

HoCL semantics v1.2

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Chapter 1

Abstract syntax

This is the abstract syntax used to formalize the typing rules and static semantics in chapters 2 and 3.

```

⟨program⟩ ::= ⟨type_decl⟩* ⟨val_decl⟩* ⟨node_decl⟩*

⟨type_decl⟩ ::= type IDENT

⟨node_decl⟩ ::= node IDENT ( ⟨io_decl⟩* ) ( ⟨io_decl⟩* ) [⟨node_impl⟩]
               | graph IDENT ( ⟨io_decl⟩* ) ( ⟨io_decl⟩* ) ⟨node_impl⟩

⟨io_decl⟩ ::= IDENT : ⟨type_expr⟩ [= ⟨const_expr⟩]

⟨node_impl⟩ ::= ⟨val_decl⟩*

⟨val_decl⟩ ::= val [rec] ⟨binding⟩and+

⟨binding⟩ ::= ⟨pattern⟩ = ⟨expr⟩

⟨pattern⟩ ::= IDENT
            | ( ⟨pattern⟩+ )
            | ( )

⟨expr⟩ ::= ⟨const_expr⟩
          | IDENT
          | ⟨expr⟩ ⟨expr⟩
          | ( ⟨expr⟩+ )
          | fun ⟨funpat⟩ → ⟨expr⟩
          | let [rec] ⟨binding⟩and+ in ⟨expr⟩
          | ( )

⟨funpat⟩ ::= IDENT

⟨const_expr⟩ ::= INT
              | true
              | false

⟨type_expr⟩ ::= IDENT ⟨type_expr⟩*
```


Chapter 2

Typing

The type language is fairly standard. A type τ is either :

- a type variable α
- a constructed type $\chi \langle \tau_1, \dots, \tau_n \rangle$,
- a functional type $\tau_1 \rightarrow \tau_2$,
- a product type $\tau_1 \times \dots \times \tau_n$,

Typing occurs in the context of a *typing environment* consisting of :

- a type environment TE, recording type constructors,
- a variable environment VE, mapping identifiers to types¹.

The initial type environment TE_0 records the type of the *builtin* type constructors :

$TE_0 = [\text{int} \mapsto \text{Int}, \text{bool} \mapsto \text{Bool}, \text{param} \mapsto \tau \rightarrow \text{Param } \tau, \dots]$

The initial variable environment VE_0 contains the types of the builtin primitives :

$VE_0 = [+ \mapsto \text{Int} \times \text{Int} \rightarrow \text{Int}, = \mapsto \text{Int} \times \text{Int} \rightarrow \text{Bool}, \dots]$

2.1 Notations

Both type and variable *environments* are viewed as partial maps from identifiers to types and from type constructors to types respectively. If E is an environment, the domain of E is denoted by $\text{dom}(E)$. The empty environment is written \emptyset . $[x \mapsto y]$ denotes the singleton environment mapping x to y and $E(x)$ the result of applying the underlying map to x (for ex. if E is $[x \mapsto y]$ then $E(x) = y$) and $E[x \mapsto y]$ the environment that maps x to y and behaves like E otherwise. $E \oplus E'$ denotes the environment obtained by adding the mappings of E' to those of E . If E and E' are not disjoint, then the mappings of E are “shadowed” by those of E' . Given two types τ and τ' , we will note $\tau \simeq \tau'$ if τ and τ' are equal modulo unification².

For convenience and readability, we will adhere to the following naming conventions throughout this chapter :

¹More precisely, to *type schemes* $\sigma = \forall \alpha. \tau$; but, for simplicity, we do not distinguish types from type schemes in this presentation, *i.e.* the instantiation of a type scheme into a type and the generalisation of a (polymorphic) type into a type scheme are left implicit in the rules given above. The corresponding definitions are completely standard.

²For monotypes, this is structural equality.

Meta-variable	Meaning
TE	Type environment
VE	Variable environment
t	Type expression
τ	Type or type scheme
χ	Type constructor
id	Identifier
<i>pat</i>	Pattern
<i>expr</i>	Expression

Syntactical terminal symbols are written in **bold**. Non terminals in *italic*. Types values are written in serif.

2.2 Programs

$$\boxed{\vdash \text{Program} \Rightarrow \text{VE}'}$$

$$\frac{\begin{array}{l} \text{TE}_0 \vdash \textit{typedecls} \Rightarrow \text{TE}' \\ \text{TE}_0 \oplus \text{TE}', \text{VE}_0 \vdash \textit{valdecls} \Rightarrow \text{VE}' \\ \text{TE}_0 \oplus \text{TE}', \text{VE}' \vdash \textit{nodedecls} \Rightarrow \text{VE} \end{array}}{\text{TE}_0, \text{VE}_0 \vdash \mathbf{program} \textit{ typedecls valdecls nodedecls} \Rightarrow \text{VE}} \quad (\text{PROGRAM})$$

Typing a program consists in

- typing the type declarations, resulting in an augmented type environment,
- typing the global value declarations, resulting in an augmented value environment,
- typing the sequence of node declarations in these augmented environments.

The result is an environment containing the type of each declared node.

2.3 Type declarations

$$\boxed{\text{TE} \vdash \text{TypeDecls} \Rightarrow \text{TE}'}$$

$$\frac{\forall i. 1 \leq i \leq n, \text{TE} \vdash \textit{typedecl}_i \Rightarrow \text{TE}_i}{\text{TE}, \text{VE} \vdash \textit{typedecl}_1 \dots \textit{typedecl}_n \Rightarrow \bigoplus_{i=1}^n \text{TE}_i} \quad (\text{TYPEDECLS})$$

$$\boxed{\text{TE} \vdash \text{TypeDecl} \Rightarrow \text{TE}'}$$

$$\overline{\text{TE}, \text{VE} \vdash \mathbf{type} \text{ id} \Rightarrow [\text{id} \mapsto 0]} \quad (\text{TYPEDECL})$$

An abstract type declaration simply adds the corresponding type constructor in the type environment.

2.4 Node declarations

$$\boxed{\text{TE, VE} \vdash \text{NodeDecls} \Rightarrow \text{VE}'}$$

$$\frac{\text{VE}_0 = \text{VE} \quad \forall i. 1 \leq i \leq n, \text{ TE, VE}_{i-1} \vdash \text{nodedecl}_i \Rightarrow \text{VE}_i}{\text{TE, VE} \vdash \text{nodedecl}_1 \dots \text{nodedecl}_n \Rightarrow \text{VE}_n} \quad (\text{NODEDECLS})$$

Node declarations are typed in the order of their declaration. A declaration can be used in the subsequent ones.

$$\boxed{\text{TE, VE} \vdash \text{NodeDecl} \Rightarrow \text{VE}'}$$

$$\frac{\begin{array}{l} \forall i. 1 \leq i \leq m, \text{ TE} \vdash t_i \Rightarrow \tau_i \\ \forall i. 1 \leq i \leq n, \text{ TE} \vdash t'_i \Rightarrow \tau'_i \\ \tau = \tau_1 \rightarrow \dots \rightarrow \tau_m \rightarrow \tau'_1 \times \dots \times \tau'_n \end{array}}{\text{TE, VE} \vdash \mathbf{node} \text{ id } (id_1 : t_1, \dots, id_m : t_m) (id'_1 : t'_1, \dots, id'_n : t'_n) \Rightarrow \text{VE} \oplus [id \mapsto \tau]} \quad (\text{NODEDECL1})$$

At the type level, an *opaque* node (actor) declared as

$$\mathbf{node} \text{ name } \mathbf{in} (i_1:t_1, \dots, i_m:t_m) \mathbf{outs} (o_1:t'_1, \dots, o_n:t'_n)$$

is viewed as a function having type

$$\tau_1 \rightarrow \dots \tau_m \rightarrow \tau'_1 \times \dots \times \tau'_n$$

i.e. as a function taking m arguments in curried form (one after the other) and returning its n results as a tuple³.

$$\frac{\begin{array}{l} \forall i. 1 \leq i \leq m, \text{ TE} \vdash t_i \Rightarrow \tau_i \\ \forall i. 1 \leq i \leq n, \text{ TE} \vdash t'_i \Rightarrow \tau'_i \\ \text{TE, VE} \bigoplus_{i=1}^m [id_i \mapsto \tau_i] \vdash \text{valdecls} \Rightarrow \text{VE}' \\ \forall i. 1 \leq i \leq n, \text{ TE} \vdash \tau'_i \simeq \text{VE}'(id'_i) \\ \tau = \tau_1 \rightarrow \dots \rightarrow \tau_m \rightarrow \tau'_1 \times \dots \times \tau'_n \end{array}}{\text{TE, VE} \vdash \mathbf{node} \text{ id } (id_1 : t_1, \dots, id_m : t_m) (id'_1 : t'_1, \dots, id'_n : t'_n) \text{ valdecls} \Rightarrow \text{VE} \oplus [id \mapsto \tau]} \quad (\text{NODEDECL2})$$

For “transparent” nodes, *i.e.* nodes defined by a set of value declarations, we also check that the type assigned to outputs by these declarations are compatible with the type assigned to the corresponding node output.

2.5 Graph declarations

Graph declarations are handled exactly as node declarations except that the value optionally attached to inputs is type checked against the declared type⁴ and that graph declarations always have a *valdecls* section (there’s no such thing as an opaque graph declaration).

³In OCAML for example, such a function could have been defined like : `let f x1 ... xm = (e1, ..., en).`

⁴Strictly speaking, such values can only be attached to inputs declared as *parameters* (*i.e.* with type `t param`). This distinction is omitted here for brevity.

$$\boxed{\text{TE, VE} \vdash \text{GraphDecl} \Rightarrow \text{VE}'}$$

$$\frac{\begin{array}{l} \forall i. 1 \leq i \leq m, \text{ TE} \vdash t_i \Rightarrow \tau_i \\ \forall i. 1 \leq i \leq m, \text{ TE}, \emptyset \vdash e_i \Rightarrow \tau_i'' \\ \forall i. 1 \leq i \leq m, \tau_i \simeq \tau_i'' \\ \forall i. 1 \leq i \leq n, \text{ TE} \vdash t'_i \Rightarrow \tau_i' \\ \text{TE, VE} \bigoplus_{i=1}^m [\text{id}_i \mapsto \tau_i] \vdash \text{valdecls} \Rightarrow \text{VE}' \\ \forall i. 1 \leq i \leq n, \text{ TE} \vdash \tau_i' \simeq \text{VE}'(\text{id}'_i) \\ \tau = \tau_1 \rightarrow \dots \rightarrow \tau_m \rightarrow \tau'_1 \times \dots \times \tau'_n \end{array}}{\text{TE, VE} \vdash \mathbf{graph} \text{ id } (\text{id}_1 : t_1 = e_1, \dots, \text{id}_m : t_m = e_m) (\text{id}'_1 : t'_1, \dots, \text{id}'_n : t'_n) \text{ valdecls} \Rightarrow \text{VE} \oplus [\text{id} \mapsto \tau]} \quad (\text{GRAPHDECL})$$

2.6 Value declarations

$$\boxed{\text{TE, VE} \vdash \text{ValDecls} \Rightarrow \text{VE}'}$$

$$\frac{\begin{array}{l} \text{VE}_0 = \text{VE} \\ \forall i. 1 \leq i \leq n, \text{ TE, VE}_{i-1} \vdash \text{valdecl}_i \Rightarrow \text{VE}_i \end{array}}{\text{TE, VE} \vdash \text{valdecl}_1 \dots \text{valdecl}_n \Rightarrow \text{VE}_n} \quad (\text{VALDECLS})$$

$$\boxed{\text{TE, VE} \vdash \text{ValDecl} \Rightarrow \text{VE}'}$$

$$\frac{\text{TE, VE} \vdash \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow \text{VE}'}{\text{TE, VE} \vdash \mathbf{val} \text{ pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow \text{VE} \oplus \text{VE}'} \quad (\text{VALDECL})$$

$$\boxed{\text{TE, VE} \vdash_r \text{ValDecl} \Rightarrow \text{VE}'}$$

$$\frac{\text{TE, VE} \vdash_r \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow \text{VE}'}{\text{TE, VE} \vdash \mathbf{val} \mathbf{rec} \text{ pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow \text{VE} \oplus \text{VE}'} \quad (\text{RECVALDECL})$$

$$\boxed{\text{TE, VE} \vdash \text{PatExprs} \Rightarrow \text{VE}'}$$

$$\frac{\begin{array}{l} \forall i. 1 \leq i \leq n, \text{ TE, VE} \vdash \text{pat}_i = \text{expr}_i \Rightarrow \text{VE}'_i \\ \text{VE}' = \bigoplus_{i=1}^n \text{VE}'_i \end{array}}{\text{TE, VE} \vdash \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow \text{VE}'} \quad (\text{BINDINGS})$$

The rule Bindings deals with multiple bindings, as found in **val** *p1=e1* and ... and *pn=en* declarations or **let** *p1=e1* and ... and *pn=en* expressions.

$$\boxed{\text{TE}, \text{VE} \vdash_r \text{PatExprs} \Rightarrow \text{VE}'}$$

$$\frac{\forall i. 1 \leq i \leq n, \quad \text{TE}, \text{VE} \oplus \text{VE}' \vdash \text{pat}_i = \text{expr}_i \Rightarrow \text{VE}'_i \quad \text{VE}' = \bigoplus_{i=1}^n \text{VE}'_i}{\text{TE}, \text{VE} \vdash_r \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow \text{VE}'} \quad (\text{RECBINDINGS})$$

The rule **RecBindings** deals with multiple recursive bindings. Note that in this case, the recursively defined symbols are available when typing the RHS expressions.

$$\boxed{\text{TE}, \text{VE} \vdash \text{Pat} = \text{Expr} \Rightarrow \text{VE}'}$$

$$\frac{\text{TE}, \text{VE} \vdash \text{expr} \Rightarrow \tau \quad \vdash_p \text{pat}, \tau \Rightarrow \text{VE}'}{\text{TE}, \text{VE} \vdash \text{pat} = \text{expr} \Rightarrow \text{VE}'} \quad (\text{BINDING})$$

where

$$\vdash_p \text{pat}, \tau \Rightarrow \text{VE}$$

means that declaring *pat* with type τ creates the variable environment VE , as described in Sec. 2.6.1.

2.6.1 Patterns

$$\boxed{\vdash_p \text{Pat}, \tau \Rightarrow \text{VE}}$$

$$\overline{\vdash_p \text{id}, \tau \Rightarrow [\text{id} \mapsto \tau]} \quad (\text{PATVAR})$$

$$\frac{\forall i. 1 \leq i \leq n, \quad \vdash_p \text{pat}_i, \tau_i \Rightarrow \text{VE}_i}{\vdash_p (\text{pat}_1, \dots, \text{pat}_n), \tau_1 \times \dots \times \tau_n \Rightarrow \bigoplus_{i=1}^n \text{VE}_i} \quad (\text{PAT TUPLE})$$

$$\overline{\vdash_p (), \text{Unit} \Rightarrow \emptyset} \quad (\text{PATUNIT})$$

$$\overline{\vdash_p -, \tau \Rightarrow \emptyset} \quad (\text{PATIGNORE})$$

2.6.2 Expressions

$$\boxed{\text{TE}, \text{VE} \vdash \text{Expr} \Rightarrow \tau}$$

$$\frac{\text{VE}(\text{id}) = \tau}{\text{TE}, \text{VE} \vdash \text{id} \Rightarrow \tau} \quad (\text{EVAR})$$

$$\frac{\forall i. 1 \leq i \leq n, \quad \text{TE}, \text{VE} \vdash \text{expr}_i \Rightarrow \tau_i}{\text{TE}, \text{VE} \vdash (\text{expr}_1, \dots, \text{expr}_n) \Rightarrow \tau_1 \times \dots \times \tau_n} \quad (\text{ETUPLE})$$

$$\begin{array}{c}
\frac{\text{TE, VE} \vdash \text{expr}_1 \Rightarrow \tau \rightarrow \tau' \quad \text{TE, VE} \vdash \text{expr}_2 \Rightarrow \tau}{\text{TE, VE} \vdash \text{expr}_1 \text{ expr}_2 \Rightarrow \tau'} \quad (\text{EAPP}) \\
\\
\frac{\vdash_p \text{pat}, \tau \Rightarrow \text{VE}' \quad \text{TE, VE} \oplus \text{VE}' \vdash \text{expr} \Rightarrow \tau'}{\text{TE, VE} \vdash \mathbf{fun} \text{ pat} \rightarrow \text{expr} \Rightarrow \tau \rightarrow \tau'} \quad (\text{EFUN}) \\
\\
\frac{\text{TE, VE} \vdash \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow \text{VE}' \quad \text{TE, VE} \oplus \text{VE}' \vdash \text{expr}' \Rightarrow \tau}{\text{TE, VE} \vdash \mathbf{let} \text{ pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \mathbf{in} \text{expr}' \Rightarrow \tau} \quad (\text{ELET}) \\
\\
\frac{\text{TE, VE} \vdash_r \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow \text{VE}' \quad \text{TE, VE} \oplus \text{VE}' \vdash \text{expr}' \Rightarrow \tau}{\text{TE, VE} \vdash \mathbf{let} \mathbf{rec} \text{ pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \mathbf{in} \text{expr}' \Rightarrow \tau} \quad (\text{ELETREC}) \\
\\
\frac{}{\text{TE, VE} \vdash () \Rightarrow \text{Unit}} \quad (\text{EUNIT}) \\
\\
\frac{}{\text{TE, VE} \vdash \text{int} \Rightarrow \text{Int}} \quad (\text{EINT}) \\
\\
\frac{}{\text{TE, VE} \vdash \text{bool} \Rightarrow \text{Bool}} \quad (\text{EBOOL}) \\
\\
\frac{\text{VE}(\text{op}) = \tau_1 \times \tau_2 \rightarrow \tau_3 \quad \text{TE, VE} \vdash \text{expr}_1 \Rightarrow \tau_1 \quad \text{TE, VE} \vdash \text{expr}_2 \Rightarrow \tau_2}{\text{TE, VE} \vdash \text{expr}_1 \text{ op } \text{expr}_2 \Rightarrow \tau_3} \quad (\text{EBINOP}) \\
\\
\frac{\text{TE, VE} \vdash \text{expr} \Rightarrow \text{Bool} \quad \text{TE, VE} \vdash \text{expr}_1 \Rightarrow \tau \quad \text{TE, VE} \vdash \text{expr}_2 \Rightarrow \tau}{\text{TE, VE} \vdash \mathbf{if} \text{ expr } \mathbf{then} \text{ expr}_1 \mathbf{else} \text{ expr}_2 \Rightarrow \tau} \quad (\text{EIF})
\end{array}$$

2.7 Type expressions

$$\boxed{\text{TE} \vdash t \Rightarrow \tau}$$

$$\frac{\text{TE}(\chi) = \tau}{\text{TE} \vdash \chi \Rightarrow \tau} \quad (\text{TYCON0})$$

$$\frac{\text{TE}(\chi) = \tau_1 \rightarrow \dots \rightarrow \tau_n \rightarrow \tau \quad \forall i. 1 \leq i \leq n, \text{ TE} \vdash t_i \Rightarrow \tau_i}{\text{TE} \vdash \chi \langle t_1, \dots, t_n \rangle \Rightarrow \tau} \quad (\text{TYCON1})$$

Chapter 3

Static semantics

The static semantics gives the interpretation of HoCL programs, described with the abstract syntax given in chapter 1, as a set of (dataflow) *graphs*, where each graph is defined as a set of *boxes* connected by *wires*. The formulation given here assumes that the program has been successfully type checked.

The static semantics is built upon the semantic domain given below.

Variable	Set ranged over	Definition	Meaning
v	Val	Loc + Node + Tuple + Clos Unit + Int + Bool + Prim	Value
ℓ	Loc	$\langle \text{bid}, \text{sel} \rangle$	Graph location
n	Node	$\langle \text{NCat}, \{\text{id} \mapsto \text{Val}\}, \{\text{id}\}, \text{NImpl} \rangle$	Node description
κ	NCat	node + graph	Node category
vs	Tuple	Val^+	Tuple
cl	Clos	$\langle \text{pattern}, \text{expr}, \text{Env} \rangle$	Closure
E	Env	$\{\text{id} \mapsto \text{Val}\}$	Value environment
η	NImpl	actor + Graph	Node implementation
g	Graph	$\langle \text{Boxes}, \text{Wires} \rangle$	Graph description
B	Boxes	$\{\text{bid} \mapsto \text{Box}\}$	Box environment
W	Wires	$\{\text{wid} \mapsto \text{Wire}\}$	Wire environment
L	Locs	Loc*	Location set
b	Box	$\langle \text{BCat}, \{\text{sel} \mapsto \text{wid}\}, \{\text{sel} \mapsto \text{wid}^*\}, \text{Val} \rangle$	Box
c	BCat	actor + graph + src + snk + rec inParam + localParam	Box category
w	Wire	$\langle \langle \text{bid}, \text{sel} \rangle, \langle \text{bid}, \text{sel} \rangle \rangle$	Wire (src loc, dst loc)
l, l'	bid	$\{0, 1, 2, \dots\}$	Box id
k, k'	wid	$\{0, 1, 2, \dots\}$	Wire id
s, s'	sel	$\{0, 1, 2, \dots\}$	Slot selector
	Int	$\{\dots, -2, -1, 0, 1, \dots\}$	Integer value
β	Bool	$\{\text{true}, \text{false}\}$	Boolean value
π	Prim	$\{\text{Value} \mapsto \text{Value}\}$	Primitive function

Values in the category Loc correspond to graph *locations*, where a location comprises a box index and a selector. Selectors are used to distinguish inputs (resp. outputs when the box has several of them¹).

¹Valid selectors start at 1. The selector value 0 is used for incomplete box definitions.

Nodes are described by

- a category, indicating whether the node is a toplevel graph or an ordinary node²,
- a list of inputs, each with an attached value³,
- a list of outputs,
- an implementation, which is either empty (in case of opaque actors) or given as a graph.

Boxes are described by

- a category,
- a input environment, mapping selector values (1,2,...) to wire identifiers,
- a output environment, mapping selector values to sets of wire identifiers⁴,
- an optional value.

Box categories separate boxes

- resulting from the instantiation of a node,
- materializing graph inputs and outputs,
- materializing graph input parameters,
- materializing graph local parameters.

The category `rec` is used internally for building cyclic graphs (see Sec. 3.5.2).

The optional box value is only meaningful for local parameters bound to constants or for toplevel input parameters (giving in this case the constant value).

Wires are pairs of graph locations : one for the source box and the other for the destination box.

Closures correspond to functional values.

Primitives correspond to builtin functions operating on integer or boolean values (+, =, ...).

The environments E, B and W respectively bind

- identifiers to semantic values,
- box indices to box description,
- wire indices to wire description.

All *environments* are viewed as partial maps from keys to values. If E is an environment, the domain of E is denoted by $\text{dom}(E)$. The empty environment is written \emptyset . $[x \mapsto y]$ denotes the singleton environment mapping x to y . $E(x)$ denotes the result of applying the underlying map to x (for ex. if E is $[x \mapsto y]$ then $E(x) = y$) and $E \oplus E'$ the environment obtained by adding the mappings of E' to those of E , assuming that E and E' are disjoint.

²This avoids having two distincts but almost identical semantic values for nodes and toplevel graphs.

³These values are used to handle partial application.

⁴A box output can be broadcasted to several other boxes.

3.1 Programs

$$\boxed{\vdash \text{Program} \Rightarrow E}$$

$$\frac{\begin{array}{c} E_0, \emptyset \vdash \text{valdecls} \Rightarrow E, B, W \\ E, \emptyset \vdash \text{nodedecls} \Rightarrow E' \end{array}}{\vdash \text{program } \text{typedecls } \text{valdecls } \text{nodedecls} \Rightarrow E'} \quad (\text{PROGRAM})$$

Global values are first evaluated to give a value environment (boxes and wires resulting from this evaluation are here ignored). Nodes declarations are evaluated in this environment. The result is an environment associating a node description to each defined node.

The initial environment E_0 contains, the value of the builtin primitives ($+$, $=$, \dots).

3.2 Node and graph declarations

$$\boxed{E, B \vdash \text{NodeDecls} \Rightarrow E', B'}$$

$$\frac{\begin{array}{c} E_0 = E \\ B_0 = B \\ \forall i. 1 \leq i \leq n, \quad E_{i-1}, B_{i-1} \vdash \text{nodedecl}_i \Rightarrow E_i, B_i \end{array}}{E, B \vdash \text{nodedecl}_1 \dots \text{nodedecl}_n \Rightarrow E_n, B_n} \quad (\text{NODEDECLS})$$

Node declarations are interpreted in the order of their declaration. A declaration can be used in the subsequent ones.

$$\boxed{E, B \vdash \text{NodeDecl} \Rightarrow E', B'}$$

$$\frac{n = \text{Node}(\text{node}, [\text{id}_1 \mapsto \text{Unit}, \dots, \text{id}_m \mapsto \text{Unit}], [\text{id}'_1, \dots, \text{id}'_n], \text{actor})}{E, B \vdash \text{node id } (\text{id}_1 : t_1, \dots, \text{id}_m : t_m) (\text{id}'_1 : t'_1, \dots, \text{id}'_n : t'_n) \Rightarrow E \oplus [\text{id} \mapsto n], B} \quad (\text{NODEDECL1})$$

Nodes with no attached definition are mapped to opaque actors. The **Unit** value initially attached to inputs here means “yet unconnected”). Types are ignored at this level.

$$\frac{\begin{array}{c} B \vdash_i (\text{id}_1 : t_1, \dots, \text{id}_m : t_m) \Rightarrow E_i, B_i \\ B_i \vdash_o (\text{id}'_1 : t'_1, \dots, \text{id}'_n : t'_n) \Rightarrow E_o, B_o \\ E \oplus E_i \oplus E_o, B \oplus B_i \oplus B_o \vdash \text{valdecls} \Rightarrow B', W' \\ n = \text{Node}(\text{node}, [\text{id}_1 \mapsto \text{Unit}, \dots, \text{id}_m \mapsto \text{Unit}], \text{outs}, \text{Graph}(B', W')) \end{array}}{E, B \vdash \text{node id } (\text{id}_1 : t_1, \dots, \text{id}_m : t_m) (\text{id}'_1 : t'_1, \dots, \text{id}'_n : t'_n) \text{ valdecls} \Rightarrow E \oplus [\text{id} \mapsto n], B \oplus B_i \oplus B_o} \quad (\text{NODEDECL2})$$

For nodes with an attached definition, this definition is evaluated in an environment augmented with its input and output declarations, and the resulting graph (a pair of boxes and wires) is attached to the node description.

$$\boxed{B \vdash_{i/o} \text{NodeIOs} \Rightarrow E, B'}$$

$$\frac{\begin{array}{c} B_0 = B \\ \forall j. 1 \leq j \leq n, \quad B_{j-1} \vdash_{i/o} \text{id}_j : t_j \Rightarrow E_j, B_j \end{array}}{B \vdash_{i/o} (\text{id}_1 : t_1, \dots, \text{id}_n : t_n) \Rightarrow \bigoplus_{j=1}^n E_j, B_n} \quad (\text{NODEIOS})$$

$$\boxed{B \vdash_{i/o} \text{NodeIO} \Rightarrow E, B'}$$

$$\frac{l \notin \text{Dom}(B)}{B \vdash_i \text{id} : t \Rightarrow [\text{id} \mapsto \text{Loc}\langle l, 0 \rangle], B \oplus [l \mapsto \text{Box}\langle \text{src}, \emptyset, [1 \mapsto \emptyset] \rangle]} \quad (\text{NODEINP})$$

$$\frac{\begin{array}{c} l \notin \text{Dom}(B) \\ t \Rightarrow \text{Param } \tau \end{array}}{B \vdash_i \text{id} : t \Rightarrow [\text{id} \mapsto \text{Loc}\langle l, 0 \rangle], B \oplus [l \mapsto \text{Box}\langle \text{inParam}, \emptyset, [1 \mapsto \emptyset] \rangle]} \quad (\text{NODEPARAMINP})$$

$$\frac{l \notin \text{Dom}(B)}{B \vdash_o \text{id} : t \Rightarrow [\text{id} \mapsto \text{Loc}\langle l, 0 \rangle], B \oplus [l \mapsto \text{Box}\langle \text{snk}, [1 \mapsto 0], \emptyset \rangle]} \quad (\text{NODEOUTP})$$

Each input and output adds a box in the enclosing graph. Output boxes have category **snk**. Input boxes category **src** or **inParam**, depending on the their type. These boxes have no input (resp. no output). The premise $l \notin \text{Dom}(B)$ ensures that l is a “fresh” box index.

TODO: Need reference to typing rules (end hence env) here !

3.2.1 Graph declaration

$$\boxed{E, B \vdash \text{GraphDecls} \Rightarrow E', B'}$$

$$\frac{\begin{array}{c} B \vdash_i (\text{id}_1 : t_1 = e_1, \dots, \text{id}_m : t_m = e_m) \Rightarrow E_i, B_i \\ B_i \vdash_o (\text{id}'_1 : t'_1, \dots, \text{id}'_n : t'_n) \Rightarrow E_o, B_o \\ E \oplus E_i \oplus E_o, B \oplus B_i \oplus B_o \vdash \text{valdecls} \Rightarrow B', W' \\ \mathbf{n} = \text{Node}(\text{graph}, [\text{id}_1 \mapsto \text{Unit}, \dots, \text{id}_m \mapsto \text{Unit}], \text{outs}, \text{Graph}\langle B', W' \rangle) \end{array}}{E, B \vdash \mathbf{graph} \text{ id } (\text{id}_1 : t_1 = e_1, \dots, \text{id}_m : t_m = e_m) (\text{id}'_1 : t'_1, \dots, \text{id}'_n : t'_n) \text{ valdecls} \Rightarrow E \oplus [\text{id} \mapsto \mathbf{n}], B \oplus B_i \oplus B_o} \quad (\text{GRAPHDECL})$$

Evaluation of toplevel graph declarations is similar to that of node declarations. The only difference is that the optional value of inputs is evaluated and attached to the corresponding box⁵.

$$\boxed{B \vdash_i \text{GraphInp} \Rightarrow E, B'}$$

$$\frac{\begin{array}{c} l \notin \text{Dom}(B) \\ t \Rightarrow \text{Param } \tau \\ \emptyset, \emptyset \vdash e \Rightarrow v, \emptyset, \emptyset \end{array}}{B \vdash_i \text{id} : t = e \Rightarrow [\text{id} \mapsto \text{Loc}\langle l, 0 \rangle], B \oplus [l \mapsto \text{Box}\langle \text{inParam}, \emptyset, [1 \mapsto \emptyset], v \rangle]} \quad (\text{GRAPHINP})$$

Boxes materializing input parameters for toplevel graphs hold the value of the specified expression. Type checking ensures that this value is an integer or boolean constant⁶.

⁵As for the typing rules, strictly speaking, such values can only be attached to inputs declared as *parameters* (i.e. with type **t param**). This distinction is, here again, omitted for brevity.

⁶So that the evaluation of the defining expression creates no box nor wire.

3.3 Value declarations

$$\boxed{E, B \vdash \text{ValDecls} \Rightarrow E', B', W}$$

$$\frac{\begin{array}{c} E_0 = E, B_0 = B, W_0 = \emptyset \\ \forall i. 1 \leq i \leq n, \quad E_{i-1}, B_{i-1}, W_{i-1} \vdash \text{valdecl}_i \Rightarrow E_i, B_i, W_i \end{array}}{E, B \vdash \text{valdecl}_1 \dots \text{valdecl}_n \Rightarrow E_n, B_n, W_n} \quad (\text{VALDECLS})$$

Within a node definition, value declarations are interpreted in the order of their declaration. A declaration can be used in the subsequent ones. Each declaration updates the value, box and wire environments.

$$\boxed{E, B, W \vdash \text{ValDecl} \Rightarrow E', B', W'}$$

$$\frac{E, B \vdash \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow E', B', W'}{E, B, W \vdash \mathbf{val} \text{ pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow E \oplus E', B \oplus B', W \oplus W'} \quad (\text{VALDECL})$$

$$\boxed{E, B, W \vdash_{\text{rec}} \text{ValDecl} \Rightarrow E', B', W'}$$

$$\frac{E, B \vdash_{\text{rec}} \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow E', B', W'}{E, B, W \vdash \mathbf{val} \text{ rec } \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow E \oplus E', B \oplus B', W \oplus W'} \quad (\text{RECVALDECL})$$

$$\boxed{E, B \vdash \text{PatExprs} \Rightarrow E', B', W'}$$

$$\frac{\forall i. 1 \leq i \leq n, \quad E, B \vdash \text{pat}_i = \text{expr}_i \Rightarrow E'_i, B'_i, W_i}{E, B \vdash \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow \bigoplus_{i=1}^n E'_i, \bigoplus_{i=1}^n B'_i, \bigoplus_{i=1}^n W'_i} \quad (\text{BINDINGS})$$

$$\boxed{E, B \vdash \text{Pat}=\text{Expr} \Rightarrow E', B', W'}$$

$$\frac{\begin{array}{c} E, B \vdash \text{expr} \Rightarrow v, B', W' \\ E, B \overset{\leftarrow}{\oplus} B' \vdash_p \text{pat}, v \Rightarrow E', B'', W'' \end{array}}{E, B \vdash \text{pat} = \text{expr} \Rightarrow E', B' \overset{\leftarrow}{\oplus} B'', W' \oplus W''} \quad (\text{BINDING})$$

Evaluating a **val** declaration consists in evaluating the RHS expression and binding the result value to the LHS pattern.

The $\overset{\leftarrow}{\oplus}$ operator used in rule **Binding** merges box descriptors. If a box appears in both argument environments, the resulting environment contains a single occurrence of this box in which the respective input and output environments have been merged. For example

$$\begin{aligned} [1 \mapsto \text{Box}(\text{actor}, [1 \mapsto 0], [1 \mapsto \{2\}])] &\overset{\leftarrow}{\oplus} [1 \mapsto \text{Box}(\text{actor}, [1 \mapsto 4], [1 \mapsto \{3\}])] \\ &= [1 \mapsto \text{Box}(\text{actor}, [1 \mapsto 4], [1 \mapsto \{2, 3\}])] \end{aligned}$$

The semantics of *recursive* definitions ($E, B \vdash_{\text{rec}} \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n$) is given in Sec. 3.5.

3.4 Expressions

$$\boxed{E, B \vdash \text{Expr} \Rightarrow v, B', W}$$

$$\frac{E(\text{id}) = v}{E, B \vdash \text{id} \Rightarrow v, \emptyset, \emptyset} \quad (\text{EVAR})$$

The value of a variable is simply obtained from the value environment.

$$\frac{\forall i. 1 \leq i \leq n, \quad E, B \vdash \text{expr}_i \Rightarrow v_i, B_i, W_i}{E, B \vdash (\text{expr}_1, \dots, \text{expr}_n) \Rightarrow \langle v_1, \dots, v_n \rangle, \bigoplus_{i=1}^n B_i, \bigoplus_{i=1}^n W_i} \quad (\text{ETUPLE})$$

For tuples, each component is evaluated separately.

$$\frac{}{E, B \vdash \mathbf{fun} \text{ pat} \rightarrow \text{exp} \Rightarrow \text{Clos}(\langle \text{pat}, \text{exp}, E \rangle, \emptyset, \emptyset)} \quad (\text{EFUN})$$

Functions are evaluated, classically, as closures, capturing the current value environment.

$$\frac{\begin{array}{c} E, B \vdash \text{pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \Rightarrow E', B', W' \\ E \oplus E', B \oplus B' \vdash \text{exp}_2 \Rightarrow v, B'', W'' \end{array}}{E, B \vdash \mathbf{let} \text{ pat}_1 = \text{expr}_1 \dots \text{pat}_n = \text{expr}_n \mathbf{in} \text{exp}' \Rightarrow v, B \oplus B', W \oplus W'} \quad (\text{ELET})$$

$$\frac{}{E, B \vdash () \Rightarrow \text{Unit}, \emptyset, \emptyset} \quad (\text{EUNIT})$$

$$\frac{}{E, B \vdash \text{int} \Rightarrow \text{Int}, \emptyset, \emptyset} \quad (\text{EINT})$$

$$\frac{}{E, B \vdash \text{bool} \Rightarrow \text{Bool}, \emptyset, \emptyset} \quad (\text{EBOOL})$$

$$\frac{\begin{array}{c} E, B \vdash \text{exp} \Rightarrow \text{true}, B', W' \\ E, B \vdash \text{exp}_1 \Rightarrow v, B'', W'' \end{array}}{E, B \vdash \mathbf{if} \text{ exp} \mathbf{then} \text{exp}_1 \mathbf{else} \text{exp}_2 \Rightarrow v, B' \oplus B'', W' \oplus W''} \quad (\text{EIf0})$$

$$\frac{\begin{array}{c} E, B \vdash \text{exp} \Rightarrow \text{false}, B', W' \\ E, B \vdash \text{exp}_2 \Rightarrow v, B'', W'' \end{array}}{E, B \vdash \mathbf{if} \text{ exp} \mathbf{then} \text{exp}_1 \mathbf{else} \text{exp}_2 \Rightarrow v, B' \oplus B'', W' \oplus W''} \quad (\text{EIf1})$$

$$\frac{\begin{array}{c} E, B \vdash \text{exp}_1 \Rightarrow \text{Clos}(\langle \text{pat}, \text{exp}, E' \rangle, B_f, W_f) \\ E, B \vdash \text{exp}_2 \Rightarrow v, B_a, W_a \\ \emptyset, \emptyset \vdash_p \text{pat}, v \Rightarrow E_p, B_p, W_p \\ E' \oplus E_p, B \vdash \text{exp} \Rightarrow v', B', W' \end{array}}{E, B \vdash \text{exp}_1 \text{exp}_2 \Rightarrow v', B_f \oplus B_a \oplus B_p, W_f \oplus W_a \oplus W'} \quad (\text{EAPPC})$$

Rule EAPPC deals with the application of closures and follows the classical call-by-value strategy (the closure body is evaluated in an environment augmented with the bindings resulting from binding the pattern to the value of argument).

$$\begin{array}{c}
E, B \vdash \text{exp}_1 \Rightarrow \text{Node}(\kappa, [\text{id}_1 \mapsto \ell_1, \dots, \text{id}_{k-1} \mapsto \ell_{k-1}, \text{id}_k \mapsto \text{Unit}, \dots, \text{id}_m \mapsto \text{Unit}], [\text{id}'_1, \dots, \text{id}'_n], \eta), B_f, W_f \\
\quad k < m - 1 \\
\quad E, B \vdash \text{exp}_2 \Rightarrow \ell, B_a, W_a \\
\text{Node}(\kappa, [\text{id}_1 \mapsto \ell_1, \dots, \text{id}_{k-1} \mapsto \ell_{k-1}, \text{id}_k \mapsto \ell, \dots, \text{id}_m \mapsto \text{Unit}], [\text{id}'_1, \dots, \text{id}'_n], \eta) \\
\hline
E, B \vdash \text{exp}_1 \text{ exp}_2 \Rightarrow n, B_f \oplus B_a, W_f \oplus W_a
\end{array} \quad (\text{EAPPN1})$$

Rule EAPPN1 deals with the *partial* application of nodes. The value resulting from the evaluation of the arguments (which must be a graph location) is simply “pushed” on the list of supplied inputs.

$$\begin{array}{c}
E, B \vdash \text{exp}_1 \Rightarrow \text{Node}(\kappa, [\text{id}_1 \mapsto \ell_1, \dots, \text{id}_{m-1} \mapsto \ell_{m-1}, \text{id}_m \mapsto \text{Unit}], [\text{id}'_1, \dots, \text{id}'_n], \eta), B_f, W_f \\
\quad E, B \vdash \text{exp}_2 \Rightarrow \ell_m, B_a, W_a \\
\quad 1 \notin \text{Dom}(B) \\
\quad \forall j. 1 \leq j \leq m, \quad k_j \notin \text{Dom}(W), \quad w_j = \langle \ell_j, \text{Loc}(l, j) \rangle \\
\quad b = \text{Box}(\text{cat}(\kappa), [1 \mapsto k_1, \dots, m \mapsto k_m], [1 \mapsto \emptyset, \dots, n \mapsto \emptyset]) \\
\quad B' = [l \mapsto b] \\
\quad W' = [k_1 \mapsto w_1, \dots, k_m \mapsto w_m] \\
\quad v' = \langle \text{Loc}(l, 1), \dots, \text{Loc}(l, n) \rangle \\
\hline
E, B \vdash \text{exp}_1 \text{ exp}_2 \Rightarrow v', B_f \oplus B_a \oplus B', W_f \oplus W_a \oplus W'
\end{array} \quad (\text{EAPPN2})$$

Rule EAPPN2 deals with the complete application of nodes. It creates a new box and a set of wires connecting the parameters and arguments to the inputs of the inserted box (parameters first, then arguments). The outputs of the box will be connected by the binding step described in the next section. The function $\text{cat} : \text{NImpl} \rightarrow \text{BCat}$ is trivially defined as $\text{cat}(\text{actor}) = \text{actor}$ and $\text{cat}(\text{Graph}) = \text{graph}$.

3.5 Recursive definitions

There are two kinds of recursive definitions. The first case is when the defined value (resp. set of values in case of *mutually* recursive definitions) is a *function* (resp. set of functions). The second case is when the defined values (resp. set of values) denotes a *wire* in the graph (resp. set of wires). In the first case, the result is a circular closure (resp. set of mutually recursive closures). In the second case, the recursively defined values correspond to *cycles* in the network. These related rules are given in Sec. 3.5.1 and 3.5.2 respectively.

3.5.1 Recursive functions

$$\boxed{E, B \vdash_{\text{rec}} \text{pat}_1 = \text{exp}_1 \dots \text{pat}_n = \text{exp}_n \Rightarrow E', B', W}$$

$$\begin{array}{c}
\forall i. 1 \leq i \leq n, \quad \text{pat}_i = \text{id}_i, \quad \text{exp}_i = \mathbf{fun} \text{ pat}'_i \rightarrow \text{exp}'_i \\
\forall i. 1 \leq i \leq n, \quad E'_i = [\text{id}_i \mapsto \text{Clos}(\text{pat}'_i, \text{exp}'_i, E')] \\
\quad E' = \bigoplus_{i=1}^n E'_i \\
\hline
E, B \vdash_{\text{rec}} \text{pat}_1 = \text{exp}_1 \dots \text{pat}_n = \text{exp}_n \Rightarrow E', \emptyset, \emptyset
\end{array} \quad (\text{RECBINDINGSF})$$

3.5.2 Recursive wires

If the defined value is *not* a function, then the recursively defined values correspond to *cycles* in the network. Evaluation is then carried out as follows:

1. First, a pair of *recursive* value and box environments E_r and B_r are created by binding each identifier occurring in the LHS patterns, and not designating an output, to the location of a temporary, freshly created, box with the special tag *rec* :

$$\boxed{E, B \vdash_{rec} Pat \Rightarrow E_r, B_r}$$

$$\frac{\begin{array}{c} E(id) = \text{Loc}\langle l', s' \rangle \\ B(l') \neq \text{Box}\langle \text{snk}, \cdot, \cdot \rangle \\ l' \notin \text{Dom}(B) \\ b = \text{Box}\langle \text{rec}, [1 \mapsto 0], [1 \mapsto \emptyset] \rangle \end{array}}{E, B \vdash_{rec} id \Rightarrow [id \mapsto \text{Loc}\langle l, 0 \rangle], [l \mapsto b]} \quad (\text{RPATVAR})$$

$$\frac{\forall i. 1 \leq i \leq n, \vdash_{rec} pat_i \Rightarrow E_i, B_i}{\vdash_{rec} (pat_1, \dots, pat_n) \Rightarrow \bigoplus_{i=1}^n E_i, \bigoplus_{i=1}^n B_i} \quad (\text{RPATTUPLE})$$

2. Second, all the RHS expressions are evaluated in environments augmented with E_r and B_r , and the resulting values are bound, as in the non-recursive case, to the LHS patterns.
3. Third, the temporary *rec* boxes are removed from the resulting graph.

$$\frac{\begin{array}{c} \forall i. 1 \leq i \leq n, \exp_i \neq \mathbf{fun} \ pat'_i \rightarrow \exp'_i \\ \forall i. 1 \leq i \leq n, E, B \vdash_{rec} pat_i \Rightarrow E_i, B_i \\ E_r = \bigoplus_{i=1}^n E_i \quad B_r = \bigoplus_{i=1}^n B_i \\ \forall i. 1 \leq i \leq n, E \oplus E_r, B \oplus B_r \vdash \exp_i \Rightarrow v_i, B'_i, W'_i \\ B' = \bigoplus_{i=1}^n B'_i \quad W' = \bigoplus_{i=1}^n W'_i \\ \forall i. 1 \leq i \leq n, E \oplus E_r, B \oplus B_r \oplus B' \vdash_{pat} pat_i, v_i \Rightarrow E'_i, B''_i, W'''_i \\ E'' = \bigoplus_{i=1}^n E'_i \quad B'' = \bigoplus_{i=1}^n B''_i \quad W'' = \bigoplus_{i=1}^n W'''_i \\ \langle B''', W''' \rangle = \langle B'', W'' \rangle \ominus B_r \end{array}}{E, B \vdash_{rec} pat_1 = \exp_1 \dots pat_n = \exp_n \Rightarrow E', B'', W''} \quad (\text{RECBINDINGSV})$$

where \ominus , when applied to a graph, represented as a pair of box and wires environments, and a box environments, denotes the operation of removing all boxes occurring in the latter from the former, shortening the corresponding paths of wires accordingly.