#### What it is:

An analog X-Y pen plotter output to HP-GL translator. (Hewlett-Packard Graphics Language (http://en.wikipedia.org/wiki/HPGL)

## What it does:

Some measurement devices, like the Tektronix 2232 Digital Storage Oscilloscope, have an analog X-Y pen plotter output port so that the display image can be captured to an analog X-Y pen plotter or recorder. See oscilloscope display, below.

The problem is one wishes to capture the display image in digital form onto a modern day personal computer, since analog pen plotters are virtually extinct. PC images can be pasted directly into documents.

The 'Analog X-Y Pen Plotter Output To HP-GL Translator' will continually sample the X and Y analog voltages from the plotter port, digitize them, and package the values into a series of plain text HP-GL plotter commands, which are output via a USB port to a file on a PC. The HP-GL file can be processed into a display image by any commonly available plotter emulator application, such as PrintCapture (http://www.printcapture.com). See actual plot image, below.

#### What it's made of:

- 1. <u>Arduino UNO</u> for the ADC conversions, digital filtering, assembly of HP-GL commands and serial output.
- 2. Arduino 'Shield' type board for signal conditioning (voltage translation), voltage reference and power monitoring. See schematic and boards, below.
- 3. DB9 cable for connection to the oscilloscope plotter port. See Auxiliary Connector, below.
- 4. USB cable between Arduino UNO and PC.
- 5. 9VDC AC adapter (a wall wart).

## What's on the Arduino shield board:

The Arduino shield board contains circuitry comprised of (see schematic);

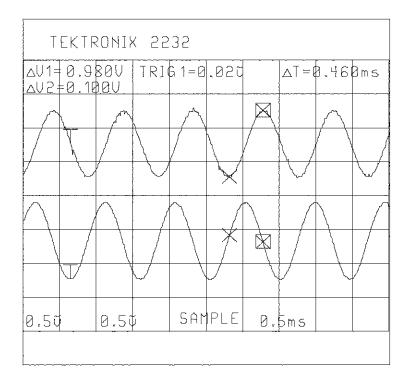
- 1. Two (2) precision, unity-gain differential amplifiers (wired as summing amps) to translate the ±2.5V analog X and Y voltages into 0 to 5V for the Arduino analog pins. U2, U3
- A 'charge pump' voltage converter to convert 9VDC to ±9VDC to power the amplifiers. U1, C1,
   C2
- 3. A precision 2.50V voltage reference to the amplifiers for the voltage translation. U4
- 4. A precision 5.00V voltage reference to the Arduino AREF pin. U5
- 5. A voltage divider network so the 9V Vin can be reduced to 5V for the Arduino analog pin. A schottky diode protects the pin if a higher voltage power supply is used. R1, R2, D1
- 6. A bi-color red/green LED as a Go/No Go indicator that the 9V power supply is connected, or not. The Arduino sketch will stay in the setup() routine until a 9VDC, or greater, power supply is plugged into the Arduino UNO. These IC's cannot run accurately on the USB ~5V power! LED, R3
- 7. A slide switch to start the data stream and stop it when the plot is completed. S1
- 8. A pair of capacitors to filter the DAC dithering of the plotter port X and Y voltage signals. C9, C10
- 9. A 10-pin header for connection to the oscilloscope plotter port. J1

## Operation:

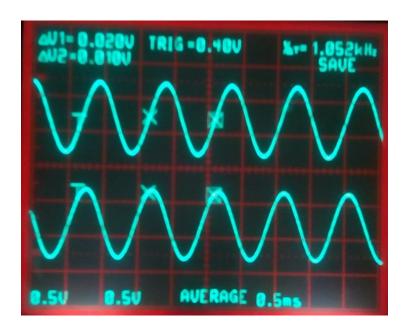
- 1. Slide switch to OFF.
- 2. Connect Arduino via DB-9 connector to oscilloscope plotter port.
- 3. Connect Arduino USB to PC. Arduino powers up, LED is red.
- 4. Connect 9VDC power to Arduino. LED is green.
- 5. Launch listening application, like TeraTerm or PrintCapture. Ensure your application is set to the Arduino UNO COM port 6, 115200, 8, none, 1.
- 6. Slide switch to ON. (data stream commences)
- 7. Immediately press PLOT key on scope.
- 8. When scope plot completes immediately slide switch to OFF. (data stream halts)
- 9. Reset Arduino in order to start the next plot.

## Example HP-GL output to file:

```
IN;
PS8900,8900;
IPO,0,8900,8900;
SC0,250,0,1023,1;
PU;
           // Pen Up
SP1;
PA77,984; // Plot Absolute to (77,984)
           // more data points (PA) every 1.6 milliseconds
PD;
            // Pen Down
PA53,92;
           // more data points (PA) every 1.6 milliseconds
PU;
SP;
IN;
```

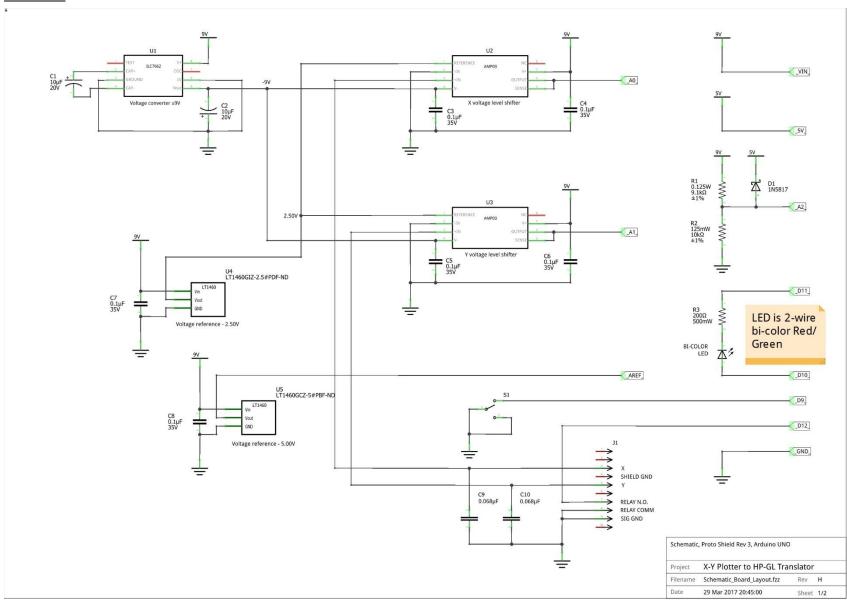


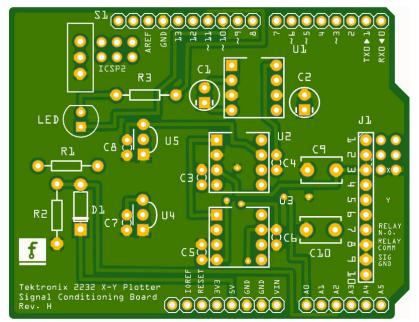
Actual plot image from an HP-GL file created by the Translator of a Tektronix 2232 oscilloscope display. Image created by <a href="PrintCapture">PrintCapture</a>.



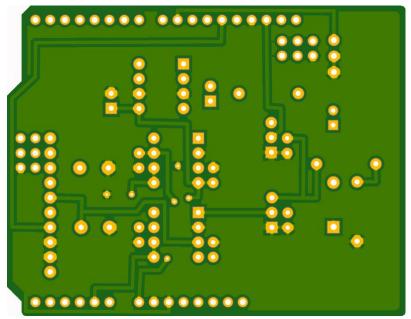
Actual Tektronix 2232 oscilloscope display.

# Schematic:

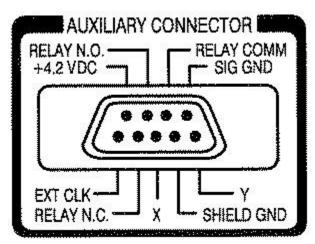




Arduino shield board front



Arduino shield board back



Tektronix Auxiliary Connector for X-Y plotter. Relay is for pen up/down

## Arduino Sketch:

```
*************************
* Tektronix 2232 Digital Storage Oscilloscope analog X-Y pen plotter to HP-GL
* translator. (Hewlett-Packard Graphics Language http://en.wikipedia.org/wiki/HPGL)
* John Horstman
* 3/19/2017 Rev H
* This sketch continuously reads the X and Y analog pen plotter voltages, and the
* pen up/down signal, and packages the ADC values in successive HP-GL commands. The
* commands can be serially output to a file, via TeraTerm, or to a plotter application
* like PrintCapture at http://www.printcapture.com/.
* The HP-GL commands used in this sketch are:
* IN; Initialize
* PS: Plot size
* IP; Input P1 & P2
* SC; Scale
* SP; Select pen
* PU; Pen UP
* PD; Pen DOWN
* PA; Plot Absolute
* Example HPGL output of this sketch:
* IN;
* PS8900,8900;
* IPO,0,8900,8900;
* SC0,250,0,1023,1;
* PU;
* SP1;
* PA77,984;
             // data points every 1.6 milliseconds
* ...
* PD;
* PA53,92;
* ...
* PU;
* SP;
* IN;
* This sketch is for Arduino UNO with Proto Shield. The Proto Shield contains signal
* conditioning circuitry comprised of;
* 1. Two (2) precision, unity-gain differential amplifiers (wired as summing amps)
    to translate the ±2.5V analog X and Y voltages into 0 to 5V for the Arduino analog
\star 2. A 'charge pump' voltage converter to convert 9VDC to \hat{A}\pm 9VDC to power the amplifiers.
* 3. A precision 2.50V voltage reference to the amplifiers for the voltage translation.
* 4. A precision 5.00V voltage reference to the Arduino AREF pin.
```

```
* 5. A voltage divider network so the 9V Vin can be reduced to 5V for the Arduino
      analog pin. A schottky diode protects the pin if a higher voltage power supply
      is used.
 * 6. A bi-color red/green LED as a Go/No Go indicator that the 9V power supply
     is connected, or not. This sketch will stay in the setup() routine until a
      9VDC, or greater, power supply is plugged in to the Arduino. These IC's
      cannot run accurately on the USB ~5V power!
 * 7. A slide switch to start the data stream and stop it when the plot is completed.
 * 8. A pair of capacitors to filter the DAC dithering of the plotter X-Y voltage signals.
 * 9. A 9-pin cable with DB-9 male connector for connection to the oscilloscope plotter
      port.
 * Operation:
 * Slide switch to OFF.
 * Connect Arduino via DB-9 connector to oscilloscope plotter port.
 * Connect Arduino USB to PC. Arduino powers up, LED is red.
 * Connect 9VDC power to Arduino. LED is green.
 * Launch listening application, like TeraTerm or PrintCapture. Ensure your application
 * is set to the Arduino COM port 6, 115200, 8, none, 1.
 * Slide switch to ON. (data stream commences)
 * Immediately press PLOT key on scope.
 * When scope plot completes immediately slide switch to OFF. (data stream halts)
 * Reset Arduino in order to start the next plot.
* /
//#define serial plotter // uncomment to calibrate with Arduino Serial Plotter tool
//#define dummy data // uncomment to use dummy data for testing
// The pins
#define TestPin 8  // Digital pin 8
#define SwitchPin 9 // Digital pin 9
#define LEDGreenPin 10 // Digital pin 10
#define LEDRedPin 11 // Digital pin 11
#define PenInputPin 12 // Digital pin 12
#define IdleLED 13  // Digital pin 13
#define X voltage 0  // Analog pin A0
#define Y voltage 1 // Analog pin A1
#define VinVoltage 2 // Analog pin A2
// The numbers
unsigned long LoopTime; // Marker for loop() delay timer
unsigned int PenState = HIGH;  // Default pen up
unsigned int OldPenState = PenState; //
const unsigned int numReadings = 8;
                                         // Must be a power of two so we can right shift later
unsigned int Xreadings[numReadings];
                                         // Arrays for computing moving average for smoothing
unsigned int Yreadings[numReadings];
unsigned int Xtotal = numReadings * 511; // Arrays will be preloaded
unsigned int Ytotal = Xtotal;
unsigned int readIndex = 0;
                                         //
const unsigned int dcXOffset = 0; //21; // Compensate for any DC offset. Adjust this to get approximately 511,511.
```

```
const unsigned int dcYOffset = 0; //23; //
// The strings
String ADCXStr; // ADC X counts string
String ADCYStr; // ADC Y counts string
String CmdStr; // HPGL command string
#ifdef dummy data
const float slew = 614.0; // max slew rate is 3.0 volts/second = 614 counts/second (@5 volts = 1023 counts)
const float Freq = (1.0/PI) * (slew / 1023.0); // This frequency sinusoidal will have that slew rate (at the zero crossing)
const float TWO PI F = 2.0 * PI * Freq;
#endif
 void setup() {
 // Set I/O pins
 pinMode(TestPin, OUTPUT); // timing test pin
 pinMode(IdleLED, OUTPUT);
 pinMode (LEDRedPin, OUTPUT);
 pinMode(LEDGreenPin, OUTPUT);
  pinMode (SwitchPin, INPUT PULLUP);
 pinMode (PenInputPin, INPUT PULLUP); // Pen signal is from Normally Open (N.O.) relay contacts
  analogReference(DEFAULT);
 // Set LEDs
  digitalWrite(IdleLED, HIGH); // Turn on 'idle' LED
  digitalWrite(LEDRedPin, LOW); // Turn red/green LED off
  digitalWrite(LEDGreenPin, LOW);
  // initialize serial communication:
 Serial.begin(115200);
 // Check for 9V Vin external power, stay in setup() until 9V supply connected
  * Why 900 counts? To gaurantee that a 7.5 VDC±5% power pack will not trigger the
  * 'Go' signal under maximal conditions:
   * 7.5v+5%; R1\Omega-1%; R2\Omega+1%; USB 5v-5% (AREF); +3 counts (2 LSB ADC error)
  while (analogRead(VinVoltage) < 900) {</pre>
   digitalWrite(LEDRedPin, HIGH); // Turn LED red (no-go)
   digitalWrite(LEDGreenPin, LOW);
   delay(100);
  } // Wait here until user plugs in a 9VDC, or greater, power supply
  // Vin OK, continue
  digitalWrite(LEDRedPin, LOW); // Turn LED green (go)
  digitalWrite(LEDGreenPin, HIGH);
```

```
//Wait here for switch to be switched on (ground the pin)
 while (digitalRead(SwitchPin) == HIGH) {
   delay(100);
  // User is ready for data stream, let 'er rip!
  analogReference (EXTERNAL); // External precision 5.00V reference
  // Preset the averaging arrays
  for (int thisReading = 0; thisReading < numReadings; thisReading++) {</pre>
 Xreadings[thisReading] = 511;
 Yreadings[thisReading] = 511;
  digitalWrite(IdleLED, LOW); // turn off 'idle' LED, transmission will commence (TX LED will light)
  // HP-GL plot header commands
  Serial.println("IN;"); // Initialize
  Serial.println("PS8900,8900;"); // Plot size; A-size
  Serial.println("IPO,0,8900,8900;"); // Input Scaling Points P1 & P2; A-size drawing (8.5" x 11", less margins)
  Serial.println("SC0,1023,0,1023,1;"); // Scale; Isotropic
 //Serial.println("OH;"); // Output hard clip limits
 //Serial.println("OP;"); // Output P1 & P2
 Serial.println("PU;"); // Pun Up
 Serial.println("SP1;"); // Select Pen 1
} // end setup
 void loop() {
 LoopTime = micros(); // mark loop start
 // Read X, Y and Pen signals as close together as possible and compute a moving average for smoothing
 Xtotal -= Xreadings[readIndex]; // Subtract an old value from the total
 Ytotal -= Yreadings[readIndex]; //
  PenState = digitalRead(PenInputPin); // Read pen input; returns HIGH or LOW
 Xreadings[readIndex] = analogRead(X voltage) - dcXOffset; // compensate for dc offset
  delayMicroseconds(16); // Delay two ADC clock cycles (there is less 'jitter' on the Y readings than for a one ADC clock cycle
dalay, don't ask me why)
  Yreadings[readIndex] = analogRead(Y voltage) - dcYOffset;
 Xtotal += Xreadings[readIndex]; // Add the new value to the total
 Ytotal += Yreadings[readIndex++]; // Increment readIndex here
  readIndex %= numReadings; // Wrap around readIndex here
 ADCXStr = Xtotal >> 3; // Total divided by numReadings (and convert to string)
```

```
ADCYStr = Ytotal >> 3;
//
// If pen has changed state then output pen command
// Pen UP signal is HIGH (relay open, interanl pull up resistor), pen DOWN is LOW (relay closed to ground)
if (PenState != OldPenState) {
  (PenState == HIGH) ? (CmdStr = "PU;") : (CmdStr = "PD;");
  OldPenState = PenState; // Remember pen state
  Serial.println(CmdStr);
#ifdef dummy data
// dummy data for now, plot a circle
 float t = (float)millis() / 1000.0;
 float arg = TWO PI F * t;
 ADCXStr = int(511.5*cos(arg)+511.5);
  ADCYStr = int(511.5*sin(arg)+511.5);
#endif
#ifdef serial plotter
  int Pen;
  (PenState == HIGH) ? Pen = 10 : Pen = 0; // View the Pen up/down signal
  CmdStr = "1023 0 " + ADCXStr + " " + ADCYStr + " " + Pen; // 1023 0 prevents autoscaling
  // 'Plot Absolute' Ex: PA1023,250;
  CmdStr = "PA" + ADCXStr + "," + ADCYStr + ";";
#endif
Serial.println(CmdStr);
// If switch went HIGH, output final commands, stop data stream, the plot is completed, wait here until RESET
if (digitalRead(SwitchPin) == HIGH) {
  Serial.println("PU;");
  Serial.println("SP;");
  Serial.println("IN;");
  while (true) { // wait here for RESET
    // flash 'idle' LED to indicate need for reset
    digitalWrite(IdleLED, HIGH);
    delay(200);
    digitalWrite(IdleLED, LOW);
    delav(300);
  }
//
/* Wait here for remainder of loop time.
 * Full scale plot swing is 1023 counts in 1.667 seconds (5 volt full swing / 3.0 volts/second).
 * So, no more than one plot command every 1.630ms is necessary (1.667/1023). ~614 samples/second.
```

```
*/
while (micros() - LoopTime < 1630) {;} // wait here for remainder of loop time

// Short (0.250µs) output pulse to test loop timing.
PORTB |= B1; PORTB ^= B1; // digitalWrite(TestPin, HIGH); digitalWrite(TestPin, LOW);
} // end loop</pre>
```

# Part List:

Reference	Quantity	Part Number	Description
C1,C2	2	USR1E100MDD1TP	Aluminum Electrolytic Capacitors - Leaded 10uF 25V 85c 4x7 20% 1.5LS
C3,C4,C5,C6,C7,C8	6	TAP104K035SRW	Tantalum Capacitors - Solid Leaded 35volts 0.1uF 10%
C9,C10	2	BFC237042682	CAP FILM 6800PF 5% 250VDC RADIAL
D1	1	1N5817	DIODE SCHOTTKY 20V 1A DO41
J1	1	68001-410HLF	CONN HEADER 10POS .100 STR TIN
LED	1	B4301H1/5	T1 3/4, 2 Lead, Red/Green LED with Clear Lens Cap Mounting Clip
R1	1	RN55D9101FB14	Metal Film Resistors - Through Hole 1/8watt 9.1Kohms 1% 100ppm
R2	1	RN55D1002FB14	Metal Film Resistors - Through Hole 1/8watt 10Kohms 1% 100ppm
R3	1	OF201JE	Carbon Composition Resistors 1/2W 200 ohms 5%
S1	1	TS02CBE	Slide Switches Switch Slide Spst Pc Mnt
U1	1	ICL7662CPA+	IC REG SWTCHD CAP INV RATIO 8DIP
U2,U3	2	AMP03GPZ	IC OPAMP DIFFERENTIAL 3MHZ 8DIP
U4	1	LT1460GIZ-2.5#PBF	IC VREF SERIES 2.5V TO92-3
U5	1	LT1460GCZ-5#PBF	IC VREF SERIES 5V TO92-3
			Off board parts
	Quantity	Part Number	Description
	1	15388100	CONN CIC FFC RCPT 10POS 2.54MM
	1	30-9506-99	CABLE DB9 FEMALE/MALE 6'
	1	SWI6-9-N-P5	AC/DC WALL MOUNT ADAPTER 9V 6W

# Cost:

Arduino UNO	\$25
Arduino Proto Shield	\$8
(needed for the headers only. I spun my own board)	
Parts (25)	\$57
Board by <u>Aiser</u> (qty 3)	\$34 (€31)
Total	\$124 (€114)

# References:

- Atmel ATmega328/P 8-bit AVR Microcontroller Datasheet.
- Arduino Programming Nootebook by Brian W. Evans.
- Arduino Uno Rev3 Schematic
- Tektronix 2232 Digital Storage Oscilloscope User Manual, 070-7066-01
- Tektronix 2232 Digital Storage Oscilloscope Service Manual, 070-7067-01
- The HP-GL/2 and HP RTL Reference Guide, A Handbook for Program Developers, 5961-3526