# **Jack Schultz**

Mechanical Engineer – Graduate Research Assistant

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Passionate and driven mechanical engineer with 4+ years of experience in robotics and controls research, and 1+ years of experience in the automotive industry. Primary research goal is to develop intelligent assistive technologies to empower individuals to lead productive and healthy lifestyles.

# **WORK EXPERIENCE**

## Graduate Research Assistant

Center for Human Machine Systems 07/2018 – Present

# Achievements/Roles

- Lead the development of a ROS enabled robotassisted feeding system combining robotics, computer vision, eye-tracking, and speech recognition for individuals with spinal cord injury.
- Performed a research study investigating the effects of entangled sensory and motor responsibilities on eye-hand coordination.
- Developed a model architecture using MATLAB & Simulink with dSPACE Control Desk to facilitate real-time 3D gaze-control of a rehabilitation robot.

Contact: Eric Schearer – e.schearer@csuohio.edu

# Undergraduate Research Assistant

Engineering Wellness Through Biomechanics Lab 01/2017 – 12/2017

## Achievements/Roles

- Lead the development of an <u>assistive device</u> that monitored a walker user's posture as a part of the University's STEM Catalyst grant.
- Mentored undergraduate students in the design of other rollator walker adaptive devices such as a lighting system.

Contact: Kim Bigelow – kbigelow1@udayton.edu

# Mechanical Engineering Co-op

Inteva Products, LLC 05/2015 – 12/2016

# Achievements/Roles

- Product Design: Developed new materials and technologies to improve the current manufacturing process
- Injection Molding and Facilities: Oversaw and executed installation of new injection molding machines in existing plant facilities
- Soft Tooling: Designed, fabricated, and tested injection tooling for prototype polyurethane armrest liners.

#### **EDUCATION**

# Ph.D. Mechanical Engineering

Cleveland State University Cleveland, OH 07/2018 – Present GPA: 3.94/4.0

# **B.S. Mechanical Engineering**

University of Dayton 08/2013 – 12/2017 Dayton, OH GPA: 3.77/4.0

# **SKILLS**

MATLAB & Simulink	ROS/Gazebo • • •
SolidWorks 3D CAD •••	Python • • • •
Version Control/Git ● ● ○	C/C++ • • • • •

#### **AWARDS**

# Graduate Student Research Award

Cleveland State University – 2022

# Excellent Doctoral Dissertation Award Cleveland State University – 2022

3 Minute Thesis 1<sup>st</sup> Place Winner Cleveland State University – 2021 & 2022

## **INTERESTS**

Robotics Controls Machine Learning Technology

# **PUBLICATIONS**

Conference

# Proof of Concept: A Hands-Free Interface for Robot-Assisted Self-Feeding

J. Schultz, A. Slifkin, H. Yu, E. Schearer *RehabWeek ICORR* – (07/2022)

Journal

# Controlling an Effector with Eye Movements: The Effect of Entangled Sensory and Motor Responsibilities

J. Schultz, A. Slifkin, E. Schearer *PLoS One – (02/2022)* 

Journal

# The Effects of a Positional Feedback Device on Rollator Walker Use: A Validation Study

C. Golembiewski, J. Schultz, et al. Assistive Technology – (07/2019)