
A note on the potential outcomes framework in continuous time

Johan Sebastian Ohlendorff

johan.ohlendorff@sund.ku.dk

University of Copenhagen

ABSTRACT

In this brief note, we consider the target parameters of [Ryalen \(2024\)](#) and compare it with the target parameter given in [Rytgaard et al. \(2022\)](#), corresponding to their marked point process settings. It is shown that the resulting target parameters are the same if and only if the probability of being treated given that you go to the doctor at time t is equal to 1 for Lebesgue-almost all t , provided that the transition hazards for dying are strictly positive for almost all t .

1 Introduction

We consider a multi-state model with at most one visitation time for the treatment (that is at most one point where treatment may change), no time-varying covariates, and no baseline covariates. In the initial state (0) everyone starts as treated. We consider the setting with no censoring. The multi-state model is shown in [Figure 1](#). We observe the counting processes $N_t = (N_t^{01}, N_t^{02}, N_t^{03}, N_t^{13}, N_t^{23})$ on the canonical filtered probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, P)$, where $\mathcal{F}_t = \sigma(N_s \mid s \leq t)$. This means that we can represent the observed data as $O = (T_{(1)}, D_{(1)}, T_{(2)})$, where $T_{(1)}$ is the first event time, $D_{(1)} \in \{01, 02, 03\}$ is the first event type, $A(T_1) = \mathbb{1}\{D_1 \neq 02\}$ is the treatment at the first event time, and $T_{(2)}$ is the second event time, possibly ∞ . We will assume that the distribution of the jump times are continuous and that there are no jumps in common between the counting processes. By a well-known result for marked point processes (Proposition 3.1 of [Jacod \(1975\)](#)), we know there exist functions h^{ij} , such that the compensators Λ^{ij} of the counting processes N^{ij} with respect to $P - \mathcal{F}_t$ are given by

$$\Lambda^{0j}(dt) = \mathbb{1}\{t \leq T_{(1)}\} h^{0j}(t) dt, \quad j = 1, 2, 3$$

$$\Lambda^{i3}(dt) = \mathbb{1}\{T_{(1)} < t \leq T_{(2)}\} h^{i3}(T_{(1)}, t) dt, \quad i = 2, 3$$

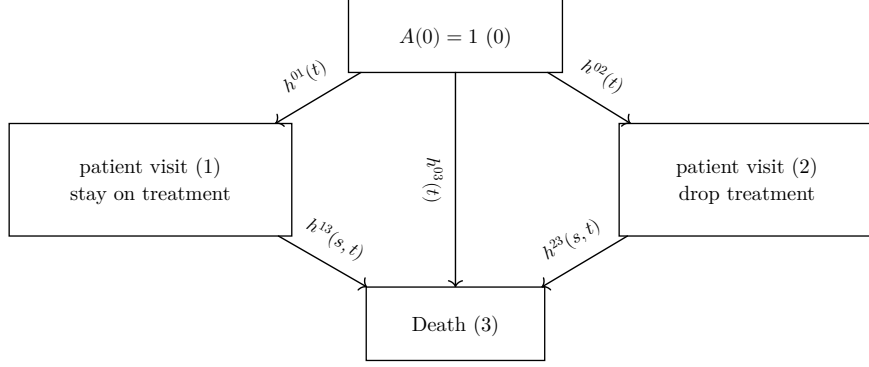


Figure 1: A multi-state model allowing one visitation time for the treatment with the possible treatment values 0/1.

2 The potential outcomes framework

To follow along [Ryalen \(2024\)](#), we restrict the observations to the interval $[0, \tau]$ for $\tau > 0$. We first need to define the intervention of interest, defining the counting processes that we would have like to have observed under the intervention. We can intervene on two components of N (N^{02}, N^{01}), defining the “interventional” processes as

$$\begin{aligned} N_t^{g,0} &= 0 \\ N_t^{g,1} &= N_t^{01} + N_t^{02} \end{aligned}$$

This treatment regime defines that the doctor always treats the patient at the visitation time and does not prevent the patient from visiting the doctor if they drop out of the treatment. This thus dictates that an individual that transitioned from 0 to 2 should instead transition to 1. We define $T^{a,g}$ as the first time where the observed and the interventional process deviate.

Define also the single “intervention” process

$$N_t^{g^*,0} = N_t^{g,0} = 0$$

where the interventional component is N^{02} . This dictates that an individual that transitioned from 0 to 2 should not transition to anything at that point. This intuitively thus means that a patient is prevented from visiting the doctor if they drop out of the treatment. The key issue in [Ryalen \(2024\)](#) is that we will not be able to differentiate between target parameters for g and g^* . The reason is that the likelihood under the intervention only depends on the stopping time T^a and the problem that the stopping time T^a is the same under g and g^* .

To see this, let T^{a,g^*} be the first time where the observed and the interventional process (according to g^*) deviate. We have

$$T^{a,g} = \inf_{t>0} \{N_t^{g,0} \neq N_t^{01}\} \wedge \inf_{t>0} \{N_t^{g,1} \neq N_t^{02}\} = \inf_{t>0} \{N_t^{g,0} \neq 0\} = \inf_{t>0} \{N_t^{g^*,0} \neq 0\} = T^{a,g^*}$$

Applying Theorem 2.1, we find that the target parameters are the same because the weights W_t are the same under g and g^* .

We now define the target parameter of interest in [Ryalen \(2024\)](#). The outcome of interest is death at time t , i.e.,

$$Y_t = N_t^{13} + N_t^{03} + N_t^{23} = \mathbb{1}\{T_1 \leq t, D_1 = y\} + \mathbb{1}\{T_2 \leq t\}$$

and we want to estimate $\mathbb{E}_P[\tilde{Y}_t]$ where \tilde{Y}_t denotes the outcome at time t , had the treatment regime (staying on treatment), possibly contrary to fact, been followed.

Theorem 2.1 (Theorem 1 of [Ryalen \(2024\)](#)): We suppose that there exists a potential outcome process $(\tilde{Y}_t)_{t \in [0, \tau]}$ such that

1. Consistency: $\tilde{Y}_t \mathbb{1}\{T^A > t\} = Y_t \mathbb{1}\{T^A > t\}$ for all $t > 0$ P -a.s.
2. Exchangeability: The $P - \mathcal{F}_t$ compensators $\Lambda^{01}, \Lambda^{02}$ are also compensators for $\mathcal{G}_t = \mathcal{F}_t \vee \sigma(\tilde{Y}_s, \tau \geq s \geq 0)$. Here \tilde{Y}_s is added at baseline, so that $\mathcal{G}_0 = \sigma(\tilde{Y}_s, \tau \geq s \geq 0)$.
3. Positivity: $W_t = \frac{\mathbb{1}\{T^A > t\}}{\exp(-\Lambda^{02}(t))} = \frac{1 - \mathbb{1}\{T_{(1)} \leq t, D_{(1)} = a, A_{(1)} = 0\}}{\exp(-\int_0^t \mathbb{1}\{s \leq T_{(1)}\} h^a(s) \pi_s(0) ds)}^1$ is a uniformly integrable martingale or equivalently that R^{Pal} given by $dR^{\text{Pal}} = W_\tau dP$ is a probability measure.

Then the estimand of interest $\Psi_t^{\text{Ryalen}} : \mathcal{M} \rightarrow \mathbb{R}_+$ is identifiable by

$$\Psi_t^{\text{Ryalen}}(P) := \mathbb{E}_P[\tilde{Y}_t] = \mathbb{E}_P[Y_t W_t] = \mathbb{E}_{R^{\text{Pal}}}[Y_t]$$

From this, we can derive an alternate representation of the target parameter. We have that

$$\begin{aligned} \Psi_t^{\text{Ryalen}}(P) &= \mathbb{E}_P[Y_t W_t] \\ &= \mathbb{E}_P[\mathbb{1}\{T_{(1)} \leq t\} Y_t W_t] + \mathbb{E}_P[\mathbb{1}\{T_{(2)} \leq t\} Y_t W_t] \\ &= \mathbb{E}_P \left[\mathbb{1}\{T_{(1)} \leq t\} Y_t \frac{1 - \mathbb{1}\{T^a > t\}}{\exp(-\int_0^{T_{(1)}} h^{02}(s) ds)} \right] + \mathbb{E}_P \left[\mathbb{1}\{T_{(2)} \leq t\} Y_t \frac{1 - \mathbb{1}\{T^a > t\}}{\exp(-\int_0^{T_{(1)}} h^{02}(s) ds)} \right] \\ &= \mathbb{E}_P \left[\mathbb{1}\{T_{(1)} \leq t, D_{(1)} = 03\} \frac{1}{\exp(-\int_0^{T_{(1)}} h^{02}(s) ds)} \right] + \mathbb{E}_P \left[\mathbb{1}\{T_{(2)} \leq t\} \frac{1 - N_t^{02}}{\exp(-\int_0^{T_{(1)}} h^{02}(s) ds)} \right] \\ &= \mathbb{E}_P \left[\mathbb{1}\{T_{(1)} \leq t, D_{(1)} = 03\} \frac{1}{\exp(-\int_0^{T_{(1)}} h^{02}(s) ds)} \right] + \mathbb{E}_P \left[\mathbb{1}\{T_{(2)} \leq t, D_{(1)} = 01\} \frac{1}{\exp(-\int_0^{T_{(1)}} h^{02}(s) ds)} \right] \\ &= \int_0^t \frac{1}{\exp(-\int_0^s h^{02}(s) ds)} \exp\left(-\sum_j \int_0^s h^{0j}(u) du\right) h^{03}(s) ds \\ &\quad + \int_0^t \frac{1}{\exp(-\int_0^s h^{02}(s) ds)} \exp\left(-\sum_j \int_0^s h^{0j}(u) du\right) \left(\int_s^t \exp\left(-\int_s^w h^{13}(s, u) du\right) h^{13}(s, w) dw\right) h^{01}(s) ds \\ &= \int_0^t \exp\left(-\sum_{j \neq 2} \int_0^s h^{0j}(u) du\right) h^{03}(s) ds \\ &\quad + \int_0^t \exp\left(-\sum_{j \neq 2} \int_0^s h^{0j}(u) du\right) \left(\int_s^t \exp\left(-\int_s^w h^{13}(s, u) du\right) h^{13}(s, w) dw\right) h^{01}(s) ds \end{aligned}$$

2.1 The target parameter in [Rytgaard et al. \(2022\)](#)

To discuss [Rytgaard et al. \(2022\)](#), additionally define

¹In the notation of [Ryalen \(2024\)](#), $\tau^A = T^a$, $N_t = \mathbb{1}\{T^A \leq t\} = N_t^{02}$ and Λ_t^{02} is the compensator of this process.

$$\Lambda^a(t) = (h^{01}(t) + h^{02}(t))\mathbb{1}\{T_{(1)} \leq t\}$$

$$\pi_t(1) = \frac{h^{01}(t)}{h^{01}(t) + h^{02}(t)}$$

Here, we can interpret $\Lambda^a(t)$ as the intensity of the visitation times and $\pi_t(1)$ as the probability of being treated given that you go to the doctor at time t . Here $\Lambda^a(t)$ is the compensator of the counting process $N_t^a = N_t^{01} + N_t^{02}$ with respect to $P - \mathcal{F}_t$. Furthermore, let $N_t^d = N_t^{03} + N_t^{13} + N_t^{23}$ be the counting process for the event of interest. Then, its compensator is given by

$$\begin{aligned} \Lambda^d(dt) &= \mathbb{1}\{t \leq T_{(1)}\} h^{03}(t) dt \\ &\quad + \mathbb{1}\{T_{(1)} < t \leq T_{(2)}\} (\mathbb{1}\{D_{(1)} = 01\} h^{13}(T_{(1)}, t) + \mathbb{1}\{D_{(1)} = 02\} h^{23}(T_{(1)}, t)) dt \end{aligned}$$

Furthermore, let $A(t) = \mathbb{1}\{T_{(1)} > t\} + \mathbb{1}\{T_{(1)} \leq t, D_{(1)} \neq 02\}$ be the treatment process at time t . [Rytgaard et al. \(2022\)](#) give their likelihood as

$$\begin{aligned} dP(O) &= \prod_{t \in (0, \tau]} \left(d\Lambda^a(t) (\pi_t(1))^{\mathbb{1}\{A(t)=1\}} (1 - \pi_t(1))^{\mathbb{1}\{A(t)=0\}} \right)^{\Delta N^a(t)} (1 - d\Lambda^a(t))^{1 - N^a(dt)} \\ &\quad \times \prod_{t \in (0, \tau]} (d\Lambda^d(t))^{\Delta N^d(t)} (1 - d\Lambda^d(t))^{1 - N^d(dt)} \\ &= \prod_{t \in (0, \tau]} \left((\pi_t(1))^{\mathbb{1}\{A(t)=1\}} (1 - \pi_t(1))^{\mathbb{1}\{A(t)=0\}} \right)^{\Delta N^a(t)} \\ &\quad \times \prod_{t \in (0, \tau]} (d\Lambda^a(t))^{\Delta N^a(t)} (1 - d\Lambda^a(t))^{1 - N^a(dt)} (d\Lambda^d(t))^{\Delta N^d(t)} (1 - d\Lambda^d(t))^{1 - N^d(dt)} \\ &= \prod_{t \in (0, \tau]} dG_t dQ_t \end{aligned}$$

where

$$dG_t = \left((\pi_t(1))^{\mathbb{1}\{A(t)=1\}} (1 - \pi_t(1))^{\mathbb{1}\{A(t)=0\}} \right)^{N^a(dt)}$$

$$dQ_t = (d\Lambda^a(t))^{N^a(dt)} (1 - d\Lambda^a(t))^{1 - N^a(dt)} (d\Lambda^d(t))^{N^d(dt)} (1 - d\Lambda^d(t))^{1 - N^d(dt)}$$

Let $dG_t^* = ((1)^{\mathbb{1}\{A(t)=1\}} (0)^{\mathbb{1}\{A(t)=0\}})^{N^a(dt)} = ((0)^{\mathbb{1}\{A(t)=0\}})^{N^a(dt)}$. Then define the likelihood as

$$dP_{Q, G^*}(O) = \prod_{t \in (0, \tau]} dG_t^* dQ_t$$

and their target estimand $\Psi_t^{\text{Rytgaard}} : \mathcal{M} \rightarrow \mathbb{R}_+$ as

$$\Psi_t^{\text{Rytgaard}}(P) = \mathbb{E}_{P_{Q, G^*}}[N_\tau^d] = P_{Q, G^*}(T_{(1)} \leq \tau, D_{(1)} = 03) + P_{Q, G^*}(T_{(2)} \leq \tau)$$

Let us calculate the density $dP_{Q, G^*}(O)$ restricted to $\mathcal{F}_{T_{(1)}} = (T_{(1)}, D_{(1)})$ and $\mathcal{F}_{T_{(2)}} = (T_{(1)}, D_{(1)}, T_{(2)})$ (further restricted to $T_{(2)} < \infty$). To get a fully rigorous result, consider Proposition 1 in [Ryalen \(2024\)](#) and Theorem 8.1.2 in [Last & Brandt \(1995\)](#).

We have

$$\prod_{t \in (0, \tau]} dG_t^* dQ_t = \prod_{t \in (0, t_{(1)}]} dG_t^* dQ_t \prod_{t \in (t_{(1)}, \tau]} dG_t^* dQ_t$$

Since $\int_{(0, \tau]} \prod_{t \in (t_{(1)}, \tau]} dG_t^* dQ_t \mathbb{1}\{t_1 < t_2\} = 1$ ($\prod_{t \in (t_{(1)}, \tau]} dG_t^* dQ_t$ is the conditional density of t_2 given (t_1, d_1) integrated over t_2 ; in the case where $d_1 = 03$ (death initially occurs), we define this integral as 1), we get $P_{Q, G^*}(T_{(1)} \in dt_1, D_{(1)} = d_1)$ by

$$\begin{aligned}
\pi_{t \in (0, t_{(1)}]} dG_t^* dQ_t &= ((0)^{\mathbb{1}\{d_1=02\}})^{\mathbb{1}\{d_1 \in \{01, 02\}\}} \\
&\times (d\Lambda^a(t_1))^{\mathbb{1}\{d_1 \in \{01, 02\}\}} (d\Lambda^d(t_1))^{\mathbb{1}\{d_1=03\}} \pi_{t \in (0, t_{(1)}]} (1 - d\Lambda^d(t))(1 - d\Lambda^a(t)) \\
&= (d\Lambda^a(t_1))^{\mathbb{1}\{d_1 \in \{01\}\}} (0dt_1)^{\mathbb{1}\{d_1 \in \{02\}\}} (d\Lambda^d(t_1))^{\mathbb{1}\{d_1=03\}} \pi_{t \in (0, t_{(1)}]} (1 - d(\Lambda^d(t) + \Lambda^a(t))) \\
&= ((h^{01}(t_1) + h^{02}(t_1))dt_1)^{\mathbb{1}\{d_1 \in \{01\}\}} (0dt_1)^{\mathbb{1}\{d_1 \in \{02\}\}} (h^{03}(t_1)dt_1)^{\mathbb{1}\{d_1=03\}} \pi_{t \in (0, t_{(1)}]} \left(1 - \sum_j h^{0j}(t)dt\right) \\
&= \pi_{t \in (0, t_{(1)}]} \left(1 - \sum_j h^{0j}(t)dt\right) \mathbb{1}\{d_1 = 01\} (h^{01}(t_1) + h^{02}(t_1))dt_1 \\
&+ \pi_{t \in (0, t_{(1)}]} \left(1 - \sum_j h^{0j}(t)dt\right) \mathbb{1}\{d_1 = 03\} h^{03}(t_1)dt_1
\end{aligned}$$

(compare with Equation (11) in [Ryalen \(2024\)](#)). Similarly, we may find $P_{Q, G^*}(T_{(1)}, D_{(1)}, T_{(2)} \in (dt_1, d_1, dt_2))$ on $T_2 < \infty$ given by

$$\begin{aligned}
&\pi_{t \in (0, t_{(1)}]} dG_t^* dQ_t \pi_{t \in (t_{(1)}, t_{(2)}]} dG_t^* dQ_t \mathbb{1}\{t_1 < t_2\} \\
&= \mathbb{1}\{t_1 < t_2\} \pi_{t \in (0, t_{(1)}]} \left(1 - \sum_j h^{0j}(t)dt\right) \mathbb{1}\{d_1 = 01\} (h^{01}(t_1) + h^{02}(t_1)) \\
&\quad \times \pi_{t \in (t_{(1)}, t_{(2)}]} (1 - h^{13}(t_1, t)dt) h^{13}(t_1, t_2) dt_2 dt_1
\end{aligned}$$

Then for the target estimand, we have

$$\begin{aligned}
\Psi_\tau^{\text{Rytgaard}}(P) &= P_{Q, G^*}(T_{(1)} \leq \tau, D_{(1)} = 03) + P_{Q, G^*}(T_{(2)} \leq \tau) \\
&= \int_0^\tau \exp\left(-\sum_j \int_0^s h^{0j}(u)du\right) h^{03}(s)ds \\
&+ \int_0^\tau \exp\left(-\sum_j \int_0^s h^{0j}(u)du\right) \left(\int_s^\tau \exp\left(-\int_s^w h^{13}(s, u)du\right) h^{13}dw\right) (h^{01}(s) + h^{02}(s))ds
\end{aligned}$$

2.2 Comparison of the approaches

We are now in a position, where we can readily compare the approaches in [Rytgaard et al. \(2022\)](#) and [Ryalen \(2024\)](#).

Suppose that $h^{02}(s) > 0$ and $h^{13}(s, w) > 0$ for Lebesgue almost all s, w . From this, we conclude that $\Psi_t^{\text{Rytgaard}}(P) = \Psi_t^{\text{Ryalen}}(P)$ if and only if $h^{02} \equiv 0$ a.e. if and only if $\pi_t(1) \equiv 1$ a.e. To see this, note that

$$\begin{aligned}
\Psi_t^{\text{Rylen}}(P) - \Psi_t^{\text{Rytgaard}}(P) &= \int_0^t \exp\left(-\sum_{j \neq 2} \int_0^s h^{0j}(u) du\right) \left(1 - \exp\left(-\int_0^s h^{02}(u) du\right)\right) h^{03}(s) ds \\
&\quad + \int_0^t \exp\left(-\sum_{j \neq 2} \int_0^s h^{0j}(u) du\right) \left(\int_s^t \exp\left(-\int_s^w h^{13}(s, u) du\right) h^{13} dw\right) \\
&\quad \quad \times \left(1 - \exp\left(-\int_0^s h^{02}(u) du\right)\right) h^{01}(s) ds \\
&\quad + \int_0^t \exp\left(-\sum_j \int_0^s h^{0j}(u) du\right) \left(\int_s^t \exp\left(-\int_s^w h^{13}(s, u) du\right) h^{13} dw\right) h^{02}(s) ds
\end{aligned}$$

Since each term is non-negative, $\Psi_t^{\text{Rytgaard}}(P) = \Psi_t^{\text{Rylen}}(P)$ implies that each term is equal to zero. Since each of the integrands are non-negative, we must have that the integrands are equal to zero for Lebesgue almost all $t > 0$, i.e., for the first term we see that and letting m denote the Lebesgue measure, we have

$$\begin{aligned}
\exp\left(-\sum_{j \neq 2} \int_0^s h^{0j}(u) du\right) \left(1 - \exp\left(-\int_0^s h^{02}(u) du\right)\right) h^{03}(s) &= 0 \quad m - \text{a.e.} \Leftrightarrow \\
\left(1 - \exp\left(-\int_0^s h^{02}(u) du\right)\right) h^{03}(s) &= 0 \quad m - \text{a.e.} \Leftrightarrow \\
\left(1 - \exp\left(-\int_0^s h^{02}(u) du\right)\right) &= 0 \quad m - \text{a.e.} \Leftrightarrow \\
h^{02}(s) &= 0 \quad m - \text{a.e.}
\end{aligned}$$

with similar arguments for the second and third terms.

3 Does the g-formula in Rytgaard et al. (2022) have a causal interpretation?

We now consider the question concerning whether there is a causal interpretation of the g-formula in Rytgaard et al. (2022). Given W_t^* as in the next theorem, we can calculate that, $\mathbb{E}_P[\tilde{Y}_t] = \mathbb{E}_P[Y_t W_t^*] = \Psi_t^{\text{Rytgaard}}(P)$.

A simple result is given in the following theorem. Note that we can also formulated the exchangeability condition for each t separately instead of formulating stochastic process conditions.

Theorem 3.1: We suppose that there exists a potential outcome process $(\tilde{Y}_t)_{t \in [0, \tau]}$ such that

1. Consistency: $\tilde{Y}_t \mathbb{1}\{T^A > t\} = Y_t \mathbb{1}\{T^A > t\}$ for all $t > 0$ P -a.s.
2. Exchangeability: We have

$$(\tilde{Y}_t)_{t \in [0, \tau]} \perp A(T_{(1)}) \mid T_{(1)}, D_{(1)}$$

3. Positivity: The measure given by $dR^{\text{Helene}} = W dP$ where $W_t^* = \left(\frac{\mathbb{1}\{A(T_{(1)})=1\}}{\pi_{T_{(1)}}(1)} \right)^{N_t^{01} + N_t^{02}}$ is a probability measure.

Then the estimand of interest is identifiable by

$$\mathbb{E}_P[\tilde{Y}_t] = \mathbb{E}_P[Y_t W_t] = \mathbb{E}_{R^{\text{Helene}}}[Y_t]$$

Proof: Write $\tilde{Y}_t = \mathbb{1}\{t < T_{(1)}\} \tilde{Y}_t + \mathbb{1}\{T_{(1)} \leq t\} \tilde{Y}_t$. Now, we see immediately that

$$\begin{aligned} \mathbb{E}_P[\mathbb{1}\{t < T_{(1)}\} \tilde{Y}_t] &= \mathbb{E}_P[\mathbb{1}\{t < T_{(1)}\} \tilde{Y}_t \mathbb{1}\{T^a > t\}] \\ &= \mathbb{E}_P[\mathbb{1}\{t < T_{(1)}\} Y_t \mathbb{1}\{T^a > t\}] \\ &= \mathbb{E}_P[\mathbb{1}\{t < T_{(1)}\} Y_t] \\ &= \mathbb{E}_P[\mathbb{1}\{t < T_{(1)}\} Y_t W_t] \end{aligned}$$

since T^a must be $T_{(1)}$ if finite. On the other hand, we have that

$$\begin{aligned} \mathbb{E}_P[\mathbb{1}\{T_{(1)} \leq t\} Y_t W_t] &= \mathbb{E}_P[\mathbb{1}\{T_{(1)} \leq t\} \mathbb{1}\{T^a > t\} Y_t W_t] \\ &= \mathbb{E}_P[\mathbb{1}\{T_{(1)} \leq t\} \mathbb{1}\{T^a > t\} \tilde{Y}_t W_t] \\ &= \mathbb{E}_P[\mathbb{1}\{T_{(1)} \leq t\} \tilde{Y}_t W_t] \\ &= \mathbb{E}_P \left[\mathbb{1}\{T_{(1)} \leq t\} \tilde{Y}_t \left(\frac{\mathbb{1}\{A(T_{(1)})=1\}}{\pi_{T_{(1)}}(1)} \right)^{\mathbb{1}\{D_{(1)}=a\}} \right] \\ &= \mathbb{E}_P \left[\mathbb{E}_P[\mathbb{1}\{T_{(1)} \leq t\} \tilde{Y}_t \mid A(T_{(1)}), D_1, T_1] \left(\frac{\mathbb{1}\{A(T_{(1)})=1\}}{\pi_{T_{(1)}}(1)} \right)^{\mathbb{1}\{D_{(1)}=a\}} \right] \\ &= \mathbb{E}_P \left[\mathbb{E}_P[\mathbb{1}\{T_{(1)} \leq t\} \tilde{Y}_t \mid D_1, T_1] \left(\frac{\mathbb{1}\{A(T_{(1)})=1\}}{\pi_{T_{(1)}}(1)} \right)^{\mathbb{1}\{D_{(1)}=a\}} \right] \\ &= \mathbb{E}_P \left[\mathbb{E}_P[\mathbb{1}\{T_{(1)} \leq t\} \tilde{Y}_t \mid D_1, T_1] \mathbb{E}_P \left[\left(\frac{\mathbb{1}\{A(T_{(1)})=1\}}{\pi_{T_{(1)}}(1)} \right)^{\mathbb{1}\{D_{(1)}=a\}} \mid T_1, D_1 \right] \right] \\ &= \mathbb{E}_P[\mathbb{E}_P[\mathbb{1}\{T_{(1)} \leq t\} \tilde{Y}_t \mid D_1, T_1]] \\ &= \mathbb{E}_P[\mathbb{1}\{T_{(1)} \leq t\} \tilde{Y}_t] \end{aligned}$$

which suffices to show the claim. \square

With more than two events, though, the exchangeability condition becomes more difficult to interpret. In the case with at most three events, for the previous argument to go through, we would need the three exchangeability conditions

$$\begin{aligned} & \left(\tilde{Y}_t \mathbb{1}\{T_{(1)} \leq t < T_{(2)}\} \right)_{t \in [0, \tau]} \perp A(T_{(1)}) \mid T_{(1)}, D_{(1)}, \\ & \left(\tilde{Y}_t \mathbb{1}\{T_{(2)} \leq t\} \right)_{t \in [0, \tau]} \perp A(T_{(1)}) \mid T_{(1)}, D_{(1)}, \\ & \left(\tilde{Y}_t \right)_{t \in [0, \tau]} \perp A(T_{(2)}) \mid T_{(2)}, D_{(2)}, A(T_{(1)}), T_{(1)}, D_{(1)}, \end{aligned}$$

It would be interesting to see if there are some explicit conditions such that

$$\left(\tilde{Y}_t \right)_{t \in [0, \tau]} \perp A(T_{(1)}) \mid T_{(1)}, D_{(1)}$$

implies the two first exchangeability conditions. An obvious one is if the event times are independent of the treatment given the history which is unlikely to hold.

The next theorem gives a different causal interpretation of the g-formula in [Rytgaard et al. \(2022\)](#). Unlike the previous theorem, the exchangeability won't have to be specified in terms of \tilde{Y}_t multiplied by a stochastic indicator function if there are more than two events. This issue is however that we are assuming the existence of multiple potential outcome processes and not just one.

Theorem 3.2: We suppose that there exists two potential outcome process $(\tilde{Y}_{t,1})_{t \in [0, \tau]}$ and $(\tilde{Y}_{t,2})_{t \in [0, \tau]}$ such that these are potential outcomes of $Y_{t,1} = N_t^{03}$ and $Y_{t,2} = N_t^{13} + N_t^{23}$, respectively (the potential outcomes for each possible event where the outcome can occur). Then we obviously define that $\tilde{Y}_t = \tilde{Y}_{t,1} + \tilde{Y}_{t,2}$ and $Y_t = Y_{t,1} + Y_{t,2}$.

1. Consistency: $\tilde{Y}_{t,i} \mathbb{1}\{T^A > t\} = Y_{t,i} \mathbb{1}\{T^A > t\}$ for all $t > 0$ P -a.s for $i = 1, 2$.
2. Exchangeability: We have

$$\left(\tilde{Y}_{t,i} \right)_{t \in [0, \tau]} \perp A(T_{(1)}) \mid T_{(1)}, D_{(1)}$$

for $i = 1, 2$.

3. Positivity: The measure given by $dR^{\text{Helene}} = W dP$ where $W_t = \left(\frac{\mathbb{1}\{A(T_{(1)})=1\}}{\pi_{T_1}(1)} \right)^{N_t^{01} + N_t^{02}}$ is a probability measure.

Then the estimand of interest is identifiable by

$$\mathbb{E}_P[\tilde{Y}_t] = \mathbb{E}_P[Y_t W_t] = \mathbb{E}_{R^{\text{Helene}}}[Y_t]$$

Proof: Now, we see immediately that

$$\mathbb{E}_P[Y_{t,1} W_t] = \mathbb{E}_P[\tilde{Y}_{t,1}]$$

because $\tilde{Y}_{t,1}$ is always $Y_{t,1}$. On the other hand, we have that

$$\begin{aligned}
\mathbb{E}_P[Y_{t,2}W_t] &= \mathbb{E}_P \left[Y_{t,2} \left(\frac{\mathbb{1}\{A(T_{(1)}) = 1\}}{\pi_{T_{(1)}}(1)} \right)^{\mathbb{1}\{D_{(1)}=a\}} \right] \\
&= \mathbb{E}_P \left[\tilde{Y}_{t,2} \left(\frac{\mathbb{1}\{A(T_{(1)}) = 1\}}{\pi_{T_{(1)}}(1)} \right)^{\mathbb{1}\{D_{(1)}=a\}} \right] \\
&= \mathbb{E}_P \left[\mathbb{E}_P[\tilde{Y}_{t,2} \mid A(T_{(1)}), D_1, T_1] \left(\frac{\mathbb{1}\{A(T_{(1)}) = 1\}}{\pi_{T_{(1)}}(1)} \right)^{\mathbb{1}\{D_{(1)}=a\}} \right] \\
&= \mathbb{E}_P \left[\mathbb{E}_P[\tilde{Y}_{t,2} \mid D_1, T_1] \left(\frac{\mathbb{1}\{A(T_{(1)}) = 1\}}{\pi_{T_{(1)}}(1)} \right)^{\mathbb{1}\{D_{(1)}=a\}} \right] \\
&= \mathbb{E}_P \left[\mathbb{E}_P[\tilde{Y}_{t,2} \mid D_1, T_1] \mathbb{E}_P \left[\left(\frac{\mathbb{1}\{A(T_{(1)}) = 1\}}{\pi_{T_{(1)}}(1)} \right)^{\mathbb{1}\{D_{(1)}=a\}} \mid T_1, D_1 \right] \right] \\
&= \mathbb{E}_P [\mathbb{E}_P[\tilde{Y}_{t,2} \mid D_1, T_1]] \\
&= \mathbb{E}_P [\tilde{Y}_{t,2}]
\end{aligned}$$

which suffices to show the claim. \square

Bibliography

- Jacod, J. (1975). Multivariate point processes: predictable projection, Radon-Nikodym derivatives, representation of martingales. *Zeitschrift Für Wahrscheinlichkeitstheorie Und Verwandte Gebiete*, 31(3), 235–253.
- Last, G., & Brandt, A. (1995). *Marked Point Processes on the Real Line: The Dynamical Approach*. Springer. <https://link.springer.com/book/9780387945477>
- Ryalen, P. (2024). *On the role of martingales in continuous-time causal inference*.
- Rytgaard, H. C., Gerds, T. A., & Laan, M. J. van der. (2022). Continuous-Time Targeted Minimum Loss-Based Estimation of Intervention-Specific Mean Outcomes. *The Annals of Statistics*, 50(5), 2469–2491. <https://doi.org/10.1214/21-AOS2114>