HoCL semantics
v1.2

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Chapter 1

Abstract syntax

This is the abstract syntax used to formalize the typing rules and static semantics in chapters 2 an 3.

$\langle\text{program}\rangle$ ::= $\langle\text{type\_decl}\rangle^*$ $\langle\text{val\_decl}\rangle^*$ $\langle\text{node\_decl}\rangle^*$

$\langle\text{type\_decl}\rangle$ ::= **type** IDENT

$\langle\text{node\_decl}\rangle$ ::= **node** IDENT **(** $\langle\text{io\_decl}\rangle^*_,$ **)** **(** $\langle\text{io\_decl}\rangle^*_,$ **)** $[\langle\text{node\_impl}\rangle]$
      | **graph** IDENT **(** $\langle\text{io\_decl}\rangle^*_,$ **)** **(** $\langle\text{io\_decl}\rangle^*_,$ **)** $\langle\text{node\_impl}\rangle$

$\langle\text{io\_decl}\rangle$ ::= IDENT **:** $\langle\text{type\_expr}\rangle$ $[= \langle\text{const\_expr}\rangle]$

$\langle\text{node\_impl}\rangle$ ::= $\langle\text{val\_decl}\rangle^*$

$\langle\text{val\_decl}\rangle$ ::= **val** [**rec**] $\langle\text{binding}\rangle^+_{\textbf{and}}$

$\langle\text{binding}\rangle$ ::= $\langle\text{pattern}\rangle = \langle\text{expr}\rangle$

$\langle\text{pattern}\rangle$ ::= IDENT
      | **(** $\langle\text{pattern}\rangle^+_,$ **)**
      | **( )**

$\langle\text{expr}\rangle$ ::= $\langle\text{const\_expr}\rangle$
      | IDENT
      | $\langle\text{expr}\rangle$ $\langle\text{expr}\rangle$
      | **(** $\langle\text{expr}\rangle^+_,$ **)**
      | **fun** $\langle\text{funpat}\rangle \to \langle\text{expr}\rangle$
      | **let** [**rec**] $\langle\text{binding}\rangle^+_{\textbf{and}}$ **in** $\langle\text{expr}\rangle$
      | **( )**

$\langle\text{funpat}\rangle$ ::= IDENT

$\langle\text{const\_expr}\rangle$ ::= INT
      | **true**
      | **false**

$\langle\text{type\_expr}\rangle$ ::= IDENT $\langle\text{type\_expr}\rangle^*$

Chapter 2

Typing

The type language is fairly standard. A type τ is either :

- a type variable α

- a constructed type $\chi \langle \tau_1, \ldots, \tau_n \rangle$,

- a functional type $\tau_1 \to \tau_2$,

- a product type $\tau_1 \times \ldots \times \tau_n$,

Typing occurs in the context of a *typing environment* consisting of :

- a type environment TE, recording type constructors,

- a variable environment VE, mapping identifiers to types[1].

The initial type environment TE_0 records the type of the *builtin* type constructors :
$$\mathrm{TE}_0 \quad = \quad [\mathsf{int} \mapsto \mathsf{Int}, \quad \mathsf{bool} \mapsto \mathsf{Bool}, \quad \mathsf{param} \mapsto \tau \to \mathsf{Param}\ \tau, \quad \ldots]$$
The initial variable environment VE_0 contains the types of the builtin primitives :
$$\mathrm{VE}_0 \quad = \quad [+ \mapsto \mathsf{Int} \times \mathsf{Int} \to \mathsf{Int}, \quad = \mapsto \mathsf{Int} \times \mathsf{Int} \to \mathsf{Bool}, \quad \ldots]$$

2.1 Notations

Both type and variable *environments* are viewed as partial maps from identifiers to types and from type constructors to types respectively. If E is an environment, the domain of E is denoted by $\mathrm{dom}(E)$. The empty environment is written $\varnothing$. $[x \mapsto y]$ denotes the singleton environment mapping x to y and $E(x)$ the result of applying the underlying map to x (for ex. if E is $[x \mapsto y]$ then $E(x) = y$) and $E[x \mapsto y]$ the environment that maps x to y and behaves like E otherwise. $E \oplus E'$ denotes the environment obtained by adding the mappings of E' to those of E. If E and E' are not disjoints, then the mappings of E are "shadowed" by those of E'. Given two types τ and τ', we will note $\tau \simeq \tau'$ if τ and τ' are equal modulo unification[2].

For convenience and readability, we will adhere to the following naming conventions throughout this chapter :

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[1]More precisely, to *type schemes* $\sigma = \forall \alpha.\ \tau$; but, for simplicity, we do not distinguish types from type schemes in this presentation, *i.e.* the instanciation of a type scheme into a type and the generalisation of a (polymorphic) type into a type scheme are left implicit in the rules given above. The corresponding definitions are completely standard.

[2]For monotypes, this is structural equality.

Meta-variable	Meaning
TE	Type environment
VE	Variable environment
t	Type expression
τ	Type or type scheme
χ	Type constructor
id	Identifier
pat	Pattern
expr	Expression

Syntactical terminal symbols are written in **bold**. Non terminals in *italic*. Types values are written in serif.

2.2 Programs

$$\boxed{\vdash \text{Program} \Rightarrow \text{VE}'}$$

$$
\frac{
\begin{array}{c}
\text{TE}_0 \vdash \textit{typedecls} \Rightarrow \text{TE}' \\
\text{TE}_0 \oplus \text{TE}', \text{VE}_0 \vdash \textit{valdecls} \Rightarrow \text{VE}' \\
\text{TE}_0 \oplus \text{TE}', \text{VE}' \vdash \textit{nodedecls} \Rightarrow \text{VE}
\end{array}
}{
\text{TE}_0, \text{VE}_0 \vdash \textbf{program } \textit{typedecls valdecls nodedecls} \Rightarrow \text{VE}
} \quad (\textsc{Program})
$$

Typing a program consists in

- typing the type declarations, resulting in an augmented type environment,

- typing the global value declarations, resulting in an augmented value environment,

- typing the sequence of node declarations in these augmented environments.

The result is an environment containing the type of each declared node.

2.3 Type declarations

$$\boxed{\text{TE} \vdash \text{TypeDecls} \Rightarrow \text{TE}'}$$

$$
\frac{
\forall i.\ 1 \leq i \leq n, \quad \text{TE} \vdash \textit{typedecl}_i \Rightarrow \text{TE}_i
}{
\text{TE}, \text{VE} \vdash \textit{typedecl}_1 \ \ldots \ \textit{typedecl}_n \Rightarrow \bigoplus_{i=1}^{n} \text{TE}_i
} \quad (\textsc{TypeDecls})
$$

$$\boxed{\text{TE} \vdash \text{TypeDecl} \Rightarrow \text{TE}'}$$

$$
\frac{}{
\text{TE}, \text{VE} \vdash \textbf{type } \text{id} \Rightarrow [\text{id} \mapsto 0]
} \quad (\textsc{TypeDecl})
$$

An abstract type declaration simply adds the corresponding type constructor in the type environment.

2.4 Node declarations

$$\boxed{\text{TE}, \text{VE} \vdash \text{NodeDecls} \Rightarrow \text{VE}'}$$

$$
\frac{
\begin{array}{c}
\text{VE}_0 = \text{VE} \\
\forall i.\ 1 \leq i \leq n, \quad \text{TE}, \text{VE}_{i-1} \vdash \mathit{nodedecl}_i \Rightarrow \text{VE}_i
\end{array}
}{
\text{TE}, \text{VE} \vdash \mathit{nodedecl}_1 \ \ldots \ \mathit{nodedecl}_n \Rightarrow \text{VE}_n
}
\quad (\textsc{NodeDecls})
$$

Node declarations are typed in the order of their declaration. A declaration can be used in the subsequent ones.

$$\boxed{\text{TE}, \text{VE} \vdash \text{NodeDecl} \Rightarrow \text{VE}'}$$

$$
\frac{
\begin{array}{c}
\forall i.\ 1 \leq i \leq m, \quad \text{TE} \vdash \text{t}_i \Rightarrow \tau_i \\
\forall i.\ 1 \leq i \leq n, \quad \text{TE} \vdash \text{t'}_i \Rightarrow \tau'_i \\
\tau = \tau_1 \to \ldots \to \tau_m \to \tau'_1 \times \ldots \times \tau'_n
\end{array}
}{
\text{TE}, \text{VE} \vdash \textbf{node}\ \text{id}\ (\text{id}_1 : \text{t}_1, \ldots, \text{id}_m : \text{t}_m)\ (\text{id'}_1 : \text{t'}_1, \ldots, \text{id'}_n : \text{t'}_n) \ \Rightarrow \text{VE} \oplus [\text{id} \mapsto \tau]
}
\quad (\textsc{NodeDecl1})
$$

At the type level, an *opaque* node (actor) declared as

$$\textbf{node}\ \text{name}\ \textbf{in}\ (\text{i}_1{:}\text{t}_1, \ldots, \text{i}_m{:}\text{t}_m)\ \textbf{outs}\ (\text{o}_1{:}\text{t}'_1, \ldots, \text{o}_n{:}\text{t}'_n)$$

is viewed as a function having type

$$\tau_1 \to \ldots \tau_m \to \tau'_1 \times \ldots \times \tau'_n$$

i.e. as a function taking m arguments in curried form (one after the other) and returning its n results as a tuple[3].

$$
\frac{
\begin{array}{c}
\forall i.\ 1 \leq i \leq m, \quad \text{TE} \vdash \text{t}_i \Rightarrow \tau_i \\
\forall i.\ 1 \leq i \leq n, \quad \text{TE} \vdash \text{t'}_i \Rightarrow \tau'_i \\
\text{TE}, \text{VE} \bigoplus_{i=1}^{m} [\text{id}_i \mapsto \tau_i] \vdash \mathit{valdecls} \Rightarrow \text{VE}' \\
\forall i.\ 1 \leq i \leq n, \quad \text{TE} \vdash \tau'_i \simeq \text{VE}'(\text{id}'_i) \\
\tau = \tau_1 \to \ldots \to \tau_m \to \tau'_1 \times \ldots \times \tau'_n
\end{array}
}{
\text{TE}, \text{VE} \vdash \textbf{node}\ \text{id}\ (\text{id}_1 : \text{t}_1, \ldots, \text{id}_m : \text{t}_m)\ (\text{id'}_1 : \text{t'}_1, \ldots, \text{id'}_n : \text{t'}_n)\ \mathit{valdecls} \Rightarrow \text{VE} \oplus [\text{id} \mapsto \tau]
}
$$
$$(\textsc{NodeDecl2})$$

For "tranparent" nodes, *i.e.* nodes defined by a set of value declarations, we also check that the type assigned to outputs by these declarations are compatible with the type assigned to the corresponding node output.

2.5 Graph declarations

Graph declarations are handled exactly as node declarations except that the value optionally attached to inputs is type checked against the declared type[4] and that graph declarations always have a *valdecls* section (there's no such thing as an opaque graph declaration).

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[3]In OCAML for example, such a function could have been defined like : `let f x1 ...  xm = (e1, ..., en)`.

[4]Strictly speacking, such values can only be attached to inputs declared as *parameters* (*i.e.* with type `t param`). This distinction is omitted here for brevity.

$$\boxed{\text{TE}, \text{VE} \; \vdash \text{GraphDecl} \Rightarrow \text{VE}'}$$

$$
\begin{array}{c}
\forall i.\; 1 \le i \le m, \quad \text{TE} \vdash \text{t}_i \Rightarrow \tau_i \\
\forall i.\; 1 \le i \le m, \quad \text{TE}, \varnothing \vdash e_i \Rightarrow \tau_i'' \\
\forall i.\; 1 \le i \le m, \tau_i \simeq \tau_i'' \\
\forall i.\; 1 \le i \le n, \quad \text{TE} \vdash \text{t'}_i \Rightarrow \tau_i' \\
\text{TE}, \text{VE} \bigoplus_{i=1}^{m} [\text{id}_i \mapsto \tau_i] \vdash \textit{valdecls} \Rightarrow \text{VE}' \\
\forall i.\; 1 \le i \le n, \quad \text{TE} \vdash \tau_i' \simeq \text{VE}'(\text{id}_i') \\
\tau = \tau_1 \to \ldots \to \tau_m \to \tau_1' \times \ldots \times \tau_n' \\
\hline
\text{TE}, \text{VE} \; \vdash \textbf{graph} \; \text{id} \; (\text{id}_1 : \text{t}_1 = \text{e}_1, \ldots, \text{id}_m : \text{t}_m = \text{e}_m) \; (\text{id'}_1 : \text{t'}_1, \ldots, \text{id'}_n : \text{t'}_n) \; \textit{valdecls} \Rightarrow \text{VE} \oplus [\text{id} \mapsto \tau]
\end{array}
$$
$$(\textsc{GraphDecl})$$

2.6 Value declarations

$$\boxed{\text{TE}, \text{VE} \; \vdash \text{ValDecls} \Rightarrow \text{VE}'}$$

$$
\begin{array}{c}
\text{VE}_0 = \text{VE} \\
\forall i.\; 1 \le i \le n, \quad \text{TE}, \text{VE}_{i-1} \vdash \textit{valdecl}_i \Rightarrow \text{VE}_i \\
\hline
\text{TE}, \text{VE} \; \vdash \textit{valdecl}_1 \; \ldots \; \textit{valdecl}_n \Rightarrow \text{VE}_n
\end{array}
\qquad (\textsc{ValDecls})
$$

$$\boxed{\text{TE}, \text{VE} \; \vdash \text{ValDecl} \Rightarrow \text{VE}'}$$

$$
\frac{\text{TE}, \text{VE} \vdash \textit{pat}_1 = \textit{expr}_1 \; \ldots \; \textit{pat}_n = \textit{expr}_n \Rightarrow \text{VE}'}{\text{TE}, \text{VE} \vdash \textbf{val} \; \textit{pat}_1 = \textit{expr}_1 \; \ldots \; \textit{pat}_n = \textit{expr}_n \; \Rightarrow \text{VE} \oplus \text{VE}'}
\qquad (\textsc{ValDecl})
$$

$$\boxed{\text{TE}, \text{VE} \; \vdash_r \text{ValDecl} \Rightarrow \text{VE}'}$$

$$
\frac{\text{TE}, \text{VE} \vdash_r \textit{pat}_1 = \textit{expr}_1 \; \ldots \; \textit{pat}_n = \textit{expr}_n \Rightarrow \text{VE}'}{\text{TE}, \text{VE} \vdash \textbf{val rec} \; \textit{pat}_1 = \textit{expr}_1 \; \ldots \; \textit{pat}_n = \textit{expr}_n \; \Rightarrow \text{VE} \oplus \text{VE}'}
\qquad (\textsc{RecValDecl})
$$

$$\boxed{\text{TE}, \text{VE} \; \vdash \text{PatExprs} \Rightarrow \text{VE}'}$$

$$
\begin{array}{c}
\forall i.\; 1 \le i \le n, \quad \text{TE}, \text{VE} \vdash \textit{pat}_i = \textit{expr}_i \Rightarrow \text{VE}_i' \\
\text{VE}' = \bigoplus_{i=1}^{n} \text{VE}_i' \\
\hline
\text{TE}, \text{VE} \vdash \textit{pat}_1 = \textit{expr}_1 \; \ldots \; \textit{pat}_n = \textit{expr}_n \; \Rightarrow \text{VE}'
\end{array}
\qquad (\textsc{Bindings})
$$

The rule Bindings deals with multiple bindings, as found in `val p1=e1 and ... and pn=en` declarations or `let p1=e1 and ... and pn=en` expressions.

$$\boxed{\text{TE}, \text{VE} \vdash_r \text{PatExprs} \Rightarrow \text{VE}'}$$

$$\frac{\forall i.\ 1 \le i \le n, \quad \text{TE}, \text{VE} \oplus \text{VE}' \vdash pat_i = expr_i \Rightarrow \text{VE}'_i \\ \text{VE}' = \bigoplus_{i=1}^{n} \text{VE}'_i}{\text{TE}, \text{VE} \vdash_r pat_1 = expr_1 \ \ldots\ pat_n = expr_n \Rightarrow \text{VE}'} \quad (\textsc{RecBindings})$$

The rule RecBindings deals with multiple recursive bindings. Note that in this case, the recursively defined symbols are available when typing the RHS expressions.

$$\boxed{\text{TE}, \text{VE} \vdash \text{Pat=Expr} \Rightarrow \text{VE}'}$$

$$\frac{\text{TE}, \text{VE} \vdash expr \Rightarrow \tau \\ \vdash_p pat, \tau \Rightarrow \text{VE}'}{\text{TE}, \text{VE} \vdash pat = expr \Rightarrow \text{VE}'} \quad (\textsc{Binding})$$

where

$$\vdash_p pat, \tau \Rightarrow \text{VE}$$

means that declaring *pat* with type τ creates the variable environment VE, as described in Sec. 2.6.1.

2.6.1 Patterns

$$\boxed{\vdash_p \text{Pat}, \tau \Rightarrow \text{VE}}$$

$$\frac{}{\vdash_p \text{id}, \tau \Rightarrow [\text{id} \mapsto \tau]} \quad (\textsc{PatVar})$$

$$\frac{\forall i.\ 1 \le i \le n, \quad \vdash_p pat_i, \tau_i \Rightarrow \text{VE}_i}{\vdash_p (pat_1, \ldots pat_n), \tau_1 \times \ldots \times \tau_n \Rightarrow \bigoplus_{i=1}^{n} \text{VE}_i} \quad (\textsc{PatTuple})$$

$$\frac{}{\vdash_p (), \textsf{Unit} \Rightarrow \varnothing} \quad (\textsc{PatUnit})$$

$$\frac{}{\vdash_p \_, \tau \Rightarrow \varnothing} \quad (\textsc{PatIgnore})$$

2.6.2 Expressions

$$\boxed{\text{TE}, \text{VE} \vdash \text{Expr} \Rightarrow \tau}$$

$$\frac{\text{VE}(id) = \tau}{\text{TE}, \text{VE} \vdash \text{id} \Rightarrow \tau} \quad (\textsc{EVar})$$

$$\frac{\forall i.\ 1 \le i \le n, \quad \text{TE}, \text{VE} \vdash expr_i \Rightarrow \tau_i}{\text{TE}, \text{VE} \vdash (expr_1, \ldots expr_n) \Rightarrow \tau_1 \times \ldots \times \tau_n} \quad (\textsc{ETuple})$$

$$\frac{\begin{array}{c} \text{TE}, \text{VE} \vdash expr_1 \Rightarrow \tau \rightarrow \tau' \\ \text{TE}, \text{VE} \vdash expr_2 \Rightarrow \tau \end{array}}{\text{TE}, \text{VE} \vdash expr_1 \ expr_2 \Rightarrow \tau'} \quad \text{(EApp)}$$

$$\frac{\vdash_p pat, \tau \Rightarrow \text{VE}' \qquad \text{TE}, \text{VE} \oplus \text{VE}' \vdash expr \Rightarrow \tau'}{\text{TE}, \text{VE} \vdash \textbf{fun} \ pat \rightarrow expr \Rightarrow \tau \rightarrow \tau'} \quad \text{(EFun)}$$

$$\frac{\begin{array}{c} \text{TE}, \text{VE} \vdash pat_1 = expr_1 \ \ldots \ pat_n = expr_n \Rightarrow \text{VE}' \\ \text{TE}, \text{VE} \oplus \text{VE}' \vdash expr' \Rightarrow \tau \end{array}}{\text{TE}, \text{VE} \vdash \textbf{let} \ pat_1 = expr_1 \ \ldots \ pat_n = expr_n \ \textbf{in} \ expr' \Rightarrow \tau} \quad \text{(ELet)}$$

$$\frac{\begin{array}{c} \text{TE}, \text{VE} \vdash_r pat_1 = expr_1 \ \ldots \ pat_n = expr_n \Rightarrow \text{VE}' \\ \text{TE}, \text{VE} \oplus \text{VE}' \vdash expr' \Rightarrow \tau \end{array}}{\text{TE}, \text{VE} \vdash \textbf{let rec} \ pat_1 = expr_1 \ \ldots \ pat_n = expr_n \ \textbf{in} \ expr' \Rightarrow \tau} \quad \text{(ELetRec)}$$

$$\frac{}{\text{TE}, \text{VE} \vdash () \Rightarrow \mathsf{Unit}} \quad \text{(EUnit)}$$

$$\frac{}{\text{TE}, \text{VE} \vdash \text{int} \Rightarrow \mathsf{Int}} \quad \text{(EInt)}$$

$$\frac{}{\text{TE}, \text{VE} \vdash \text{bool} \Rightarrow \mathsf{Bool}} \quad \text{(EBool)}$$

$$\frac{\begin{array}{c} \text{VE}(\text{op}) = \tau_1 \times \tau_2 \rightarrow \tau_3 \\ \text{TE}, \text{VE} \vdash expr_1 \Rightarrow \tau_1 \\ \text{TE}, \text{VE} \vdash expr_2 \Rightarrow \tau_2 \end{array}}{\text{TE}, \text{VE} \vdash expr_1 \ \text{op} \ expr_2 \Rightarrow \tau_3} \quad \text{(EBinop)}$$

$$\frac{\begin{array}{c} \text{TE}, \text{VE} \vdash expr \Rightarrow \mathsf{Bool} \\ \text{TE}, \text{VE} \vdash expr_1 \Rightarrow \tau \\ \text{TE}, \text{VE} \vdash expr_2 \Rightarrow \tau \end{array}}{\text{TE}, \text{VE} \vdash \textbf{if} \ expr \ \textbf{then} \ expr_1 \ \textbf{else} \ expr_2 \Rightarrow \tau} \quad \text{(EIf)}$$

2.7 Type expressions

$$\boxed{\text{TE} \ \vdash \mathsf{t} \Rightarrow \tau}$$

$$\frac{\text{TE}(\chi) = \tau}{\text{TE} \vdash \chi \Rightarrow \tau} \quad \text{(TyCon0)}$$

$$\frac{\begin{array}{c} \text{TE}(\chi) = \tau_1 \rightarrow \ldots \rightarrow \tau_n \rightarrow \tau \\ \forall i.\ 1 \leq i \leq n, \ \ \text{TE} \vdash \mathsf{t}_i \Rightarrow \tau_i \end{array}}{\text{TE} \vdash \chi \ \langle \mathsf{t}_1, \ldots, \mathsf{t}_n \rangle \Rightarrow \tau} \quad \text{(TyCon1)}$$

Chapter 3

Static semantics

The static semantics gives the interpretation of HoCL programs, described with the abstract syntax given in chapter 1, as a set of (dataflow) *graphs*, where each graph is defined as a set of *boxes* connected by *wires*. The formulation given here assumes that the program has been successfully type checked.

The static semantics is built upon the semantic domain given below.

Variable	Set ranged over	Definition	Meaning
v	Val	$\mathsf{Loc} + \mathsf{Node} + \mathsf{Tuple} + \mathsf{Clos}$	Value
		$\mathsf{Unit} + \mathsf{Int} + \mathsf{Bool} + \mathsf{Prim}$	
ℓ	Loc	$\langle \mathsf{bid}, \mathsf{sel} \rangle$	Graph location
n	Node	$\langle \mathsf{NCat}, \{\mathsf{id} \mapsto \mathsf{Val}\}, \{\mathsf{id}\}, \mathsf{NImpl} \rangle$	Node description
κ	NCat	$\mathsf{node} + \mathsf{graph}$	Node category
vs	Tuple	Val^+	Tuple
cl	Clos	$\langle \textit{pattern}, \textit{expr}, \mathsf{Env} \rangle$	Closure
E	Env	$\{\mathsf{id} \mapsto \mathsf{Val}\}$	Value environment
η	NImpl	$\mathsf{actor} + \mathsf{Graph}$	Node implementation
g	Graph	$\langle \mathsf{Boxes}, \mathsf{Wires} \rangle$	Graph description
B	Boxes	$\{\mathsf{bid} \mapsto \mathsf{Box}\}$	Box environment
W	Wires	$\{\mathsf{wid} \mapsto \mathsf{Wire}\}$	Wire environment
L	Locs	Loc^*	Location set
b	Box	$\langle \mathsf{BCat}, \{\mathsf{sel} \mapsto \mathsf{wid}\}, \{\mathsf{sel} \mapsto \mathsf{wid}^*\}, \mathsf{Val} \rangle$	Box
c	BCat	$\mathsf{actor} + \mathsf{graph} + \mathsf{src} + \mathsf{snk} + \mathsf{rec}$	Box category
		$\mathsf{inParam} + \mathsf{localParam}$	
w	Wire	$\langle \langle \mathsf{bid}, \mathsf{sel} \rangle, \langle \mathsf{bid}, \mathsf{sel} \rangle \rangle$	Wire (src loc, dst loc)
l, l'	bid	$\{0, 1, 2, \dots\}$	Box id
k, k'	wid	$\{0, 1, 2, \dots\}$	Wire id
s, s'	sel	$\{0, 1, 2, \dots\}$	Slot selector
	Int	$\{\dots, -2, -1, 0, 1, \dots\}$	Integer value
β	Bool	$\{\mathsf{true}, \mathsf{false}\}$	Boolean value
π	Prim	$\{\mathsf{Value} \mapsto \mathsf{Value}\}$	Primitive function

Values in the category Loc correspond to graph *locations*, where a location comprises a box index and and a selector. Selectors are used to distinguish inputs (resp. outputs when the box has several of them[1].

---

[1]Valid selectors start at 1. The selector value 0 is used for incomplete box definitions.

Nodes are described by

- a category, indicating whether the node is a toplevel graph or an ordinary node[2],

- a list of inputs, each with an attached value[3],

- a list of outputs,

- an implementation, which is either empty (in case of opaque actors) or given as a graph.

Boxes are described by

- a category,

- a input environment, mapping selector values (1,2,...) to wire identifiers,

- a output environment, mapping selector values to sets of wire identifiers[4],

- an optional value.

Box categories separate boxes

- resulting from the instanciation of a node,

- materializing graph inputs and outputs,

- materializing graph input parameters,

- materializing graph local parameters.

The category rec is used internally for building cyclic graphs (see Sec. **??**).

The optional box value is only meaningful for local parameters bound to constants or for toplevel input parameters (giving in this case the constant value).

Wires are pairs of graph locations : one for the source box and the other for the destination box.

Closures correspond to functional values.

Primitives correspond to builtin functions operating on integer or boolean values (+, =, ...).

The environments E, B and W respectively bind

- identifiers to semantic values,

- box indices to box description,

- wire indices to wire description.

All *environments* are viewed as partial maps from keys to values. If E is an environment, the domain of E is denoted by $\text{dom}(E)$. The empty environment is written $\varnothing$. $[x \mapsto y]$ denotes the singleton environment mapping x to y. $E(x)$ denotes the result of applying the underlying map to x (for ex. if E is $[x \mapsto y]$ then $E(x) = y$) and $E \oplus E'$ the environment obtained by adding the mappings of E' to those of E, assuming that E and E' are disjoints.

---

[2]This avoids having two distincts but almost identical semantic values for nodes and toplevel graphs.
[3]These values are used to handle partial application.
[4]A box output can be broadcasted to several other boxes.

3.1 Programs

$$\boxed{\vdash \text{Program} \Rightarrow \text{E}}$$

$$\frac{\begin{array}{c} \text{E}_0, \varnothing \vdash \textit{valdecls} \Rightarrow \text{E}, \text{B}, \text{W} \\ \text{E}, \varnothing \vdash \textit{nodedecls} \Rightarrow \text{E}' \end{array}}{\vdash \textbf{program } \textit{typedecls valdecls nodedecls} \Rightarrow \text{E}'} \quad (\text{Program})$$

Global values are first evaluated to give a value environment (boxes and wires resulting from this evaluation are here ignored). Nodes declarations are evaluated in this environment. The result is an environment associating a node description to each defined node.

The initial environment E_0 contains, the value of the builtin primitives (+, =, . . .).

3.2 Node and graph declarations

$$\boxed{\text{E}, \text{B} \vdash \text{NodeDecls} \Rightarrow \text{E}', \text{B}'}$$

$$\frac{\begin{array}{c} \text{E}_0 = \text{E} \\ \text{B}_0 = \text{B} \\ \forall i.\ 1 \le i \le n, \quad \text{E}_{i-1}, \text{B}_{i-1} \vdash \textit{nodedecl}_i \Rightarrow \text{E}_i, \text{B}_i \end{array}}{\text{E}, \text{B} \vdash \textit{nodedecl}_1\ \ldots\ \textit{nodedecl}_n \Rightarrow \text{E}_n, \text{B}_n} \quad (\text{NodeDecls})$$

Node declarations are interpreted in the order of their declaration. A declaration can be used in the subsequent ones.

$$\boxed{\text{E}, \text{B} \vdash \text{NodeDecl} \Rightarrow \text{E}', \text{B}'}$$

$$\frac{\mathsf{n} = \mathsf{Node}\langle \mathsf{node}, [\mathrm{id}_1 \mapsto \mathsf{Unit}, \ldots, \mathrm{id}_m \mapsto \mathsf{Unit}], [\mathrm{id}'_1, \ldots, \mathrm{id}'_n], \mathsf{actor}\rangle}{\text{E}, \text{B} \vdash \textbf{node } \mathrm{id}\ (\mathrm{id}_1 : \mathrm{t}_1, \ldots, \mathrm{id}_m : \mathrm{t}_m)\ (\mathrm{id}'_1 : \mathrm{t}'_1, \ldots, \mathrm{id}'_n : \mathrm{t}'_n)\ \Rightarrow \text{E} \oplus [\mathrm{id} \mapsto n], \text{B}} \ (\text{NodeDecl1})$$

Nodes with no attached definition are mapped to opaque actors. The Unit value initially attached to inputs here means "yet unconnected"). Types are ignored at this level.

$$\frac{\begin{array}{c} \text{B} \vdash_i (\mathrm{id}_1 : \mathrm{t}_1, \ldots, \mathrm{id}_m : \mathrm{t}_m) \Rightarrow \text{E}_i, \text{B}_i \\ \text{B}_i \vdash_o (\mathrm{id}'_1 : \mathrm{t}'_1, \ldots, \mathrm{id}'_n : \mathrm{t}'_n) \Rightarrow \text{E}_o, \text{B}_o \\ \text{E} \oplus \text{E}_i \oplus \text{E}_o,\ \text{B} \oplus \text{B}_i \oplus \text{B}_o \vdash \textit{valdecls} \Rightarrow \text{B}',\ \text{W}' \\ \mathsf{n} = \mathsf{Node}\langle \mathsf{node}, [\mathrm{id}_1 \mapsto \mathsf{Unit}, \ldots, \mathrm{id}_m \mapsto \mathsf{Unit}], \mathsf{outs}, \mathsf{Graph}\langle \text{B}', \text{W}'\rangle\rangle \end{array}}{\text{E}, \text{B} \vdash \textbf{node } \mathrm{id}\ (\mathrm{id}_1 : \mathrm{t}_1, \ldots, \mathrm{id}_m : \mathrm{t}_m)\ (\mathrm{id}'_1 : \mathrm{t}'_1, \ldots, \mathrm{id}'_n : \mathrm{t}'_n)\ \textit{valdecls} \Rightarrow \text{E} \oplus [\mathrm{id} \mapsto \mathsf{n}], \text{B} \oplus \text{B}_i \oplus \text{B}_o}$$
$$(\text{NodeDecl2})$$

For nodes with an attached definition, this definition is evaluated in an environment augmented with its input and output declarations, and the resulting graph (a pair of boxes and wires) is attached to the node description.

$$\boxed{B \vdash_{i/o} \text{NodeIOs} \Rightarrow E, B'}$$

$$
\frac{\begin{array}{c} B_0 = B \\ \forall j.\ 1 \le j \le n, \quad B_{j-1} \vdash_{i/o} \text{id}_j : t_j \Rightarrow E_j, B_j \end{array}}{B \vdash_{i/o} (\text{id}_1 : t_1, \dots, \text{id}_n : t_n) \Rightarrow \bigoplus_{j=1}^{n} E_j,\ B_n} \quad \text{(NodeIOs)}
$$

$$\boxed{B \vdash_{i/o} \text{NodeIO} \Rightarrow E, B'}$$

$$
\frac{l \notin Dom(B)}{B \vdash_i \text{id} : t \Rightarrow [\text{id} \mapsto \mathsf{Loc}\langle l, 0 \rangle],\ B \oplus [l \mapsto \mathsf{Box}\langle \mathsf{src}, \varnothing, [1 \mapsto \varnothing] \rangle]} \quad \text{(NodeInp)}
$$

$$
\frac{\begin{array}{c} l \notin Dom(B) \\ t \Rightarrow \mathsf{Param}\ \tau \end{array}}{B \vdash_i \text{id} : t \Rightarrow [\text{id} \mapsto \mathsf{Loc}\langle l, 0 \rangle],\ B \oplus [l \mapsto \mathsf{Box}\langle \mathsf{inParam}, \varnothing, [1 \mapsto \varnothing] \rangle]} \quad \text{(NodeParamInp)}
$$

$$
\frac{l \notin Dom(B)}{B \vdash_o \text{id} : t \Rightarrow [\text{id} \mapsto \mathsf{Loc}\langle l, 0 \rangle],\ B \oplus [l \mapsto \mathsf{Box}\langle \mathsf{snk}, [1 \mapsto 0], \varnothing \rangle]} \quad \text{(NodeOutp)}
$$

Each input and output adds a box in the enclosing graph. Output boxes have category snk. Input boxes category src or $\mathsf{inParam}$, depending on the their type. These boxes have no input (resp. no output). The premise $l \notin Dom(B)$ ensures that l is a "fresh" box index.

<div style="font-size:small">TODO: Need reference to typing rules (end hence env) here !</div>

3.2.1 Graph declaration

$$\boxed{E, B \vdash \text{GraphDecls} \Rightarrow E', B'}$$

$$
\frac{\begin{array}{c} B \vdash_i (\text{id}_1 : t_1 = e_1, \dots, \text{id}_m : t_m = e_m) \Rightarrow E_i, B_i \\ B_i \vdash_o (\text{id'}_1 : t'_1, \dots, \text{id'}_n : t'_n) \Rightarrow E_o, B_o \\ E \oplus E_i \oplus E_o,\ B \oplus B_i \oplus B_o \vdash \textit{valdecls} \Rightarrow B',\ W' \\ n = \mathsf{Node}\langle \mathsf{graph}, [\text{id}_1 \mapsto \mathsf{Unit}, \dots, \text{id}_m \mapsto \mathsf{Unit}], \mathsf{outs}, \mathsf{Graph}\langle B', W' \rangle \rangle \end{array}}{E, B \vdash \mathbf{graph}\ \text{id}\ (\text{id}_1 : t_1 = e_1, \dots, \text{id}_m : t_m = e_m)\ (\text{id'}_1 : t'_1, \dots, \text{id'}_n : t'_n)\ \textit{valdecls} \Rightarrow E \oplus [\text{id} \mapsto \mathbf{n}], B \oplus B_i \oplus B_o}
$$
$$\text{(GraphDecl)}$$

Evaluation of toplevel graph declarations is similar to that of node declarations. The only difference is that the optional value of inputs is evaluated and attached to the corresponding box[5].

$$\boxed{B \vdash_i \text{GraphInp} \Rightarrow E, B'}$$

$$
\frac{\begin{array}{c} l \notin Dom(B) \\ t \Rightarrow \mathsf{Param}\ \tau \\ \varnothing, \varnothing \vdash e \Rightarrow v, \varnothing, \varnothing \end{array}}{B \vdash_i \text{id} : t = e \Rightarrow [\text{id} \mapsto \mathsf{Loc}\langle l, 0 \rangle],\ B \oplus [l \mapsto \mathsf{Box}\langle \mathsf{inParam}, \varnothing, [1 \mapsto \varnothing], v \rangle]} \quad \text{(GraphInp)}
$$

Boxes materializing input parameters for toplevel graphs hold the value of the specified expression. Type checking ensures that this value is an integer or boolean constant[6].

---

[5] As for the typing rules, strictly speacking, such values can only be attached to inputs declared as *parameters* (*i.e.* with type `t param`). This distinction is, here again, omitted for brevity.

[6] So that the evaluation of the defining expression creates no box nor wire.

3.3   Value declarations

$$\boxed{E, B \vdash \text{ValDecls} \Rightarrow E', B', W}$$

$$\frac{E_0 = E, B_0 = B, W_0 = \varnothing \quad \forall i.\ 1 \le i \le n, \quad E_{i-1}, B_{i-1}, W_{i-1} \vdash valdecl_i \Rightarrow E_i, B_i, W_i}{E, B \vdash valdecl_1 \ \dots \ valdecl_n \Rightarrow E_n, B_n, W_n} \quad (\text{ValDecls})$$

Within a node definition, value declarations are interpreted in the order of their declaration. A declaration can be used in the subsequent ones. Each declaration updates the value, box and wire environments.

$$\boxed{E, B, W \vdash \text{ValDecl} \Rightarrow E', B', W'}$$

$$\frac{E, B \vdash pat_1 = expr_1 \ \dots \ pat_n = expr_n \Rightarrow E', B', W'}{E, B, W \vdash \textbf{val}\ pat_1 = expr_1 \ \dots \ pat_n = expr_n \Rightarrow E \oplus E', \ B \oplus B', \ W \oplus W'} \quad (\text{ValDecl})$$

$$\boxed{E, B, W \vdash_{rec} \text{ValDecl} \Rightarrow E', B', W'}$$

$$\frac{E, B \vdash_{rec} pat_1 = expr_1 \ \dots \ pat_n = expr_n \Rightarrow E', B', W'}{E, B, W \vdash \textbf{val rec}\ pat_1 = expr_1 \ \dots \ pat_n = expr_n \Rightarrow E \oplus E', \ B \oplus B', \ W \oplus W'} \quad (\text{RecValDecl})$$

$$\boxed{E, B \vdash \text{PatExprs} \Rightarrow E', B', W'}$$

$$\frac{\forall i.\ 1 \le i \le n, \quad E, B \vdash pat_i = expr_i \Rightarrow E'_i, B'_i, W_i}{E, B \vdash pat_1 = expr_1 \ \dots \ pat_n = expr_n \ \Rightarrow \bigoplus_{i=1}^{n} E'_i, \bigoplus_{i=1}^{n} B'_i, \bigoplus_{i=1}^{n} W'_i} \quad (\text{Bindings})$$

$$\boxed{E, B \vdash \text{Pat=Expr} \Rightarrow E', B', W'}$$

$$\frac{E, B \vdash expr \Rightarrow v, B', W' \quad E, B \overset{\leftarrow}{\oplus} B' \vdash_p pat,\ v \Rightarrow E', B'', W''}{E, B \vdash pat = expr \Rightarrow E', \ B' \overset{\leftarrow}{\oplus} B'', \ W' \oplus W''} \quad (\text{Binding})$$

Evaluating a `val` declaration consists in evaluating the RHS expression and binding the result value to the LHS pattern.

The $\overset{\leftarrow}{\oplus}$ operator used in rule Binding merges box descriptors. If a box appears in both argument environments, the resulting environment contains a single occurrence of this box in which the respective input and output environments have been merged. For example

$$[l \mapsto \text{Box}\langle \text{actor}, [1 \mapsto 0], [1 \mapsto \{2\}]\rangle] \ \overset{\leftarrow}{\oplus} \ [l \mapsto \text{Box}\langle \text{actor}, [1 \mapsto 4], [1 \mapsto \{3\}]\rangle]$$
$$= \ [l \mapsto \text{Box}\langle \text{actor}, [1 \mapsto 4], [1 \mapsto \{2, 3\}]\rangle]$$

The semantics of *recursive* definitions ($E, B \vdash_{rec} pat_1 = expr_1 \ \dots \ pat_n = expr_n$) is given in Sec. **??**.

3.4 Expressions

$$\boxed{E, B \vdash \text{Expr} \Rightarrow v, B', W}$$

$$\frac{E(\text{id}) = v}{E, B \vdash \text{id} \Rightarrow v, \ \varnothing, \ \varnothing} \tag{EVar}$$

The value of a variable is simply obtained from the value environment.

$$\frac{\forall i.\ 1 \le i \le n, \quad E, B \vdash expr_i \Rightarrow v_i, B_i, W_i}{E, B \vdash (expr_1, \ldots, expr_n) \Rightarrow \langle v_1, \ldots, v_n \rangle, \ \bigoplus_{i=1}^{n} B_i, \ \bigoplus_{i=1}^{n} W_i} \tag{ETuple}$$

For tuples, each component is evaluated separately.

$$\frac{}{E, B \vdash \mathbf{fun}\ pat \to exp \ \Rightarrow \mathsf{Clos}\langle pat, exp, E \rangle, \ \varnothing, \ \varnothing} \tag{EFun}$$

Functions are evaluated, classically, as closures, capturing the current value environment.

$$\frac{\begin{array}{c} E, B \vdash pat_1 = expr_1 \ \ldots \ pat_n = expr_n \Rightarrow E', B', W' \\ E \oplus E', B \overleftarrow{\oplus} B' \vdash exp_2 \Rightarrow v, B'', W'' \end{array}}{E, B \vdash \mathbf{let}\ pat_1 = expr_1 \ \ldots \ pat_n = expr_n \ \mathbf{in}\ expr' \Rightarrow v, B \overleftarrow{\oplus} B', W \oplus W'} \tag{ELet}$$

$$\frac{}{E, B \vdash () \Rightarrow \mathsf{Unit}, \ \varnothing, \ \varnothing} \tag{EUnit}$$

$$\frac{}{E, B \vdash \text{int} \Rightarrow \mathsf{Int}, \ \varnothing, \ \varnothing} \tag{EInt}$$

$$\frac{}{E, B \vdash \text{bool} \Rightarrow \mathsf{Bool}, \ \varnothing, \ \varnothing} \tag{EBool}$$

$$\frac{\begin{array}{c} E, B \vdash exp \Rightarrow \mathsf{true}, B', W' \\ E, B \vdash exp_1 \Rightarrow v, B'', W'' \end{array}}{E, B \vdash \mathbf{if}\ exp\ \mathbf{then}\ exp_1\ \mathbf{else}\ exp_2 \Rightarrow v, B' \overleftarrow{\oplus} B'', W' \oplus W''} \tag{EIf0}$$

$$\frac{\begin{array}{c} E, B \vdash exp \Rightarrow \mathsf{false}, B', W' \\ E, B \vdash exp_2 \Rightarrow v, B'', W'' \end{array}}{E, B \vdash \mathbf{if}\ exp\ \mathbf{then}\ exp_1\ \mathbf{else}\ exp_2 \Rightarrow v, B' \overleftarrow{\oplus} B'', W' \oplus W''} \tag{EIf1}$$

$$\frac{\begin{array}{c} E, B \vdash exp_1 \Rightarrow \mathsf{Clos}\langle pat, exp, E' \rangle, B_f, W_f \\ E, B \vdash exp_2 \Rightarrow v, B_a, W_a \\ \varnothing, \varnothing \vdash_p pat, v \Rightarrow E_p, B_p, W_p \\ E' \oplus E_p, B \vdash exp \Rightarrow v', B', W' \end{array}}{E, B \vdash exp_1\ exp_2 \Rightarrow v', B_f \overleftarrow{\oplus} B_a \overleftarrow{\oplus} B', W_f \oplus W_a \oplus W'} \tag{EAppC}$$

Rule EAppC deals with the application of closures and follows the classical call-by-value strategy (the closure body is evaluated in an environment augmented with the bindings resulting from binding the pattern to the value of argument).

$$\dfrac{\begin{array}{c} \mathrm{E,B} \vdash \mathit{exp}_1 \Rightarrow \mathsf{Node}\langle\kappa, [\mathrm{id}_1 \mapsto \ell_1, \ldots, \mathrm{id}_{k-1} \mapsto \ell_{k-1}, \mathrm{id}_k \mapsto \mathsf{Unit}, \ldots, \mathrm{id}_m \mapsto \mathsf{Unit}], [\mathrm{id}'_1, \ldots, \mathrm{id}'_n], \eta\rangle, \mathrm{B}_f, \mathrm{W}_f \\ k < m-1 \\ \mathrm{E,B} \vdash \mathit{exp}_2 \Rightarrow \ell, \mathrm{B}_a, \mathrm{W}_a \\ \mathsf{Node}\langle\kappa, [\mathrm{id}_1 \mapsto \ell_1, \ldots, \mathrm{id}_{k-1} \mapsto \ell_{k-1}, \mathrm{id}_k \mapsto \ell, \ldots, \mathrm{id}_m \mapsto \mathsf{Unit}], [\mathrm{id}'_1, \ldots, \mathrm{id}'_n], \eta\rangle \end{array}}{\mathrm{E,B} \vdash \mathit{exp}_1 \ \mathit{exp}_2 \Rightarrow \mathrm{n}, \mathrm{B}_f \overleftarrow{\oplus} \mathrm{B}_a, \mathrm{W}_f \oplus \mathrm{W}_a}$$
$$(\textsc{EAppN1})$$

Rule EAppN1 deals with the *partial* application of nodes. The value resulting from the evaluation of the arguments (which must be a graph location) is simply "pushed" on the list of supplied inputs.

$$\dfrac{\begin{array}{c} \mathrm{E,B} \vdash \mathit{exp}_1 \Rightarrow \mathsf{Node}\langle\kappa, [\mathrm{id}_1 \mapsto \ell_1, \ldots, \mathrm{id}_{m-1} \mapsto \ell_{m-1}, \mathrm{id}_m \mapsto \mathsf{Unit}], [\mathrm{id}'_1, \ldots, \mathrm{id}'_n], \eta\rangle, \mathrm{B}_f, \mathrm{W}_f \\ \mathrm{E,B} \vdash \mathit{exp}_2 \Rightarrow \ell_m, \mathrm{B}_a, \mathrm{W}_a \\ l \notin \mathit{Dom}(\mathrm{B}) \\ \forall j.\ 1 \le j \le m,\quad \mathrm{k}_j \notin \mathit{Dom}(\mathrm{W}),\quad \mathrm{w}_j = \langle\ell_j, \mathsf{Loc}\langle l, j\rangle\rangle \\ \mathrm{b} = \mathsf{Box}\langle\mathsf{cat}(\kappa), [1 \mapsto k_1, \ldots, m \mapsto k_m], [1 \mapsto \varnothing, \ldots, n \mapsto \varnothing]\rangle \\ \mathrm{B}' = [l \mapsto b] \\ \mathrm{W}' = [k_1 \mapsto w_1, \ldots, k_m \mapsto w_m] \\ \mathrm{v}' = \langle \mathsf{Loc}\langle l, 1\rangle, \ldots, \mathsf{Loc}\langle l, n\rangle\rangle \end{array}}{\mathrm{E,B} \vdash \mathit{exp}_1 \ \mathit{exp}_2 \Rightarrow \mathrm{v}', \mathrm{B}_f \overleftarrow{\oplus} \mathrm{B}_a \overleftarrow{\oplus} \mathrm{B}', \mathrm{W}_f \oplus \mathrm{W}_a \oplus \mathrm{W}'} \quad (\textsc{EAppN2})$$

Rule EAppN2 deals with the complete application of nodes. It creates a new box and a set of wires connecting the parameters and arguments to the inputs of the inserted box (parameters first, then arguments). The outputs of the box will be connected by the binding step described in the next section. The function $\mathsf{cat}\ : \mathsf{NImpl} \to \mathsf{BCat}$ is trivially defined as $\mathsf{cat}(\mathsf{actor}) = \mathsf{actor}$ and $\mathsf{cat}(\mathsf{Graph}) = \mathsf{graph}$.