

HW #4

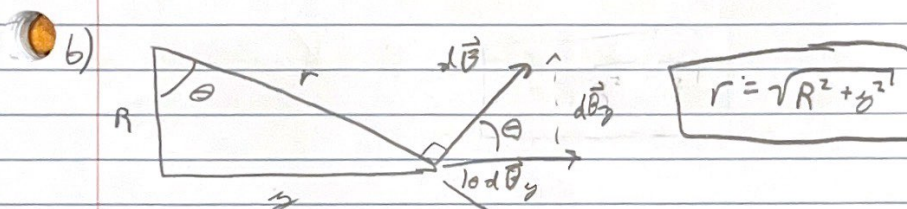
1) $d\vec{B} = \frac{\mu_0 d \vec{l} \times \hat{r}}{4\pi r^2}$

a) find \vec{B} @ center of loop, Dist. same @ $r=R$, find \vec{B}

$d\vec{B} = \frac{\mu_0 d \vec{l} \times \hat{r}}{4\pi r^2}$ $\vec{r} \rightarrow -\hat{r}$ & $d\vec{l} = R d\phi \hat{\phi}$

$d\vec{B} = \frac{\mu_0 d}{4\pi R^2} \begin{vmatrix} \hat{r} & \hat{\phi} & \hat{z} \\ 0 & R d\phi & 0 \\ -1 & 0 & 0 \end{vmatrix} = \frac{\mu_0 d}{4\pi R^2} (R d\phi) \hat{z} = \frac{\mu_0 d}{4\pi R} d\phi \hat{z}$

$\vec{B} = \int d\vec{B} = \int \frac{\mu_0 d}{4\pi R} d\phi \hat{z} = \frac{\mu_0 d}{4\pi R} \hat{z} \int_0^{2\pi} d\phi = \frac{\mu_0 d}{4\pi R} (2\pi) \hat{z} = \boxed{\frac{\mu_0 d}{2R} \hat{z}}$ on axis



c) $\sin \theta = \frac{z}{r}$ $\sin \theta = \frac{dB_z}{dB} \Rightarrow dB \sin \theta = dB_z$
 $\cos \theta = \frac{R}{r}$ $\cos \theta = \frac{dB_y}{dB} \Rightarrow dB \cos \theta = dB_y$

d) $\sin \theta = -\frac{dB_z}{dB'} \Rightarrow -dB' \sin \theta = dB_z = -dB'_z$
 $\cos \theta = \frac{dB_y}{dB'} \Rightarrow dB' \cos \theta = dB_y = dB'_y$

The \hat{z} components of $d\vec{B}$ & $d\vec{B}'$ will cancel out

\therefore particle will only feel force in \hat{y} (on-axis)

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e) $\cos \theta = \frac{A}{r} = \frac{R}{\sqrt{R^2 + z^2}}$

f) $d\vec{B} = \frac{\mu_0 I d\vec{\ell} \times \hat{r}}{4\pi r^2} = \frac{\mu_0 I}{4\pi r^2} \begin{vmatrix} \hat{r} & \hat{\phi} & \hat{z} \\ 0 & R d\phi & 0 \\ -\cos \theta & 0 & 0 \end{vmatrix} = \frac{\mu_0 I d\phi R \sin \theta}{4\pi r^2} \hat{z}$

$\Rightarrow \frac{\mu_0 I R}{4\pi r^2} \frac{R \hat{z}}{\sqrt{R^2 + z^2}} \int_0^{2\pi} d\phi = \frac{\mu_0 I R^2}{4\pi} \frac{1}{(R^2 + z^2)^{3/2}} \cdot 2\pi \hat{z}$

$\Rightarrow \vec{B} = \frac{\mu_0 I R^2}{2(R^2 + z^2)^{3/2}} \hat{z}$

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2) uniform $\vec{B} = B_0 \hat{z}$

mirror $\vec{B} = B_0 \left[1 + \left(\frac{z}{a_0} \right)^2 \right] \hat{z}$

a) mass m , charge q , find $v_{||}(z)$ for $I \ll I_c$, assume particle mirrors @ $z = \pm z_t$

II) mirror ratio

$$B_{max} = B(z_t) = B_0 \left[1 + \left(\frac{z_t}{a_0} \right)^2 \right]$$

$$B_{min} = B(0) = B_0 [1 + 0] = B_0$$

$$\Rightarrow R_m = \frac{B_0 \left[1 + \left(\frac{z_t}{a_0} \right)^2 \right]}{B_0} = 1 + \left(\frac{z_t}{a_0} \right)^2$$

$$I) \quad m \dot{\vec{v}} = q \vec{v} \times \vec{B} = q \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ v_x & v_y & v_z \\ 0 & 0 & B_0 \end{vmatrix} = q B_0 (v_y \hat{x} - v_x \hat{y})$$

$$m \dot{v}_z = 0 \Rightarrow \boxed{v_z = v_{z0} = v_{||,0}}$$

$$\begin{cases} \text{II) } \frac{1}{2} m v_{\perp}^2 + \frac{1}{2} m v_{||}^2 = C_0 \Rightarrow v_{\perp}^2 + v_{||}^2 = C \\ \Rightarrow v_{||} = \sqrt{C - v_{\perp}^2}, \quad (v_{||}(\pm z_t) = 0 = \sqrt{C - v_{\perp}^2} \Rightarrow C = v_{\perp}^2(\pm z_t) \\ \text{reflects } \uparrow \\ v_{||} = \sqrt{v_{\perp}^2(\pm z_t) - v_{\perp}^2(z)} \end{cases}$$

$$\mu = \frac{1}{2} m \frac{v_{\perp}^2}{B} \Rightarrow v_{\perp}^2 = \frac{2\mu B}{m} \quad v_{\perp}^2(z) = \frac{2\mu}{m} B(z)$$

$$\Rightarrow v_{\perp}^2(z) = \frac{2\mu}{m} \left[B_0 + B_0 \left(\frac{z}{a_0} \right)^2 \right], \quad v_{\perp}^2(\pm z_t) = \frac{2\mu}{m} \left[B_0 + B_0 \left(\frac{\pm z_t}{a_0} \right)^2 \right]$$

$$\Rightarrow v_{||} = \sqrt{\frac{2\mu B_0}{m} \left[1 + \left(\frac{\pm z_t}{a_0} \right)^2 \right] - \frac{2\mu B_0}{m} \left[1 + \left(\frac{z}{a_0} \right)^2 \right]}$$

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$$\Rightarrow v_{||} = \sqrt{\frac{2\mu B_0}{ma_0^2} (z_t - z)}$$

b) show $F_{||} \propto \frac{\partial B}{\partial z} \hat{z}$

$$F_{||} = m \frac{dv_{||}}{dt}, \quad v_{||} = \frac{dz}{dt} \Rightarrow F_{||} = m \frac{dv_{||}}{dt} = m \frac{dv_{||}}{dz} \left[\frac{dz}{dt} \right]$$

$$F_{||} = m v_{||} \frac{dv_{||}}{dz} = \frac{m}{2} \frac{d(v_{||}^2)}{dz} = \frac{m}{2} \frac{d}{dz} \left[\frac{2\mu B_0}{ma_0^2} (z_t^2 - z^2) \right]$$

$$\Rightarrow F_{||} = m \left(\frac{2\mu B_0}{ma_0^2} (-2z) \right) = \frac{-2\mu B_0}{a_0^2} z = F_{||}$$

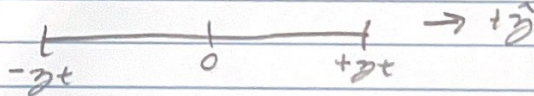
$$\frac{\partial v}{\partial z} = \frac{B_0}{a_0^2} 2z$$

$$F_{||} \neq \mu \quad \therefore F_{||}(z) \propto \frac{\partial B}{\partial z}$$

c) I) $F_{||}(z) = 0$ as $v_z \parallel B_z$

The force does nothing to the particle

$$\text{II) } F_{||}(z) = \frac{-2\mu B_0}{a_0^2} z$$



as $z \rightarrow +z_t$, the force gets stronger in $-\hat{z}$ forcing particle back to center

as $z \rightarrow -z_t$, the force gets stronger in $+\hat{z}$ forcing particle back to center

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$$2d) F_{||} = m \frac{dv_{||}}{dt} = \frac{-2\mu B_0 z}{a_0^3} = m \ddot{z}$$

$$\Rightarrow \boxed{\frac{d^2 z}{dt^2} + \underbrace{\left(\frac{2\mu B_0}{m a_0^3} \right)}_{\omega^2} z = 0} \quad \omega / \quad \omega^2 = \frac{2\mu B_0}{m a_0^3}$$

Period

$$\frac{2\pi}{T} = \omega = \sqrt{\frac{2\mu B_0}{m a_0^3}}$$

\Rightarrow

$$\boxed{\therefore T = 2\pi \sqrt{\frac{m a_0^3}{2\mu B_0}}}$$

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3) find trajectory w/ $B(90,1)$ & $E=(E_0 \sin(\omega t), 0, 0)$

$$\omega_c = \frac{qB_0}{m} = 1 \text{ in code}$$

if $\omega \ll \omega_c$, the perturbations happen so quickly that it looks like the trajectory is constant like for constant E field.

if $\omega \sim \omega_c$, the local perturbations are much more noticeable & the x & y positions move about a guiding center w/ sinusoidal perturbations about the trajectory of constant E

For $\omega \ll \omega_c$ & $\omega \sim \omega_c$, the mean behavior is roughly the same. Although the trajectory for y is the same in all cases, the sinusoidally oscillating E fields have a lower final x position than a constant E field. This makes sense as the varying E will exert less force when averaged over a period of oscillation than a constant field over the same period.