

1 Basic Equations

The so-called Stokes stream function, used in axisymmetric situations, is given by

$$\mathbf{u} = \begin{bmatrix} \frac{1}{r} \partial_z \psi \hat{\mathbf{r}} \\ u_\phi \hat{\phi} \\ -\frac{1}{r} \partial_r \psi \hat{\mathbf{z}} \end{bmatrix}; \quad (1)$$

here we define A in the same way.

Using the definitions in

$$\begin{aligned} \partial_t \left[\frac{1}{r} \left(\nabla^2 \psi - \frac{2\partial_r \psi}{r} \right) \right] + \frac{1}{r^2} J(\psi, \nabla^2 A - \frac{2\partial_r \psi}{r}) &= \frac{\partial_z A}{r^3} \left(\nabla^2 A - \frac{2\partial_r A}{r} \right) \\ &+ \frac{1}{r} J \left(A, \frac{1}{r} \left(\nabla^2 A - \frac{2\partial_r A}{r} \right) \right) - \frac{2B_\phi \partial_z B_\phi}{r} \\ &+ \nu \left\{ \nabla^2 \left[\frac{1}{r} \left(\nabla^2 \psi - \frac{2\partial_r \psi}{r} \right) \right] - \frac{1}{r^2} \left(\nabla^2 \psi - \frac{2\partial_r \psi}{r} \right) \right\} \end{aligned} \quad (2)$$

For the expanded form of the Ψ equation, Susan gets:

$$\partial_t u_\phi + \frac{J(\psi, u_\phi)}{r} + \frac{u_\phi \partial_z \psi}{r^2} = \frac{J(A, B_\phi)}{r} + \frac{B_\phi \partial_z A}{r^2} + \nu \left(\nabla^2 u_\phi - \frac{u_\phi}{r} \right) \quad (3)$$

$$\partial_t A = \frac{1}{r} J(A, \psi) + \frac{1}{\text{Rm}} \left(\nabla^2 A - \frac{2\partial_r A}{r} \right) \quad (4)$$

$$\begin{aligned} \partial_t B_\phi &= \frac{1}{r} J(A, u_\phi) + \frac{1}{r} J(B_\phi, \psi) \\ &+ \frac{1}{r^2} B_\phi \partial_z \psi - \frac{1}{r^2} u_\phi \partial_z A + \eta \left(\nabla^2 B_\phi - \frac{1}{r^2} B_\phi \right) \end{aligned} \quad (5)$$

2 Detailed Derivation of Ψ Equation

The Ψ equation, governing the x- and z-components of the velocity, is particularly tricky to derive so I will write out the steps here.

1. Find $\hat{\mathbf{r}}$ and $\hat{\mathbf{z}}$ components of the momentum equation, i.e.:

$$\partial_t u_z + [u \cdot \nabla u]_z = [(\nabla \times B) \times B]_z + \frac{1}{\text{Re}} [\nabla^2 u]_z \quad (6)$$

We sub in our stream/flux function notation and expand the operators in cylindrical coordinates. Then take ∂_r of the resulting equation to obtain:

$$\begin{aligned}
& \frac{1}{r^2} \partial_t \partial_r \Psi - \frac{1}{r} \partial_t \partial_r^2 \Psi - \frac{3}{r^4} \partial_z \Psi \partial_r \Psi + \frac{1}{r^3} \partial_r (\partial_z \Psi \partial_r \Psi) + \frac{2}{r^3} \partial_z \Psi \partial_r^2 \Psi - \frac{1}{r^2} \partial_r (\partial_z \Psi \partial_r^2 \Psi) \\
& \quad - \frac{2}{r^3} \partial_r \Psi \partial_r \partial_z \Psi + \frac{1}{r^2} \partial_r (\partial_r \Psi \partial_r \partial_z \Psi) = \\
& \partial_r (B_\phi \partial_z B_\phi) + \frac{2}{r^3} \partial_z^2 A \partial_z A - \frac{1}{r^2} \partial_r (\partial_z^2 A \partial_z A) + \frac{3}{r^4} \partial_z A \partial_r A - \frac{1}{r^3} \partial_r (\partial_z A \partial_r A) - \frac{2}{r^3} \partial_z A \partial_r^2 A \\
& \quad + \frac{1}{r^2} \partial_r (\partial_z A \partial_r^2 A) + \frac{1}{\text{Re}} \left[\frac{3}{r^4} \partial_r \Psi - \frac{3}{r^3} \partial_r^2 \Psi + \frac{2}{r^2} \partial_r^3 \Psi - \frac{1}{r} \partial_r^4 \Psi \right] \quad (7)
\end{aligned}$$

Repeat this process for the $\hat{\mathbf{r}}$ component of the momentum equation,

$$\partial_t u_r + [u \cdot \nabla u]_r = [(\nabla \times B) \times B]_r + \frac{1}{\text{Re}} [\nabla^2 u]_r \quad (8)$$

and take ∂_z of the expanded equation to obtain

$$\begin{aligned}
& \frac{1}{r} \partial_t \partial_z^2 \Psi - \frac{1}{r^3} \partial_z (\partial_z \Psi \partial_z \Psi) + \frac{1}{r^2} \partial_z (\partial_z \Psi \partial_z \partial_r \Psi) - \frac{1}{r^2} \partial_z (\partial_r \Psi \partial_z^2 \Psi) - \frac{1}{r} 2u_\phi \partial_z u_\phi \\
& = -\frac{1}{r^2} \partial_z^3 A \partial_r A - \frac{1}{r^2} \partial_z^2 A \partial_r \partial_z A + \frac{2}{r^3} \partial_r \partial_z A \partial_r A - \frac{1}{r^2} \partial_r^2 \partial_z A \partial_r A - \frac{1}{r^2} \partial_r^2 A \partial_r \partial_z A \\
& \quad + \frac{1}{\text{Re}} \left[-\frac{1}{r^2} \partial_z^2 \partial_r \Psi + \frac{1}{r} \partial_z^2 \partial_r^2 \Psi + \frac{1}{r} \partial_z^4 \Psi \right] \quad (9)
\end{aligned}$$

It is clear from the ∂_t terms that we must combine these equations by subtracting the $\hat{\mathbf{z}}$ equation from the $\hat{\mathbf{r}}$ equation.

When we do, we can simplify the LHS of the equation to:

$$\frac{1}{r} \partial_t \left(\nabla^2 \Psi - \frac{2}{r} \partial_r \Psi \right) + J \left(\Psi, \frac{1}{r^2} \left(\nabla^2 \Psi - \frac{2}{r} \partial_r \Psi \right) \right) - \frac{1}{r} 2u_\phi \partial_z u_\phi \quad (10)$$

Note that the relevant quantity appears to be $\nabla^2 \Psi - \frac{2}{r} \partial_r \Psi$, and that the $\frac{1}{r^2}$ in the second term cannot come out of the Jacobian (a point of disagreement with Jeff's equation above). Also I'm confused why Jeff's has no u_ϕ term. The RHS of this equation is significantly more complicated.

RHS viscous term:

$$\frac{1}{\text{Re}} \left[\nabla^2 \left(\frac{1}{r} \nabla^2 \Psi \right) - \frac{1}{r^3} \partial_r^2 \Psi - \frac{1}{r^4} \partial_r \Psi \right] \quad (11)$$

Full Ψ equation according to Susan:

$$\begin{aligned}
& \frac{1}{r} \partial_t \left(\nabla^2 \Psi - \frac{2}{r} \partial_r \Psi \right) + J \left(\Psi, \frac{1}{r^2} \left(\nabla^2 \Psi - \frac{2}{r} \partial_r \Psi \right) \right) - \frac{1}{r} 2u_\phi \partial_z u_\phi \\
& = J \left(A, \frac{1}{r^2} \left(\nabla^2 A - \frac{2}{r} \partial_r A \right) \right) - \frac{2}{r} B_\phi \partial_z B_\phi \\
& \quad + \frac{1}{\text{Re}} \left[\nabla^2 \left(\frac{1}{r} \nabla^2 \Psi \right) - \frac{1}{r^3} \partial_r^2 \Psi - \frac{1}{r^4} \partial_r \Psi \right] \quad (12)
\end{aligned}$$

Note that this is actually beautifully symmetric. Except the viscous term which still seems clunky....

The derivation of the non-viscous term on the righthand side of the momentum equation ($\mathbf{J} \times \mathbf{B}$) is as follows.

$$\partial_z ([(\nabla \times B) \times B]_r) - \partial_r ([(\nabla \times B) \times B]_z) \quad (13)$$

$$\begin{aligned}
& = \partial_z \left(\left[(\partial_z B_r - \partial_r B_z) B_z - \left(\frac{1}{r} \partial_r (r B_\phi) \right) B_\phi \right] \right) - \partial_r \left([(-\partial_z B_\phi) B_\phi - (\partial_z B_r - \partial_r B_z) B_r] \right) \\
& \quad (14)
\end{aligned}$$

$$\begin{aligned}
& = -\frac{1}{r^2} \partial_z^3 A \partial_r A + \frac{1}{r^3} \partial_r \partial_z A \partial_r A - \frac{1}{r^2} \partial_r^2 \partial_z A \partial_r A - \frac{2}{r^3} \partial_z^2 A \partial_z A \\
& \quad + \frac{1}{r^2} \partial_z^2 \partial_r A \partial_z A + \frac{3}{r^4} \partial_r A \partial_z A - \frac{3}{r^3} \partial_r^2 A \partial_z A + \frac{1}{r^2} \partial_r^3 A \partial_z A - \frac{2}{r} B_\phi \partial_z B_\phi \quad (15)
\end{aligned}$$

This simplifies to

$$J \left(A, \frac{1}{r^2} \left(\nabla^2 A - \frac{2}{r} \partial_r A \right) \right) - \frac{2}{r} B_\phi \partial_z B_\phi \quad (16)$$

Full derivation of viscous term:

$$\partial_z \left(\frac{1}{\text{Re}} [\nabla^2 u]_r \right) - \partial_r \left(\frac{1}{\text{Re}} [\nabla^2 u]_z \right) \quad (17)$$

$$= \frac{1}{\text{Re}} \left[\partial_z \left(\nabla^2 u_r - \frac{1}{r^2} u_r \right) - \partial_r \left(\nabla^2 u_z \right) \right] \quad (18)$$

$$\begin{aligned}
& = \frac{1}{\text{Re}} \left[-\frac{2}{r^2} \partial_z^2 \partial_r \Psi + \frac{2}{r} \partial_z^2 \partial_r^2 \Psi + \frac{1}{r} \partial_z^4 \Psi - \frac{3}{r^4} \partial_r \Psi + \frac{3}{r^3} \partial_r^2 \Psi - \frac{2}{r^2} \partial_r^3 \Psi + \frac{1}{r} \partial_r^4 \Psi \right] \\
& \quad (19)
\end{aligned}$$

3 Recovery of Narrow Gap Equations

4 Nondimensionalization

4.1 Controlled gap width nondimensionalization

The idea is to parameterize the gap width rather than simply nondimensionalizing lengths by a point in the center of the channel r_0 , as we did below.

There are many ways to do this but one option is to define

$$\tilde{r} = r_0 + \tilde{x} \quad (20)$$

Where tildes indicate dimensional quantities. Then for \tilde{x} to stay Cartesian, we need

$$\tilde{r} - r_0 \ll r_2 - r_1 = d \quad (21)$$

where $r_2 = r_1 = d$ is the gap width. Also define $\tilde{x} \ll d$ and $d/r_0 \ll 1$ for the small gap approximation. Thus when we nondimensionalize,

$$r = \frac{\tilde{r}}{r_0} = 1 + \frac{\tilde{x}}{r_0} \quad (22)$$

Note that we could control the gap width in terms of a small parameter ϵx instead of a fraction $\frac{x}{r_0}$, but I believe both should work the same way.

In the example Jeff worked out before, we looked at the base velocity profile in the thin gap limit. The rotation profile is given by $\Omega(r) = \Omega_0 r^{-q}$ in dimensionless quantities, and the background flow $u = r\Omega(r)$, so in our new notation:

$$u = \left(1 + \frac{\tilde{x}}{r_0}\right) \Omega_0 \left(1 + \frac{\tilde{x}}{r_0}\right)^{-q} = \Omega_0 \left(1 + \frac{\tilde{x}}{r_0}\right)^{1-q} \quad (23)$$

Taylor expanding the $\exp(1-q)$ quantity, we arrive at

$$u = \Omega_0 \left(1 + \frac{\tilde{x}}{r_0}\right) - \Omega_0 q \frac{\tilde{x}}{r_0} \quad (24)$$

Then if we define this with respect to a rest frame $\Omega_0 \left(1 + \frac{\tilde{x}}{r_0}\right)$ and define a dimensionless $x = \tilde{x}/r_0$, we get the Umurhan+ base flow $u = -\Omega_0 q x$.

This makes sense to me but I'm having trouble extending it to the actual equations. This implies, for example, that the term $\frac{1}{\eta} \nabla^2 B$, which in the $\hat{\phi}$ equation is

$$[\nabla^2 B]_{\phi} = \nabla^2 B_{\phi} - \frac{B_{\phi}}{r^2}, \quad (25)$$

should become

$$\nabla^2 B_{\phi} - B_{\phi} \left(1 - \frac{2\tilde{x}}{r_0}\right) \quad (26)$$

after substitution and Taylor expansion of the r^{-2} . But clearly there's no $-B_\phi \left(1 - \frac{2\tilde{x}}{r_0}\right)$ in the thin gap equation. What am I missing?? Is this not the right place to be substituting in the new definition of r ??

4.2 Typical nondimensionalization

The momentum equation must be nondimensionalized. Here are the definitions of all of the dimensional components:

$$\begin{aligned}\tilde{u} &= \Omega_0 r_0 \delta u \\ \tilde{x} &= \delta r_0 x \\ \tilde{\nabla} &= \frac{\nabla}{\delta r_0} \\ \tilde{t} &= \frac{t}{\Omega_0} \\ \tilde{B} &= B_0 B \\ \tilde{P} &= P_0 P \\ \tilde{\rho} &= \rho_0 \rho\end{aligned}\tag{27}$$

If we define the velocity scale v_0 as the local sound speed scale $\left(c_{s0} \equiv \sqrt{\frac{P_0}{\rho_0}}\right)$, then $\Omega_0 r_0 \delta = \sqrt{\frac{P_0}{\rho_0}}$.

Nondimensionalizing the momentum equation and dividing by a factor of $\Omega_0^2 r_0 \delta$ yields

$$\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} = \frac{1}{4\pi\rho} \frac{B_0^2}{\rho_0 \Omega_0^2 r_0^2 \delta^2} (\nabla \times \mathbf{B}) \times \mathbf{B} + \frac{1}{\text{Re}} \nabla^2 \mathbf{u} - 2\boldsymbol{\Omega} \times \mathbf{u} - \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \mathbf{r}) \tag{28}$$

If we define

$$\beta \equiv \frac{P}{P_{mag}} = \frac{\rho_0 \Omega_0^2 r_0^2 8\pi}{B_0^2} \tag{29}$$

where $P_{mag} = \frac{B_0^2}{8\pi}$, then the factor in front of $(\nabla \times \mathbf{B}) \times \mathbf{B}$ should be $\frac{2}{\beta}$. Agreed?

5 Perturbed Equations

We perturb the wide gap equations according to

$$\mathbf{B} = B_0 \hat{z} + \mathbf{B}_1, \tag{30}$$

which is the same perturbation we used in the thin-gap construction. But wait! We perturbed the thin-gap equations according to

$$\mathbf{u} = -q\Omega_0 r \hat{\phi} + \mathbf{u}_1 \tag{31}$$

but I don't think this is valid in the wide-gap case. To be sure, I'm going to perturb instead by

$$\mathbf{u} = r\Omega(r)\hat{\phi} + \mathbf{u}_1 \quad (32)$$

where $\Omega(r) = \Omega_0 \left(\frac{r}{r_0}\right)^{-q} = \Omega_0(r)^{-q}$ in dimensionless coordinates (but keeping Ω_0 to flag a rotational term...) Agreed?

We also add the Coriolis and centrifugal terms $-2\boldsymbol{\Omega} \times \mathbf{u} - \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \mathbf{r})$ which expand as follows:

$$-2\Omega(r)\hat{\mathbf{z}} \times (\mathbf{u}_1 + r\Omega(r)\hat{\phi}) = -2\Omega(r)u_r\hat{\phi} + 2\Omega(r)u_\phi\hat{\mathbf{r}} + 2r\Omega(r)^2\hat{\mathbf{r}} \quad (33)$$

$$-\Omega(r)\hat{\mathbf{z}} \times (\Omega(r)\hat{\mathbf{z}} \times r\hat{\mathbf{r}}) = +\Omega(r)^2r\hat{\mathbf{r}} \quad (34)$$

The $\hat{\mathbf{r}}$ terms will have ∂_z applied to them, which will destroy the $3\Omega(r)^2r\hat{\mathbf{r}}$ term and so the righthand side of the Ψ equation will ultimately gain only the term $2\Omega(r)\partial_z u_\phi\hat{\mathbf{r}}$. The $\hat{\phi}$ equation gains the term $-\frac{2}{r}\Omega(r)\partial_z\Psi$ on the righthand side.

The Ψ equation becomes

$$\begin{aligned} \frac{1}{r}\partial_t \left(\nabla^2\Psi - \frac{2}{r}\partial_r\Psi \right) + J \left(\Psi, \frac{1}{r^2} \left(\nabla^2\Psi - \frac{2}{r}\partial_r\Psi \right) \right) - \frac{1}{r}2u_\phi\partial_z u_\phi - \partial_z(u_\phi\Omega(r)) \\ = \frac{2}{\beta}J \left(A, \frac{1}{r^2} \left(\nabla^2 A - \frac{2}{r}\partial_r A \right) \right) - \frac{2}{\beta}\frac{2}{r}B_\phi\partial_z B_\phi + 2\Omega(r)\partial_z u_\phi \\ + \frac{1}{\text{Re}} \left[\nabla^2 \left(\frac{1}{r}\nabla^2\Psi \right) - \frac{1}{r^3}\partial_r^2\Psi - \frac{1}{r^4}\partial_r\Psi \right] + \frac{2}{\beta}\frac{1}{r}B_0\partial_z \left(\nabla^2 A - \frac{2}{r}\partial_r A \right) \end{aligned} \quad (35)$$

Note that one of the terms gained from the base state in the $(\mathbf{u} \cdot \nabla)\mathbf{u}$ term can be combined with the term gained from the Coriolis term, but here I write them separately so we can check the equation. Equation 3 becomes

$$\begin{aligned} \partial_t u_\phi + \frac{J(\psi, u_\phi)}{r} + \frac{u_\phi\partial_z\psi}{r^2} + \partial_z\Psi \left(\frac{2}{r}\Omega(r) + \partial_r\Omega(r) \right) = \\ \frac{2}{\beta}\frac{J(A, B_\phi)}{r} + \frac{2}{\beta}\frac{B_\phi\partial_z A}{r^2} + \frac{1}{\text{Re}} \left(\nabla^2 u_\phi - \frac{u_\phi}{r} \right) + \frac{2}{\beta}B_0\partial_z B_\phi - \frac{2}{r}\Omega(r)\partial_z\Psi \end{aligned} \quad (36)$$

Equation 4 picks up $+\Omega(r)B_\phi$ from the term $-(u_0\hat{\phi} \cdot \nabla)\mathbf{B}_1$ and $-\Omega(r)B_\phi$ from the term $+(\mathbf{B}_1 \cdot \nabla)\hat{\phi}$ and, so those cancel and the equation becomes

$$\partial_t A = \frac{1}{r}J(A, \psi) + \frac{1}{\text{Rm}} \left(\nabla^2 A - \frac{2\partial_r A}{r} \right) + B_0\partial_z\Psi \quad (37)$$

Note that this is perfectly analogous to the thin-gap version of this equation.

The $\hat{\phi}$ component of the induction equation, Equation 5, becomes

$$\begin{aligned} \partial_t B_\phi &= \frac{1}{r} J(A, u_\phi) + \frac{1}{r} J(B_\phi, \psi) \\ &+ \frac{1}{r^2} B_\phi \partial_z \psi - \frac{1}{r^2} u_\phi \partial_z A + \frac{1}{\text{Rm}} \left(\nabla^2 B_\phi - \frac{1}{r^2} B_\phi \right) + B_0 \partial_z u_\phi + \partial_z A \left(\frac{2}{r} \Omega(r) + \partial_r \Omega(r) \right) \end{aligned} \quad (38)$$

6 Matrix Formulation

This is all pending a rigorous check of Equations 35 - 38, which Jeff is working on, but I'll start putting this into a matrix construction.

First, the nonlinear vector, on the lefthand side of the equation, is

$$\mathbf{N} = \begin{bmatrix} J\left(\Psi, \frac{1}{r^2} (\nabla^2 \Psi - \frac{2}{r} \partial_r \Psi)\right) - \frac{2}{\beta} J\left(A, \frac{1}{r^2} (\nabla^2 A - \frac{2}{r} \partial_r A)\right) - \frac{2}{r} u_\phi \partial_z u_\phi + \frac{2}{\beta} \frac{2}{r} B_\phi \partial_z B_\phi \\ \frac{1}{r} J(\Psi, u_\phi) - \frac{1}{r} \frac{2}{\beta} J(A, B_\phi) + \frac{1}{r^2} u_\phi \partial_z \Psi - \frac{2}{\beta} \frac{1}{r^2} B_\phi \partial_z A \\ - \frac{1}{r} J(A, \Psi) \\ - \frac{1}{r} J(A, u_\phi) - \frac{1}{r} J(B_\phi, \Psi) - \frac{1}{r^2} B_\phi \partial_z \Psi + \frac{1}{r^2} u_\phi \partial_z A \end{bmatrix} \quad (39)$$

Note that these differ from the thin-gap nonlinear terms not only because of the curvature terms in the Jacobians, but also because of the additional advective terms in all but the \mathbf{A} equation.

The ∂_t terms are grouped together into

$$\partial_t D = \partial_t \begin{bmatrix} \frac{1}{r} \nabla^2 - \frac{2}{r^2} \partial_r & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad (40)$$

For the righthand side of the equation, I'll follow the same process that I did with the thin-gap. That is I'll first separate the matrices by physical meaning, and then regroup terms based on z -dependence. The RHS can be described by three matrices: one representing the rotational terms, one representing the background field terms, and one representing the viscous/resistive terms.

$$\begin{aligned}
RHS &= \begin{bmatrix} 3\Omega(r)\partial_z u_\phi \\ -\frac{4}{r}\Omega(r)\partial_z \Psi - \partial_r \Omega(r)\partial_z \Psi \\ 0 \\ \frac{2}{r}\Omega(r)\partial_z A + \partial_r \Omega(r)\partial_z A \end{bmatrix} + \begin{bmatrix} \frac{2}{\beta} \frac{1}{r} B_0 \partial_z (\nabla^2 A - \frac{2}{r} \partial_r A) \\ \frac{2}{\beta} B_0 \partial_z B_\phi \\ B_0 \partial_z \Psi \\ B_0 \partial_z u_\phi \end{bmatrix} + \begin{bmatrix} \frac{1}{\text{Re}} [\nabla^2 (\frac{1}{r} \nabla^2 \Psi) - \frac{1}{r^3} \partial_r^2 \Psi - \frac{1}{r^4} \partial_r \Psi] \\ \frac{1}{\text{Re}} (\nabla^2 u_\phi - \frac{1}{r} u_\phi) \\ \frac{1}{\text{Re}} (\nabla^2 A - \frac{2}{r} \partial_r A) \\ \frac{1}{\text{Re}} (\nabla^2 B_\phi - \frac{1}{r^2} B_\phi) \end{bmatrix} \\
&= \begin{bmatrix} 0 & 3\Omega(r)\partial_z & 0 & 0 \\ -\frac{4}{r}\Omega(r)\partial_z - \partial_r \Omega(r)\partial_z & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{2}{r}\Omega(r)\partial_z + \partial_r \Omega(r)\partial_z & 0 \end{bmatrix} + \\
&\begin{bmatrix} 0 & 0 & \frac{2}{\beta} \frac{1}{r} B_0 \partial_z (\nabla^2 - \frac{2}{r} \partial_r) & 0 \\ 0 & 0 & 0 & \frac{2}{\beta} B_0 \partial_z \\ B_0 \partial_z & 0 & 0 & 0 \\ 0 & B_0 \partial_z & 0 & 0 \end{bmatrix} + \begin{bmatrix} \frac{1}{\text{Re}} (\nabla^2 (\frac{1}{r} \nabla^2) - \frac{1}{r^3} \partial_r^2 - \frac{1}{r^4} \partial_r) \\ \frac{1}{\text{Re}} (\nabla^2 - \frac{1}{r}) \\ \frac{1}{\text{Re}} (\nabla^2 - \frac{2}{r} \partial_r) \\ \frac{1}{\text{Re}} (\nabla^2 - \frac{1}{r^2}) \end{bmatrix} \quad (41)
\end{aligned}$$

We separate the viscous/resistive matrix out in terms of ∂_z dependence.

$$\begin{aligned}
&\text{viscous terms} = \\
&\begin{bmatrix} \frac{1}{\text{Re}} (-\frac{3}{r^4} \partial_r + \frac{3}{r^3} \partial_r^2 - \frac{2}{r^2} \partial_r^3 + \frac{1}{r} \partial_r^4) & 0 & 0 & 0 \\ 0 & \frac{1}{\text{Re}} (\partial_r^2 + \frac{1}{r} \partial_r - \frac{1}{r}) & 0 & 0 \\ 0 & 0 & \frac{1}{\text{Re}} (\partial_r^2 - \frac{1}{r} \partial_r) & 0 \\ 0 & 0 & 0 & \frac{1}{\text{Re}} (\partial_r^2 + \frac{1}{r} \partial_r - \frac{1}{r^2}) \end{bmatrix} \\
&+ \partial_z^2 \begin{bmatrix} \frac{1}{\text{Re}} (-\frac{2}{r^2} \partial_r + \frac{2}{r} \partial_r^2) & 0 & 0 & 0 \\ 0 & \frac{1}{\text{Re}} & 0 & 0 \\ 0 & 0 & \frac{1}{\text{Re}} & 0 \\ 0 & 0 & 0 & \frac{1}{\text{Re}} \end{bmatrix} \\
&+ \partial_z^4 \begin{bmatrix} \frac{1}{\text{Re}} \frac{1}{r} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad (42)
\end{aligned}$$

Note that the form of each of the terms is different in the first matrix.

We also separate the terms in the $B0$ matrix by ∂_z dependence:

$$\begin{aligned}
B_0 \text{ terms} &= \partial_z \begin{bmatrix} 0 & 0 & \frac{2}{\beta} \frac{1}{r} B_0 (\partial_r^2 - \frac{1}{r} \partial_r) & 0 \\ 0 & 0 & 0 & \frac{2}{\beta} B_0 \\ B_0 & 0 & 0 & 0 \\ 0 & B_0 & 0 & 0 \end{bmatrix} + \partial_z^3 \begin{bmatrix} 0 & 0 & \frac{2}{\beta} \frac{1}{r} B_0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad (43)
\end{aligned}$$

We replace B_0 with our lower magnetic field strength $(1 - \epsilon^2)$:

$$B_0 \text{ terms} = (1 - \epsilon^2) \partial_z \begin{bmatrix} 0 & 0 & \frac{2}{\beta} \frac{1}{r} (\partial_r^2 - \frac{1}{r} \partial_r) & 0 \\ 0 & 0 & 0 & \frac{2}{\beta} \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} + (1 - \epsilon^2) \partial_z^3 \begin{bmatrix} 0 & 0 & \frac{2}{\beta} \frac{1}{r} & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad (44)$$

We now define, in analogy to the thin-gap matrices, the following:

$$\mathcal{L}_0 = \begin{bmatrix} \frac{1}{\text{Re}} \left(-\frac{3}{r^4} \partial_r + \frac{3}{r^3} \partial_r^2 - \frac{2}{r^2} \partial_r^3 + \frac{1}{r} \partial_r^4 \right) & 0 & 0 & 0 \\ 0 & \frac{1}{\text{Re}} \left(\partial_r^2 + \frac{1}{r} \partial_r - \frac{1}{r} \right) & 0 & 0 \\ 0 & 0 & \frac{1}{\text{Rm}} \left(\partial_r^2 - \frac{1}{r} \partial_r \right) & 0 \\ 0 & 0 & 0 & \frac{1}{\text{Rm}} \left(\partial_r^2 + \frac{1}{r} \partial_r - \frac{1}{r^2} \right) \end{bmatrix} \quad (45)$$

$$\mathcal{L}_1 = \begin{bmatrix} 0 & 3\Omega(r) & \frac{2}{\beta} \frac{1}{r} (\partial_r^2 - \frac{1}{r} \partial_r) & 0 \\ -\frac{4}{r} \Omega(r) - \partial_r \Omega(r) & 0 & 0 & \frac{2}{\beta} \\ 1 & 0 & 0 & 0 \\ 0 & 1 & \frac{2}{r} \Omega(r) + \partial_r \Omega(r) & 0 \end{bmatrix} \quad (46)$$

$$\mathcal{L}_2 = \begin{bmatrix} \frac{1}{\text{Re}} \left(-\frac{2}{r^2} \partial_r + \frac{2}{r} \partial_r^2 \right) & 0 & 0 & 0 \\ 0 & \frac{1}{\text{Re}} & 0 & 0 \\ 0 & 0 & \frac{1}{\text{Rm}} & 0 \\ 0 & 0 & 0 & \frac{1}{\text{Rm}} \end{bmatrix} \quad (47)$$

$$\mathcal{L}_3 = \begin{bmatrix} 0 & 0 & \frac{2}{\beta} \frac{1}{r} & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad (48)$$

$$\mathcal{L}_4 = \begin{bmatrix} \frac{1}{\text{Re}} \frac{1}{r} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad (49)$$

$$\mathcal{G} = \begin{bmatrix} 0 & 0 & \frac{2}{\beta} \frac{1}{r} (\partial_r^2 - \frac{1}{r} \partial_r) & 0 \\ 0 & 0 & 0 & \frac{2}{\beta} \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \quad (50)$$

Defining

$$\mathcal{L} = \mathcal{L}_0 + \mathcal{L}_1 \partial_z + \mathcal{L}_2 \partial_z^2 + \mathcal{L}_3 \partial_z^3 + \mathcal{L}_4 \partial_z^4 \quad (51)$$

and

$$\tilde{\mathcal{G}} = -\mathcal{G} \partial_z - \mathcal{L}_3 \partial_z^3, \quad (52)$$

we have

$$\mathcal{D}\partial_t \mathbf{V} + \mathbf{N} = \mathcal{L}\mathbf{V} + \epsilon^2 \tilde{\mathcal{G}}\mathbf{V} \quad (53)$$

which we then expand:

$$\begin{aligned} \partial_t &\rightarrow \epsilon^2 \partial_T \\ \partial_z &\rightarrow \partial_z + \epsilon \partial_Z \end{aligned} \quad (54)$$

and perturb:

$$\mathbf{V} = \epsilon \mathbf{V}_1 + \epsilon^2 \mathbf{V}_2 + \epsilon^3 \mathbf{V}_3 \quad (55)$$

Note that as we have defined these matrices, the matrices are of course different than in the thin-gap case, and the nonlinear terms are different, but the equations for behavior at each order in ϵ are identical, that is

$$\mathcal{L}\mathbf{V}_1 = 0 \quad (56)$$

$$\mathcal{L}\mathbf{V}_2 = \mathbf{N}_2 - \tilde{\mathcal{L}}_1 \partial_Z \mathbf{V}_1 \quad (57)$$

$$\mathcal{D}\partial_T \mathbf{V}_1 + \mathbf{N}_3 = \mathcal{L}\mathbf{V}_3 + \tilde{\mathcal{L}}_1 \partial_Z \mathbf{V}_2 + \tilde{\mathcal{L}}_2 \partial_Z^2 \mathbf{V}_1 + \tilde{\mathcal{G}}\mathbf{V}_1 \quad (58)$$

are still the correct equations to orders ϵ , ϵ^2 , and ϵ^3 , respectively.

7 Notes for paper

– Comment on channel mode formation w.r.t. parasitic modes?

A Cylindrical derivatives

Everything here follows <http://farside.ph.utexas.edu/teaching/336L/Fluidhtml/node177.html#scyl>.

For a scalar field ψ ,

$$\nabla \psi = \frac{\partial \psi}{\partial r} \hat{\mathbf{r}} + \frac{1}{r} \frac{\partial \psi}{\partial \phi} \hat{\phi} + \frac{\partial \psi}{\partial z} \hat{\mathbf{z}}. \quad (59)$$

However, for a *vector* field \mathbf{u} ,

$$\nabla \cdot \mathbf{u} = \frac{1}{r} \frac{\partial(r u_r)}{\partial r} + \frac{1}{r} \frac{\partial u_\phi}{\partial \phi} + \frac{\partial u_z}{\partial z} \quad (60)$$

and

$$\nabla \times \mathbf{u} = \left(\frac{1}{r} \frac{\partial u_z}{\partial \phi} - \frac{\partial u_\phi}{\partial z} \right) \hat{\mathbf{r}} + \left(\frac{\partial u_r}{\partial z} - \frac{\partial u_z}{\partial r} \right) \hat{\phi} + \left(\frac{1}{r} \frac{\partial(r u_\phi)}{\partial r} - \frac{1}{r} \frac{\partial u_r}{\partial \phi} \right) \hat{\mathbf{z}}. \quad (61)$$

We also need the ϕ component of the convective derivative $\mathbf{u} \cdot \nabla \mathbf{u}$,

$$[\mathbf{u} \cdot \nabla \mathbf{u}]_\phi = \mathbf{u} \cdot \nabla u_\phi + \frac{u_r u_\phi}{r}, \quad (62)$$

and finally, the vector Laplacian,

$$(\nabla^2 \mathbf{u})_r = \nabla^2 u_r - \frac{u_r}{r^2} - \frac{2}{r^2} \frac{\partial u_\phi}{\partial \phi} \quad (63)$$

$$(\nabla^2 \mathbf{u})_\phi = \nabla^2 u_\phi + \frac{2}{r^2} \frac{\partial u_r}{\partial \phi} - \frac{u_\phi}{r^2} \quad (64)$$

$$(\nabla^2 \mathbf{u})_z = \nabla^2 u_z, \quad (65)$$

where ∇ on the vector components is given by equation (59).

Note that, expanding the definition of the vector Laplacian, where the cylindrical scalar Laplacian is substituted in for $\nabla^2 u_r$ and $\nabla^2 u_z$