Divide and Conquer

Table of Contents

- Overview
- General divide and conquer recurrence relation
- Binary Tree
 - Height
- Tree traversals
- Closest Pair

Overview

- divide and conquer:
 - split into multiple smaller problems
 - solve these: typically recursive, and may become brute force when sufficiently small
 - combine sub-problem results to get final solution

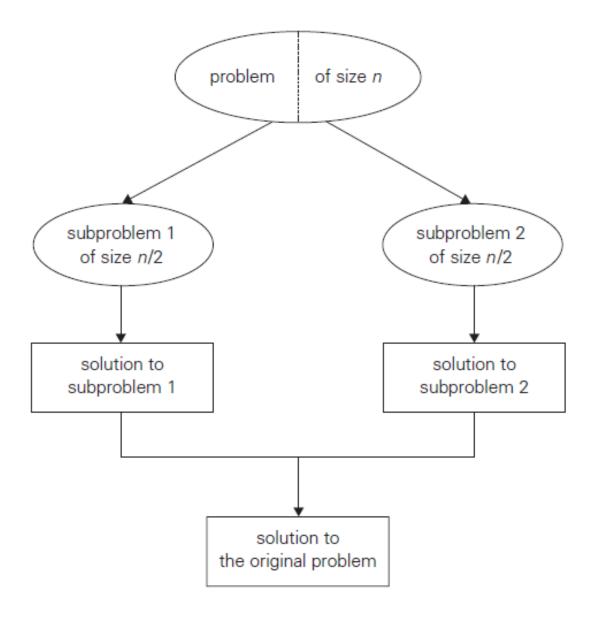


Figure 1: divide_and_conquer

- not necessarily more efficient than brute force
- some divide and conquer algorithms are the most efficient algorithms possible
- well suited to parallel computation, where each subproblem is solved simultaneously on a distinct processor

General divide and conquer recurrence relation

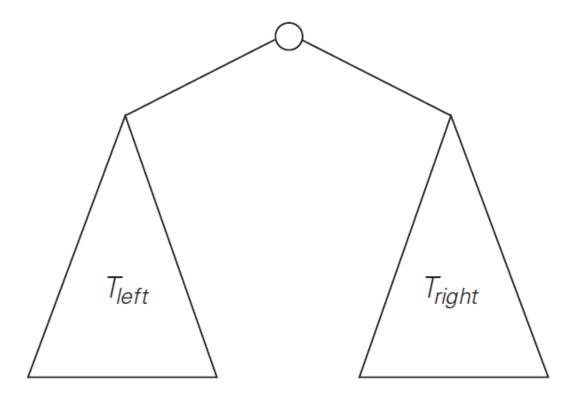
- problem size n can be divided into b sub-problems of size n/b, with a sub-problems needing to be solved
 - i.e. $a \ge 1, b > 1$, with a, b constants
- with $n = b^k$ for some $k \in \mathbb{Z}^+$: time complexity T(n)

$$T(n) = aT(\frac{a}{b}) + f(n)$$

- f(n): time spent dividing into subproblems and combining subproblem solutions
- applying the master theorem: if $f(n) \in \Theta(n), k > 0$:

$$T(n) \in \begin{cases} \Theta(n^k) \text{ if } a < b^k \\ \Theta(n^k \log n) \text{ if } a = b^k \\ \Theta(n^{\log a_b)} \text{ if } a > b^k \end{cases}$$

Binary Tree



- Binary tree T: finite set of nodes; a root + 2 disjoint binary trees T_L (left) and T_R ; otherwise empty
 - all subtrees are also binary trees: many problems can be approached with divide and conquer/recursive algorithms
 - not all questions about binary trees require traversal of entire tree
 - e.g. search and insert requires processing one of two subtrees

Height

• height: length of longest path from root to leaf

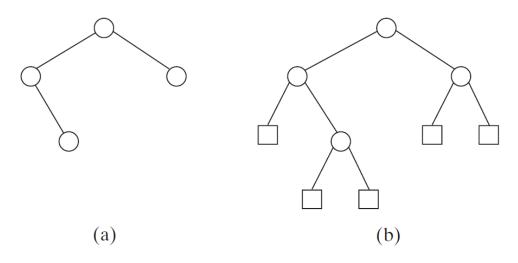
```
1 """
2 Recusively compute height of binary tree
3 input: binary tree T
4 output: height of T
5 """
6 Height(T):
7 if T is empty:
8 return -1
```

```
9 else:
10 return max(Height(T_L), Height(T_R) + 1
```

- measure instance size by number of nodes n(T)
- number of comparisons for max height will be the same as number of additions A(n(T)), so for n(T)>0 with A(0)=0:

$$A(n(T)) = A(n(T_L)) + A(n(T_R)) + 1$$

- checking the tree is empty is actually the most common operation here
- consider the tree drawn with internal nodes (circles) and empty children as external nodes



(rectangles)

- \implies comparison to empty set occurs for *all* internal and external nodes, while addition is only for internal nodes
- for a full binary tree with n internal nodes, every node except the root is 1 of 2 children
- total internal + external nodes is then:

$$n + x = 2n + 1$$

So

$$x = n + 1$$

Number of comparisons to empty tree C(n) is then:

$$C(n) = n + x = n + 1$$

Number of additions A(n) is:

$$A(n) = n$$

Tree traversals

• most import divide and conquer algorithms for trees are tree traversals

- **preorder traversal**: root \rightarrow left subtree \rightarrow right subtree

- inorder traversal: left subtree \rightarrow root \rightarrow right subtree

- **postorder traversal**: left subtree \rightarrow right subtree \rightarrow root

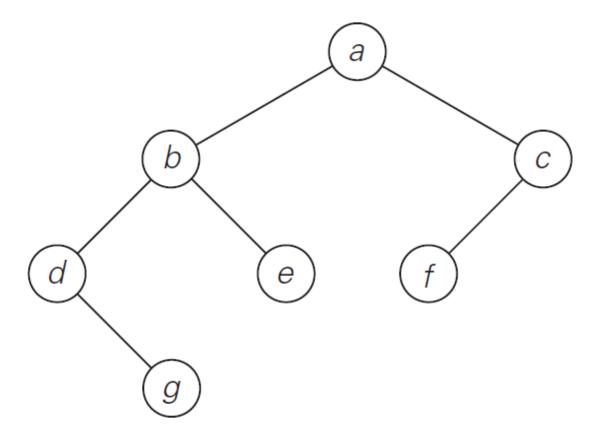


Figure 2: tree_traversals

 $\bullet \ \, {\rm preorder} \hbox{:}\ \, a,b,d,g,e,c,f$

• inorder: d, g, b, e, a, f, c

• postorder: g, d, e, b, f, c, a

• efficiency: identical to that of height, as recursive calls are made for each node of extended binary tree

Closest Pair

- brute force closest pair: $\Theta(n^2)$
- P: set of n > 1 distinct points in Cartesian plane, ordered by x-coordinate (non-decreasing)
- Q: set of n > 1 distinct points in Cartesian plane, ordered by y-coordinate (non-decreasing)
- if 2 < n < 3: solve by brute force
- n > 3:
 - divide points into 2 subsets P_l, P_r of size $\lfloor n/2 \rfloor$, analogous to vertical line through median x-coordinate
 - solve recursively for P_l, P_r , to produce minimum distance d_l, d_r
 - combine result: $d = \min d_l, d_r$
 - now need to consider whether there are any pairs of points $p_l \in P_l, p_r \in P_r$ such that $dist(p_l, p_r) < d$; i.e. are there any points between P_l, P_r closer than d that we missed by splitting up the problem?
 - only need to consider points from a strip of width 2d around the median, call these points S obtained from Q
 - scan S, looking for any points closer than $d_{m}in$:
 - * for a point p'(x', y') to be closer to p(x, y) than $d_m in$, the point must follow p'(x, y)
 - * i.e. $|y y'| < d_m in$
 - $\star~$ so p^\prime must be in a rectangle with width 2d and height d_min
 - \star rectangle can only contain a few points as points in left and right rectangle must be at least d distance apart
 - * can be shown that rectangle has ≤ 8 points (more rigorously ≤ 6)
 - * algorithm considers no more than 5 next points on list S before moving to the next p
- linear time for dividing problem in two
- linear time for combining solutions
- if *n* is a power of 2:

$$T(n) = 2T(\frac{n}{2}) + f(n)$$

where $f(n) \in \Theta(n)$ Applying master theorem, with a = 2, b = 2, d = 1:

$$T(n) \in \Theta(n \log n)$$

- best efficiency possible for this problem: can be shown that any algorithm for this problem is $\Omega(n\log n)$

```
1 EfficientClosestPair(P, Q):
2 # solve closest pair using divide and conquer
3 # input: array P of n >= 2 points sorted in nondecreasing order in x-
4 #
            array Q in >= 2 points sorted in nondecreasing order in y-
      coord
5 # output: euclidean distance between closest pair of points
6 if n <= 3:
       return BruteForceClosestPair(P, Q)
7
8 else:
9
       copy first ceil(n/2) points of P to array P_l
10
       copy same ceil(n/2) points of Q to array Q_l
       copy remaining floor(n/2) points of P to array P_r
11
       copy same floor(n/2) points of Q to Q_r
12
       d_l = EfficientClosestPair(P_l, Q_l)
14
       d_r = EfficientClosestPair(P_r, Q_r)
       d = \min(d_l, d_r)
       m = P[ceil(n/2)-1].x
16
       copy all points of Q for which abs(x-m) < d into S[0..num-1]
       dminsq = d^2
18
19
       for i = 0 to num-2:
20
           k = i + 1
           while k <= num-1 and (S[k].y-S[i].y)^2 < dminsq:
21
               dminsq = min((S[k].x-S[i].x)^2+(S[k].y-S[i].y)^2, dminsq)
22
23
               k += 1
24
25
       return sqrt(dminsq)
```