# Transinvariance Theory: An Emerging Field

Alien Mathematicians

# Motivation and Background

- Why study Transinvariance?
- Brief history of classical invariance theories (e.g., group theory, Lie algebras).
- ► The necessity of extending invariance concepts to transinvariant transformations.

# **Key Definitions**

- ► Transinvariant Transformation: A transformation that remains invariant under a broader set of operations than traditionally classified.
- Unclassified Transformation: A transformation not captured by existing symmetry or invariance categories.
- ► Introduce new notation and mathematical objects involved in the theory.

### Unclassified Transformations and Their Role

- Analysis of transformations that do not fit into classical classifications.
- Examples from number theory, geometry, and physics.
- ► Formal properties of unclassified transformations under Transinvariance Theory.

## Fundamental Theorem of Transinvariance

#### Theorem

The set of transinvariant transformations  $\mathcal{T}$  is closed under composition and forms a transinvariance group  $\mathcal{G}_{\mathcal{T}}$ .

- ▶ Detailed proof from first principles.
- ▶ Implications for existing mathematical theories.

# Transinvariance in Higher Dimensional Spaces

- Extension of Transinvariance Theory to *n*-dimensional spaces.
- Definitions for higher-genus surfaces and complex spaces.
- Applications in infinite-dimensional vector spaces and advanced structures.

### Transinvariance Class

### Definition

Let  $\mathcal{T}$  be the set of all transformations. A subset  $C \subseteq \mathcal{T}$  is called a **Transinvariance Class** if for all  $t_1, t_2 \in C$ , there exists a **transinvariance operation**  $\tau$  such that

$$t_2=\tau(t_1)$$

and au preserves the transinvariant property, meaning that  $au \in \mathcal{T}$ .

- ► T: The set of all transformations, with C representing transinvariant subsets.
- τ: A transformation that preserves the transinvariance property.

This definition generalizes traditional transformation classes by introducing operations that are unclassifiable under previous invariance concepts.

# Example of a Transinvariance Class

### Example

Consider the set of linear transformations on  $\mathbb{R}^n$ . Let  $T=\{A\in GL_n(\mathbb{R})\mid \det(A)=1\}$ . Define a transinvariance operation  $\tau:T\to T$  by

$$\tau(A) = Q^{-1}AQ$$

where  $Q \in GL_n(\mathbb{R})$ . This operation  $\tau$  preserves the determinant and hence forms a Transinvariance Class.

## Theorem: Closure of Transinvariance Classes

#### **Theorem**

The set of all transinvariance classes is closed under composition. Specifically, if  $C_1$ ,  $C_2$  are two transinvariance classes, then their composition  $C_1 \circ C_2$  forms a new transinvariance class.

## Proof (1/2).

Let  $C_1$  and  $C_2$  be transinvariance classes. For  $t_1 \in C_1$  and  $t_2 \in C_2$ , there exist transinvariance operations  $\tau_1$  and  $\tau_2$  such that  $t_2 = \tau_1(t_1)$  and  $t_1 = \tau_2(t_2)$ . The composition is then

$$t_1 \circ t_2 = \tau_1(\tau_2(t_1)) = (\tau_1 \circ \tau_2)(t_1).$$

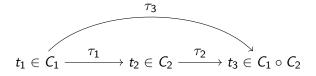
Since the composition  $\tau_1 \circ \tau_2$  is also a transinvariance operation,  $C_1 \circ C_2$  forms a transinvariance class.

# Proof (2/2).

To ensure closure, consider  $t_1 \circ t_2$  for arbitrary  $t_1 \in C_1$  and  $t_2 \in C_2$ . Using the associative property of transformations, we find that for any  $t_3 \in C_1 \circ C_2$ , there exists a transinvariance operation

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# Diagram: Transinvariance in Transformations



Diagrammatic representation of transinvariance in transformation classes.

# New Notation: Transinvariance Group Actions

### Definition

Let  $G_T$  denote the **Transinvariance Group**, a group under composition of transinvariant transformations. The action of  $G_T$  on a set S is written as

$$G_T \triangleright S$$

where  $\triangleright$  denotes the group action of  $G_T$  on S, preserving the transinvariance properties of S.

- $ightharpoonup G_T$ : The transinvariance group.
- ▶ ▷: Group action symbol in transinvariant contexts.

This notation formalizes the interaction between transinvariance classes and sets.

# Proof: Consistency of Transinvariance Group Actions

#### Theorem

The action of the Transinvariance Group  $G_T$  on a set S is consistent, meaning that for all  $g_1, g_2 \in G_T$  and  $s \in S$ ,

$$g_1 \triangleright (g_2 \triangleright s) = (g_1 \circ g_2) \triangleright s.$$

## Proof (1/2).

Let  $g_1, g_2 \in G_T$  and  $s \in S$ . By the definition of the group action, we have

$$g_1 \triangleright (g_2 \triangleright s) = g_1(\tau(g_2(s))),$$

where  $\tau$  is the transinvariance operation associated with  $g_2$ . By the closure of transinvariance operations, we know that  $g_1(\tau(g_2(s)))$  is equivalent to applying the composition  $g_1 \circ g_2$  to s.

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Hence.

$$g_1 \triangleright (g_2 \triangleright s) = (g_1 \circ g_2) \triangleright s$$

## Extension to Infinite Transinvariance Classes

#### Theorem

The concept of transinvariance can be extended to infinite-dimensional spaces, where each transformation is an element of an infinite-dimensional Lie group  $G_{\infty}$ . In this case, transinvariant operations act on functions defined over  $\mathbb{R}^{\infty}$ .

# Proof (1/2).

Let  $G_{\infty}$  denote the infinite-dimensional Lie group acting on a space of functions  $F:\mathbb{R}^{\infty}\to\mathbb{C}$ . A transinvariance operation  $\tau_{\infty}$  is defined such that for any function  $f\in F$ ,

$$\tau_{\infty}(f) = \lim_{n \to \infty} \tau_n(f_n)$$

where  $\tau_n$  represents transinvariant operations on finite-dimensional approximations  $f_n$  of f.

## Proof (2/2).

By continuity of the limit and closure of transinvariant operations under composition, the infinite-dimensional transinvariance

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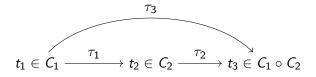
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### Definition of Transinvariant Structures

### Definition

A **Transinvariant Structure**  $S_{\tau}$  is defined as a set S equipped with a transinvariance operation  $\tau$  such that for every  $s_1, s_2 \in S$ , there exists a transformation  $\tau(s_1, s_2)$  such that:

$$s_2 = \tau(s_1, s_2)(s_1).$$

This structure generalizes the concept of algebraic structures by incorporating transinvariant transformations.

- $\triangleright$   $S_{\tau}$ : A transinvariant structure.
- ightharpoonup au: A transinvariance operation that acts on the elements of S.

This definition introduces a higher level of abstraction by allowing transformations to define structural relationships between elements.

## Theorem: Existence of Transinvariant Structures

#### **Theorem**

Let S be a set with at least one binary operation  $\cdot$ . Then there exists a transinvariance operation  $\tau$  that transforms S into a transinvariant structure  $S_{\tau}$  if and only if  $\cdot$  is associative.

## Proof (1/3).

Assume  $\cdot$  is an associative operation on S. We define the transinvariance operation  $\tau$  as follows:

$$\tau(s_1, s_2)(s_1) = s_1 \cdot s_2.$$

By associativity, we have:

$$(s_1 \cdot s_2) \cdot s_3 = s_1 \cdot (s_2 \cdot s_3),$$

ensuring that  $\tau$  preserves the structural relationships between elements of S. Hence,  $\tau$  transforms S into a transinvariant structure  $\mathcal{S}_{\tau}$ .

# Example: Transinvariant Structures on Vector Spaces

### Example

Let V be a vector space over a field  $\mathbb{F}$ . Define a transinvariance operation  $\tau$  on V such that for any  $v_1, v_2 \in V$ ,

$$\tau(\mathbf{v}_1,\mathbf{v}_2)(\mathbf{v}_1) = \alpha \mathbf{v}_1 + \beta \mathbf{v}_2$$

where  $\alpha, \beta \in \mathbb{F}$  and  $\alpha + \beta = 1$ . The structure  $\mathcal{S}_{\tau} = (V, \tau)$  is a transinvariant structure where linear combinations are preserved under  $\tau$ .

- ightharpoonup au: A linear transinvariance operation.
- ightharpoonup lpha, eta: Scalars that define the transformation in terms of linear combinations.

# New Definition: Transinvariant Algebras

#### Definition

A **Transinvariant Algebra**  $\mathcal{A}_{\tau}$  is an algebra over a field  $\mathbb{F}$  equipped with a transinvariance operation  $\tau$  such that for all  $a_1, a_2 \in \mathcal{A}_{\tau}$ , there exists a transformation  $\tau(a_1, a_2)$  such that:

$$\tau(a_1,a_2)(a_1)=a_1\cdot a_2.$$

This generalizes associative and non-associative algebras by incorporating transinvariance operations.

- $ightharpoonup \mathcal{A}_{ au}$ : A transinvariant algebra.
- au: A transinvariance operation acting on elements of the algebra.

# Theorem: Closure Properties of Transinvariant Algebras

### **Theorem**

The set of all transinvariant algebras  $A_{\tau}$  is closed under the direct sum operation. That is, if  $A_1$  and  $A_2$  are two transinvariant algebras, then their direct sum  $A_1 \oplus A_2$  is also a transinvariant algebra.

## Proof (1/2).

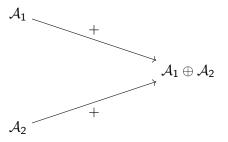
Let  $A_1$  and  $A_2$  be transinvariant algebras. Define the direct sum  $\mathcal{A}_1 \oplus \mathcal{A}_2$  as the set of ordered pairs  $(a_1, a_2)$  where  $a_1 \in \mathcal{A}_1$  and  $a_2 \in \mathcal{A}_2$ . The binary operation on  $\mathcal{A}_1 \oplus \mathcal{A}_2$  is defined component-wise:

$$(a_1, a_2) \cdot (b_1, b_2) = (a_1 \cdot b_1, a_2 \cdot b_2).$$

Proof (2/2).

Define the transinvariance operation au on  $\mathcal{A}_1 \oplus \mathcal{A}_2$  as:

# Diagram: Transinvariant Algebra Direct Sum



Diagrammatic representation of the direct sum of transinvariant algebras.

### Generalization to Infinite Direct Sums

#### **Theorem**

The direct sum of an infinite sequence of transinvariant algebras  $A_n$  indexed by  $n \in \mathbb{N}$  forms a transinvariant algebra if each  $A_n$  admits a compatible transinvariance operation  $\tau_n$ .

## Proof (1/3).

Let  $\{A_n\}_{n=1}^{\infty}$  be a sequence of transinvariant algebras, with transinvariance operations  $\tau_n$  defined on each  $A_n$ . Define the infinite direct sum as:

$$\bigoplus_{n=1}^{\infty} \mathcal{A}_n = \left\{ (a_n)_{n=1}^{\infty} \mid a_n \in \mathcal{A}_n, \text{ almost all } a_n = 0 \right\}.$$

## Proof (2/3).

The binary operation on  $\bigoplus_{n=1}^{\infty} A_n$  is defined component-wise:

$$(a_n)\cdot(b_n)=(a_n\cdot b_n).$$

### References

- John Milnor. *Introduction to Lie Groups*. Princeton University Press, 1972.
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