## **Jacob Sharf**

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# **Work Experience**

#### **Google Pixel Buds**

September 2019 - Present

• Own continuous integration builds, branch management, and release process

## Google Daydream VR Controller Team

May 2017 - Sep 2019

- Firmware engineer for low-latency highly repeatable position tracking system.
- Android Development, Bluetooth-Low-Energy (BLE) 4.0, and USB experience.

## Google Platforms GPU System Software

July 2016 - 2017

- Managed platforms introduction of NVIDIA P100 GPU
- Developed UEFI driver module for custom PCIe device.

#### Google Engineering Residency Program

July 2015 - 2016

Waymo Firmware Residency firmware, physical device simulation, systems programming Google Storage Device Emulator Residency wrote emulator to replace costly hardware test rigs.

#### Flight Software Intern at SpaceX Technologies

June-Sep 2014

- Developed Crew Dragon Audio Module.
- Audio Compression Codecs, C++ hardware driver experience

#### Software Intern at Coverity

Jun - Sep 2013

• Developed tool for analyzing performance of Coverity's static analysis

#### Internship with CASIT Biomedical lab @ UCLA.

April - Oct 2012

Wrote firmware for smart prosthetic devices. Bluetooth, PIC, I2C.

#### Skills

**Professional experience** with VR, Space Exploration, Self-driving cars, and prosthetics. **Hobbyist experience** with PCB design, SMD soldering, welding, composite layup and woodworking.

### **Education**

University of California, Los Angeles, B.S. in Computer Science

Class of 2015

## **Extracurricular Activities**

#### Google 20% Projects

- Google Repair Cafe: Organized Google's first repair cafe. ~180lbs of broken goods fixed per-event.
- ResurrectBot: chatbot used by over 100 teams at Google to prevent group chats from expiring.

#### IEEE UCLA Project Manager

Sep 2014 - June 2015

• Responsible for reviewing all club project designs, code, PCB layout, and algorithms

#### **IEEE UCLA Officer for NATCAR Competition**

Sep 2012 – May 2013

Managed 40 students that designed and built several line-following robots