Representation Theory in Braid Groups

by

Jaxon Green

None

A dissertation submitted in partial satisfaction of the requirements for the degree of

Master of Science

in

Mathematics

in the

GRADUATE DIVISION

of the

UNIVERSITY OF CALIFORNIA, SAN LUIS OBISPO

Committee in charge:
Professor Ben Richert
Professor of Mathematics, Chair
Professor Sean Gasiorek

June 2024

Representation Theory in Braid Groups

Copyright 2024

by

Jaxon Green

Abstract

Representation Theory in Braid Groups

by

Jaxon Green

Master of Science in Mathematics

University of California, San Luis Obispo

Professor Ben Richert Professor of Mathematics, Chair

Write an abstract here.

Any acknowledgements?

Contents

List of Tables					
Li	st of	Figures	\mathbf{v}		
1	Sample Chapter 1				
	1.1	First Section of Introduction	1		
2	Sample Chapter 2				
	2.1	MY FIRST SECTION	2		
		2.1.1 Interesting subsection title	2		
		2.1.2 Another interesting subsection title	2		
3	Representation Theory				
	3.1	Introduction to Representations	4		
Bi	ibliog	graphy	6		
ΑI	PPEN	NDICES			
	A	Appendix A Title	7		

List of Tables

List of Figures

2.1	This is a sample figure. It is not	interesting. Note tha	t figures will "float" to
	wherever LATEX wants to put th	em	

Chapter 1

SAMPLE CHAPTER 1

1.1 First Section of Introduction

This is an equation:

$$c^2 = a^2 + b^2. (1.1)$$

SAMPLE CHAPTER 2

2.1 MY FIRST SECTION

There are lots of great resources on the internet to help you learn LATEX. Perhaps start with examples like the ones at

http://en.wikibooks.org/wiki/LaTeX/Sample_LaTeX_documents.

It is important to cite references. [1, 2, 5]

Organize the paper into sections and subsections.

2.1.1 Interesting subsection title

You get the idea. Hey, this one has some displayed math,

$$\frac{2}{x} = \sin(\epsilon),$$

not that it makes any sense whatsoever. And here is how you do a numbered equation,

$$\int_0^{y^2} f(x) \, dx = \sqrt{z+y}. \tag{2.1}$$

Don't forget to punctuate your equations as part of the sentence. You can do inline math, too, as in $f(x) = \lim_{n \to \infty} n f(x)/n$, which is trivial.

2.1.2 Another interesting subsection title

Okay, not really.



Figure 2.1: This is a sample figure. It is not interesting. Note that figures will "float" to wherever \LaTeX wants to put them.

REPRESENTATION THEORY

3.1 Introduction to Representations

Over the course of this chapter, we will develop the theory and utility of representations. At a glance, representations give us the ability to dial back the complexity of a mysterious group by viewing its elements as matrices. Thanks to the rigorous development and study of linear algebra, groups of matrices are well-understood structures. Representations allow us to unravel the mystery of an unknown group structure and reveal a group's fundamental properties as results of linear algebra techniques.

Definition 3.1. A representation of degree n is a group homomorphism that maps a group into $GL_n(\mathbb{C})$

To illustrate to idea of a representation, we will consider the group of all roots of unity (G). We can construct multiple homomorphisms from G to showcase different kinds of representations.

Note: we will be treating $GL_1(\mathbb{C})$ as \mathbb{C} since they are isomorphic.

Example 3.2. (Trivial Representation)

Let
$$\phi: G \to GL_1(\mathbb{C})$$

 $g \mapsto 1$

This map is the trivial homomorphism from G to $GL_1(\mathbb{C})$ and therefore it easily satisfies the requirement of a degree 1 representation of G. We say that ϕ is the **trivial representation** of G.

Example 3.3. (Nontrivial Degree 1 Representation)

By construction of G, if $g \in G$, then $g = e^{\frac{2\pi i m}{n}}$ where $m, n \in \mathbb{Z}$

Let
$$\phi: G \to GL_1(\mathbb{C})$$

 $g \mapsto g$

where we view G as a multiplicative subgroup of \mathbb{C} . This observation trivializes the argument that ϕ is a homomorphism. Therefore, ϕ is a degree 1 representation of G.

$$\begin{aligned} \phi: G \to GL_2(\mathbb{C}) \\ Let & e^{2\pi i \frac{m}{n}} \mapsto \begin{bmatrix} \cos(\frac{2\pi m}{n}) & \sin(\frac{2\pi m}{n}) \\ -\sin(\frac{2\pi m}{n}) & \cos(\frac{2\pi m}{n}) \end{bmatrix} \end{aligned}$$

To show this map is a homomorphism, we will take two elements of G, say $e^{2\pi i \frac{x}{y}}$ and $e^{2\pi i \frac{a}{b}}$ and track the image of their product under ϕ .

$$\begin{split} \phi(e^{2\pi i \frac{x}{y}} * e^{2\pi i \frac{a}{b}}) &= \phi(e^{2\pi i (\frac{x}{y} + \frac{a}{b})}) \\ &= \begin{bmatrix} \cos(2\pi (\frac{x}{y} + \frac{a}{b})) & \sin(2\pi (\frac{x}{y} + \frac{a}{b})) \\ -\sin(2\pi (\frac{x}{y} + \frac{a}{b})) & \cos(2\pi (\frac{x}{y} + \frac{a}{b})) \end{bmatrix} \\ &= \begin{bmatrix} \cos(2\pi \frac{x}{y}) \cos(2\pi \frac{a}{b}) - \sin(2\pi \frac{x}{y}) \sin(2\pi \frac{a}{b}) & \sin(2\pi \frac{x}{y}) \cos(2\pi \frac{a}{b}) + \cos(2\pi \frac{x}{y}) \sin(2\pi \frac{a}{b}) \\ -\sin(2\pi \frac{x}{y}) \cos(2\pi \frac{a}{b}) - \cos(2\pi \frac{x}{y}) \sin(2\pi \frac{a}{b}) & \cos(2\pi \frac{x}{y}) \cos(2\pi \frac{a}{b}) - \sin(2\pi \frac{x}{y}) \sin(2\pi \frac{a}{b}) \end{bmatrix} \\ &= \begin{bmatrix} \cos(2\pi \frac{x}{y}) & \sin(2\pi \frac{x}{y}) \\ -\sin(2\pi \frac{x}{y}) & \cos(2\pi \frac{x}{y}) \end{bmatrix} \begin{bmatrix} \cos(2\pi \frac{a}{b}) & \sin(2\pi \frac{a}{b}) \\ -\sin(2\pi \frac{a}{b}) & \cos(2\pi \frac{a}{b}) \end{bmatrix} \\ &= \phi(e^{2\pi i \frac{x}{y}}) * \phi(e^{2\pi i \frac{a}{b}}) \end{split}$$

$$(3.1)$$

Since, ϕ has been shown to be a homomorphism, we can conclude that ϕ is also a degree 2 representation of G.

As illustrated in the previous example, the process of confirming a map is a representation is relatively standard. However, there does not seem to be any intuitive way to come up with a new representation. The rest of this chapter will be devoted the process of comparing and characterizing every representation of a given group.

Definition 3.5. Two representations, ϕ and ψ , are said to be **equivalent representations** if there exists some invertible group homomorphism, μ , such that

$$\phi = \mu \psi \mu^{-1}$$

Bibliography

- [1] A. F. Blumberg and G. L. Mellor. A description of a three-dimensional coastal circulation model. In N. Heaps, editor, *Three Dimensional Coastal Ocean Models*, pages 1–16. Amer. Geophys. Union, 1987.
- [2] A. Gill. Atmosphere Ocean Dynamics. Academic Press, 1982.
- [3] P. F. Choboter, R. M. Samelson, and J. S. Allen. A New Solution of a Nonlinear Model of Upwelling. *J. Phys Oceanogr.*, 35:532–544, 2005.
- [4] S. J. Lentz and D. C. Chapman. The importance of non-linear cross-shelf momentum flux during wind-driven coastal upwelling. *J. Phys. Oceanogr.*, 34:2444–2457, 2004.
- [5] J. Pedlosky. A Nonlinear Model of the Onset of Upwelling. J. Phys Oceanogr., 8:178–187, 1978.

APPENDICES

Appendix A

APPENDIX A TITLE

Blah blah