

Exploring the saturation of the MRI via weakly nonlinear analysis

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stuff about the MRI?

set-up

boundary conditions

parameter range

open questions, etc

We solve the non-ideal MRI equations.

momentum

$$\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{1}{\rho} \nabla P - \nabla \Phi + \frac{1}{\rho} (\mathbf{J} \times \mathbf{B}) - 2\boldsymbol{\Omega} \times \mathbf{u} - \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \mathbf{r}) + \nu \nabla^2 \mathbf{u}$$

induction

$$\partial_t \mathbf{B} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B}$$

constraints

$$\nabla \cdot \mathbf{u} = 0$$

$$\nabla \cdot \mathbf{B} = 0$$

We solve the non-ideal MRI equations.

momentum

$$\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{1}{\rho} \nabla P - \nabla \Phi + \frac{1}{\rho} (\mathbf{J} \times \mathbf{B}) - 2\boldsymbol{\Omega} \times \mathbf{u} - \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \mathbf{r}) + \nu \nabla^2 \mathbf{u}$$

induction

$$\partial_t \mathbf{B} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B}$$

microscopic
viscosity



magnetic
resistivity



constraints

$$\nabla \cdot \mathbf{u} = 0$$

$$\nabla \cdot \mathbf{B} = 0$$

We nondimensionalize and perturb
the nonlinear MRI equations.

magnetic
resistivity

microscopic
viscosity

We work in terms of flux and stream functions.

momentum

$$\partial_t \nabla^2 \Psi = \frac{2}{\beta} B_0 \partial_z \nabla^2 A + 2 \partial_z u_y + \frac{2}{\beta} J(A, \nabla^2 A) - J(\Psi, \nabla^2 \Psi) + \frac{1}{Re} \nabla^4 \Psi$$

$$\partial_t u = \frac{2}{\beta} B_0 \partial_z B_y - (2 - q) \partial_z \Psi + \frac{2}{\beta} J(A, B_y) - J(\Psi, u_y) + \frac{1}{Re} \nabla^2 u_y$$

induction

$$\partial_t A = B_0 \partial_z \Psi + J(A, \Psi) + \frac{1}{Rm} \nabla^2 A$$

$$\partial_t B_y = B_0 \partial_z u_y - q \Omega_0 \partial_z A + J(A, u_y) - J(\Psi, B_y) + \frac{1}{Rm} \nabla^2 B_y$$

We work in terms of flux and stream functions.

momentum

viscous

$$\partial_t \nabla^2 \Psi = \frac{2}{\beta} B_0 \partial_z \nabla^2 A + 2 \partial_z u_y + \frac{2}{\beta} J(A, \nabla^2 A) - J(\Psi, \nabla^2 \Psi) + \boxed{\frac{1}{Re} \nabla^4 \Psi}$$

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induction

$$\partial_t A = B_0 \partial_z \Psi + J(A, \Psi) + \boxed{\frac{1}{Rm} \nabla^2 A}$$

resistive

$$\partial_t B_y = B_0 \partial_z u_y - q \Omega_0 \partial_z A + J(A, u_y) - J(\Psi, B_y) + \boxed{\frac{1}{Rm} \nabla^2 B_y}$$

We work in terms of flux and stream functions.

momentum

nonlinear

viscous

$$\partial_t \nabla^2 \Psi = \frac{2}{\beta} B_0 \partial_z \nabla^2 A + 2 \partial_z u_y + \underbrace{\frac{2}{\beta} J(A, \nabla^2 A) - J(\Psi, \nabla^2 \Psi)}_{\text{nonlinear}} + \boxed{\frac{1}{Re} \nabla^4 \Psi}$$

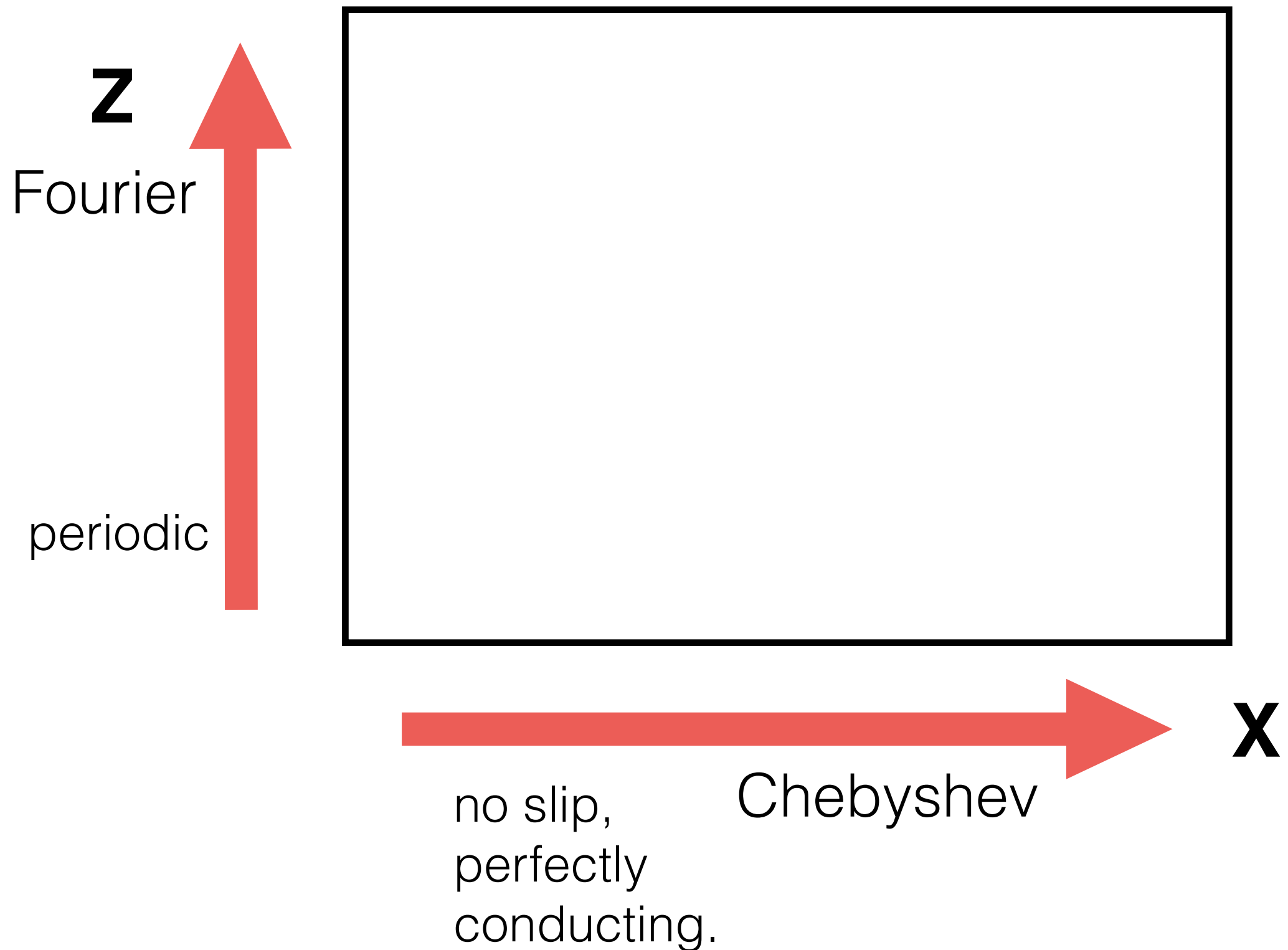
$$\partial_t u = \frac{2}{\beta} B_0 \partial_z B_y - (2 - q) \partial_z \Psi + \underbrace{\frac{2}{\beta} J(A, B_y) - J(\Psi, u_y)}_{\text{nonlinear}} + \boxed{\frac{1}{Re} \nabla^2 u_y}$$

induction

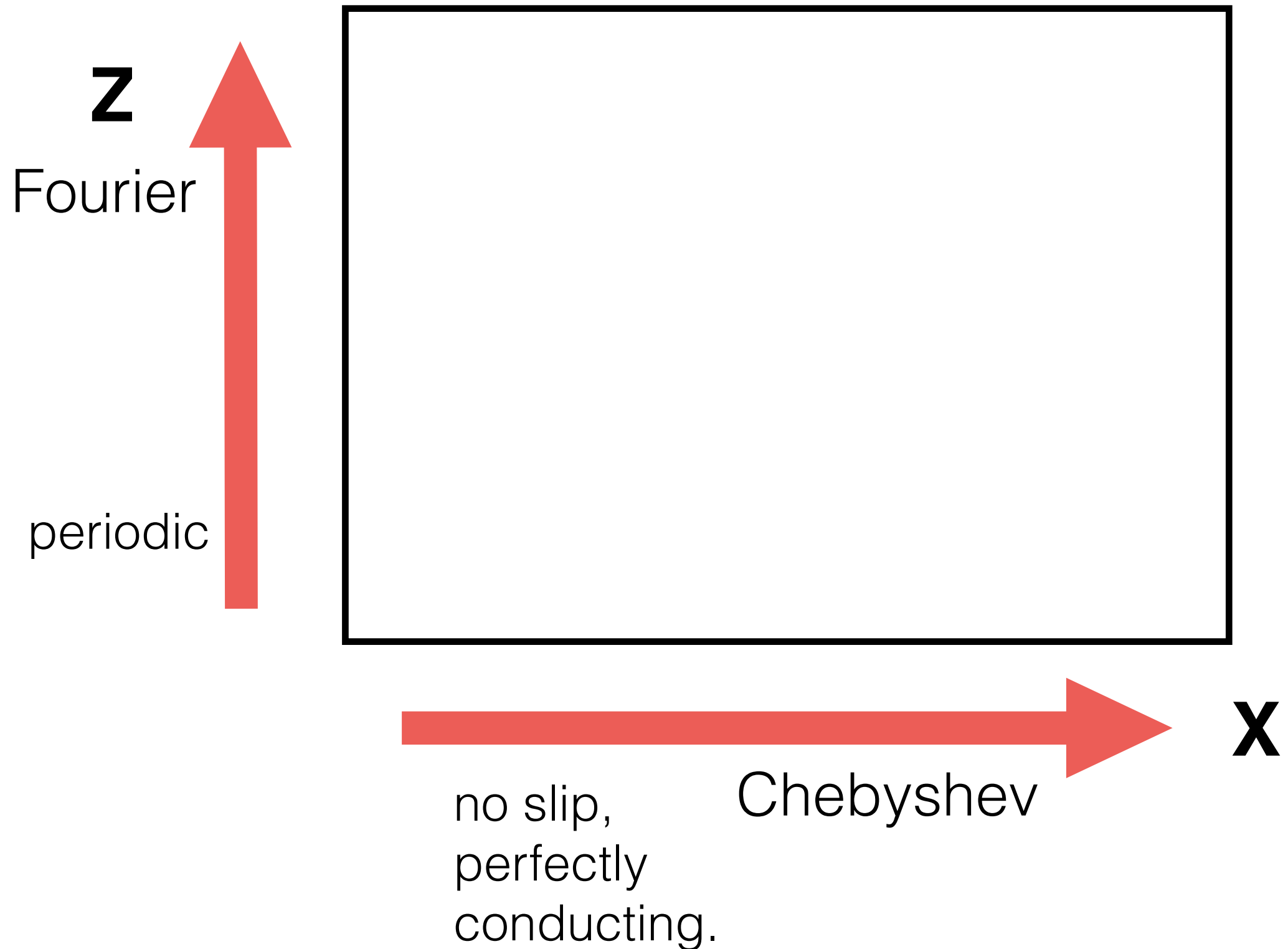
$$\partial_t A = B_0 \partial_z \Psi + \underbrace{J(A, \Psi)}_{\text{nonlinear}} + \boxed{\frac{1}{Rm} \nabla^2 A} \quad \text{resistive}$$

$$\partial_t B_y = B_0 \partial_z u_y - q \Omega_0 \partial_z A + \underbrace{J(A, u_y) - J(\Psi, B_y)}_{\text{nonlinear}} + \boxed{\frac{1}{Rm} \nabla^2 B_y}$$

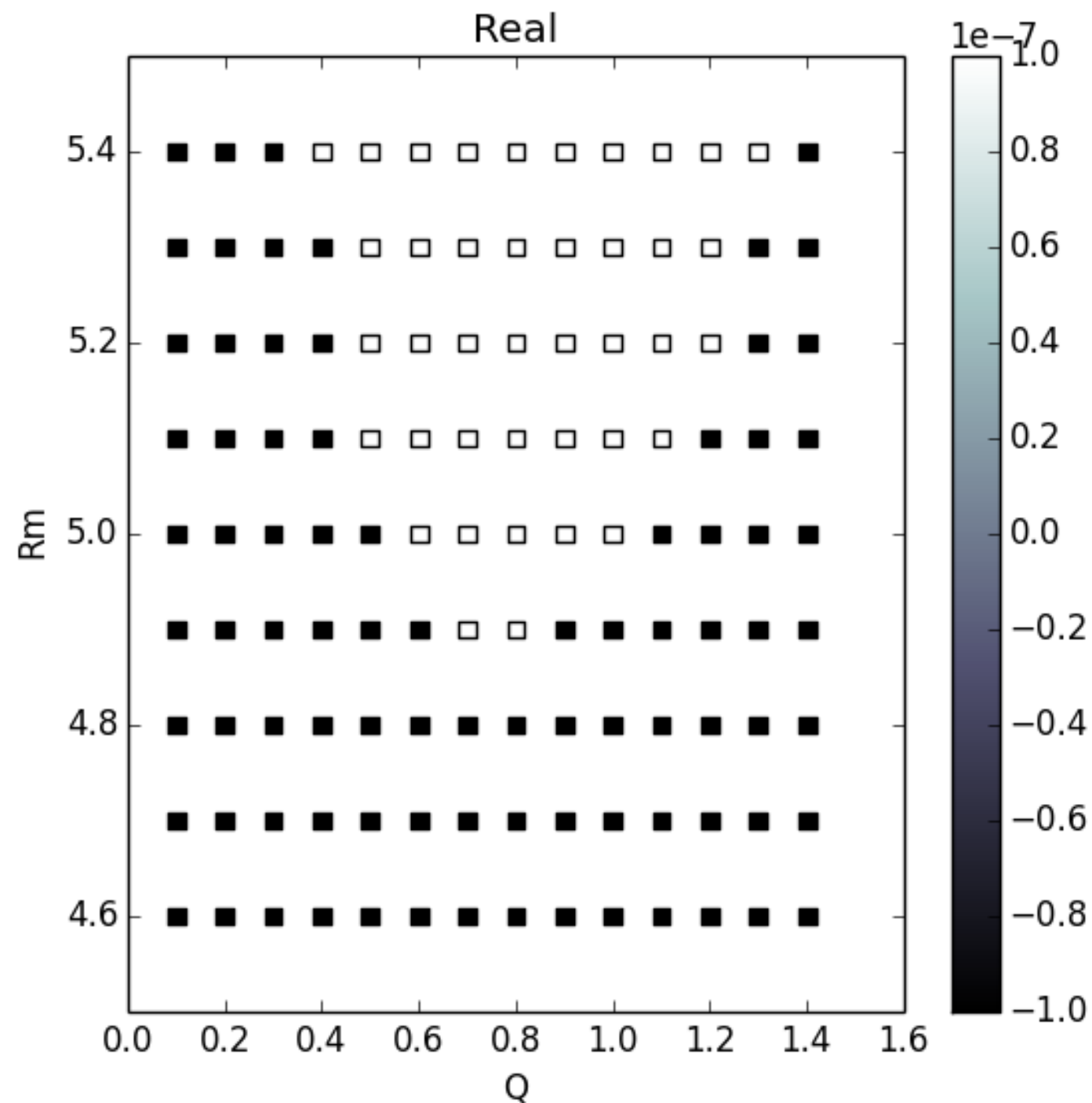
Dedalus is a general-purpose spectral code.



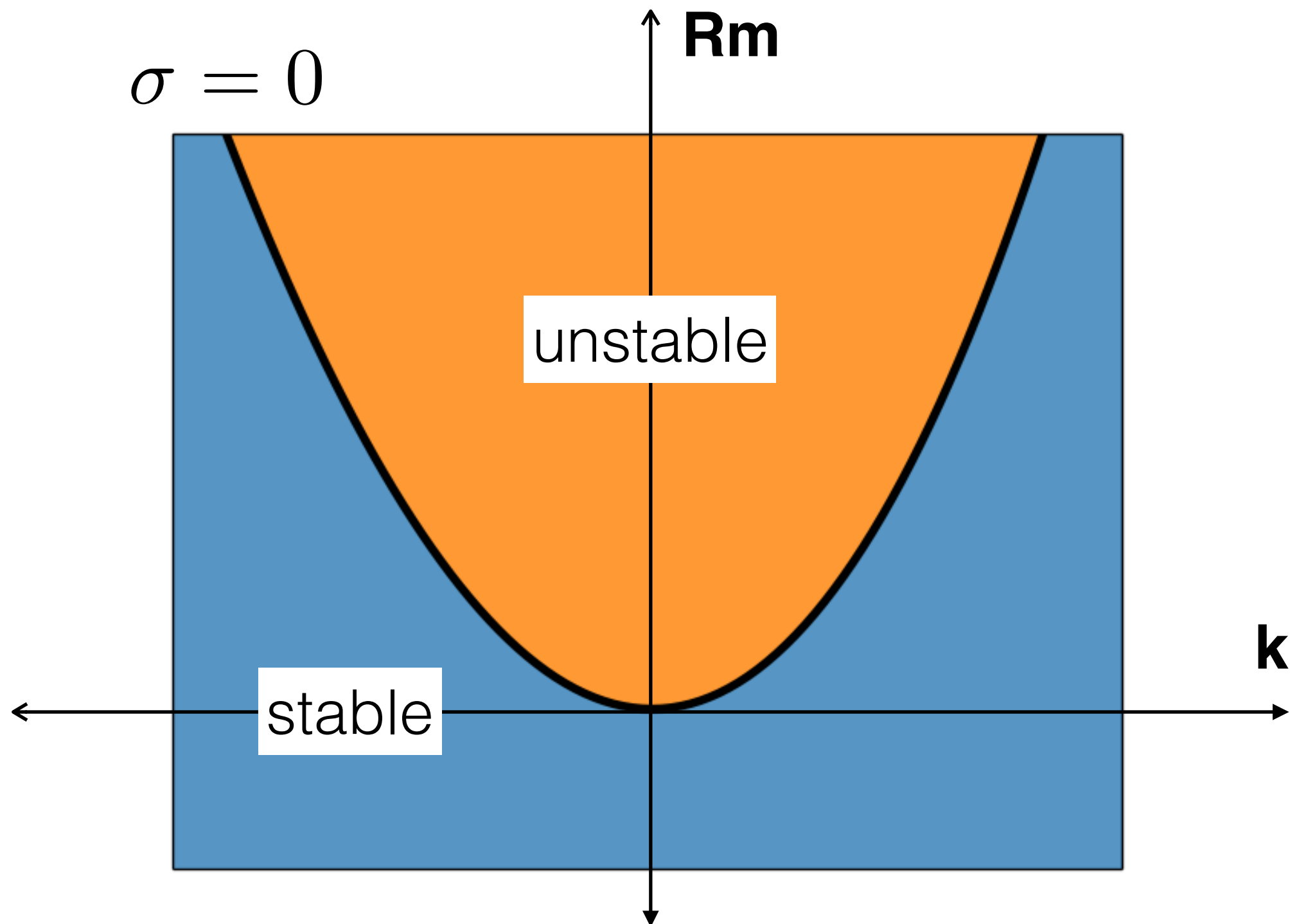
We use experimentally relevant boundary conditions.



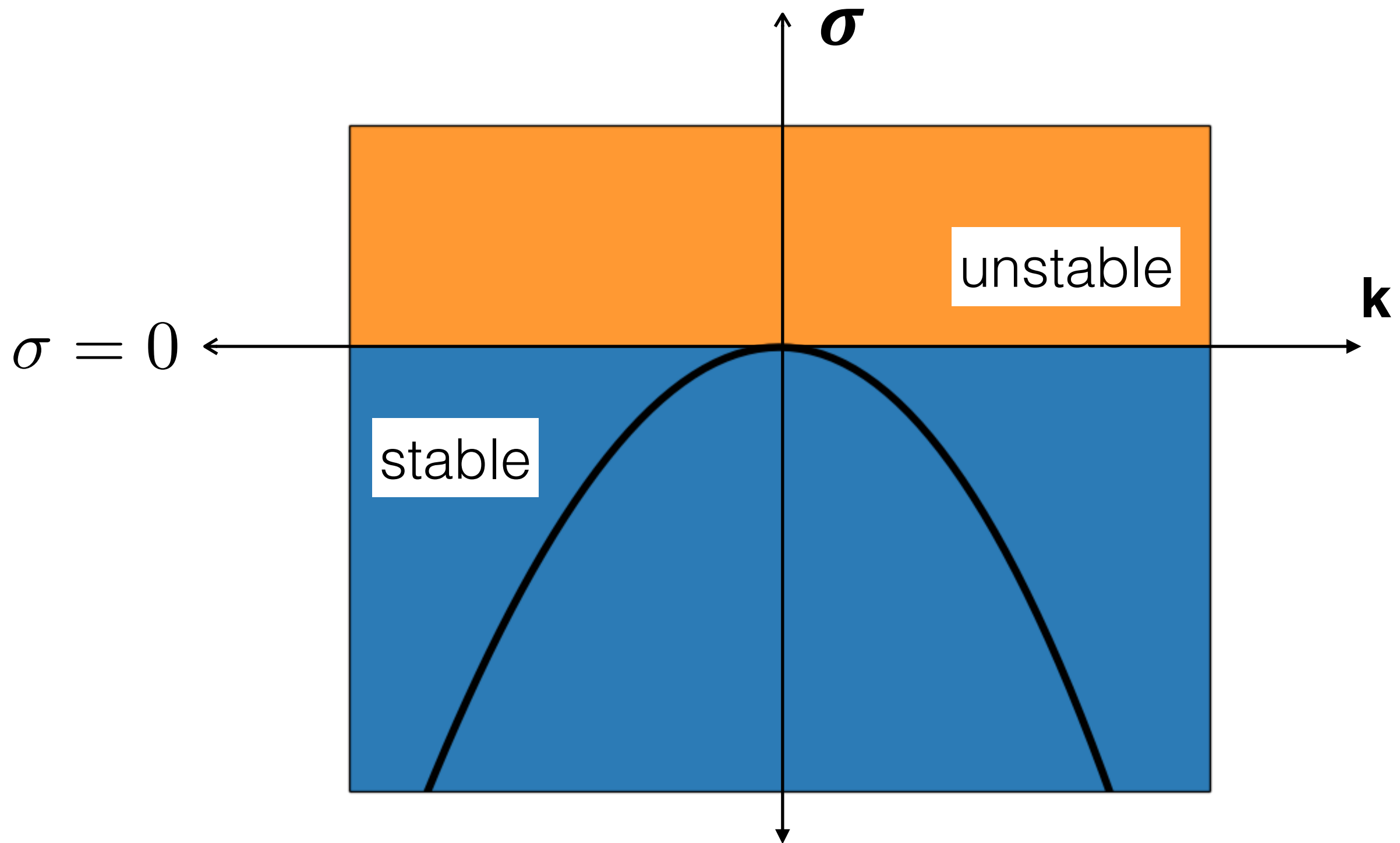
Weakly nonlinear analysis explores behavior at the margin of instability.



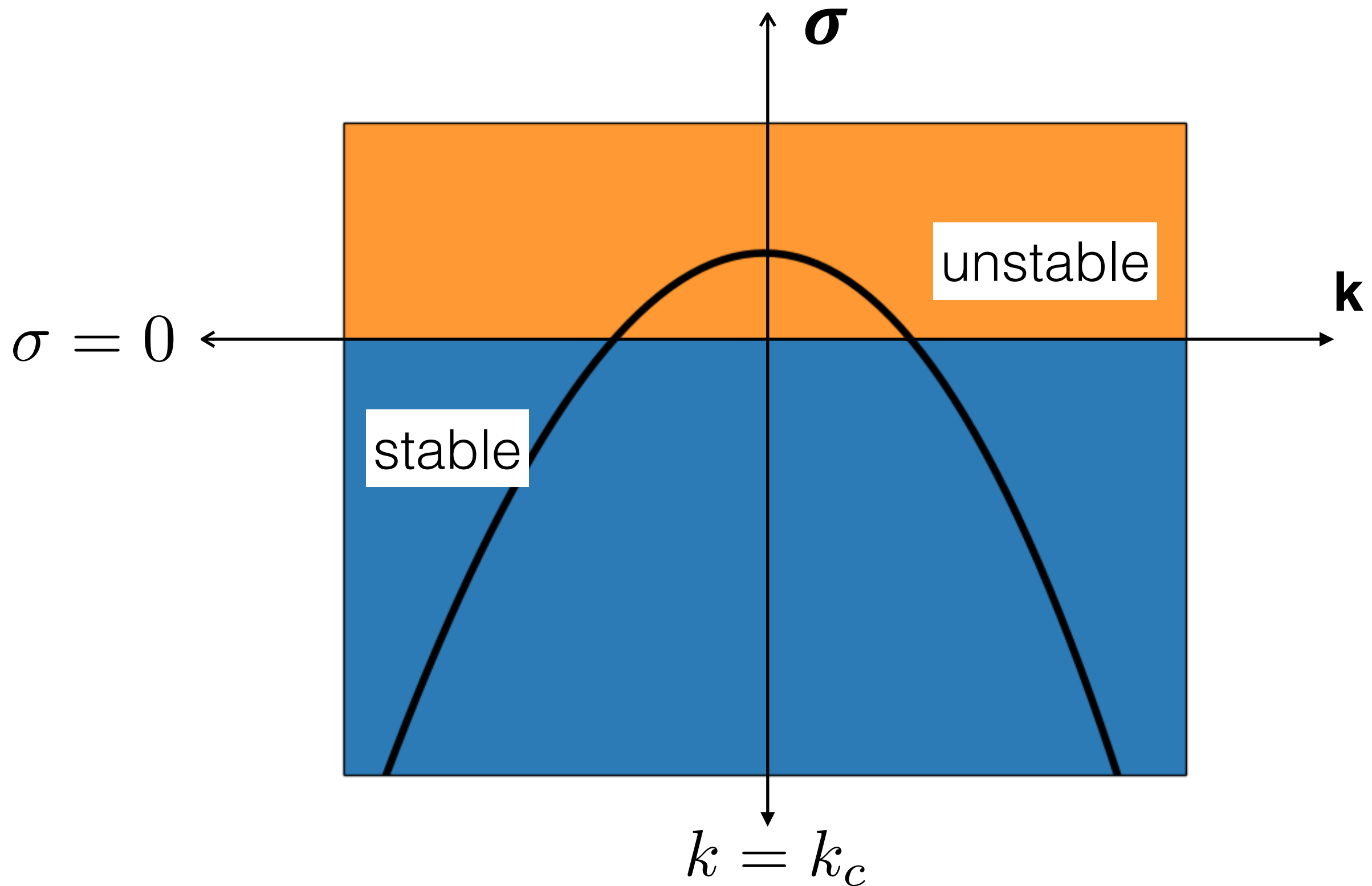
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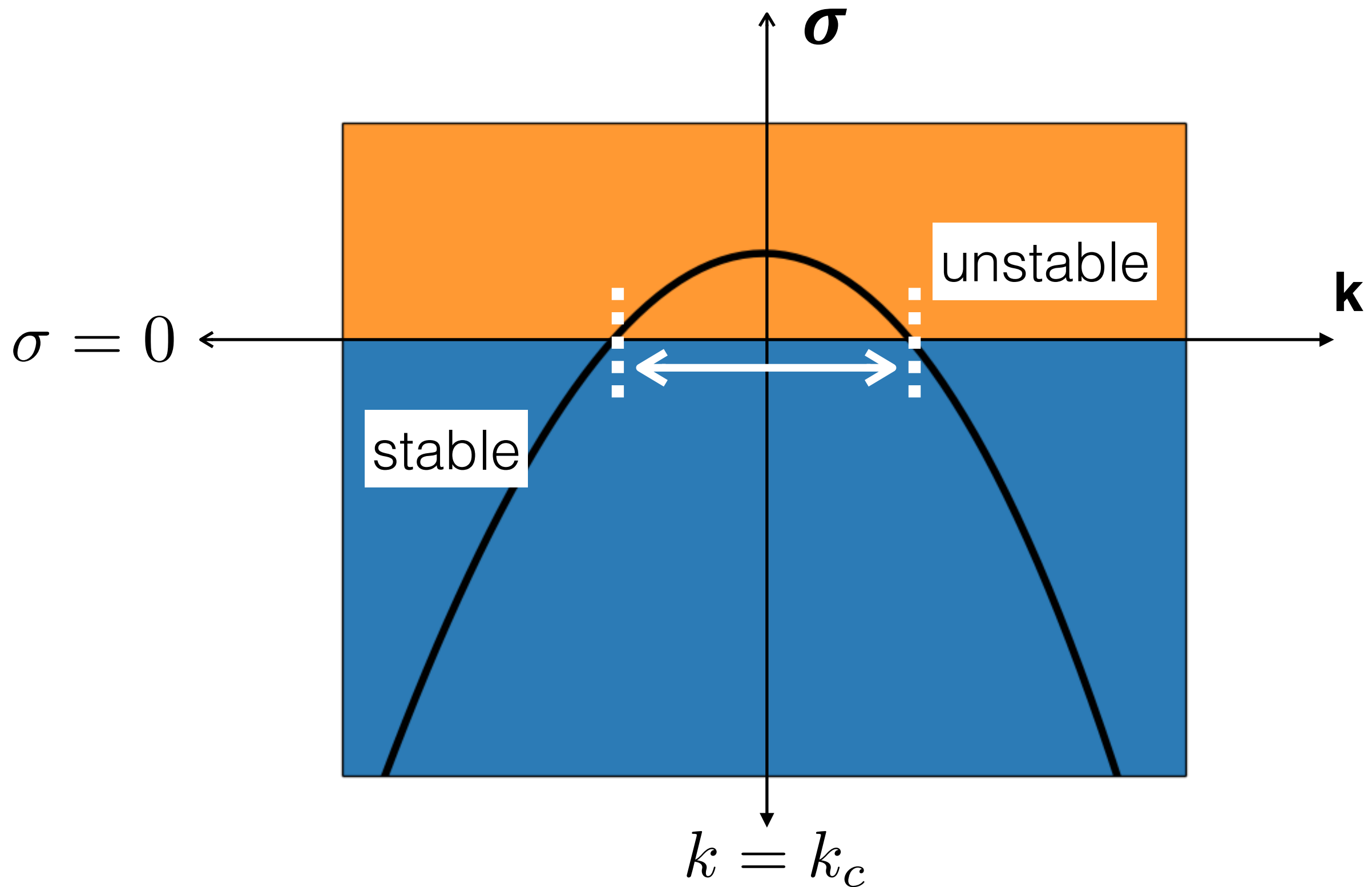
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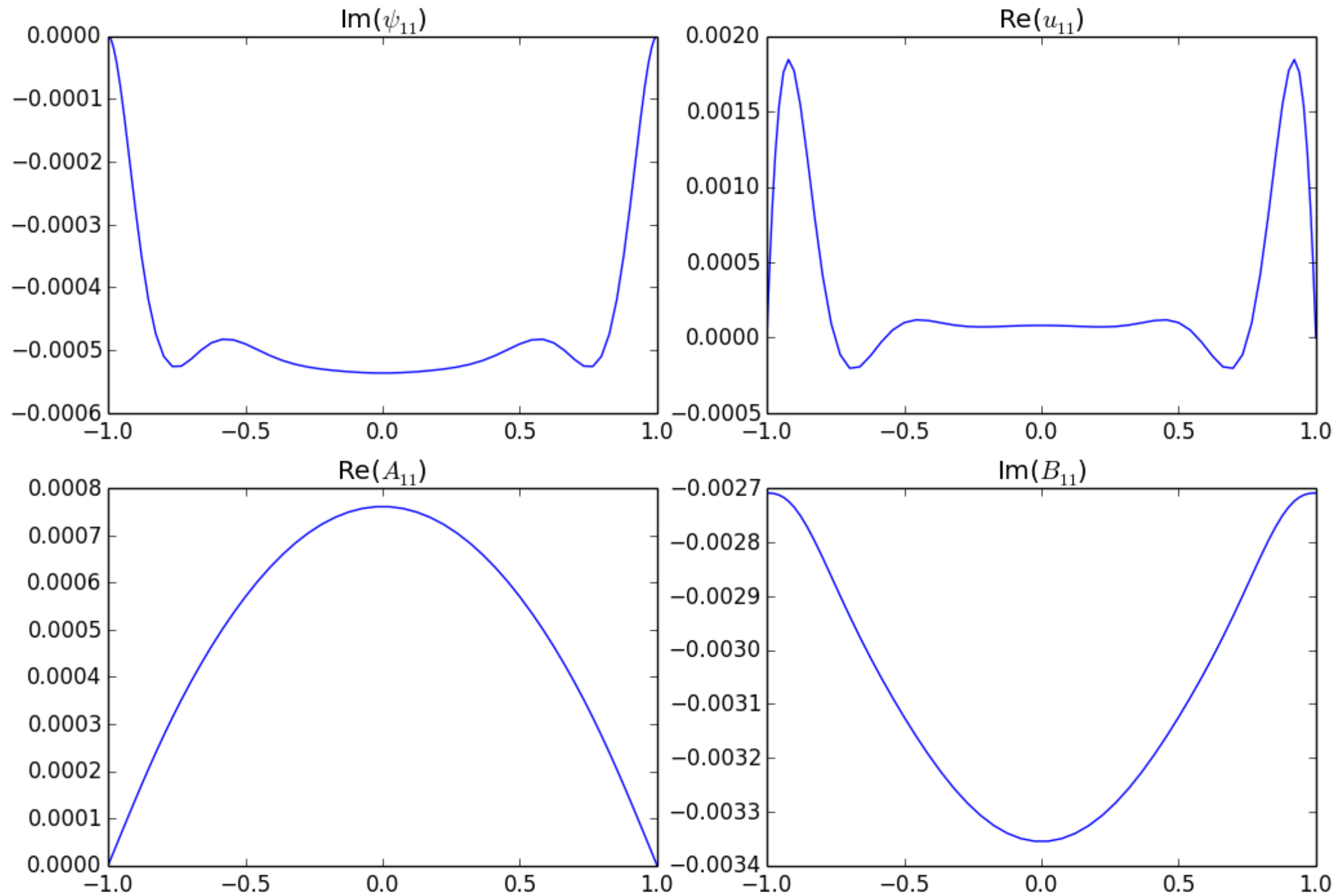
Weakly nonlinear analysis explores behavior at the margin of instability.



Weakly nonlinear analysis explores behavior at the margin of instability.

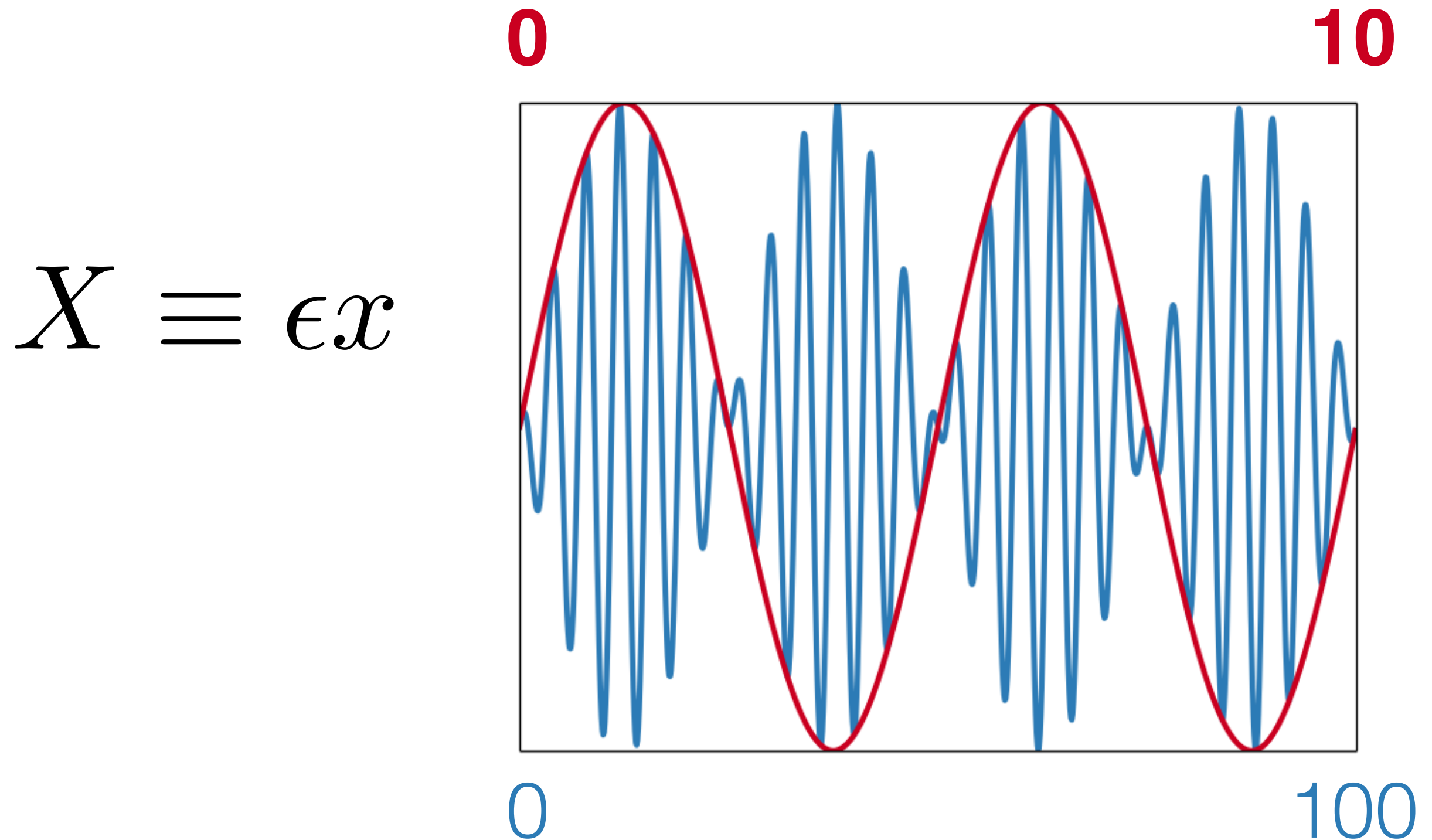


Identify the most unstable mode of the linear MRI.



Tune this mode just over the threshold of instability.

Multiscale analysis tracks the evolution of fast and slow variables.

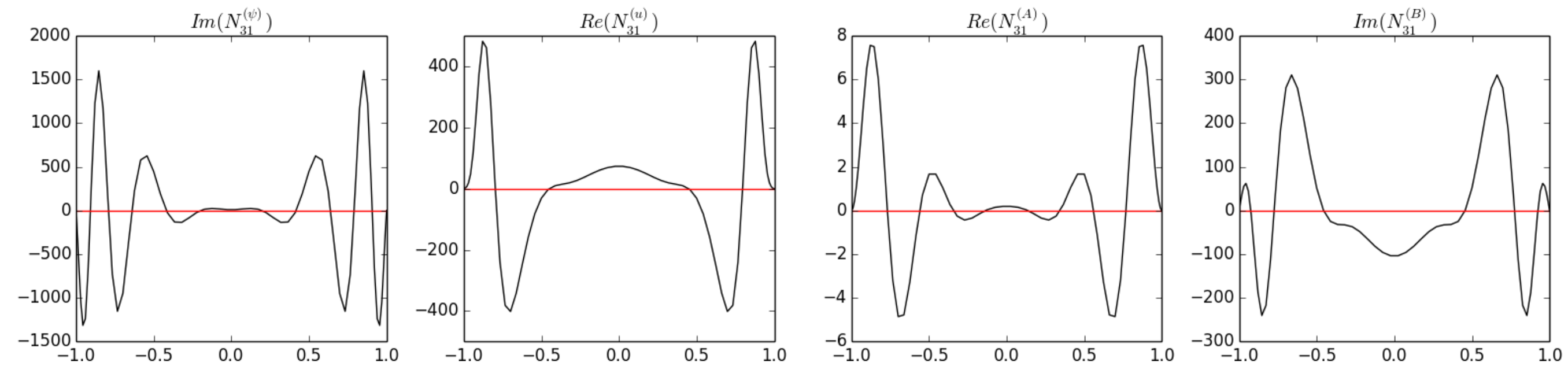


Equations are solved in a
matrix formulation.

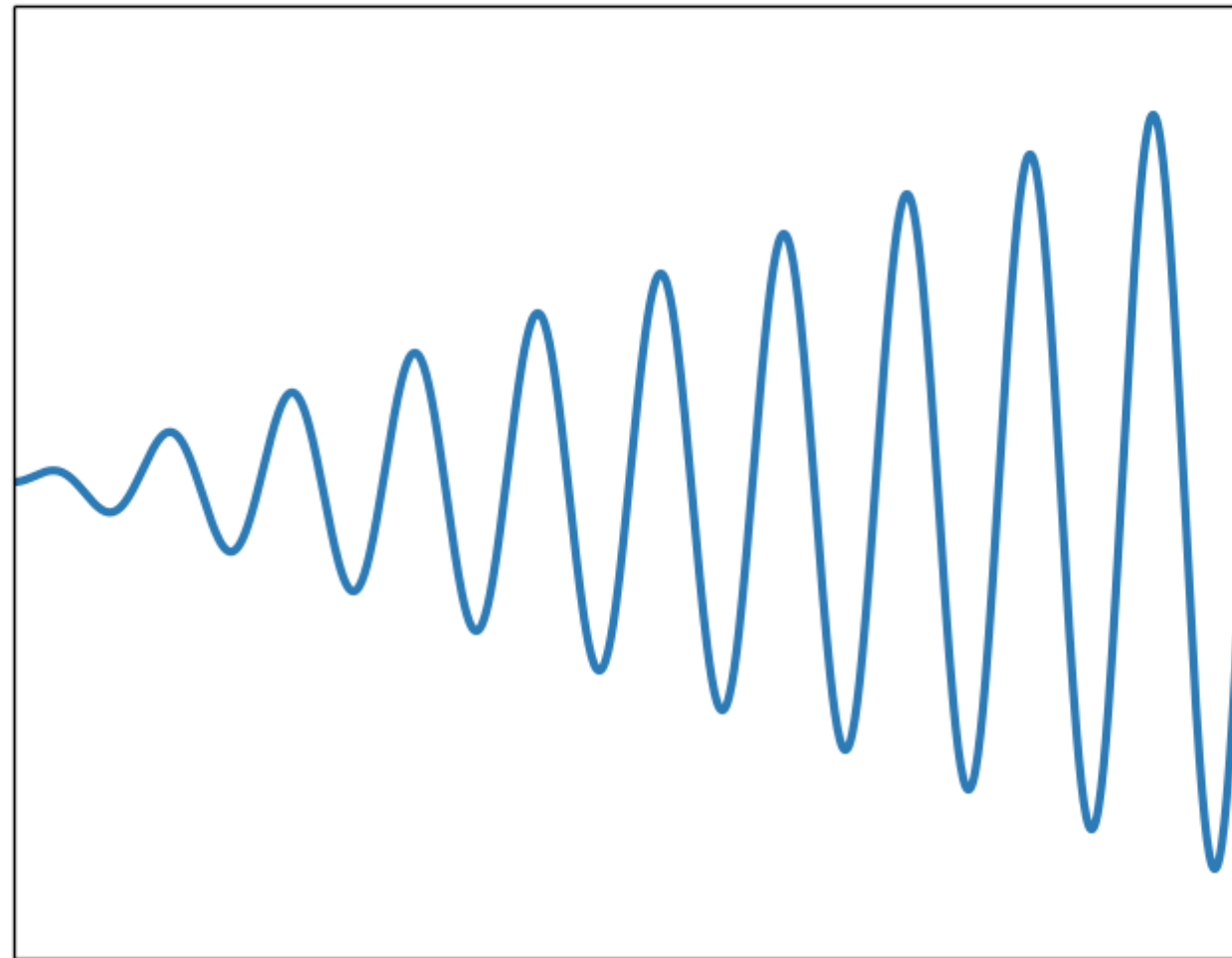
The fluid quantities are expanded
in a perturbation series.

$$\mathbf{V} = \epsilon \mathbf{V}_1 + \epsilon^2 \mathbf{V}_2 + \epsilon^3 \mathbf{V}_3 + \dots$$

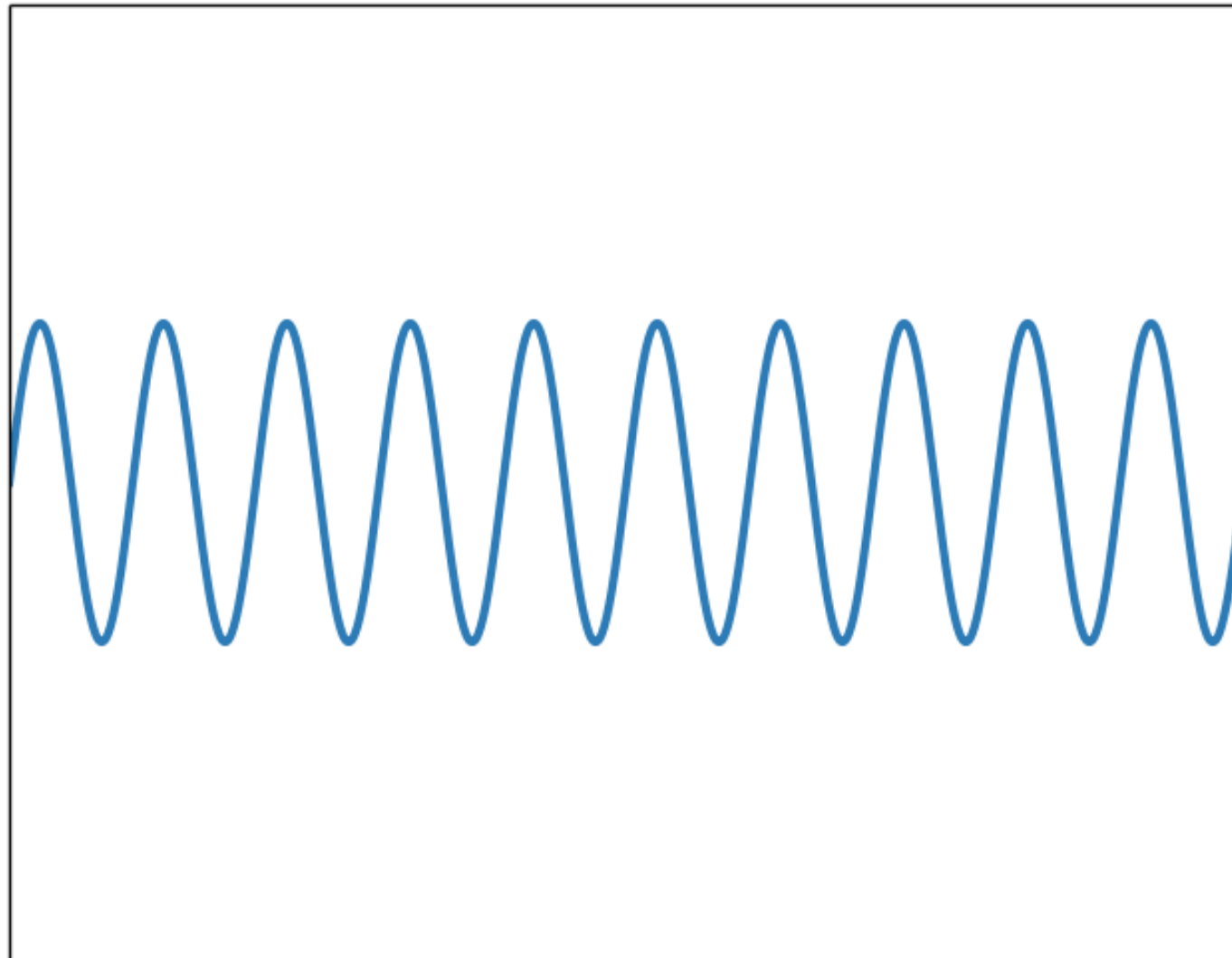
something about boundary layers?



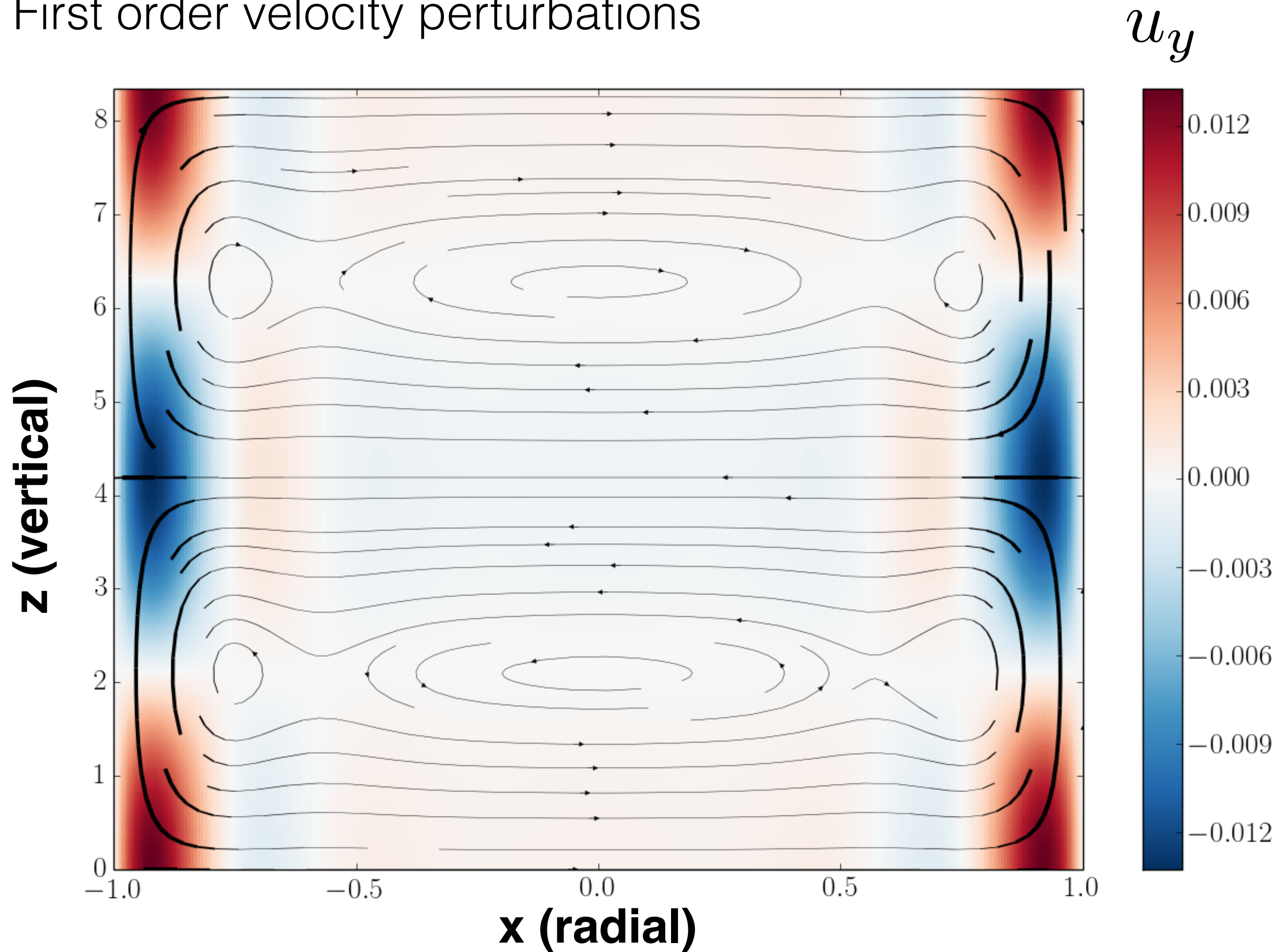
The removal of secular terms yields
solvability criteria.



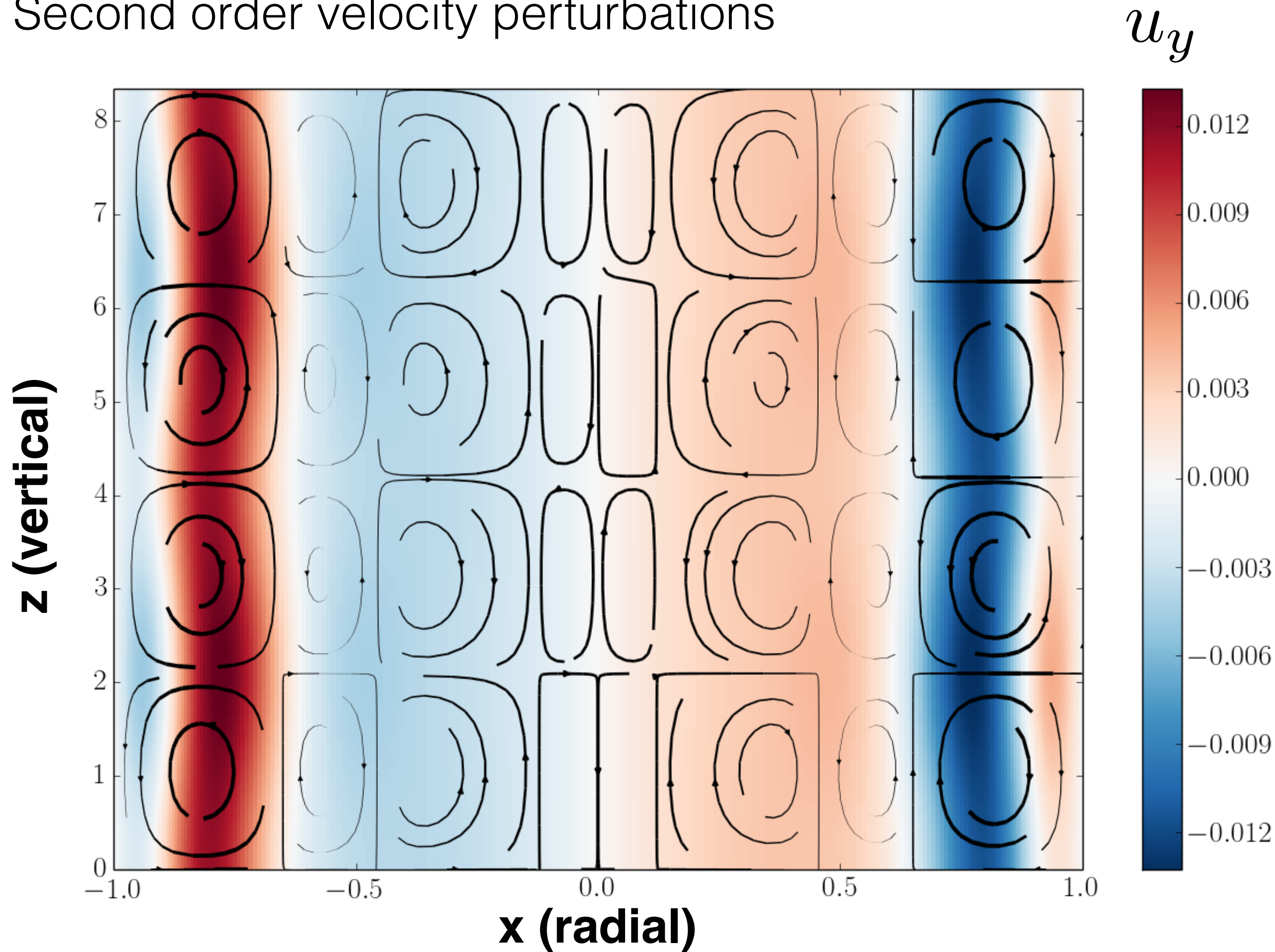
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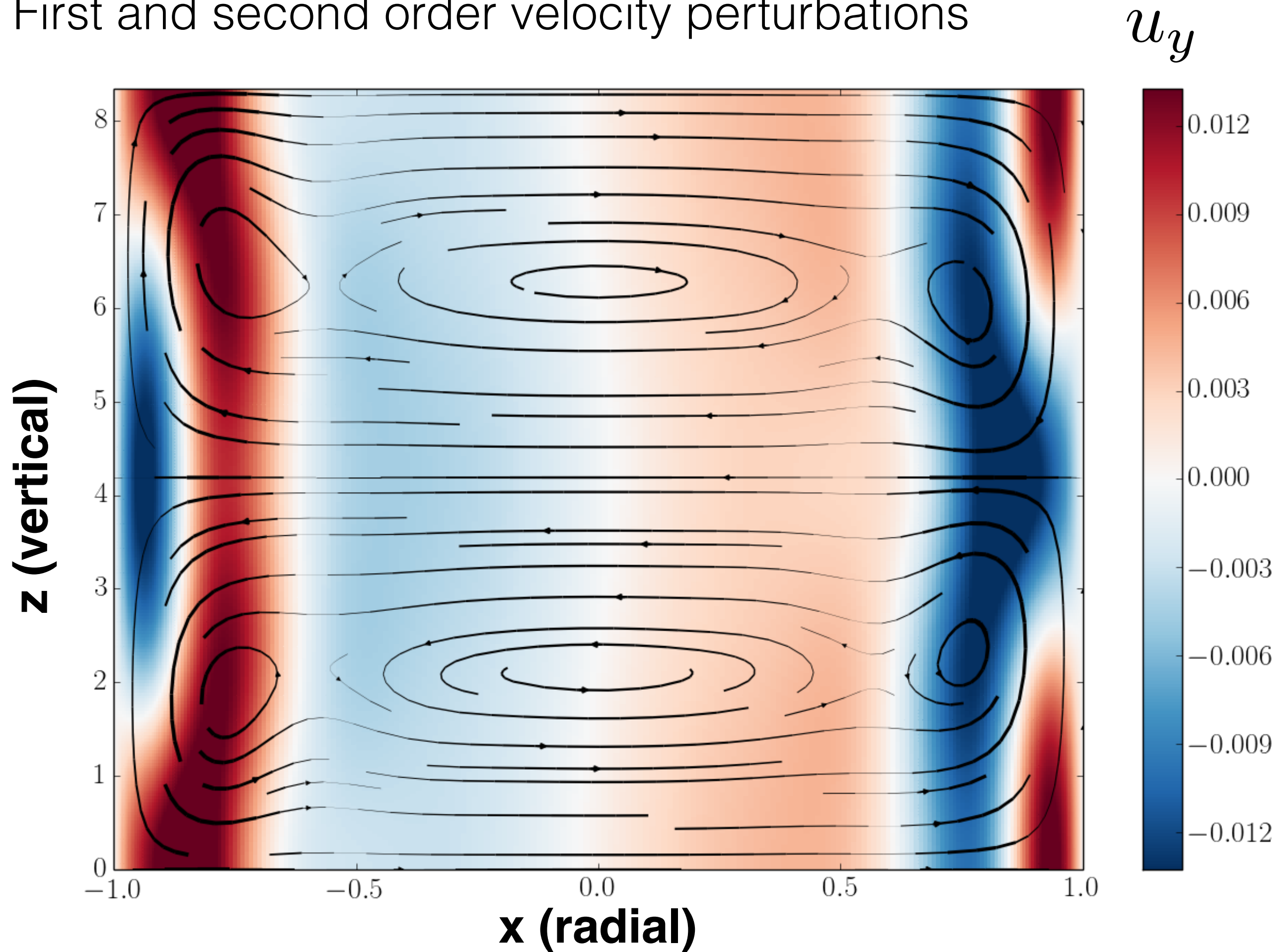
First order velocity perturbations



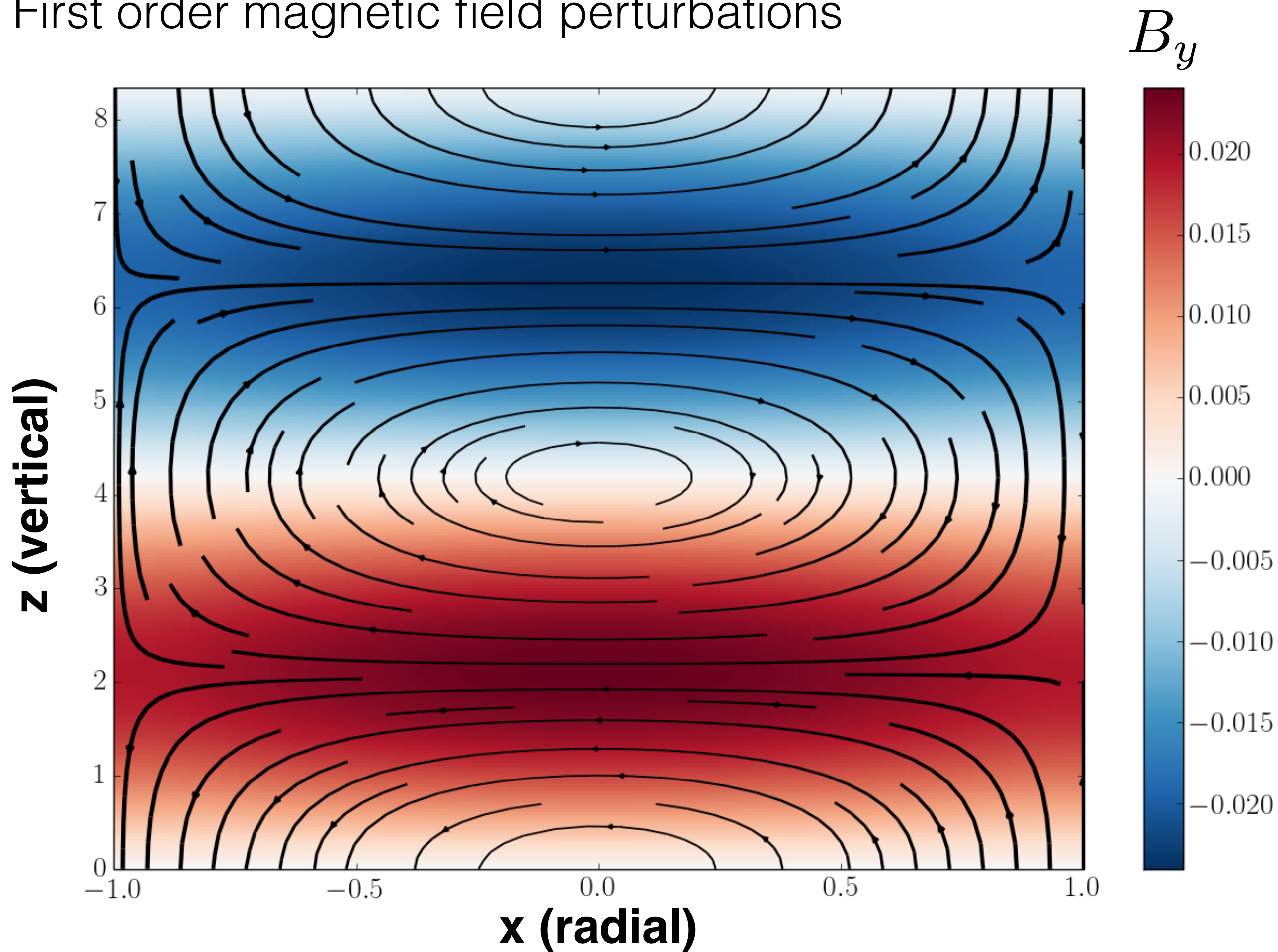
Second order velocity perturbations



First and second order velocity perturbations



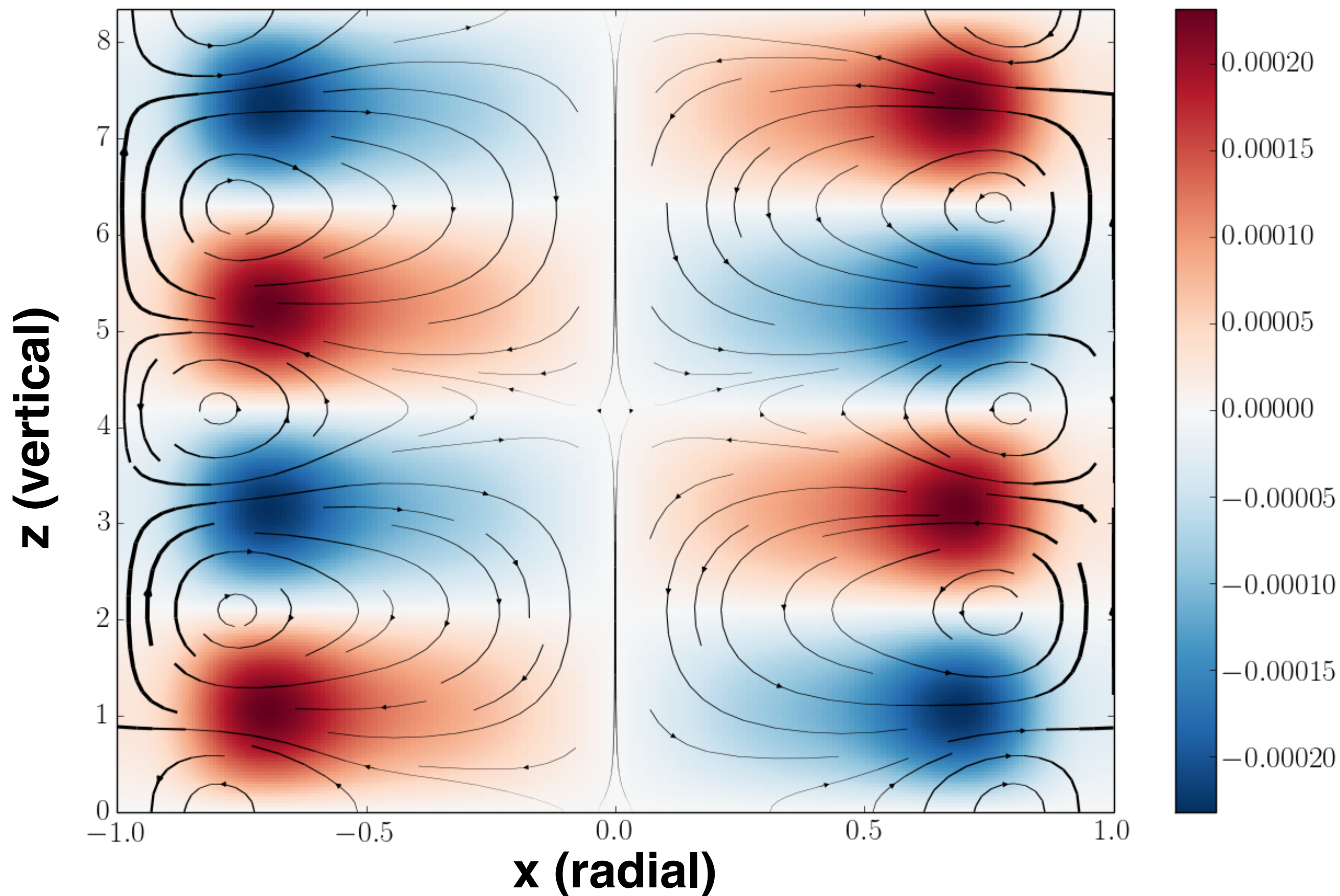
First order magnetic field perturbations



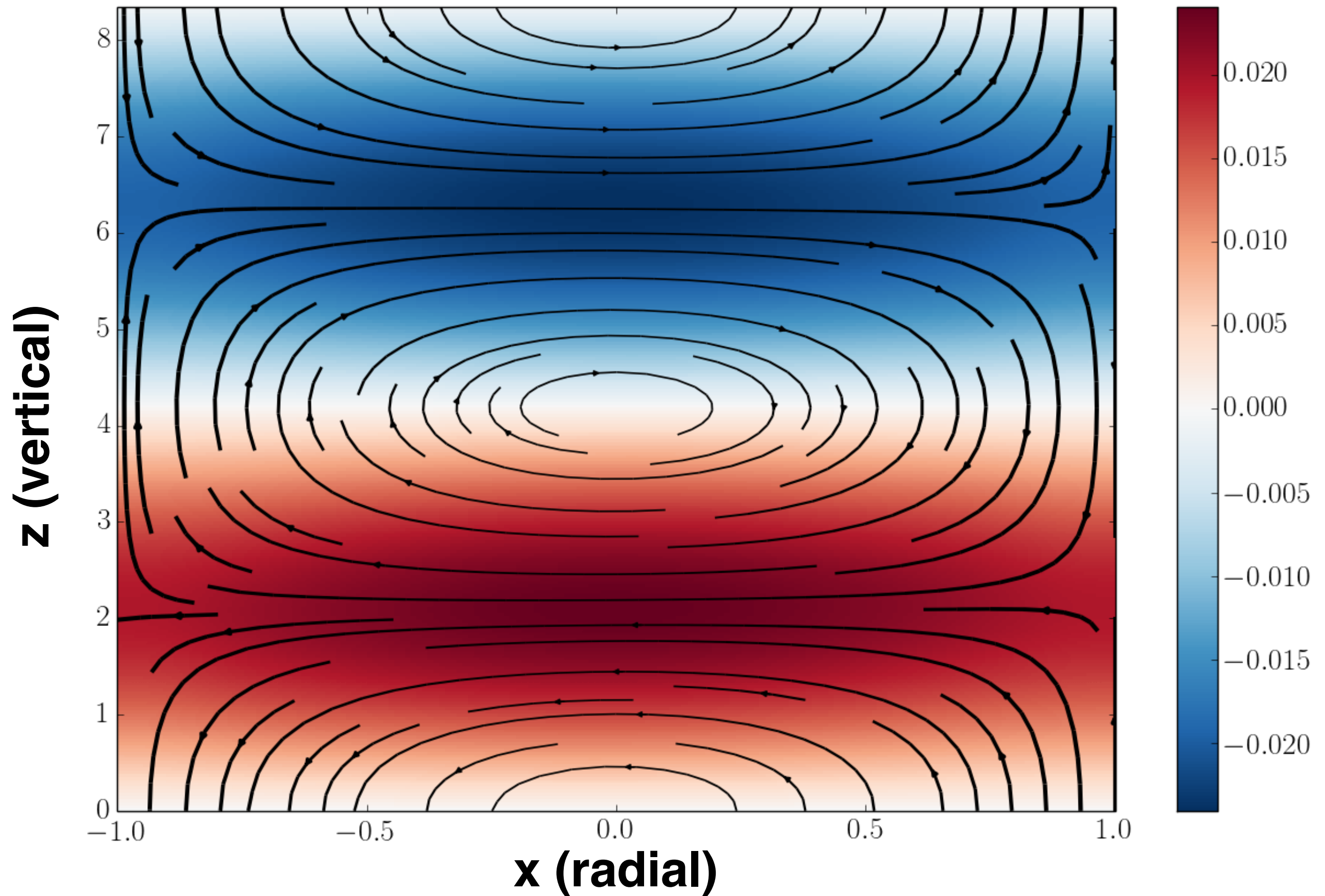
Second order magnetic field perturbations

two OOM smaller!

B_y



First and second order magnetic field perturbations B_y



Future work:

non-thin gap approximation

helical MRI

explore parameter space

comparison to experiment