A gentle introduction to the HoCL language

v I.I - Avr 2020 J. Sérot (jocelyn.serot@uca.fr)

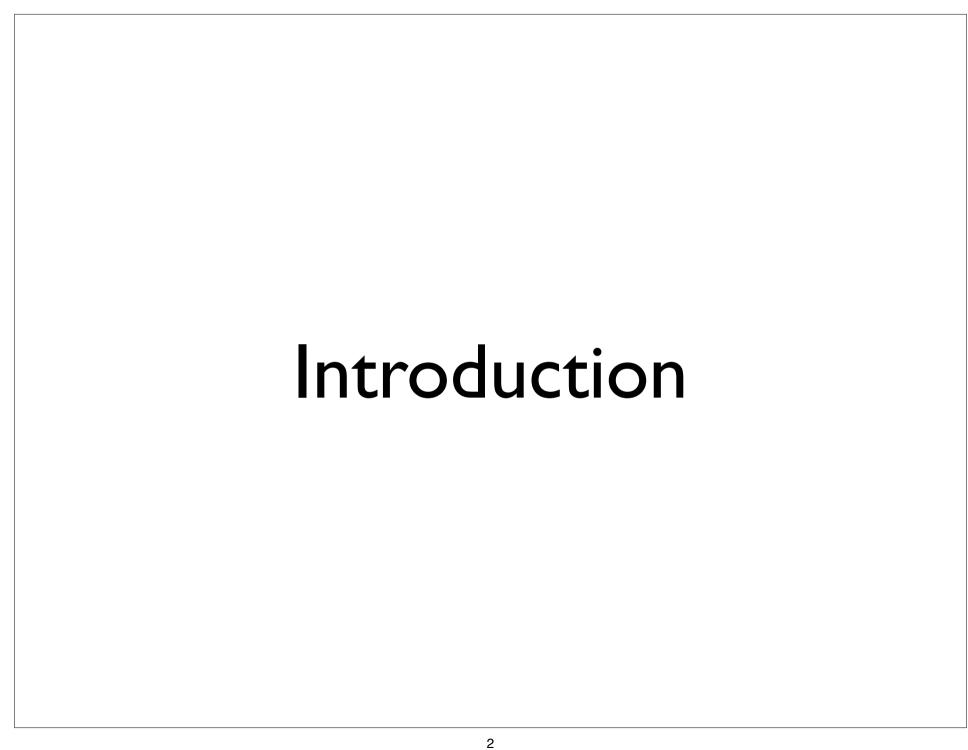
github.com/jserot/hocl









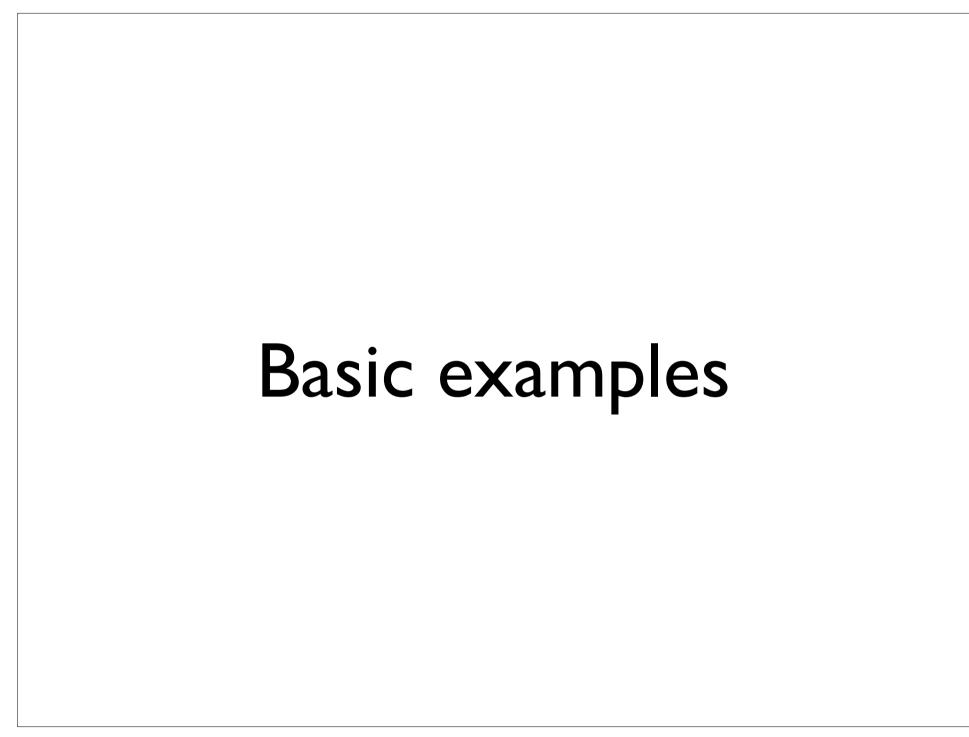


Motivations

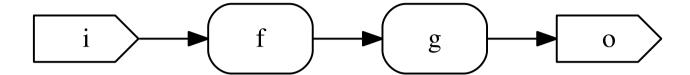
- HoCL = Higher-order Coordination Language
- Language for describing dataflow process networks
- Hierarchical and/or parameterized graphs
- Multi-style descriptions (structural or functional)
- Support of data flow variants (SDF, PSDF, ...) by means of annotations
- Independant of the target implementation platform (software, hardware, mixed, ...)
 - targeting done using dedicated backends (Preesm, DIF, XDF, SystemC, ...)

This document

- Informal presentation of the main language features
 - by means of small examples
- Introduce the main existing backends
 - DOT
 - SystemC
 - PREESM



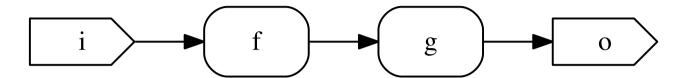
Example 1



```
node f
  in (i: int) out(o: int);
node q
  in (i: int) out(o: int);
graph top
  in (i: int)
 out (o: int)
struct
 wire w: int
  node n1: f(i)(w)
  node n2: g(w)(o)
end;
```

- This defines a graph top, with input i and output o.
- This graph is built from two nodes,
 n I and n2, linked by a wire w
- Nodes and wires are typed
- Each node is an instance of an actor (f and g resp.), here viewed as black boxes
- The graph *top* is here defined structurally

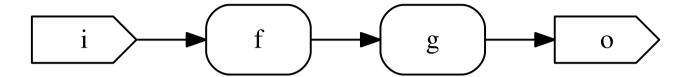
Example 1



```
node f
  in (i: int)
 out(o: int);
node q
  in (i: int)
 out(o: int);
graph top
  <u>in</u> (i: int)
 out (o: int)
fun
  val o = g (f i)
end;
```

- This is an alternative description of graph top using a functional style
- Nodes are interpreted as functions and the graph is described using function application
 - applying function f to value x (here denoted as f x) builds a node by instantiating actor f and connecting the wire representing the value x to its input
 - Function composition here corresponds to actor chaining

Example I



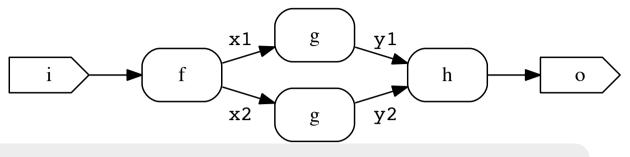
```
node f
 in (i: int)
 out(o: int);
node g
 in (i: int)
 out(o: int);
graph top
 in (i: int)
 out (o: int)
fun
 val o = i |> f |> g
end;
```

• Another functional formulation using the reverse application operator |>:

$$x > f = f x$$

Example 2

A slightly more complex graph



```
node f in (i: int) out (o1: int, o2:int);
node g in (i: int) out (o: int);
node h in (i1: int, i2:int) out (o:int);
```

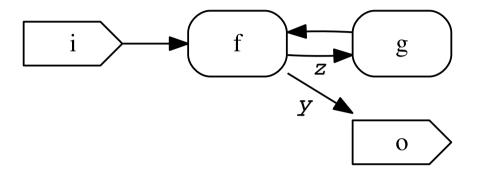
Structural description

```
graph top
  in (i: int)
  out (o: int)
struct
  wire x1,x2: int
  wire y1,y2: int
  node n1: f(i)(x1,x2)
  node n2: g(x1)(y1)
  node n3: g(x2)(y2)
  node n4: h(y1,y2)(o)
end;
```

Functional description

```
graph top
  in (i: int)
  out (o: int)
fun
  val (x1,x2) = f i
  val o = h (g x1, g x2)
end;
```

Cycles and recursive wiring



Functional description

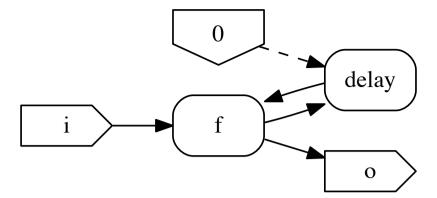
```
graph top
  in (i: int) out (o: int)
fun
  val rec (o,z) = f (i, g z)
end;
```

Structural description

```
graph top
  in (i: int) out (o: int)
struct
  wire w1, w2: int
  node n1: f(i,w1)(o,w2)
  node n2: g(w2)(w1)
end;
```

• Cycles in the graph are created using recursive definitions

Delayed cycles

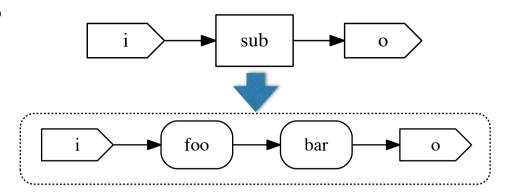


```
graph top
  in (i: int) out (o: int)
fun
  val rec (o,z) = f (i, delay 0 z)
end;
```

```
graph top
  in (i: int) out (o: int)
struct
  wire w1, w2: int
  node n1: f(i,w1)(o,w2)
  node n2: delay[0](w2)(w1)
end;
```

- Delays are required to avoid deadlock when **simulating** the graph (they provide the initial token(s) on the feedback edge(s)
- The special actor *delay* is predefined (and interpreted specifically by the various backends)
 - the actor parameter (0, here) specifies the initial value)
- Using type or application specific delay actors is also possible

Hierarchical graphs



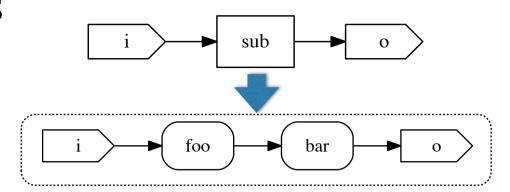
```
node foo in (i: t) out (o: t);
node bar in (e: t) out (s: t);

node sub in (i: t) out (o: t)
fun
  val o = i |> foo |> bar
end;

graph top in (i: t) out (o: t)
fun
  val o = i |> sub
end;
```

- Nodes can be described as (sub)graphs (either structurally or functionally), giving rise to hierarchical graphs
- Node with no description are interpreted as opaque actors (« blackboxes »)
- **Toplevel** graphs are identified with the *graph* keyword

Hierarchical graphs



```
node foo in (i: t) out (o: t);
node bar in (e: t) out (s: t);
node sub in (i: t) out (o: t)
struct
 wire w1, w2: t
 node n1: foo(i)(w1)
 node n2: bar(w1)(o)
end;
graph top in (i: t) out (o: t)
fun
 val o = i > sub
end;
```

 Within hierarchical descriptions, structural and functional definitions can be mixed freely

Parameters

```
node mult
  param (k: int)
  in (i: int) out(o: int);

graph top
  in (i: int) out (o: int)
fun
  val o = i |> mult 2
end;
```

```
mult
o

mult
o

mult
o

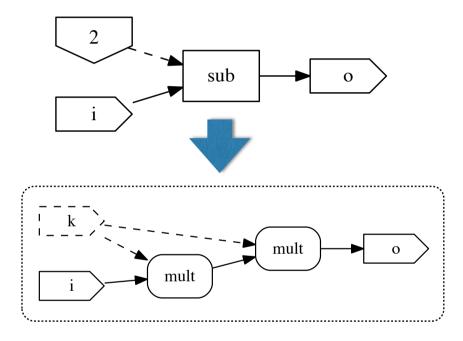
graph top
  in (i: int) out (o: int)
struct
  node n: mult[2](i)(o)
end;
```

- Parameters are used to configure nodes
- Their values are (now) limited to ints and bools
- In functional descriptions parameters are passed as initial arguments to the applied node (curried form)
 - this allows parameterized nodes to be described by partial application
- In structural descriptions, parameters are specified between [.]
- Parameter dependencies are drawn with dashes (---) by the dot backend
- The value of the k parameter for the mult node is here specified as a constant in the toplevel graph top

Parameter passing

```
node sub
  param (k: int)
  in (i: int) out (o: int)
fun
  val o =
    i |> mult k |> mult k
end;

graph top
  in (i: int) out (o: int)
fun
  val o = i |> sub 2
end;
```

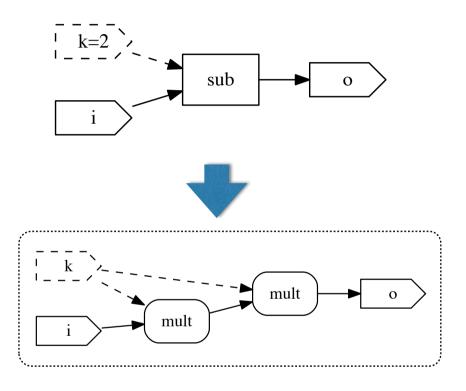


• Parameters can be passed from one hierarchy level to a nested one

Parameter passing

```
node sub
  param (k: int)
  in (i: int) out (o: int)
fun
  val o =
    i |> mult<k> |> mult<k>
end;

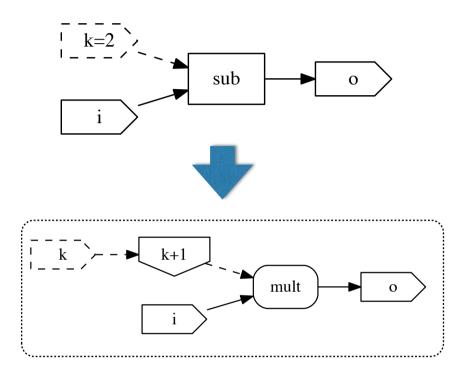
graph top
  param (k: int = 2)
  in (i: int) out (o: int)
fun
  val o = i |> sub k
end;
```



• The value of the toplevel parameters can be defined in the corresponding graph interface

Parameter dependencies

```
node sub
  param (k: int)
  in (i: int) out (o: int)
fun
  val o =
    i |> mult (k+1)
end;
graph top
  param (k: int = 2)
  in (i: int) out (o: int)
fun
 val o = i > sub k
end;
```



- The value of some parameters can depend on that of other parameters, defined at the same or at higher level(s) in the graph hierarchy
- Dependencies between parameter values create a tree in graph, which is "orthogonal" to the data flow

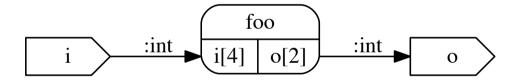
Dataflow modeling

- HoCL is a priori independent of the target execution model (SDF, CSDF, DDF, ...)
 - because the topology of the graph does not depend on this model
- Model-specific informations are passed to the backends using annotations
- Default annotations refer to production/consumption rates in (P)SDF

Example

```
node foo
   in (i: int[4])
   out (o: int[2]);

graph top
   in (i: int[4])
   out (o: int[2])
fun
   val o = i |> foo
end;
```



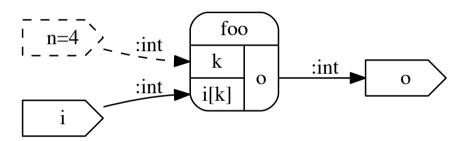
• The actor *foo* consumes 4 tokens (ints) and produces 2 tokens per activation

Dataflow modeling

 PSDF models are described/implemented by binding C/P rates to parameter values

Example

```
node foo
param (k: int)
    in (i: int[k])
   out (o: int[1]);
graph top
param (n: int = 3)
    in (i: int[n])
 out (o: int[1])
fun
 val o = i > foo n
end;
```

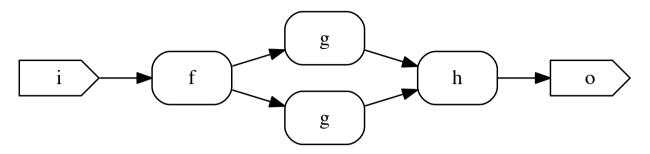


- The actor *foo* here consumes 3 tokens (ints) and produces I token per activation
- This can simply be changed by adjusting the value of the toplevel parameter *n*

Higher order features

... hence the name

Wiring functions

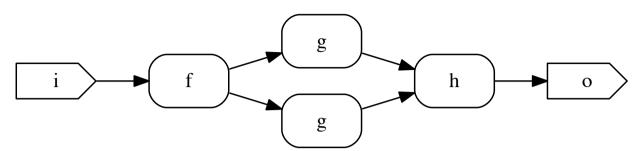


Another formulation:

```
graph top
  in (i: int)
  out (o: int)
fun
  val body x =
  let (x1,x2) = f x in
  h (g x1, g x2)
  val o = body i
end;
```

- body is a wiring function: it encapsulates the wiring pattern of the encoded graph
- The definition of body makes use of a local definition (let .. in)
- The top graph is built by simply applying this function
- Wiring functions can be defined within a (sub)graph (local scope) or globally

Higher order wiring functions

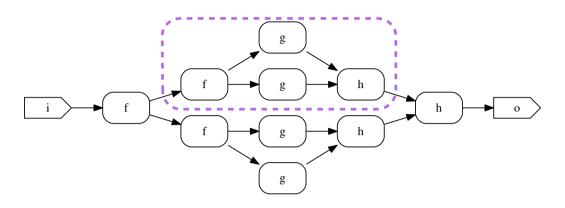


Pushing the abstraction a bit further:

```
graph top
  in (i: int)
  out (o: int)
fun
  val diamond left middle right x =
  let (x1,x2) = left x in
   right (middle x1, middle x2)
  val o = diamond f g h i
end;
```

- The diamond function abstracts further the definition of body, by taking as parameters the actors to be instantiated to build the defined graph
- The graph top is built by supplying the actual actors (f, g and h) as arguments to diamond.
- diamond is an higherorder wiring function (HOWF)

Higher order wiring functions



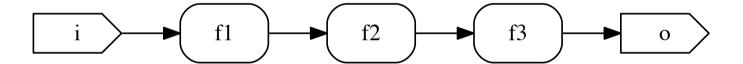
```
graph top
  in (i: int) out (o: int)
fun
  val diamond l m r x = ...
  val sub = diamond f g h
  val o = diamond f sub h i
end;
```

```
graph top
  in (i: int) out (o: int)
struct
 wire w1,w2,w3,w4,
       w5, w6, w7, w8,
       w9,w10,w11,w12:int
 node f1: f(i)(w1,w2)
 node f2: f(w1)(w3, w4)
  node f3: f(w2)(w5, w6)
  node q1: q(w3)(w7)
 node q2: q(w4)(w8)
  node q3: q(w5)(w9)
 node q4: q(w6)(w10)
 node h1: h(w7, w8)(w11)
 node h2: h(w9, w10)(w12)
  node h3: h(w11, w12)(0)
end;
```

- The diamond function is here instantiated at two levels :
 - within the sub function, to describe the « inner » diamond structure
 - within the definition of the output o, to build the toplevel graph structure

« Classic » higher order wiring functions

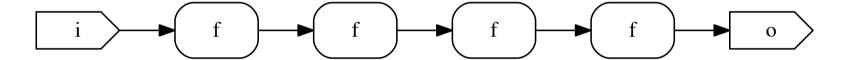
- Many recurrent graph patterns can be encapsulated using higher-order wiring functions
- Several of these functions are given in the HoCL standard library



```
graph top
  in (i: int)
  out (o: int)
fun
  val o = i |> pipe [f1;f2;f3]
end;
```

Classic higher order wiring functions

- Many recurrent graph patterns can be encapsulated using higher-order wiring functions
- Several of these functions are given in the HoCL standard library

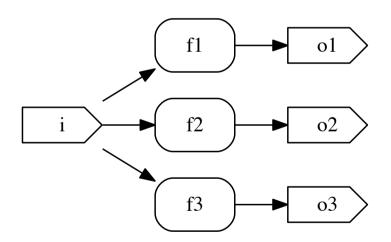


```
graph top
  in (i: int)
  out (o: int)
fun
  val o = i |> iter 4 f
end;
```

Classic higher order wiring functions

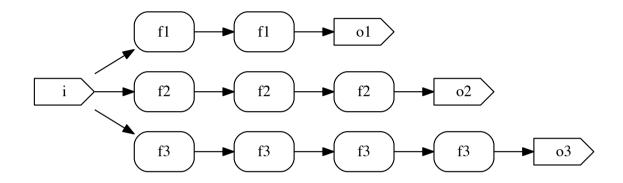
- Many recurrent graph patterns can be encapsulated using higher-order wiring functions
- Several of these functions are given in the HoCL standard library

```
graph top
  in (i:int)
  out (o1:int, o2:int, o3:int)
fun
  val (o1,o2,o3) =
   i |> mapf [f1;f2;f3]
end;
```

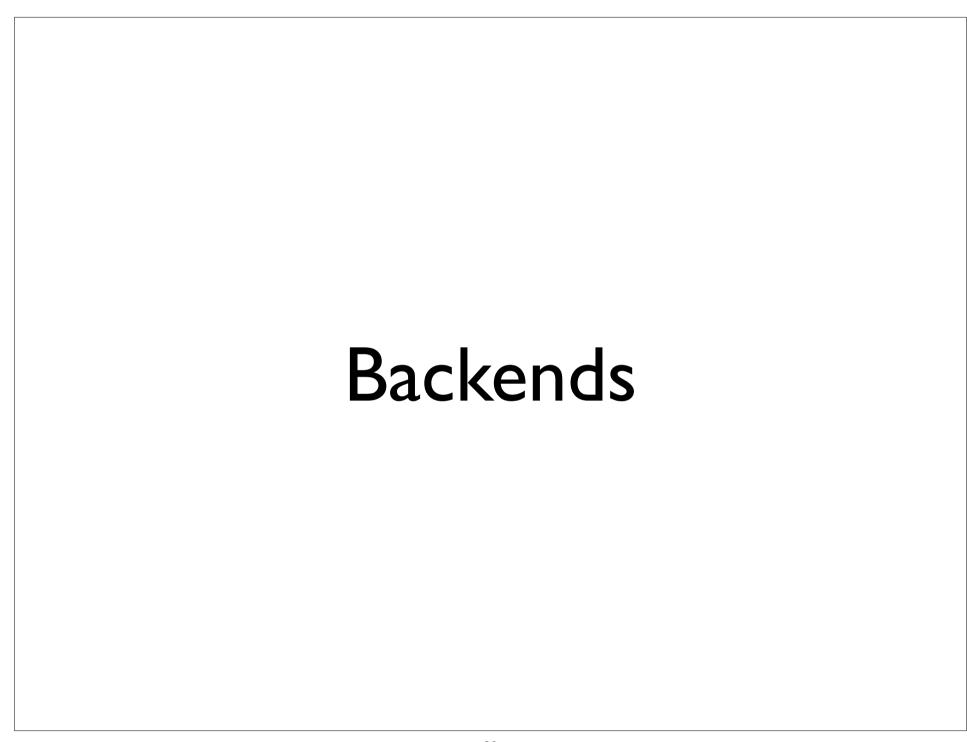


Classic higher order wiring functions

• HOWFs can be combined to describe complex structured graph patterns



```
graph top
  in (i:int)
  out (o1:int, o2:int, o3:int)
fun
  val (o1,o2,o3) =
    i |> mapf
    [iter 2 f1;
    iter 3 f2;
    iter 4 f3]
end;
```



Dot

- Used to generate graphical representations of the described DPNs
- One graph per toplevel entity (graph) and sub-network (node ... struct/fun)
- Many options to customize aspects
- No actor implementation required at this level

Example

```
node foo in (i: t) out (o: t);
node bar in (e: t) out (s: t);

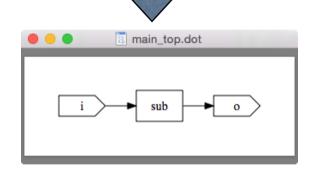
node sub in (i: t) out (o: t)
fun
  val o = i |> foo |> bar
end;

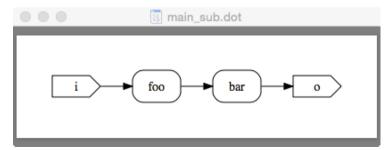
graph top in (i: t) out (o: t)
fun
  val o = i|> sub
end;

main.hcl
```



bash> hoclc -dot main.hcl
Wrote file ./main_top.dot
Wrote file ./main_sub.dot
bash> graphviz *.dot





SystemC

- Used to simulate the described DPNs
- Initialisation and per-activation code provided as external C functions
- Automatic generation of FIFOs, delay, broadcast and IO nodes (reading/writing files)

Example

```
node foo
  in (i: int) out (o: int)
actor
  systemc(
    loop_fn="foo",
    incl_file="foo.h",
    src_file="foo.cpp")
end;

graph top
  in (i: int) out (o: int)
fun
  val o = i |> foo
end;
  main.hcl
```

foo

:int

:int

```
foo.h
void foo(IN int *i, OUT int *o);
void foo(IN int *i, OUT int *o)
                                       foo.c
  \{ *o = *i * 2; \}
1 2 3 4 ...
                                     top_i.dat
bash > hoclc -systemc main.hcl
# Wrote file systemc/main top.cpp
# Wrote file systemc/top gph.h
# Wrote file systemc/foo act.h
# Wrote file systemc/foo act.cpp
 bash > cd ./systemc; make
2 4 6 8 ...
                                     top_o.dat
```

main.hcl node inp in () out(o: int) actor preesm(loop fn="inp", init fn="inpInit", incl file="input.h", src file="input.cpp") end; node foo param (k: int, p: int) in (i: int) out (o: int) actor preesm(loop fn="foo", incl file="foo.h", src file="foo.cpp") end; node outp param (p: int) in (i: int) out () actor preesm(loop fn="outp", init fn="outpInit", incl file="output.h", src file="output.cpp") end; graph top param (k:int=2, p:int=2) in () out () fun val $_$ = inp |-> foo (k,p) |> outp p end;

Preesm

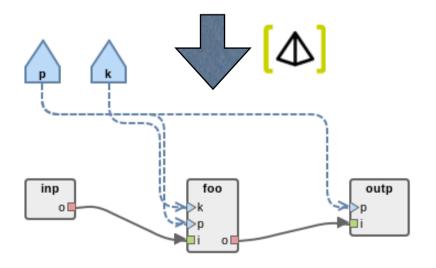
```
#include "preesm.h"
void foo(int k, IN int *i, OUT int *o);

#include "preesm.h"
void inpInit(void);
void inp(OUT int *o);

#include "preesm.h"
void outp(int p, IN int *i);
void outpInit(void);
output.h
```



bash> hoclc -preesm main.hcl
Wrote file ./main_top.pi

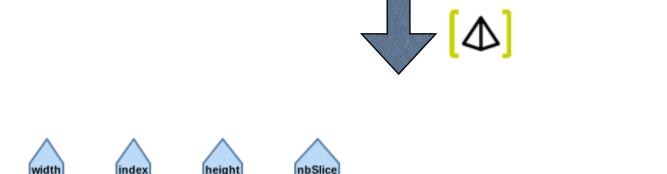


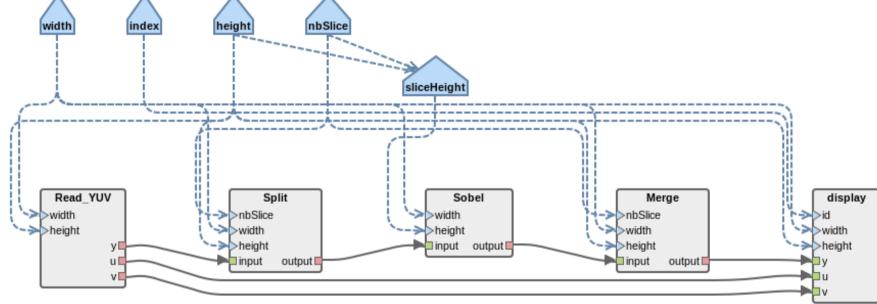
PREESM backend - A classical example

```
type uchar;
node ReadYUV
  param (width: int, height: int)
  in ()
  out (y: uchar[height*width],
       u: uchar[height/2*width/2],
       v: uchar[height/2*width/2])
actor
  systemc(loop fn="yuvRead",
    init fn="yuvReadInit",
    incl file="yuvRead.h",
    src file="yuvRead.c")
end;
node DisplayYUV
  param (id:int, width:int,
         height: int)
  in (y: uchar[height*width],
      u: uchar[height/2*width/2],
      v: uchar[height/2*width/2])
  out ()
actor
  systemc(loop fn="yuvDisplay",
   init fn="yuvDisplayInit",
   incl file="yuvDisplay.h",
   src file="yuvDisplay.c")
end;
```

```
node Sobel
  param (width:int, height:int)
  in (input: uchar[height*width])
  out (output: uchar[height*width])
actor
  systemc(loop fn="sobel",
   incl file="sobel.h",
   src file="sobel.c")
end;
graph main
  param (width:int=352, height:int=288,
         index:int=0)
 in () out ()
fun
 val(yi,u,v) =
   ReadYUV(width,height) ()
 val yo =
   yi |> Sobel(width, height)
 val =
   DisplayYUV(index,width,height) (yo,u,v)
end;
```

PREESM backend - A classical example





https://github.com/jserot/hocl/tree/master/examples/working/apps/sobel

Other backends

- DIF (Dataflow Interchange Format)
 - for interfacing to external dataflow analysis tools / writing specific code generators
- XDF
 - for interfacing to CAL-based design flows / writing specific code generators

- ✓ Open source and documented API (OCamI) for writing dedicated backends « from the inside »
 - gaining advantage of the compiler synthetized informations (types, annotations, ...)