

tesseract_environment
::Command



```
graph BT; A[tesseract_environment::AddKinematicsInformationCommand] --> B[tesseract_environment::Command];
```

The diagram illustrates an inheritance relationship. A light gray box at the bottom represents the base class, and a white box at the top represents the derived class. A blue arrow points from the base class box to the derived class box, indicating that the derived class inherits from the base class.

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