

Problema 1

a) $X_t = \beta_0 + \epsilon_t$

i) $E(X_t) = E(\beta_0 + \epsilon_t)$
 $= \beta_0 + E(\epsilon_t)$

$\rightarrow 0$, recordar
 que
 $\epsilon_t \sim iid(0,1)$

ii) $V(X_t) = V(\beta_0 + \epsilon_t)$
 $= V(\beta_0)^0 + V(\epsilon_t)^1$
 $+ 2 \underset{0}{\text{cov}}(\beta_0, \epsilon_t)$
 $= 1$

iii) $\text{cov}(X_t, X_{t-1}) = \text{cov}(\beta_0 + \epsilon_t, \beta_0 + \epsilon_{t-1})$
 $= \text{cov}(\beta_0^0, \beta_0^0) + \text{cov}(\epsilon_t^0, \beta_0^0)$
 $+ \text{cov}(\beta_0^0, \epsilon_{t-1}^0) + \text{cov}(\epsilon_t^0, \epsilon_{t-1}^0)$
 $= 0$

b) $X_t = \beta_1 X_{t-1} + \epsilon_t$

i) $E(X_t) = E(\beta_1 X_{t-1} + \epsilon_t)$
 $= \beta_1 E(X_{t-1}) + E(\epsilon_t)^0$

Si X_t es estacionaria $E(X_t) = E(X_{t-1})$

$$E(x_t) = 0$$

$$\text{ii)} \quad \text{Var}(x_t) = \text{Var}(\beta_1 x_{t-1} + e_t) \\ = \beta_1^2 \text{Var}(x_{t-1}) + \text{Var}(e_t)$$

Sei x_t ex ante dienstbar, $\text{Var}(x_t) = \text{Var}(Y_{t-1})$

$$\text{Var}(x_t) = \frac{\sigma^2}{1 - \beta_1^2}$$

$$\text{iii)} \quad \text{Cov}(x_t, x_{t-1}) = \text{Cov}(\beta_1 x_{t-1} + e_t, x_{t-1}) \\ = \beta_1 \text{Cov}(x_{t-1}, x_{t-1}) + \text{Cov}(e_t, x_{t-1})$$

$$\text{Definition } \gamma_1 \equiv \text{Cov}(x_t, x_{t-1})$$

Es definiert γ_1 als die Kovarianz von (ausgegr.)
der Differenz.

$$\text{Cov}(x_t, x_{t-1}) \equiv \gamma_1 = \beta_1 \text{Var}(x_t)$$

$$\gamma_1 = \frac{\beta_1}{1 - \beta_1^2}$$

c)

$$x_t = \beta_1 u_{t-1} + u_t \quad , \quad u_t \sim \text{iid}(\mu, \sigma^2)$$

$$\text{i)} \quad E(x_t) = E(\beta_1 u_{t-1} + u_t)$$

$$= \beta_1 \mu + \mu$$

$$\text{ii) } \text{Var}(x_t) = \text{Var}(\beta_1 u_{t-1} + u_t) \quad u_t \sim \text{iid.}$$

$$= \beta_1^2 \sigma^2 + \sigma^2 + 2 \text{Cov}(\beta_1 u_{t-1}, u_t)$$

$$= \beta_1^2 \sigma^2 + \sigma^2$$

$$\text{iii) } \text{Cov}(x_t, x_{t-1}) = \text{Cov}(\beta_1 u_{t-1} + u_t, \beta_1 u_{t-2} + u_{t-1})$$

$$= \beta_1^2 \text{Cov}(u_{t-1}, u_{t-2}) +$$

$$\beta_1 \text{Cov}(u_t, u_{t-2}) + \beta_1 \text{Cov}(u_{t-1})$$

$$+ \text{Cov}(u_t, u_{t-1})$$

$$= \beta_1 \sigma^2$$

Problema 2

a) $x_t = 0.5 x_{t-1} + e_t$

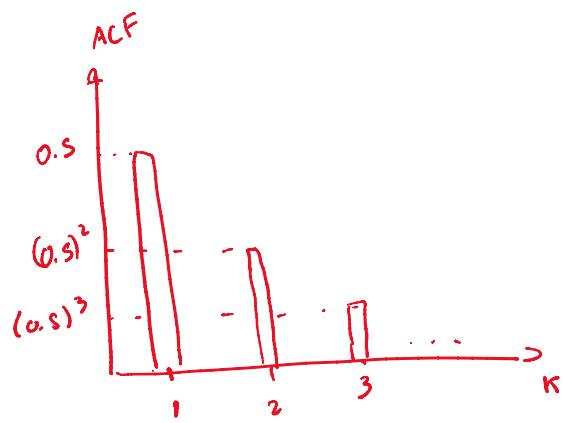
ACF. Sea ρ_k la covariación entre x_t, x_{t-k}

$$\rho_1 = \frac{\text{Cov}(x_t, x_{t-1})}{\text{Var}(x_t)} = 0.5$$

$$\rho_2 = \frac{\text{Cov}(x_t, x_{t-2})}{\text{Var}(x_t)} = (0.5)^2$$

:

$$\rho_k = \frac{\text{Cov}(x_t, x_{t-k})}{\text{Var}(x_t)} = (0.5)^k$$



$$\rho_k = \frac{\text{Cov}(x_t, x_{t-k})}{\text{Var}(x_t)} = (0.5)^k$$

PACF

$$\frac{\partial x_t}{\partial x_{t-1}} = 0.5$$



$$b) X_t = 0.5 X_{t-1} - 0.2 X_{t-2} + \epsilon_t$$

ACF.

$$\rho_1 = \frac{\text{Cov}(x_t, x_{t-1})}{\text{Var}(x_t)} = \frac{\gamma_1}{\text{Var}(x_t)}$$

$$\text{Cov}(x_t, x_{t-1}) = \text{Cov}(0.5 X_{t-1} - 0.2 X_{t-2} + \epsilon_t, X_{t-1})$$

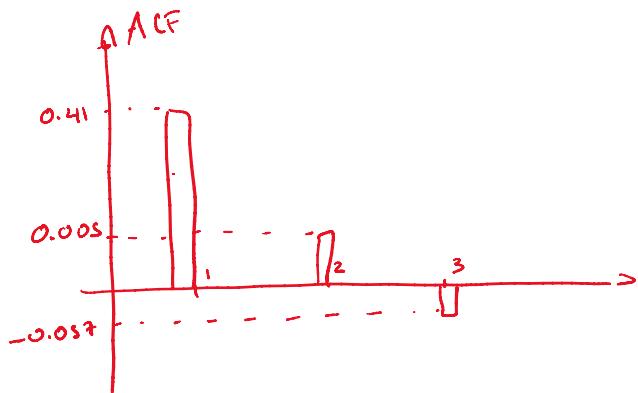
$$\begin{aligned} \text{Cov}(x_t, x_{t-1}) &= 0.5 \text{Cov}(X_{t-1}, X_{t-1}) - 0.2 \text{Cov}(X_{t-1}, X_{t-2}) \\ &\quad + \text{Cov}(\epsilon_t, X_{t-1}) \end{aligned}$$

$$\gamma_1 = 0.5 \text{Var}(x_t) - 0.2 \gamma_1$$

$$\gamma_1 = 0.41 \text{Var}(x_t)$$

$$\rho_1 = \frac{0.41 \text{Var}(x_t)}{\text{Var}(x_t)} = 0.41$$

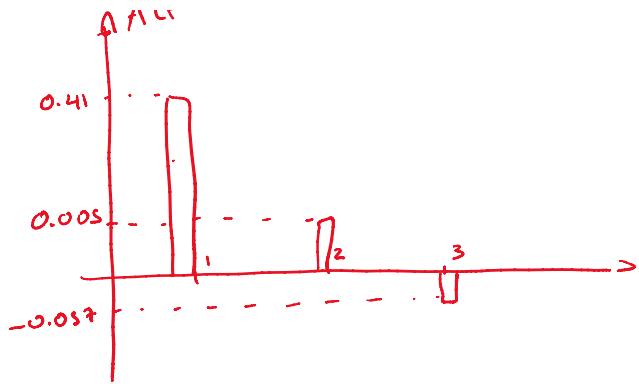
$$\rho_2 = \frac{\text{Cov}(x_t, x_{t-2})}{\text{Var}(x_t)} = 0.005$$



$$\rho_1 = \frac{0.41 \operatorname{Var}(Y_t)}{\operatorname{Var}(X_t)} = 0.41$$

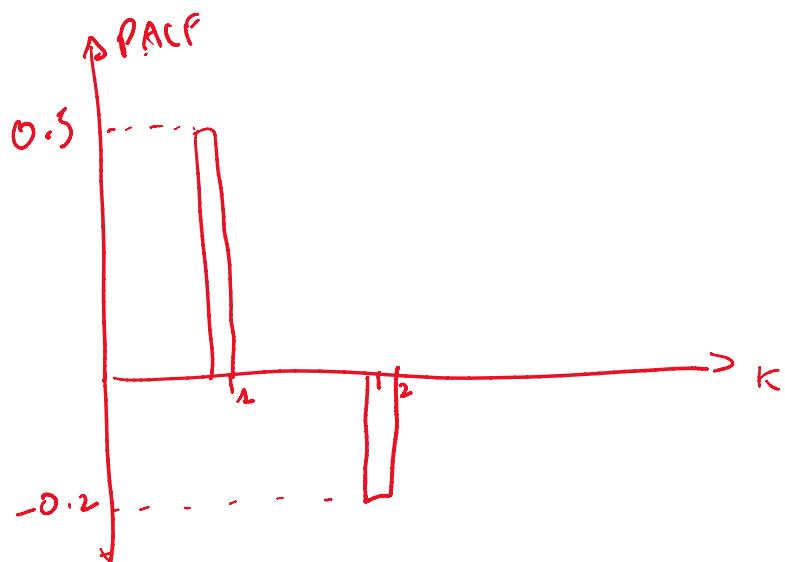
$$\rho_2 = \frac{\operatorname{Cov}(X_t, X_{t-2})}{\operatorname{Var}(X_t)} = 0.005$$

$$\rho_3 = \frac{\operatorname{Cov}(X_t, X_{t-3})}{\operatorname{Var}(X_t)} = -0.057$$



PACF

$$\frac{\partial X_t}{\partial X_{t-1}} = 0.5 \quad , \quad \frac{\partial X_t}{\partial X_{t-2}} = -0.2$$



C) $X_t = u_t + 0.5 u_{t-1}$

ACF

$$\begin{aligned}
 \rho_1 &= \frac{\text{Cov}(x_t, x_{t-1})}{\text{Var}(x_t)} \\
 &= \frac{\text{Cov}(u_t + 0.5 u_{t-1}, u_{t-1} + 0.5 u_{t-2})}{\text{Var}(u_t + 0.5 u_{t-1})} \\
 &= \frac{0.5 \text{Var}(u_t)}{1.25 \text{Var}(u_t)} \\
 &= 0.4
 \end{aligned}$$

$$\rho_2 = \rho_3 = \dots = 0$$

PACF

$$x_t = (1 + 0.5 L) u_t$$

$$\frac{x_t}{1 - (-0.5)L} = u_t$$

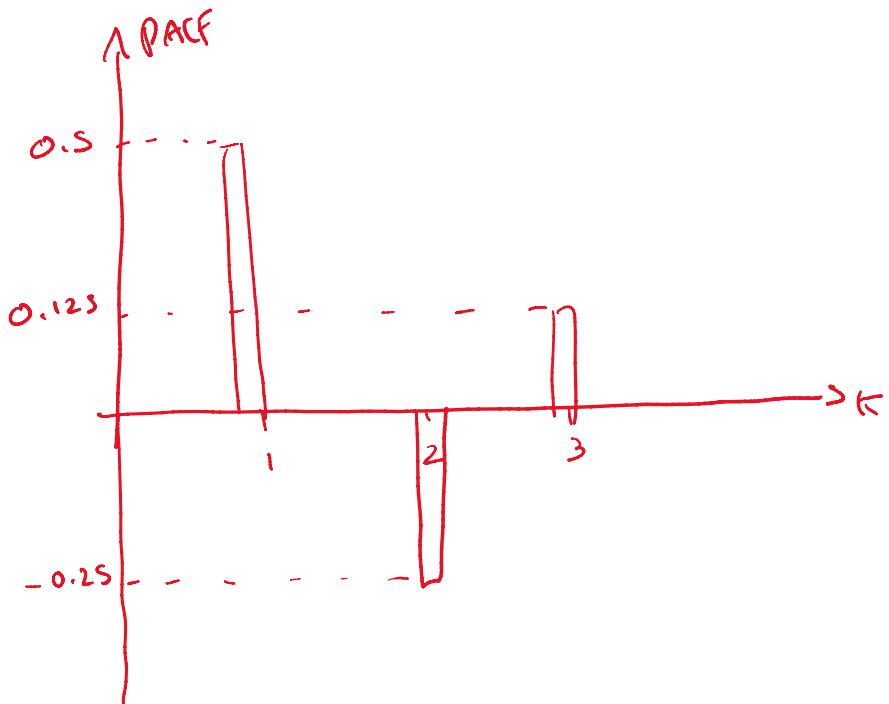
$$u_t = [1 + (-0.5)L + (-0.5)^2 L^2 + (-0.5)^3 L^3 + \dots] x_t$$

$$u_t = x_t - 0.5 x_{t-1} + 0.25 x_{t-2} - 0.125 x_{t-3} + \dots$$

$$x_t = 0.5 x_{t-1} - 0.25 x_{t-2} + 0.125 x_{t-3} + \dots u_t$$

$$\frac{\partial x_t}{\partial x_{t-1}} = 0.5 \quad \frac{\partial x_t}{\partial x_{t-2}} = -0.25, \quad \frac{\partial x_t}{\partial x_{t-3}} = 0.125$$

A PACF



Problema 3

$$a) \quad X_t = 1.05 X_{t-1} + e_t$$

De modo que $\beta_1 = 1.05 > 1 \Rightarrow$

el motor NO es estacionario

$$x_t - 1.03 L x_t = e_t$$

$$(1 - 1.05L)x_t = e_t$$

$$\Phi(L) = 1 - 1.05L$$

¿Cuál es el valor de L , tal que $\bar{f}(c) = 0$?

$$O = 1 - 1.05L$$

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- $L < 1$ Dado que los raíces son menores a uno el proceso es NO estacionario
- Si hubiere $\rho_1 > 1$, entonces el proceso es estacionario

b) $X_t = \underbrace{0.6}_{\beta_1} X_{t-1} + \underbrace{0.10}_{\beta_2} X_{t-2} + \epsilon_t$

Recordemos que

$$X_t - \beta_1 X_{t-1} - \beta_2 X_{t-2} = \epsilon_t$$

$$\Phi(L) = 1 - \beta_1 L - \beta_2 L^2$$

$\left\{ \begin{array}{l} \text{Si los valores de este} \\ \text{ecuación cuadrática} \\ \text{son } > 1, \text{ entonces } X_t \\ \text{ES ESTACIONARIO} \end{array} \right.$

Una forma complementaria es trabajar con la inversa ecuación cuadrática, es decir

$$Z^2 - \beta_1 Z - \beta_2 = 0$$

De esto obtenemos la ecuación

$$\rho_1, \rho_2 = \frac{\beta_1 \pm \sqrt{\beta_1^2 + 4\beta_2}}{2}$$

$$|r_1 \text{ y } r_2| < 1$$

De esto se generan 3 condiciones:

1) $\beta_1^2 + 4\beta_2 > 0 \rightarrow (0.6)^2 + 4(0.1) > 0$

2) $\beta_1 + \beta_2 < 1 \rightarrow 0.6 + 0.1 = 0.7 < 1$

3) $\beta_2 - \beta_1 < 1 \rightarrow 0.1 - 0.6 = -0.5 < 1$

Entonces el proceso es estacionario

c)

$$X_t = 0.8 X_{t-1} - 0.10 X_{t-2} + \epsilon_t$$

1) $\beta_1^2 + 4\beta_2 > 0 \rightarrow (0.8)^2 + 4(-0.10) > 0$

2) $\beta_1 + \beta_2 < 1 \rightarrow 0.8 - 0.10 = 0.70 < 1$

3) $\beta_2 - \beta_1 < 1 \rightarrow -0.10 - 0.8 = -0.90 < 1$

Entonces el proceso es estacionario

Problema 4

a) $X_t = 0.5 X_{t-1} + 0.10 X_{t-2} + \epsilon_t$

$$X_t - 0.5 L X_t - 0.10 L^2 X_t = \epsilon_t$$

$$(1 - 0.5 L - 0.10 L^2) X_t = \epsilon_t$$

$$G(L) = 1 - 0.5 L - 0.10 L^2$$

la ecuación característica inversa:

$$z^2 - 0.5 z - 0.10 = 0$$

$$r_1, r_2 = \frac{0.5 \pm \sqrt{(0.5)^2 + 4(0.10)}}{2}$$

$$r_1 = 0.6531$$

$$r_2 = -0.1531$$

b) $X_t = 1.10 X_{t-1} - 0.2 X_{t-2} + \epsilon_t$

$$r_1, r_2 = \frac{-1.10 \pm \sqrt{(1.10)^2 + 4(0.2)}}{2}$$

$$r_1 = -1.2388$$

$$r_2 = 0.1589$$