

Change in grading scheme

- 1) Assignments (derivations): 10 marks**
- 2) Two lab exams: 30 marks (9th March, 6th April)**
- 3) Project (implementation of a journal paper):
30 marks**
 - Paper selection: 15th March**
 - Project presentation: 21st April**
- 4) Final written exam: 30 marks (28th April)**

E9 285 Biomedical imaging-Inverse problems

Chapter 2.b (2)

Representative reconstruction methods for fluorescence microscopy

Discrete Wavelets (Multiscale Derivative Transforms)

A simple transform:

Input:

$$\{x(0), x(1), x(2), x(3), x(4), x(5), x(6), x(7)\}$$

Output 1:

$$\left\{ \underbrace{x(0) + x(1), x(2) + x(3), x(4) + x(5), x(6) + x(7)}_{x_A^{(1)}}, \underbrace{x(1) - x(0), x(3) - x(2), x(5) - x(4), x(7) - x(6)}_{x_D^{(1)}} \right\}$$

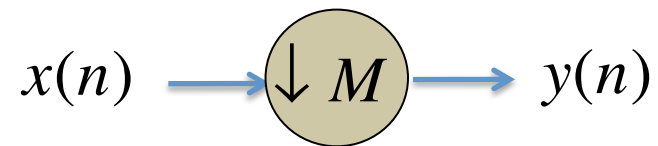
Output 2:

$$\left\{ \underbrace{x_A^{(1)}(0) + x_A^{(1)}(1), x_A^{(1)}(2) + x_A^{(1)}(3)}_{x_A^{(2)}}, \underbrace{x_A^{(1)}(1) - x_A^{(1)}(0), x_A^{(1)}(3) - x_A^{(1)}(2)}_{x_D^{(2)}}, \{x_D^{(1)}\} \right\}$$

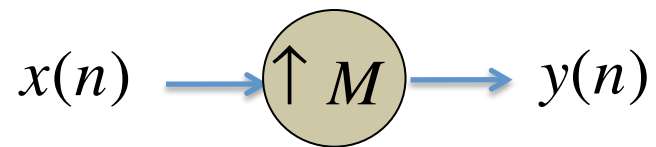
Output 3:

$$\left\{ \underbrace{x_A^{(2)}(0), +x_A^{(2)}(1)}_{x_A^{(3)}}, \underbrace{x_A^{(2)}(1) - x_A^{(2)}(0)}_{x_D^{(3)}}, \{x_D^{(2)}\}, \{x_D^{(1)}\} \right\}$$

Upsampler and downsampler

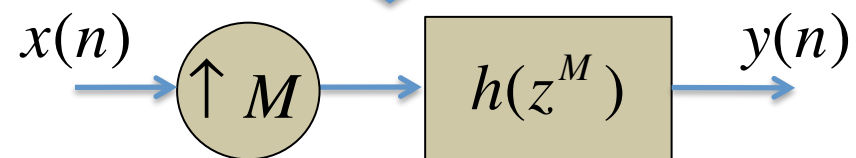
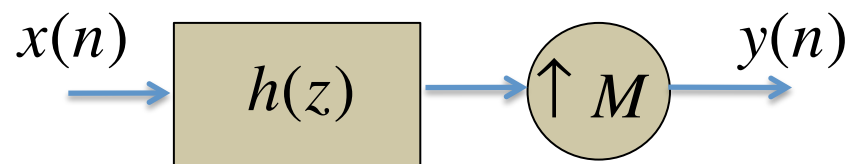
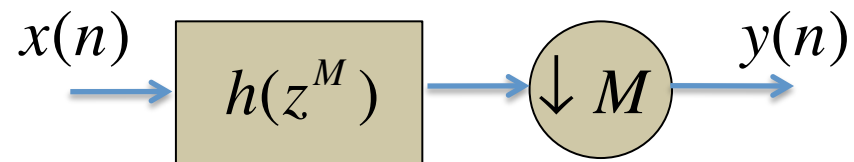
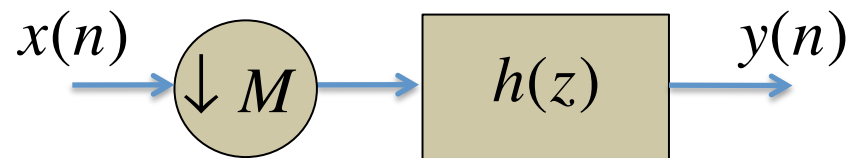


$$y(n) = x(nM)$$

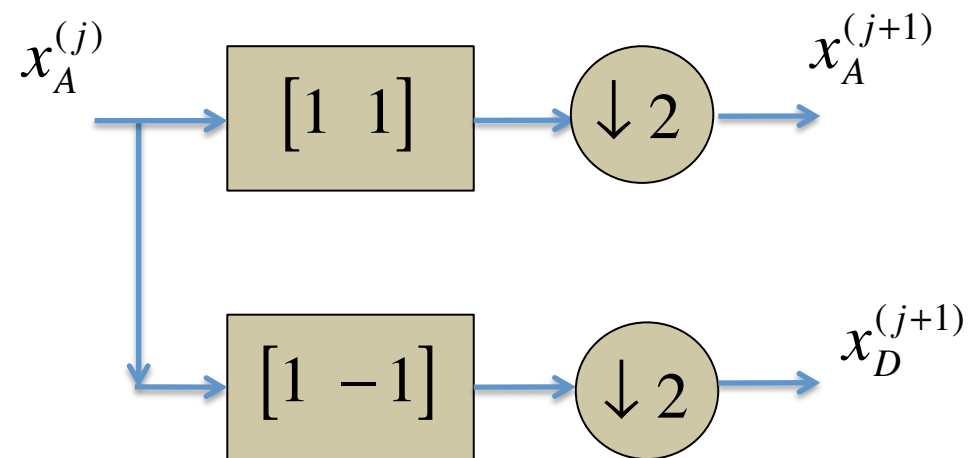


$$y(n) = \begin{cases} x(n / M), & \text{for } n / M \text{ being} \\ & \text{an integer} \\ 0, & \text{Otherwise} \end{cases}$$
$$\Rightarrow y(z) = x(z^M)$$

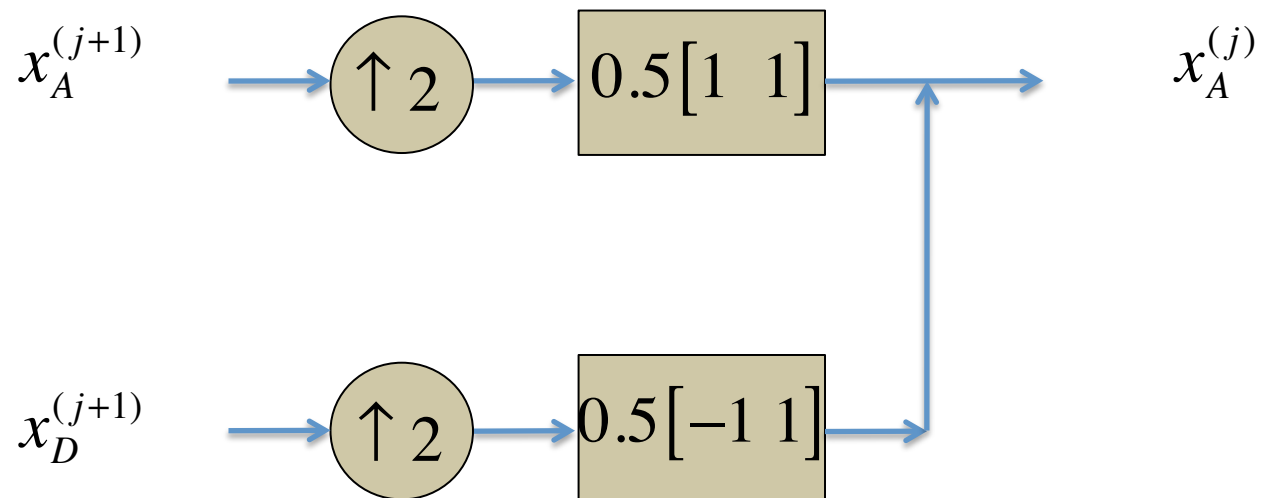
Noble (??) identities



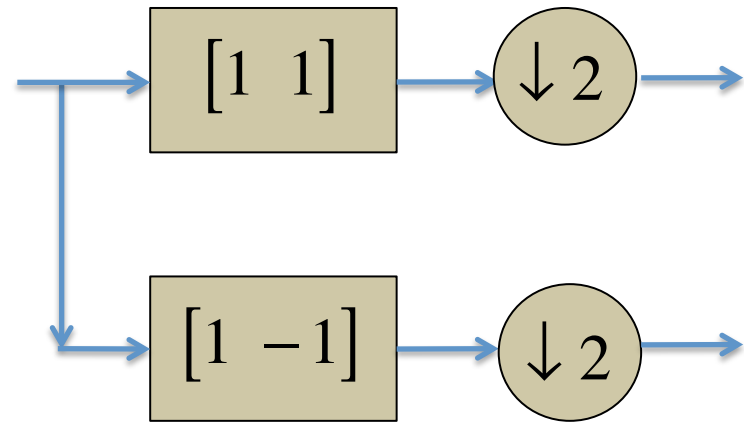
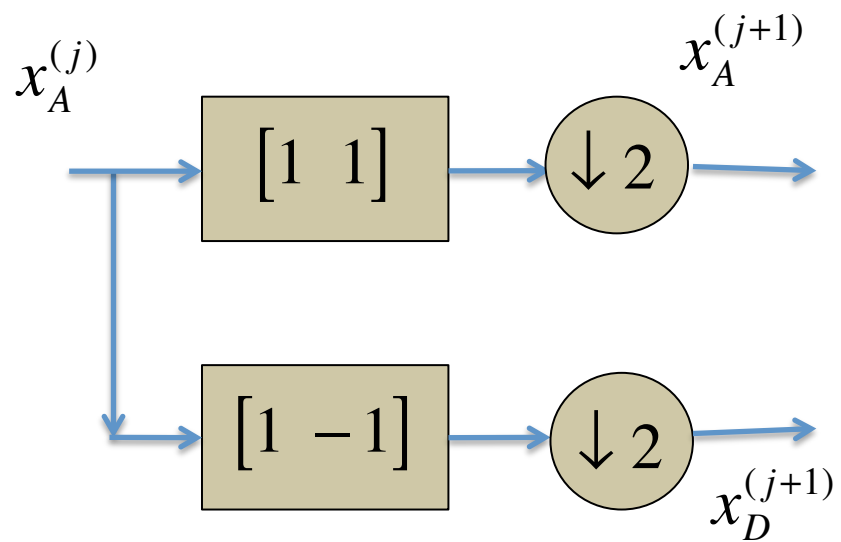
Analysis filter bank



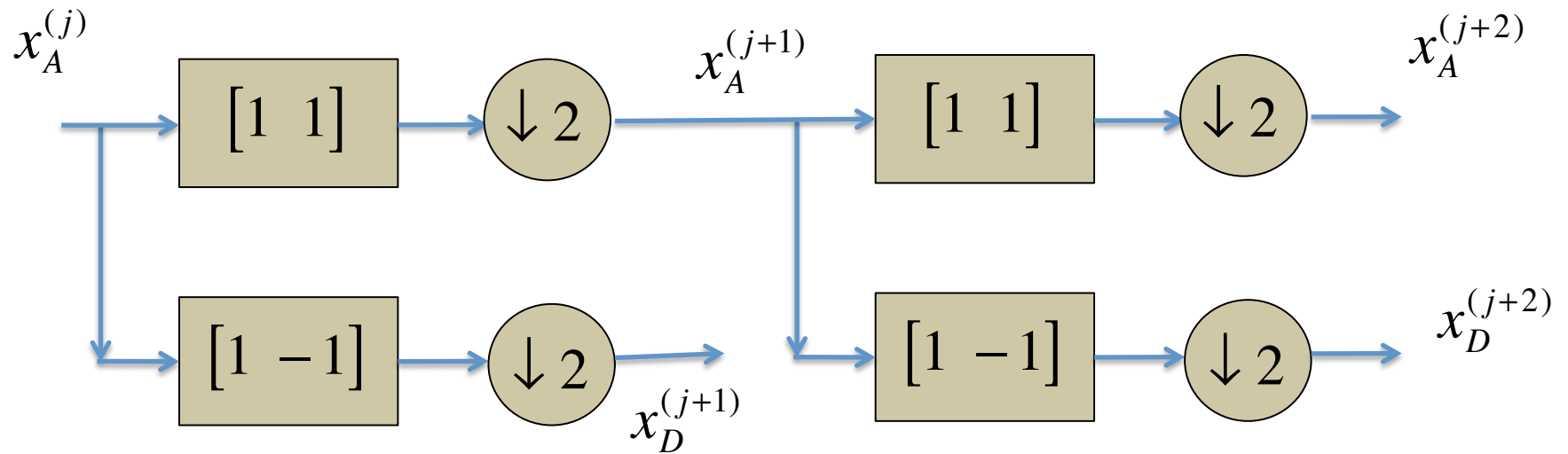
Synthesis filter bank



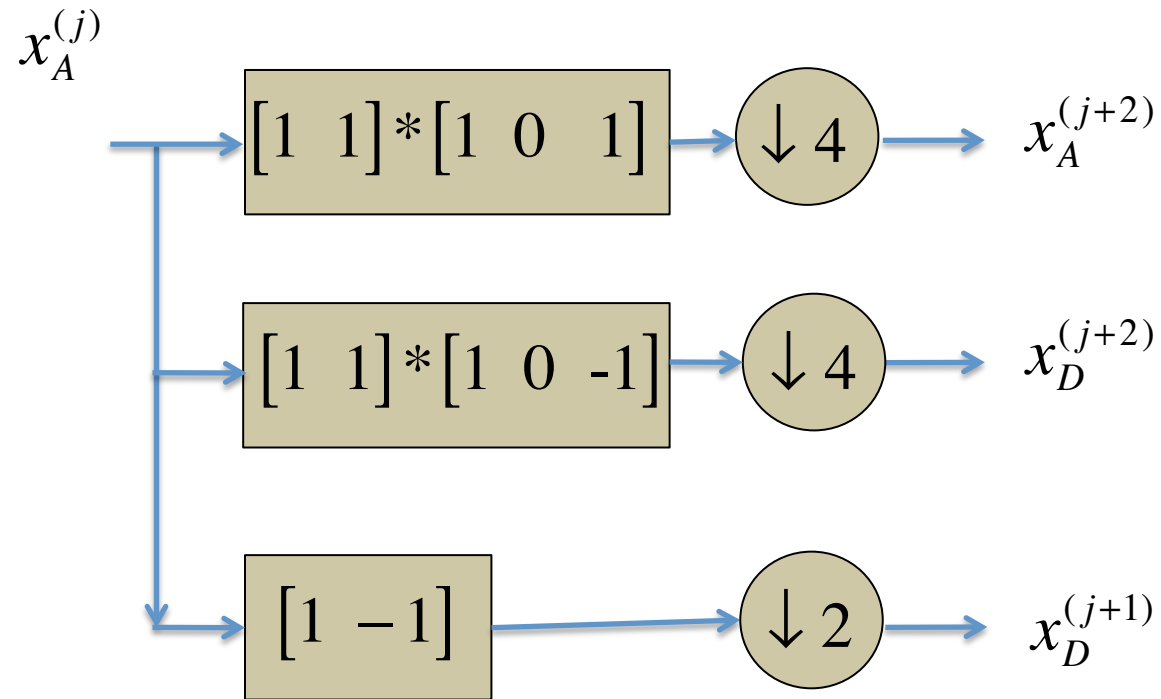
Why do we call it a multiscale derivative transform ?



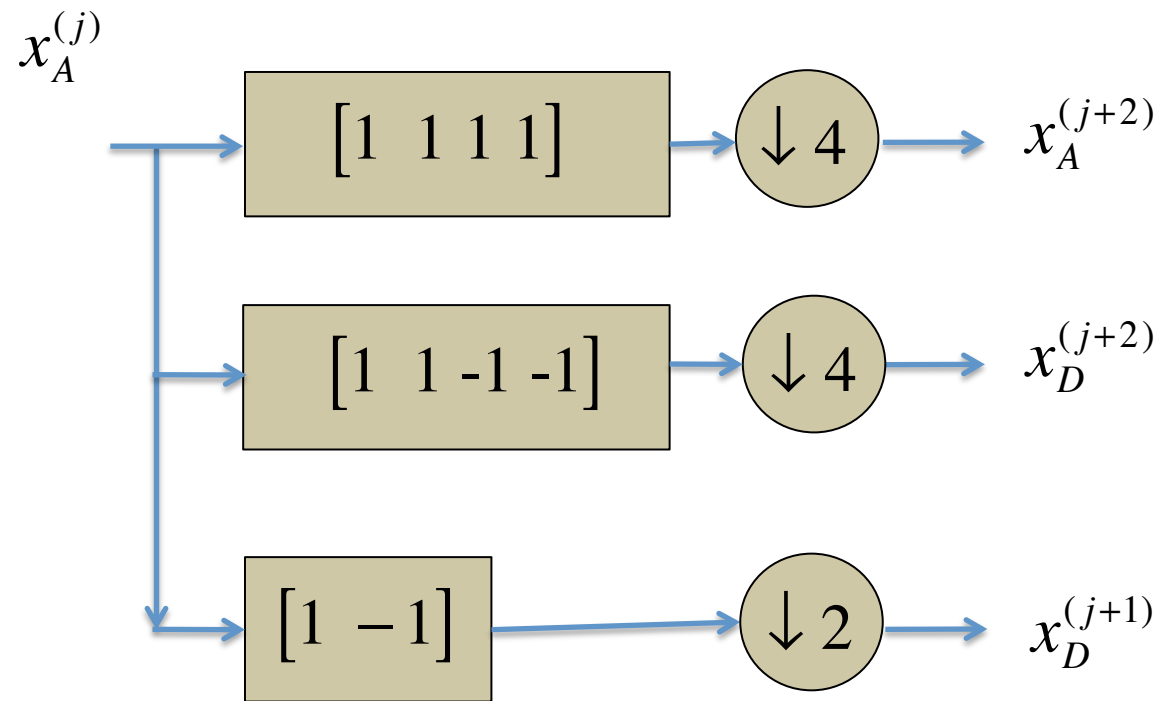
Why do we call it a multiscale derivative transform ?



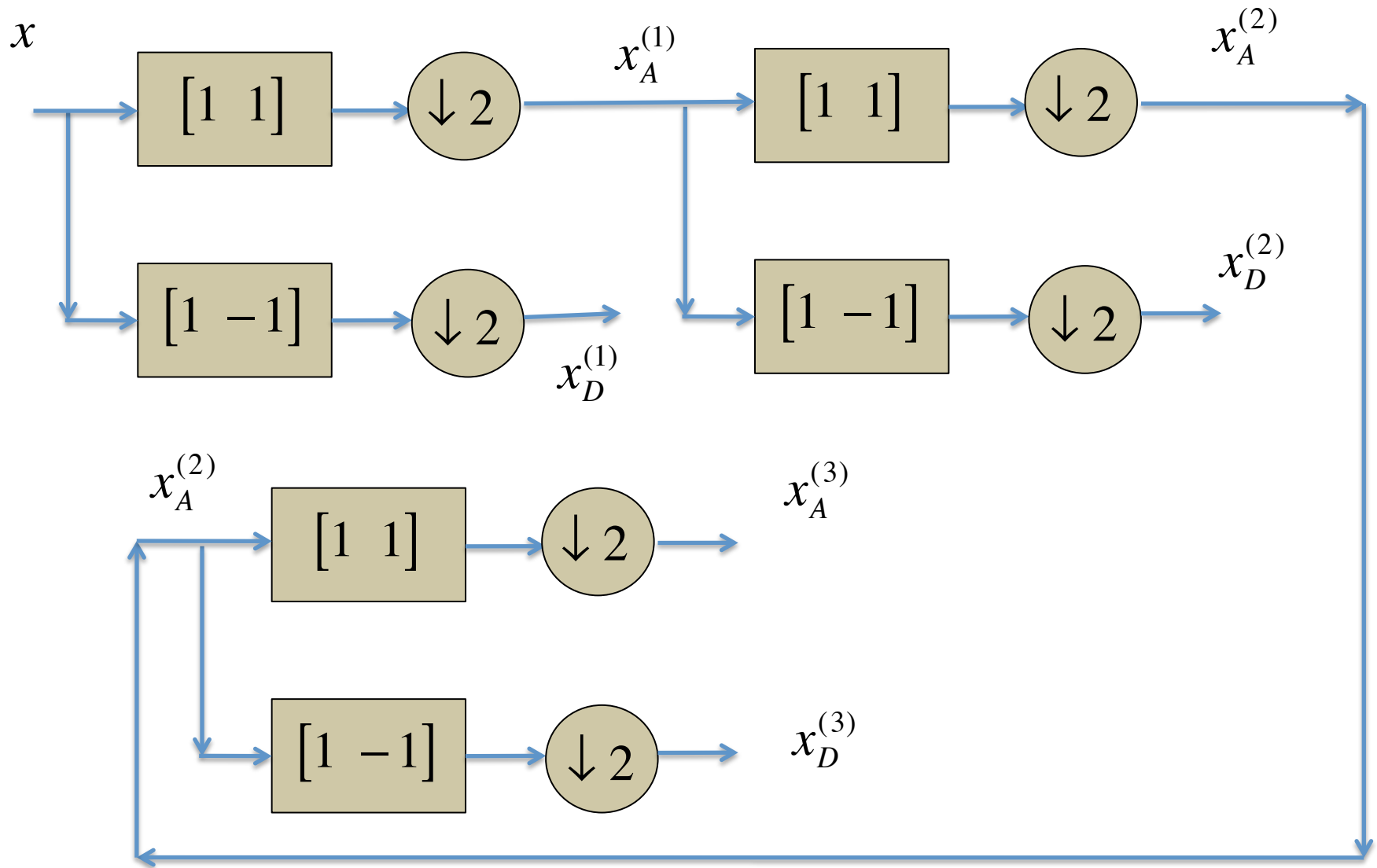
Why do we call it a multiscale derivative transform ?



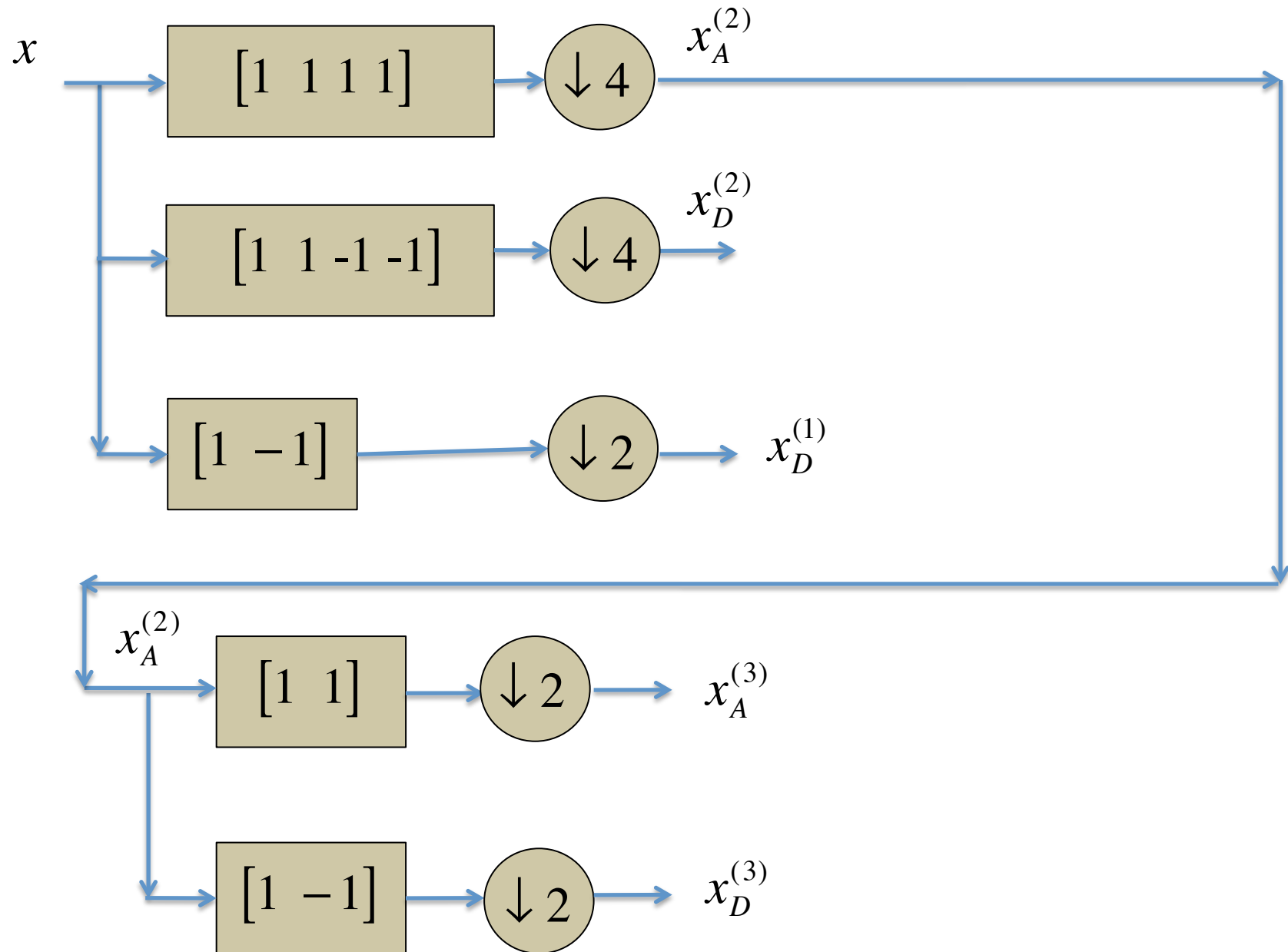
Why do we call it a multiscale derivative transform ?



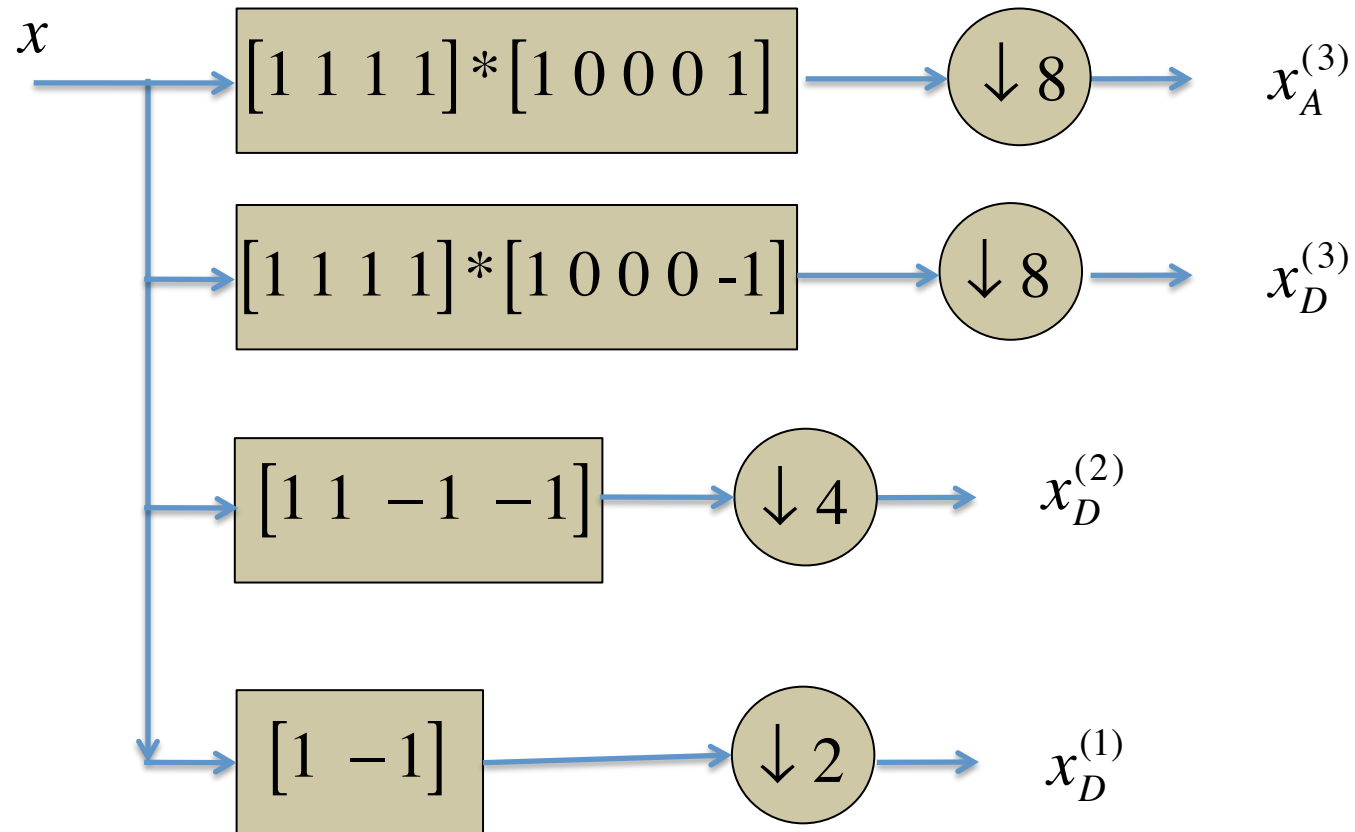
Why do we call it a multiscale derivative transform ?



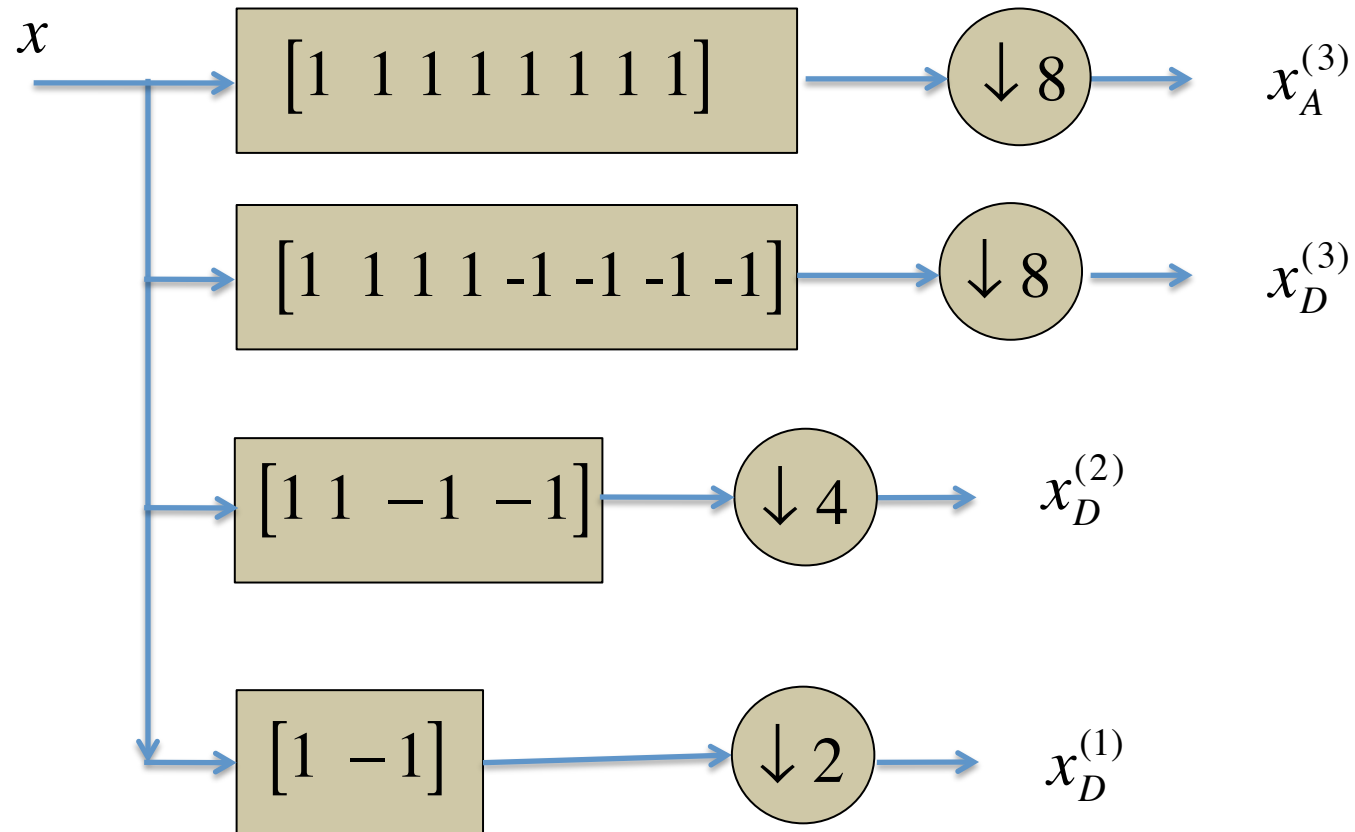
Why do we call it a multiscale derivative transform ?



Why do we call it a multiscale derivative transform ?



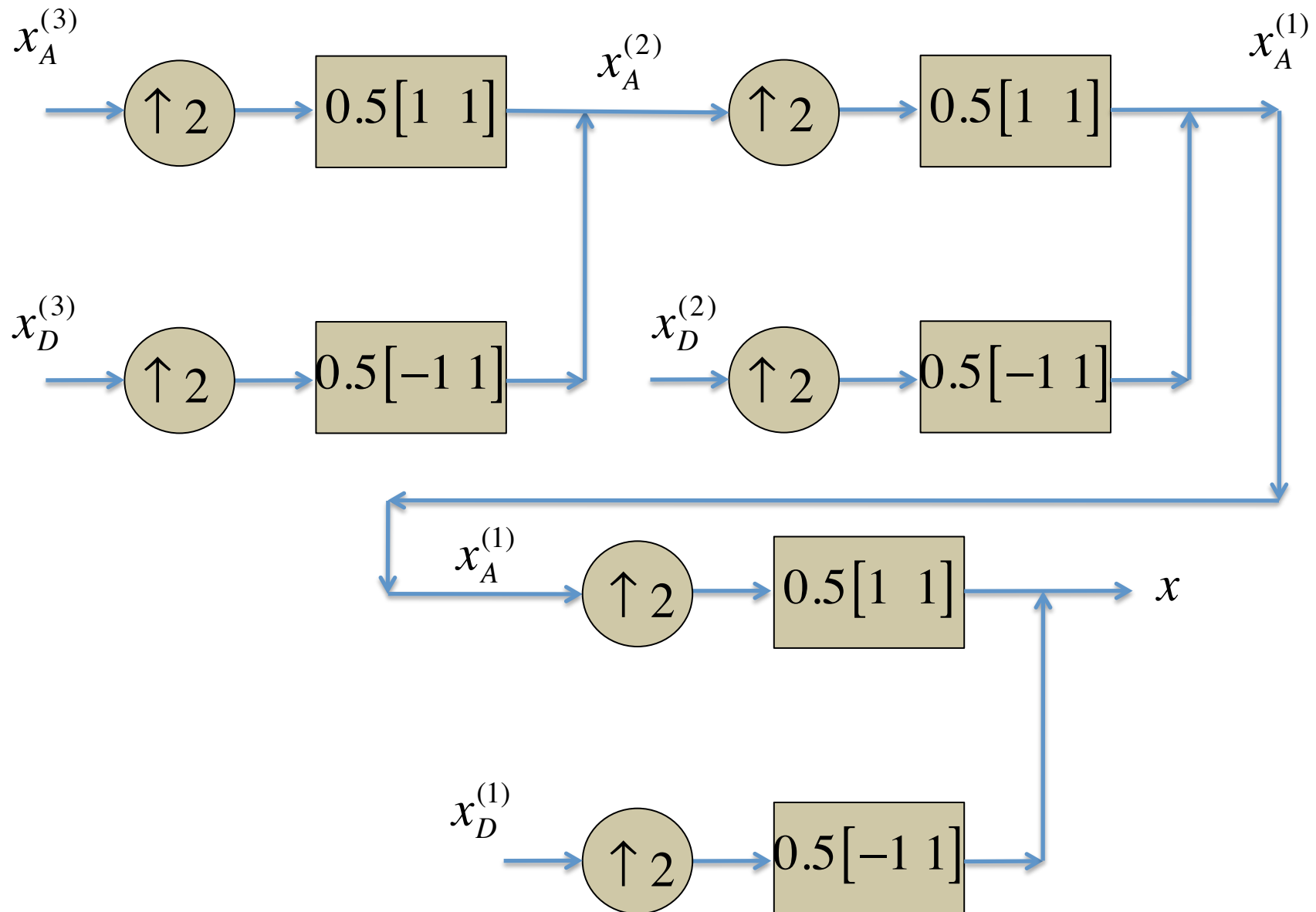
Why do we call it a multiscale derivative transform ?

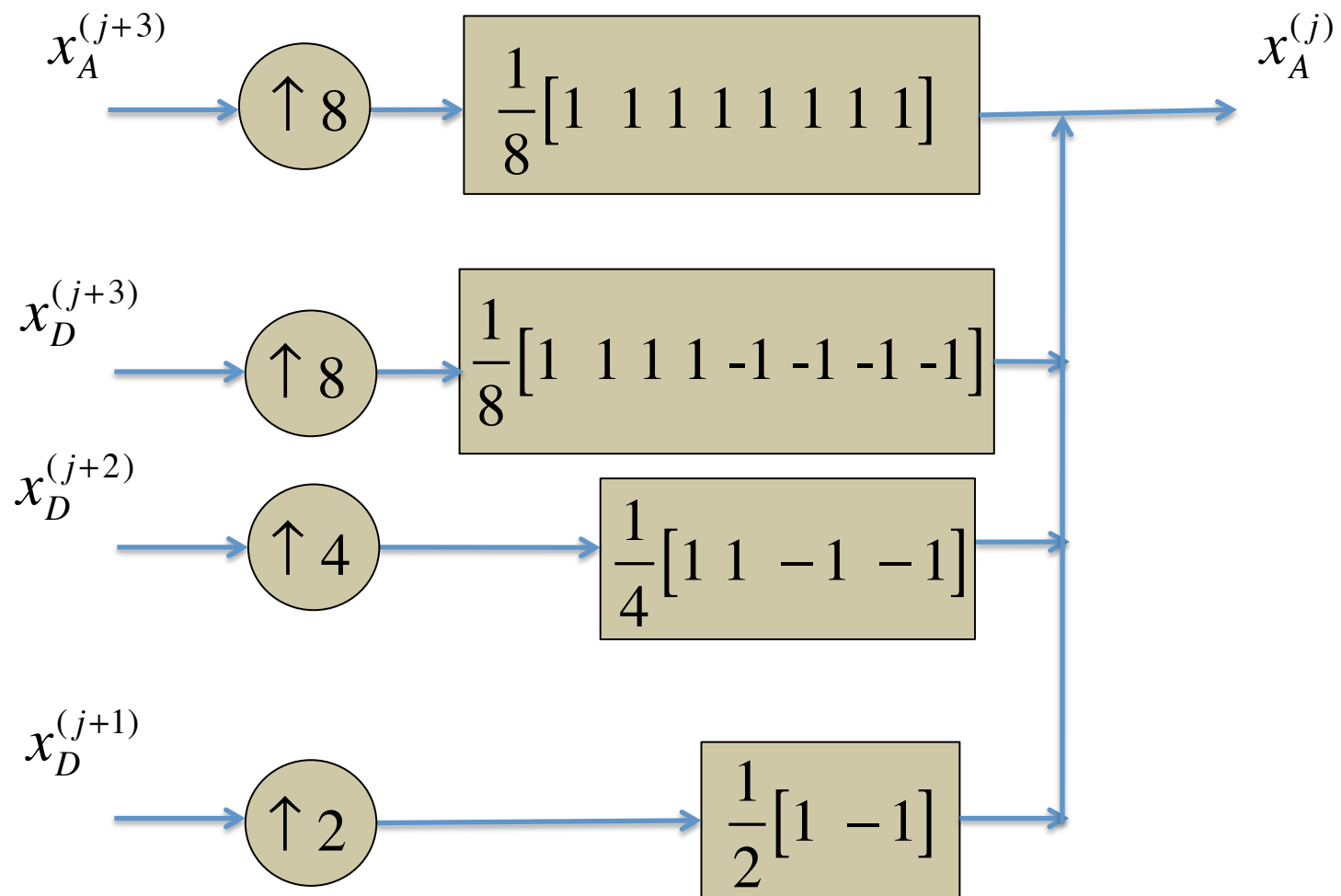


How does the analysis matrix look like ?

$$\begin{bmatrix} \mathbf{x}_A^{(3)} \\ \mathbf{x}_D^{(3)} \\ \mathbf{x}_D^{(2)} \\ \mathbf{x}_D^{(1)} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 0 & 1 & 1 & -1 & -1 \\ 1 & 1 & -1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \mathbf{x}$$

The reconstruction (synthesis)

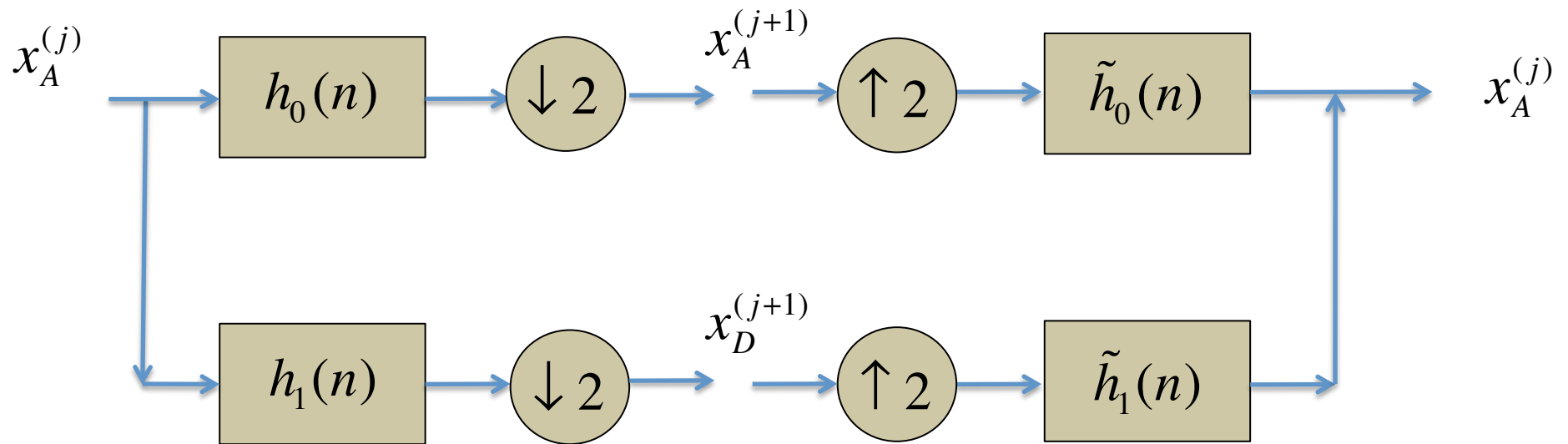




How does the analysis matrix look like ?

$$\mathbf{X} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 0 & 1 & 1 & -1 & -1 \\ 1 & 1 & -1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}^{-1} \begin{bmatrix} \mathbf{x}_A^{(3)} \\ \mathbf{x}_D^{(3)} \\ \mathbf{x}_D^{(2)} \\ \mathbf{x}_D^{(1)} \end{bmatrix}$$

Using other type of filters



What is the condition such that matrix equivalent of the iterated filter bank is orthogonal ?

$$\langle h_i(n - 2l), h_j(n - 2m) \rangle = \delta(i - j) \delta(l - m)$$

Using other type of filters

What is the condition such that matrix equivalent of the iterated filter bank is orthogonal ?

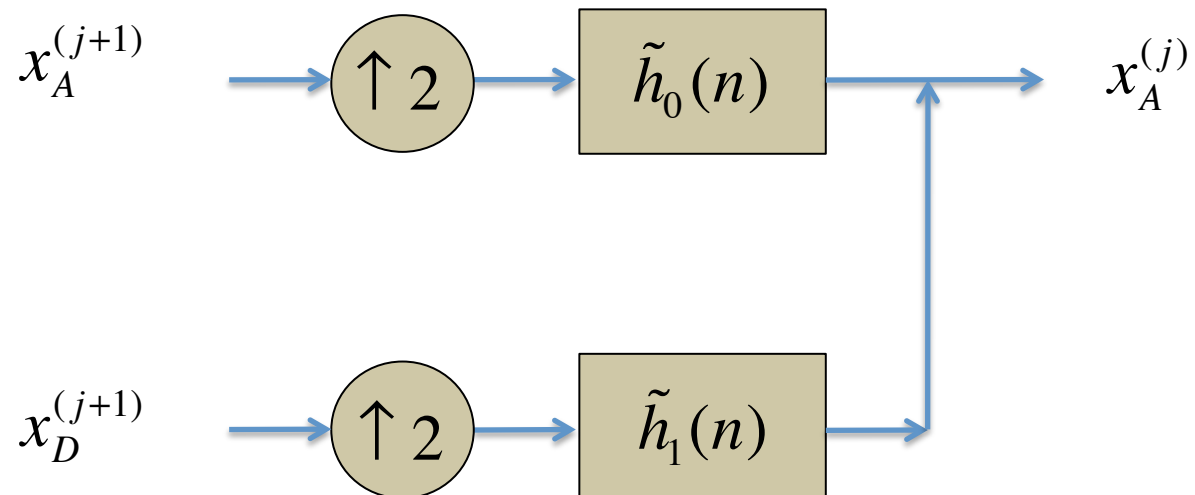
$$\langle h_i(n-2l), h_j(n-2m) \rangle = \delta(i-j)\delta(l-m)$$

\Downarrow

$$\langle h_0(n-2l), h_0(n-2l) \rangle = \delta(l-m) \Rightarrow H_0(z)H_0(z^{-1}) + H_0(-z)H_0(-z^{-1}) = 1$$

$$h_1(n) = (-1)^n h_0(n)$$

Using more other type of filters



$$\tilde{h}_0(n) = h_0(-n)$$

$$\tilde{h}_1(n) = h_1(-n)$$

Order of approximation

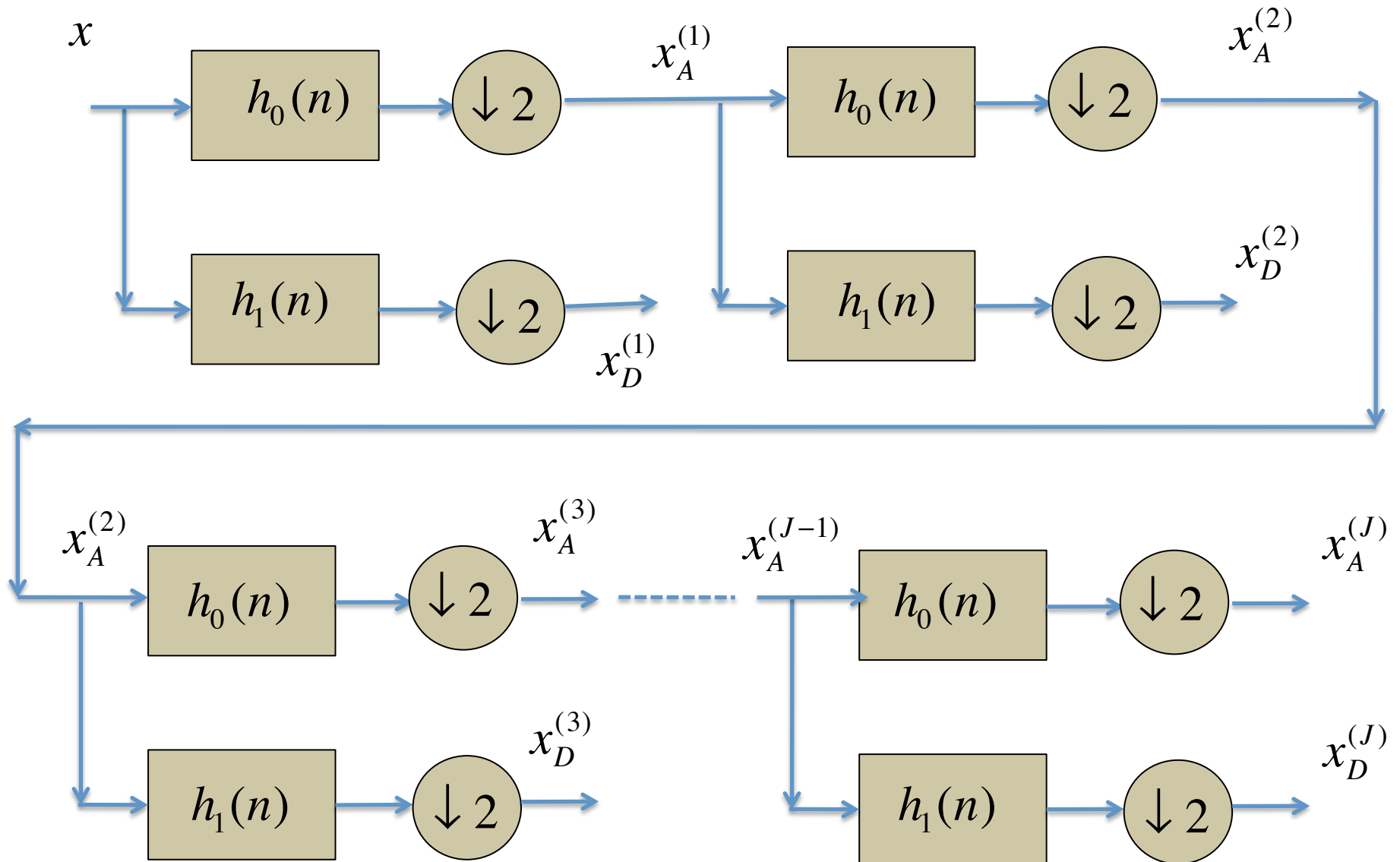
If $H_1(z)$ can be factorized as

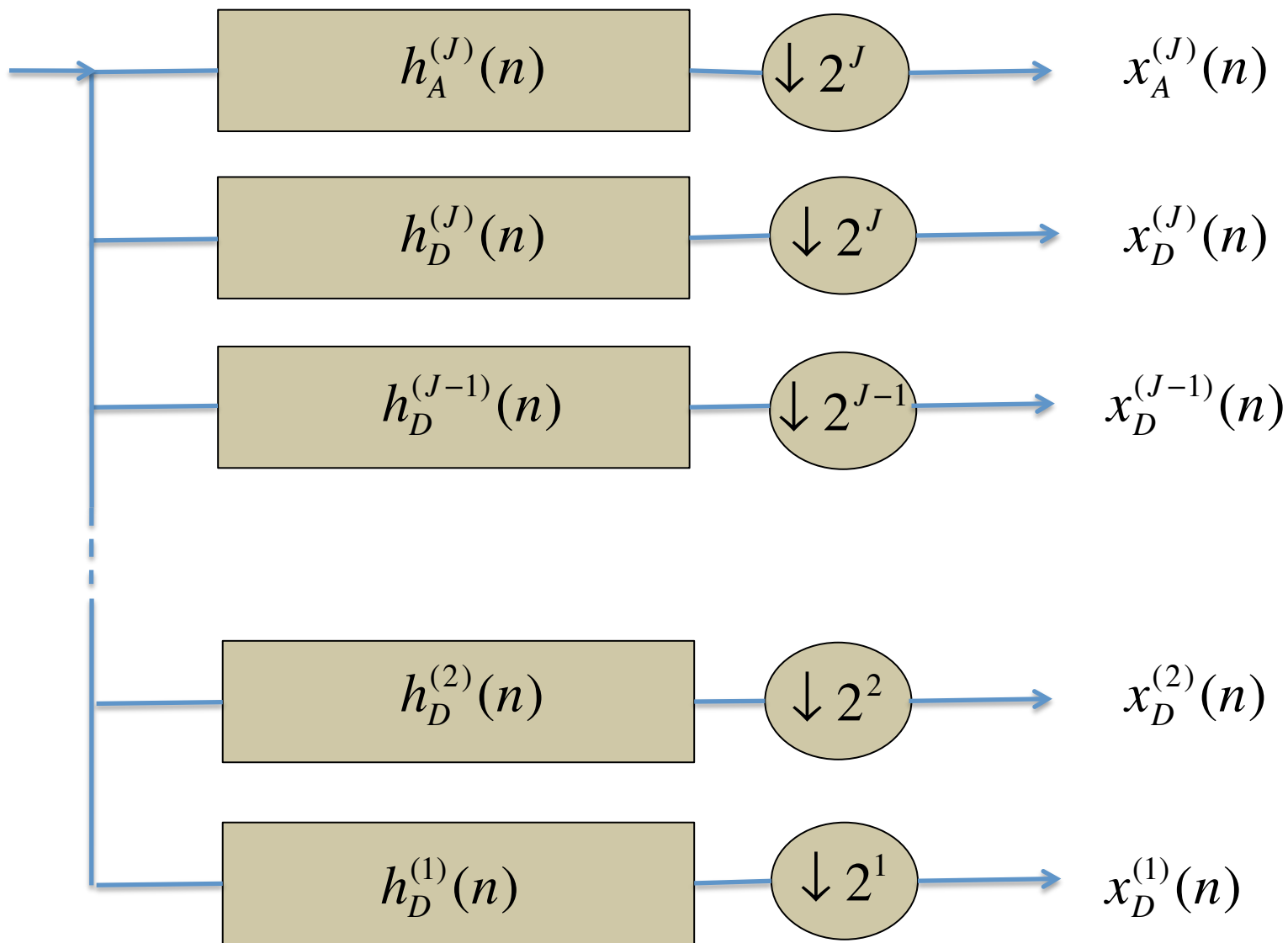
$H_1(z) = (1 - z^{-1})^N R(z)$, then the wavelet has an order of approximation N . Then wavelet decomposition will kill polynomials of degree $N - 1$.

Daubechies family of orthogonal finite length filter banks

D2 (Haar)	D4	D6	D8	D10
1	0.6830127	0.47046721	0.32580343	0.22641898
1	1.1830127	1.14111692	1.01094572	0.85394354
	0.3169873	0.650365	0.8922014	1.02432694
	-0.1830127	-0.19093442	-0.03957503	0.19576696
		-0.12083221	-0.26450717	-0.34265671
		0.0498175	0.0436163	-0.04560113
			0.0465036	0.10970265
			-0.01498699	-0.00882680
				-0.01779187
				4.71742793e-3

Why do we call it a multiscale derivative transform ?





$$x_A^{(J)}(n) = \sum_m h_A^{(J)}(m - 2^J n) x(m)$$

$$x_D^{(j)}(n) = \sum_m h_D^{(j)}(m - 2^j n) x(m)$$

$$j = 1, \dots, J$$

The discrete wavelets

$$h_D^{(1)}(z) = h_1(z)$$

$$h_D^{(2)}(z) = h_0(z)h_1(z^2)$$

$$h_D^{(3)}(z) = h_0(z)h_0(z^2)h_1(z^4)$$

$$h_D^{(j)}(z) = h_0(z)h_0(z^2)\cdots h_0(z^{2^{j-1}})h_1(z^{2^j})$$

$$h_D^{(J)}(z) = h_0(z)h_0(z^2)\cdots h_0(z^{2^{J-1}})h_1(z^{2^J})$$

$$h_A^{(J)}(z) = h_0(z)h_0(z^2)\cdots h_0(z^{2^J})$$

Orthogonality

$$\langle h_0(n-2l), h_0(n-2m) \rangle = \delta(l-m) \quad h_1(n) = (-1)^n h_0(n)$$

\Downarrow

$$\langle h_A^{(J)}(n-2^J l), h_A^{(J)}(n-2^J m) \rangle = \delta(l-m)$$

$$\langle h_D^{(j)}(n-2^j l), h_D^{(k)}(n-2^k m) \rangle = \delta(j-k)\delta(l-m)$$

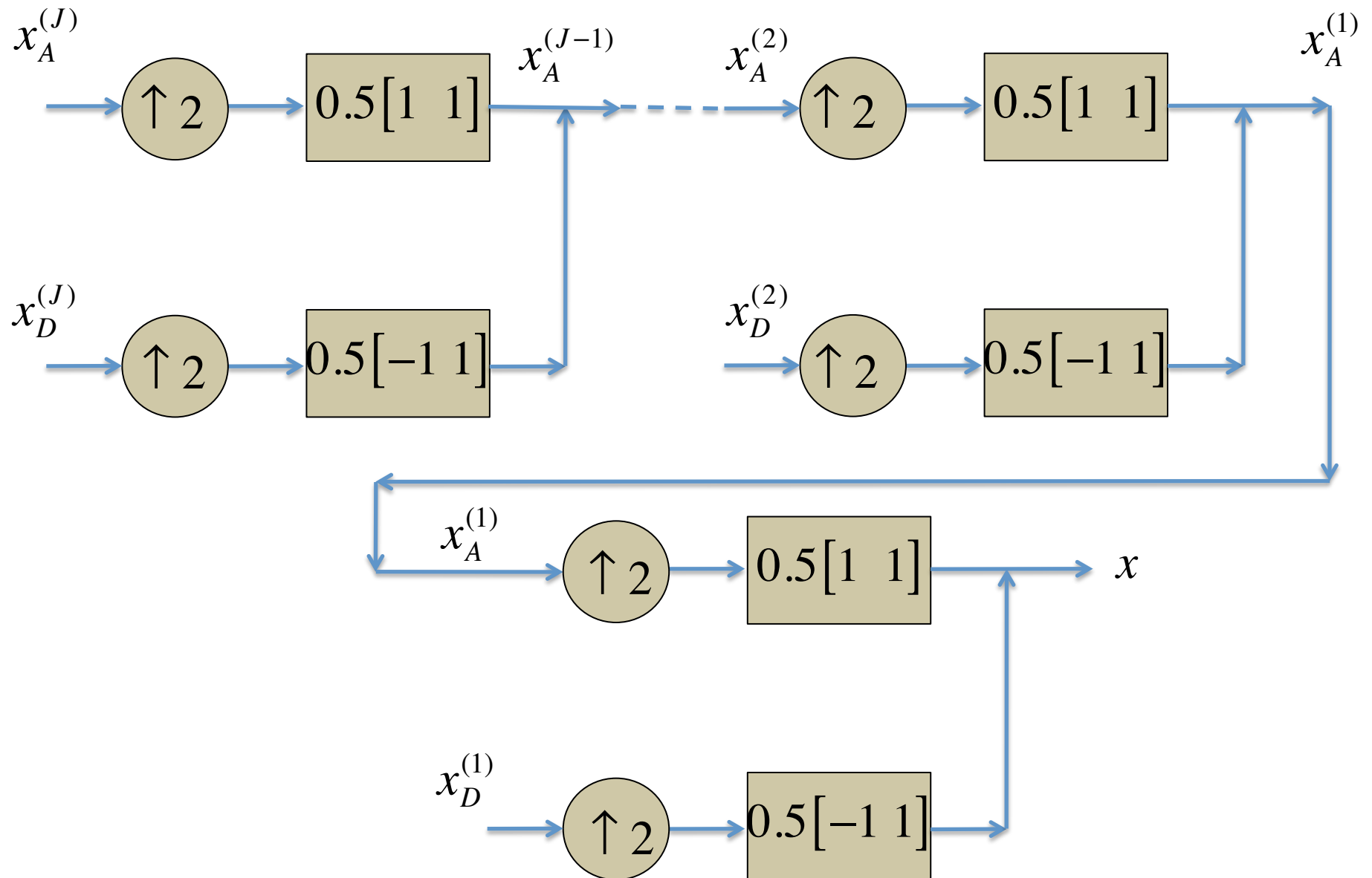
$$\langle h_D^{(j)}(n-2^j l), h_A^{(J)}(n-2^J m) \rangle = 0$$

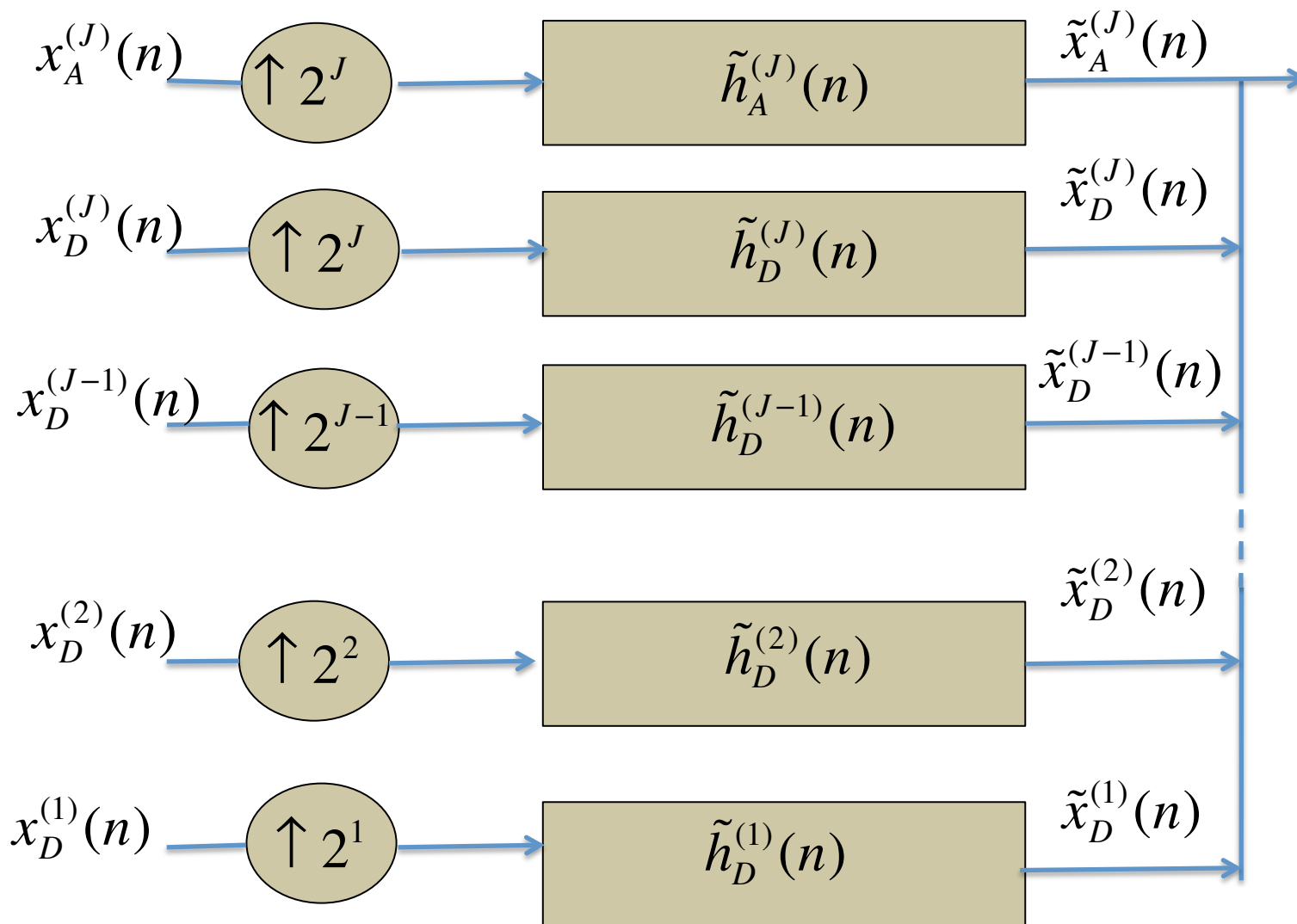
\Downarrow

The matrix defined in the equation

$$\begin{bmatrix} \mathbf{x}_A^{(J)} \\ \mathbf{x}_{AD}^{(J)} \\ \mathbf{x}_D^{(J-1)} \\ \vdots \\ \mathbf{x}_D^{(2)} \\ \mathbf{x}_D^{(1)} \end{bmatrix} = \mathbf{M}\mathbf{x} \text{ is orthogonal.}$$

The reconstruction (synthesis)





$$\tilde{x}_A^{(J)}(n) = \sum_m \tilde{h}_A^{(J)}(2^J m - n) x_A^{(J)}(m)$$

$$\tilde{x}_D^{(j)}(n) = \sum_m \tilde{h}_D^{(j)}(2^j m - n) x_D^{(j)}(m)$$

$$j = 1, \dots, J$$

The discrete synthesis wavelets

$$\tilde{h}_D^{(j)}(n) = h_D^{(j)}(-n), j = 1, \dots, J$$

$$\tilde{h}_A^{(J)}(z) = h_A^{(J)}(-n)$$