

# HW5. XV6 Priority Scheduler 구현하기

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## 1. 과제 개요

본 과제에서는 우선순위가 높은 순서대로 프로세스를 스케줄링 하는 Priority Scheduler 를 구현하고, test\_sched1, test\_sched2 코드를 통해 올바른 동작을 확인한다.

## 2. 소스코드

(수정한 코드를 캡처하고 간단히 설명함)

### 1) scheduler

```
320 // via switch back to the scheduler.
321 void
322 scheduler(void) {
323     struct proc *p;
324     struct proc *pp;
325     struct cpu *c = mycpu();
326     c->proc = 0;
327
328     int MaxPriority = -1; //HW#5 highest priority in table
329
330     for (;;) {
331         // Enable interrupts on this processor.
332         sti();
333
334         // Loop over process table looking for process to run.
335         acquire(&table.lock);
336
337         for (p = table.proc; p < &table.proc[NPROC]; p++) {
338             //HW#5 run most highest priority process
339             for (pp = table.proc; pp < &table.proc[NPROC]; pp++) {
340                 if (pp->state != RUNNABLE)
341                     continue;
342                 if (pp->priority > MaxPriority) {
343                     MaxPriority = pp->priority;
344                 }
345             }
346
347             if (p->state != RUNNABLE)
348                 continue;
349             if (p->priority < MaxPriority)
350                 continue;
351
352             MaxPriority = -1;
353
354             // Switch to chosen process. It is the process's job
355             // to release table.lock and then reacquire it
356             // before jumping back to us.
357             c->proc = p;
358             switchvm(p);
359             p->state = RUNNING;
360
361             switch(&(c->scheduler), p->context);
362             switchvm(p);
363
364             // Process is done running for now.
365             // It should have changed its p->state before coming back.
366             c->proc = 0;
367         }
368         release(&table.lock);
369     }
370 }
371 }
372 }
373 }
```

scheduler context를 불러와서 scheduler가 실행될 때 338번 줄 루프에서 처음부터 ptable을 탐색하는 것이 아닌 context에 저장되어있던 process 부터 탐색한다. 루프 안에서 가장 큰 priority 를 검색 해주고, context에 있던 process 기준으로 뒤의 process 중 maxpriority 이상 가진 것이 없으면, 다시 ptable 처음부터 검색을 시작하여 maxpriority를 가진 process를 실행한다.

324: pp는 340번 줄의 루프를 돌기 위해서 필요한 변수  
339~346: 가장 큰 priority 값을 찾기 위한 루프  
350~351: p->priority 가 MaxPriority보다 작으면 다음 프로세스를 조회한다.

## 2) fork

```
179 int
180 fork(void) {
181     int i, pid;
182     struct proc *np;
183     struct proc *curproc = myproc();
184
185     // Allocate process.
186     if ((np = allocproc()) == 0) {
187         return -1;
188     }
189
190     // Copy process state from proc.
191     if ((np->pgdir = copyuvm(curproc->pgdir, curproc->sz)) == 0) {
192         kfree(np->kstack);
193         np->kstack = 0;
194         np->state = UNUSED;
195         return -1;
196     }
197     np->sz = curproc->sz;
198     np->parent = curproc;
199     *np->tf = *curproc->tf;
200     np->priority = 5; //HWM#5
201
202     // Clear %eax so that fork returns 0 in the child.
203     np->tf->eax = 0;
204
205     for (i = 0; i < NOFILE; i++)
206         if (curproc->ofile[i])
207             np->ofile[i] = filedup(curproc->ofile[i]);
208     np->cwd = idup(curproc->cwd);
209
210     safestrcpy(np->name, curproc->name, sizeof(curproc->name));
211
212     pid = np->pid;
213
214     acquire(&ptable.lock);
215     np->state = RUNNABLE;
216     release(&ptable.lock);
217
218     yield();
219
220     return pid;
221 }
222 }
```

200: Child process 의 priority를 중간 값인 5로 설정한다.

220: yield() 함수를 호출해 새로 스케줄링한다.

## 3) trap

```
63     kbdintr();
64     lapiceoi();
65     break;
66     case T_IRQ0 + IRQ_COM1:
67         uextintr();
68         lapiceoi();
69         break;
70     case T_IRQ0 + 7:
71     case T_IRQ0 + IRQ_SPURIOUS:
72         cprintf("cpu%d: spurious interrupt at %x:%x\n",
73             cpuid(), tf->cs, tf->eip);
74         lapiceoi();
75         break;
76
77     //PAGEBREAK: 13
78     default:
79         if (myproc() == 0 || (tf->cs & 3) == 0) {
80             // In kernel, it must be our mistake.
81             cprintf("unexpected trap %d from cpu %d eip %x (cr2=0x%x)\n",
82                 tf->trapno, cpuid(), tf->eip, rcr2());
83             panic("trap");
84         }
85         // In user space, assume process misbehaved.
86         cprintf("pid %d %s: trap %d err %d on cpu %d "
87             "eip 0x%x addr 0x%x--kill proc\n",
88             myproc()->pid, myproc()->name, tf->trapno,
89             tf->err, cpuid(), tf->eip, rcr2());
90         myproc()->killed = 1;
91     }
92
93     // Force process exit if it has been killed and is in user space.
94     // (If it is still executing in the kernel, let it keep running
95     // until it gets to the regular system call return.)
96     if (myproc() && myproc()->killed && (tf->cs & 3) == DPL_USER)
97         exit();
98
99     // Force process to give up CPU on clock tick.
100     // If interrupts were on while locks held, would need to check nlock.
101     if(myproc() && myproc()->state == RUNNING &&
102         tf->trapno == T_IRQ0+IRQ_TIMER)
103         yield();
104
105     // Check if the process has been killed since we yielded
106     if (myproc() && myproc()->killed && (tf->cs & 3) == DPL_USER)
107         exit();
```

101~103: timer interrupt를 주석처리한다.

#### 4) getnice setnice

```
543
544 int setnice(int pid, int nice) {
545     if (nice < 0 || nice > 10)
546         return -1;
547     if (pid < 1)
548         return -1;
549
550     struct proc *p;
551     acquire(&ptable.lock);
552     int priority = 0;
553     priority = 10 - nice;
554
555     /* do program */
556     /* do program */
557     for (p = ptable.proc; p < &ptable.proc[NPROC]; p++) {
558         if (p->pid == pid) {
559             p->priority = priority;
560             release(&ptable.lock);
561             return 0;
562         }
563     }
564
565     myproc()->state = RUNNABLE;
566     release(&ptable.lock);
567
568     yield(); // Call Scheduler due to priority change
569     return -1; //non-existing pid
570 }
571
572 int getnice(int pid) {
573
574     if (pid < 1)
575         return -1;
576
577     struct proc *p;
578     acquire(&ptable.lock);
579
580     /* do program */
581     /* do program */
582     for (p = ptable.proc; p < &ptable.proc[NPROC]; p++) {
583         if (p->pid == pid) {
584             release(&ptable.lock);
585             return (10 - p->priority);
586         }
587     }
588
589     release(&ptable.lock);
590
591     return -1; //non-existing pid
592 }
593
594
595
596
597
```

552~553: nice value가 높으면 priority value 는 반대로 낮아진다. user로 부터 들어온 nice 값을 priority값으로 변경해 priority 변수에 저장한다.

569: priority 가 변경되었으므로 새로 스케줄링한다.

588: priority 값을 nice value로 변경하여 리턴한다.

#### 3.결과

(테스트 실행결과를 캡처)

```
format=raw -smp 1 -m 512
xv6...
cpu0: starting 0
sb: size 1000 nblocks 941 ninodes 200 nlog 30 logstart 2 i
nodestart 32 bmap start 58
init: starting sh
$ test_sched1
#### State 1 ####
#### State 2 ####
PID 4 is finished
#### State 3 ####
PID 3 is finished
```

test\_sched1

```
$ test_sched2
#### State 2 ####
PID 6 is finished
#### State 1 ####
#### State 3 ####
PID 5 is finished
$
```

test\_sched2