

tesseract_kinematics
/test/abb_irb2400_ikfast
_kinematics.h

```
graph BT; A["tesseract_kinematics<br>/test/abb_irb2400_ikfast<br>_kinematics.cpp"] --> B["tesseract_kinematics<br>/test/abb_irb2400_ikfast<br>_kinematics.h"]; C["tesseract_kinematics<br>/test/ikfast_kinematics<br>_unit.cpp"] --> B;
```

This diagram illustrates the relationship between three C++ files. At the top is a header file, `tesseract_kinematics/test/abb_irb2400_ikfast_kinematics.h`, which is shaded gray. Below it are two source files in white boxes. Blue arrows point from each source file to the header file, indicating that both source files include this header. The source file on the left is `tesseract_kinematics/test/abb_irb2400_ikfast_kinematics.cpp`, and the source file on the right is `tesseract_kinematics/test/ikfast_kinematics_unit.cpp`.

tesseract_kinematics
/test/abb_irb2400_ikfast
_kinematics.cpp

tesseract_kinematics
/test/ikfast_kinematics
_unit.cpp