

tesseract\_kinematics  
/test/abb\_irb2400\_ikfast  
\_kinematics.h

```
graph BT; A["tesseract_kinematics<br>/test/abb_irb2400_ikfast<br>_kinematics.cpp"] --> C["tesseract_kinematics<br>/test/abb_irb2400_ikfast<br>_kinematics.h"]; B["tesseract_kinematics<br>/test/ikfast_kinematics<br>_unit.cpp"] --> C;
```

The diagram illustrates a dependency structure where two source files, `_kinematics.cpp` and `_unit.cpp`, both include the header file `_kinematics.h`. The header file is represented by a grey box at the top, while the source files are in white boxes below it. Blue arrows point from each source file to the header file.

tesseract\_kinematics  
/test/abb\_irb2400\_ikfast  
\_kinematics.cpp

tesseract\_kinematics  
/test/ikfast\_kinematics  
\_unit.cpp