

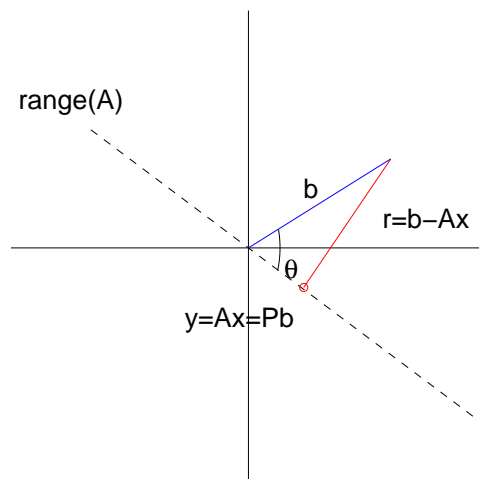
# Lecture 18 - *Conditioning of Least-Squares Problems*

## OBJECTIVE:

The conditioning of least-squares problems is subtle: it combines the conditioning of linear systems of equations with the geometry of orthogonal projection. It is important because of the implications for the stability of least-squares algorithms.

## ◇ FOUR CONDITIONING PROBLEMS

Recall the least-squares problem (Lecture 11), illustrated geometrically as follows:



We assume  $\mathbf{A}$  has full rank, and let  $\|\cdot\| = \|\cdot\|_2$ .

Then, given  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $m \geq n$ , and  $\mathbf{b} \in \mathbb{R}^m$ , find  $\mathbf{x} \in \mathbb{R}^n$  such that  $\|\mathbf{b} - \mathbf{A}\mathbf{x}\|$  is minimized.

The solution  $\mathbf{x}$  and the closest point  $\mathbf{y} = \mathbf{A}\mathbf{x}$  to  $\mathbf{b}$  are

$$\mathbf{x} = \mathbf{A}^\dagger \mathbf{b} \quad \text{and} \quad \mathbf{y} = \mathbf{P}\mathbf{b}$$

where  $\mathbf{A}^\dagger = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T$  is the pseudoinverse of  $\mathbf{A}$  and  $\mathbf{P} = \mathbf{A}\mathbf{A}^\dagger$  is the orthogonal projector onto  $\text{range}(\mathbf{A})$ .

We consider the conditioning of the least-squares problems with respect to perturbations.

(Recall conditioning pertains to the sensitivity of solutions to perturbations in the data).

We will look at this in two ways for the least-squares problem. In either case, the data are  $\mathbf{A}$  and  $\mathbf{b}$   
→ we can perturb one of these.

The solution can be considered to be either  $\mathbf{x}$  or  $\mathbf{y}$ .

(This is how we get 4 conditioning problems!)

## ◇ THEORETICAL RESULT

We have theory that provides answers to these questions.

The results involve 3 (dimensionless) parameters that appear repeatedly in analyzing least-squares problems.

They are

1.  $\kappa(\mathbf{A})$  – the condition number of  $\mathbf{A}$ .

Recall, if  $\mathbf{A}$  is square,  $\kappa(\mathbf{A}) = \|\mathbf{A}\| \|\mathbf{A}^{-1}\|$ .

If  $\mathbf{A}$  is rectangular, this definition generalizes to

$$\kappa(\mathbf{A}) = \|\mathbf{A}\| \|\mathbf{A}^\dagger\| = \frac{\sigma_1}{\sigma_n}.$$

Note:  $1 \leq \kappa(\mathbf{A}) \leq \infty$ .

2. angle  $\theta$  (recall figure)

This is a measure of how close  $\mathbf{b}$  is to  $\mathbf{y}$ :

$$\theta = \cos^{-1} \frac{\|\mathbf{y}\|}{\|\mathbf{b}\|}$$

Note:  $0 \leq \theta \leq \frac{\pi}{2}$ .

3.  $\eta$ , a measure of how much  $\|\mathbf{y}\|$  falls short of its maximum value, given  $\|\mathbf{A}\|$  and  $\|\mathbf{x}\|$

$$\eta = \frac{\|\mathbf{A}\| \|\mathbf{x}\|}{\|\mathbf{y}\|} = \frac{\|\mathbf{A}\| \|\mathbf{x}\|}{\|\mathbf{Ax}\|}$$

Note:  $1 \leq \eta \leq \kappa(\mathbf{A})$ .

**Theorem 1.** Let  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $m \geq n$ , with full rank and  $\mathbf{b} \in \mathbb{R}^m$  be given.

The least-squares problem has the following 2-norm relative condition numbers describing the sensitivities of  $\mathbf{y}$  and  $\mathbf{x}$  with respect to perturbations in  $\mathbf{b}$  and  $\mathbf{A}$ :

	$\mathbf{y}$	$\mathbf{x}$
$\mathbf{b}$	$\frac{1}{\cos(\theta)}$	$\frac{\kappa(\mathbf{A})}{\eta \cos(\theta)}$
$\mathbf{A}$	$\frac{\kappa(\mathbf{A})}{\cos(\theta)}$	$\kappa(\mathbf{A}) + \frac{\kappa^2(\mathbf{A}) \tan(\theta)}{\eta}$

**Note 1.** The results in the first row are exact (tight), while the results in the second row are upper bounds.

**Note 2.** When  $m = n$  (i.e., we have a square, nonsingular system and  $\theta = 0$ ) the bounds in the second column reduce to  $\frac{\kappa(\mathbf{A})}{\eta}$  and  $\kappa(\mathbf{A})$ . The results in the first column are no longer relevant.

## ◇ TRANSFORMATION TO A DIAGONAL MATRIX

We will provide simple proofs of the conditioning results with respect to perturbations in  $\mathbf{b}$  only.

(The full proofs of conditioning results with respect to perturbations in  $\mathbf{A}$  are in the text, pp. 133-135.)

First, we transform the general least-squares problem to a convenient diagonal problem.

How do we do this? SVD!

Let  $\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$ .

Because perturbations are measured by their 2-norms, they are unaffected by the orthogonal transformations  $\mathbf{U}, \mathbf{V}^T$ .

i.e., the perturbation behaviour of  $\mathbf{A}$  is the same as that of  $\mathbf{\Sigma}$ !

Thus, without loss of generality, we can forget about  $\mathbf{A}$  and deal with  $\mathbf{\Sigma}$  directly.

So, let

$$\mathbf{A} = \mathbf{\Sigma} = \begin{bmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_n \\ & & & & \mathbf{0} \end{bmatrix} = \begin{bmatrix} \mathbf{A}_1 \\ \mathbf{0} \end{bmatrix}$$

The orthogonal projection of  $\mathbf{b}$  onto  $\text{range}(\mathbf{A})$  is now trivial.

If

$$\mathbf{b} = \begin{bmatrix} \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix}$$

where  $\mathbf{b}_1 \in \mathbb{R}^n$ , then

$$\mathbf{y} = \mathbf{P}\mathbf{b} = \begin{bmatrix} \mathbf{b}_1 \\ \mathbf{0} \end{bmatrix}.$$

The corresponding  $\mathbf{x}$  can be found from  $\mathbf{A}\mathbf{x} = \mathbf{y}$ .

i.e.,

$$\begin{bmatrix} \mathbf{A}_1 \\ \mathbf{0} \end{bmatrix} \mathbf{x} = \begin{bmatrix} \mathbf{b}_1 \\ \mathbf{0} \end{bmatrix}$$

or

$$\mathbf{x} = \mathbf{A}_1^{-1} \mathbf{b}_1.$$

From the results, it is easy to see

$$\mathbf{P} = \begin{bmatrix} \mathbf{I} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}, \quad \mathbf{A}^\dagger = \begin{bmatrix} \mathbf{A}_1^{-1} & \mathbf{0} \end{bmatrix}$$

◇ SENSITIVITY OF  $\mathbf{y}$  TO PERTURBATIONS IN  $\mathbf{b}$

$$\mathbf{y} = \mathbf{P}\mathbf{b}$$

∴ Jacobian of mapping  $\mathbf{b} \rightarrow \mathbf{y}$  is  $\mathbf{J} = \mathbf{P}$   
and  $\|\mathbf{P}\| = 1$ . (why?)

Thus, the condition number of  $\mathbf{y}$  with respect to perturbations in  $\mathbf{b}$  is

$$\kappa_{\mathbf{b} \rightarrow \mathbf{y}} = \frac{\|\mathbf{P}\|}{\|\mathbf{y}\|/\|\mathbf{b}\|} = \frac{1}{\cos(\theta)}$$



◇ SENSITIVITY OF  $\mathbf{x}$  TO PERTURBATIONS IN  $\mathbf{b}$

$$\mathbf{x} = \mathbf{A}^\dagger \mathbf{b}$$

$\therefore$  Jacobian of mapping  $\mathbf{b} \rightarrow \mathbf{x}$  is  $\mathbf{J} = \mathbf{A}^\dagger$ .

Thus, the condition number of  $\mathbf{x}$  with respect to perturbations in  $\mathbf{b}$  is

$$\begin{aligned}\kappa_{\mathbf{b} \rightarrow \mathbf{x}} &= \frac{\|\mathbf{A}^\dagger\|}{\|\mathbf{x}\|/\|\mathbf{b}\|} \\ &= \frac{\|\mathbf{A}^\dagger\| \|\mathbf{b}\| \|\mathbf{y}\|}{\|\mathbf{y}\| \|\mathbf{x}\|} \\ &= \|\mathbf{A}^\dagger\| \frac{1}{\cos(\theta)} \frac{\|\mathbf{A}\|}{\eta} \\ &= \frac{\kappa(\mathbf{A})}{\eta \cos(\theta)}\end{aligned}$$