

tesseract_kinematics
/test/abb_irb2400_ikfast
_kinematics.h

```
graph BT; A["tesseract_kinematics<br>/test/abb_irb2400_ikfast<br>_kinematics.cpp"] --> B["tesseract_kinematics<br>/test/abb_irb2400_ikfast<br>_kinematics.h"]; C["tesseract_kinematics<br>/test/ikfast_kinematics<br>_unit.cpp"] --> B;
```

This diagram illustrates the relationship between three source files in a project. At the top is a header file, `tesseract_kinematics/test/abb_irb2400_ikfast_kinematics.h`, which is shaded gray. Below it are two source files: `tesseract_kinematics/test/abb_irb2400_ikfast_kinematics.cpp` on the left and `tesseract_kinematics/test/ikfast_kinematics_unit.cpp` on the right. Both source files have blue arrows pointing to the header file, indicating that they include it.

tesseract_kinematics
/test/abb_irb2400_ikfast
_kinematics.cpp

tesseract_kinematics
/test/ikfast_kinematics
_unit.cpp