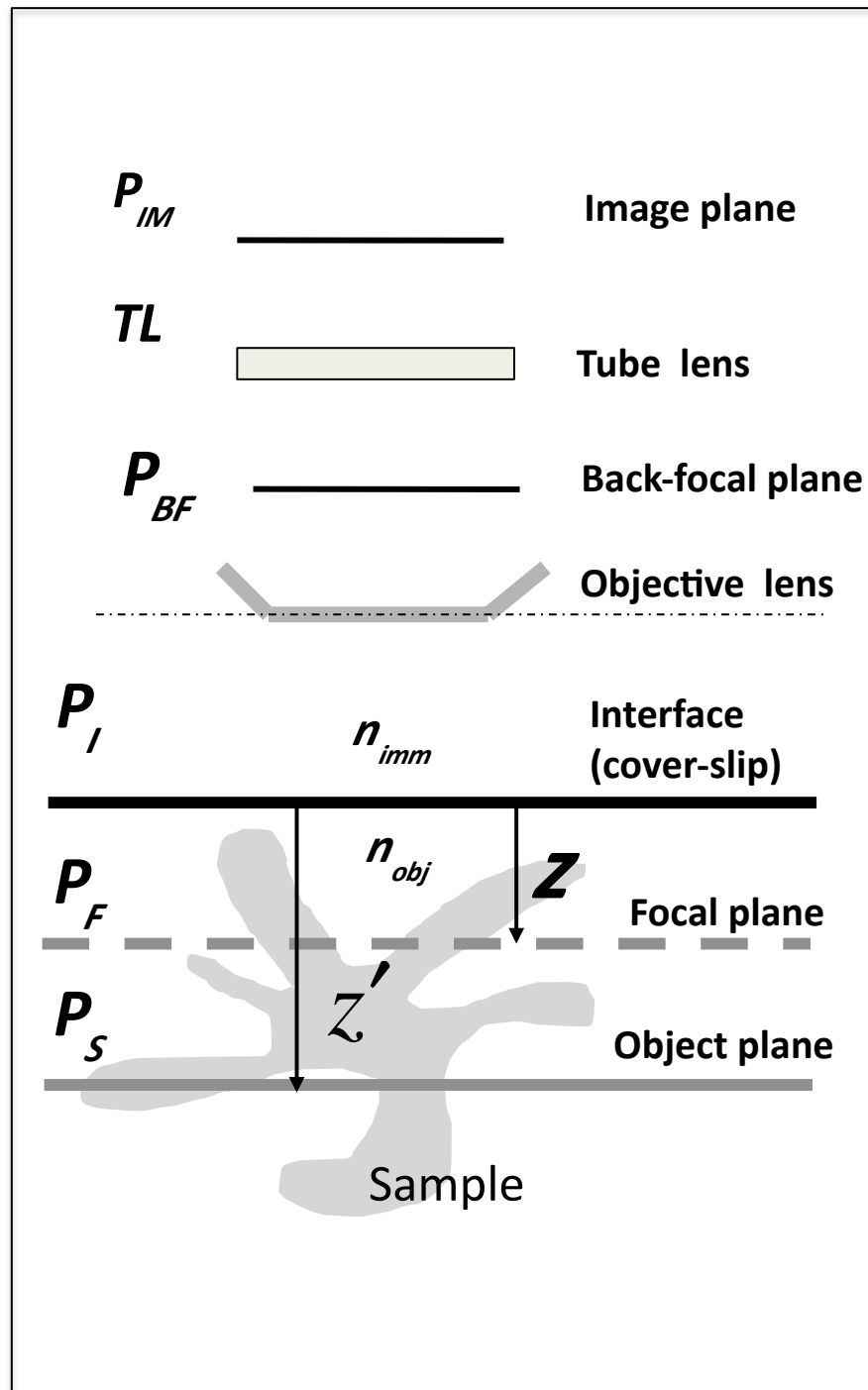
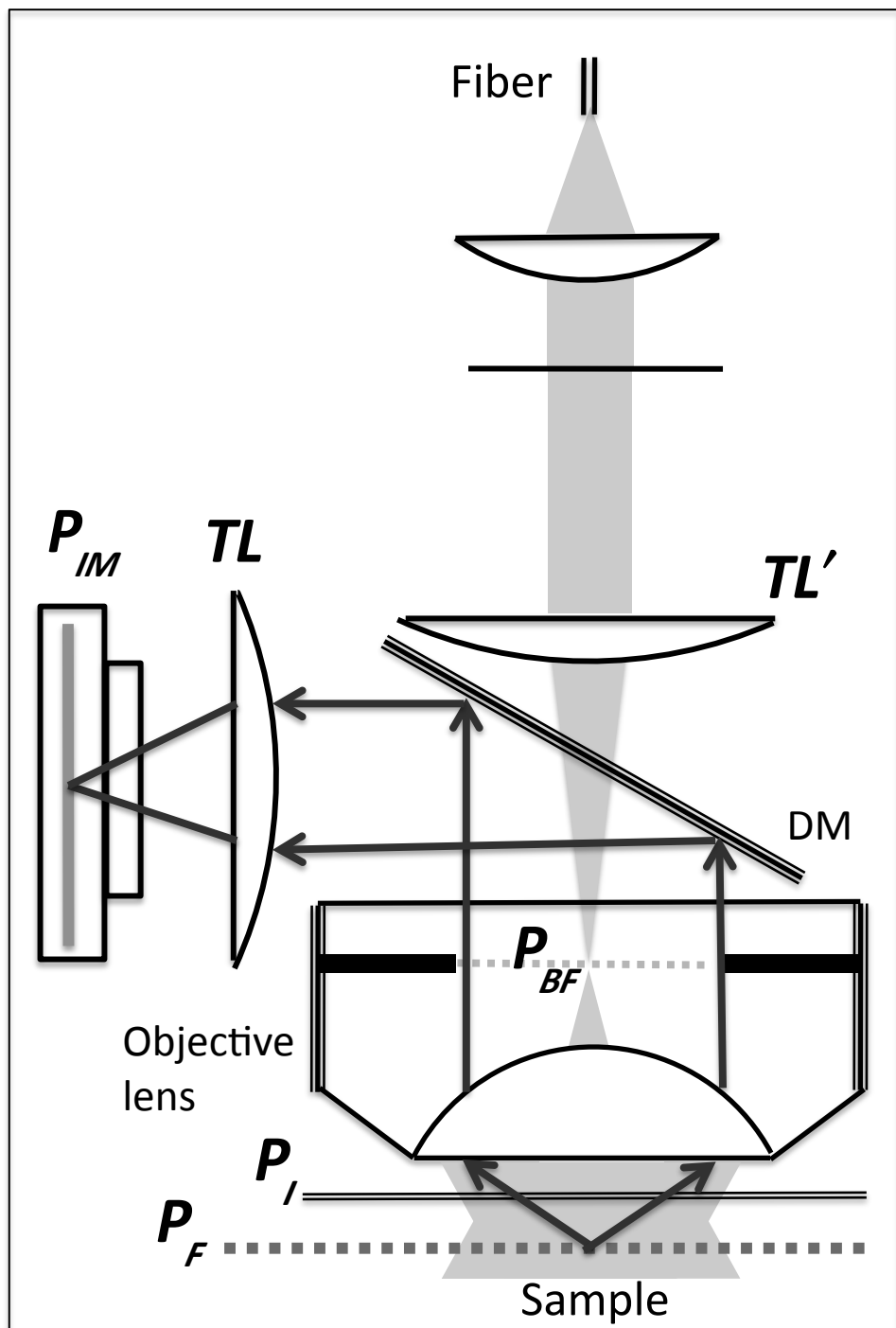
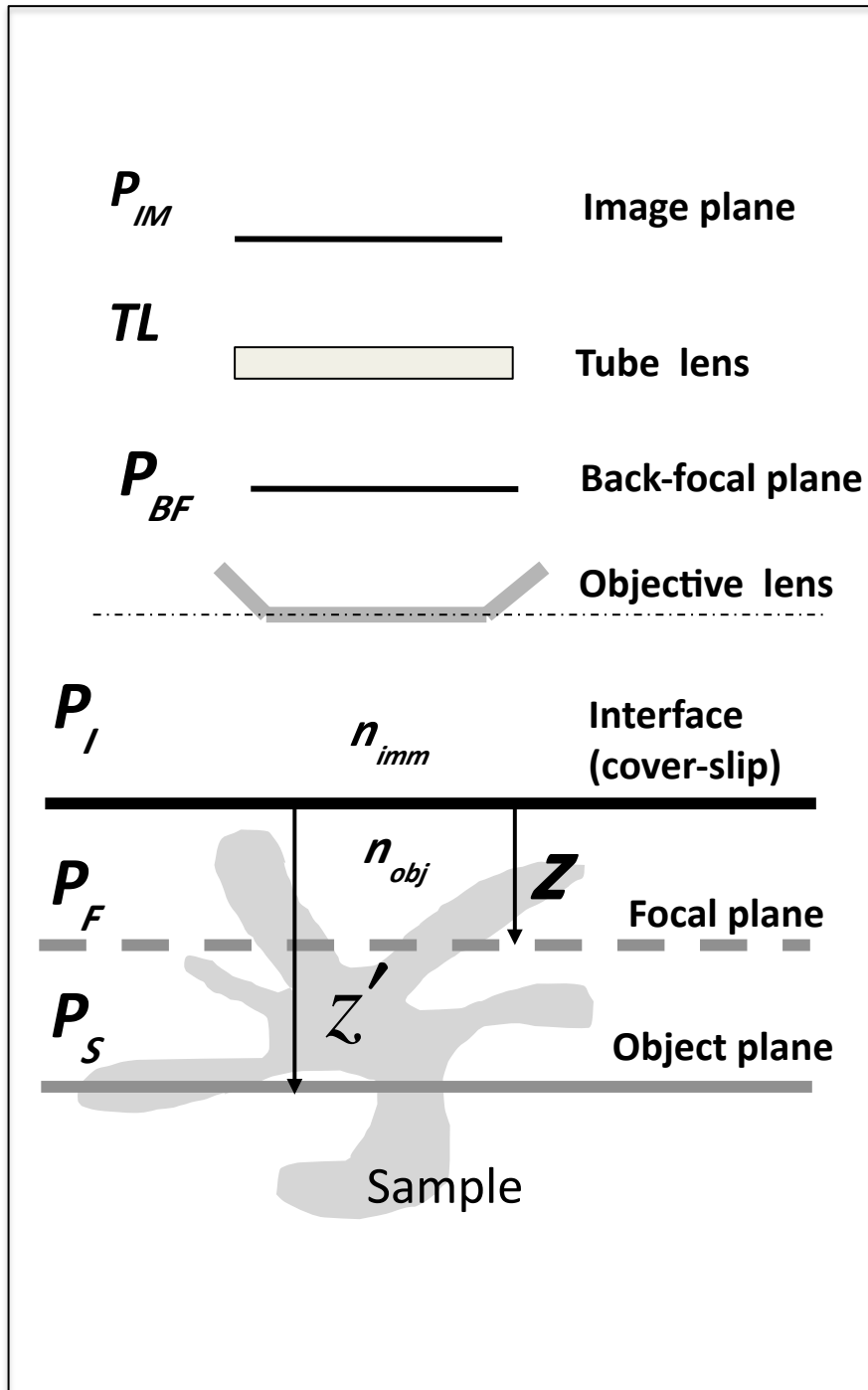


E9 285 Biomedical imaging-Inverse problems

Chapter 2.a **Introduction to basic fluorescence** **microscopes**

The widefield microscope





$S_a(x, y, z')$: complex signal
amplitude

$$S(x, y, z') = |S_a(x, y, z')|^2$$

(image to be measured)

z : user depth variable

z' : object depth variable

$W_{BF}(X, Y, z)$: image at P_{BF}

$S_a(X, Y, z')$: xy Fourier transform
of the signal.

$T(X, Y, z, z')$: Transfer function

$$W_{BF}(X, Y, z) = \int_{z'} \left[S_a(X, Y, z') \times T(X, Y, z, z') \right] dz'$$

$$W_{BF}(X,Y,z) = \int_{z'} [S_a(X,Y,z')T(X,Y,z,z')] dz'$$

The measured image:

$$\begin{aligned} R(x,y,z) &= \left| F_{xy}^{-1} [W_{BF}(X,Y,z)] \right|^2 \\ &= \int_{z'} g(x,y,z,z') \oplus_{xy} S(x,y,z') dz' \end{aligned}$$

$$g(x,y,z,z') = \left| F_{xy}^{-1} [T(X,Y,z,z')] \right|^2$$

Assumption: $g(x,y,z,z') = g(x,y,z-z',0)$

Then

$$\begin{aligned} R(x,y,z) &= \int_{z'} g(x,y,z-z',0) \oplus_{xy} S(x,y,z') dz' \\ &= g_0(x,y,z) * S(x,y,z), \end{aligned}$$

where $g_0(x,y,z) = g(x,y,z-z',0)$

$$g_0(x,y,z) = F_{xy}^{-1} [T_0(X,Y,z)]$$

$$T(X,Y,z) = A(X,Y) \exp(j2\pi Q(X,Y))$$

$$\times \exp \left[j \frac{2\pi n z}{\lambda} \sqrt{1 - (\lambda X / n)^2 - (\lambda Y / n)^2} \right]$$

$A(X,Y)$: aperture (normally circular)

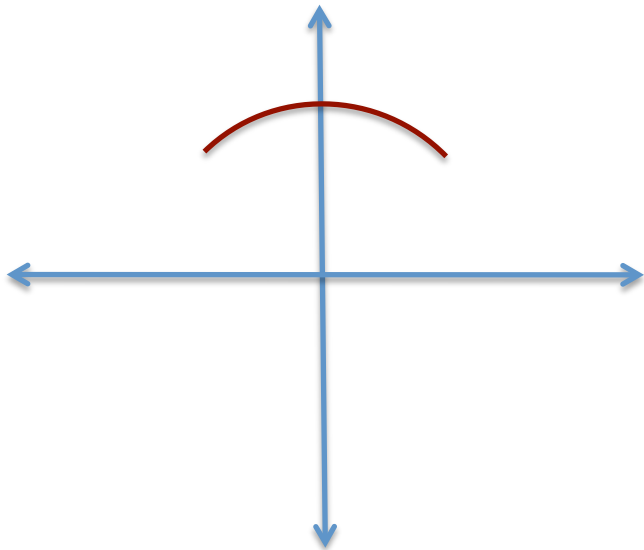
$Q(X,Y)$: smooth phase function

λ : wavelength

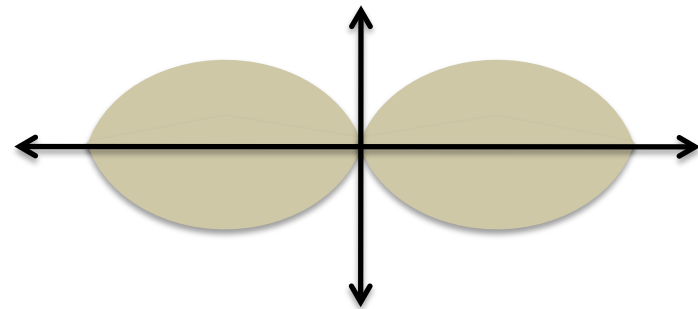
n : refractive index of the medium below the object lens

$$T(X,Y,z) = A(X,Y) \exp(j2\pi Q(X,Y)) \\ \times \exp\left[j \frac{2\pi n z}{\lambda} \sqrt{1 - (\lambda X / n)^2 - (\lambda Y / n)^2} \right]$$

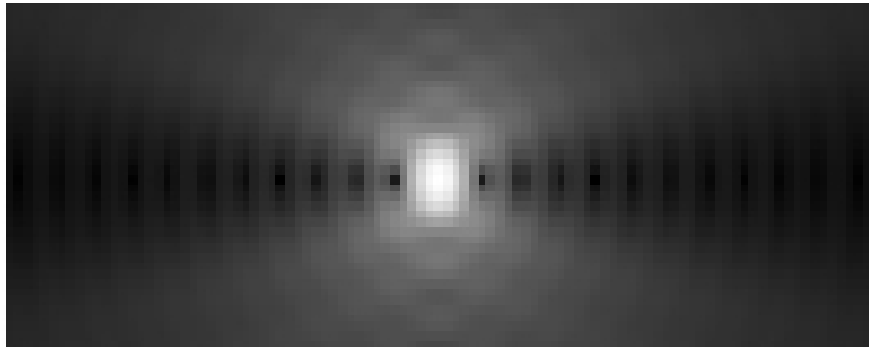
$$T(X,Y,Z) = ?$$



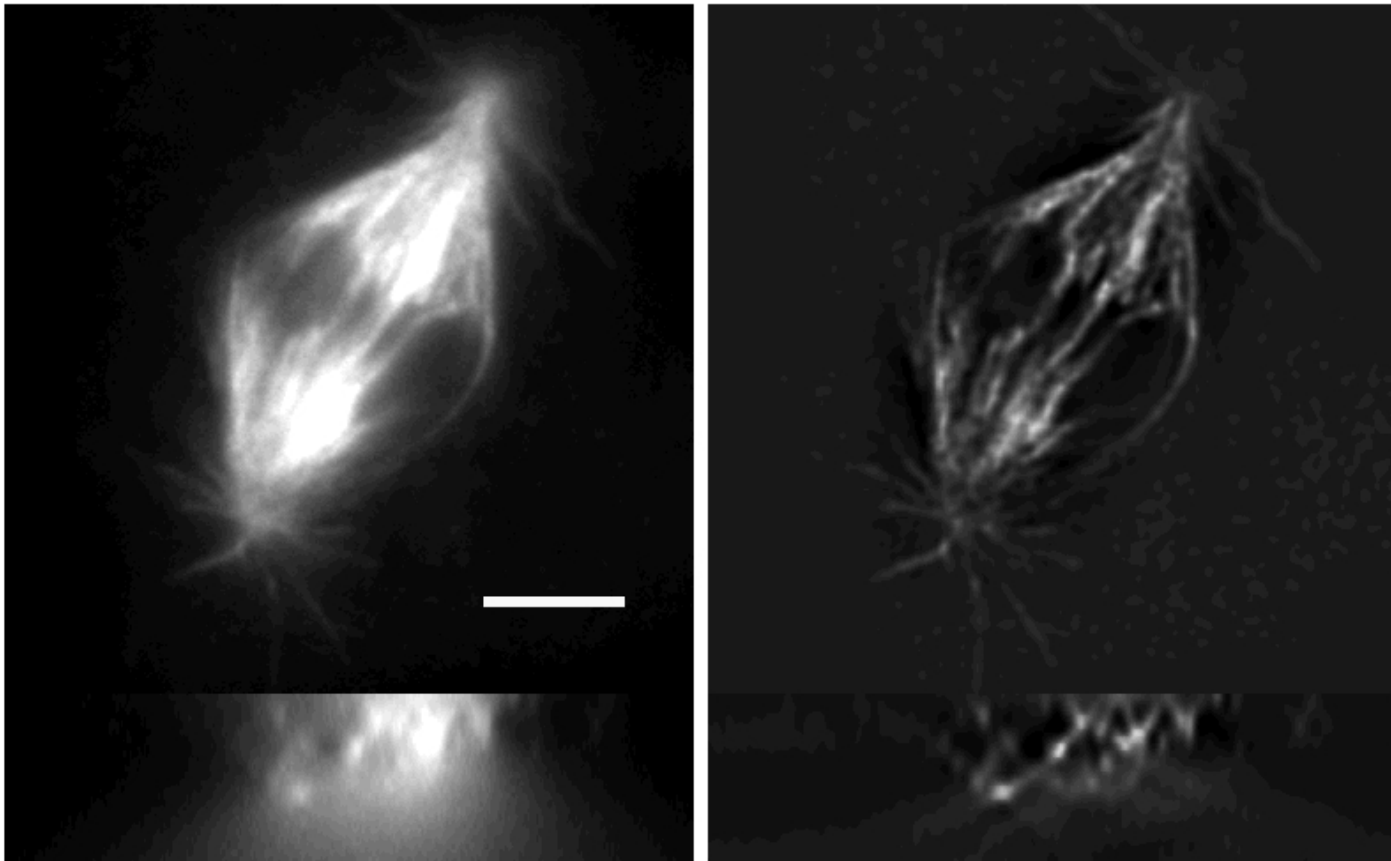
$$g_0(X,Y,Z) = ?$$



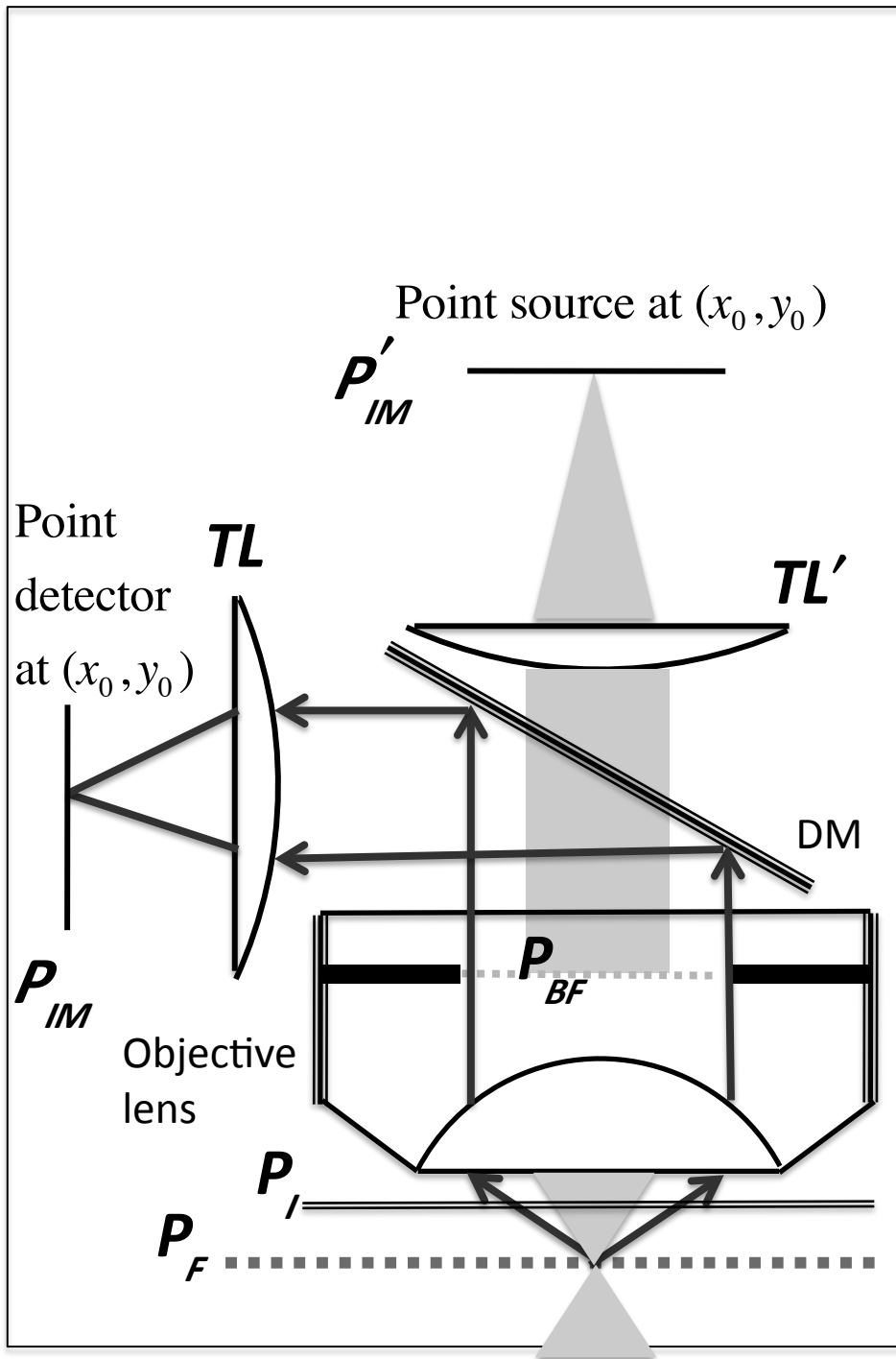
$$g_0(x,y,z)$$



An image example:



The confocal microscope



PSF from P'_{IM} to sample space: $g'(x, y, z)$

PSF from P_{IM} to sample space: $g(x, y, z)$

Let the slide position be z_0

Fluorescence intensity at sample space:

$$F_I(x, y, z) = S(x, y, z)g'(x - x_0, y - y_0, z - z_0)$$

Intensity at detector point:

$$D(x_0, y_0, z_0) = \sum_{x, y, z} \begin{bmatrix} F_I(x, y, z) \\ \times g(x - x_0, y - y_0, z - z_0) \end{bmatrix}$$

$$= \sum_{x, y, z} \begin{bmatrix} S(x, y, z) \\ \times g'(x - x_0, y - y_0, z - z_0) \\ \times g(x - x_0, y - y_0, z - z_0) \end{bmatrix}$$

Hence

$$D(x, y, z) = S(x, y, z) * [g(x, y, z)g'(x, y, z)]$$

E9 285 Biomedical imaging-Inverse problems

Chapter 2.a

Representative reconstruction methods

Tikhonov inverse filtering

Recap: P-MLE for Gaussian

$$\mathbf{x}_{opt} = \arg \min_{\mathbf{x}} \left[\sum_{\mathbf{r} \in [1:N]^D} (\mathbf{v}_{\mathbf{r}}^T \mathbf{x} - d_{\mathbf{r}})^2 + \lambda J_R(x) \right]$$

In terms of convolution:

$$x_{opt}(\mathbf{r}) = \arg \min_{x(\mathbf{r})} \left[\underbrace{\sum_{\mathbf{r}' \in [1:N]^D} ((h * x)(\mathbf{r}') - D(\mathbf{r}'))^2}_{J_e(x)} + \lambda J_R(x) \right]$$

$d_{\mathbf{r}'} = D(\mathbf{r}')$, $\mathbf{v}_{\mathbf{r}'}$: scanned vector from $h(\mathbf{r} - \mathbf{r}')$

J is quadratic in Tikhonov filtering:

$$J_R(x) = \sum_{\mathbf{r}'} \left(\sum_{j=1}^{N_F} ((L_j * x)(\mathbf{r}'))^2 \right)$$

First consider the data term:

$$J_e(x) = \sum_{\mathbf{r}} ((h * x)(\mathbf{r}'))^2 + \sum_{\mathbf{r}} D^2(\mathbf{r}') - 2 \sum_{\mathbf{r}} (h * x)(\mathbf{r}') D(\mathbf{r}')$$

Consider the individual terms:

$$\sum_{\mathbf{r}} ((h * x)(\mathbf{r}'))^2 = \langle h * x, h * x \rangle = \langle x, h^T * h * x \rangle, \text{ where } h^T(\mathbf{r}) = h(-\mathbf{r})$$

$$\sum_{\mathbf{r}} (h * x)(\mathbf{r}') D(\mathbf{r}') = \langle h * x, D \rangle = \langle x, h^T * D \rangle$$

Hence we get

$$J_e(x) = \langle x, h^T * h * x \rangle - 2 \langle x, h^T * D \rangle + \langle D, D \rangle$$

$$J_R(x) = \langle x, h^T * h * x \rangle$$

$$\text{Total cost: } J_e(x) + \lambda J_R(x)$$

With respect to the terminology of quadratic forms:

Q: matrix equivalent of $h^T * h * x + \lambda \sum_{j=1}^{N_F} L_j^T * L_j * x$

b: scanned vector of the image $(h^T * D)(\mathbf{r})$

c: $\langle D, D \rangle$

To get the gradient of $J_e(x)$:

Evaluate $\lim_{\alpha \rightarrow 0} \frac{J_e(x + \alpha y) - J_e(x)}{\alpha} = \langle y, u \rangle.$

u will be the gradient.

$$\nabla J_e(\mathbf{r}) = \left(h^T * h * x \right)(\mathbf{r}) - \left(h^T * D \right)(\mathbf{r})$$

$$\nabla J_R(\mathbf{r}) = \sum_{j=1}^{N_F} \left(L_j^T * L_j * x \right)(\mathbf{r})$$

The required solution is given by

$$\nabla J_e(\mathbf{r}) + \lambda \nabla J_R(\mathbf{r}) = 0$$

$$\left(h^T * h * x \right)(\mathbf{r}) + \lambda \sum_{j=1}^{N_F} \left(L_j^T * L_j * x \right)(\mathbf{r}) = \left(h^T * D \right)(\mathbf{r})$$

Assignment 2:Tikhonov filtering on simulated data

- 1) Choose a biomedical image
- 2) Write a program for Gaussian blurring with a possibility of adding different levels of Gaussian and Poisson noise after blurring
- 3) Write a program for Tikhonov filtering with λ as an input
- 4) Write a program to compute

$$C(\eta) = \frac{\langle \hat{x}_o, \hat{x}_d \rangle_{\|\omega\|=\eta}}{\sqrt{\langle \hat{x}_o, \hat{x}_o \rangle_{\|\omega\|=\eta}} \sqrt{\langle \hat{x}_d, \hat{x}_d \rangle_{\|\omega\|=\eta}}}$$

where \hat{x}_o and \hat{x}_d are the Fourier transforms of the original and deconvolved images

- 5) Plot $(\eta, C(\eta))$ for different values of λ , for a given Gaussian noise level
- 6) Repeat 5 for Poisson noise
- 7) Plot $(\eta, C(\eta))$ for different Gaussian noise levels with correct value of λ
- 8) Repeat 7 for Poissons noise.

Iterative constrained Tikhonov Miller method (ICTM)

[1] H.T.M. van der Voort and K.C. Strasters, "Restoration of confocal images for quantitative image analysis," *J. Microsc.*, vol. 178, no. 2, pp. 165–181, 1995.

[2] G.M.P. van der Kempen, L.J. van Vliet, P.J. Verveer, and H.T.M. van der Voort, "A quantitative comparison of image restoration methods for confocal microscopy," *J. Microsc.*, vol. 185, no. 3, pp. 354–365, 1997.

ICTM

- 1) $\{L_1, \dots, L_{N_F}\}$: first derivative filters
- 2) Implements steepest descent and conjugate gradient algorithm where the gradient is clipped for negative values at each step.

Assignment 3

Write program to compute $\nabla J_e(\mathbf{r}) + \lambda \nabla J_R(\mathbf{r})$ for Tikhonov filtering problem.
Implement regularization filters of real space