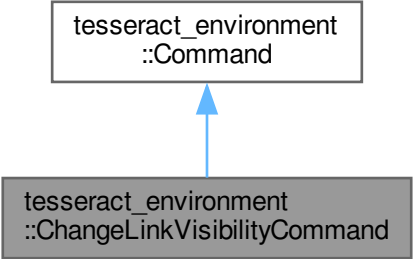


tesseract_environment
::Command



```
graph BT; A[tesseract_environment::ChangeLinkVisibilityCommand] --> B[tesseract_environment::Command];
```

The diagram illustrates an inheritance relationship. A light blue box at the bottom represents the base class, `tesseract_environment::ChangeLinkVisibilityCommand`. A blue arrow points upwards from this box to a white box at the top, which represents the derived class, `tesseract_environment::Command`. This indicates that `ChangeLinkVisibilityCommand` inherits from `Command`.

tesseract_environment
::ChangeLinkVisibilityCommand