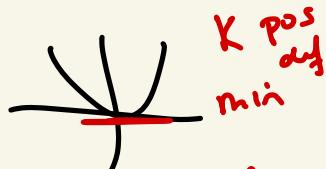



Yesterday ...

minimize

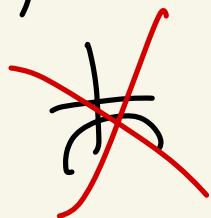
$$p(x) = x^T K x - 2 x^T f + c$$

K pos def.



$$x^* = K^{-1} f$$

$$p(x^*) = \underline{c} - f^T x^*$$



Minimize

$$\|w - b\|^2, \text{ where } w \in W \text{ a subspace } \subseteq \mathbb{R}^n.$$

$$\text{and } b \in \mathbb{R}^n$$

Two ways to figure out

$$\min \left\{ \|w - b\|^2 \mid w \in W \right\}.$$

$$\cdot w = x_1 w_1 + \dots + x_k w_k \quad w_1, \dots, w_k \text{ basis}$$

$\therefore w$.

Solve for x_1, \dots, x_k

let $W \subseteq \mathbb{R}^n$ be a subspace,
 $b \in \mathbb{R}^n$. minimize $\|w-b\|^2$.

Suppose w_1, \dots, w_k is a basis of W .

$A = (w_1, \dots, w_k)$. Then we
know that $\text{img}(A) = \text{span}(w_1, \dots, w_k)$
= W .

On the other hand

$$\text{img}(A) = \{Ax \mid x \in \mathbb{R}^k\}.$$

$$\min \left\{ \|w-b\|^2 \mid w \in W \right\}$$

$$= \min \left\{ \|Ax - b\|^2 \mid x \in \mathbb{R}^k \right\}$$

$$\|Ax - b\|^2 = (Ax - b) \cdot (Ax - b)$$

$$= (Ax - b)^T (Ax - b)$$

$$\begin{aligned}
 & (Ax - b)^T (Ax - b) \\
 &= ((Ax)^T - b^T)(Ax - b) \\
 &= (x^T A^T - b^T)(Ax - b) \\
 &= x^T A^T Ax - b^T Ax - x^T A^T b \\
 &\quad + b^T b
 \end{aligned}$$

$$\begin{aligned}
 &= \underbrace{x^T A^T Ax}_{\downarrow} - \underbrace{b^T Ax}_{+ \|b\|^2} - \underbrace{x^T A^T b}_{?} \\
 & \qquad \qquad \qquad \text{These two terms are equal!} \\
 & " = " x^T K x - 2x^T f + \underbrace{\|b\|^2}_{\text{constant}}
 \end{aligned}$$

$$K = A^T A \quad \begin{matrix} \text{gram} \\ \text{matrix for } w_1, \dots, w_k \end{matrix}$$

Side calculation

Claim: $b^T A x = x^T A^T b$.

PF $b^T A x \in \mathbb{R}^1$

so $(b^T A x) = (b^T A x)^T$ trivially

$$= x^T A^T b^T = x^T A^T x$$

$$\|A x - b\|^2$$

$$= x^T A^T A x - \underbrace{b^T A x - x^T A^T b}_{\text{equal}} + \|b\|^2$$

$$= \underbrace{x^T A^T A x}_{\text{K}} - 2 \underbrace{x^T A^T b}_{f} + \|b\|^2$$

Therefore $x^* = K^{-1} f$ (yesterday)

$$x^* = (A^T A)^{-1} A^T b \quad \curvearrowright$$

$$x^* = (A^T A)^{-1} A^T b \quad \text{minimize} \\ \|Ax - b\|^2.$$

$w = Ax$ $w \in W$. What is

the actual vector $w^* \in W$

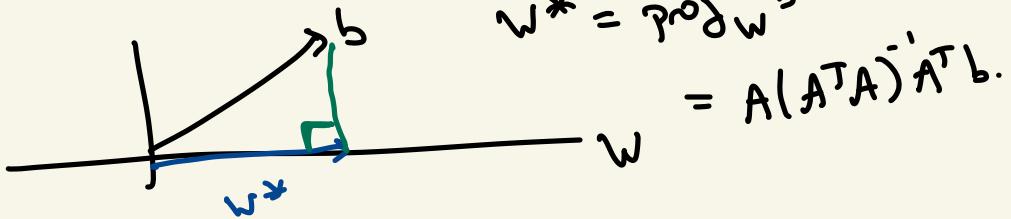
s.t. w^* is closest to b ?

$$w^* = Ax^* - \underbrace{A(A^T A)^{-1} A^T b}_{\text{from HW}}.$$

$$\text{proj}_W b = A(A^T A)^{-1} A^T b \quad \text{from HW}$$

The projection should be the closest vector

w^* to b s.t. $w^* \in W$.



$$\underline{\text{Ex}} \quad W = \text{Span} \left(\begin{pmatrix} 1 \\ 2 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 2 \end{pmatrix} \right), \quad b = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Closest distance from b to W ?

which vector $w^* \in W$ is closest
to b ?

$$w^* = A(A^T A)^{-1} A^T b$$

where $A = \begin{pmatrix} 1 & 0 \\ 2 & 0 \\ -1 & -1 \\ 0 & 2 \end{pmatrix}$

$$A^T A = \begin{pmatrix} 5 & 1 \\ 1 & 5 \end{pmatrix} \quad (A^T A)^{-1} = \frac{1}{25} \begin{pmatrix} 5 & -1 \\ -1 & 5 \end{pmatrix}$$

$$w^* = \begin{pmatrix} 1 & 0 \\ 2 & 0 \\ -1 & -1 \\ 0 & 2 \end{pmatrix} \frac{1}{25} \begin{pmatrix} 5 & 1 \\ 1 & 5 \end{pmatrix} \begin{pmatrix} 1 & 2 & -1 & 0 \\ 0 & 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$= \frac{1}{25} \begin{pmatrix} 5 \\ 10 \\ -4 \\ 2 \end{pmatrix} \quad \text{is closest to } \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

from W .

On the other hand

$$w^* = \text{proj}_W b$$

① G-S basis of W

② $w^* = \langle u_1, b \rangle u_1 + \langle u_2, b \rangle u_2$

These methods are the same.

$$d = \|w^* - b\|$$

$$= \sqrt{\|b\|^2 - f^T x^*} = \frac{1}{29} (2\sqrt{274})$$

is the minimal distance from

$$b = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \text{ to } W = \text{Span} \left(\begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 2 \end{pmatrix} \right).$$

$(A^T A)^{-1} A^T$ matrix helps computation
quite nicely.

5.4 least squares

Def let $Ax = b$ be a system of equations. b may or not be in $\text{img}(A)$.

Then the vector x^* which minimizes the distance $\|Ax - b\|^2$ is called the least squares solution to $Ax = b$.

Letting $W = \text{img}(A)$. Find x^*

by

$$x^* = (A^T A)^{-1} A^T x$$

any matrix A may not have independent columns

$(A^T A)^{-1}$ might not exist.

let A be an $m \times n$ matrix.

When is $A^T A$ invertible?

If the columns of A are independent

$K = A^T A =$ Gram matrix
independent vectors

\Rightarrow always positive definite

$\Rightarrow K = (A^T A)^{-1}$ invertible.

When are columns of A independent?
 $m \times n$

columns are independent

$\Leftrightarrow \text{rank}(A) = n$. (every column has a pivot)

If $n < m$.

$\Leftrightarrow \underline{\text{ker}(A)} = \{0\}$.

A $m \times n$ (which we want to do
least squares to)

$$x^* = (A^T A)^{-1} A^T b, (A^T A)^{-1} \text{ needs to exist.}$$

Claim : If A is $m \times n$, $n < m$,
and $\ker(A) = 0$, then

$$(A^T A)^{-1} \text{ exists.}$$

$$A : \mathbb{R}^n \longrightarrow \mathbb{R}^m$$

$$\dim \mathbb{R}^n < \dim \mathbb{R}^m$$

Linear transformation from
smaller vector space to a bigger
one.

$$A : \mathbb{R}^n \longrightarrow \mathbb{R}^m$$

$$\dim \mathbb{R}^n < \dim \mathbb{R}^m$$

Linear transformation from
smaller vector space to a bigger
one.

If $\ker(A) = 0$. Claim :

$$\dim(\text{img}(A)) = n$$

||

$$\text{rank}(A)$$

Since $\dim(\text{img}(A)) = n$

$$\text{img}(A) \subseteq \mathbb{R}^m \quad m > n.$$

We can think of $\text{img}(A)$ just as
a copy of \mathbb{R}^n but tilted
and stuck inside \mathbb{R}^m
somehow.

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} : \mathbb{R}^2 \longrightarrow \mathbb{R}^3$$

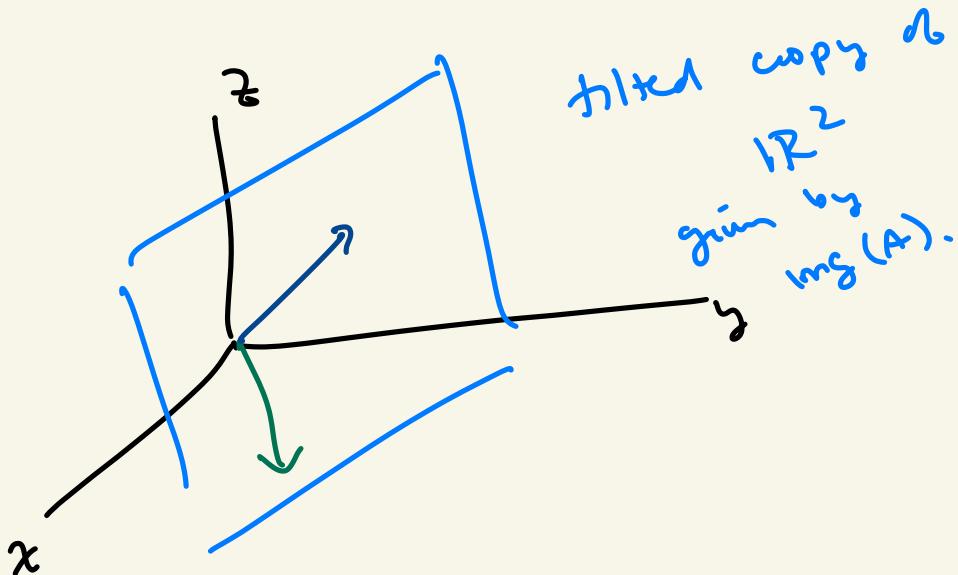
2 1nd column

\implies rank 2

$\implies \ker(A) = 0.$

$\implies \dim(\text{img}(A)) = 2$

$\text{img}(A)$ is a 2D subspace
of \mathbb{R}^3 .

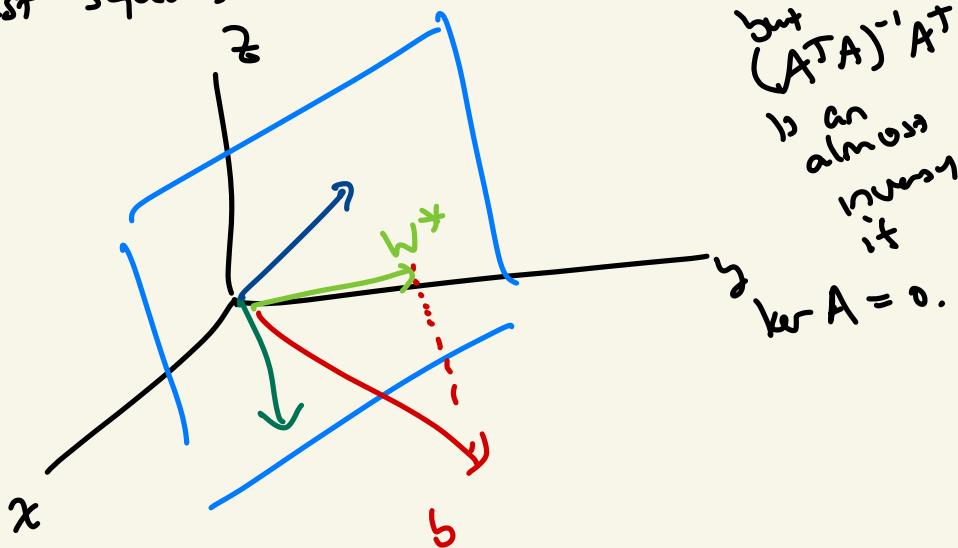


$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} : \mathbb{R}^2 \xrightarrow{\quad F \quad} \mathbb{R}^3$$

$(A^T A)^{-1} A^T$

Square
matrices
don't have
inverses

least squares



but
 $(A^T A)^{-1} A^T$
is an
almost
inverse
it
 $\ker A = 0.$

$x^* = (A^T A)^{-1} A^T b$ is coordinates
of w^* in terms of the
columns of A

x^* is coefficients of w_1, \dots, w_k
which make w^* .

$$(A^T A)^{-1} A^T : \mathbb{R}^3 \xrightarrow{\quad b \quad} \mathbb{R}^2$$

x^*

Another way to think about x^*

is it's closest variable to being
a solution to $Ax = b$.

If $Ax = b$ has an actual solution
 z , then $z = x^*$.

Since $d = \min_{\text{min}} \|Ax^* - b\| = 0$
 $\text{so } x^* = z.$

Note: If $\ker(A) \neq 0$, then there
is not a unique least squares
solution ! $x^* = (A^T A)^{-1} A^T b$
makes no sense

If $z \in \ker(A)$. x^* is a least
squares solution

then $w = x^* + z$ is also
a least squares solution.

x^* minimizes , $w = x^* + z$,
 $\|Ax - b\|^2$.
 $\underline{\geq \text{ker}(A)}$

$$\underline{\|Aw - b\|^2}$$

$$= \|A(x^* + z) - b\|^2$$

$$= \|Ax^* + A\cancel{z} - b\|^2 = \underline{\|Ax^* - b\|^2}$$

which is minimal.

so $\|Aw - b\|^2$ is also minimal.

$bw = x^* + z$ is also a least squares solution.

Need $\text{ker}(A) = 0$ to get a unique solution

$$x^* = (A^T A)^{-1} A^T b \text{ works.}$$

Thm let A be $m \times n$, s.t either
 $\text{rank}(A) = n \Leftrightarrow \ker(A) = 0$.

Then $Ax = b$ has a unique least
squares solution $x^* = \underline{(A^T A)^{-1} A^T b}$.

Ex:

$$\begin{pmatrix} 1 & 2 & 0 \\ 3 & -1 & 1 \\ 1 & 2 & 1 \\ 1 & -1 & -2 \\ 2 & 1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ -1 \\ 2 \\ 2 \end{pmatrix}$$

\downarrow
 A 5×3 matrix.

Tell by row reduction

① . $\text{rank}(A) = 3$
: all columns are independent
: $\ker(A) = 0$

② $Ax = b$ has no solution!

$$\left(\begin{array}{cccc} 1 & 2 & 0 \\ 3 & -1 & 1 \\ 1 & 2 & 1 \\ 1 & -1 & -2 \\ 2 & 1 & -1 \end{array} \right) \left(\begin{array}{c} x \\ y \\ z \\ \\ \\ x \end{array} \right) = \left(\begin{array}{c} 1 \\ 0 \\ 1 \\ 2 \\ 2 \\ b \end{array} \right)$$

||

A

Since $\text{ker}(A) = 0$ Then there is

a unique least squares
solution!

$$x^* = \underbrace{(A^T A)^{-1}}_{K} \underbrace{A^T b}_{f}$$

$$K = A^T A = \left(\begin{array}{ccc} 16 & -2 & -2 \\ -2 & " & 2 \\ -2 & 2 & 7 \end{array} \right) *$$

$$f = A^T b = \left(\begin{array}{c} 8 \\ 0 \\ -7 \end{array} \right)$$

↓

Closest
(x ,
 y ,
 z)
to being
a solution!

$$x^* = K^{-1} f = (A^T A)^{-1} A^T b$$

$$= \frac{1}{556} \left(\begin{array}{c} 355 \\ -58 \\ -674 \end{array} \right) = \left(\begin{array}{c} 0.4119 \\ -2482 \\ -9532 \end{array} \right)$$

Calculator ...

Suppose we have a bunch of data

$$(t_1, y_1), \dots, (t_m, y_m)$$

Suppose $y = \alpha + \beta t$ is supposed
to relate t, y .

which α, β fit best?

actual data \downarrow *supposed y-value* \downarrow

$$\epsilon_1 = \varepsilon_1 = y_1 - (\alpha + \beta t_1)$$
$$\epsilon_2 = y_2 - (\alpha + \beta t_2)$$

⋮

$$\epsilon_m = y_m - (\alpha + \beta t_m)$$

$$\begin{pmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_m \end{pmatrix} = \begin{pmatrix} y_1 \\ \vdots \\ y_m \end{pmatrix} - \underbrace{\begin{pmatrix} \alpha + \beta t_1 \\ \vdots \\ \alpha + \beta t_m \end{pmatrix}}_{\text{matrix product}}$$

$$\begin{pmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_m \end{pmatrix} = \begin{pmatrix} y_1 \\ \vdots \\ y_m \end{pmatrix} - \begin{pmatrix} \alpha + \beta t_1 \\ \vdots \\ \alpha + \beta t_m \end{pmatrix}$$

$$\begin{pmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_m \end{pmatrix} = \begin{pmatrix} y_1 \\ \vdots \\ y_m \end{pmatrix} - \begin{pmatrix} 1 & t_1 \\ 1 & t_2 \\ \vdots & \vdots \\ 1 & t_m \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

↑

$$\varepsilon = y - \begin{pmatrix} 1 & t_1 \\ 1 & t_2 \\ \vdots & \vdots \\ 1 & t_m \end{pmatrix} x$$

A

$$\varepsilon = y - Ax.$$

α, β fix best when
 $\sum \varepsilon_i^2$ is minimal.
 (least squares)

$$\varepsilon = y - Ax.$$

α, β fix best when

$\sum \varepsilon_i^2$ is minimal.
(least squares)

$$\min. \underbrace{\sum \varepsilon_i^2}_{\varepsilon^2} = \|\varepsilon\|^2 = \underbrace{\|y - Ax\|^2}_{\varepsilon^2}$$

in terms
of data

we know
how to
solve this

$$x = \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \underbrace{(A^T A)^{-1}}_{\text{matrix}} \underbrace{A^T y}_{\text{vector}}$$

$$A^T A = \begin{pmatrix} 1 & \cdots & 1 \\ t_1 & t_2 & \cdots & t_m \end{pmatrix} \begin{pmatrix} 1 \\ t_1 \\ t_2 \\ \vdots \\ t_m \end{pmatrix}$$

$$= \begin{pmatrix} m & \sum t_i \\ \sum t_i & \sum t_i^2 \end{pmatrix}$$

$$\underbrace{(A^T A)^{-1}}_{\text{matrix}} = \frac{1}{m \sum t_i^2 - (\sum t_i)^2} \begin{pmatrix} \sum t_i^2 & -\sum t_i \\ -\sum t_i & m \end{pmatrix}$$

$$\underline{A^T y} = \begin{pmatrix} 1 & \dots & 1 \\ t_1, t_2, \dots, t_m \end{pmatrix} \begin{pmatrix} y_1 \\ \vdots \\ y_m \end{pmatrix}$$

$$= \begin{pmatrix} \sum y_i \\ \sum t_i y_i \end{pmatrix}$$

$$y = \alpha + \beta t$$

$$\begin{pmatrix} \alpha \\ \beta \end{pmatrix} = (A^T A)^{-1} A^T y$$

$$= \frac{1}{m(\sum t_i^2) - (\sum t_i)^2} \begin{pmatrix} \sum t_i^2 - \sum t_i \\ -\sum t_i \quad m \end{pmatrix} \begin{pmatrix} \sum y_i \\ \sum t_i y_i \end{pmatrix}$$

$$= \frac{1}{m(\sum t_i^2) - (\sum t_i)^2} \begin{pmatrix} (\sum t_i^2)(\sum y_i) - (\sum t_i)(\sum t_i y_i) \\ -(\sum t_i)(\sum y_i) + m(\sum t_i y_i) \end{pmatrix}$$

So we solved for α, β
 in terms of $(t_1, y_1), \dots, (t_m, y_m)$.

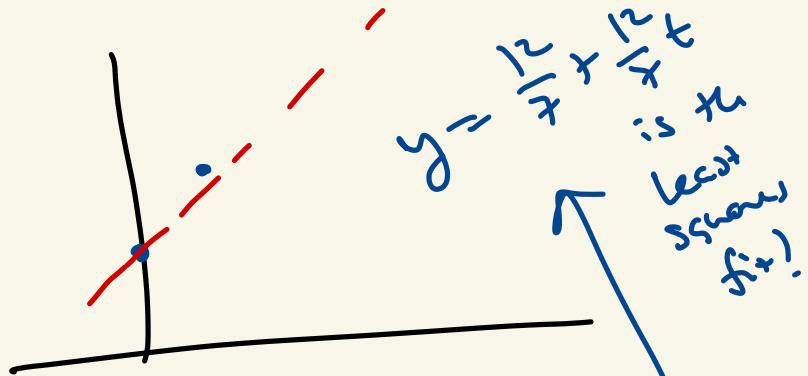
Ex:

| | | | | |
|----------|---|---|---|----|
| <u>t</u> | 0 | 1 | 3 | 6 |
| y | 2 | 3 | 7 | 12 |

time

?

$y = \alpha t + \beta t$?



$$y = \frac{12}{7}t + \frac{12}{7}t$$

is the
least squares
fit!

$$A = \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \\ 1 & 6 \end{pmatrix} \quad y = \begin{pmatrix} 2 \\ 3 \\ 7 \\ 12 \end{pmatrix}$$

$$\begin{pmatrix} \alpha \\ \beta \end{pmatrix} = (A^T A)^{-1} A^T y$$

$$A^T A = \begin{pmatrix} 4 & 10 \\ 10 & 46 \end{pmatrix}$$

$$A^T y = \begin{pmatrix} 24 \\ 96 \end{pmatrix}$$

$$\begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} 4 & 10 \\ 10 & 46 \end{pmatrix}^{-1} \begin{pmatrix} 24 \\ 96 \end{pmatrix} = \underline{\begin{pmatrix} 12/7 \\ -2/7 \end{pmatrix}}$$

Same method for any polynomial fit!

$$(t_1, y_1) \dots (t_m, y_m)$$

$$y = \alpha_0 + \alpha_1 t^1 + \dots + \alpha_n t^n$$

$$\varepsilon_i = y_i - (\underline{\alpha_0} + \underline{\alpha_1 t_i^1} + \dots + \underline{\alpha_n t_i^n})$$

$$\varepsilon = y - A \begin{pmatrix} \alpha_0 \\ \vdots \\ \alpha_n \end{pmatrix}$$
$$A = \begin{pmatrix} 1 & t_1 & t_1^2 & \dots & t_1^n \\ 1 & t_2 & t_2^2 & \dots & t_2^n \\ \vdots & & & & \\ 1 & t_m & t_m^2 & \dots & t_m^n \end{pmatrix}$$

Least squares is ...

$$\begin{pmatrix} \alpha_0 \\ \vdots \\ \alpha_n \end{pmatrix} = (A^T A)^{-1} A^T y$$

$$A = \begin{pmatrix} | & t_1 & \cdots & t_n \\ | & \vdots & & \vdots \\ | & t_m & \cdots & t_m^n \end{pmatrix} \quad n+1 \text{ columns}$$

is called a Vandermonde matrix.

A is a square matrix when

$$\overline{m=n+1.} \quad A = \begin{pmatrix} | & t_1 & \cdots & t_1^n \\ | & \vdots & & \vdots \\ | & t_{n+1} & \cdots & t_{n+1}^n \end{pmatrix}_{n+1, n+1}$$

If $t_i \neq t_j$ then

A^{-1} exists in this case.

$$x^* = (A^T A)^{-1} A^T x$$

$$= A^{-1} (A^T)^{-1} A^T y$$

$$= A^{-1} y$$

determines
which polynomial
goes thru data
points exactly

Ex : If $m=3$, then if I fit

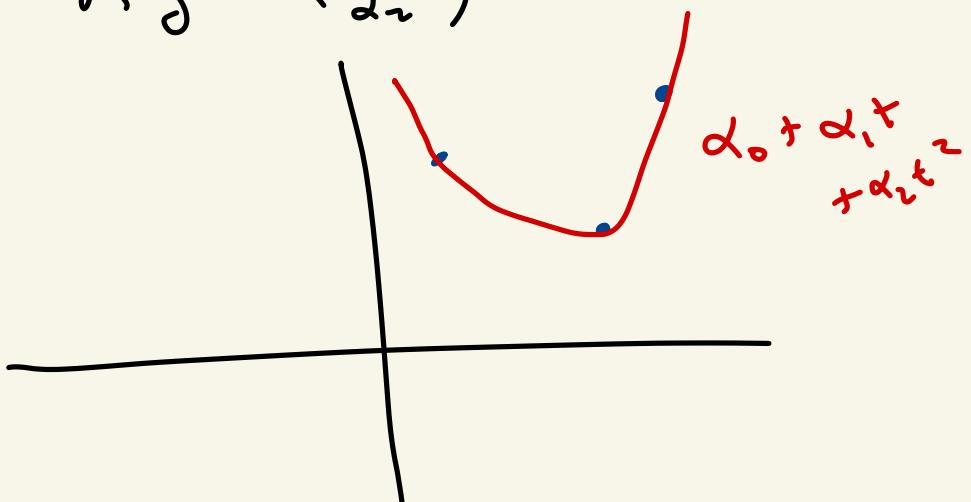
$$(t_1, y_1), \dots, (t_3, y_3)$$

to a degree 2 polynomial

$$p(t) = \alpha_0 + \alpha_1 t + \alpha_2 t^2$$

$$\begin{pmatrix} \alpha_0 \\ \alpha_1 \\ \alpha_2 \end{pmatrix} = \left(\begin{array}{ccc} 1 & t_1 & t_1^2 \\ 1 & t_2 & t_2^2 \\ 1 & t_3 & t_3^2 \end{array} \right)^{-1} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$$

$$A y = \begin{pmatrix} \alpha_0 \\ \vdots \\ \alpha_n \end{pmatrix}$$



Remember: $A \in \mathbb{R}^{m \times n}$, $n < m$

$$A : \mathbb{R}^n \longrightarrow \mathbb{R}^m$$

stretches \mathbb{R}^n inside \mathbb{R}^m
in some way

$$(ATA)^{-1} A^T : \mathbb{R}^m \longrightarrow \mathbb{R}^n$$

best way to go backwards.

8.7 Singular Values

Take A , $\text{rank}(A) = r$, $n \times m$.

$\text{ker}(A) = 0$, r independent
columns.

$K = A^T A$, pos def, invertible
symmetric

Eigenvalues of $A^T A$, $\lambda_i > 0$

Def: Given a matrix A ,
 the singular values of A are $\sigma_i = \sqrt{\lambda_i}$
 λ_i is a eigenvalue of $K = A^T A$.

We don't have $\text{rank}(A) = n$.

If $\text{rank}(A) < n$.

$K = A^T A$ is positive semi-definite

$$\lambda_1, \dots, \lambda_r > 0 \rightsquigarrow \sigma_i = \sqrt{\lambda_i}$$

$$\lambda_{r+1}, \dots, \lambda_n = 0.$$

Ex: $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ singular values?

$$K = A^T A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$K = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\rightarrow \left\{ \begin{array}{l} \lambda = 0 \\ \lambda = 1 \\ \lambda = 3 \end{array} \right. \quad v_1 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \quad v_3 = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

The singular values of $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}$

$$\rightarrow \text{are } \sigma_1 = \sqrt{1} = 1 \quad \sigma_2 = \sqrt{3} = \sqrt{3}.$$

Recall: K symmetric,

$$\text{then } K = Q \Delta Q^T$$

Δ diagonal Q orthogonal matrix

Spectral decomp.

Generalize this to non-square matrices!

Singular Value Decomposition :

Thm let A be $m \times n$, w singular values $\sigma_1, \dots, \sigma_r$ $\underline{\text{rank}(A) = r}$.

Then

$$A = P \Sigma Q^T$$

$$\begin{matrix} P, & m \times r \\ \Sigma & r \times r \\ Q & r \times n \end{matrix}$$

where the columns of Q
are orthonormal eigenvectors
of $A^T A$ for $\lambda_i = \sigma_i^2$.

$$\Sigma = \begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r \end{pmatrix}$$

P has orthonormal columns given by

$$P_i = \frac{A g_i}{\sigma_i}.$$

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = P \cdot \Sigma Q^T$$

$$A^T A = \begin{pmatrix} 1 & 0 \\ 1 & 2 \\ 0 & 1 \end{pmatrix}$$

$$\sigma_1 = 1 \quad \sigma_2 = \sqrt{3}$$

$$\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$



$$u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \quad u_2 = \frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

$$Q = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ 0 & \frac{\sqrt{2}}{\sqrt{6}} \\ \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{6}} \end{pmatrix}$$

$$\Sigma = \begin{pmatrix} 1 & 0 \\ 0 & \sqrt{3} \end{pmatrix}$$

$$P = \begin{pmatrix} \frac{A_{g1}}{\sigma_1} & \frac{A_{g2}}{\sigma_2} \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & \sqrt{3} \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{6}} \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \end{pmatrix}$$

P

have orthonormal
columns

Q^T
orthonormal
rows

$$\text{let } A = P \Sigma Q^T$$

$$\text{almost } A^{-1} = (P \Sigma Q^T)^{-1}$$

$$= (Q^T)^{-1} \Sigma^{-1} P^{-1}$$

$$= Q \Sigma^{-1} P^T$$

$$A^{-1} = Q \underbrace{\left(\frac{1}{\sigma_1} \cdots \frac{1}{\sigma_r} \right)}_{\Sigma^{-1}} P^T$$

Def Given any matrix A , $m \times n$,
 $A = P \Sigma Q^T$, then the pseudoinverse
is $A^+ = Q \Sigma^{-1} P^T$.

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & \sqrt{3} \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & \frac{2}{\sqrt{6}} & \frac{-1}{\sqrt{6}} \end{pmatrix}$$

$$A = P \sum Q^T$$

$$A^+ = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & \frac{\sqrt{2}}{\sqrt{6}} \\ \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{6}} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & \frac{1}{\sqrt{3}} \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix}$$

$$A : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$(A^T A)^{-1} A^T : \mathbb{R}^m \rightarrow \mathbb{R}^n$$

$$A^+ : \mathbb{R}^m \rightarrow \mathbb{R}^n$$

Thm If $\text{rank}(A) = n$ then

$$\underline{A^+ = \underline{(A^T A)^{-1} A^T}}.$$

$\lambda_i \approx$
 $\nwarrow = A^T A$

compute
naturally

$$\underline{\text{Pf}} : \text{Let } A = P \Sigma Q^T$$

$$A^+ = Q \Sigma^{-1} P^T.$$

$$A^T A = (P \Sigma Q^T)^T (P \Sigma Q^T)$$

$$= Q \Sigma^T P^T \cancel{P \Sigma Q^T}$$

orthonormal
columns

$$= Q \Sigma^T \Sigma Q^T , \Sigma^T = \Sigma$$

square
diagonal

$$= Q \Sigma^2 Q^T$$

$$(A^T A)^{-1} = Q \left(\frac{1}{\sigma_1^2} \dots \frac{1}{\sigma_r^2} \right) Q^T \quad (\text{spectral decom})$$

$$= Q \Sigma^{-2} Q^T$$

$$\boxed{(A^T A)^{-1} A^T} = (Q^T \Sigma^{-2} Q)(P \Sigma Q^T)^T$$

orthonormal
columns

$$= Q \Sigma^{-2} Q^T \cancel{Q \Sigma^T P^T}$$

$$= Q \Sigma^{-2} \Sigma P^T = Q \Sigma^1 P^T = \boxed{A^+}$$