

tesseract_kinematics
/test/abb_irb2400_ikfast
_kinematics.h

```
graph BT; A["tesseract_kinematics<br>/test/abb_irb2400_ikfast<br>_kinematics.cpp"] --> C["tesseract_kinematics<br>/test/abb_irb2400_ikfast<br>_kinematics.h"]; B["tesseract_kinematics<br>/test/ikfast_kinematics<br>_unit.cpp"] --> C;
```

The diagram illustrates a dependency structure where two source files, `_kinematics.cpp` and `_unit.cpp`, both include the header file `_kinematics.h`. The header file is positioned at the top in a grey box, while the source files are at the bottom in white boxes. Blue arrows point from each source file to the header file.

tesseract_kinematics
/test/abb_irb2400_ikfast
_kinematics.cpp

tesseract_kinematics
/test/ikfast_kinematics
_unit.cpp