Representation Theory in Braid Groups

by

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None

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Abstract

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Write an abstract here.

Any acknowledgements?

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Chapter 1

SAMPLE CHAPTER 1

1.1 First Section of Introduction

This is an equation:

$$c^2 = a^2 + b^2. (1.1)$$

SAMPLE CHAPTER 2

2.1 MY FIRST SECTION

There are lots of great resources on the internet to help you learn LATEX. Perhaps start with examples like the ones at

http://en.wikibooks.org/wiki/LaTeX/Sample_LaTeX_documents.

It is important to cite references. [1, 2, 5]

Organize the paper into sections and subsections.

2.1.1 Interesting subsection title

You get the idea. Hey, this one has some displayed math,

$$\frac{2}{x} = \sin(\epsilon),$$

not that it makes any sense whatsoever. And here is how you do a numbered equation,

$$\int_0^{y^2} f(x) \, dx = \sqrt{z+y}. \tag{2.1}$$

Don't forget to punctuate your equations as part of the sentence. You can do inline math, too, as in $f(x) = \lim_{n \to \infty} n f(x)/n$, which is trivial.

2.1.2 Another interesting subsection title

Okay, not really.



Figure 2.1: This is a sample figure. It is not interesting. Note that figures will "float" to wherever \LaTeX wants to put them.

Chapter 3

REPRESENTATION THEORY

3.1 Introduction to Representations

Over the course of this chapter, we will develop the theory and utility of representations. At a glance, representations give us the ability to dial back the complexity of a mysterious group by viewing its elements as matrices. Thanks to the rigorous development and study of linear algebra, groups of matrices are well-understood structures. Representations allow us to unravel the mystery of an unknown group structure and reveal a group's fundamental properties as results of linear algebra techniques.

Definition 3.1. (First Definition) A representation of degree n is a group homomorphism that maps a group into $GL_n(\mathbb{C})$

$$\phi: G \to GL_n(\mathbb{C})$$

We say that ϕ is a representation of G. If ϕ is an injective homomorphism, we say that the representation is **faithful**. Otherwise, the representation is called **degenerate**.

To illustrate to concept of representations, we will consider the group of all roots of unity, G, for the following examples. We can construct multiple homomorphisms from G to showcase different kinds of representations.

Note: Since $GL_1(\mathbb{C})$ as \mathbb{C} are isomorphic, we identify each 1x1 matrix with its corresponding entry with its element in \mathbb{C} .

Example 3.2. (Trivial Representation)

Let
$$\phi: G \to GL_1(\mathbb{C})$$

 $g \mapsto 1$

This map is the trivial homomorphism from G to $GL_1(\mathbb{C})$ and therefore it easily satisfies the requirement of a degree 1 representation of G. We say that ϕ is the **trivial representation** of G.

Example 3.3. (Nontrivial Degree 1 Representation)

By construction of G, if $g \in G$, then $g = e^{\frac{2\pi i m}{n}}$ where $m, n \in \mathbb{Z}$

Let
$$\phi: G \to GL_1(\mathbb{C})$$

 $g \mapsto g$

where we view G as a multiplicative subgroup of \mathbb{C} . This observation trivializes the argument that ϕ is a homomorphism. Therefore, ϕ is a degree 1 representation of G.

Example 3.4. (Degree 2 Representation)

$$\begin{aligned}
\phi: G \to GL_2(\mathbb{C}) \\
Let & e^{2\pi i \frac{m}{n}} \mapsto \begin{bmatrix} \cos(\frac{2\pi m}{n}) & \sin(\frac{2\pi m}{n}) \\ -\sin(\frac{2\pi m}{n}) & \cos(\frac{2\pi m}{n}) \end{bmatrix}
\end{aligned}$$

To show this map is a homomorphism, we will take two elements of G, say $e^{2\pi i \frac{x}{y}}$ and $e^{2\pi i \frac{a}{b}}$ and track the image of their product under ϕ .

$$\begin{split} \phi(e^{2\pi i \frac{x}{y}} * e^{2\pi i \frac{a}{b}}) &= \phi(e^{2\pi i (\frac{x}{y} + \frac{a}{b})}) \\ &= \begin{bmatrix} \cos(2\pi (\frac{x}{y} + \frac{a}{b})) & \sin(2\pi (\frac{x}{y} + \frac{a}{b})) \\ -\sin(2\pi (\frac{x}{y} + \frac{a}{b})) & \cos(2\pi (\frac{x}{y} + \frac{a}{b})) \end{bmatrix} \\ &= \begin{bmatrix} \cos(2\pi \frac{x}{y}) \cos(2\pi \frac{a}{b}) - \sin(2\pi \frac{x}{y}) \sin(2\pi \frac{a}{b}) & \sin(2\pi \frac{x}{y}) \cos(2\pi \frac{a}{b}) + \cos(2\pi \frac{x}{y}) \sin(2\pi \frac{a}{b}) \\ -\sin(2\pi \frac{x}{y}) \cos(2\pi \frac{a}{b}) - \cos(2\pi \frac{x}{y}) \sin(2\pi \frac{a}{b}) & \cos(2\pi \frac{x}{y}) \cos(2\pi \frac{a}{b}) - \sin(2\pi \frac{x}{y}) \sin(2\pi \frac{a}{b}) \end{bmatrix} \\ &= \begin{bmatrix} \cos(2\pi \frac{x}{y}) & \sin(2\pi \frac{x}{y}) \\ -\sin(2\pi \frac{x}{y}) & \cos(2\pi \frac{a}{b}) & \sin(2\pi \frac{a}{b}) \\ -\sin(2\pi \frac{a}{b}) & \cos(2\pi \frac{a}{b}) \end{bmatrix} \\ &= \phi(e^{2\pi i \frac{x}{y}}) * \phi(e^{2\pi i \frac{a}{b}}) \end{split}$$

$$(3.1)$$

Since, ϕ has been shown to be a homomorphism, we can conclude that ϕ is also a degree 2 representation of G.

Is ϕ faithful or degenerate? A faithful representation would have a trivial kernel. Suppose $\phi(e^{2\pi i \frac{x}{y}}) = I_2$ (I_n is the Identity Matrix of dimension $n \times n$).

$$\begin{bmatrix} \cos(2\pi \frac{x}{y}) & \sin(2\pi \frac{x}{y}) \\ -\sin(2\pi \frac{x}{y}) & \cos(2\pi \frac{x}{y}) \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$
 (3.2)

Comparing entrywise, we see that $\cos(2\pi \frac{x}{y}) = 1$ and $\pm \sin(2\pi \frac{x}{y}) = 0$. Using any of these equations, we see that $\frac{x}{y} = n$ for some $n \in \mathbb{Z}$. Therefore, $\ker(\phi) = \mathbb{Z}$ and this representation is degenerate.

Alternatively, we can formulate the definition of a representation in a different context, illuminating a useful interpretation that will be used extensively throughout this paper.

Definition 3.5. (Second Definition) Let G be a group, let V be a linear vector space, and let $\mathcal{L}(V)$ be the group of linear operators on V together with the operation of composition. A representation of G is a group homomorphism that maps G into $\mathcal{L}(V)$.

$$\phi: G \to \mathcal{L}(V)$$

The degree of the representation is the dimension of V.

Remark 3.6. In the case where we have a finite dimensional vector space, we can make an interesting observation. Suppose V is finite dimensional and G is a group. It is easy to identify both definitions of representations with one another. Let $\{e_i\}_{i=1}^n$ be a basis for V. Let $\phi: G \to \mathcal{L}(V)$ be a representation of G. Then $\forall g \in G$, $U_g := \phi(g)$ is a linear operator on V. U_g has a corresponding matrix, $M(U_g)$, with coefficients defined by the image of our basis vectors of V.

$$M(U_g) = \begin{bmatrix} m_{11} & m_{12} & \dots & m_{1n} \\ m_{21} & m_{22} & \dots & m_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ m_{n1} & m_{n2} & \dots & m_{nn} \end{bmatrix} = e_1$$

$$U_g(e_j) = \sum_{i=1}^n m_{ij} e_i$$

Does the map $\psi: G \to GL_n(\mathbb{C})$ $g \mapsto M(U_g)$ satisfy the criteria to be considered a representation (by the first definition)? If $g, h \in G$, then

$$\psi(qh) = M(U_{qh}) = M(U_q \circ U_h) = M(U_q) * M(U_h) = \psi(q)\psi(h)$$

Where the homomorphism property of ϕ is used in succession with link between composition and multiplication of operators and their corresponding matrices. Therefore, we have established a very special link between th

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APPENDICES

Appendix A

APPENDIX A TITLE

Blah blah