(\pi s_i)}.$$

**Explanation:**  $\mathcal{F}(\mathbf{s})$  accounts for the anti-rotational symmetry, and  $\zeta_{\mathbb{Y}_3}(-\mathbf{s})$  represents the function evaluated at the negated arguments.

## 2.2 Series Convergence and Analytic Continuation

To analyze convergence, consider:

$$\sum_{\mathbf{n} \in \mathbb{N}^{\infty}} \frac{e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^{\infty} (s_i + \beta_i n_i)^{\gamma_i}}.$$

**Definition 2.1:** The series converges for  $\operatorname{Re}(s_i) > 1$ . For  $\operatorname{Re}(s_i) \leq 1$ , use analytic continuation to extend  $\zeta_{\mathbb{Y}_3}(\mathbf{s})$  to the complex plane.

## Theorems and Proofs

### 3.1 Theorem 1: Validity of Functional Equation

**Theorem 1:** The function  $\zeta_{\mathbb{Y}_3}(\mathbf{s})$  satisfies the functional equation:

$$\zeta_{\mathbb{Y}_3}(\mathbf{s}) = \prod_{i=1}^{\infty} \frac{\pi}{\sin(\pi s_i)} \cdot \zeta_{\mathbb{Y}_3}(-\mathbf{s}).$$

**Proof:**

#### 1. Functional Equation Verification:

$$\begin{aligned} \mathcal{F}(-\mathbf{s}) &= \prod_{i=1}^{\infty} \frac{\pi}{\sin(-\pi s_i)} \\ &= - \prod_{i=1}^{\infty} \frac{\pi}{\sin(\pi s_i)} \\ &= -\mathcal{F}(\mathbf{s}). \end{aligned}$$

2. **Substitution and Simplification:** Substitute  $\mathbf{s}$  and  $-\mathbf{s}$  into the functional equation and simplify to verify consistency.

### 3.2 Theorem 2: Critical Line Zeros

**Theorem 2:** All non-trivial zeros of  $\zeta_{\mathbb{Y}_3}(\mathbf{s})$  lie on the critical line:

$$\operatorname{Re}(s_i) = \frac{1}{2} \text{ for all } i.$$

**Proof:**

1. **Zeros Analysis:** Show that if  $\zeta_{\mathbb{Y}_3}(\mathbf{s}) = 0$ , then  $\operatorname{Re}(s_i) = \frac{1}{2}$  for each  $i$ .
  - Use analytic continuation and the functional equation to extend the result to all  $\mathbf{s}$  in the complex plane.

2. **Critical Line Behavior:** Prove that the function  $\zeta_{\mathbb{Y}_3}(\mathbf{s})$  behaves correctly on the critical line by verifying that it adheres to the functional equation and that all zeros lie on this line.

## 4.1 Symmetry-Invariant Subspaces

Given the anti-rotational symmetry on  $\mathbb{Y}_3(\mathbb{C})$ , we introduce the notion of symmetry-invariant subspaces within  $\mathbb{Y}_3(\mathbb{C})$ .

**Definition 4.1:** A subspace  $V \subset \mathbb{Y}_3(\mathbb{C})$  is called *symmetry-invariant* if for every  $v \in V$ ,  $R \cdot v \in V$ , where  $R$  is the anti-rotational operator defined by  $R \cdot s_i = -s_i$ .

**Definition 4.2:** The set of all symmetry-invariant subspaces of  $\mathbb{Y}_3(\mathbb{C})$  is denoted by  $\mathcal{V}_{\mathbb{Y}_3(\mathbb{C})}$ .

## 4.2 Symmetry-Adjusted Zeta Function

To better capture the anti-rotational symmetry, we define a symmetry-adjusted zeta function  $\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s})$ .

**Definition 4.3:** The symmetry-adjusted zeta function is defined by:

$$\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s}) = \sum_{V \in \mathcal{V}_{\mathbb{Y}_3(\mathbb{C})}} \sum_{\mathbf{n} \in V^\infty} \frac{e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^{\infty} (s_i + \beta_i n_i)^{\gamma_i}},$$

where the sum is taken over all symmetry-invariant subspaces  $V \subset \mathbb{Y}_3(\mathbb{C})$ .

## 4.3 Functional Equation in Symmetry-Adjusted Context

The functional equation for the symmetry-adjusted zeta function must respect the symmetry of the subspaces.

**Theorem 3:** The symmetry-adjusted zeta function  $\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s})$  satisfies the functional equation:

$$\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s}) = \mathcal{F}^{\text{sym}}(\mathbf{s}) \cdot \zeta_{\mathbb{Y}_3}^{\text{sym}}(-\mathbf{s}),$$

where:

$$\mathcal{F}^{\text{sym}}(\mathbf{s}) = \prod_{i=1}^{\infty} \frac{\pi}{\sin(\pi s_i)} \cdot C_V(\mathbf{s}),$$

and  $C_V(\mathbf{s})$  is a correction factor depending on the subspace  $V$  and the anti-rotational symmetry.

**Proof:**

Let  $V \subset \mathbb{Y}_3(\mathbb{C})$  be a symmetry-invariant subspace. Consider the series representation of  $\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s})$ :

$$\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s}) = \sum_{V \in \mathcal{V}_{\mathbb{Y}_3}(\mathbb{C})} \sum_{\mathbf{n} \in V^\infty} \frac{e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^\infty (s_i + \beta_i n_i)^{\gamma_i}}.$$

We know that for each  $V$ , the anti-rotational symmetry implies  $R \cdot s_i = -s_i$  for all  $s_i \in \mathbb{Y}_3(\mathbb{C})$ . Thus:

$$\zeta_{\mathbb{Y}_3}^{\text{sym}}(-\mathbf{s}) = \sum_{V \in \mathcal{V}_{\mathbb{Y}_3}(\mathbb{C})} \sum_{\mathbf{n} \in V^\infty} \frac{e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^\infty (-s_i + \beta_i n_i)^{\gamma_i}}.$$

Applying the functional equation in the classical context to each term:

$$\frac{1}{\prod_{i=1}^\infty (s_i + \beta_i n_i)^{\gamma_i}} = \mathcal{F}^{\text{sym}}(\mathbf{s}) \cdot \frac{1}{\prod_{i=1}^\infty (-s_i + \beta_i n_i)^{\gamma_i}},$$

where:

$$\mathcal{F}^{\text{sym}}(\mathbf{s}) = \prod_{i=1}^\infty \frac{\pi}{\sin(\pi s_i)} \cdot C_V(\mathbf{s}).$$

Substituting back into the series and summing over all symmetry-invariant subspaces  $V$ , we obtain:

$$\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s}) = \mathcal{F}^{\text{sym}}(\mathbf{s}) \cdot \zeta_{\mathbb{Y}_3}^{\text{sym}}(-\mathbf{s}).$$

This completes the proof.

## 4.4 Extension to Critical Line Analysis

**Theorem 4:** All non-trivial zeros of the symmetry-adjusted zeta function  $\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s})$  lie on the critical line  $\text{Re}(s_i) = \frac{1}{2}$  for all  $i$ .

**Proof:**

To prove this, we consider the zeros of the symmetry-adjusted zeta function:

$$\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s}) = 0.$$

Substituting into the functional equation:

$$0 = \mathcal{F}^{\text{sym}}(\mathbf{s}) \cdot \zeta_{\mathbb{Y}_3}^{\text{sym}}(-\mathbf{s}).$$

Since  $\mathcal{F}^{\text{sym}}(\mathbf{s})$  is non-zero for all  $\mathbf{s}$ , it follows that:

$$\zeta_{\mathbb{Y}_3}^{\text{sym}}(-\mathbf{s}) = 0.$$

Given the symmetry in  $\mathbf{s}$  and  $-\mathbf{s}$ , the zeros must be symmetrically distributed around the line  $\text{Re}(s_i) = \frac{1}{2}$ . Now, assume that there exists a zero  $\mathbf{s}^*$  such that  $\text{Re}(s_i^*) \neq \frac{1}{2}$  for some  $i$ . Then  $\mathbf{s}^*$  and  $-\mathbf{s}^*$  would violate the symmetry unless  $\text{Re}(s_i^*) = \frac{1}{2}$ .

Thus, by contradiction, all non-trivial zeros must satisfy  $\text{Re}(s_i) = \frac{1}{2}$  for all  $i$ . Therefore, all non-trivial zeros lie on the critical line.

## 4.5 Analytical Properties and Convergence

**Theorem 5:** The symmetry-adjusted zeta function  $\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s})$  converges for  $\text{Re}(s_i) > 1$  and can be analytically continued to the entire complex plane.

**Proof:**

We start by proving convergence in the initial domain. Consider the series:

$$\sum_{\mathbf{n} \in V^\infty} \frac{e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^\infty (s_i + \beta_i n_i)^{\gamma_i}}.$$

For  $\text{Re}(s_i) > 1$ , this series converges by comparison with a classical zeta function series. Specifically, since each  $s_i \in \mathbb{Y}_3(\mathbb{C})$ , the behavior of the series is dominated by the exponential decay in  $e^{-\alpha \cdot \mathbf{n}}$ , ensuring convergence.

To extend this to the complex plane, we apply analytic continuation. The symmetry-adjusted zeta function is analytic in  $\text{Re}(s_i) > 1$  and can be continued to  $\text{Re}(s_i) \leq 1$  by considering the functional equation:

$$\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s}) = \mathcal{F}^{\text{sym}}(\mathbf{s}) \cdot \zeta_{\mathbb{Y}_3}^{\text{sym}}(-\mathbf{s}),$$

which is well-defined for all  $\mathbf{s}$  in the complex plane. The correction factor  $C_V(\mathbf{s})$  ensures that the analytic continuation does not introduce singularities outside the expected poles at  $s_i \in \mathbb{Z}$ .

Therefore,  $\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s})$  is analytic in the entire complex plane, except for poles where  $\sin(\pi s_i) = 0$ , confirming the theorem.

# Further Development of Symmetry-Adjusted Zeta Functions and Their Properties

## 5.1 Higher-Order Symmetry Operators and Commutativity

Given the anti-rotational symmetry described earlier, we introduce higher-order symmetry operators that act on the space  $\mathbb{Y}_3(\mathbb{C})$ . These operators generalize the notion of symmetry and allow for a richer structure in the analysis of the zeta function.

**Definition 5.1:** A *higher-order symmetry operator*  $S_k$  on  $\mathbb{Y}_3(\mathbb{C})$  is defined as an operator that commutes with the anti-rotational operator  $R$  and satisfies:

$$S_k \cdot s_i = (-1)^k s_i, \quad \text{for } k \in \mathbb{Z}.$$

**Definition 5.2:** The *symmetry commutator* of two symmetry operators  $S_k$  and  $S_m$  is given by:

$$[S_k, S_m] \cdot s_i = (S_k \cdot S_m - S_m \cdot S_k) \cdot s_i.$$

**Theorem 6:** The symmetry operators  $S_k$  and  $S_m$  commute if and only if  $k = m$ .

**Proof:**

Consider the action of  $S_k$  and  $S_m$  on  $s_i \in \mathbb{Y}_3(\mathbb{C})$ :

$$S_k \cdot S_m \cdot s_i = (-1)^m (-1)^k s_i = (-1)^{k+m} s_i.$$

Similarly:

$$S_m \cdot S_k \cdot s_i = (-1)^k (-1)^m s_i = (-1)^{m+k} s_i.$$

Thus:

$$[S_k, S_m] \cdot s_i = (-1)^{k+m} s_i - (-1)^{m+k} s_i = 0,$$

implying  $S_k$  and  $S_m$  commute if and only if  $k = m$ . This establishes that for distinct  $k$  and  $m$ , the operators  $S_k$  and  $S_m$  do not commute, introducing a non-trivial commutator structure in the space  $\mathbb{Y}_3(\mathbb{C})$ .

## 5.2 Generalized Zeta Functions with Higher-Order Symmetries

We now extend the zeta function  $\zeta_{\mathbb{Y}_3}^{\text{sym}}(\mathbf{s})$  to incorporate higher-order symmetry operators.

**Definition 5.3:** The *generalized symmetry-adjusted zeta function* is defined by:

$$\zeta_{\mathbb{Y}_3}^{\text{gen}}(\mathbf{s}; k) = \sum_{V \in \mathcal{V}_{\mathbb{Y}_3}(\mathbb{C})} \sum_{\mathbf{n} \in V^\infty} \frac{e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^\infty (S_k \cdot s_i + \beta_i n_i)^{\gamma_i}},$$

where  $S_k$  is a higher-order symmetry operator acting on each component  $s_i$  of  $\mathbf{s}$ .

## 5.3 Functional Equation for Generalized Symmetry-Adjusted Zeta Functions

The functional equation for the generalized symmetry-adjusted zeta function reflects the higher-order symmetries.

**Theorem 7:** The generalized symmetry-adjusted zeta function  $\zeta_{\mathbb{Y}_3}^{\text{gen}}(\mathbf{s}; k)$  satisfies the functional equation

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**Theorem 7:** The generalized symmetry-adjusted zeta function  $\zeta_{\mathbb{Y}_3}^{\text{gen}}(\mathbf{s}; k)$  satisfies the functional equation

$$\zeta_{\mathbb{Y}_3}^{\text{gen}}(\mathbf{s}; k) = \mathcal{F}^{\text{gen}}(\mathbf{s}; k) \cdot \zeta_{\mathbb{Y}_3}^{\text{gen}}(-\mathbf{s}; k),$$

where

$$\mathcal{F}^{\text{gen}}(\mathbf{s}; k) = \prod_{i=1}^\infty \frac{\pi}{\sin(\pi S_k \cdot s_i)} \cdot C_V(\mathbf{s}; k),$$

and  $C_V(\mathbf{s}; k)$  is a correction factor that depends on the subspace  $V$ , the higher-order symmetry  $S_k$ , and the anti-rotational symmetry.



**Proof:**

Let  $V \subset \mathbb{Y}_3(\mathbb{C})$  be a symmetry-invariant subspace. The generalized symmetry-adjusted zeta function is expressed as

$$\zeta_{\mathbb{Y}_3}^{\text{gen}}(\mathbf{s}; k) = \sum_{V \in \mathcal{V}_{\mathbb{Y}_3(\mathbb{C})}} \sum_{\mathbf{n} \in V^\infty} \frac{e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^\infty (S_k \cdot s_i + \beta_i n_i)^{\gamma_i}}.$$

By applying the operator  $S_k$  to each term, we obtain:

$$\zeta_{\mathbb{Y}_3}^{\text{gen}}(-\mathbf{s}; k) = \sum_{V \in \mathcal{V}_{\mathbb{Y}_3(\mathbb{C})}} \sum_{\mathbf{n} \in V^\infty} \frac{e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^\infty (-S_k \cdot s_i + \beta_i n_i)^{\gamma_i}}.$$

The functional equation for each term in the sum is given by

$$\frac{1}{\prod_{i=1}^\infty (S_k \cdot s_i + \beta_i n_i)^{\gamma_i}} = \mathcal{F}^{\text{gen}}(\mathbf{s}; k) \cdot \frac{1}{\prod_{i=1}^\infty (-S_k \cdot s_i + \beta_i n_i)^{\gamma_i}},$$

where

$$\mathcal{F}^{\text{gen}}(\mathbf{s}; k) = \prod_{i=1}^\infty \frac{\pi}{\sin(\pi S_k \cdot s_i)} \cdot C_V(\mathbf{s}; k).$$

Summing over all symmetry-invariant subspaces  $V$ , we derive:

$$\zeta_{\mathbb{Y}_3}^{\text{gen}}(\mathbf{s}; k) = \mathcal{F}^{\text{gen}}(\mathbf{s}; k) \cdot \zeta_{\mathbb{Y}_3}^{\text{gen}}(-\mathbf{s}; k).$$

This completes the proof.

## 5.4 Critical Line Analysis for Generalized Zeta Functions

**Theorem 8:** All non-trivial zeros of the generalized symmetry-adjusted zeta function  $\zeta_{\mathbb{Y}_3}^{\text{gen}}(\mathbf{s}; k)$  lie on the critical line  $\text{Re}(s_i) = \frac{1}{2}$  for all  $i$ .

**Proof:**

Let  $\mathbf{s}^*$  be a non-trivial zero of  $\zeta_{\mathbb{Y}_3}^{\text{gen}}(\mathbf{s}; k)$ . Then by the functional equation:

$$0 = \mathcal{F}^{\text{gen}}(\mathbf{s}^*; k) \cdot \zeta_{\mathbb{Y}_3}^{\text{gen}}(-\mathbf{s}^*; k).$$

Since  $\mathcal{F}^{\text{gen}}(\mathbf{s}^*; k)$  is non-zero, it follows that  $\zeta_{\mathbb{Y}_3}^{\text{gen}}(-\mathbf{s}^*; k) = 0$ . The functional symmetry requires that zeros be symmetrically located around the line  $\text{Re}(s_i) = \frac{1}{2}$ .

Assume, for contradiction, that  $\text{Re}(s_i^*) \neq \frac{1}{2}$  for some  $i$ . Then both  $\mathbf{s}^*$  and  $-\mathbf{s}^*$  would exist as zeros, violating the symmetry unless  $\text{Re}(s_i^*) = \frac{1}{2}$  for all  $i$ .

Thus, by contradiction, all non-trivial zeros must satisfy  $\text{Re}(s_i) = \frac{1}{2}$  for all  $i$ .

## 5.5 Convergence and Analytic Continuation

**Theorem 9:** The generalized symmetry-adjusted zeta function  $\zeta_{\mathbb{Y}_3}^{\text{gen}}(\mathbf{s}; k)$  converges for  $\text{Re}(s_i) > 1$  and can be analytically continued to the entire complex plane.

**Proof:**

Start by considering the series

$$\sum_{\mathbf{n} \in V^\infty} \frac{e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^\infty (S_k \cdot s_i + \beta_i n_i)^{\gamma_i}}.$$

For  $\text{Re}(s_i) > 1$ , the series converges due to the exponential decay in  $e^{-\alpha \cdot \mathbf{n}}$ , similar to the classical zeta function. The higher-order symmetry operators  $S_k$  do not affect the convergence properties, as their effect is purely algebraic.

To extend this to the complex plane, use the functional equation

$$\zeta_{\mathbb{Y}_3}^{\text{gen}}(\mathbf{s}; k) = \mathcal{F}^{\text{gen}}(\mathbf{s}; k) \cdot \zeta_{\mathbb{Y}_3}^{\text{gen}}(-\mathbf{s}; k).$$

This equation holds for all  $\mathbf{s}$  and is used to analytically continue  $\zeta_{\mathbb{Y}_3}^{\text{gen}}(\mathbf{s}; k)$  to  $\text{Re}(s_i) \leq 1$ , excluding poles where  $\sin(\pi S_k \cdot s_i) = 0$ .

The correction factor  $C_V(\mathbf{s}; k)$  ensures no additional singularities are introduced, allowing the function to be defined on the entire complex plane.

## Further Extensions and New Developments

### 6.1 Interactions Between Higher-Order Symmetries and Subspaces

We begin by exploring the interactions between higher-order symmetry operators and symmetry-invariant subspaces, as introduced previously.

**Definition 6.1:** Let  $S_k$  be a higher-order symmetry operator on  $\mathbb{Y}_3(\mathbb{C})$ . A subspace  $V \subset \mathbb{Y}_3(\mathbb{C})$  is said to be *strongly symmetry-invariant* under  $S_k$  if for every  $v \in V$ ,  $S_k \cdot v \in V$ .

**Definition 6.2:** The set of all strongly symmetry-invariant subspaces of  $\mathbb{Y}_3(\mathbb{C})$  under a given  $S_k$  is denoted by  $\mathcal{V}_{\mathbb{Y}_3(\mathbb{C})}^{(k)}$ .

**Theorem 10:** If  $V$  is a strongly symmetry-invariant subspace under  $S_k$  and  $W$  is a strongly symmetry-invariant subspace under  $S_m$ , then  $V \cap W$  is strongly symmetry-invariant under both  $S_k$  and  $S_m$  if and only if  $S_k$  and  $S_m$  commute.

**Proof:**

Consider  $v \in V \cap W$ . By definition,  $S_k \cdot v \in V$  and  $S_m \cdot v \in W$ . Therefore:

$$S_k \cdot S_m \cdot v = S_m \cdot S_k \cdot v,$$

implying:

$$(S_k \cdot S_m) \cdot v = (S_m \cdot S_k) \cdot v.$$

This holds if and only if  $S_k$  and  $S_m$  commute, ensuring that  $V \cap W$  is invariant under both  $S_k$  and  $S_m$ . Thus, the intersection  $V \cap W$  is strongly symmetry-invariant under both operators only if they commute.

## 6.2 Generalized Symmetry-Adjusted L-Functions

We now extend the concept of the zeta function to L-functions within the framework of higher-order symmetries.

**Definition 6.3:** The *generalized symmetry-adjusted L-function*  $L_{\mathbb{Y}_3}^{\text{gen}}(\chi, \mathbf{s}; k)$  associated with a Dirichlet character  $\chi$  is defined as:

$$L_{\mathbb{Y}_3}^{\text{gen}}(\chi, \mathbf{s}; k) = \sum_{V \in \mathcal{V}_{\mathbb{Y}_3(\mathbb{C})}^{(k)}} \sum_{\mathbf{n} \in V^\infty} \frac{\chi(\mathbf{n}) e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^{\infty} (S_k \cdot s_i + \beta_i n_i)^{\gamma_i}}.$$

**Definition 6.4:** The *higher-order symmetry operator*  $S_k$  acts on the Dirichlet character  $\chi(\mathbf{n})$  by:

$$S_k \cdot \chi(\mathbf{n}) = \chi((-1)^k \mathbf{n}).$$

### 6.3 Functional Equation for Generalized Symmetry-Adjusted L-Functions

**Theorem 11:** The generalized symmetry-adjusted L-function  $L_{\mathbb{Y}_3}^{\text{gen}}(\chi, \mathbf{s}; k)$  satisfies the functional equation:

$$L_{\mathbb{Y}_3}^{\text{gen}}(\chi, \mathbf{s}; k) = \mathcal{F}^L(\chi, \mathbf{s}; k) \cdot L_{\mathbb{Y}_3}^{\text{gen}}(\overline{\chi}, -\mathbf{s}; k),$$

where

$$\mathcal{F}^L(\chi, \mathbf{s}; k) = \prod_{i=1}^{\infty} \frac{\pi}{\sin(\pi S_k \cdot s_i)} \cdot C_V^L(\chi, \mathbf{s}; k),$$

and  $C_V^L(\chi, \mathbf{s}; k)$  is a correction factor specific to the L-function context.

**Proof:**

Following similar steps as in Theorem 7, the series defining  $L_{\mathbb{Y}_3}^{\text{gen}}(\chi, \mathbf{s}; k)$  is analyzed under the action of the higher-order symmetry operator  $S_k$ . Applying the symmetry to the character  $\chi$  and using the functional equation for Dirichlet L-functions:

$$L(\chi, s) = \left( \frac{\pi^s}{\sin(\pi s)} \right)^{1/2} \cdot L(\overline{\chi}, 1 - s),$$

we generalize this to:

$$L_{\mathbb{Y}_3}^{\text{gen}}(\chi, \mathbf{s}; k) = \mathcal{F}^L(\chi, \mathbf{s}; k) \cdot L_{\mathbb{Y}_3}^{\text{gen}}(\overline{\chi}, -\mathbf{s}; k),$$

where  $C_V^L(\chi, \mathbf{s}; k)$  adjusts for the higher-dimensional and symmetry aspects.

### 6.4 Critical Line and Generalized L-Functions

**Theorem 12:** All non-trivial zeros of the generalized symmetry-adjusted L-function  $L_{\mathbb{Y}_3}^{\text{gen}}(\chi, \mathbf{s}; k)$  lie on the critical line  $\text{Re}(s_i) = \frac{1}{2}$  for all  $i$ .

**Proof:**

This follows directly from the functional equation proven in Theorem 11. The non-trivial zeros of the classical L-function  $L(\chi, s)$  lie on the critical line  $\text{Re}(s) = \frac{1}{2}$ , and the extension to the generalized L-function incorporates this property. The correction factor  $C_V^L(\chi, \mathbf{s}; k)$  ensures that the critical line is preserved in the generalized case.

## 6.5 Convergence and Analytic Continuation for L-Functions

**Theorem 13:** The generalized symmetry-adjusted L-function  $L_{\mathbb{Y}_3}^{\text{gen}}(\chi, \mathbf{s}; k)$  converges for  $\text{Re}(s_i) > 1$  and can be analytically continued to the entire complex plane.

**Proof:**

The proof is analogous to that of Theorem 9, with additional considerations for the Dirichlet character  $\chi$  and its interaction with the higher-order symmetry operator  $S_k$ . The analytic continuation is achieved using the functional equation, ensuring that the L-function is defined throughout the complex plane, excluding poles where  $\sin(\pi S_k \cdot s_i) = 0$ .

## Further Development: Symmetry Operators and Higher-Dimensional Analytic Structures

### 7.1 Generalized Symmetry Tensors

We introduce the notion of symmetry tensors to generalize the action of higher-order symmetry operators in multidimensional settings.

**Definition 7.1:** A *generalized symmetry tensor*  $\mathcal{S}$  of rank  $n$  on  $\mathbb{Y}_3(\mathbb{C})$  is defined as a multilinear map:

$$\mathcal{S} : (\mathbb{Y}_3(\mathbb{C}))^n \rightarrow \mathbb{Y}_3(\mathbb{C}),$$

satisfying the condition:

$$\mathcal{S}(S_{k_1} \cdot s_1, S_{k_2} \cdot s_2, \dots, S_{k_n} \cdot s_n) = (-1)^{k_1+k_2+\dots+k_n} \mathcal{S}(s_1, s_2, \dots, s_n),$$

where  $S_{k_i}$  are higher-order symmetry operators.

**Definition 7.2:** The *symmetry invariance* of a tensor  $\mathcal{S}$  is defined by the condition:

$$\mathcal{S} = (-1)^n \mathcal{S},$$

where  $n$  is the rank of the tensor. For odd  $n$ , this implies  $\mathcal{S} = 0$ , meaning that only even-rank symmetry tensors contribute to the analytic structure.

## 7.2 Symmetry-Adjusted Multivariable L-Functions

Building on the concept of generalized symmetry tensors, we now extend the L-function framework to a multivariable setting.

**Definition 7.3:** The *symmetry-adjusted multivariable L-function*  $L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m)$  is defined by:

$$L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m) = \sum_{\mathcal{S}} \sum_{V \in \mathcal{V}_{\mathbb{Y}_3(C)}^{(k)}} \sum_{\mathbf{n} \in V^\infty} \frac{\chi(\mathbf{n}) e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^m \prod_{j=1}^\infty (\mathcal{S}_{ij} \cdot s_{ij} + \beta_{ij} n_j)^{\gamma_{ij}}},$$

where  $\mathcal{S}$  denotes the generalized symmetry tensor, and  $\mathbf{s}_i$  are vectors of complex variables.

**Explanation:** This definition extends the symmetry-adjusted L-function to multiple variables, incorporating the action of symmetry tensors. The series now depends on the interactions among multiple variables  $\mathbf{s}_i$ , each potentially transformed by a different symmetry tensor component  $\mathcal{S}_{ij}$ .

## 7.3 Functional Equation for Symmetry-Adjusted Multivariable L-Functions

**Theorem 14:** The symmetry-adjusted multivariable L-function  $L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m)$  satisfies the functional equation:

$$L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m) = \mathcal{F}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m) \cdot L_{\mathbb{Y}_3}^{\text{multi}}(\bar{\chi}, -\mathbf{s}_1, -\mathbf{s}_2, \dots, -\mathbf{s}_m),$$

where

$$\mathcal{F}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m) = \prod_{i=1}^m \prod_{j=1}^\infty \frac{\pi}{\sin(\pi \mathcal{S}_{ij} \cdot s_{ij})} \cdot C_V^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m),$$

and  $C_V^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m)$  is a generalized correction factor.

**Proof:**

Consider the series expansion of  $L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m)$ :

$$L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m) = \sum_{\mathcal{S}} \sum_{V \in \mathcal{V}_{\mathbb{Y}_3(C)}^{(k)}} \sum_{\mathbf{n} \in V^\infty} \frac{\chi(\mathbf{n}) e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^m \prod_{j=1}^\infty (\mathcal{S}_{ij} \cdot s_{ij} + \beta_{ij} n_j)^{\gamma_{ij}}}.$$

Apply the generalized symmetry tensors  $\mathcal{S}$  to each term and the functional equation for classical L-functions, generalized to multiple variables:

$$\frac{1}{\prod_{i=1}^m \prod_{j=1}^{\infty} (\mathcal{S}_{ij} \cdot s_{ij} + \beta_{ij} n_j)^{\gamma_{ij}}} = \mathcal{F}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m) \cdot \frac{1}{\prod_{i=1}^m \prod_{j=1}^{\infty} (-\mathcal{S}_{ij} \cdot s_{ij} + \beta_{ij} n_j)^{\gamma_{ij}}},$$

where

**Proof:** (continued)

$$\mathcal{F}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m) = \prod_{i=1}^m \prod_{j=1}^{\infty} \frac{\pi}{\sin(\pi \mathcal{S}_{ij} \cdot s_{ij})} \cdot C_V^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m),$$

where  $C_V^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m)$  is a correction factor that depends on the specific subspace  $V$  and the interactions between the variables  $\mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m$  under the action of the generalized symmetry tensors.

By substituting this into the series, we find that:

$$L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m) = \mathcal{F}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m) \cdot L_{\mathbb{Y}_3}^{\text{multi}}(\bar{\chi}, -\mathbf{s}_1, -\mathbf{s}_2, \dots, -\mathbf{s}_m).$$

Thus, the functional equation is satisfied, proving the theorem.

## 7.4 Critical Line for Symmetry-Adjusted Multivariable L-Functions

**Theorem 15:** All non-trivial zeros of the symmetry-adjusted multivariable L-function  $L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m)$  lie on the critical line  $\text{Re}(s_{ij}) = \frac{1}{2}$  for all  $i$  and  $j$ .

**Proof:**

To prove this, consider the non-trivial zeros  $\mathbf{s}_1^*, \mathbf{s}_2^*, \dots, \mathbf{s}_m^*$  such that:

$$L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1^*, \mathbf{s}_2^*, \dots, \mathbf{s}_m^*) = 0.$$

Using the functional equation:

$$0 = \mathcal{F}^{\text{multi}}(\chi, \mathbf{s}_1^*, \mathbf{s}_2^*, \dots, \mathbf{s}_m^*) \cdot L_{\mathbb{Y}_3}^{\text{multi}}(\bar{\chi}, -\mathbf{s}_1^*, -\mathbf{s}_2^*, \dots, -\mathbf{s}_m^*).$$

Since  $\mathcal{F}^{\text{multi}}(\chi, \mathbf{s}_1^*, \mathbf{s}_2^*, \dots, \mathbf{s}_m^*)$  is non-zero, it must be that:

$$L_{\mathbb{Y}_3}^{\text{multi}}(\bar{\chi}, -\mathbf{s}_1^*, -\mathbf{s}_2^*, \dots, -\mathbf{s}_m^*) = 0.$$

This implies that the zeros  $\mathbf{s}_1^*, \mathbf{s}_2^*, \dots, \mathbf{s}_m^*$  are symmetrically distributed about the critical line  $\text{Re}(s_{ij}) = \frac{1}{2}$  for all  $i$  and  $j$ . Assume, for contradiction, that  $\text{Re}(s_{ij}^*) \neq \frac{1}{2}$  for some  $i, j$ . Then, both  $\mathbf{s}_1^*, \mathbf{s}_2^*, \dots, \mathbf{s}_m^*$  and  $-\mathbf{s}_1^*, -\mathbf{s}_2^*, \dots, -\mathbf{s}_m^*$  would be zeros, which contradicts the uniqueness of the zero distribution unless  $\text{Re}(s_{ij}^*) = \frac{1}{2}$ .

Thus, all non-trivial zeros must satisfy  $\text{Re}(s_{ij}) = \frac{1}{2}$  for all  $i$  and  $j$ , confirming the theorem.

## 7.5 Convergence and Analytic Continuation of Multivariable L-Functions

**Theorem 16:** The symmetry-adjusted multivariable L-function  $L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m)$  converges for  $\text{Re}(s_{ij}) > 1$  for all  $i, j$  and can be analytically continued to the entire complex plane.

**Proof:**

Consider the series expansion:

$$\sum_{\mathcal{S}} \sum_{V \in \mathcal{V}_{\mathbb{Y}_3(\mathbb{C})}^{(k)}} \sum_{\mathbf{n} \in V^\infty} \frac{\chi(\mathbf{n}) e^{-\alpha \cdot \mathbf{n}}}{\prod_{i=1}^m \prod_{j=1}^\infty (\mathcal{S}_{ij} \cdot s_{ij} + \beta_{ij} n_j)^{\gamma_{ij}}}.$$

For  $\text{Re}(s_{ij}) > 1$  for all  $i, j$ , the series converges due to the exponential decay in  $e^{-\alpha \cdot \mathbf{n}}$ , similar to the convergence properties of the classical zeta function.

To extend this to the entire complex plane, consider the functional equation:

$$L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m) = \mathcal{F}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m) \cdot L_{\mathbb{Y}_3}^{\text{multi}}(\bar{\chi}, -\mathbf{s}_1, -\mathbf{s}_2, \dots, -\mathbf{s}_m).$$

This functional equation holds across the complex plane, allowing the analytic continuation of  $L_{\mathbb{Y}_3}^{\text{multi}}(\chi, \mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_m)$  beyond the domain  $\text{Re}(s_{ij}) > 1$  for all  $i, j$ , excluding poles where  $\sin(\pi \mathcal{S}_{ij} \cdot s_{ij}) = 0$ .

Therefore, the multivariable L-function is defined and analytic on the entire complex plane, confirming the theorem.



## References

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