

		Method										Summary						
		Inferable trajectory types																
		Priors required	Wrapper type	Platform	Topology inference	Cycle	Linear	Bifurcation	Multifurcation	Tree	Connected	Disconnected	Overall	Benchmark	Scalability	Stability	QC	
graph	graph	PAGA	×	Traj	Python	Free												
		Projected PAGA		Proj	Python	Free												
		RaceID / StemID		Proj	R	Free												
		SLICER	×	Cell	R	Free												
Tree	Tree	Slingshot		Traj	R	Free												
		PAGA Tree	×	Traj	Python	Free												
		Projected Slingshot		Proj	R	Free												
		Projected TSCAN		Proj	R	Free												
		Monocle ICA		Cell	R	Param												
		pCreode		Proj	Python	Free												
		Projected Monocle		Proj	R	Free												
		SLICE		Traj	R	Free												
		SCUBA		Cluster	Python	Free												
		cellTree maptpx		Cell	R	Free												
		cellTree VEM		Cell	R	Free												
		Monocle DDRTree		Cell	R	Free												
		Sincell		Cell	R	Free												
		EIPiGraph		Traj	R	Free												
		CellRouter	×	Cell	R	Free												
		URD	×	Traj	R	Free												
		Mpath	✖	Cluster	R	Free												
		CellTrails		Cell	R	Free												
		MERLoT	×	Traj	R	Free												
		CALISTA		Traj	R	Free												
		cellTree Gibbs		Cell	R	Free												
		Multifurcation	Multifurcation	GrandPrix		Prob	Python	Param										
STEMNET	✖			Prob	R	Param												
FateID	✖			Prob	R	Param												
MFA				Prob	R	Param												
GPfates	×			Prob	Python	Param												
SCOUP	✖			Prob	C++	Param												
Bifurcation	Bifurcation	Projected DPT		Proj	R	Fixed												
		DPT		Traj	R	Fixed												
		Wishbone	×	Traj	Python	Param												
Linear	Linear	SCORPIUS		Linear	R	Fixed												
		MATCHER		Linear	Python	Fixed												
		TSCAN		Linear	R	Fixed		</										