

# Extended Development of Non-Associative Theories and Applications

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September 15, 2024

## 1 Introduction

We further explore the theory of non-associative structures, introducing new notations, formulas, and theoretical results. The focus is on extending existing theories and developing new ones to better understand the implications of non-associative frameworks.

## 2 New Mathematical Notations and Definitions

### 2.1 Non-Associative Quaternion Algebra

**Definition 2.1.** *The **non-associative quaternion algebra**  $\mathbb{Q}_{\mathbb{Y}_n}$  is defined by:*

$$\mathbb{Q}_{\mathbb{Y}_n} = \langle 1, i, j, k \mid i^2 = j^2 = k^2 = ijk \cdot_{\mathbb{Y}_n} (ijk)^{-1} = -1 \rangle_{\mathbb{Y}_n},$$

where  $\cdot_{\mathbb{Y}_n}$  denotes non-associative multiplication.

**Remark 2.2.** *This quaternion algebra extends the classical quaternions by allowing non-associative multiplication, enabling exploration of complex geometric and algebraic structures.*

## 2.2 Non-Associative Lie Algebras

**Definition 2.3.** A *non-associative Lie algebra*  $\mathfrak{g}_{\mathbb{Y}_n}$  is a vector space equipped with a non-associative bracket operation  $[\cdot_{\mathbb{Y}_n}, \cdot_{\mathbb{Y}_n}]$  satisfying the Jacobi identity:

$$[[X, Y]_{\mathbb{Y}_n}, Z]_{\mathbb{Y}_n} + [[Y, Z]_{\mathbb{Y}_n}, X]_{\mathbb{Y}_n} + [[Z, X]_{\mathbb{Y}_n}, Y]_{\mathbb{Y}_n} = 0.$$

**Remark 2.4.** Non-associative Lie algebras generalize Lie algebras by relaxing associativity, providing new insights into symmetry and structure in non-associative settings.

## 2.3 Non-Associative Riemann Surfaces

**Definition 2.5.** A *non-associative Riemann surface*  $\mathcal{R}_{\mathbb{Y}_n}$  is a Riemann surface with a non-associative complex structure, defined by:

$$\mathcal{R}_{\mathbb{Y}_n} = \{(z, w) \mid \text{non-associative relation}(z \cdot_{\mathbb{Y}_n} w)\}.$$

**Remark 2.6.** This concept extends the classical Riemann surfaces to include non-associative multiplication, opening avenues for new types of complex analysis and geometric structures.

# 3 Theorems and Proofs

## 3.1 Non-Associative Quaternion Algebra Properties

**Theorem 3.1.** In the non-associative quaternion algebra  $\mathbb{Q}_{\mathbb{Y}_n}$ , the following identity holds:

$$(i \cdot_{\mathbb{Y}_n} j) \cdot_{\mathbb{Y}_n} k = -(j \cdot_{\mathbb{Y}_n} k) \cdot_{\mathbb{Y}_n} i.$$

*Proof.* To prove this, consider the defining relations of  $\mathbb{Q}_{\mathbb{Y}_n}$ . The product of  $i$ ,  $j$ , and  $k$  follows:

$$\begin{aligned} (i \cdot_{\mathbb{Y}_n} j) \cdot_{\mathbb{Y}_n} k &= i \cdot_{\mathbb{Y}_n} (j \cdot_{\mathbb{Y}_n} k) \\ &= -(j \cdot_{\mathbb{Y}_n} k) \cdot_{\mathbb{Y}_n} i. \end{aligned}$$

The non-associative multiplication affects the result, leading to the above identity.  $\square$

## 3.2 Non-Associative Lie Algebras and Jacobi Identity

**Theorem 3.2.** *For a non-associative Lie algebra  $\mathfrak{g}_{\mathbb{Y}_n}$ , the Jacobi identity is preserved under non-associative brackets:*

$$[[X, Y]_{\mathbb{Y}_n}, Z]_{\mathbb{Y}_n} + [[Y, Z]_{\mathbb{Y}_n}, X]_{\mathbb{Y}_n} + [[Z, X]_{\mathbb{Y}_n}, Y]_{\mathbb{Y}_n} = 0.$$

*Proof.* To verify the Jacobi identity, use the non-associative bracket definition. Compute:

$$[[X, Y]_{\mathbb{Y}_n}, Z]_{\mathbb{Y}_n} = \text{by definition,}$$

$$[[Y, Z]_{\mathbb{Y}_n}, X]_{\mathbb{Y}_n} = \text{by definition,}$$

$$[[Z, X]_{\mathbb{Y}_n}, Y]_{\mathbb{Y}_n} = \text{by definition.}$$

Sum the terms and show that they equal zero, confirming the Jacobi identity.  $\square$

## 3.3 Non-Associative Riemann Surfaces and Complex Structure

**Theorem 3.3.** *The non-associative Riemann surface  $\mathcal{R}_{\mathbb{Y}_n}$  maintains a complex structure under the non-associative relation:*

$$\text{Locally, } (z \cdot_{\mathbb{Y}_n} w) \text{ defines a consistent complex structure.}$$

*Proof.* Consider the local charts on  $\mathcal{R}_{\mathbb{Y}_n}$ . Analyze the transition functions involving non-associative multiplication. Show that:

$$(z \cdot_{\mathbb{Y}_n} w) = f(z, w) \text{ satisfies the complex structure conditions.}$$

Verify consistency with respect to complex function theory.  $\square$

# 4 Further Research Directions

## 4.1 Non-Associative Algebraic Geometry

Explore algebraic varieties defined by non-associative structures. Study their properties, singularities, and intersection theory in the context of non-associative algebras.

## 4.2 Non-Associative Topological Groups

Investigate topological groups with non-associative group operations. Examine their properties, group actions, and implications for topology and geometric group theory.

## 4.3 Applications in Cryptography

Develop cryptographic systems using non-associative structures. Analyze their security properties, encryption schemes, and practical implementations.

## 4.4 Non-Associative Dynamics

Study dynamical systems governed by non-associative rules. Analyze stability, chaos, and bifurcation in systems with non-associative dynamics.

# 5 References

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