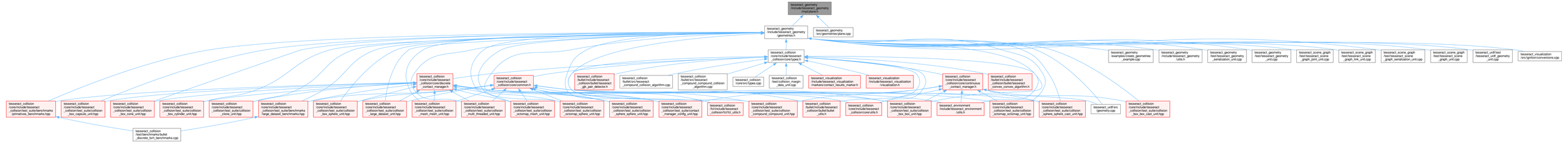
tesseract_geometry /include/tesseract_geometry /mesh/plane.h
tesseract_geometry /include/tesseract_geometry /geometries.h
tesseract_geometry /src/geometries/plane.cpp
tesseract_collision /core/include/tesseract _collision/core/types.h
tesseract_collision /core/include/tesseract _collision/core/discrete _contact_manager.h
tesseract_collision /core/include/tesseract _collision/core/common.h
tesseract_collision /bullet/include/tesseract _collision/bullet/tesseract _gjk_pair_detector.h
tesseract_collision /bullet/src/tesseract _compound_collision_algorithm.cpp
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tesseract_collision /fcl/src/collision_margin _data_unit.cpp
tesseract_visualization /include/tesseract_visualization /markers/contact_results_marker.h
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tesseract_collision /bullet/include/tesseract _collision/bullet/tesseract _convex_convex_algorithm.h
tesseract_geometry /examples/create_geometries _example.cpp
tesseract_geometry /include/tesseract_geometry /utils.h
tesseract_geometry /test/tesseract_geometry _serialization_unit.cpp
tesseract_geometry /test/tesseract_geometry _unit.cpp
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tesseract_scene_graph /test/tesseract_scene _graph_link_unit.cpp
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tesseract_urdf/test /tesseract_urdf_geometry _unit.cpp
tesseract_visualization /src/gridlocorversions.cpp
tesseract_collision /core/include/tesseract _collision/test_suite/benchmarks _primitives_benchmarks.hpp
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tesseract_collision /test/benchmarks/bullet _discrete_bvh_benchmarks.cpp