

tesseract_environment
::Command



```
graph BT; A[tesseract_environment::AddKinematicsInformationCommand] --> B[tesseract_environment::Command];
```

The diagram illustrates a class hierarchy. At the bottom is a gray box containing the text 'tesseract_environment::AddKinematicsInformationCommand'. A blue arrow points vertically upwards from this box to a white box at the top containing the text 'tesseract_environment::Command'. This indicates that 'AddKinematicsInformationCommand' inherits from 'Command'.

tesseract_environment
::AddKinematicsInformationCommand