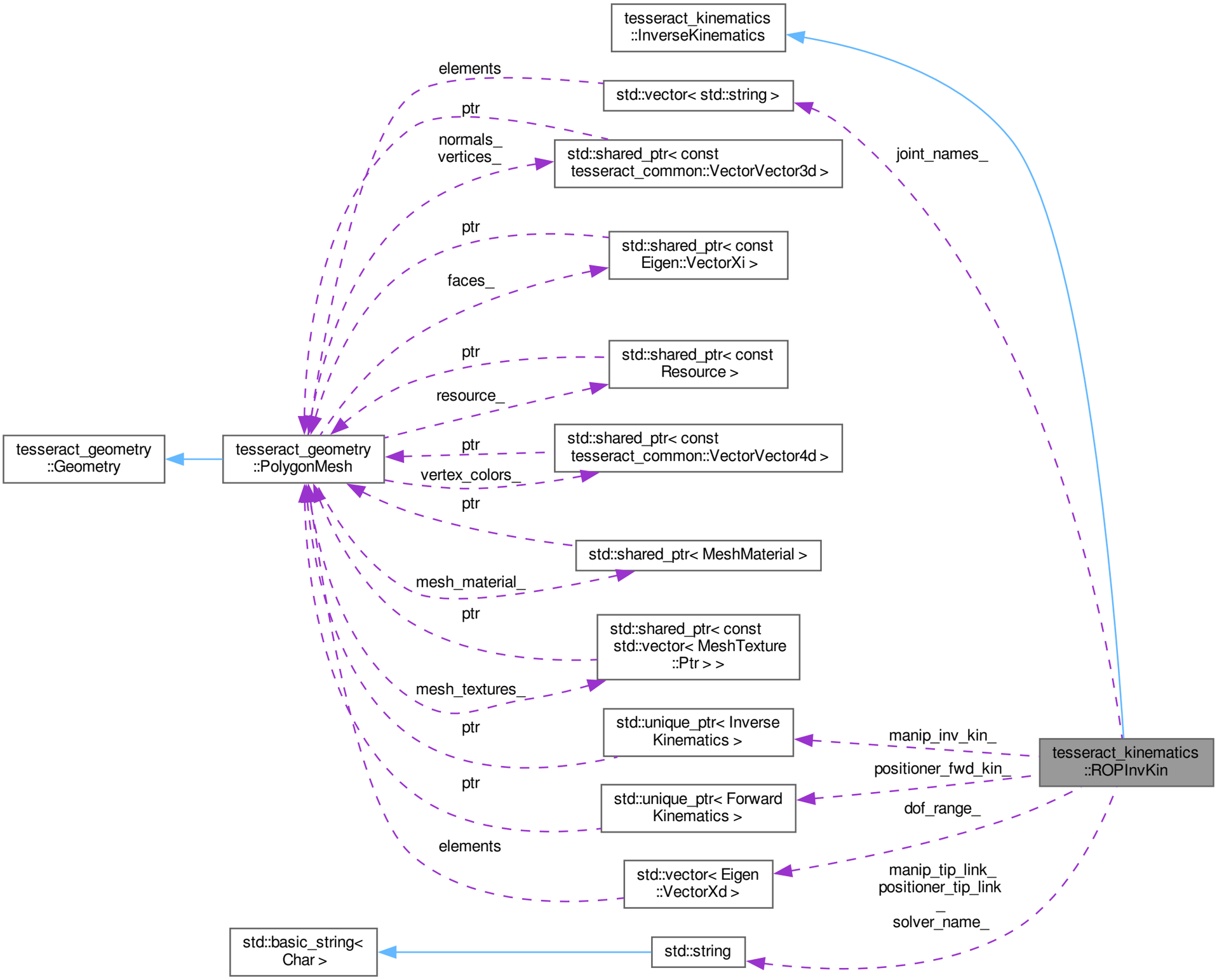
tesseract_kinematics ::InverseKinematics
elements
std::vector< std::string >
ptr
normals_
vertices_
std::shared_ptr< const tesseract_common::VectorVector3d >
joint_names_
ptr
std::shared_ptr< const Eigen::VectorXi >
faces_
ptr
std::shared_ptr< const Resource >
resource_
tesseract_geometry ::Geometry
tesseract_geometry ::PolygonMesh
ptr
std::shared_ptr< const tesseract_common::VectorVector4d >
vertex_colors_
ptr
std::shared_ptr< MeshMaterial >
mesh_material_
ptr
std::shared_ptr< const std::vector< MeshTexture ::Ptr > >
mesh_textures_
ptr
std::unique_ptr< Inverse Kinematics >
manip_inv_kin_
tesseract_kinematics ::ROPInvKin
positioner_fwd_kin_
ptr
std::unique_ptr< Forward Kinematics >
dof_range_
elements
std::vector< Eigen ::VectorXd >
manip_tip_link_
positioner_tip_link _
solver_name_
std::basic_string< Char >
std::string