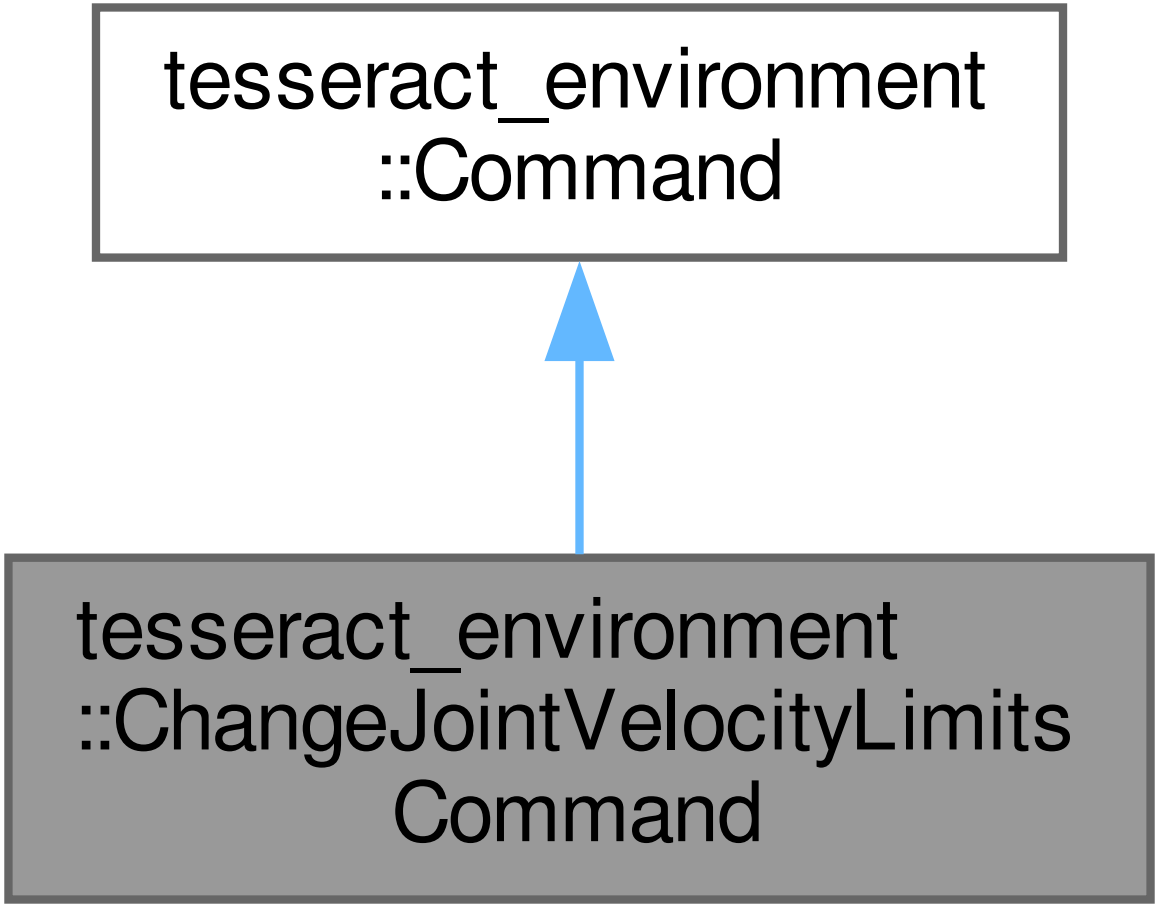
tesseract_environment
::Command
tesseract_environment
::ChangeJointVelocityLimits
Command