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$$1. \text{ Let } A = \begin{pmatrix} 2 & 3 & -2 \\ -3 & 0 & 0 \\ -4 & -6 & 4 \end{pmatrix} .$$

$$\text{a) } \det(A - \lambda I) = 0$$

$$\det \begin{pmatrix} 2-\lambda & 3 & -2 \\ -3 & -\lambda & 0 \\ -4 & -6 & 4-\lambda \end{pmatrix} = 0$$

$$3 \det \begin{pmatrix} 3-\lambda & -2 \\ -6 & 4-\lambda \end{pmatrix} + (-\lambda) \det \begin{pmatrix} 2-\lambda & -2 \\ -4 & 4-\lambda \end{pmatrix} = 0$$

$$3(3(u-\lambda) - 12) + (-\lambda)((2-\lambda)(4-\lambda) - 8) = 0$$

$$3(\cancel{12} - 3\lambda - \cancel{12}) + -\lambda(8 - 6\lambda^2 + \lambda^2 - 8) = 0$$

$$-9\lambda + -\lambda(\lambda^2 - 6\lambda) = 0$$

$$-\lambda^3 + 6\lambda^2 - 9\lambda = 0$$

$$-\lambda(\lambda^2 - 6\lambda + 9) = 0$$

$$-\lambda(\lambda - 3)^2 = 0$$

$$\boxed{\lambda = 0}, \quad \boxed{\lambda = 3, 3}$$

$$(b) \quad V_0 = \ker(A - 0I) = \ker(A)$$

$$= \ker \begin{pmatrix} 2 & 3 & -2 \\ -3 & 0 & 0 \\ -4 & -6 & 4 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 3 & -2 \\ -3 & 0 & 0 \\ -4 & -6 & 4 \end{pmatrix} \xrightarrow{2r_1 + r_3} \begin{pmatrix} 2 & 3 & -2 \\ -3 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{\frac{3}{2}r_1 + r_2} \begin{pmatrix} 2 & 3 & -2 \\ 0 & \frac{9}{2} & 3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{-\frac{2}{3}r_2 + r_1} \begin{pmatrix} 2 & 0 & 0 \\ 0 & 9 & 3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -2/3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\text{So } \ker(A) = \begin{pmatrix} 0 \\ 2/3 \\ 1 \end{pmatrix} = \text{Span}\left(\begin{pmatrix} 0 \\ 2 \\ 3 \end{pmatrix}\right)$$

For the eigenvalue  $\lambda = 0$  has alg mult = 1  
and geom mult = 1

$$V_{\lambda=3} = \ker(A - 3I) = \ker \begin{pmatrix} -1 & 3 & -2 \\ -3 & -3 & 0 \\ -4 & -6 & 1 \end{pmatrix}$$

$$\xrightarrow{-r_1 - r_2 - r_3} \begin{pmatrix} 1 & -3 & 2 \\ 3 & 3 & 0 \\ 4 & 6 & -1 \end{pmatrix}$$

$$\xrightarrow{\begin{array}{l} -3r_1 + r_2 \\ -4r_1 + r_3 \end{array}} \begin{pmatrix} 1 & -3 & 2 \\ 0 & 12 & -6 \\ 0 & 18 & -9 \end{pmatrix}$$

$$\xrightarrow{-\frac{3}{2}r_2 + r_3}$$

$$\xrightarrow{\frac{1}{6}r_2}$$

$$\left( \begin{array}{ccc} 1 & -3 & 2 \\ 0 & 2 & -1 \\ 0 & 0 & 0 \end{array} \right)$$

$$\xrightarrow{\frac{3}{2}r_2 + r_1}$$

$$\left( \begin{array}{ccc} 1 & 0 & \frac{1}{2} \\ 0 & 2 & -1 \\ 0 & 0 & 0 \end{array} \right)$$

$$\xrightarrow{\frac{1}{2}r_2}$$

$$\left( \begin{array}{ccc} 1 & 0 & \frac{1}{2} \\ 0 & 1 & -\frac{1}{2} \\ 0 & 0 & 0 \end{array} \right)$$

$$\text{so } V_3 = \ker(A - 3I) = \left( \begin{array}{c} -\frac{1}{2} \\ \frac{1}{2} \\ 1 \end{array} \right)$$

$$= \text{span} \left( \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \right)$$

So the alg mult of  $\lambda = 3$  is 2  
but the geom mult is 1.

(c) We need 1 generalized eigenvector for  $\lambda = 3$ . Therefore we solve

$$(A - 3I) w_2 = \left( \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \right).$$

$$\left( \begin{array}{ccc} -1 & 3 & -2 \\ -3 & -3 & 0 \\ -4 & -6 & 1 \end{array} \right) \left( \begin{array}{c} x \\ y \\ z \end{array} \right) = \left( \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \right)$$

$$\left( \begin{array}{ccc|cc} -1 & 3 & -2 & -1 & \\ -3 & -3 & 0 & 1 & \\ -4 & -6 & 1 & 2 & \end{array} \right)$$

same steps!

$$\left( \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \right) \rightarrow \left( \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix} \right) \xrightarrow{\substack{-3r_1 + r_2 \\ -4r_1 + r_3}} \left( \begin{pmatrix} 1 \\ -4 \\ -6 \end{pmatrix} \right)$$

$$\begin{array}{c}
 -3r_2 + r_3 \\
 \xrightarrow{\frac{1}{6}r_2} \left( \begin{array}{c} 1 \\ -2/3 \\ 0 \end{array} \right) \xrightarrow{\frac{3}{2}r_2 + r_1} \left( \begin{array}{c} 0 \\ -2/3 \\ 0 \end{array} \right)
 \end{array}$$

$$\xrightarrow{\frac{1}{2}r_2} \left( \begin{array}{c} 0 \\ -1/3 \\ 0 \end{array} \right) \text{ so}$$

REF

$$\Rightarrow \left( \begin{array}{ccc|c}
 1 & 0 & 1/2 & 0 \\
 0 & 1 & -1/2 & -1/3 \\
 0 & 0 & 0 & 0
 \end{array} \right) \text{ and}$$

$$w_2 = \left( \begin{array}{c} -1 \\ 1 \\ 2 \end{array} \right) z + \left( \begin{array}{c} 0 \\ -1/3 \\ 0 \end{array} \right) \text{ and we can}$$

use  $\left( \begin{array}{c} 0 \\ -1/3 \\ 0 \end{array} \right)$  as the generalized eigenvalue.

Therefore the Jordan decomposition is

$$A = \left( \begin{array}{ccc}
 0 & -1 & 0 \\
 2 & 1 & -1/3 \\
 3 & 2 & 0
 \end{array} \right) \left( \begin{array}{ccc}
 0 & 0 & 0 \\
 0 & 3 & 1 \\
 0 & 0 & 3
 \end{array} \right) \left( \begin{array}{ccc}
 0 & -1 & 0 \\
 2 & 1 & -1/3 \\
 3 & 2 & 0
 \end{array} \right)^{-1}$$


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2. In matrix form this system is

$$\begin{pmatrix} 2 & 3 \\ -1 & -1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}$$

Therefore the LSS is

$$x^* = (A^T A)^{-1} A^T \vec{b}$$

$$A^T A = \begin{pmatrix} 2 & -1 & 2 \\ 3 & -1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 3 \\ -1 & -1 \\ 2 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 9 & 9 \\ 9 & 11 \end{pmatrix}$$

$$(A^T A)^{-1} = \frac{1}{18} \begin{pmatrix} 11 & -9 \\ -9 & 9 \end{pmatrix}$$

$$A^T \vec{b} = \begin{pmatrix} 2 & -1 & 2 \\ 3 & -1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} -2 \\ -2 \end{pmatrix}$$

So the LSS explicitly is

$$x^* = \frac{1}{18} \begin{pmatrix} 11 & -9 \\ -9 & 9 \end{pmatrix} \begin{pmatrix} -2 \\ -2 \end{pmatrix} = \boxed{\frac{1}{18} \begin{pmatrix} -4 \\ 0 \end{pmatrix}}$$

3.

(a) The vertex-edge formula says that

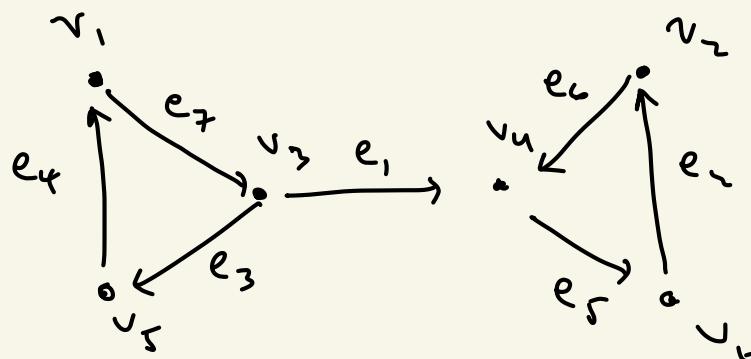
$$\#v - \#e = 1 - \#\text{ind circ}$$

So  $6 - 7 = 1 - \#\text{ind circ}$

$$\Rightarrow \boxed{\#\text{ind circ} = 2}$$

This is expected since the graph has 2 "holes" in it. One given by  $e_3 + e_4 + e_7$  and the other  $e_2 + e_5 + e_6$ .

(b)  $\partial(e) = \text{end} - \text{start}$ , so we need to label the vertices first.



And a circuit is an element of the kernel of  $\partial$

$$\begin{aligned}
 \partial(e_1 + e_2 - 2e_3 - 2e_4 + e_5 + e_6 - 2e_7) \\
 &= v_4 - v_3 + \cancel{v_2} - \cancel{v_6} - 2\cancel{v_5} + 2\cancel{v_3} - 2v_1 + 2\cancel{v_5} \\
 &\quad + \cancel{v_6} - \cancel{v_4} + \cancel{v_4} - \cancel{v_2} - 2\cancel{v_3} + 2\cancel{v_1} \\
 &= v_4 - v_3 \neq 0. \quad \text{So this is } \underline{\text{not}} \\
 &\quad \text{a circuit.}
 \end{aligned}$$

4.

(a) Writing  $\langle \cdot, \cdot \rangle$  in matrix form we have

$$\begin{aligned} & \langle (x_1, y_1), (x_2, y_2) \rangle \\ &= (x_1, y_1) \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} \end{aligned}$$

Bilinearity

$$\cdot \langle \vec{u} + \vec{v}, \vec{w} \rangle = (\vec{u} + \vec{v})^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w}$$

$$= (\vec{u}^T + \vec{v}^T) \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w}$$

$$= \vec{u}^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w} + \vec{v}^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w}$$

$$= \langle \vec{u}, \vec{w} \rangle + \langle \vec{v}, \vec{w} \rangle$$

$$\cdot \langle c\vec{v}, \vec{w} \rangle = (c\vec{v})^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w}$$

$$= c\vec{v}^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \vec{w} = c \langle \vec{v}, \vec{w} \rangle$$

The other side is similar.

Symmetry

$$\langle \vec{x}_1, \vec{x}_2 \rangle = 2x_1x_2 - x_1y_2 - x_2y_1 + y_1y_2$$

$$= 2x_1x_2 - x_2y_1 - x_1y_2 + y_1y_2$$

$$= \langle \vec{x}_2, \vec{x}_1 \rangle.$$



Positivity.

Recall that  $v^T K v > 0$  for all  $v \neq 0$   
iff  $K$  is positive definite.

But  $K$  is positive definite since

$$\det \begin{pmatrix} 2-\lambda & -1 \\ -1 & 1-\lambda \end{pmatrix} = 0$$

$$(2-\lambda)(1-\lambda) - 1 = 0$$

$$\lambda^2 - 3\lambda + 2 - 1 = 0$$

$$\lambda^2 - 3\lambda + 1 = 0$$

$$\lambda = \frac{3 \pm \sqrt{9-4}}{2} = \frac{3 \pm \sqrt{5}}{2} > 0$$

It's eigenvalues are both positive!

$$\text{So } \langle v, v \rangle = v^T \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} v > 0$$

and  $\langle \cdot, \cdot \rangle$  is positive. ✓

$$(b) |2v_1 v_2 - v_1 v_2 - v_2 w_1 + w_1 w_2| \\ \leq \sqrt{2v_1^2 - 2v_1 v_2 + v_2^2} \sqrt{2w_1^2 - 2w_1 w_2 + w_2^2}$$

5.

(a) The vectors  $\{v_1, v_2, v_3, v_4\}$  do not form a basis of any  $\mathbb{R}^n$ . These vectors live in  $\mathbb{R}^4$  so the only possibility is  $n=4$ . But they don't form a basis of  $\mathbb{R}^4$  either.

They are not independent since  $v_3 \in \text{span}(v_1, v_2)$  according to the RREF. In particular

$$v_3 = -2v_1 + 4v_2 \text{ is a dependency.}$$

they also don't span since  $\begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \notin \text{span of columns}$  of RREF.

Since they neither span nor are independent, they can't be a basis.

$$(b) \ker(M) = \ker \begin{pmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \begin{aligned} x &= 2z \\ y &= -4z \\ w &= 0 \end{aligned}$$

$$\ker(M) = \begin{pmatrix} 2z \\ -4z \\ z \\ 0 \end{pmatrix} = \text{span} \begin{pmatrix} 2 \\ -4 \\ 1 \\ 0 \end{pmatrix}$$

$$\text{thus } \dim(\ker(M)) = 1.$$

(c). By rank-nullity

$$\dim(\ker(M)) + \text{rank}(M) = 4$$

$$1 + \text{rank}(M) = 4$$

$$\Rightarrow \text{rank}(M) = 3.$$

Alternatively  $\text{rk}(M) = \# \text{ of leading } 1's$   
 $= 3.$

(d)  $M$  is not invertible since

- $\text{rk}(M) \neq 4$
- columns don't form a basis
- rows don't form a basis
- RREF  $\neq$  Identity

Any of these are good enough answers, by the  
Fundamental Theorem.

b. First  $\exp((x_1, y_1) + (x_2, y_2))$

$$= \exp(x_1 + x_2, y_1 + y_2)$$

$$= (e^{x_1+x_2}, e^{y_1+y_2})$$

$$= (e^{x_1}e^{x_2}, e^{y_1}e^{y_2})$$

$$= (e^{x_1}, e^{y_1}) + Q (e^{x_2}, e^{y_2})$$

$$= \exp(x_1, y_1) + Q \exp(x_2, y_2)$$

Constants also can come out



$$\exp((x, y)) = \exp(x, y)$$

$$= (e^x, e^y)$$

$$= ((e^x)^c, (e^y)^c) = c(e^x, e^y)$$

$$= c(\exp(x, y)). \quad \checkmark$$

$$7. (a) \omega_1 = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \quad \omega_2 = \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \quad \omega_3 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$v_1 = \omega_1 = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$

$$v_2 = \omega_2 - \frac{\omega_2 \cdot v_1}{\|v_1\|^2} v_1$$

$$= \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} - \frac{2}{2} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$

$$v_2 = \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} - \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$$

$$v_3 = \omega_3 - \frac{\omega_3 \cdot v_1}{\|v_1\|^2} v_1 - \frac{\omega_3 \cdot v_2}{\|v_2\|^2} v_2$$

$$= \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} - \frac{-1}{2} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} - \frac{2}{4} \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} -1/2 \\ 1/2 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -1/2 \\ 1/2 \\ 0 \end{pmatrix}$$

$$v_3 = \begin{pmatrix} 1/2 \\ 1/2 \\ 0 \end{pmatrix}$$

Normalizing we get

$$u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \quad u_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad u_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}.$$

(b)

$\text{Proj}_W v = (v \cdot u_1)u_1 + (v \cdot u_2)u_2$  where  
 $u_1, u_2$  are an orthonormal basis of  $W$ .

From part (a)  $W$  has orthonormal basis

$$u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \text{ and } u_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$$

$$\begin{aligned} \text{Proj}_W (2, 1, 2) &= \left( \left( \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \right) \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \right. \\ &\quad \left. + \left( \left( \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right) \right) \\ &= \frac{1}{2}(-1) \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + 2 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix} \\ &= \begin{pmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ 2 \end{pmatrix}. \end{aligned}$$

8.

$$(a) \quad A = \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix}$$

$$A^2 = \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} = \begin{pmatrix} -3 & -3 & 6 \\ 3 & 3 & -6 \\ 0 & 0 & 0 \end{pmatrix}$$

$$A^3 = \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} -3 & -3 & 6 \\ 3 & 3 & -6 \\ 0 & 0 & 0 \end{pmatrix} = \boxed{\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}}$$

(b) Since  $A^3 = 0$ , then

$$e^A = I + A + \frac{1}{2}A^2 + 0 + 0 + \dots$$

$$= I + A + \frac{1}{2}A^2$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix}$$

$$+ \frac{1}{2} \begin{pmatrix} -3 & -3 & 6 \\ 3 & 3 & -6 \\ 0 & 0 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & -3 \\ 2 & 3 & -1 \\ 1 & 1 & -1 \end{pmatrix} + \begin{pmatrix} -1/2 & -3/2 & 3 \\ 3/2 & 3/2 & -3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$= \boxed{\begin{pmatrix} -1/2 & -3/2 & 0 \\ 7/2 & 9/2 & -4 \\ 1 & 1 & -1 \end{pmatrix}}$$

- Alternatively, the longer way is to compute the Jordan form. I had hoped that part (a) was a hint to do it the first way.

$$\det(A - \lambda I) = \det \begin{pmatrix} -\lambda & 0 & -3 \\ 2 & 2-\lambda & -1 \\ 1 & 1 & -2-\lambda \end{pmatrix} = 0$$

$$-\lambda((2-\lambda)(-2-\lambda) + 1) + (-3)(2 - (2-\lambda)) = 0$$

$$-\lambda(-4 + \lambda^2 + 1) + (-3\lambda) = 0$$

$$-\lambda^3 + 3\lambda - 3\lambda = 0$$

$$-\lambda^3 = 0 \Rightarrow \lambda = 0, 0, 0$$

$$V_0 = \ker(A) = \ker \begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix}$$

$$\left( \begin{array}{ccc} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{array} \right) \xrightarrow{\text{Swap } R_1, R_3} \left( \begin{array}{ccc} 1 & 1 & -2 \\ 2 & 2 & -1 \\ 0 & 0 & -3 \end{array} \right)$$

$$\xrightarrow{-2R_1 + R_2} \left( \begin{array}{ccc} 1 & 1 & -2 \\ 0 & 0 & 3 \\ 0 & 0 & -3 \end{array} \right)$$

$$\xrightarrow{+R_2 + R_3} \left( \begin{array}{ccc} 1 & 1 & -2 \\ 0 & 0 & 3 \\ 0 & 0 & 0 \end{array} \right)$$

$$\xrightarrow{\frac{1}{3}R_2} \left( \begin{array}{ccc} 1 & 1 & 0 \\ 0 & 0 & 3 \\ 0 & 0 & 0 \end{array} \right)$$

$$\xrightarrow{\frac{1}{3}R_2} \left( \begin{array}{ccc} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{array} \right)$$

$$\therefore V_0 = \ker(A) = \left( \begin{array}{c} -y \\ y \\ 0 \end{array} \right) = \text{Span} \left( \begin{array}{c} -1 \\ 1 \\ 0 \end{array} \right)$$

So Jordan chain is  $w_1 = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$ ,  $w_2, w_3$ ,

$$Aw_2 = w_1 \quad \text{and} \quad Aw_3 = w_2.$$

$$\begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \xrightarrow{\text{swap}} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \xrightarrow{-2r_1+r_2} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} \xrightarrow{r_1+r_2} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\xrightarrow{2/3r_2+r_1} \begin{pmatrix} 2/3 \\ 1 \\ 0 \end{pmatrix} \xrightarrow{1/3r_2} \begin{pmatrix} 2/3 \\ 1/3 \\ 0 \end{pmatrix}$$

$$\left( \begin{array}{ccc|c} 1 & 1 & 0 & 2/3 \\ 0 & 0 & 1 & 1/3 \\ 0 & 0 & 0 & 0 \end{array} \right) \rightarrow \begin{aligned} x &= -y + 2/3 \\ z &= 1/3 \end{aligned}$$

$$\text{so } w_2 = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -y + 2/3 \\ y \\ 1/3 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}y + \begin{pmatrix} 2/3 \\ 0 \\ 1/3 \end{pmatrix}$$

$$\Rightarrow w_2 = \begin{pmatrix} 2/3 \\ 0 \\ 1/3 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} w_3 = \begin{pmatrix} 2/3 \\ 0 \\ 1/3 \end{pmatrix}$$

$$\begin{pmatrix} 2/3 \\ 0 \\ 1/3 \end{pmatrix} \rightarrow \begin{pmatrix} 1/3 \\ 0 \\ 2/3 \end{pmatrix} \rightarrow \begin{pmatrix} 1/3 \\ -2/3 \\ 2/3 \end{pmatrix} \rightarrow \begin{pmatrix} 1/3 \\ -2/3 \\ 0 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} -1/9 \\ -2/9 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} -1/9 \\ -2/9 \\ 0 \end{pmatrix}$$

$$\left( \begin{array}{ccc|c} 1 & 1 & 0 & -1/9 \\ 0 & 0 & 1 & -2/9 \\ 0 & 0 & 0 & 0 \end{array} \right) \begin{aligned} x &= -y - 1/9 \\ z &= -2/9 \end{aligned}$$

$$w_3 = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -y - 1/9 \\ y \\ -2/9 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}y + \begin{pmatrix} -1/9 \\ 0 \\ -2/9 \end{pmatrix}$$

$$\text{So } \omega_3 = \begin{pmatrix} -1/9 \\ 0 \\ -2/9 \end{pmatrix}.$$

Thus

$$\begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix} = \begin{pmatrix} -1 & 2/3 & -1/9 \\ 1 & 0 & 0 \\ 0 & 1/3 & -2/9 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 2/3 & -1/9 \\ 1 & 0 & 0 \\ 0 & 1/3 & -2/9 \end{pmatrix}$$

$$\text{So } e^{\begin{pmatrix} 0 & 0 & -3 \\ 2 & 2 & -1 \\ 1 & 1 & -2 \end{pmatrix}} = \begin{pmatrix} -1 & 2/3 & -1/9 \\ 1 & 0 & 0 \\ 0 & 1/3 & -2/9 \end{pmatrix} e^{\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}} \begin{pmatrix} -1 & 2/3 & -1/9 \\ 1 & 0 & 0 \\ 0 & 1/3 & -2/9 \end{pmatrix}$$

$$e^{\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}} = I + N + \frac{1}{2}N^2$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow e^A = \begin{pmatrix} -1 & 2/3 & -1/9 \\ 1 & 0 & 0 \\ 0 & 1/3 & -2/9 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1/2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 2 & 2 & -1 \\ 3 & 3 & 6 \end{pmatrix}$$

$$= \begin{pmatrix} -1/2 & -3/2 & 0 \\ 7/2 & 9/2 & -4 \\ 1 & 1 & -1 \end{pmatrix}$$

anyway don't  
do it this  
way if you  
can avoid it!

9.

$$(a). \text{ Let } \Lambda = \begin{pmatrix} \lambda_1 & \lambda_2 & \lambda_3 \end{pmatrix}.$$

Then

$$\begin{aligned} P_A(\Lambda) &= c_3 \begin{pmatrix} \lambda_1 & \lambda_2 & \lambda_3 \end{pmatrix}^3 + c_2 \begin{pmatrix} \lambda_1 & \lambda_2 & \lambda_3 \end{pmatrix}^2 \\ &\quad + c_1 \begin{pmatrix} \lambda_1 & \lambda_2 & \lambda_3 \end{pmatrix} + c_0 \begin{pmatrix} 1 & 1 & 1 \end{pmatrix} \\ &= c_3 \begin{pmatrix} \lambda_1^3 & \lambda_2^3 & \lambda_3^3 \end{pmatrix} + c_2 \begin{pmatrix} \lambda_1^2 & \lambda_2^2 & \lambda_3^2 \end{pmatrix} \\ &\quad + c_1 \begin{pmatrix} \lambda_1 & \lambda_2 & \lambda_3 \end{pmatrix} + c_0 \begin{pmatrix} 1 & 1 & 1 \end{pmatrix} \\ &= \begin{pmatrix} c_3 \lambda_1^3 + c_2 \lambda_1^2 + c_1 \lambda_1 + c_0 \\ c_3 \lambda_2^3 + c_2 \lambda_2^2 + c_1 \lambda_2 + c_0 \\ \vdots \\ c_3 \lambda_3^3 + c_2 \lambda_3^2 + c_1 \lambda_3 + c_0 \end{pmatrix} \end{aligned}$$

Since  $\lambda_i$  are roots of the char poly then

$$c_3 \lambda_i^3 + c_2 \lambda_i^2 + c_1 \lambda_i + c_0 = 0$$

Each of the above diagonal entries is 0, so

$$\Rightarrow P_A(\Lambda) = 0. \quad \square$$

(b). By the decomposition

$$A = S \Lambda S^{-1} \text{ to}$$

$$\begin{aligned} P_A(A) &= c_3 (S \Lambda S^{-1})^3 + c_2 (S \Lambda S^{-1})^2 + c_1 (S \Lambda S^{-1}) \\ &\quad + c_0 I \\ &= c_3 S \Lambda^3 S^{-1} + c_2 S \Lambda^2 S^{-1} + c_1 S \Lambda S^{-1} \\ &\quad + c_0 S I S^{-1} \end{aligned}$$

$$= S \left( c_3 \Delta^3 + c_2 \Delta^2 + c_1 \Delta + c_0 I \right) S^{-1}$$

$$= S P_A(\Delta) S^{-1} = S O S^{-1} = 0$$

All  $c_i = 0$   $P_A(A) = 0$ .

□