

Chapter 10: Parametric Equations and Polar Coordinates

10.1 Curves Defined by Parametric Equations

Parametric equations: $x = f(t)$ $y = g(t)$

- Know how curves are drawn and direction, how much

10.2 Calculus with Parametric Curves

Tangents: $\frac{dy}{dx} = \frac{dy/dt}{dx/dt}$ if $\frac{dx}{dt} \neq 0$

2nd Derivative: $\frac{d^2y}{dx^2} = \frac{d}{dx} \left(\frac{dy}{dx} \right) = \frac{\frac{d}{dt} \left(\frac{dy}{dx} \right)}{dx/dt}$
(Concavity)

Area: $A = \int_a^b g(t) f'(t) dt$ if $x = f(t), y = g(t), a \leq t \leq b$
" " " "

Arc Length: $L = \int_a^b \sqrt{\left(\frac{dx}{dt} \right)^2 + \left(\frac{dy}{dt} \right)^2} dt$

Surface Area: $S = 2\pi \int_a^b y \sqrt{\left(\frac{dx}{dt} \right)^2 + \left(\frac{dy}{dt} \right)^2} dt$ if rotated around x-axis

10.3 Polar Coordinates

Polar coordinate system: (r, θ)

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$r^2 = x^2 + y^2$$

$$\tan \theta = \frac{y}{x}$$

rect \rightarrow polar

polar \rightarrow rect

Polar graphs

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$r = c$: circle

$\theta = c$: line

Cardioid/Limacon: $r = a \pm b \cos \theta$, $r = a \pm b \sin \theta$

Inner loop: $b > a$

Cardioid (heart): $a = b$

Roses: $r = a \cos(n\theta)$

$r = a \sin(n\theta)$

if n is odd: petals = n

even: petals = $2n$

Tangents:

$$\frac{dy}{dx} = \frac{\frac{dr}{d\theta} \sin \theta + r \cos \theta}{\frac{dr}{d\theta} \cos \theta - r \sin \theta}$$

since

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \end{aligned}$$

10.4 Areas and Lengths in Polar Coordinates

Area: $A = \frac{1}{2} \int_a^b r^2 d\theta$

Arc length: $L = \int_a^b \sqrt{r^2 + \left(\frac{dr}{d\theta}\right)^2} d\theta$

Chapter 12: Vectors and the Geometry of Space

12.1 3D Systems

Distance: $d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$

Eq of sphere: $(x-a)^2 + (y-b)^2 + (z-c)^2 = r^2$

12.2 Vectors

vector has both magnitude and direction

$$\vec{a} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$$

Magnitude: $|a| = \sqrt{a_1^2 + a_2^2 + a_3^2}$

$$a + b = \langle a_1 + b_1, a_2 + b_2 \rangle$$

$$a - b = \langle a_1 - b_1, a_2 - b_2 \rangle$$

$$ca = \langle ca_1, cb_1 \rangle$$

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$$\vec{a} = |a| \langle \cos \theta, \sin \theta \rangle$$

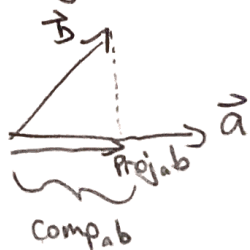
12.3 Dot Product

$$\vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2 + a_3 b_3$$

$$\cos \theta = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}| |\vec{b}|} \quad \text{where } \theta \text{ is the angle between vectors } \vec{a} \text{ and } \vec{b}$$

if $\vec{a} \cdot \vec{b} = 0$, vectors are orthogonal

Projections



Scalar proj of b onto a

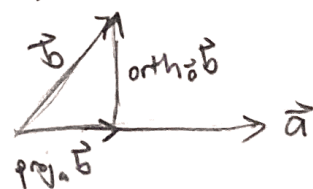
$$\text{comp}_a b = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}|}$$

vector proj of b onto a

$$\text{proj}_a b = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}|^2} \vec{a}$$

Orthogonal Vector

$$\text{orth}_a b = \vec{b} - \text{proj}_a b$$



$$\text{Work} = F \cdot D \cos \theta = |\vec{F}| |\vec{D}| \cos \theta$$

12.4 Cross Product

$$\text{Det. } \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

$$\vec{a} \times \vec{b} = \det \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} \vec{i} - \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} \vec{j} + \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} \vec{k}$$

$\vec{a} \times \vec{b}$ is orthogonal to both \vec{a} and \vec{b}

$$|\vec{a} \times \vec{b}| = |\vec{a}| |\vec{b}| \sin \theta$$

if $\vec{a} \times \vec{b} = 0$, vectors \vec{a} and \vec{b} are parallel

$|\vec{a} \times \vec{b}|$ is equal to parallelogram made by \vec{a} and \vec{b}

Scalar triple product : $\vec{a} \cdot (\vec{b} \times \vec{c})$

(Volume of parallelepiped) = $|\vec{a} \cdot (\vec{b} \times \vec{c})|$

Torque : $\vec{\tau} = \vec{r} \times \vec{F}$ $|\tau| = |\vec{r} \times \vec{F}| = |\vec{r}| |\vec{F}| \sin \theta$

12.5 Equations of Lines and Planes

Vector eq of Line: $\vec{r} = \vec{r}_0 + t \vec{v}$ where \vec{v} is a direction vector and \vec{r}_0 is a vector on the line

parametric eqs: $x = x_0 + at$ $y = y_0 + bt$ $z = z_0 + ct$

Symmetric eqs: $\frac{x-x_0}{a} = \frac{y-y_0}{b} = \frac{z-z_0}{c}$

Planes

Scalar eq of plane: $a(x-x_0) + b(y-y_0) + c(z-z_0) = 0$ where $\langle a, b, c \rangle$ is a vector normal to plane

Linear eq of plane: $ax + by + cz + d = 0$

- Use normal vectors to find angle between planes

Distance from point to plane:

$$D = \frac{|ax_1 + by_1 + cz_1 + d|}{\sqrt{a^2 + b^2 + c^2}}$$

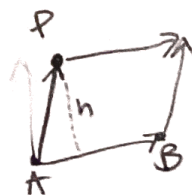
where (x_1, y_1, z_1) is point and plane $ax + by + cz + d = 0$

$$D = \frac{|\vec{n} \cdot \vec{b}|}{|\vec{n}|}$$

Distance from point to line:

$$h = \frac{|\vec{AB} \times \vec{AP}|}{|\vec{AB}|}$$

(area of parallelogram) / (base)



Intersections

Check if direction vectors are parallel (scalar multiples)

Set $x_1 = x_2$, $y_1 = y_2$, $z_1 = z_2$ in terms of t and s

12.6 Cylinders and Quadric Surfaces

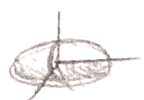
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Cylinder is a surface consisting of all lines through plane

Quadric Surfaces

$$Ax^2 + By^2 + Cz^2 + Dxy + Eyz + Fxz + Gx + Hy + Iz + J = 0$$

Use traces, setting $z, y, x = c$ and graph



Ellipsoid :

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

traces are ellipses
a=b=c sphere

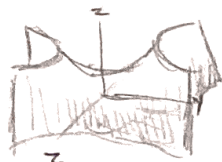


Elliptic

Paraboloid :

$$\frac{z}{c} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$$

traces are ellipses
↓ traces are parabolas



Hyperbolic

Paraboloid :

$$\frac{z}{c} = \frac{x^2}{a^2} - \frac{y^2}{b^2}$$

traces are hyperbolas
↓ traces are parabolas



Cone :

$$\frac{z^2}{c^2} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$$

traces are ellipses
↓ traces $x=k$ hyperbolas
 $k \neq 0$ pairs of lines



Hyperboloid
of One Sheet :

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$$

traces ellipses
↓ traces Hyperbolas



Hyperboloid
of Two Sheets :

$$-\frac{x^2}{a^2} - \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

traces in $z=k$ ellipses
↓ traces are hyperbolas

Chapter 13: Vector Functions

13.1 Vector Functions and Space Curves

$$\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$$

$$\lim_{t \rightarrow a} \vec{r}(t) = \left\langle \lim_{t \rightarrow a} f(t), \lim_{t \rightarrow a} g(t), \lim_{t \rightarrow a} h(t) \right\rangle$$

13.2 Derivatives and Integrals of Vector Func. (6)

$$\vec{r}'(t) = \langle f'(t), g'(t), h'(t) \rangle$$

Unit Tangent Vector: $\vec{T}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$

$$\int_a^b \vec{r}(t) dt = \left\langle \int_a^b f(t) dt, \int_a^b g(t) dt, \int_a^b h(t) dt \right\rangle$$

13.3 Arc Length and Curvature

Arc Length: $s = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt = \int_a^b |\vec{r}'(t)| dt$

$$\frac{ds}{dt} = |\vec{r}'(t)|$$

Reparametrize in terms of s :

$$\vec{r}(t) \Rightarrow \vec{r}(s)$$

① Solve for s

② use eq to solve for t in terms of s

③ Plug t equation into $\vec{r}(t)$

Curvature: how quickly

curve changes direction

$r = \frac{1}{\kappa}$
of osculating circle

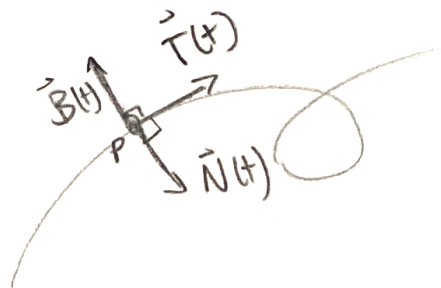
$$\kappa = \frac{|\vec{r}'(t)|}{|\vec{r}''(t)|}$$

or

$$\frac{|\vec{r}'(t) \times \vec{r}''(t)|}{|\vec{r}'(t)|^3}$$

Normal and Binormal vectors

$$\vec{N}(t) = \frac{\vec{T}'(t)}{|\vec{T}'(t)|}$$



$$\vec{B}(t) = \vec{T}(t) \times \vec{N}(t)$$

The vectors $\vec{N}(t)$ and $\vec{T}(t)$ are on the osculating plane

13.4 Motion in Space: Velocity and Acceleration ⑦

position: \vec{r}

velocity: $\vec{v} = \vec{r}'(t)$

acceleration: $\vec{a} = \vec{r}''(t) = \vec{v}'(t)$

Force: $\vec{F} = m \vec{a}(t)$

Projectile Motion

$$\mathbf{a} = \langle 0, -9.8 \rangle$$

$$v(0) = v_0 \quad \alpha = \text{angle}$$

$$\mathbf{r}(t) = \langle (v_0 \cos \alpha)t, (v_0 \sin \alpha)t - \frac{1}{2}gt^2 \rangle$$

$$d = \frac{v_0^2 \sin 2\alpha}{g} = \frac{2v_0^2 \sin \alpha \cos \alpha}{g}$$

Acceleration

$$\vec{a} = v' \vec{T} + \kappa v^2 \vec{N} \quad \text{where } v = |\vec{v}|$$

$$a_T = v'$$

$$a_N = \kappa v^2$$

$$a_T = \frac{\vec{r}'(t) \cdot \vec{r}''(t)}{|\vec{r}'(t)|}$$

$$a_N = \frac{|\vec{r}'(t) \times \vec{r}''(t)|}{|\vec{r}'(t)|^2}$$

