view_frames Result Recorded at time: 1612434224.072 world Broadcaster: /map_tfA_fetch1075_2948_351775703621313053 Average rate: 10.207 Hz Most recent transform: 1612434224.051 (0.022 sec old) Buffer length: 4.507 sec Broadcaster: /map_tf02_fetch1075_2948_6818341207471055347 Broadcaster: /map_tf00_fetch1075_2948_2743084831236826793 Broadcaster: /map_tf04_fetch1075_2948_3992693322383446703 Broadcaster: /map_tf06_fetch1075_2948_1900341524653032962 Broadcaster: /map_tf08_fetch1075_2948_2828541037517221912 Average rate: 10.212 Hz Average rate: 10.199 Hz Average rate: 10.206 Hz Average rate: 10.215 Hz Average rate: 10.213 Hz Most recent transform: 1612434224.110 (-0.038 sec old) Most recent transform: 1612434224.060 (0.012 sec old) Most recent transform: 1612434224.067 (0.006 sec old) Most recent transform: 1612434224.048 (0.025 sec old) Most recent transform: 1612434224.022 (0.050 sec old) Buffer length: 4.605 sec Buffer length: 4.503 sec Buffer length: 4.504 sec Buffer length: 4.505 sec Buffer length: 4.510 sec eng2/1f eng2/7f eng2/3f eng2/2f eng2/8f Broadcaster: /map_tfB_fetch1075_2948_8945247658257955516 Broadcaster: /tf_mux Average rate: 10.212 Hz Average rate: $10.20\overline{6}$ Hz Most recent transform: 1612434224.037 (0.035 sec old) Most recent transform: 1612434224.050 (0.023 sec old) Buffer length: 4.504 sec Buffer length: 4.507 sec eng2/7f/73B2 Broadcaster: /amcl Average rate: 15.215 Hz Most recent transform: 1612434224.414 (-0.342 sec old) Buffer length: 4.535 sec odom Broadcaster: /ukf_se Average rate: 50.418 Hz Most recent transform: 1612434223.966 (0.106 sec old) Buffer length: 4.562 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /base_footprint_tf_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.216 Hz Average rate: 50.216 Hz Average rate: 50.216 Hz Average rate: 28.912 Hz Average rate: 50.216 Hz Average rate: 28.912 Hz Average rate: 28.912 Hz Average rate: 2.221 Hz Most recent transform: 1612434224.504 (-0.431 sec old) | Most recent transform: 1612434224.504 (-0.431 sec o Buffer length: 4.620 sec Buffer length: 4.600 sec Buffer length: 4.620 sec Buffer length: 4.620 sec Buffer length: 4.620 sec Buffer length: 4.600 sec Buffer length: 4.600 sec Buffer length: 4.501 sec torso_lift_link laser_link l_wheel_link r_wheel_link estop_link torso_fixed_link base_footprint base_camera_mount Broadcaster: /robot_state_publisher Average rate: 28.912 Hz Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.216 Hz Average rate: 28.912 Hz Average rate: 28.912 Hz Most recent transform: 1612434224.504 (-0.431 sec old) | Most recent transform: 1612434223.976 (0.097 sec old) | Most recent transform: 1612434223.976 (0.097 sec old) | Most recent transform: 1612434223.976 (0.097 sec old) Buffer length: 4.620 sec Buffer length: 4.600 sec Buffer length: 4.600 sec Buffer length: 4.600 sec head_pan_link bellows_link shoulder_pan_link bellows_link2 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /respeaker_transformer Average rate: 50.216 Hz Average rate: 28.912 Hz Average rate: 28.912 Hz Average rate: 10.210 Hz Most recent transform: 1612434223.976 (0.097 sec old) Most recent transform: 1612434224.504 (-0.431 sec old) Most recent transform: 1612434223.976 (0.097 sec old) Most recent transform: 1612434224.035 (0.037 sec old) Buffer length: 4.620 sec Buffer length: 4.600 sec Buffer length: 4.505 sec Buffer length: 4.600 sec shoulder_lift_link head_box_link head_tilt_link respeaker_base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 28.912 Hz Average rate: 50.216 Hz Most recent transform: 1612434224.504 (-0.431 sec old) Most recent transform: 1612434223.976 (0.097 sec old) Buffer length: 4.620 sec Buffer length: 4.600 sec head_camera_link upperarm_roll_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.216 Hz Average rate: 28.912 Hz Average rate: 50.216 Hz Most recent transform: 1612434224.504 (-0.431 sec old) Most recent transform: 1612434223.976 (0.097 sec old) Most recent transform: 1612434224.504 (-0.431 sec old) Buffer length: 4.620 sec Buffer length: 4.620 sec Buffer length: 4.600 sec head_camera_rgb_frame head_camera_depth_frame elbow_flex_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.216 Hz Average rate: 28.912 Hz Average rate: 50.216 Hz Most recent transform: 1612434224.504 (-0.431 sec old) Most recent transform: 1612434224.504 (-0.431 sec old) Most recent transform: 1612434223.976 (0.097 sec old) Buffer length: 4.620 sec Buffer length: 4.620 sec Buffer length: 4.600 sec head_camera_depth_optical_frame head_camera_rgb_optical_frame forearm_roll_link Broadcaster: /robot_state_publisher Broadcaster: /display_point Average rate: 7.249 Hz Average rate: 28.912 Hz Most recent transform: 1612434223.933 (0.139 sec old) Most recent transform: 1612434223.976 (0.097 sec old) Buffer length: 4.600 sec Buffer length: 4.553 sec wrist_flex_link ray_target Broadcaster: /robot_state_publisher Average rate: 28.912 Hz Most recent transform: 1612434223.976 (0.097 sec old) Buffer length: 4.600 sec wrist_roll_link Broadcaster: /robot_state_publisher Average rate: 50.216 Hz Most recent transform: 1612434224.504 (-0.431 sec old) Buffer length: 4.620 sec gripper_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 38.661 Hz Average rate: 38.661 Hz Most recent transform: 1612434224.009 (0.064 sec old) Most recent transform: 1612434224.009 (0.064 sec old) Buffer length: 4.630 sec Buffer length: 4.630 sec

l_gripper_finger_link

r_gripper_finger_link