

Faculty of Science

Linear Classification

Statistical Methods for Machine Learning

Christian Igel Department of Computer Science



Recall I: Gaussian Distribution

Gaussian distribution of a single real-valued variable with mean $\mu \in \mathbb{R}$ and variance σ^2 :

$$N(x \mid \mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{1}{2\sigma^2}(x - \mu)^2\right\}$$

Multivariate Gaussian distribution of a d-dimensional real-valued random vector with mean $\mu \in \mathbb{R}^d$ and covariance matrix $\Sigma \in \mathbb{R}^{d \times d}$:

$$\mathsf{N}(\boldsymbol{x} \,|\, \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{\sqrt{(2\pi)^d \det \boldsymbol{\Sigma}}} \exp \left\{ -\frac{1}{2} (\boldsymbol{x} - \boldsymbol{\mu})^\mathsf{T} \boldsymbol{\Sigma}^{-1} (\boldsymbol{x} - \boldsymbol{\mu}) \right\}$$



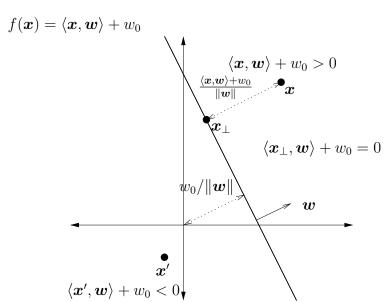
Some reasons for Gaussians

Normal distributions play an important role in modeling for several reasons:

- Gaussians arise in the central limit theorem, which states that the probability distribution of a sum of n i.i.d. random variables with finite mean and variance approaches a Gaussian distribution with increasing n.
 - Thus, if some outcome depends on several sources of randomness (and we assume that these sources add up) it may be well described by a Gaussian.
- Among all distributions having some given mean and variance, the Gaussian distribution has the highest entropy.
 - This means, if we can or want to fix mean and variance and want to express maximum uncertainty about the outcomes, then we arrive at the Gaussian distribution.



Recall II: Linear functions





- 1 Linear Discriminant Analysis
- Linear Classification and Margins
- 3 Perceptron Learning
- Convergence of Perceptron Learning
- Summary



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Decision functions

- Classification means assigning an input $x \in \mathcal{X}$ to one class of a finite set of classes $\mathcal{Y} = \{\mathcal{C}_1, \dots, \mathcal{C}_m\}$, $2 \leq m < \infty$.
- One approach is to learn appropriate discrimination functions $\delta_k: \mathcal{X} \to \mathbb{R}, \ 1 \leq k \leq m$, and assign a pattern x to class \hat{y} using:

$$\hat{y} = h(x) = \operatorname{argmax}_k \delta_k(x)$$



Binary decision functions

• If we have only two classes, we can consider a single function

$$\delta(x) = \delta_1(x) - \delta_2(x)$$

and the hypothesis

$$h(x) = \begin{cases} \mathcal{C}_1 & \text{if } \delta(x) > 0 \\ \mathcal{C}_2 & \text{otherwise} \end{cases}.$$

• For $\mathcal{Y} = \{-1, 1\}$ this is equal to

$$h(x) = \operatorname{sgn}(\delta(x)) = \begin{cases} 1 & \text{if } \delta(x) > 0 \\ -1 & \text{otherwise} \end{cases}.$$



Decision functions and class posteriors

• If we know the class posteriors $\Pr(Y \mid X)$ we can perform optimal classification: a pattern x is assigned to class \mathcal{C}_k with maximum $\Pr(Y = \mathcal{C}_k \mid X = x)$, i.e.,

$$\hat{y} = h(x) = \operatorname{argmax}_k \Pr(Y = \mathcal{C}_k \mid X = x)$$

or in the binary case with $\mathcal{Y} = \{-1, 1\}$

$$\delta = \Pr(Y = \mathcal{C}_1 \mid X = x) - \Pr(Y = \mathcal{C}_2 \mid X = x)$$

and $\hat{y} = h(x) = \operatorname{sgn}(\delta(x))$.

• $\Pr(Y = \mathcal{C}_k \mid X = x)$ is proportional to the class-conditional density $p(X = x \mid Y = \mathcal{C}_k)$ times the class prior $\Pr(Y = \mathcal{C}_k)$:

$$\Pr(Y = \mathcal{C}_k \mid X = x) = \frac{p(X = x \mid Y = \mathcal{C}_k) \Pr(Y = \mathcal{C}_k)}{p(X = x)}$$



Gaussian class-conditionals

Let's consider

$$\ln \Pr(Y = \mathcal{C}_k \mid X = \boldsymbol{x}) = \ln p(X = \boldsymbol{x} \mid Y = \mathcal{C}_k) + \ln \Pr(Y = \mathcal{C}_k) + \text{const}$$

For $\mathcal{X} = \mathbb{R}^d$ and Gaussian class-conditionals

$$p(X = x | Y = C_k) = N(\boldsymbol{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k, Y = C_k)$$

we have:

$$\ln \mathsf{N}(\boldsymbol{x} \mid \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k, Y = \mathcal{C}_k) =$$

$$\ln\left(\frac{1}{\sqrt{(2\pi)^d \det \Sigma_k}} \exp\left\{-\frac{1}{2}(\boldsymbol{x} - \boldsymbol{\mu}_k)^\mathsf{T} \boldsymbol{\Sigma}_k^{-1}(\boldsymbol{x} - \boldsymbol{\mu}_k)\right\}\right) = \\ -\frac{d}{2} \ln 2\pi - \frac{1}{2} \ln \det \Sigma_k - \frac{1}{2}(\boldsymbol{x} - \boldsymbol{\mu}_k)^\mathsf{T} \boldsymbol{\Sigma}_k^{-1}(\boldsymbol{x} - \boldsymbol{\mu}_k) = \\ -\frac{d}{2} \ln 2\pi - \frac{1}{2} \ln \det \Sigma_k - \frac{1}{2} \boldsymbol{x}^\mathsf{T} \boldsymbol{\Sigma}_k^{-1} \boldsymbol{x} - \frac{1}{2} \boldsymbol{\mu}_k^\mathsf{T} \boldsymbol{\Sigma}_k^{-1} \boldsymbol{\mu}_k + \boldsymbol{x}^\mathsf{T} \boldsymbol{\Sigma}_k^{-1} \boldsymbol{\mu}_k$$

Linear Discriminant Analysis (LDA)

Assume identical covariance matrix for all class-conditionals

$$\ln \Pr(Y = \mathcal{C}_k \mid X = \boldsymbol{x}) - \operatorname{const} = \ln \Pr(Y = \mathcal{C}_k)$$

$$-\frac{d}{2} \ln 2\pi - \frac{1}{2} \ln \det \boldsymbol{\Sigma} - \frac{1}{2} \boldsymbol{x}^\mathsf{T} \boldsymbol{\Sigma}^{-1} \boldsymbol{x} - \frac{1}{2} \boldsymbol{\mu}_k^\mathsf{T} \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_k + \boldsymbol{x}^\mathsf{T} \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_k \Rightarrow$$

$$\delta_k(\boldsymbol{x}) = \boldsymbol{x}^\mathsf{T} \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_k - \frac{1}{2} \boldsymbol{\mu}_k^\mathsf{T} \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_k + \ln \Pr(Y = \mathcal{C}_k)$$

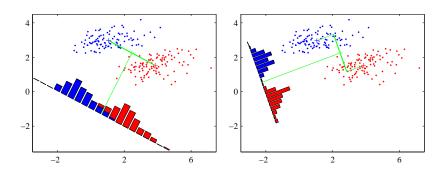
With $S_k = \{(\boldsymbol{x}, y) \in S \mid y = \mathcal{C}_k\}$ and $\ell_k = |S_k|$ we estimate:

$$\hat{\boldsymbol{\mu}}_k = \frac{\ell_k}{\ell_k} \sum_{(\boldsymbol{x}, y) \in S_k} \boldsymbol{x}$$

$$\hat{\Sigma} = \frac{1}{\ell - m} \sum_{k=1}^{m} \sum_{(\boldsymbol{x}, y) \in S_k} (\boldsymbol{x} - \hat{\boldsymbol{\mu}}_k) (\boldsymbol{x} - \hat{\boldsymbol{\mu}}_k)^\mathsf{T}$$



Effect of learning the covariance



C. M. Bishop. Pattern Recognition and Machine Learning. Springer-Verlag, 2006



Linear and Quadratic Discriminant Analysis

- In LDA the decision boundaries $\{x \mid \delta_i(x) = \delta_j(x)\}$ between two classes i and j are linear, and the hypotheses are linear functions $\mathbb{R}^d \to \mathbb{R}$.
- Modeling independent covariance matrices for the class-conditionals leads to quadratic discriminant analysis (QDA) with quadratic decision functions:

$$\delta_k(\boldsymbol{x}) = -\frac{1}{2} \ln \det \boldsymbol{\Sigma}_k - \frac{1}{2} \boldsymbol{x}^\mathsf{T} \boldsymbol{\Sigma}_k^{-1} \boldsymbol{x} - \frac{1}{2} \boldsymbol{\mu}_k^\mathsf{T} \boldsymbol{\Sigma}_k^{-1} \boldsymbol{\mu}_k + \boldsymbol{x}^\mathsf{T} \boldsymbol{\Sigma}_k^{-1} \boldsymbol{\mu}_k + \mathbf{y}^\mathsf{T} \boldsymbol{\Sigma}_k^{-1} \boldsymbol{\mu}_k + \mathbf{y}^\mathsf{T} \boldsymbol{\Sigma}_k^{-1} \boldsymbol{\mu}_k + \mathbf{y}^\mathsf{T} \boldsymbol{\Sigma}_k^{-1} \boldsymbol{\mu}_k$$



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General linear binary classification

- LDA is a linear classification method
- Given training examples

$$S = \{(\boldsymbol{x}_1, y_1), \dots, (\boldsymbol{x}_{\ell}, y_{\ell})\} \subseteq (\mathbb{R}^n \times \{-1, 1\})^{\ell}$$

a binary linear classifier assigns $\boldsymbol{x} \in \mathbb{R}^n$ to one of two classes $\{-1,1\}$ by an affine linear decision function identified by (\boldsymbol{w},w_0) :

$$\delta(\boldsymbol{x}) = \langle \boldsymbol{w}, \boldsymbol{x} \rangle + w_0 = \boldsymbol{w}^\mathsf{T} \boldsymbol{x} + w_0 = \sum_{i=1}^n w_i x_i + w_0$$

x belongs to the first class if $\delta(x) \ge 0$, otherwise to the second, i.e., the resulting hypothesis is:

$$h(\boldsymbol{x}) = \operatorname{sgn}(\delta(\boldsymbol{x}))$$



Margins I

The functional margin of an example (\boldsymbol{x}_i,y_i) with respect to a hyperplane (\boldsymbol{w},w_0) is

$$\gamma_i := y_i(\langle \boldsymbol{w}, \boldsymbol{x}_i \rangle + w_0)$$
.

The geometric margin of an example (\boldsymbol{x}_i,y_i) with respect to a hyperplane (\boldsymbol{w},w_0) is

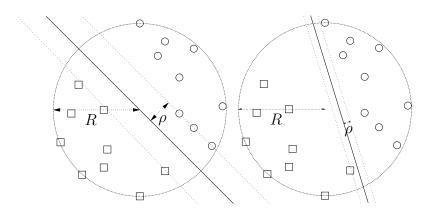
$$\rho_i := y_i(\langle \boldsymbol{w}, \boldsymbol{x}_i \rangle + w_0) / \|\boldsymbol{w}\| = \gamma_i / \|\boldsymbol{w}\|.$$

A positive margin implies correct classification.

The margin of a hyperplane (\boldsymbol{w}, w_0) with respect to a training set S is $\min_i \rho_i$. The margin of a training set S is the maximum geometric margin over all hyperplanes. A hyperplane realizing this margin is called maximum margin hyperplane.



Margins II





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Analyzing the Perceptron

Why should we look at the Perceptron?

- Linear classifiers such as perceptrons are the basis of technical neurocomputing
- Support Vector Machines are basically linear classifiers
- Basic concepts of learning theory can be explained easily:
 - Margins
 - Dual representation
 - Bounds involving margins and the radius of the ball containing the data



Perceptron learning algorithm (primal form)

For simplicity, consider hyperplanes with no bias $(w_0 = 0)$, i.e., $\mathcal{H} = \{h(\boldsymbol{x}) = \operatorname{sgn}(\langle \boldsymbol{w}, \boldsymbol{x} \rangle) \mid \boldsymbol{w} \in \mathbb{R}^n\}$.

Algorithm 1: Perceptron

```
Input: separable data \{(\boldsymbol{x}_1,y_1),\dots\}\subseteq (\mathbb{R}^n\times\{-1,1\})^\ell

Output: hypothesis h(\boldsymbol{x})=\mathrm{sgn}(\langle\boldsymbol{w}_k,\boldsymbol{x}\rangle)

1 \boldsymbol{w}_0\leftarrow\mathbf{0}; k\leftarrow0

2 repeat

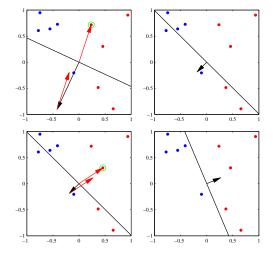
3 | for i=1,\dots,\ell do
```

$$\begin{array}{c|c} \mathbf{3} & \text{for } i=1,\ldots,\ell \text{ do} \\ \mathbf{4} & \text{if } y_i \left< \boldsymbol{w}_k, \boldsymbol{x}_i \right> \leq 0 \text{ then} \\ \mathbf{5} & \boldsymbol{w}_{k+1} \leftarrow \boldsymbol{w}_k + y_i \boldsymbol{x}_i \\ k \leftarrow k+1 \end{array}$$

7 until no mistake made within for loop



Perceptron learning in pictures





C. M. Bishop. Pattern Recognition and Machine Learning. Springer-Verlag, 2006

Dual representation

 Weight vector of hyperplane computed by online perceptron algorithm can be written as

$$\boldsymbol{w} = \sum_{i=1}^{\ell} \alpha_i y_i \boldsymbol{x}_i$$

• Function $h(\boldsymbol{x}) = \operatorname{sgn}(\delta(\boldsymbol{x}))$ can be written in dual coordinates

$$\delta(\boldsymbol{x}) = \langle \boldsymbol{w}, \boldsymbol{x} \rangle$$

$$= \left\langle \sum_{i=1}^{\ell} \alpha_i y_i \boldsymbol{x}_i, \boldsymbol{x} \right\rangle$$

$$= \sum_{i=1}^{\ell} \alpha_i y_i \langle \boldsymbol{x}_i, \boldsymbol{x} \rangle$$



Perceptron learning algorithm (dual form)

Algorithm 2: Perceptron (dual form)

Input: separable data $\{(\boldsymbol{x}_1,y_1),\dots\}\subseteq (\mathbb{R}^n\times\{-1,1\})^\ell$ **Output**: hypothesis $h(\boldsymbol{x}) = \mathrm{sgn}\left(\sum_{i=1}^{\ell} \alpha_i y_i \left\langle \boldsymbol{x}_i, \boldsymbol{x} \right\rangle\right)$ $1 \alpha \leftarrow 0$

- repeat

$$\begin{array}{c|c} \mathbf{3} & \mathbf{for} \ i=1,\dots,\ell \ \mathbf{do} \\ \mathbf{4} & \mathbf{if} \ y_i \sum_{j=1}^\ell \alpha_j y_j \left\langle \boldsymbol{x}_j, \boldsymbol{x}_i \right\rangle \leq 0 \ \mathbf{then} \\ \mathbf{5} & \alpha_i \leftarrow \alpha_i + 1 \end{array}$$

6 until no mistake made within for loop



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Novikoff

Theorem (Novikoff)

Let $S = \{(\boldsymbol{x}_1, y_1), \dots, (\boldsymbol{x}_\ell, y_\ell)\}$ be a non-trivial training set (i.e., containing patterns of both classes), $\boldsymbol{w}_0 = \boldsymbol{0} = \sum_{i=1}^m 0\boldsymbol{x}_i$ and let

$$R \leftarrow \max_{1 \leq i \leq \ell} \|\boldsymbol{x}_i\|$$
.

Suppose that there exists $oldsymbol{w}_{\it opt}$ and ho>0 such that

$$\|\boldsymbol{w}_{opt}\| = 1$$
 and

$$y_i \left\langle \boldsymbol{w}_{opt}, \boldsymbol{x}_i \right\rangle \ge \rho > 0$$

for $1 \le i \le \ell$. Then the number of updates k made by the online perceptron algorithm on S is at most

$$\left(\frac{R}{\rho}\right)^2$$



Novikoff, sketch of proof I

Let i be the index of the example in update k

$$\|\boldsymbol{w}_{k+1}\|^2 = \langle \boldsymbol{w}_k + y_i \boldsymbol{x}_i, \boldsymbol{w}_k + y_i \boldsymbol{x}_i \rangle$$

$$= \|\boldsymbol{w}_k\|^2 + 2y_i \langle \boldsymbol{w}_k, \boldsymbol{x}_i \rangle + \|\boldsymbol{x}_i\|^2$$

$$\leq \|\boldsymbol{w}_k\|^2 + R^2$$

$$\leq (k+1)R^2$$



Novikoff, sketch of proof II

$$\langle \boldsymbol{w}_{\mathsf{opt}}, \boldsymbol{w}_{k+1} \rangle = \langle \boldsymbol{w}_{\mathsf{opt}}, \boldsymbol{w}_{k} \rangle + y_{i} \langle \boldsymbol{w}_{\mathsf{opt}}, \boldsymbol{x}_{i} \rangle$$

$$\geq \langle \boldsymbol{w}_{\mathsf{opt}}, \boldsymbol{w}_{k} \rangle + \rho$$

$$\geq (k+1)\rho$$

$$k^2 \rho^2 \le \langle \boldsymbol{w}_{\mathsf{opt}}, \boldsymbol{w}_k \rangle^2 \le \|\boldsymbol{w}_{\mathsf{opt}}\|^2 \|\boldsymbol{w}_k\|^2 \le kR^2$$

$$k \le \frac{R^2}{\rho^2}$$



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Summary

- Linear discriminant analysis (LDA)
 - gives good results in practice,
 - is easy to use, because it has no hyperparameters,
 - usually does not overfit, but may not capture essential non-linearities,
 - it is highly recommended as a baseline method.
- Hey, we also now know about
 - perceptron learning,
 - margins,
 - dual representation,
 - bounds involving margins and the radius of the ball containing the data.

References:

- J. Shawe-Taylor and N. Cristianini. Kernel Methods for Pattern Analysis. Cambridge University Press, 2004
- C. M. Bishop. Pattern Recognition and Machine Learning. Springer-Verlag, 2006

