

## Chapter 10: Parametric Equations and Polar Coordinates

## 10.1 Curves Defined by Parametric Equations

Parametric equations:  $x = f(t)$   $y = g(t)$ 

- Know how curves are drawn and direction, how much

## 10.2 Calculus with Parametric Curves

Tangents:  $\frac{dy}{dx} = \frac{dy/dt}{dx/dt}$  if  $\frac{dx}{dt} \neq 0$ 2nd Derivative:  $\frac{d^2y}{dx^2} = \frac{d}{dx} \left( \frac{dy}{dx} \right) = \frac{\frac{d}{dt} \left( \frac{dy}{dx} \right)}{dx/dt}$   
(Concavity)Area:  $A = \int_a^b g(t) f'(t) dt$  if  $x = f(t), y = g(t), a \leq t \leq b$   
↓  
"Arc Length:  $L = \int_a^b \sqrt{\left( \frac{dx}{dt} \right)^2 + \left( \frac{dy}{dt} \right)^2} dt$ Surface Area:  $S = 2\pi \int_a^b y \sqrt{\left( \frac{dx}{dt} \right)^2 + \left( \frac{dy}{dt} \right)^2} dt$  if rotated around x-axis

## 10.3 Polar Coordinates

Polar coordinate system:  $(r, \theta)$ 

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$r^2 = x^2 + y^2$$

$$\tan \theta = \frac{y}{x}$$

rect  $\rightarrow$  polarpolar  $\rightarrow$  rect

Polar graphs $r = c$  : circle $\theta = c$  : lineCardioid/Limacon:  $r = a \pm b \cos \theta$  ,  $r = a \pm b \sin \theta$ Inner loop:  $b > a$ Cardioid (heart):  $a = b$ Roses:  $r = a \cos(n\theta)$  $r = a \sin(n\theta)$ if  $n$  is odd: petals =  $n$ even: petals =  $2n$ Tangents:

$$\frac{dy}{dx} = \frac{\frac{dr}{d\theta} \sin \theta + r \cos \theta}{\frac{dr}{d\theta} \cos \theta - r \sin \theta}$$

since

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \end{aligned}$$

10.4 Areas and Lengths in Polar Coordinates

Area:  $A = \frac{1}{2} \int_a^b r^2 d\theta$

Arc length:  $L = \int_a^b \sqrt{r^2 + \left(\frac{dr}{d\theta}\right)^2} d\theta$

Chapter 12: Vectors and the Geometry of Space12.1 3D Systems

Distance:  $d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$

Eq of sphere:  $(x - a)^2 + (y - b)^2 + (z - c)^2 = r^2$

12.2 Vectors

vector has both magnitude and direction

$$\vec{a} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$$

Magnitude:  $|\mathbf{a}| = \sqrt{a_1^2 + a_2^2 + a_3^2}$

$$\mathbf{a} + \mathbf{b} = \langle a_1 + b_1, a_2 + b_2, a_3 + b_3 \rangle$$

$$\mathbf{a} - \mathbf{b} = \langle a_1 - b_1, a_2 - b_2, a_3 - b_3 \rangle$$

$$c\mathbf{a} = \langle ca_1, ca_2, ca_3 \rangle$$

$$\vec{a} = |a| \langle \cos \theta, \sin \theta \rangle$$

### 12.3 Dot Product

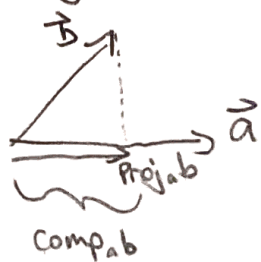
$$\vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2 + a_3 b_3$$

$$\cos \theta = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}| |\vec{b}|}$$

where  $\theta$  is the angle between vectors  $\vec{a}$  and  $\vec{b}$

if  $\vec{a} \cdot \vec{b} = 0$ , vectors are orthogonal

#### Projections



Scalar proj of b onto a

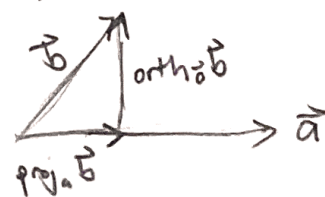
$$\text{comp}_a b = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}|}$$

vector proj of b onto a

$$\text{proj}_a b = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}|^2} \vec{a}$$

#### Orthogonal Vector

$$\text{orth}_a b = \vec{b} - \text{proj}_a b$$



$$\text{Work} = F \cdot D \cos \theta = |\vec{F} \cdot \vec{D}|$$

### 12.4 Cross Product

$$\text{Det. } \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

$$\vec{a} \times \vec{b} = \text{det} \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} \vec{i} - \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} \vec{j} + \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} \vec{k}$$

$\vec{a} \times \vec{b}$  is orthogonal to both  $\vec{a}$  and  $\vec{b}$

$$|\vec{a} \times \vec{b}| = |\vec{a}| |\vec{b}| \sin \theta$$

if  $\vec{a} \times \vec{b} = 0$ , vectors  $\vec{a}$  and  $\vec{b}$  are parallel

$|\vec{a} \times \vec{b}|$  is equal to parallelogram made by  $\vec{a}$  and  $\vec{b}$

Scalar triple product :  $\vec{a} \cdot (\vec{b} \times \vec{c})$  (4)

(Volume of parallel piped) =  $|\vec{a} \cdot (\vec{b} \times \vec{c})|$

Torque :  $\vec{\tau} = \vec{r} \times \vec{F}$   $|\tau| = |\vec{r} \times \vec{F}| = |\vec{r}| |\vec{F}| \sin \theta$

## 12.5 Equations of Lines and Planes

Vector eq of Line :  $\vec{r} = \vec{r}_0 + t \vec{v}$  where  $\vec{v}$  is a direction vector and  $\vec{r}_0$  is a vector on the line

parametric eqs :  $x = x_0 + at$   $y = y_0 + bt$   $z = z_0 + ct$

Symmetric eqs :  $\frac{x-x_0}{a} = \frac{y-y_0}{b} = \frac{z-z_0}{c}$

## Planes

Scalar eq of plane :  $a(x-x_0) + b(y-y_0) + c(z-z_0) = 0$  where  $\langle a, b, c \rangle$  is a vector normal to plane

Linear eq of plane :  $ax + by + cz + d = 0$

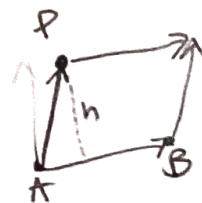
- Use normal vectors to find angle between planes

Distance from point to plane :  $D = \frac{|ax_1 + by_1 + cz_1 + d|}{\sqrt{a^2 + b^2 + c^2}}$  where  $(x_1, y_1, z_1)$  is point and plane  $ax + by + cz + d = 0$

$$D = \frac{|\vec{n} \cdot \vec{b}|}{|\vec{n}|}$$

Distance from a point to line :  $h = \frac{|\vec{AB} \times \vec{AP}|}{|\vec{AB}|}$

(area of parallelogram) / (base)



## Intersections

Check if direction vectors are parallel (scalar multiples)

Set  $x_1 = x_2$ ,  $y_1 = y_2$ ,  $z_1 = z_2$  in terms of  $t$  and  $s$



# 12.6 Cylinders and Quadric Surfaces

Cylinder is a surface consisting of all lines through plane

Quadric Surfaces

$$Ax^2 + By^2 + Cz^2 + Dxy + Eyz + Fxz + Gx + Hy + Iz + J = 0$$

Use traces, setting  $z, y, x = c$  and graph



Ellipsoid :

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

traces are ellipses  
 $a=b=c$  sphere



Elliptic  
Paraboloid :

$$\frac{z}{c} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$$

# traces are ellipses  
√ traces are parabolas



Hyperbolic  
Paraboloid :

$$\frac{z}{c} = \frac{x^2}{a^2} - \frac{y^2}{b^2}$$

# traces are hyperbolas  
√ traces are parabolas



Cone :

$$\frac{z^2}{c^2} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$$

# traces are ellipses  
√ traces  $x=k$  hyperbolas  
 $k \neq 0$  pairs of lines



Hyperboloid  
of One Sheet :

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$$

# traces ellipses  
√ traces Hyperbolas



Hyperboloid  
of Two Sheets :

$$-\frac{x^2}{a^2} - \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

# traces in  $z=k$  ellipses  
√ traces are hyperbolas

## Chapter 13: Vector Functions

### 13.1 Vector Functions and Space Curves

$$\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$$

$$\lim_{t \rightarrow a} \vec{r}(t) = \left\langle \lim_{t \rightarrow a} f(t), \lim_{t \rightarrow a} g(t), \lim_{t \rightarrow a} h(t) \right\rangle$$

## 13.2 Derivatives and Integrals of Vector Func. (6)

$$\vec{r}'(t) = \langle f'(t), g'(t), h'(t) \rangle$$

Unit Tangent Vector:  $\vec{T}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$

$$\int_a^b \vec{r}(t) dt = \left\langle \int_a^b f(t) dt, \int_a^b g(t) dt, \int_a^b h(t) dt \right\rangle$$

## 13.3 Arc Length and Curvature

Arc Length:  $s = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt = \int_a^b |\vec{r}'(t)| dt$

$$\frac{ds}{dt} = |\vec{r}'(t)|$$

Reparametrize in terms of  $s$ :

$$\vec{r}(t) \Rightarrow \vec{r}(s)$$

① Solve for  $s$

② use eq to solve for  $t$  in terms of  $s$

③ Plug  $t$  equation into  $\vec{r}(t)$

Curvature: how quickly curve changes direction

$\kappa = \frac{1}{r}$   
of osculating circle

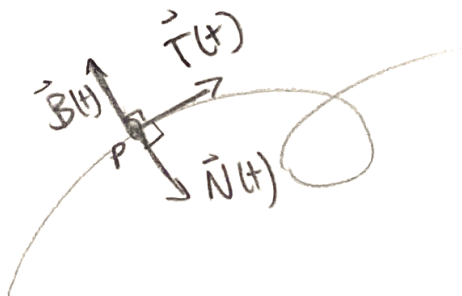
$$\kappa = \frac{|\vec{T}'(t)|}{|\vec{r}'(t)|}$$

or

$$\frac{|\vec{r}'(t) \times \vec{r}''(t)|}{|\vec{r}'(t)|^3}$$

Normal and Binormal vectors

$$\vec{N}(t) = \frac{\vec{T}'(t)}{|\vec{T}'(t)|}$$



$$\vec{B}(t) = \vec{T}(t) \times \vec{N}(t)$$

The vectors  $\vec{N}(t)$  and  $\vec{T}(t)$  are on the osculating plane

# 13.4 Motion in Space: Velocity and Acceleration ⑦

position:  $\vec{r}$

velocity:  $\vec{v} = \vec{r}'(t)$

acceleration:  $\vec{a} = \vec{r}''(t) = \vec{v}'(t)$

Force:  $\vec{F} = m \vec{a}(t)$

## Projectile Motion

$$a = \langle 0, -9.8 \rangle$$

$$v(0) = v_0 \quad \alpha = \text{angle}$$

$$\vec{r}(t) = \langle (v_0 \cos \alpha)t, (v_0 \sin \alpha)t - \frac{1}{2}gt^2 \rangle$$

$$d = \frac{v_0^2 \sin 2\alpha}{g} = \frac{2v_0^2 \sin \alpha \cos \alpha}{g}$$

## Acceleration

$$\vec{a} = v' \vec{T} + K v^2 \vec{N}$$

$$\text{where } v = |\vec{v}|$$

$$a_T = v'$$

$$a_N = K v^2$$

$$a_T = \frac{\vec{r}'(t) \cdot \vec{r}''(t)}{|\vec{r}'(t)|}$$

$$a_N = \frac{|\vec{r}'(t) \times \vec{r}''(t)|}{|\vec{r}'(t)|}$$

