Plan : Objects

1 — String :   10 — 00 » 10

* 1. _Using Processing's classes_
* .length()
* .toUpperCase()
* .contains()

2 — PImage :   10 — 10 » 20

PDE >> **objectPImageDog.pde**

* .width
* .height
* .resize()

3.1 * Sketch the Robot :   5 — 20 » 25

* draw in _SketchBooks_
* get 6 numbers

3.2 — Robot Classes **WATCH**:   15 — 25 » 40

PDE >> **lectureRobots.pde**

* mk0 * Method
* mk1 * Does Nothing
* mk2 * Data & Methods
* mk3 * Arguments
* mk4 * Behaviour

3.3 * Robot Classes **WATCH** :   5 — 30 » 45

* mk5 * Interaction
* mk6 * Groups

4. WRAP—UP 5 :   5 — 45 » 50

* Slides
* Data Later