## **Traffic Operations**

## **URMS**

## **Universal Ramp Metering Software**



User Manual - Draft May 2012







# URMS Users Manual URMS-2070-UM-013

Version 1.13

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## **Revision History**

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#### Note:

The latest revision of this manual is available at the following Caltrans Intranet website:

http://trac



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#### **Overview**

The Universal Ramp Metering Software (URMS) program allows the Model 2070 Controller to function as a ramp metering controller for use throughout the State. It was designed to incorporate most of the functionally already utilized for ramp metering operations used by various Caltrans Districts into one program. The main operational features of URMS are:

#### **Features**

- 4 Metered Lanes with up to 4 queues for each lane
- 8 Mainline Lanes Dual or Single detector per lane
- 8 Opposite Mainline Lanes Dual or Single detector per lane
- 16 Additional Detector Locations
- 8 General Purpose Outputs Non-Flashing, or flashing
- 1 Failsafe Input
- 10 Traffic Responsive Plans, each with 15 levels
- Command Sources: Manual, Communications, Time-of-Day and Default
- Command Actions: Fixed Rate, Traffic Responsive, Rest-in-Dark, Rest-In-Green and Emergency Green
- 16 Fixed Holidays
- 12 Floating Holidays
- Automatic Daylight Saving Time correction
- Time of Day Modes: Fixed, Traffic Responsive, Dark, Green, Emergency Green and Traffic Responsive Slave.
- Communications: 1200, 2400, 4800, 9600, 19200, 38400 baud, EIA-232, 2/4 Wire Modem and TCP/IP Polling
- Supports Telnet and FTP communications
- Supports remote access to the controller front panel using Telnet
- Supports standard SDRMS, SATMS and TOS polling and time synchronization functionality

#### **Keyboard and Display Operations**

URMS is fully menu-driven. The user can access all screens through the selection of menu choices. Menu selections are made by pressing the key corresponding to the selection desired. The selection key is always shown to the left of the choice, followed by the dash character. Once a menu selection key has been pressed, the selected screen or a sub-menu will be displayed from which further selections can be made. It may be necessary to proceed through up to three sub-menus to access certain screens. To return to a previous menu, press the [ESC] key. Repeated pressing of the [ESC] key will eventually return the display to the main menu.



On data entry screens, the position of the cursor is designated by two arrows [<>] surrounding a data entry position. The cursor position may be moved by pressing any of the four arrow keys  $[\Leftarrow]$ ,  $[\Leftrightarrow]$ ,  $[\diamondsuit]$  or  $[\diamondsuit]$ . In the case of multiple page data entry screens, the cursor will move to the next adjacent page if moved beyond the end of the screen. The [NEXT] key may also be used to advance directly to the next page on multiple page data entry screens.

Once the desired data entry position is selected, data may be entered. There are three different types of data entry positions on the various data entry screens. These include decimal data entry (both with and without a decimal point), flag data entry and list data entry.

Decimal data entry is accomplished by pressing the number keys [0] to [9] corresponding to the data entered. As each key is pressed, the digits entered scroll from right to left. Fields with decimal points have the decimal placed automatically, and are entered identically to those without decimal points. Once the data entry process has begun by pressing a number key, the cursor arrows will turn from arrows "<>" into square brackets "[ ]". This indicates that data entry is in progress. Continue entering the decimal digits until the desired number is shown in the field. If errors are made press the [ESC] key, the up arrow [ $\updownarrow$ ] or the down arrow [ $\updownarrow$ ] keys to completely cancel the entry. Then reselect the item and re-enter the desired data. Once the entry is complete, pressing the [ENT] key will save the data.

There is one type of flag data entry which is day-of-week. Day-of-week bit set consists of eight bits labeled SMTWTFSH. Press the key corresponding to the desired bit to toggle that flag entry: [1] is for Sunday, [2] is for Monday, [3] is for Tuesday, [4] is for Wednesday, [5] is for Thursday, [6] is for Friday, [7] is for Saturday and [8] is for Holiday. Once again, press the [ENT] key to save the day-of-week data.

The list type data entry allows the selection of one setting for each entry, which is usually presented as text, but sometimes consists of discrete numbers. Press the [+] or [-] keys to advance through the available choices. Once the list type data entry process has begun by pressing the [+] or [-] key, the cursor arrows will begin flashing. The list of choices is cyclic, and continuing to press either the [+] or [-] key will eventually return to the original selection. After a change has been made, press the [ENT] key to save the data. The [ESC] key can be pressed to cancel any change made and restore the original selection. List type data entry with the values of "YES" or "NO" may also be changed by pressing the [YES] or [NO] keys.

The Active LED on the front panel indicates the status of the controller, and blinks once per second during normal program operation. However, when the URMS is creating a backup copy of all user data entered to the Datakey, the Active LED will blink rapidly at five times per second. The copy procedure lasts about 60 seconds. Do not turn the power to the controller off when the Active LED is blinking rapidly, or the backup copy will not be completed.



#### **Input and Output Assignments**

URMS provides complete flexibility when configuring inputs. Each physical input is configured by assigning it to a device. Likewise, each physical output is configured by assigning it to a Load Switch Output. The Model 2070 Controller has 64 physical inputs numbered from 0 to 63 and 64 physical outputs also numbered from 0 to 63. The following table shows each physical input number for each input and output file slot for a Model 334 cabinet; however, the URMS is also capable of being configured for other cabinet models. For convenience, most current ramp metering output configurations can be selected under the Physical I/O Configuration Menu (menu item 8-7).

	URMS Configuation Input and Output Numbers													
					C1 In	out to	I File	Input	Numl	bers				
	1	2	3	4	5	6	7	8	9	10	11	12	13	14
	C1-46	C1-50	C1-49	C1-55	C1-51	C1-57	C1-59	C1-61	C1-81	C1-79	C1-53	C1-41	C1-43	C1-45
UPPER	7	11	10	16	12	18	20	22	46	44	14	2	4	6
	C1-39	C1-47	C1-48	C1-56	C1-52	C1-58	C1-60	C1-62	C1-80	C1-82	C1-54	C1-40	C1-42	C1-44
LOWER	0	8	9	17	13	19	21	23	45	47	15	1	3	5
					C1 Sv	vitchp	ack O	utput	Numb	oers				
	1	2	3						9	10	11	12	13	14
	C1-2	C-4	C1-7						C1-97	C1-94	C1-91	C1-88	C1-85	C1-83
RED	0	2	5						53	50	48	45	42	40
	C1-37	C1-5	C1-8						C1-98	C1-95	C1-101	C1-89	C1-86	C1-100
YELLOW	34	3	6						54	51	37	46	43	36
	C1-3	C1-6	C1-9						C1-99	C1-96	C1-93	C1-90	C1-87	C1-84
GREEN	1	4	7						55	52	49	47	44	41



If additional inputs are needed then an additional input rack or "J" file can also be connected to the controller. When used, the URMS input numbers and 2070 C1/C11 connections are as shown on the table below.

	URMS Configuation Additional Rack Input Numbers													
	C1/C11 Input to Ramp Metering J File Input Numbers													
00	1	2	3	4	5	6	7	8	9	10	11	12	13	14
	C1-73	C1-75	C1-77	C1-67	C11-10	C11-12	C11-15	C11-17	C11-19	C11-21	C11-23	C11-25	C11-27	C11-29
UPPER	38	40	42	32	24	26	48	50	52	54	56	58	60	62
	C1-74	C1-76	C1-78	C1-68	C11-11	C11-13	C11-16	C11-18	C11-20	C11-22	C11-24	C11-26	C11-28	C11-30
LOWER	39	41	43	33	25	27	49	51	53	55	57	59	61	63



#### **URMS Initialization Errors**

When the controller boots up, the URMS checks to ensure that a valid configuration file exists on the controller..

If any configuration error is found, then the following error screen will be displayed. Press any key to go to the Main Menu. URMS will still run, but you may want to remove this unit from service until the reason for the error is determined.

URMS CONFIGURATION FILE ERRORS
WERE FOUND WHEN LOADING THE
CONFIGURATION FILE /ro/urms.cfg

If the URMS configuration file cannot be found by URMS or if the configuration file is corrupt, then the following error screen will appear. URMS will not run without a valid configuration file. Load a new URMS configuration file or remove the controller from service.

URMS CONFIGURATION FILE NOT FOUND PLEASE ENSURE THE CONFIGURATION FILE /ro/urms.cfg IS LOADED AND NOT CORRUPT



#### **URMS Main Menu**

The Main Menu is the home screen for URMS. If you don't know what menu screen you are on in the program, pressing [ESC] repeatedly will eventually bring you back to the Main Menu. The Main Menu is divided into 10 logical areas which allow the user to view the controller status and to modify the current configuration.

#### URMS VERSION 2.08 - MAIN MENU

1-Metered Lanes 6-Time of Day 2-Mainline 7-Communications 3-Additional Detection 8-General

4-Traffic Resp. Plans 9-Utilities 5-Command Source A-Status

**Metered Lanes** Status and configuration for up to 4 metered lanes.

**Mainline** Status and configuration for up to 8 mainline and 8

Opposite mainline lanes.

**Additional Detection** Status and configuration for up to 16 additional detection

stations which can include off ramp, on ramp, merge

detection or any other location which the user would like to

collect traffic monitoring data.

**Plans** Metering plans used for traffic responsive metering.

**Command Source** The status and configuration for the various controller

command sources that can command the controller such as

time-of-day or communications.

**Time-of-Day** Used for time-of-day functions such a setting the clock,

time-of-day tables, and both fixed and floating holidays.

**Communications** Status and configuration for serial ports 1, 2 and TCP/IP.

**General** Physical I/O Setup, current I/O configuration, General

Purpose Output ON and OFF flashing times and failsafe

feedback.



**Utilities** Power failure logging, raw input and outputs detection

status, detector reset, wiring and signal test, software status,

configurations backup as well as several other utility

functions.

**Status** Controller status indications of timing, traffic responsive

rate, current plans, current metering rates and other ramp

metering status information.



#### 1. Metered Lanes

The Metered Lanes menu has 5 menu items to allow a user to get the status of and to modify the configuration of up to 4 metered lanes.

#### **METERED LANES**

1-Stati sti cs

2-Detection

3-Detector Status

4-Car Count

5-Confi gurati on 6-Queue Confi gurati on

**Statistics** Shows the last 30-second volume and occupancy data for

each Queue, Demand, and Passage Detector.

**Detection** Shows the current detection state of each Queue, Demand,

and Passage Detector.

**Detector Status** Shows the current operational status of each Queue, Demand,

and Passage Detector.

**Car Count** Shows the number of vehicles that have been detected on

each Queue, Demand and Passage Detector since the

controller was turned on.

Configuration Allow the user to configure the metered lane timing and

detector configuration parameters.

Queue Configuration Allow the user to configure the queue detection and

configuration parameters.

#### 1-1 Statistics

The Statistics menu show the last 30 seconds of data for each of the configured metered lane. The data shown is updated every 30 seconds. It should also be noted that the controller will only display data for the number of lanes configured.



	Mete	ered Lan	e 30 Secon	d Data	1
LANE	QU	EUE	DEMAND	PAS	SAGE
	VOL	OCC%	VOL	VOL	OCC%
1	6	15. 3	5	3	12. 4
2	5	12. 3	4	4	13. 4
3	7	12. 4	4	3	12. 4
4	4	10. 3	4	3	12. 3
				_	

**Queue Volume** The number of vehicles that have passed through the queue

detection zone during the last 30-second interval.

**Queue Occupancy** The percentage of time that vehicles were present in the queue

detection zone during the last 30-second interval.

**Demand Volume** The number of vehicles that have passed through the demand

detection zone during the last 30-second interval.

**Passage Volume** The number of vehicles that have passed through the passage

detection zone during the last 30-second interval.

Passage Occupancy The percentage of time that vehicles were present in the

passage detection zone during the last 30-second interval.

#### **1-2 Detection Status**

The Detection Status menu displays whether a Queue, Demand or Passage Detector for each metered lane is currently in the actuated or de-actuated state. A dot ( . ) represents a de-actuated /OFF state while an asterisk ( \* ) represents an actuated /ON state.

METERED	LANE DE	TECTI OI	N STATI	JS	
LANE	1	2	3	4	
Queue4	•	•	•		
Queue3	•	•	•		
Queue2	•	*	•	•	
Queue1	•	•	•	•	
Demand	•	•	•		
Passage	•	•	*	•	





#### **1-3 Detector Status**

The Detector Status menu displays the current operational status of the metered lane Queue, Demand and Passage Detectors.

METERED	LANE	DET	ECTOR :	STATUS	<del></del>	
Lane		1	2	3	4	
Queue4		W	W	D	D	
Queue3		W	W	D	D	
Queue2		W	W	D	D	
Queue1		W	W	D	D	
Demand		W	R	R	D	
Passage		W	W	MP	D	
1 11 1 1 1 3						

Due to space limitations the following abbreviations are used in the display of the metered lanes detector status:

Working [W]	Indicates that this detector currently appears to be working normally.
Recalled [R]	Represents that the detector has been configured to be in a continuous recalled or ON state.
Disabled [D]	Represents that the detector has been configured to be in a continuous de-actuated or OFF state.
Maximum Presence [MP]	Indicates that the input on the detector for a metered lane has been continuously actuated for longer than the configured Maximum Presence Time.
No Activity [NA]	Indicates that the input on the detector for a metered lane has been continuously de-actuated or OFF state for longer than the configured Maximum No Activity Time.
Erratic Count [EC]	Indicates that the vehicle count on the detector for a metered lane exceeded the maximum number of counts allowed under the configured Erratic Count Threshold

during the last 30-second interval.



#### **1-4 Car Counts**

The Car Counts menu show the number of cars that have traveled over a detector since the controller was powered on or the car counts were reset. For metered lanes only the last 5 digits of the car counts are displayed on the front panel.

	Metered	Lane	Car Co	unts	
Lane		1	2	3	4
Queue4		7521	7312	7443	6923
Queue3		7421	7321	7432	6985
Queue2		7444	7242	7446	6953
Queue1		7434	7431	7438	6983
Demand		7432	7422	7412	6974
Passage		7436	7345	7423	6877
i assage		7 400	7040	7720	0077

#### **Note:**

Car Counts can be cleared using menu 9-C (clear car counts)

#### 1-5 Configuration

The Configuration menu displays the metered lanes configuration menu.

METERED	LANE CONFIGURATION
1-General	6-Demand
2-Startup	7-Passage
3-Meteri ng	8-Queue Usage
4-Shutdown	9-Metering Defaults
5-Groups	A-Queue Override

General	Represents the general items related to a lane such as the Lane Group Number.
Startup	Represents those items which relate to the transition of the ramp meter from the non-metering state to the metering state.
Metering	Represents those items which relate to the timing that occurs while the controller is actively metering traffic



**Shutdown** Represents those items which relate to the transition

from the active metering state to the non-metering state.

**Dependency Groups** Represent configuration items that affect ramp metering

groups such as fixed metering offset time or fractional

offset time.

**Demand** Represents the configuration items for the metered lane

Demand Detector.

**Passage** Represents the configuration items for the metered lane

Passage Detector.

Queue Adjustment Limits Represents the method by which Queue Override if

enabled will occur.

Queue Adjustment Rates Represents the adjustment rate and levels used for rate,

rateup and level adjustments.

Queue Override Represents those items that can prevent queue override

from occurring if the mainline is extremely congested.

#### **1-5-1 General**

The General Configuration menu displays the items of each metered lane which are fairly general in nature.

METERED LANE	CONFI	GURATI (	ON – GE	ENERAL
Lane	1	2	3	4
Dep Group	Α	Α	С	С
Veh-Per-Green	1	1	1	1
Meter Enabled	YES	YES	YES	YES
Yellow Fail	2.0	2.0	2.0	2. 0
Max Meter Rate	0	0	0	0
Min Meter Rate	0	0	0	0

**Dependency Group** A group to which each metered lane is associated with. Every

lane within a group must start and end metering at the same time. Groups can also incorporate other dependent

functionality such as fixed offset times. The dependency group

can be configured to be group A, B, or C.





**Vehicles-Per-Green** How many vehicles per green light activation are allowed to

pass. The configurable range is 1 to 3 vehicles.

**Meter Enabled** Enables a metered lane. YES means that the lane will meter as

requested. NO means the lane will be prevented from

transitioning from the Pre-Meter Non-Green Interval (DARK)

to the Pre-Meter Green Interval. Note that setting this

configuration item to a value of NO will not turn off a metered lane that is currently metering. It only prevents a metered lane from starting the metering sequence by preventing it from

entering the Pre-Meter Green Interval.

**Yellow Fail** If the status of the Demand Detector shows any error condition

and the Demand Fail Yellow Time is greater than zero then the Demand Yellow Time will be used rather than Yellow Time for the respective Metering Yellow or Shutdown Yellow

interval. If the Demand Fail Yellow Time is set to zero, then no adjustment will be made. The Configurable Range is 0 and 0.5

to 5.0 Seconds in 0.1-second increments.

**Max Meter Rate** Limits the metering rate to meter at a rate equal to or less that

the rate entered. A value of zero (0) will deactivate maximum metering rate limiting. The configurable range is 0 and 240 to

1800 VPH in 1 VPH increments.

**Min Meter Rate** Limits the metering rate to meter at a rate equal to or greater

that the rate entered. A value of zero (0) will deactivate minimum metering rate limiting. The configurable range is 0

and 240 to 1800 VPH in 1 VPH increments.





#### 1-5-2 Metering Startup

The Metering Startup Configuration menu displays those configuration items used by a metered lane during the transition from non-metering to fixed rate or traffic responsive metering.

METERED LAN	IE CONF	I GURATI	ON - S	TARTUP
Lane	1	2	3	4
Min Meter(M)	10	10	10	10
Start Alert	1.0	1. 0	1. 0	1. 0
Start Warn	1.0	1. 0	1. 0	1. 0
Start Green	10.0	10. 0	10.0	10. 0
Start Yellow	4.0	4. 0	4. 0	4. 0
Start Red	2.0	2. 0	2.0	2. 0

**Minimum Meter** The minimum amount of time that once the metered lanes have

started metering the lanes will continue to actively meter. The configurable range is 0 to 60 minutes in 1-minute increments.

**Startup Alert** The length of time to turn on the advanced warning signs prior to

Startup Green Interval. The configurable range is 0 to 60.0

seconds in 0.1-second increments.

The length of time to turn on the Advanced Warning Signs prior **Startup Warning** 

> to the Startup Green Interval. If the value of Startup Warning is set to 0 and the commanded action is traffic responsive metering then the Advance Warning Sign will always be ON, even when the ramp is not actively metering traffic. If the value is greater than 0 then the Advance Warning will be turned OFF when the program is not actively metering. The configurable range is 0 to

60.0 seconds in 0.1-second increments.

**Startup Green** The length of the Startup Green Interval. The configurable range

is 0 to 60.0 seconds in 0.1-second increments.

The length of the Startup Yellow Interval. The configurable **Startup Yellow** 

range is 0 to 10.0 seconds in 0.1-second increments.

The length of the Startup Red Interval. The configurable range is Startup Red

0 to 10.0 seconds in 0.1-second increments.



#### 1-5-3 Metering

The Metering menu displays those configuration items used by a metered lane when actively metering during fixed rate or traffic responsive metering.

METERED LANE	CONFIC	GURATI ON	- METI	ERI NG
Lane	1	2	3	4
Min Green	2.0	2. 0	2.0	2.0
Max Green	3.0	3.0	3. 0	3. 0
Yellow	0.0	0.0	0.0	0. 0
Min Red	2.0	2. 0	2.0	2. 0
Demand Gap	1. 0	1. 0	1. 0	1. 0
Demand Red	3.8	3.8	3.8	3.8

**Minimum Green** The minimum length of the Green Interval. The configurable

range is 1.0 to 5.0 seconds in 0.1-second increments.

**Maximum Green** The maximum length of the Green Interval. The configurable

range is 1.0 to 15.0 seconds in 0.1-second increments.

**Yellow** The length of the Yellow Interval. The configurable range is 0

seconds and 0.5 to 5.0 seconds in 0.1-second increments. A value of zero (0) indicates that the Yellow Interval shall be skipped.

**Minimum Red** The minimum length of the Red Interval. The configurable range

is 1.0 to 15.0 seconds in 0.1-second increments.

**Demand Gap** The length of time that can elapse after the Red Interval has

expired without actuation of the Demand Detector that a vehicle will still be considered to have been over the Demand Detector during the red cycle. The configurable range is 1.0 to 5.0 in 0.1-

second increments.

**Demand Red** The length of time by which the current Red Interval will be

extended if a vehicle has not been detected on the Demand Detector during the normal Red Interval. This is to prevent the metered lane from cycling to green before the vehicle has

actually stopped on over the Demand Detector. The configurable range is 0 and 1.0 to 15.0 in 0.1-second increments. A value of

zero (0) indicates that no time shall be extended.



#### 1-5-4 Metering Shutdown

The Metering Shutdown configuration menu displays those parameters that relate to the transitioning of the metered lane from the metering state to the non-metering state.

	- 31101	DOWN
2	3	4
3. 0	3. 0	3.0
30. 0	30.0	30. 0
0	0	0
4	4	4
NO	NO	NO
	30. 0 0 4	30. 0 30. 0 0 0 4 4

**Shutdown Warning** The length of the Shutdown Warning Interval. This is the

final period during which the Advanced Warning Signs are ON (unless an Advance Warning Time of zero (0) has been selected). The configurable range is 0 to 60 seconds in 0.1-

second increments.

**Post Green** The length of the Post Metering Green Time that shall

occur after the Advance Warning Sign has been turned OFF (unless an Advance Warning Time of zero (0) has been selected). The configurable range is 0 to 60 seconds in

0.1-second increments.

**Shutdown Time** The maximum length of shutdown metering. Shutdown is

metering that is done at a different or shutdown rate. This can be used to clear out metering ramps prior to final metering shutdown. The configurable range is 0 to 60 minutes in 1-minute increments. Normally this value is

zero (0).

**Minimum Non-Meter** The minimum length of the non-metering state. This will

prevent excessive transitioning of the ramp meter between the metering and non-metering states. The configurable

range is 0 to 60 minutes in 1-minute increments.

**Q VS Shutdown** Selects if active metering shall be restricted from

transitioning into the non-metering state if the Queue Flag

is set.





#### 1-5-5 Dependency Groups

The Dependency Groups menu configures how metered lanes associated in a metered lane group will be affected by other lanes in the same metering group.

METERED LANE CO	NFI GURA	TION -	GROUPS
Group	Α	В	C
Signal Serv Mode Grn Offset Time	MUTEX	FI XED 4. 0	FRACT 4.0
Fract Offset Time	4. 0 3. 0	3.0	4. 0 3. 0
Shutdown Gap Time	0. 0	0. 0	0. 0

**Signal Service Mode** Determines the method of inter-dependency between each

metered lane in the dependency group.

The following group modes are available:

**None** There is no dependency between the lanes within this

dependency group.

**Fixed** The start of the Green Interval for any lane will occur

no sooner than configured in the Green Offset Time.

**Fractional** The start of the Green Interval for any lane will occur

no sooner than the calculated value of the number of metered lanes in a group divided by the metering cycle length. At no time, however will the time be less than

the Fractional Offset Time.

**MUTEX** Mutually Exclusive. One and only one lane in the

dependency group shall display green at any given time

while the group is actively metering.

MUTX2 Mutually Exclusive. One and only one lane in the

dependency group shall display green or yellow at any

given time while the group is actively metering.

**Green Offset Time** Used when the controller Signal Service Mode is set to

Fixed Offsets; this item configures the length of time

between the beginnings of successive Green Intervals for





metered lanes. The configurable range is 0.5 to 10.0 in 0.1-second increments.

Fractional Offset Time Used when the controller Signal Service Mode is set to

Fractional Offsets; this item configures the minimum length of time between the beginnings of successive Green Intervals for metered lanes. The configurable range is 0, 0.5

to 5.0 in 0.1-second increments. A value of zero (0) indicates that there is no minimum length of time.

**Shutdown Gap Time** Indicates the length of time between successive actuations

of demand detectors necessary to terminate the shutdown metering. The configurable range is zero (0) to 10.0 in 0.1-

second increments.

#### 1-5-6 Demand Detector

The Demand Configuration menu allows the user to configure the Demand Detector Mode, Maximum Presence Time, No Activity Time, Erratic Count, Dependent Maximum Presence Time and Dependent No Activity Count.

METERED LANE	CONFI GL	JRATI ON	- DEMA	AND
Lane	1	2	3	4
Mode	RECAL	RECAL	ENAB	ENAB
Max Pres (M)	5	5	5	5
No Activity (M)	0	0	0	0
Erratic Cnť (V)	22	22	22	22
Dep Max Pres(S)	10	10	10	10
Dep No Act(V) ´	5	5	5	5

**Mode** The current operating mode of the Demand

Detector. It can be set to either Recalled or

Enabled.

**Enabled** Sets the Demand Detector so that it is ready to detect and will

place a call when a vehicle is present in its detection zone.

**Recalled** Sets the Demand Detector so that it shall constantly place a call,

even without a vehicle being present in its detection zone.



#### Redlk

Allows the user to lock in calls on the Demand Detector anytime the metered lane is in the red state. This can be helpful if the Demand Detector is not as reliable as it should be, but can have the unintended consequence of additional cycling of the metered lane if vehicles do clear entirely off the Demand Detector before the Green Time has expired.

#### **Maximum Presence**

The amount of time that the Demand Detector for a metered lane can be continuously actuated before the metered lane detector status will report a detector status of Maximum Presence Error. The configurable range is 0 to 720 minutes in 1-minute increments. A value of zero (0) will deactivate Maximum Presence monitoring.

#### **No Activity**

The amount of time that the Demand Detector can be continuously non-actuated before the metered lane detector status will report a detector status of No Activity Error. The configurable range is 0 to 720 minutes in 1-minute increments. A value of zero (0) will deactivate No Activity monitoring.

#### **Erratic Count**

The maximum number actuations that the Demand Detector can receive within a 30-second period before setting the lane detector status to a status of Erratic Count Error. The configurable range is 0 to 255 vehicles in 1-vehicle increments. A value of zero (0) will deactivate Erratic Count monitoring.

#### **Dependent Maximum Presence**

The number of seconds that the Demand Detector can be continuously actuated while the Passage Detector has been continuously non-actuated before the metered lane detector status will report a detector status of Maximum Presence Error. The configurable range is 0 to 600 seconds in 1-second increments. A value of zero (0) will deactivate Dependant Maximum Presence monitoring.

#### **Dependent No Activity**

The number of actuations of the Passage Detector that can occur while the Demand Detector has been continuously non-actuated before the



metered lane detector status will report a detector status of No Activity Error. The configurable range is 0 to 30 vehicles in 1-vehicle increments. A value of zero (0) will deactivate Dependant No Activity monitoring.

#### 1-5-7 Passage Detector

The Passage Configuration menu allows the user to configure the Passage Detector Mode, Maximum Presence Time, No Activity Time and the Erratic Count.

Mode

The current operating mode of the Passage Detector. It can be set to either Recalled or Enabled.

**Enabled** Sets the Passage Detector so that it is ready to detect and will place a call when a vehicle is present in its detection zone.

**Recalled** Sets the Passage Detector so that it shall constantly place a call, even without a vehicle being present in its detection zone.

**Maximum Presence** 

The amount of time that Passage Detector for a metered lane can be continuously actuated before the metered lane detector status will report a detector status of Maximum Presence Error. The configurable range is 0 to 720 minutes in 1-minute increments. Setting this parameter to zero (0) will deactivate Maximum Presence monitoring.

**No Activity** 

The amount of time that the Passage Detector can be continuously non-actuated before the metered lane detector status will report a detector status of No Activity Error. The configurable range is 0 to 720 minutes in 1-minute increments. Setting this parameter to zero (0) will deactivate No Activity monitoring.



#### **Erratic Count**

The maximum number actuations that the Passage Detector can receive within a 30-second period before setting the lane detector status to a status of Erratic Count Error. The configurable range is 0 to 255 vehicles in 1-vehicle increments. Setting this parameter to zero (0) will deactivate Erratic Count monitoring.

#### 1-5-8 Queue Usage

The Queue Usage menu allows the user to configure the method by which multiple metered lane queues will interact with each other. For metered lanes that have only a single queue detector the recommended setting is priority (PRIOR).

	METERED	LANE	QUEUE	Usage	
Lane Queue	Usage	1 ADD	2 ADD	3 PRI OR	4 PRI OR

#### **Queue Usage**

Selects the Queue Usage Mode. Additive will add the rates and level adjustments of each individual queue which has its Queue Flag SET into a combined queue rate and level adjustment. Priority will set the rate adjustment of the highest numbered queue (ie. Queue 4 has priority over Queue 3) which has its Queue Flag SET. The allowable parameter settings are Additive or Priority. Note: Queue Fixed Rate Adjustments are ignored when the Queue Usage is set to Additive.

#### 1-5-9 Default Command Source

The Default Command Source menu item sets up the default command source which has the lowest command source level. Note that this configures the same parameters as menu item 5-5, Default Command Source. Essentially this defines what action the controller will take when the controller is powered on or if it is before the first Timebased Control entry for the day. As with any command source there are 3 settable parameters which are Action, Rate, and Plan.



COMMAND SOURCE PRIORITY - DEFAULT

I aneActionRatePlan1Rest in Dark90012Rest in Dark9001

Manual Action is only valid for 6 hours

**Action** The action that you want the controller to take.

The allowable settings are:

**Rest in Green** The meter heads will be set to the green state.

**Rest in Dark** The meter heads will be turned OFF.

**Traffic Responsive** Meter responsively based on the plan number and

current mainline traffic conditions.

**Fixed Rate** The controller will meter at the rate specified

**Emergency Green** The meter heads will immediately be set to green.

If the controller is actively metering, normal

metering shutdown will not occur.

**Rate** The amount of vehicles per hour per lane that will be released. The

configurable range is 240 to 1800 vehicles in 1 VPH increments.

**Plan** The plan number used to determine the amount of mainline traffic

required before actively metering and the release rate. The configurable

plan numbers are 1 to 10.

#### 1-5-A Queue Override

The Queue Override menu allows the user to prevent increasing the Metering Rate due to Queue Override if the mainline lanes are extremely congested. In addition, the user can also select to prevent Queue Override from occurring if the unit is controlled remotely through the communications command source. This can be useful if TMC corridor control software is used such as SWARM.



#### QUEUE OVERRIDE

Critical Flow Limit 1800
Critical Occ Limit 30.5
Critical Speed Limit 40
Override if in Comm Mode NO

Critical Flow Limit If the Mainline Average Flow Rate exceeds this

value the metered lane will be prevented from incorporating queue override adjustment to the current metering rate. A value of zero (0) will inhibit the Mainline Flow Limit from affecting

Queue Adjustment.

**Critical Occupancy Limit** If the Mainline Average Flow Rate exceeds this

value, the metered lane will be prevented from incorporating queue override adjustment to the current metering rate. A value of zero (0) will inhibit the Mainline Occupancy Limit from

affecting Queue Adjustment.

**Critical Occupancy Limit** If the Mainline Average Speed is below this value,

the metered lane will be prevented from

incorporating Queue override Adjustment to the current metering rate. A value of zero (0) will inhibit the Mainline Speed Limit from affecting

Queue Adjustment.

Override if in Comm Mode Selecting YES will prevent Queue Adjustments

from occurring whenever the command source for any metered lane is Communications. Selecting NO

for this parameter will allow the controller to

incorporate local Queue Adjustments even when the

command source is Communications.

#### 1-6 Queue Configuration

The Configuration menu displays the metered lanes configuration menu.





QUEUE CONFIGURATION

1-Queue Standby Flags

2-Q1 Configuration 8-Q3 Configuration 3-Q1 Adjustment 9-Q3 Adjustment

4-Q1 Rates A-Q3 Rates

5-Q2 Configuration B-Q4 Configuration

6-Q2 Adjustment C-Q4 Adjustment

7-Q2 Rates D-Q4 Rates

Queue Standby Flags Represents the general items related to a lane such as

the Lane Group Number.

**Startup** Represents those items which relate to the transition of

the ramp meter from the non-metering state to the

metering state.

**Metering** Represents those items which relate to the timing that

occurs while the controller is actively metering traffic.

**Shutdown** Represents those items which relate to the transition

from the active metering state to the non-metering state.

**Dependency Groups** Represent configuration items that affect ramp metering

groups such as fixed metering offset time or fractional

offset time.

**Demand** Represents the configuration items for the metered lane

Demand Detector.

**Passage** Represents the configuration items for the metered lane

Passage Detector.

Queue Adjustment Limits Represents the method by which Queue Override if

enabled will occur.

**Queue Adjustment Rates** Represents the adjustment rate and levels used for rate,

rateup and level adjustments.

**Queue Override**Represents those items that can prevent queue override

from occurring if the mainline is extremely congested.





#### 1-6-1 Queue Standby

The Queue Standby menu allows the user to configure a queue as a standby queue, which can stop a controller from actively metering when the associated queue flag is set.

	QU	EUE S	TANDBY		
Queue 2 Queue 3	Standby Standby Standby Standby	1 NO NO NO NO	2 NO NO NO NO	3 NO NO NO NO	4 NO NO NO NO

**Queue Standby** 

Selects if the queue is a Standby Queue. If a standby queue is set then a meter which is actively metering will cycle into the standby metering state.

#### 1-6-2 Queue 1 Configuration

The Queue 1 Configuration menu allows the user to configure the method by which the Queue Detection Flag will be set, and how the Queue Detector will look for queue detection errors.

METERED LANE - QUEUE 1 CONFIGURATION							
Lane	1	2	3	4			
Detect Mode C	CCUP	<b>OCCUP</b>	DI SBL	DI SBL			
Max Pres (M)	5	5	5	5			
No Activity (M)	0	0	0	0			
Erratic Cnt(V)	0	0	0	0			
Dep Max Press(S)	0	0	0	0			
Dep No Act(V)	8	8	8	8			

**Detect Mode** 

The detection mode selects the current mode by which the Queue Detection Flag will be set or cleared.

**Disabled** The Queue Flag will always be clear.





**Count** The Queue Flag will be set if the Queue Count is higher than the

Queue Count High Limit. The Queue Flag will be cleared if the

Queue Count is lower than the Queue Count Low Limit.

**Occupancy** The Queue Flag will be set if the Queue Occupancy is higher

than the Queue Occupancy High Limit. The Queue Flag will be

cleared if the Queue Occupancy is lower than the Queue

Occupancy Low Limit.

**Maximum Presence** The amount of time that the Passage Detector for

a metered lane can be continuously actuated before the metered lane detector status will report a detector status of Maximum Presence Error. The

configurable range is 0 to 720 minutes in 1-minute increments. Setting this parameter to Zero

(0) will deactivate Maximum Presence

Monitoring.

**No Activity** The amount of time that the Passage Detector can

be continuously non-actuated before the metered lane detector status will report a detector status of No Activity Error. The configurable range is 0 to 720 minutes in 1-minute increments. Setting this parameter to Zero (0) will deactivate No Activity

Monitoring.

**Erratic Count** The maximum number actuations that the Queue

Detector can receive within a 30-second period before setting the lane detector status to a status of Erratic Count Error. The configurable range is 0 to 255 vehicles in 1-vehicle increments. Setting this parameter to Zero (0) will deactivate Erratic

Count monitoring.

**Dependent Maximum Presence** The number of seconds that the Queue Detector

can be continuously actuated while the Passage Detector has been continuously non-actuated before the metered lane detector status will report a detector status of Maximum Presence Error. The configurable range is 0 to 600 seconds in 1 second increments. Setting this parameter to Zero (0) will deactivate Dependant Maximum Presence

Monitoring.





#### **Dependent No Activity**

The number of actuations of the Passage Detector that can occur while the Queue Detector has been continuously non-actuated before the metered lane detector status will report a detector status of No Activity Error. The configurable range is 0 to 30 vehicles in 1-vehicle increments. Setting this parameter to Zero (0) will deactivate Dependant No Activity Monitoring.

#### 1-6-3 Queue 1 Adjustment Limits

The Queue 1 Adjustment Limits menu allows the user to configure when to set the Queue Detection Flag based on either Queue Occupancy or Queue Counts. In addition, the user can also select the Replacement rate to use if the Queue Adjustment Mode has been set to Fixed.

METERED	LANE	- QUEU	E 1 ADJ	UST
Lane	1	2	3	4
Adjust Mode	Rate	Rate	Fi xed	Fi xed
	40	40	40	40
Len Lwr Lmt	5	5	5	5
		15. 0	25. 0	25. 0
Occ Lwr Lmt		10. 0		10. 0
Replace Rate	600	600	600	600

Adjust Mode The adjustment mode determines how metering rate shall be adjusted if the Queue Flag is set.

**Fixed** The current metering rate will be replaced by the

fixed rate whenever the Queue Flag is set. Note: Fixed rate adjustments are ignored when the Queue Mode is set to Additive (menu 1-6-1).

**Rate Up** The current metering rate will be increased by the

configured amount every time the Queue Flag is set. When the Queue Flag is cleared, the metering rate will return immediately back to the base rate.

**Rate** The current metering rate will be increased by the

configured amount every time the Queue Flag is set. When the Queue Flag is cleared, the metering rate will return incrementally back to the base

rate.



**Level** The current metering level will be increased by

the configured amount every time the Queue Flag

is set. When the Queue Flag is cleared, the

metering rate will return incrementally back to the

base level.

**Length Upper Limit** The number of vehicles stored on the metered lane that,

if exceeded, will set the Queue Flag. This count is obtained by summing the differences between the vehicle counts at the Passage and Queue Detectors over successive calculation intervals. The configurable range

is 0 to 255 vehicles in 1-vehicle increments.

**Length Lower Limit** The lower threshold of vehicles stored. When the

Queue Count is below this number the Queue Flag will be cleared. The configurable range is 0 to 255 vehicles

in 1-vehicle increments.

Occupancy Upper Limit The occupancy of a Queue Detector that, if exceeded,

will set the Queue Flag. The configurable range is 0 to

99.9 percent in 0.1-percent increments.

Occupancy Lower Limit The lower occupancy limit of the Queue Detector that,

when the occupancy drops below will clear the Queue Flag. The configurable range is 0 to 99.9 percent in 0.1-

percent increments.

**Replacement Rate** The metering rate at which the metered lane will be

metered if the Queue Flag has been set and the Queue Adjustment Mode is fixed. The configurable range is

600 to 1800 VPH in 1-VPH increments.

#### 1-6-4 Queue 1 Adjustment Rates

The Queue 1 Adjustment Rates menu allows the user to select how quickly, and by how much to adjust the metering release rate base on both the actual release rate or by adjusting the plan level.



METERED	LANE -	- QUEUE	1 RA	ΓES	
Lane	1	2	3	4	
Adjust Rate	20	0	0	0	
Rate Iterat	5	0	0	0	
Rate Delay	30	30	30	30	
Adjust Level Level Iterat	3	0	0	0	
Level Iterat	3	0	0	0	
Level Delay	30	30	30	30	

### **Adjust Rate**

Indicates the rate by which the current metering rate will be increased if a queue has been detected. The configurable range is 0, 5 to 1800 VPH in 1-VPH increments. A value of zero (0) indicates that no adjustments are made to the current metering rate.

#### **Rate Iteration**

The maximum number of queue override rate adjustments which can be made during the existence of a single queue. The configurable range is 0 to 20 iterations in 1-iteration increments for Queue Detectors. A value of zero (0) indicates that the current metering rate is not increased after a queue has been detected.

### **Rate Delay**

The length of time between successive queue override rate adjustments. The configurable range is 20 to 240 seconds in 1-second increments.

### **Adjust Level**

The number of levels by which the current metering level will be decreased if a queue has been detected. The configurable range is 0 to 5 levels in 1-level increments. A value of zero (0) indicates that no adjustments are made to the current metering level.

#### **Level Iteration**

The maximum number of queue override level adjustments which can be made during the existence of a single queue. The configurable range is 0 to 5 iterations in 1-iteration increments for Queue Detectors. A value of zero (0) indicates that the current metering level is not decreased after a queue has been detected.

#### **Level Delay**

The length of time between successive queue override level adjustments. The configurable range is 20 to 240 seconds in 1-second increments.





### 1-6-5 Queue 2 Configuration

The Queue 2 Configuration menu allows the user to configure the method by which the Queue Detection Flag will be set, and how the Queue Detector will look for queue detection errors.

METERED LANE	– QUE	UE 2 CO	ONFI GUE	RATI ON
Lane	1	2	3	4
Detect Mode (	OCCUP	0CCUP	DI SBL	DISBL
Max Pres (M)	5	5	5	5
No Activity (M)	Ŏ	Ö	Ŏ	Ö
Erratic Cnt(V)	Ŏ	Ö	Ŏ	Ö
Dep Max Press(S)	) 0	Ö	Ŏ	Ö
Dep No Act(V)	, 8	8	8	8
20p 110 7101(1)				•

**Detect Mode**The detection mode selects the current mode by

which the Queue Detection Flag will be set or

cleared.

**Disabled** The Queue Flag will always be clear.

**Count** The Queue Flag will be set if the Queue Count is higher than the

Queue Count High Limit. The Queue Flag will be cleared if the

Queue Count is lower than the Queue Count Low Limit.

**Occupancy** The Queue Flag will be set if the Queue Occupancy is higher

than the Queue Occupancy High Limit. The Queue Flag will be

cleared if the Queue Occupancy is lower than the Queue

Occupancy Low Limit.

Maximum Presence The amount of time that the Passage Detector for

a metered lane can be continuously actuated before the metered lane detector status will report a detector status of Maximum Presence Error. The

configurable range is 0 to 720 minutes in 1-minute increments. Setting this parameter to Zero

(0) will deactivate Maximum Presence

Monitoring.

**No Activity** The amount of time that the Passage Detector can

be continuously non-actuated before the metered lane detector status will report a detector status of No Activity Error. The configurable range is 0 to



720 minutes in 1-minute increments. Setting this parameter to Zero (0) will deactivate No Activity

Monitoring.

**Erratic Count** The maximum number actuations that the Queue

Detector can receive within a 30-second period before setting the lane detector status to a status of Erratic Count Error. The configurable range is 0 to 255 vehicles in 1-vehicle increments. Setting this parameter to Zero (0) will deactivate Erratic

Count monitoring.

**Dependent Maximum Presence** The number of seconds that the Queue Detector

can be continuously actuated while the Passage Detector has been continuously non-actuated before the metered lane detector status will report a detector status of Maximum Presence Error. The configurable range is 0 to 600 seconds in 1 second increments. Setting this parameter to Zero (0) will deactivate Dependant Maximum Presence

Monitoring.

**Dependent No Activity** The number of actuations of the Passage Detector

that can occur while the Queue Detector has been continuously non-actuated before the metered lane detector status will report a detector status of No Activity Error. The configurable range is 0 to 30 vehicles in 1-vehicle increments. Setting this parameter to Zero (0) will deactivate Dependant

No Activity Monitoring.

## 1-6-6 Queue 2 Adjustment Limits

The Queue 2 Adjustment Limits menu allows the user to configure when to set the Queue Detection Flag based on either Queue Occupancy or Queue Counts. In addition, the user can also select the Replacement rate to use if the Queue Adjustment Mode has been set to Fixed.



METERED	LANE	<ul><li>QUEU</li></ul>	E 2 ADJ	UST
Lane	1	2	3	4
Adjust Mode	Rate	Rate	Fi xed	Fi xed
Len Up Lmt	40	40	40	40
Len Lwr Lmt	5	5	5	5
Occ Up Lmt	15.0	15. 0	25. 0	25. 0
Occ Lwr Lmt	10.0	10.0	10. 0	10. 0
Replace Rate	600	600	600	600
•				

Adjust Mode The adjustment mode determines how metering rate

shall be adjusted if the Queue Flag is set.

**Fixed** The current metering rate will be replaced by the

fixed rate whenever the Queue Flag is set. Note: Fixed rate adjustments are ignored when the Queue Mode is set to Additive (menu 1-6-1).

**Rate Up** The current metering rate will be increased by the

configured amount every time the Queue Flag is set. When the Queue Flag is cleared, the metering rate will return immediately back to the base rate.

**Rate** The current metering rate will be increased by the

configured amount every time the Queue Flag is set. When the Queue Flag is cleared, the metering rate will return incrementally back to the base

rate.

**Level** The current metering level will be increased by

the configured amount every time the Queue Flag is set. When the Queue Flag is cleared, the

metering rate will return incrementally back to the

base level.

**Length Upper Limit** The number of vehicles stored on the metered lane that,

if exceeded, will set the Queue Flag. This count is obtained by summing the differences between the vehicle counts at the Passage and Queue Detectors over successive calculation intervals. The configurable range

is 0 to 255 vehicles in 1-vehicle increments.

**Length Lower Limit** The lower threshold of vehicles stored. When the

Queue Count is below this number the Queue Flag will



be cleared. The configurable range is 0 to 255 vehicles

in 1-vehicle increments.

Occupancy Upper Limit The occupancy of a Queue Detector that, if exceeded,

will set the Queue Flag. The configurable range is 0 to

99.9 percent in 0.1-percent increments.

Occupancy Lower Limit The lower occupancy limit of the Queue Detector that,

when the occupancy drops below will clear the Queue Flag. The configurable range is 0 to 99.9 percent in 0.1-

percent increments.

**Replacement Rate** The metering rate at which the metered lane will be

metered if the Queue Flag has been set and the Queue Adjustment Mode is fixed. The configurable range is

600 to 1800 VPH in 1-VPH increments.

### 1-6-7 Queue 2 Adjustment Rates

The Queue 2 Adjustment Rates menu allows the user to select how quickly, and by how much to adjust the metering release rate base on both the actual release rate or by adjusting the plan level.

					_
METERED	LANE	- QUEUE	2 RA	TES	
Lane	1	2	3	4	
Adjust Rate	20	0	0	0	
Rate I terat	5	0	0	0	
Rate Delay	30	30	30	30	
Adiust Level	3	0	0	0	
Level Iterat	3	0	0	0	
Level Delay	30	30	30	30	

**Adjust Rate** Indicates the rate by which the current metering rate will be

increased if a queue has been detected. The configurable range is 0, 5 to 1800 VPH in 1-VPH increments. A value of zero (0) indicates that no adjustments are made to the current metering

rate.

**Rate Iteration** The maximum number of queue override rate adjustments which

can be made during the existence of a single queue. The

configurable range is 0 to 20 iterations in 1-iteration increments



for Queue Detectors. A value of zero (0) indicates that the current metering rate is not increased after a queue has been detected.

**Rate Delay** 

The length of time between successive queue override rate adjustments. The configurable range is 20 to 240 seconds in 1-second increments.

**Adjust Level** 

The number of levels by which the current metering level will be decreased if a queue has been detected. The configurable range is 0 to 5 levels in 1-level increments. A value of zero (0) indicates that no adjustments are made to the current metering level.

**Level Iteration** 

The maximum number of queue override level adjustments which can be made during the existence of a single queue. The configurable range is 0 to 5 iterations in 1-iteration increments for Queue Detectors. A value of zero (0) indicates that the current metering level is not decreased after a queue has been detected.

**Level Delay** 

The length of time between successive queue override level adjustments. The configurable range is 20 to 240 seconds in 1-second increments.

## 1-6-8 Queue 3 Configuration

The Queue 3 Configuration menu allows the user to configure the method by which the Queue Detection Flag will be set, and how the Queue Detector will look for queue detection errors.

METERED LANE	– QUE	EUE 3 CO	ONFI GUE	RATI ON
Lane	1	2	3	4
Detect Mode	OCCUP	OCCUP	DI SBL	DI SBL
Max Pres (M)	5	5	5	5
No Activity (M)	0	0	0	0
Erratic Cnť(V)	0	0	0	0
Dep Max Press(S	) 0	0	0	0
Dep No Act(V)	8	8	8	8
•				

**Detect Mode** 

The detection mode selects the current mode by which the Queue Detection Flag will be set or cleared.



**Disabled** The Queue Flag will always be clear.

**Count** The Queue Flag will be set if the Queue Count is higher than the

Queue Count High Limit. The Queue Flag will be cleared if the

Queue Count is lower than the Queue Count Low Limit.

**Occupancy** The Queue Flag will be set if the Queue Occupancy is higher

than the Queue Occupancy High Limit. The Queue Flag will be

cleared if the Queue Occupancy is lower than the Queue

Occupancy Low Limit.

Maximum Presence The amount of time that the Passage Detector for

a metered lane can be continuously actuated before the metered lane detector status will report

a detector status of Maximum Presence Error. The

configurable range is 0 to 720 minutes in 1-minute increments. Setting this parameter to Zero

(0) will deactivate Maximum Presence

Monitoring.

**No Activity** The amount of time that the Passage Detector can

be continuously non-actuated before the metered lane detector status will report a detector status of No Activity Error. The configurable range is 0 to 720 minutes in 1-minute increments. Setting this parameter to Zero (0) will deactivate No Activity

Monitoring.

**Erratic Count** The maximum number actuations that the Queue

Detector can receive within a 30-second period before setting the lane detector status to a status of Erratic Count Error. The configurable range is 0 to 255 vehicles in 1-vehicle increments. Setting this parameter to Zero (0) will deactivate Erratic

Count monitoring.

**Dependent Maximum Presence** The number of seconds that the Queue Detector

can be continuously actuated while the Passage Detector has been continuously non-actuated before the metered lane detector status will report a detector status of Maximum Presence Error. The configurable range is 0 to 600 seconds in 1 second

increments. Setting this parameter to Zero (0)





will deactivate Dependant Maximum Presence Monitoring.

### **Dependent No Activity**

The number of actuations of the Passage Detector that can occur while the Queue Detector has been continuously non-actuated before the metered lane detector status will report a detector status of No Activity Error. The configurable range is 0 to 30 vehicles in 1-vehicle increments. Setting this parameter to Zero (0) will deactivate Dependant No Activity Monitoring.

### 1-6-9 Queue 3 Adjustment Limits

The Queue 3 Adjustment Limits menu allows the user to configure when to set the Queue Detection Flag based on either Queue Occupancy or Queue Counts. In addition, the user can also select the Replacement rate to use if the Queue Adjustment Mode has been set to Fixed.

LANE ·	- QUEU	E 3 ADJ	UST
1	2	3	4
Rate	Rate	Fi xed	Fi xed
40	40	40	40
5	5	5	5
15. 0	15. 0	25. 0	25. 0
10. 0	10. 0	10. 0	10. 0
600	600	600	600
	1 Rate 40 5 15. 0 10. 0	1 2 Rate Rate 40 40 5 5 15.0 15.0 10.0 10.0	5 5 5 15.0 15.0 25.0 10.0 10.0 10.0

Adjust Mode	The adjustment mode determines how metering rate shall be adjusted if the Queue Flag is set.
Fixed	The current metering rate will be replaced by the fixed rate whenever the Queue Flag is set. Note: Fixed rate adjustments are ignored when the Queue Mode is set to Additive (menu 1-6-1).
Rate Up	The current metering rate will be increased by the configured amount every time the Queue Flag is set. When the Queue Flag is cleared, the metering rate will return immediately back to the base rate.
Rate	The current metering rate will be increased by the configured amount every time the Queue Flag is



set. When the Queue Flag is cleared, the metering rate will return incrementally back to the base

rate.

**Level** The current metering level will be increased by

the configured amount every time the Queue Flag

is set. When the Queue Flag is cleared, the

metering rate will return incrementally back to the

base level.

**Length Upper Limit** The number of vehicles stored on the metered lane that,

if exceeded, will set the Queue Flag. This count is obtained by summing the differences between the vehicle counts at the Passage and Queue Detectors over successive calculation intervals. The configurable range

is 0 to 255 vehicles in 1-vehicle increments.

**Length Lower Limit** The lower threshold of vehicles stored. When the

Queue Count is below this number the Queue Flag will be cleared. The configurable range is 0 to 255 vehicles

in 1-vehicle increments.

**Occupancy Upper Limit** The occupancy of a Queue Detector that, if exceeded,

will set the Queue Flag. The configurable range is 0 to

99.9 percent in 0.1-percent increments.

Occupancy Lower Limit The lower occupancy limit of the Queue Detector that,

when the occupancy drops below will clear the Queue Flag. The configurable range is 0 to 99.9 percent in 0.1-

percent increments.

**Replacement Rate** The metering rate at which the metered lane will be

metered if the Queue Flag has been set and the Queue Adjustment Mode is fixed. The configurable range is

600 to 1800 VPH in 1-VPH increments.

## 1-6-A Queue 3 Adjustment Rates

The Queue 3 Adjustment Rates menu allows the user to select how quickly, and by how much to adjust the metering release rate base on both the actual release rate or by adjusting the plan level.



METERED	LANE -	- QUEUE	3 RA	ΓES	
Lane	1	2	3	4	
Adjust Rate	20	0	0	0	
Rate Iterat	5	0	0	0	
Rate Delay	30	30	30	30	
Adjust Level	3	0	0	0	
Level Iterat	3	0	0	0	
Level Delay	30	30	30	30	

### **Adjust Rate**

Indicates the rate by which the current metering rate will be increased if a queue has been detected. The configurable range is 0, 5 to 1800 VPH in 1-VPH increments. A value of zero (0) indicates that no adjustments are made to the current metering rate.

#### **Rate Iteration**

The maximum number of queue override rate adjustments which can be made during the existence of a single queue. The configurable range is 0 to 20 iterations in 1-iteration increments for Queue Detectors. A value of zero (0) indicates that the current metering rate is not increased after a queue has been detected.

### **Rate Delay**

The length of time between successive queue override rate adjustments. The configurable range is 20 to 240 seconds in 1-second increments.

### **Adjust Level**

The number of levels by which the current metering level will be decreased if a queue has been detected. The configurable range is 0 to 5 levels in 1-level increments. A value of zero (0) indicates that no adjustments are made to the current metering level.

#### **Level Iteration**

The maximum number of queue override level adjustments which can be made during the existence of a single queue. The configurable range is 0 to 5 iterations in 1-iteration increments for Queue Detectors. A value of zero (0) indicates that the current metering level is not decreased after a queue has been detected.

#### **Level Delay**

The length of time between successive queue override level adjustments. The configurable range is 20 to 240 seconds in 1-second increments.



## 1-6-B Queue 4 Configuration

The Queue 4 Configuration menu allows the user to configure the method by which the Queue Detection Flag will be set, and how the Queue Detector will look for queue detection errors.

METERED LANE	– QUI	EUE 4 CO	ONFI GUE	RATI ON
Lane	1	2	3	4
Detect Mode	OCCUP	OCCUP	DI SBL	DI SBL
Max Pres (M)	5	5	5	5
No Activity (M)	0	0	0	0
Erratic Cnt(V)	Ō	Ō	Ō	Ō
Dep Max Press(S	0 (	Ō	Ō	Ō
Dep No Act(V)	´ 8	8	8	8
200 110 110 (1)				

**Detect Mode** The detection mode selects the current mode by

which the Queue Detection Flag will be set or

cleared.

**Disabled** The Queue Flag will always be clear.

Count The Queue Flag will be set if the Queue Count is higher than the

Queue Count High Limit. The Queue Flag will be cleared if the

Queue Count is lower than the Queue Count Low Limit.

Occupancy The Queue Flag will be set if the Queue Occupancy is higher

than the Queue Occupancy High Limit. The Queue Flag will be

cleared if the Queue Occupancy is lower than the Queue

Occupancy Low Limit.

**Maximum Presence** The amount of time that the Passage Detector for

> a metered lane can be continuously actuated before the metered lane detector status will report a detector status of Maximum Presence Error. The

configurable range is 0 to 720 minutes in 1minute increments. Setting this parameter to Zero

(0) will deactivate Maximum Presence

Monitoring.

**No Activity** The amount of time that the Passage Detector can

be continuously non-actuated before the metered lane detector status will report a detector status of



No Activity Error. The configurable range is 0 to 720 minutes in 1-minute increments. Setting this parameter to Zero (0) will deactivate No Activity Monitoring.

**Erratic Count** 

The maximum number actuations that the Queue Detector can receive within a 30-second period before setting the lane detector status to a status of Erratic Count Error. The configurable range is 0 to 255 vehicles in 1-vehicle increments. Setting this parameter to Zero (0) will deactivate Erratic Count monitoring.

**Dependent Maximum Presence** 

The number of seconds that the Queue Detector can be continuously actuated while the Passage Detector has been continuously non-actuated before the metered lane detector status will report a detector status of Maximum Presence Error. The configurable range is 0 to 600 seconds in 1 second increments. Setting this parameter to Zero (0) will deactivate Dependant Maximum Presence Monitoring.

**Dependent No Activity** 

The number of actuations of the Passage Detector that can occur while the Queue Detector has been continuously non-actuated before the metered lane detector status will report a detector status of No Activity Error. The configurable range is 0 to 30 vehicles in 1-vehicle increments. Setting this parameter to Zero (0) will deactivate Dependant No Activity Monitoring.

## 1-6-C Queue 4 Adjustment Limits

The Queue 4 Adjustment Limits menu allows the user to configure when to set the Queue Detection Flag based on either Queue Occupancy or Queue Counts. In addition, the user can also select the Replacement rate to use if the Queue Adjustment Mode has been set to Fixed.



LANE	- QUEU	E 4 ADJ	UST
1	2	3	4
Rate	Rate	Fi xed	Fi xed
40	40	40	40
5	5	5	5
		25. 0	25. 0
10.0	10. 0	10. 0	10. 0
600	600	600	600
	1 Rate 40 5 15.0 10.0	1 2 Rate Rate 40 40 5 5 15.0 15.0 10.0 10.0	Rate Rate Fixed 40 40 40 5 5 5 15.0 15.0 25.0 10.0 10.0 10.0

Adjust Mode The adjustment mode determines how metering rate

shall be adjusted if the Queue Flag is set.

**Fixed** The current metering rate will be replaced by the

fixed rate whenever the Queue Flag is set. Note: Fixed rate adjustments are ignored when the Queue Mode is set to Additive (menu 1-6-1).

**Rate Up** The current metering rate will be increased by the

configured amount every time the Queue Flag is set. When the Queue Flag is cleared, the metering rate will return immediately back to the base rate.

**Rate** The current metering rate will be increased by the

configured amount every time the Queue Flag is set. When the Queue Flag is cleared, the metering rate will return incrementally back to the base

rate.

**Level** The current metering level will be increased by

the configured amount every time the Queue Flag is set. When the Queue Flag is cleared, the

metering rate will return incrementally back to the

base level.

**Length Upper Limit** The number of vehicles stored on the metered lane that,

if exceeded, will set the Queue Flag. This count is obtained by summing the differences between the vehicle counts at the Passage and Queue Detectors over successive calculation intervals. The configurable range

is 0 to 255 vehicles in 1-vehicle increments.

**Length Lower Limit** The lower threshold of vehicles stored. When the

Queue Count is below this number the Queue Flag will



be cleared. The configurable range is 0 to 255 vehicles

in 1-vehicle increments.

Occupancy Upper Limit The occupancy of a Queue Detector that, if exceeded,

will set the Queue Flag. The configurable range is 0 to

99.9 percent in 0.1-percent increments.

Occupancy Lower Limit The lower occupancy limit of the Queue Detector that,

when the occupancy drops below will clear the Queue Flag. The configurable range is 0 to 99.9 percent in 0.1-

percent increments.

**Replacement Rate** The metering rate at which the metered lane will be

metered if the Queue Flag has been set and the Queue Adjustment Mode is fixed. The configurable range is

600 to 1800 VPH in 1-VPH increments.

### 1-6-D Queue 4 Adjustment Rates

The Queue 4 Adjustment Rates menu allows the user to select how quickly, and by how much to adjust the metering release rate base on both the actual release rate or by adjusting the plan level.

	METERED	LANE	- QUEUE	4 RA	TES	
Lane		1	2	3	4	
Adj ust	Rate	20	0	0	0	
Rate It	erat	5	0	0	0	
Rate De	el ay	30	30	30	30	
Adi ust	Level	3	0	0	0	
Level I	terat	3	0	0	0	
Level D	el ay	30	30	30	30	
	•					

**Adjust Rate** Indicates the rate by which the current metering rate will be

increased if a queue has been detected. The configurable range is 0, 5 to 1800 VPH in 1-VPH increments. A value of zero (0) indicates that no adjustments are made to the current metering

rate.

**Rate Iteration** The maximum number of queue override rate adjustments which

can be made during the existence of a single queue. The

configurable range is 0 to 20 iterations in 1-iteration increments



for Queue Detectors. A value of zero (0) indicates that the current metering rate is not increased after a queue has been

detected.

**Rate Delay** The length of time between successive queue override rate

adjustments. The configurable range is 20 to 240 seconds in 1-

second increments.

**Adjust Level** The number of levels by which the current metering level will be

decreased if a queue has been detected. The configurable range is 0 to 5 levels in 1-level increments. A value of zero (0) indicates that no adjustments are made to the current metering level.

**Level Iteration** The maximum number of queue override level adjustments

which can be made during the existence of a single queue. The configurable range is 0 to 5 iterations in 1-iteration increments for Queue Detectors. A value of zero (0) indicates that the current metering level is not decreased after a queue has been

detected.

**Level Delay** The length of time between successive queue override level

adjustments. The configurable range is 20 to 240 seconds in 1-

second increments.



### 2. Mainline Lanes

The mainline detector stations are used to gather data of freeway traffic conditions. The flow rate, average speed and occupancy for each individual lane are calculated. The mainline station averages are then calculated from the individual lane data for each lane that has a current detector status of "working" and has not been configured as an HOV lane.

URMS supports 2 directional mainline detection stations named Mainline and Opposite Mainline. The Mainline and Opposite Mainline each support a maximum of 8 lanes of detection. Although the URMS can support up to 8 mainline and 8 opposite mainline lanes, only the number of lane configured will be displayed. The number of mainline and opposite mainline lanes are configured in menu item 8-7, "Configure Ramp I/O".

### MAINLINE LANES

1-Mainline Lanes 2-Opposite Mainline Lanes

### 2-1 Mainline Lanes

#### MAINLINE LANES

- 1-Stati sti cs
- 2-Detection
- 3-Detector Status
- 4-Car Counts
- 5-Confi gurati on

The menu areas are:

**Statistics** Displays the mainline volume, occupancy and speed statistics

for the last 30-second calculation interval.

**Detection** Displays the current activation status of each mainline detector.

**Detector Status** Displays the current working status of each mainline detector.

Car Counts Display the number of actuations of the mainline detector since

the controller was turned on or the car counts were reset to zero

(0).

Configuration Allows users to configure the mainline lane detectors.

### 2-1-1 Statistics

The Mainline Data Statistics menu displays the current lane volume, occupancy and speed for each mainline lane during the last 30 second calculation interval. Although only 4 mainline lanes are shown in this example, the URMS is configurable for up to 8 mainline lanes. Please note that if more than 4 Mainline lanes are configured you will need to scroll down to the higher number lanes by pressing the down arrow on the front panel.

LANE		NLI NE 30 : EADI NG OCC%		DATA ILING OCC%	SPEED
1DH	5	12. 4	6	12. 5	54
2D	4	15. 3	4	15. 5	54
3D	3	14. 5	3	14. 4	56
4D	7	13. 6	7	13. 7	62
Vol ume	6	0ccupano	by 14.	5% Sp	beed 58

Lane Descriptor Shown directly after the lane number these letters show the current lane mode. In addition if a lane is configured as a HOV lane a second lane descriptor will also be shown. Current lane descriptors are:

L - Leading

T - Trailing

D - Dual

P - Preprocessed

X - Disabled

**H-HOV Lane** 

Volume Represents then number of vehicles that have passed over the

detector during the last 30-second calculation interval.



**Occupancy** Represents the percentage of time that a vehicle has been over the

detector during the last 30-second calculation interval.

**Speed** Represents the average vehicle speed during the last 30-second

calculation interval.

The last line represents the cumulative statistics for all of the lanes, except for those lanes that have been designated as an active HOV lane.

## **2-1-2 Mainline Detection**

The Mainline Detection menu displays current detector status of both the lead and the trail mainline detectors. A dot ( . ) represents a de-actuated/OFF state, an asterisk ( \* ) represents an actuated/ON state and a (P) indicated that the detector is configured to receive preprocessed data.

MAINLINE DETECTION											
LANE LEAD TRAI L	1 ·	2 *	3 *	4 ·	5	6	<b>7</b> ∵∗	8 P P			

### **Note:**

Only mainline lanes can use preprocessed data

## **2-1-3 Detector Status**

The Mainline Detector Status menu displays the current operational status of each of the mainline detectors.

MAINLINE DETECTOR STATUS										
LANE	1	2	3	4	5	6	7	8		
LEAD	Ŵ	W	Ŵ	MP	Ŵ	Ŵ	Ď	Ď		
TRAI L	Ŵ	W	ΕĊ		W		Ď	Ď		
LANE	Ŵ	W	PF	TF		Ŵ	Ď	Ď		
W-Workir		)i sa				tic (	Count	t		
MP-Max F		No Ac			-					
TF-Total Failure					Parti			ıre		
I lotai		<b></b> 0		• • •	ti	<b>ч.</b> .	٠. · ·	J		



Due to limitations in space the following abbreviations are used in the display of the current mainline detector status:

Working [W] Indicates that this detector currently appears to be

working normally.

Represents that the detector has been configured to be Disabled [D]

in a continuous de-actuated or OFF state.

Maximum Presence [MP] The input on the mainline detector has been

continuously actuated for longer than the configured

Maximum Presence threshold.

No Activity [NA] The number of minutes between detector actuations is

greater than the number of minutes according to the

following criteria:

a. No detected actuations for more than 26 minutes when the average mainline volume is less than

200 vehicles per hour.

b. No detected actuations for more than the number of minutes calculated using the formula '(Average

Mainline Flow Rate in vehicles per hour / -40) + 31' when the average mainline volume is between

200 and 1200 vehicles per hour.

c. No detected actuations for more than one minute when the average mainline volume is greater than

1200 vehicles per hour.

**Erratic Count [EC]** The number of vehicle counts read by the detector has

exceeded the configured Erratic Count Threshold

during the last 30-secondcalculation interval.

Partial Failure [PF] Indicates that a single detector of a dual loop

detection zone has failed.

Note: During partial failure speed calculations will

revert from dual detection zone speed trap

calculations to single detector speed

calculations.



**Total Failure [TF]** 

Indicates that all detectors in the lane have failed.

### 2-1-4 Car Counts

The Car Counts menu shows how many vehicles have traveled over a detection loop since the controller was powered on or the car counts were reset. Only 7 digits of data will be shown.

	MAI NLI NE	LANES	
Lane 1: Lane 2: Lane 3: Lane 4:	43533 43553	Lane 5: Lane 6: Lane 7: Lane 8:	48212 51124 51453 53525

#### Note:

Car Counts can be cleared using menu 9-C (clear car counts)

## 2-1-5 Configuration

The Mainline Configuration menu allows the use to configure up to 8 mainline lanes although .only 6 lanes are shown in this example. The actual number of lanes shown is configured in the Number of Mainline Lanes parameter (menu item 8-7).

MAI NL	INE LANES
1-Mainline 1	5-Mainline 5
2-Mainline 2	6-Mainline 6
3-Mainline 3	7-Mainline 7
4-Mainline 4	8-Mainline 8

## 2-1-5-X Configuration

The Mainline Configuration menu allows a user to configure each mainline lane detector.



MAINLINE X	CONFI GL	JRATI ON	
Lane Mode	LEAD	Threshol	ds
Lead Zone Length	6. 0	MAX	5
Trail Zone Length	6. 0	Erratic	22
Speed Trap Length	20.0		
Typ Vehicle Length	15. 0		
HŐV Lane	NO		
Speed Trap Length Typ Vehicle Length HOV Lane REV Lane	NO		

The configurable parameters are:

**Lane Mode** Configures the current operating mode of the mainline lane

for detection.

**Disabled** Configures both the leading and the trailing detector to be

disabled.

**Lead** Configures the leading detector to be enabled and the

trailing detector to disabled.

**Trail** Configures the trailing detector to be enabled and the

leading detector to disabled.

**Dual** Configures both the leading and trailing detectors to both

be enabled.

**Pre-Proc** Configures both the leading and trailing detectors to

preprocessed data mode. This allows the lane to use other external sensors such as G3 and G4 RADARs to provide

preprocessed lane data.

**Lead Zone Length** Configure the detection zone length of the leading detector.

The configurable range is 0 to 15.0 feet in 0.1 foot

increments.

**Trail Zone Length** Configures the detection zone length of the trailing detector.

The configurable range is 0 to 15.0 feet in 0.1 foot

increments.

**Speed Trap Length** Used for dual loop speed calculations, configures the distance

between the leading edge of the leading mainline detector to



the leading edge of the trailing mainline detector. The configurable range is 0 to 45.0 feet in 0.1 foot increments.

**Type Vehicle Length** Used with leading or trailing loop configurations, configures

the length of a typical vehicle, which is used for mainline

lane speed estimation with a single detector. The

configurable range is 0 to 45.0 feet in 0.1-foot increments. A

value of zero (0) shall inhibit speed estimation.

**HOV Lane** Configures the lane as an HOV lane. It can be configured to

be either YES or NO.

**REV Lane** Configures the lane as a reversible lane. It can be configured

to be either YES or NO.

**MAX Threshold** Selects the maximum threshold time that a mainline lane

detector can be continuously actuated before the Maximum Presence Error is set. The configurable range is 0 to 720 minutes in 1-minute increments. A value of zero (0) shall

inhibit the maximum presence testing.

**Erratic Count** Sets the vehicle erratic count threshold which if exceeded

will put the detector into an Erratic Count Error. The configurable range is 0 to 255 vehicles in 1-vehicle

increments. A value of zero (0) shall inhibit the erratic count

testing.

## 2-1-6 Mainline Direction

The Mainline Direction screen will show the direction of the traffic when the lane is designated as a reversible lane. The menu will show a (F) when the traffic is moving in the forward direction and a (R) when the traffic is moving in the reverse direction.

The logic is based on determining whether a pair of mainline detectors was activated within a certain cutoff time and if so, in what direction they were activated. 2.727 seconds was chosen as the cutoff time as this is the time it takes for a vehicle traveling at 5 MPH to go from one detector to the other detector when the two detectors are spaced 20 feet apart. If the time between detections is longer than this cutoff time, then it is unlikely that any single vehicle activated both loops of the dual loop set.

The calculate lane direction the following algorithm is used:

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**Leading Loop Activated** If the trailing loop was activated within the last 2.727 seconds

then subtract one to the lane direction count down to a

minimum of -8.

**Trailing Loop Activated** If leading loop was activated within the last 2.727 seconds then

add one to the lane direction count up to a maximum of 8.

**Lane Direction = Forward** If Lane Direction count has a value of -2 to 8.

**Lane Direction = Reverse** If Lane Direction count has a value of -3 to -8.

MAINLINE DIRECTION

Lane 1 2 3 4 5 6 7 8
DIR F F F F F F F

## **2-2 Opposite Mainline Lanes**

### OPPOSITE MAINLINE LANES

1-Stati sti cs

2-Detection

3-Detector Status

4-Car Counts

5-Confi gurati on

The menu areas are:

**Statistics** Displays the opposite mainline volume, occupancy and speed

statistics for the last 30-second calculation interval.

**Detection** Displays the current activation status of each opposite mainline

loop detector.



**Detector Status** Displays the current working status of each opposite mainline

loop detector.

**Car Counts** Display the number of actuations of the mainline detector since

the controller was turned on or the car counts were reset to zero

(0).

**Configuration** Allows users to configure the opposite mainline lane detectors.

### **2-2-1 Statistics**

The Opposite Mainline Data Statistics menu displays the current lane volume, occupancy and speed for each opposite mainline lane over the last 30-second calculation interval. Although only 4 mainline lanes are shown in this example, the URMS is configurable for up to 8 mainline lanes. Please note that if more the 4 Opposite Mainline lanes are configured you will need to scroll down to the higher number lanes by pressing the down arrow on the front panel.

ΛPI	IT I200	E MAINLINE	30 5	ECOND D	ΔΤΔ
LANE		EADI NG		I LI NG	SPEED
	VOL	OCC%	VOL	OCC%	
1LH	5	12. 4	6	12. 5	54
2L	4	15. 3	4	15. 5	54
3T	3	14. 5	3	14. 4	56
4T	7	13. 6	7	13. 7	62
Vol ume	6	0ccupand	y 14.	5% Sp	beed 58

**Lane Descriptor** Shown directly after the lane number these letters show the current lane mode. In addition if a lane is configured as a HOV lane a second lane descriptor will also be shown. Current lane descriptors are:

L - Leading

T - Trailing

D - Dual

X - Disabled

H - HOV Lane

**Volume** Represents then number of vehicles that have passed over the

detector during the last 30-second calculation interval.



**Occupancy** Represents the percentage of time that a vehicle has been over the

detector during the last 30-second calculation interval.

**Speed** Represents the average vehicle speed during the last 30-second

calculation interval.

### **2-2-2 Detection**

The Opposite Mainline Detection menu displays current detector status of both the lead and the trail mainline detectors. A dot (.) represents a de-actuated/OFF state while an asterisk (\*) represents an actuated/ON state.

OPPOSI	TE M	AI NL	I NE I	DETE	CTI O	N	
1	2	3	4	5	6	7	8
•	•	*	*	•	•	•	•
	1	1 2	1 2 3	1 2 3 4	1 2 3 4 5	1 2 3 4 5 6	* *

## **2-2-3 Detector Status**

The Opposite Mainline Detector Status menu displays the current operational status of each of the mainline detectors.

0PP0S	I TE I	MAI NI	LI NE	DET	ECTO	R ST	ATUS	
LANE	1	2	3	4	5	6	7	8
LEAD	W	W	W	W	W	W	W	W
TRAI L	W	W	W	W	W	W	W	W
STATUS	W		W	W	W	W	W	W
W-Worki n	g D-[	)i sak	ol ed	EC-I	Errat	tic (	Count	ţ
W-Working D-Disabled EC-Erratic Count MP-Max Presence NA-No Activity								
TF-Total	Fai I	ure		PF-F	Parti	al F	FaĬΙι	ıre

Due to limitations in the size of the front panel the following abbreviations are used for opposite mainline status.

**Working** [W] Indicates that this detector currently appears to be

working normally.

**Disabled [D]** Represents that the detector has been configured to be

in a continuous de-actuated or OFF state.

**Maximum Presence [MP]** The input on the opposite mainline detector has been

continuously actuated for longer than the configured

Maximum Presence threshold.

**No Activity [NA]** The number of minutes between detector actuations is

greater than the number of minutes according to the

following criteria:

a. No detected actuations for more than 26 minutes when the average opposite mainline volume is

less than 200 vehicles per hour.

d. No detected actuations for more than the number of minutes calculated using the formula '(Average Opposite Mainline Flow Rate in vehicles per hour

(-40) + 31 when the average mainline volume is

between 200 and 1200 vehicles per hour.

b. No detected actuations for more than one minute when the average opposite mainline volume is

greater than 1200 vehicles per hour.

**Erratic Count [EC]** The number of vehicle counts read by the detector has

exceeded the configured Erratic Count Threshold

during the last 30-second calculation interval.

Partial Failure [PF] Indicates that a single detector of a dual loop

detection zone has failed.

Note: During partial failure speed calculations will

revert from dual detection zone speed trap

calculations to single detector speed

calculations.

**Total Failure [TF]** Indicates that all detectors in the lane have failed.

### 2-1-4 Car Counts



The Car Counts menu shows how many cars have traveled over a detection loop since the controller was powered on or the car counts were reset. Only 7 digits of data will be shown.

	ОP	POSI TE	MAI NLI NE	LANE	S	
Lane Lane	2: 3:	43414 43533 43553 53134	Lane Lane Lane Lane	6: 7:	48212 51124 53423 55212	

#### **Note:**

Car Counts can be cleared using menu 9-C (clear car counts)

### **2-2-5 Configuration**

The Opposite Mainline Configuration menu allows the user to configure each opposite mainline lane detector. The actual number of lanes shown is configured in the Number of Opposite Mainline Lanes parameter (menu item 8-7).

OPPOSITE MA	AINLINE LANES
1-0pp Mainline 1	5-Opp Mainline 5
2-0pp Mainline 2	6-Opp Mainline 6
3-0pp Mainline 3	7-Opp Mainline 7
4-0pp Mainline 4	8-Opp Mainline 8

## 2-2-5-X Configuration

The Opposite Mainline Configuration menu allows a user to configure each opposite mainline lane detector

OPPOSITE MAINLIN	IE X COI	NFI GURATI C	N
Lane Mode	LEAD	Threshol	ds
Lead Zone Length	6. 0	MAX	5
Trail Zone Length	6. 0	Erratic	22
Speed Trap Length	20.0		
Speed Trap Length Typ Vehicle Length HOV Lane REV Lane	18. 0		
HÔV Lane	NO		
REV Lane	NO		

The configurable parameters are:

**Lane Mode** Configures the current operating mode of the opposite

mainline lane for detection.

**Disabled** Configures both the leading and the trailing detector to be

disabled.

**Lead** Configures the leading detector to be enabled and the

trailing detector to disabled.

**Trail** Configures the trailing detector to be enabled and the

leading detector to disabled.

**Dual** Configures both the leading and trailing detectors to both

be enabled.

**Lead Zone Length** Configure the detection zone length of the leading detector.

The configurable range is 0 to 15.0 feet in 0.1 foot

increments.

**Trail Zone Length** Configures the detection zone length of the trailing detector.

The configurable range is 0 to 15.0 feet in 0.1 foot

increments.

**Speed Trap Length** Used for dual loop speed calculations, configures the distance

between the leading edge of the leading opposite mainline detector to the leading edge of the trailing opposite mainline detector. The configurable range is 0 to 45.0 feet in 0.1 foot

increments.

**Type Vehicle Length** Used with leading or trailing loop configurations, configures

the length of a typical vehicle in 0.1 foot increments, which is

used for opposite mainline lane speed estimation with a



single detector. The configurable range is 0 to 45.0 feet in 0.1-foot increments. A value of zero (0) shall inhibit speed

estimation.

**HOV Lane** Configures the lane as an HOV lane. It can be selected to be

either YES or NO.

**REV Lane** Configures the lane as a reversible lane. It can be configured

to be either YES or NO.

MAX Threshold Selects the maximum threshold time that an opposite

mainline lane detector can be continuously actuated before the Maximum Presence Error is set. The configurable range is 0 to 720 minutes in 1-minute increments. A value of zero

(0) shall inhibit the maximum presence testing.

**Erratic Count** Sets the vehicle erratic count threshold which if exceeded

will put the detector into an Erratic Count Error. The configurable range is 0 to 255 vehicles in 1-vehicle per lane increments. A value of zero (0) shall inhibit the erratic count

testing.

## **2-2-6 Opposite Mainline Direction**

The Opposite Mainline Direction screen will show the direction of the traffic when the lane is designated as a reversible lane. The menu will show a (F) when the traffic is moving in the forward direction and a (R) when the traffic is moving in the reverse direction.

The logic is based on determining whether a pair of mainline detectors was activated within a certain cutoff time and if so, in what direction they were activated. 2.727 seconds was chosen as the cutoff time as this is the time it takes for a vehicle traveling at 5 MPH to go from one detector to the other detector when the two detectors are spaced 20 feet apart. If the time between detections is longer than this cutoff time, then it is unlikely that any single vehicle activated both loops of the dual loop set.

The calculate lane direction the following algorithm is used:

**Leading Loop Activated** If the trailing loop was activated within the last 2.727 seconds

then subtract one to the lane direction count down to a

minimum of -8.

**Trailing Loop Activated** If leading loop was activated within the last 2.727 seconds then

add one to the lane direction count up to a maximum of 8.



**Lane Direction = Forward** If Lane Direction count has a value of -2 to 8.

**Lane Direction = Reverse** If Lane Direction count has a value of -3 to -8.

	OPF	POSI	TE M	AI NL	DI RECTI ON				
Lane DI R	1 F	2 F	3 F	4 F	5 F	6 F	7 F	8 F	



## 3. Additional Detection

Additional Detection is used to collect detector data at off ramps or at other locations where occupancy and volume detection is needed.

#### Additional Detection

1-Stati sti cs

2-Detection

3-Detector Status

4-Car Counts

5-Confi gurati on

The menu areas are:

**Statistics** Displays the additional detector volume and occupancy for the

last 30-second calculation interval.

**Detection** Displays the current activation status of each detector.

**Detector Status** Displays the current working status of each detector.

**Car Counts** Display the number of cars that have crossed over the detector

since the controller was turned on.

**Configuration** Allows users to configure additional detectors.

### **3-1 Additional Detection Statistics**

The Additional Detection Statistics menu shows volume and occupancy percentage. Although only 6 additional detectors are shown in this example, the URMS is configurable for up to 16 additional detection locations. Please note that if there are more than 6 additional detectors configured pressing the down arrow key will allow the user to scroll down to the higher numbered locations.



Addi	ti onal	Detecti on	_	30	Second	Data
Lane	Vol	OCC%				
1	5	12. 4				
2	6	15. 3				
3	3	14. 5				
4	7	13. 6				
5	6	13. 5				
6	4	12. 5				

**Volume** Represents then number of vehicles that have passed over the

detector during the last 30-second calculation interval.

**Occupancy** Represents the percentage of time that vehicles have been over

the detector during the last 30-second calculation interval.

## **3-2 Additional Detection**

The Additional Detection menu shows if a detector is currently actuated. An asterisk (\*) represents an actuated state while a dot (.) represents a de-actuated state.

	Α	DDI T	I ONA	L DE	TECT	I ON	
1	2	3	4	5	6	7	8
•	•	•	•	•	•	•	•
9	10	11	12	13	14	15	16
•	•	•	•	•	•	•	•

## **3-3 Additional Detector Status**

The Additional Detector Status menu shows the current status of the additional detector. Reference the table below for a list of detector abbreviations:



	AD	DI TI	ONAL	DET	ЕСТО	R ST	ATUS	
1 W	2 W	3 W	4 D	5 W	6 W	7 D	8 D	
9 W	10 W	11 W	12 D	13 W	14 W	15 D	16 D	

Working [W] Indicates that this detector currently appears to be

working normally.

**Disabled [D]** Represents the detector has been configured to be in a

continuous de-actuated or OFF state.

**Maximum Presence [MP]** The input on the opposite mainline detector has been

continuously actuated for longer than the configured

Maximum Presence threshold.

**No Activity [NA]** The number of minutes between detector actuations is

greater than the configured No Activity Time.

**Erratic Count [EC]** The number of vehicle counts on the detector has

exceeded the configured Erratic Count Limit during

the last 30-second calculation interval.

## **3-4 Additional Detector Car Counts**

The Additional Detector Car Count menu shows the current amount of vehicles that have traveled over the detector since the controller was powered on or the car counts were reset:

	ADDTI	TI ON	AL DI	ETE	CTOR	CAR CC	UNTS	5
DET DET DET DET DET DET	2 3 4 2 5	0 43 45 34 83 23	DET DET DET DET DET DET	8 9 10 11	83	DET DET DET DET	14 15	302 60 45 49

### **Note:**

Car Counts can be cleared using menu 9-C (clear car counts)





### 3-5 Additional Detector Configuration

The Additional Detector Configuration menu shows how many additional detectors can be configured.

	<b>ONAL DETECTOR</b>	CONFI GURATI ON	
1-Det 1	7-Det 7	D-Det 13	
2-Det 2	8-Det 8	E-Det 14	
3-Det 3	9-Det 9	F-Det 15	
4-Det 4	A-Det 10	0-Det 16	
5-Det 5	B-Det 11		
6-Det 6	C-Det 12		

## **Additional Detector Configuration (3-5-X)**

Lane Mode

The Additional Detection Configuration menu allows the user to enable or disable the detectors as well as allowing the user to select error threshold levels.

ADDITIONAL DETECT	OR XX CONFIGURATION
Lane Mode	ENABLED
No Activity	2
Max Presence	10
Erratic Count	22

No Activity

The amount of time that an additional detector can be continuously non-actuated before the metered lane detector status will report a detector status of No Activity Error. The configurable range is 0 to 720 in 1-minute increments. Setting this

parameter to zero (0) will deactivate No Activity

Select whether the lane detector is enabled or

Monitoring.



#### **Maximum Presence**

The amount of time that an additional detector can be continuously actuated before the detector status will report a detector status of Maximum Presence Error. The configurable range is 0 to 720 minutes in 1-minute increments. Setting this parameter to zero (0) will deactivate Maximum Presence Monitoring.

#### **Erratic Count**

The vehicle count on the additional detector for a metered lane exceeded a pre-determined threshold. The configurable range is 0 to 255 vehicles in vehicle increments. Setting this parameter to zero (0) will deactivate Erratic Count Monitoring.



# 4. Traffic Responsive Metering Plans

## **4-1 Metering Plan Tables**

The Metering Plan Tables menu displays the total number of plans available that may be configured. This screen is view only and cannot be configured from the front panel.

2-Pl an 2 3-Pl an 3 4-Pl an 4	IETERING PLAN TABLES 7-Plan 7 8-Plan 8 9-Plan 9 A-Plan 10 B-Quickset Plan
-------------------------------------	------------------------------------------------------------------------------------------

## 4-1-X Metering Plan

The Metering Plan menu display allows the user to configure the metering plan's release rate and the occupancy, volume and speed thresholds. A total of 15 (1-15) levels are available and may be configured from the front panel. Levels 7 - 15 can be displayed by pressing the down arrow key on the front panel.

The metering rate for each metered lane will be determined by comparing the mainline traffic to the occupancy, volume and speed thresholds. The rates for each of these items will be compared and the most restrictive (rate with the highest level) will be used to select the metering rate.

When using a plan with traffic responsive metering, active metering will begin when mainline traffic exceeds level 2 and active metering will end when the current mainline traffic is lower than level 1.



TRAF	FIC RESP	ONSIVE ME	TERING P	LAN 2
LEVEL	RATE	OCC%	VOL	SPEED
1	900	10. 0	1000	60
2 3	850	15. 0	1100	55
3	800	20. 0	1300	50
4	750	25. 0	1400	45
5	700	0. 0	1700	40
6	650	0. 0	1800	35

The metering rate for each metered lane. The configurable **Metering Rate** 

range is 150 to 1800 vehicles in 1-VPH increments.

**Occupancy Threshold** The percentage of time that a detection zone was occupied.

Entering a value of zero (0) will cause the program to skip

that entry.

Volume Threshold The number of vehicles per lane per hour. Entering a value

of zero (0) will cause the program to skip that entry.

**Speed Threshold** Represents the average speed of a vehicle in miles per hour.

Entering a value of zero (0) will cause the program to skip

that entry.

#### 4-1-B Quick Plan

The Quick Plan menu display allows the user to quickly create a metering plan based on the linear interpolation of the minimum and maximum metering release rates and thresholds.

	QUI CKSE	T PLAN		
PLAN 1	MAX	Levels 12		
Rate	MIN 240	MAX 900		
0ccupancy	MIN 5.0	MAX 30.0		
Vol ume	MIN 1000	MAX 2000		
Speed	MIN O	MAX O		
·				
ENTER DATA				

Plan The Plan Number that you would like to modify

**Max Levels** The Number of Plan Levels that you would like to use. All

plan levels greater than the selected number will have the



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rate set to the maximum rate, and the Occupancy, Volume

and Speed Thresholds set to zero.

**Rate** The minimum and maximum Release Rates.

**Occupancy** The minimum and maximum Occupancy Thresholds.

**Volume** The minimum and maximum Volume Thresholds.

**Speed** The minimum and maximum Speed Thresholds.

Enter Data Has two modes, Enter Data and Set Data. The default mode

Enter Data allows the user to enter the Metering Plan Number, Number of Plan Levels, Release Rate and

Minimum and Maximum Thresholds. The Set Data mode, which can be selected by using the '+' (PLUS) key and pressing 'ENTER' will cause the program to immediately generate the selected plan using the entered parameters.

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## 5. Command Source

The Command Source menu allows the user to view or configure the command source that is currently requesting command of the controller. The currently supported command sources, listed in order of precedence, are Manual, Communications, Interconnect, Time Base Control, and Default.

#### COMMAND SOURCE

1-Manual

2-Communi cati ons

3-Interconnect

4-Timebase Control

5-Defaul t

The menu areas are:

Manual Control is from the front panel at the local controller.

**Communications** Control is from the TMC or other remote

communications device.

Not used at this time. Reserved for future use. Interconnect

Timebase Control Control request based on the Time-of-Day Entries and

Timebased Control Tables (menu item 6).

**Default** What the controller will do when all other command

sources are skip. This is what the controller will do first

when powered up or re-booted.

### 5-1 Manual

The Manual command source has the highest command priority. Any lane command other than skip will override any other command source. There are 3 settable parameters Action, Rate, and Plan for each metered lane.



COMMAND SOURCE PRIORITY - MANUAL

 I ane
 Action
 Rate
 PI an

 1
 SKIP
 900
 1

 2
 SKIP
 900
 1

**Action** The action that you want the controller to take.

The allowable settings are:

**Rest in Green** The meter heads will be set to the green state.

**Rest in Dark** The meter heads will be turned OFF.

**Traffic Responsive** Meter responsively based on the plan number and

current mainline traffic conditions.

**Fixed Rate** The controller will meter at the rate specified.

**Emergency Green** The meter heads will immediately be set to green.

If the controller is actively metering, normal

metering shutdown will not occur.

**Skip** The controller will skip to the next lower (default)

command source.

**Rate** The amount of vehicles per hour per lane that will be released. The

configurable range is 150 to 1800 vehicles in 1 VPH increments.

**Plan** The plan number used to determine the amount of mainline traffic

required before actively metering and the release rate. The configurable

plan numbers are 1 to 10.



#### **5-2 Communications**

The Communications command source menu has the second highest priority. It can only be overridden by the Manual Command Source. The communications parameters are only settable from the TMC or other remote communications facility. The 3 viewable parameters are the current Communications Action, Rate, and Plan.

COMMAND	SOURCE PRIORIT	Y-COMMUNI	CATI ONS
Lane	Action	Rate	PI an
1	Traffic Resp	900	1
2	Traffic Resp	900	1

#### **5-3 Interconnect**

The Interconnect command source has not been implemented in URMS at this time. It is only included in the menu structure for future expandability.

COMMAND SOURCE PRIORITY-INTERCONNECT			
I ane	Acti on	Rate	PI an
1	Ski p	900	1
2	Ski p	900	1

### **5-4 Timebase Control**

The Timebase Control command source priority is the second lowest command source. Its Actions, Rate and Plan Number are set by the time of day and control tables listed under main menu item 6 (Time-of-Day). The 3 viewable parameters are the current Timebased Control Action, Rate, and Plan.



COMMAND	SOURCE	PRI ORI	TY-TI MEBASE	CTRL
I ane 1 2	Action Traffic Traffic	Resp Resp	Rate 900 900	PI an 1 1

### **5-5 Default**

The Default Command Source has the lowest command source level. It can be overridden by any other command source. Essentially this defines what action the controller will take when the controller is powered on or if it is before the first Timebased Control entry for the day. There are 3 settable parameters which are Action, Rate, and Plan.

COM	MAND SOURCE PRIC	ORITY – D	EFAULT
I ane	Action	Rate	PI an
1	Rest in Dark	900	1
2	Rest in Dark	900	1

**Action** The action that you want the controller to take.

The allowable settings are:

**Rest in Green** The meter heads will be set to the green state.

**Rest in Dark** The meter heads will be turned OFF.

**Traffic Responsive** Meter responsively based on the plan number and

current mainline traffic conditions.

**Fixed Rate** The controller will meter at the rate specified

**Emergency Green** The meter heads will immediately be set to green.

If the controller is actively metering, normal

metering shutdown will not occur.

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**Rate** The amount of vehicles per hour per lane that will be released. The configurable range is 150 to 1800 vehicles in 1 VPH increments.

Plan The plan number used to determine the amount of mainline traffic required before actively metering and the release rate. The configurable plan numbers are 1 to 10.



### 6. Time-of-Day

#### **Time-of-Day Functions**

The Time-of-Day functions indicate allow the user to set the clock, set up day-of-week entries, time based control tables and set fixed and floating holidays.

#### TIME-OF-DAY FUNCTIONS

1-TOD Clock

2-Day of Week Entry 3-Timebased Control Tables 4-Fixed Holidays

5-Floating Holidays

The menu areas are:

**TOD Clock** Allows the user to set the controller date, time, and

allows them to enable or disable Daylight Savings Time

Correction.

**Day-of-Week Entry** Allow the user to select a particular Time Based

Control Table at a certain time of day and day of the

week.

**Timebased Control Tables** When selected in the day-of-week entry, allows the user

to set the action, rate and plan of the controller using

the Timebased Command Source.

**Fixed Holidays** Allows users to set fixed holidays.

**Floating Holidays** Allows users to configure floating holidays.

#### 6-1 Set TOD Clock

The Set TOD Clock menu allows you to modify the current time and date. It also allows the user to select whether or not the Daylight Savings Time Adjustments will be made internally in the controller.



TIME-OF-DAY CLOCK

TIME 02: 14: 41 DATE 01/22/2000 DAY SATURDAY

Daylight Saving: ON

#### Note:

If the current day has been configured to be either a floating or fixed holiday then the day of the week will show "HOLIDAY"

**Time** The current controller time using a 24-hour clock or military

time.

**Date** The current controller date in the form of MM/DD/YYYY.

**Daylight Saving** Selecting ON will have the controller internally make the

adjustment. Selecting OFF will disable the controller from

making Daylight Savings adjustments.

### 6-2 Day-of-Week Entry

The Day-of-Week Entry menu allows you to set the time ramp metering is to be activated any given day during the week. HOV lanes can be activated by choosing YES or deactivated by choosing NO. There are 24 Day-of-Week entries. Use the down arrow to access entries 6 though 24.

# Start	DAY OF WEEK	C ENTRY Table	HOV
Ti me 1 <08: 00> 2 00: 00 3 00: 00 4 00: 00 5 00: 00	SMTWTFSH . MTWTFS MTWTFS MTWTFS MTWTFS.	16 0 0 0	Active YES YES YES YES YES

**Start Time** Determines the time that this plan will start.



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**DOW** 

DOW selects the days of the week that this plan will operate. Using the numeric keypad the Day of the Week selections are:

- 1 Sunday
- 2 Monday
- 3 Tuesday
- 4 Wednesday
- 5 Thursday
- 6 Friday
- 7 Saturday
- 8 Any fixed or floating holiday

**Table** 

Determines which of the 16 Time of Day tables will be used to get the controllers Timebase Control Action, Rate and Plan. Setting the table number to zero (0) will disable the Timebase Control Entry.

HOV

Selects whether or not mainline lanes configured as HOV lanes will be used in traffic responsive calculations. Selecting YES will activate HOV lanes and they will not be included in the calculations. Selecting NO will deactivate the HOV lanes and all HOV lanes will be included in the mainline traffic responsive calculations.

#### **6-3 Timebase Control Tables**

The Timebase Control Tables menu allows the user to select any one of the 16 Timebase Control Tables. Each individual table contains Action, Rate and Plan entries for Timebase Controlled metering operation. Tables are selected in the Day-of-Week Entry menu (6-2).

	TOD TABLES	
1-Tabl e 1 2-Tabl e 2 3-Tabl e 3 4-Tabl e 4 5-Tabl e 5 6-Tabl e 6	7-Tabl e 7 8-Tabl e 8 9-Tabl e 9 A-Tabl e 10 B-Tabl e 11	C-Tabl e 12 D-Tabl e 13 E-Tabl e 14 F-Tabl e 15 O-Tabl e 16

#### 6-3-X Time-of-Day Table





Each of the 16 Time of Day tables tell the controller the Action (command), Rate (for fixed rate metering), and Plan (for traffic responsive metering) for each metered lane. In addition, each table allows you to enable or disable any of the 8 General Purpose outputs.

l ane 1 2	TIME-OF-DAY TABLE X Action Rate <traffic resp=""> 900 Traffic Resp 900</traffic>	PI an 1 1
Pr	ress NEXT to view GP Outp	uts

**Action** The action that you want the controller to take.

The allowable settings are:

**Rest in Green** The meter heads will be set to the green metering

state.

**Rest in Dark** The meter heads will be turned OFF.

**Traffic Responsive** Meter responsively based on the plan number and

current mainline traffic conditions.

**Fixed Rate** The controller will meter at the rate specified.

**Emergency Green** The meter heads will immediately be set to green.

If the metered lane is actively metering, normal

metering shutdown will not occur.

**Skip** The controller will skip to the next lower (default)

command source.

**Rate** The amount of vehicles per hour per lane that will be released. The

configurable range is 240 to 1800 VPH in 1-VPH increments..

**Plan** The plan number used to determine the amount of mainline traffic

required before actively metering and the release rate. The configurable

plan numbers are 1 to 10.



Selecting 'Next' will allow the user to configure the General Purpose Outputs. Each General Purpose Output can be turned ON or OFF.

TIME-OF-DA	Y TABLE X	
GP Output #1<0FF> GP Output #2 OFF GP Output #3 OFF GP Output #4 OFF	GP Output #5 GP Output #6 GP Output #7 GP Output #8 OF	FF
Press NEXT to retur	n to previous page	<b>e</b>

#### Note:

If the number of metered lanes is equal to zero (0), only the General Purpose Outputs menu will be shown when the Time-of-Day Tables are selected.

### **6-4 Fixed Holidays**

The Fixed Holidays menu allows you to configure holidays that occur on a specific date every year. There are a maximum of 12 entries. Use the down arrow to scroll down to view entries 7 through 12.

	FI XED	HOLI DAY	
Number	Month	Day	DOW
1	JAN	1	. MTWTF.
2	JAN	12	. MTWTF.
3	MAR	31	. MTWTF.
4	JUL	4	. MTWTF.
5	NOV	11	. MTWTF.
6	DEC	25	. MTWTF.
	220		

**Month** The month in which the holiday occurs.

The Selectable months are.

 $NC-Not\ Configured-Disable\ this\ Entry$ 

JAN-January

FEB – February

MAR -March

APR – April



MAY - May

JUN – June

JUL - July

AUG – August

SEP – September

OCT - October

NOV – November

DEC - December

**Day** The day-of-month on which the holiday occurs.

DOW

The day-of-week on which the holiday occurs. Note that if Saturday is NOT selected and the holiday occurs on a Saturday, the holiday will be observed on the previous Friday. Likewise, if Sunday is NOT selected and the holiday falls on a Sunday the holiday will be observed on the following Monday. The selectable day-of-week options are:

The selectable Day of Week options are:

- 1 Sunday
- 2 Monday
- 3 Tuesday
- 4 Wednesday
- 5 Thursday
- 6 Friday
- 7 Saturday

### **6-5 Floating Holidays**

The Floating Holidays menu allows the user to configure holidays that do not occur on a specific date, but rather occur on a specific month, week and day-of-week. For example Martin Luther King Jr. Day always occurs on the 3<sup>rd</sup> Monday in January. There are a maximum of 12 entries. Use the down arrow to scroll down to entries 7 through 12.

FLOATING HOLIDAY				
Number	Month	Week	Day	
1	JAN	3	MONĎAY	
2	FEB	3	MONDAY	
3	MAY	5	MONDAY	
4	SEP	1	MONDAY	
5	OCT	2	FRI DAY	
6	NOV	3	THURSDAY	



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**Month** The month in which the holiday occurs.

The selectable months are.

NC – Not Configured – Disable this Entry

JAN – January

FEB - February

MAR -March

APR - April

MAY - May

JUN - June

JUL – July

AUG - August

SEP – September

OCT - October

NOV – November

DEC - December

Week The week-of-month that this holiday occurs. If a holiday occurs in the

last week of the month select 5.

**Day** The day-of-week that this holiday occurs.

The selectable days are:

- 1 Sunday
- 2 Monday
- 3 Tuesday
- 4 Wednesday
- 5 Thursday
- 6 Friday
- 7 Saturday



### 7. Communications

The Communications menu allows the URMS to be configured to communicate with the TMC and other remote locations using 2/4 wire modems, RS-232, or TCP/IP communications architecture.

#### COMMUNICATIONS PARAMETERS

1-SP 1 Parameters 6-TCP Port 1 TX/RX 2-SP 2 Parameters 7-TCP Port 2 TX/RX 3-TCP Parameters 8-UDP Parameters

4-SP 1 TX/RX 9-SENSYS

5-SP 2 TX/RX

If config is changed-Reboot Controller

The menu areas are:

**SP 1 Parameters** Configure the communications parameters of serial port

1.

**SP 2 Parameters** Configure the communications parameters of serial port

2.

**TCP Poll Parameters** Configure the communications parameters of the

Ethernet port.

**SP 1 TX/RX** Displays the current hexadecimal packet information

for serial port 1.

SP 2 TX/RX Displays the current hexadecimal packet information

for serial port 2.

TCP Port 1 TX/RX Displays the current hexadecimal packet information

for Ethernet on TCP port number 1.

TCP Port 2 TX/RX Displays the current hexadecimal packet information

for Ethernet on TCP port number 2.

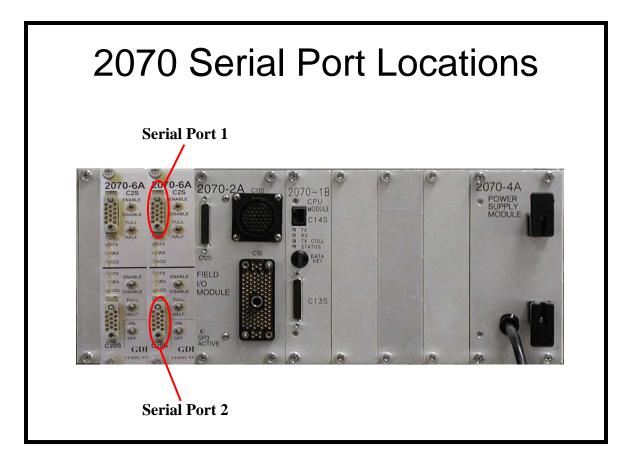
**UDP Parameters** Configure the Controller ID and the IP Address and

Port number to broadcast UDP transmissions to.



**SENSYS** 

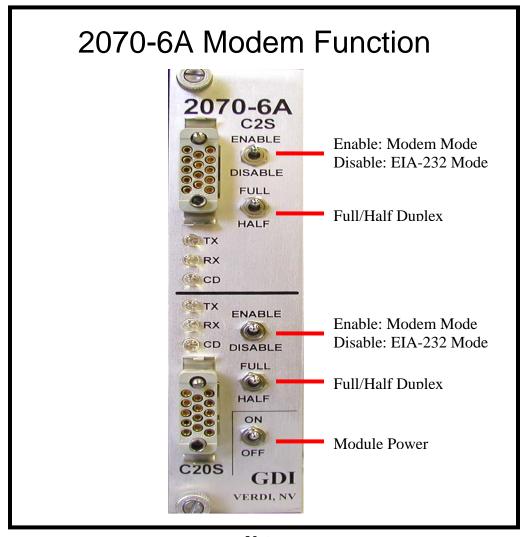
Configure the Controller ID and the IP Address and Port number to receive from Sensys access points.



#### Note:

Serial Port 1 is the upper channel of the module installed in the Model 2070 Slot A2 (the second slot from the left). Serial Port 2 is the lower channel of the module installed in the Model 2070 Slot A2. Although in the picture above a 2070-6A card is used, the 2070-6B (9600 baud modem) and the 2070-7A (RS-232 Serial) can also be used in Slot A2.



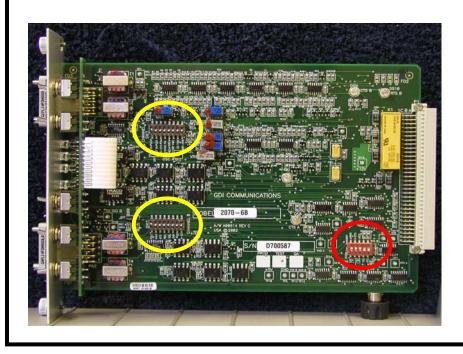


#### **Note:**

Set the modem to the Enabled mode for Modem Operation and Disabled for EIA-232 Operations. Also ensure that the Duplex Switch is set to FULL and the Modem Power Switch is set to ON.



# GDI 2070-6A Modem Dip Switches



#### **Note:**

These settings apply to GDI Model 2070-6A Modems ONLY.

The recommended settings for the DIP switches circled in Yellow (upper and lower left) are:

1-Full Duplex	OFF (Default)
2-Half Duplex	OFF (Default)
3-RTS/CTS Time	OFF (Default)
4-Soft Carrier Time	OFF (Default)
5-Half Duplex Local Echo	OFF for 4 wire operation (Default),
	ON for 2 wire operation

OFF (Default)

6-Rec. Squelch Time 7-Carrier Detect Time OFF (Default)

8-Auto-Streaming Enable ON (Default is OFF)

The recommended settings for the DIP switches (circled in Red – lower right) used for inverting the backplane RS-485 polarity signals are:

1-RXD	ON (Default)
2-CTS	ON (Default)
3-DCD	ON (Default)
4-TXD	OFF (Default)
5-RTS	OFF (Default)





#### **7-1 SP 1 Parameters**

Serial Port 1 Parameters allows the user to configure the Baud Rate, Data Bits, Parity, RTS On and OFF time, Handshaking and Address (drop number).

	SFRI AL	PORT 1	
Address	1	. •	
Baud Rate	1200	Handshake	NONE
Data Bits	8	Enabl ed	YES
Pari ty	NONE		
Stop Bits	1		
Stop Bits RTS On Time	10	(milliseconds	)
RTS Off Time	0	(milliseconds	5
		<u> </u>	•

**Address** The controller drop number.

**Baud Rate** 1200, 2400, 4800, 9600, 19200 or 38400.

**Data Bits** 5, 6, 7 or 8 Data Bits.

**Parity** None, Even or Odd.

**Stop Bits** 1 or 2.

**RTS ON Time** The amount of time the Request to Send signal will be activated

BEFORE the first byte of the response packet is transmitted. This is needed by 2- and 4-wire modem systems to set carrier frequency prior to beginning transmission of a response packet. For 4-wire modem communications, the recommended time is 20 milliseconds; for 2-wire modem communications, the recommended time is 30

milliseconds.

**RTS OFF** The amount of time the Request to Send signal will remain activated

AFTER the last byte of the response packet has been transmitted. This may be needed if packet is being truncated. Typically, this

value is set to zero.

**Handshaking** None, Manual, Auto CTS, Auto RTS, Full Auto and Dynamic. The

recommended setting is None.



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**Enabled** The current operating mode of the serial port. It can be set to either

YES if the serial port in enabled or NO if the serial port in not

enabled.

#### **7-2 SP 2 Parameters**

Just like Serial Port 1, Serial Port 2 Parameters allows the user to configure the Baud Rate, Data Bits, Parity, RTS On and Off time, Handshaking and the Address.

	SERI AL	PORT 2	
Address Baud Rate	2 1200	Handshake	NONE
Data Bits	8	Enabl ed	YES
Pari ty	NONE		
Stop Bits RTS On Time	10	(milliseconds	)
RTS Off Time	0	(milliseconds	)

**Address** The controller drop number.

**Baud Rate** 1200, 2400, 4800, 9600, 19200 or 38400.

**Data Bits** 5, 6, 7 or 8 Data Bits.

**Parity** None, Even or Odd.

**Stop Bits** 1 or 2.

**RTS ON Time** The amount of time the Request to Send signal will be activated

BEFORE the first byte of the response packet is transmitted. This is needed by 2- and 4-wire modem systems to set carrier frequency prior to beginning transmission of a response packet. For 4-wire modem communications, the recommended time is 20 milliseconds; for 2-wire modem communications, the recommended time is 30

milliseconds.

**RTS OFF** The amount of time the Request to Send signal will remain activated

AFTER the last byte of the response packet has been transmitted. This may be needed if packet is being truncated. Typically, this

value is set to zero.

**Handshaking** None, Manual, Auto CTS, Auto RTS, Full Auto and Dynamic. The

recommended setting is None.



**Enabled** The current operating mode of the serial port. It can be set to either

YES if the serial port in enabled or NO if the serial port in not

enabled.

### **7-3 TCP Port Parameters**

TCP Port Parameters allows the user to configure the TCP Port Number, Address and other TCP/IP configuration information.

TCP Parameters
Address 12
Port #1 2101 Port #2 10011
Connection Type STATIC
IP Address XXX. XXX. XXX. XXX
Netmask XXX. XXX. XXX. XXX
Broadcast XXX. XXX. XXX. XXX
Gateway XXX. XXX. XXX. XXX

**Address** This is the controller drop number.

**Port #1** The TCP port number that the remote communications device

would like to connect to. This port is general used for normal

TMC Polling.

Port #2 This second TCP port number is used for remote configuration

of the URMS from a TMC or other remote facility.

**Connection Type** Static or Dynamic. Use Static for Fixed IP addresses. Use

Dynamic for an IP address assigned through another device

through DHCP.

**IP Address** The Internet Protocol Address assigned to the controller.

**Subnet Mask** Together with the IP address defines what network this

controller belongs to.

**Broadcast Address** The broadcast address is an IP address with the same network-

part as your network, but with only ones as host-part. Every

host on your network listens to this IP address. It is meant for

broadcasting packets.

**Default Gateway** A network point that acts as an entrance to another network

point.

### 7-4 SP 1 TX/RX

Serial port 1 packet data shows the current packet data in hexadecimal that has been received by the controller. If the type of message is known to the controller and the address is correct, the controller will display the known packet type, and depending on the packet received will transmit a response.

SERIAL PORT 1 PACKET DATA
RX:

TX:

Packet Type: UNKNOWN

The current packet types to which URMS will respond to are:

SDRMS Zero Poll

**SDRMS** Normal Poll

SDRMS Opposite Side Poll

SDRMS Get

**SDRMS Set** 

**SDRMS** Reset

SATMS Poll

SATMS Get

**SATMS Set** 

SATMS Set Time

TOS Get Data

TOS Get Time

TOS Set Time

TOS Set HAR EMS

### 7-5 SP 2 TX/RX

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Serial port 2 packet data shows the current packet data in hexadecimal that has been received by the controller. If the packet type is known to the controller and the address is correct, the controller will also display the known packet type, and depending on the packet received will transmit a response.

SERI AL PORT 2 PACKET DATA RX: 7E014309210D060A0400C57E

TX: 7E014300667E

Packet Type: TOS SET TIME

#### 7-6 TCP Port 1 TX/RX

TCP Port 1 TX/RX shows the TCP Port 1 current packet data in hexadecimal that has been received by the controller on TCP port 1. If the type of message is known to the controller and the address is correct, the controller will display the known packet type, and depending on the packet received will transmit a response.

TCP PORT 1 PACKET DATA

RX: 6103000C70AA55

Packet Type: SDRMS NORMAL POLL



#### 7-7 TCP Port 2 TX/RX

TCP Port 2 TX/RX shows the TCP Port 2 current packet data in hexadecimal that has been received by the controller on the TCP port 2. If the type of message is known to the controller and the address is correct, the controller will display the known packet type, and depending on the packet received will transmit a response.

TCP PORT 2 PACKET DATA

RX: 6103000C70AA55

Packet Type: SDRMS NORMAL POLL

### **7-8 UDP Port 1 Parameters**

UDP Port parameters allows the user to configure the controller ID and IP Address and Port number to broadcast to is a UDP broadcast is selected under menu item 8-5 preferred comm. Protocol.

**UDP Parameters** 

Controller ID 21341 Port Number 2000 UDP Address 192.168.010.001

**Controller ID** An identifying identification number send as part of certain

UDP data transmissions in order to allow the central system to

identify which controller has transmitted data.

**Port Number** This UDP port number that we would like to transmit UDP

data to.



**UDP Address** The remote UDP Address that you would like to transmit UDP

data to.

### **7-9 Sensys Parameters**

Sensys parameters allows the user to configure the port, IP address and enables the user to configure the system to actively receive Sensys data.

#### **SENSYS Parameters**

Port Number 2000 Sensys IP Address 192.168.010.001 Actively Poll Sensys NO

**Port Number** This UDP port number that we would like to receive UDP

Sensys data transitions from.

**Sensys IP Address** The remote UDP Address that you would like to Sensys

UDP Sensys data transitions from.

**Actively Poll Sensys** Selects whether or not we want to receive Sensys data. Yes

means that the URMS will accept Sensys data. No means

that the URMS will not accept Sensys data.



### 8. General

General allows the user to configure and view the physical configuration of the URMS as well as both the Failsafe Feedback Inputs and Traffic Responsive Interval.

#### GENERAL ITEMS MENU

1-Input File Layout

2-Output File Layout

3-AUX Output File Layout 4-General Purpose Output ON/OFF Times

5-Other Items

6-Traffic Responsive Interval

7-Configure Ramp 1/0

The menu areas are:

**Input File Layout** View the physical layout of the input file slots 1

to 14.

**Output File Layout** View the physical layout of the output file slots

1 to 3.

**Aux Output File Layout** View the physical layout of the auxiliary output

file slots 9 to 14.

**General Purpose Outputs** Configure the ON and OFF times that the

General Purpose output will use when the

output is enabled.

**Other Items** Configure failsafe input, occupancy correction

and enable/disable flashing of the WARN01

advance warning sign.

Configure the number of 30-second periods to **Traffic Responsive Interval** 

> use for averaging mainline data for traffic responsive calculations. From 1 to 8 30-second

Calculation Intervals may be selected.

**Configure Ramp I/O** Configure the I/O configuration from one of a

> number of predetermine I/O layouts. Also allows the user to set the number of Metered,



Mainline, Opposite Mainline, Additional Detectors and the method by which the controller performs traffic responsive metering.

### **8-1 Input File Layout**

The Input File screen shows the current assignments for slots 1-14 of the input file. If the controller is not currently metering, then the user can also modify the input assigned to an input file position. Note that modifying any input will cause the controller I/O configuration type to be changed to custom. Also note that pressing the "NEXT" key will allow the user to toggle between I file and J file inputs.

1 D P	-	2 Q1 F1	I FI 3 NC NC	LE IN 4 NC NC	NPUTS 5 ML1 ML2	6 ML3 ML4	7 ML5 ML6
	IC	9 NC NC	10 NC NC	11 NC NC	12 D2 P2	13 Q2 F2	14 D3 P3

# **Note:** Select next to configure the J file inputs

Because of limitation in the size of the front panel the following abbreviations are used on this screen.

NC	Input is not configured
MLn	Mainline lane n Leading detector
MTn	Mainline lane n Trailing detector
OLn	Opposite mainline lane n Leading detector
OTn	Opposite mainline lane n Trailing detector
Fn	Additional Detector number n
Pn	Metered lane n Passage detector
Qn	Metered lane n Queue detector
Dn	Metered lane n Demand detector
NC	Input is not configured for use
RCn	Rate Code Input n
252	Failsafe Feedback Input



### **8-2 Output File**

The Output File screen shows the current assignments for slots 1 - 3 of PDA3. If the controller is not currently metering, then the user can also modify the output assigned to an output file position. Note that modifying any output will cause the controller I/O configuration type to be changed to custom.

	OUTPUTS FILE	
R Y G	1 2 3 LGRN1 RED1 RED2 WARN1A YEL1 YEL2 LGRN2 GRN1 GRN2	

Because of limitation in the size of the front panel the following abbreviations are used on this screen.

NC	Outputs is Not Configured
LGRNn	Metered Lane n Lower Green output
GRNn	Metered Lane n Green output
YELn	Metered Lane n Yellow output
REDn	Metered Lane n Red output
WARN01	Meter ON Warning Sign Solid – Non-Flashing/Flashing -
	Global
WARN02	Meter ON Warning Sign Non-Flashing/Flashing - Global
WARN03	Meter ON Warning Sign Flashing - Global
WARN04	Meter ON Warning Sign Alternate Flashing - Global
WARNA1	Meter ON Warning Sign Non-Flashing – Dependency Group A
WARNA2	Meter ON Warning Sign Flashing – Dependency Group A
WARNA3	Meter ON Warning Sign Alternate Flashing – Dependency
	Group A
WARNB1	Meter ON Warning Sign Non-Flashing – Dependency Group B
WARNB2	Meter ON Warning Sign Flashing – Dependency Group B
WARNB3	Meter ON Warning Sign Alternate Flashing – Dependency
	Group B
WARNC1	Meter ON Warning Sign Non-Flashing – Dependency Group C
WARNC2	Meter ON Warning Sign Flashing – Dependency Group C
WARNC3	Meter ON Warning Sign Alternate Flashing – Dependency
	Group C



**GPn** General Purpose Output number n

**RCn** Rate Code n

#### **8-3 Aux Output File Layout**

The Aux Output File screen shows the current output assignments for slots 9-14 of the Model 402 Auxiliary Output File. If the controller is not currently metering, then the user can also modify the output assigned to an output file position. Note that modifying any output will cause the controller I/O configuration type to be changed to custom.

		AU	X OUTPU	JTS FI	LE		
R Y G	9 NC NC NC	10 RED3 YEL3 GRN3	11 NC NC LGRN3	12 NC NC NC	13 NC NC NC	14 NC NC NC	

### **8-4 General Purpose Output ON/OFF Times**

General purpose ON and OFF times allow you to control how the General Purpose outputs will be illuminated when activated. If either the ON or the OFF time is set to zero, the device when activated will illuminate solid. If both the ON and the OFF times are set to non-zero times, the device will flash using the configured ON and OFF times. The maximum duration of each of the ON and the OFF time is 5.0 seconds.

GENERAI	PURPOSE	OUTPUT ON	OFF TH	MFS
OEITEI (				
	ON OFF		ON	OFF
GP OUT #1	0.0 0.0	GP OUT	<i>#</i> 5 0.0	0.0
GP OUT #2		GP OUT	#O U.U	0.0
GP OUT #3	0.0 0.0	GP OUT	#7 O O	0.0
GP OUT #4	0.0 0.0	GP OUT	#8 U.U	0.0

### **8-5 Other Items**



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Other items contains allows the user to configure several items of a general/global nature in the URMS software.

OTHER ITEMS		
Flash WARNO1 Occupancy Correction Failsafe Feedback Enabled Reset Detectors at Met Start Preferred Comm Protocol Reboot if loss of Comm	YES RAW NO NO SDRMS NO	·

Flash WARN01 Allow the user to have the Global Advance Warning Sign

WARN01 to either be in a flashing or solid state when enabled. No will set the WARN01 output to solid, while conversely yes will set the warning sign output to flashing

when enabled.

Occupancy Correction Occupancy correction in not used at this time. It is

included for future use.

**Failsafe Feedback Enabled** In certain ramp meter locations, it may be unsafe to meter

traffic if certain advisory signs or other devices fail. If YES is selected for the failsafe feedback input and the input fails, ramp metering will be terminated within 5 seconds, a command source of error (displayed as ERR) will be shown and all of the metering outputs will be turned OFF. Next to the failsafe input is an indication of the current status of the input with a '\*' meaning the input is currently ON, and a '.' meaning the input is currently OFF. The controller will not enable any outputs until either the input is restored or the selection is changed from YES to NO. Also note that if the failsafe feedback has not been configured to an actual URMS input, URMS will not consider the lack of input

actuation a failure even if feedback is enabled.

**Reset Detectors at Meter Start** In certain ramp meter locations, there are a large number of

callouts for detectors locking up. When set to YES, the URMS will send out a 500 millisecond pulse on the detector reset output whenever the metering location transitions from a non-metering state to a metering state.





When set to NO, no detector reset pulse will be set during metering transition.

#### **Preferred Comm Protocol**

We set the preferred communication protocol that the URMS shall use. This can be especially useful when different protocols utilize the same request for data packet. When more than one response type is possible for a received packet request, the URMS will respond with the preferred protocol.

#### Reboot if loss of Comm

Loss of communications is deemed to occur if the communications refresh time has expired. Setting this parameter to YES will cause to controller to re-boot up to 6 times if a loss of communications occurs. For safety reasons the controller will only re-boot if all of the following conditions are true:

- 1. The controller has commanded action of Dark for all metered lanes.
- 2. The controller is currently in the Pre-Metering Non-Green or EMS Standby Interval for all metered lanes.
- 3. The manual command source is set to Skip for all metered lanes.

Setting the parameter to NO will cause the controller to take no automatic action if a loss of communications occurs.

### 8-6 Traffic Responsive Calculation Interval

The URMS calculates Traffic Responsive Data over multiple 30-second calculations intervals (number of averaging periods) in order to provide data smoothing and reduce the likelihood of the controller cycling. You can select between 1 to 8 averaging periods to calculate the traffic responsive average volume, occupancy and speed.



#### TRAFFIC RESPONSIVE CALULATION INTERVAL

Number of 30 second intervals to Smooth traffic response calculations

6

#### **8-7 Physical I/O Configuration**

Physical I/O configuration allows a controller to have its inputs and outputs configured in order to support a wide variety of ramp metering configurations used statewide.

Please note that for safety, the physical I/O configuration can not be changed while the controller is actively metering. If you do select this item the following warning screen will appear.

#### PHYSICAL I/O CONFIGURATION

CAN NOT CHANGE I/O CONFIGURATION WHILE CONTROLLER IS METERING

To stop the controller metering go to Menu 5-1 and select DARK for each lane Press Any Key View Configuration

After pressing any key the Physical I/O Configuration View menu will be displayed.

PHYSICAL I/O CONFIGURATION	- VIEW ONLY
SUNRI SE_AND_50	
Ramp I/O Configuration	SDRMS
Number of Metered Lanes	2
Number of Mainline Lanes	4
Number of Opposite Lanes	0
Number of Ramps	2
Number of Ramps Traffic Responsive Mode	GREEN
•	



If the C-1 connector is NOT connected then the following configuration screen will be displayed

PHYSICAL I/O CONFIGURATION		
Ramp I/O Configuration	SDRMS	
Ramp I/O Configuration Number of Metered Lanes	2	
Number of Mainline Lanes	4	
Number of Opposite Lanes	0	
Number of Ramps	2	
Traffic Responsive Mode	GREEN	
Press Next to Change Control	ler Name	

The first item is Ramp I/O Configuration code which allows the user to select a specific URMS configuration. A table of the current URMS configurations is shown in Appendix B.

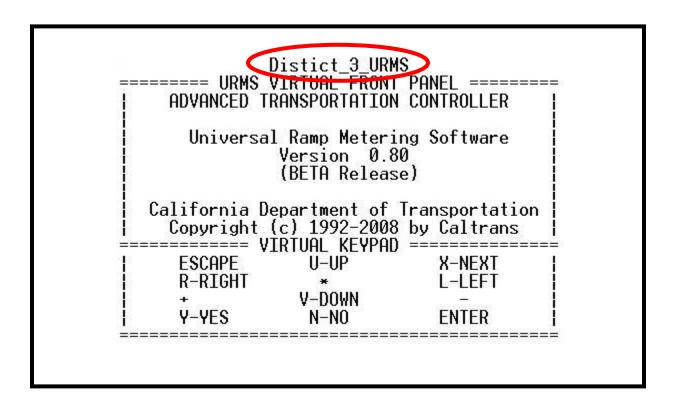
Also selectable is the number of Metered Lanes, Mainline Lanes, Opposite Mainline Lanes, and additional Ramp Metering locations that the user needs to use for this particular location.

For example if the user selects a configuration of SDRMS then there is support in the physical I/O of that configuration for up to 3 Metered Lanes, however the user may select that only one lane is used.

Also on this page is the traffic responsive mode which is selectable as either Green or Dark. This is the state that the signal heads will be set to when running traffic responsive metering and the controller is not actively metering due to low mainline traffic.

Last if you want to change the controller virtual front panel name (circled in red below) you change it from the next screen:





The controller virtual name lets the user be able to enter a name for the controller of up to 24 letters. It is useful to name the controller, so that when the controller is accessed remotely, it is clearly identified to the remote user. This will help to avoid remote users from changing the configuration on the incorrect controller.

```
Modify Controller Name

<SUNRISE_AND_50???????????? >

Press + to increment to the next char
Press - to decrement to the next char
Press -> to move the cursor
Press ENTER to change the name
```



### 9. Utilities

The Utilities menu contains various utility functions that verify that the URMS is operating properly. In addition there is also a utility to allow the user to back up their configuration file to a Datakey.

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#### UTILITIES MENU

1-ACFAIL Event Log
2-Input File Test
3-Output File Test
4-Reset Detectors
5-Keyboard Test
6-Raw Output Test
7-Continuity Test
8-Lights Test
9-File Checksums
A-Program Status
B-Backup Utilities
C-Clear Car Counts

The menu areas are:

**ACFAIL Event Log** Shows a log of the controller's short and long AC

power interruptions.

**Input File Test** Shows the current activation status of the input file.

Output File Test Shows the current activation status of the output file.

**Reset Detectors** Allows the user to send a reset pulse to the input

detectors.

**Keyboard Test** Allows users to check the functionality of the 2070

front panel keypad.

**Raw Output Test** Allows users to check the functionality of the 334

Cabinet Load Switches.

**Continuity Test** Runs a signal test which checks output continuity to a

single controller output.

**Lights Test**Turns on all associated output in sequence for a quick

verification that all lights will illuminate.

**File Checksums** Display URMS program modules and the configuration

file checksums.



**Program Status** Shows if all of the URMS subprograms are running.

**Backup Utilities** Allows users to backup the URMS configuration file to

a Datakey or the FLASH.

**Clear Car Counts** Allows uses to re-zero the controller car count values.

#### 9-1 ACFAIL Event Log

The ACFAIL Log displays a system log indicating both long power failures and short power interruptions. Any power interruption longer than 500 milliseconds will cause the controller to reboot. This reboot will be logged as a power up entry in the log. If a power interruption is shorter that 500 milliseconds and does not cause the controller to reboot it will be logged as an ACFAIL event. An ACFAIL event is sometime referred to as a short out.

URMS ACFAIL LOG			
POWER UP POWER UP POWER UP ACFAIL	01-JAN-1970 01-JAN-1970 01-JAN-1970 01-JAN-1970 01-JAN-1970	00: 27: 38 00: 28: 24 00: 29: 39 00: 31: 33 00: 36: 07	

### 9-2 Input File Test

The Input File Test menu shows the raw state of each input in the input file. A dot (.) represents the OFF state while an (\*) represents the ON state for each detector. You can also select an input to generate a tone on the 2070 when the input it actuated.



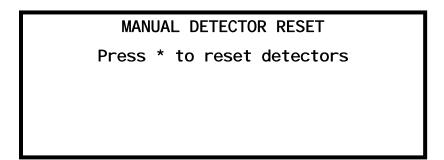
### 9-3 Output File Test

The output file test shows the raw output state of each output to the output file(s). A dot ( . ) represents the OFF state while an ( \* ) represents the ON state.

1	33 <sup>4</sup> 2	4 CAE 3	BI NET 9	– 0U 10	TPUT 11	FILE 12	TEST 13	14
	•	•	•	•	•	•	•	•
•	•	•	•	•	•	•	•	•
•	•	•	•	•	•	•	•	•
Det	Res	et.						

### **9-4 Reset Detectors**

The Reset Detectors menu allows the user to be able to turn on the detector reset output. Pressing the asterisks key (\*) while this screen is selected will turn on the detector reset output for 500 milliseconds.



### 9-5 Front Panel Keyboard Test

The Keyboard Test menu allows the user to test the 2070 front panel keypads. This screen also displays the current state of the Aux Switch on the front panel.



FRONT PANEL TEST
Last key pressed shown below
Aux
Left keypad Right keypad Switch
[ ] 0FF

### 9-6 Raw Output Test

The Raw Output Test allows the user to manually turn ON or OFF any selected load switch output. Each output can be selected and set to the desired output state. After leaving this menu all outputs will return to their command source commanded state.

334 CABINET - RAW OUTPUT FILE TEST

1 2 3 9 10 11 12 13 14
R OFF OFF<ON> OFF OFF OFF OFF OFF OFF
Y OFF OFF OFF OFF OFF OFF
G OFF OFF OFF OFF OFF OFF

### 9-7 Output Signal Test

The Output Signal Test menu allows the user to verify that the URMS physical outputs and associated cabinet wiring has been installed correctly.

Continuity Test
This is the wiring continuity test
Each configured output will be
individually tested

Press \* to start and stop test
Press + or - to change display
Press ESC to terminate testing

Any function which has been assigned to an actual C-1 Connector Output will be tested one at a time in the following order. Any output not assigned will be skipped.

```
Lower Green 1
```

Green 1

Yellow 1

Red 1

Lower Green 2

Green 2

Yellow 2

Red 2

Lower Green 3

Green 3

Yellow 3

Red 3

Lower Green 4

Green 4

Yellow 4

Red 4

Advance Warning Sign – Global 01 – Non-Flashing / Flashing

Advance Warning Sign – Global 02 – Non-Flashing

Advance Warning Sign – Global 03 – Flashing

Advance Warning Sign – Global 04 – Flashing Alternate

Advance Warning Sign – Group A – Non-Flashing

Advance Warning Sign – Group A – Flashing

Advance Warning Sign – Group A – Flashing Alternate

Advance Warning Sign – Group B – Non-Flashing

Advance Warning Sign – Group B – Flashing

Advance Warning Sign – Group B – Flashing Alternate

Advance Warning Sign – Group C – Non-Flashing

Advance Warning Sign – Group C – Flashing

Advance Warning Sign – Group C – Flashing Alternate

General Purpose Output #1

General Purpose Output #2

General Purpose Output #3

General Purpose Output #4

General Purpose Output #5

General Purpose Output #6

General Purpose Output #7

General Purpose Output #8

Rate Code 1 Output

Rate Code 2 Output

Rate Code 4 Output

Rate Code 8 Output



#### 9-8 Lights Test

The Lights Test menu is a quick signal test of all the metered lane outputs. When selected, the outputs are activated in the following order:

Lights Display Test
This is for testing signal light bulbs
Each configured display group will
be tested together

Press \* to start and stop test Press + or - to change display Press ESC to terminate testing

All Lower Green outputs will be activated All Green Signal outputs will be activated All Yellow Signal outputs will be activated All Advance Warning Sign outputs will be activated All General Purpose Outputs will be energized

### 9-9 File Checksums

The File Checksum menu shows the current file checksums for the URMS's configuration parameters.

URMS	<b>CHECKSUMS</b>
------	------------------

 GENERAL:
 4763
 TOD:
 F3C9

 METERED:
 4D27
 TBC TABLE:
 8493

 QUEUES:
 442D
 T. R. PLANS:
 0f86

 MAI NLI NE:
 F6DD
 HOLI DAYS:
 B45D

Conf File: B7DF Meter: 2FD2 TOD: 47DE



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### 9-A Program Status

The Program Status menu shows the current status of each program module as either RUNNING or CRASHED. This can let the user know if any module is not running for any reason.

	URMS BACKGRO	OUND MODULE	STATUS
CFGMAN: TI MI NG: SERMAN: UDP_TX:	RUNNI NG RUNNI NG RUNNI NG RUNNI NG	FFI OMAN: LEDMAN: ACFAI L: SENSYS:	RUNNI NG RUNNI NG RUNNI NG RUNNI NG

The modules provide the following functionality to the URMS

**CFGMAN** Handles all changes to the URMS configuration file including

ensuring items are within the allowable minimums and

maximums.

**TIMING** Handles all timing within the controller such as when to start a

day plan or when to set the meter head to green.

**SERMAN** Handles all RS-232 and 4 wire modem and communications on

serial ports 1 and 2, as well as Ethernet TCP/IP

communications. Initializes the controller IP, network mask,

broadcast and gateway addresses at boot up.

**FFIOMAN** Handles communication between the controller CPU and Field

I/O module.

**LEDMAN** Handles the front panel LED (makes the LED flash).

**ACFAIL** Logs controller power interruptions.

**SENSYS** Handles data sent from Sensys access points.

If any module shows as crashed then first try rebooting the controller. If that does not remove the problem then you may want to send in the controller for re-installation of the URMS or further repair.



### 9-B Backup Utilities

The Backup Utility menu allows the user to back up the current URMS configuration file to a Datakey inserted in the controller as well as to the controller FLASH. In addition it allows the user to recover a previously saved configuration file that was stored on the FLASH. Please note that after backing up the configuration file to the Datakey, it should be removed from the controller.

#### BACKUP UTILITIES

- 1-Backup Configuration to the Datakey 2-Backup Configuration to the FLASH 3-Recover Configuration from the FLASH

### 9-C Clear Car Counts

The Clear Car Counts menu allows the user to clear or reset the current car count numbers shown on the controller. Pressing the asterisks key (\*) will set all car counts to a value of zero.

**CLEAR CAR COUNTS** 

Press \* to Clear Car Counts



### A. Status

### **A Metered Command Source Lane Status**

The Metered Command Source menu allows the user to see the current command source, action, rate, cycle count, plan and current time. This menu is useful for quickly verifying that the controller is running in the expected action at the expected time. Pressing NEXT will select the Meter Lane Phase Timing Page.

METERED	COMMAND	SOURCE	I ANF	STATUS
Lane	1	2		01/1100
Cmd Source	TBC	TBC		
Cmd Action	DARK	DARK		
Rate	360	360		
Cycl e Count	: 0	0		
Pl an	1	1		
12: 13: 34			10	0/04/2007

### **B** Meter Lane Phase Timing

The Metered Lane Phase Timing menu displays current metering interval and phase timing that is occurring in each metered lane. Pressing NEXT will select the Traffic Responsive Status menu. You can also select this page by selecting 'B' from the main menu.

URMS METE	RED LAN	IE PHA	SE TIMI	NG
Lane Interval	Ti me	Mi n	Max G	ap Ext
	25.0	4.0		0 10 0
2 METER RED 3 DARK	19. 0	2. 0	4.05.	0 10.0
3 DAKK				
Min Metering O Min Non-Meteri	. 0	Com R	efresh	275. 7
Min Non-Meteri	ng 0.0	Shutd	own	0. 0

**Lane Interval** Represents the current metering interval that the metered lane

is in.

**Time** Represents maximum amount of time that the lane will be in

the current interval.



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**Min** Represents the minimum time that the controller will be in this

interval. When the metered lane is in the Green or Shutdown Green Intervals, this represents the Minimum Green Time; when the metered lane is in the Red or Shutdown Red Intervals, this represents the Minimum Red Time.

**Max** Represents the maximum time that the controller will be in this

interval. It is either the Maximum Green Time for the Metered Green Interval or the Maximum Red Time for the Metered Red Interval. For other intervals it is the configured interval time.

**Gap** Represents the Red Gap Time and is only shown during the

Metering Red Interval.

**Ext** Represents the Red Extension Time and is only shown during

the Metering Red Interval.

**Min Metering** Represents the remaining minimum metering time. Minimum

Metering Time is the amount of time that once the controller

starts metering, the URMS will continue to meter for,

regardless of any commanded action or the traffic responsive

rate.

**Min Non-Metering** Represents the remaining minimum Non-Metering Time.

Minimum non-metering time is the amount of time that once the controller stops actively metering; the URMS will stay in the non-metering state for, regardless of any commanded

action or the traffic responsive rate.

**Com Refresh** Represents the remaining communications timeout period. If

the time period of the communications refresh time has expired due to a loss of communications then the communications

action will automatically change to skip.

**Shutdown Time** Represents the remaining amount of time that the controller

will be actively metering in the shutdown metering mode.

### **C** Traffic Responsive Status

The Traffic Responsive Status menu tells the user what plan level the controller will operate in Traffic Responsive Mode based on mainline traffic data and queue detection. It should be noted that Traffic Responsive levels are calculated even if the controller is not currently in





the Traffic Responsive Mode. This is so metering plans can be tested even while no active metering is currently being performed. You can also select this page by selecting 'C' from the main menu.

TRAFF	IC RES	SPONSI VE	STATUS
Lane	1	2	
PI an	1	1	
Base Level	3	3	
Adjust Level	1	1	
Final Level	4	4	
Rate	360	360	
Q FLAG	SET	SET	

**Plan** The current plan number that has been selected by the active

command source.

**Base Level** The Level based on the highest or most restrictive volume,

occupancy or speed limits configured in the metering plan before any queue adjustments have been made. This is also the level that is

transmitted when the controller is a master to a slave unit.

**Adjust Level** The amount that the plan level is to be adjusted due to the number of

cars backed up into the metering queue. Plan level is only adjusted

when the Queue Adjustment Mode is set to Level.

**Final Level** The Base Level plus the Adjustment Level up to a maximum level of

15.

**Rate** The metering plan configured vehicles per hour based on the final

level.

Queue Flag Will show SET when any Queue Flag in a metered lane is set or

CLR (clear) when all Queue Flags in a metered lane are clear.



### **D** Current Metering Rates

The Current Metering Rates menu displays the current Metering Rate, Cycle Time, and the status of the Queue Flag. You can also select this page by selecting 'D' from the main menu.

CURRE	NT METE	RING RA	TES	
Lane	1	2	3	
Met Rate(VPH)	3600	120	120	
Cycle Time		30. 0	30. 0	
Que 1 Flag	CLR	CLR	CLR	
Que 2 Flag	CLR	CLR	CLR	
Que 3 Flag	CLR	CLR	CLR	
Que 4 Flag	CLR	CLR	CLR	
	÷ <b>—</b> · · · ·	÷ <b>=</b> . · ·	· ·	

**Meter Rate** The requested release rate in vehicles per hour.

**Cycle Time** The amount of time it would take to cycle in order to release vehicles

at the metering rate. It should be noted that in case the cycle time is less that Minimum Red and Minimum Green Times, then those

minimum times will override the cycle time.

Queue X Flag The current status of each individual Queue Detection Flag. It will

be either CLR when the Queue Flag is clear or SET when the Queue

Flag is set.

### **E Traffic Responsive Calculation Data**

The Traffic Responsive Calculations menu shows the volume, occupancy and speed averaged over several calculation intervals. This is the mainline average data that the Traffic Responsive Plan figured out its plan rate from. You can also select this page by selecting 'E' from the main menu.

AVERAGE LONG MAINLINE DATA USED FOR TRAFFIC RESPONSIVE CALULATIONS

AVERAGE VOLUME(VPH) 2050 AVERAGE OCCUPANCY 19.9% AVERAGE SPEED 67

LAST 240 SEC DATA UPDATED EVERY 30 SECS

# **Appendix A: Configuration Variables and their Limits**

Item	Min	Max	Special Value?	Units	
Global			value:		
Number of Metered Lanes	1	4	0	Lanes	
Number of Mainline Lanes	1	8	0	Lanes	
Number of Opposite Lanes	1	8	0	Lanes	
Number of Additional Detector Locations	1	16	0	Lanes	
Traffic Responsive Mode	Green o		1 -		
Number of Averaging Periods	1	8	none	Calculation Intervals	
Communications Protocol	SATMS UDP-1	S, SDRMS	S, REV8, O	CRMS, TOS, URMS,	
Critical Flow Limit	500	3600	0	Vehicles per Hour	
Critical Occupancy Limit	5.0	99.9	0.0	0.1%	
Critical Speed Limit	10	99	0	Miles per Hour	
Communications Queue Override	Yes, No	ii	1 -		
Daylight Savings	Yes, No				
HOV Active	Yes, No				
Failsafe Feedback Enabled	Yes, No				
Reboot on Loss on Communications	Yes, No				
General Purpose Output	,				
General Purpose Output Time On	0.1	5.0	0.0	0.1-Seconds	
General Purpose Output Time Off	0.1	5.0	0.0	0.1-Seconds	
<b>Serial Communications Port</b>		•	1		
Baud Rate	1200, 24	400, 4800	, 9600, 192	00, 38400	
Data Bits	5, 6, 7,	8			
Parity	Odd, Even, None				
Stop Bit	1, 2				
Handshaking	None, N	Jormal, A	uto, Auto C	CTS, Auto RTS	
RTS On Time	1	255	0	Milliseconds	
RTS Off Time	1	255	0	Milliseconds	
Address (Drop Number)	1	255	0		
Port Enabled	Yes, No	)			
<b>Ethernet Communications Port</b>					
Address (Drop Number)	1	255	0		
Port Number	1	65535	0		
IP Mode	Static, I	Dynamic			
Address		255	0	IP Address Format	
Network Mask	1	255	0	IP Address Format	
Broadcast	1	255	0	IP Address Format	
Gateway	1	255	0	IP Address Format	

Item	Min	Max	Special Value?	Units	
Additional Detectors			value.		
Detector Mode	Enabled, Disabled				
Erratic Count Threshold	1	30	0	Vehicles per 30 Seconds	
Max Presence Threshold	1	1500	0	Minutes	
No Activity Threshold	1	1500	0	Minutes	
Mainline Lane		•	1		
Lane Mode	Enabled	l, Disable	d		
Lead Zone Length	0.1	15.0	0.0	0.1-Feet	
Trail Zone Length	0.1	15.0	0.0	0.1-Feet	
Speed Trap Spacing	0.1	60.0	0.0	0.1-Feet	
Erratic Count Threshold	1	255	0	Vehicles per 30 Seconds	
Maximum Presence Threshold	1	720	0	Minutes	
Typical Vehicle Length	0.1	45.0	0.0	0.1-Feet	
HOV Lane	Yes, No	)			
Metered Lane					
Lane Mode	Yes, No				
Red Lock	Yes, No				
Queue Mode	Additive, Priority				
Queue Standby	Yes, No				
Queue Detection Mode	Disabled, Count, Occupancy				
Queue Adjustment Mode	Rate, Rateup, Level, Fixed				
Queue Erratic Count Threshold	1	255	0	Vehicles	
Queue Maximum Presence Threshold	1	720	0	Minutes	
Queue No Activity Threshold	1	720	0	Minutes	
Queue Dependent Max Presence Threshold	1	600	0	Seconds	
Queue Dependent No Activity Threshold	1	30	0	Vehicles	
Queue versus Shutdown Flag	Yes, No				
Queue Length Upper Limit	0	255	none	Vehicles	
Queue Length Lower Limit	0	255	none	Vehicles	
Queue Occupancy Lower Limit	0.0	99.9	none	0.1%	
Queue Occupancy Lower Limit		99.9	none	0.1%	
Queue Adjustment Rate	5	1800	0	Vehicles per Hour	
Queue Adjustment Rate Iterations	1	20	0	Iterations	
Queue Adjustment Rate Delay	20	240	none	Seconds	
Queue Adjustment Level	1	5	0		

Item	Min	Max	Special Value?	Units
Queue Adjustment Level Iterations	1	5	0	Iterations
Queue Occupancy Level Delay	20	240	none	Seconds
Queue Replacement Rate		1800	none	Vehicles per Hour
Demand Detector Mode	Enabled	l, Disable	d	
Demand Erratic Count Threshold	1	255	0	Vehicles per 30 Seconds
Demand Max Presence Threshold	1	720	0	Minutes
Demand No Activity Threshold	1	720	0	Minutes
Demand Dependent Maximum Presence Threshold	1	600	0	Seconds
Demand Dependent No Activity Threshold	1	30	0	Vehicles per 30 Seconds
Passage Detector Mode	Enabled	l, Disable	d	-
Passage Erratic Count Threshold	1	255	0	Minutes
Passage Maximum Presence Threshold	1	720	0	Minutes
Passage No Activity Threshold	1	720	0	Minutes
Dependency Group	A, B, C			
Minimum Metering Time	1	60	0	Minutes
Minimum Non-Metering Time	1	60	0	Minutes
Startup Alert Time	0.1	60.0	0.0	0.1-Seconds
Startup Warning Time	0.1	60.0	0.0	0.1-Seconds
Startup Green Time	0.1	60.0	0.0	0.1-Seconds
Startup Yellow Time	0.1	10.0	0.0	0.1-Seconds
Startup Red Time	0.1	10.0	0.0	0.1-Seconds
Minimum Red Time	1.0	15.0	none	0.1-Seconds
Demand Gap Time	1.0	15.0	0.0	0.1-Seconds
Demand Red Time	1.0	15.0	0.0	0.1-Seconds
Minimum Green Time	1.0	5.0	none	0.1-Seconds
Maximum Green Time	1.0	15.0	none	0.1-Seconds
Yellow Time	0.5	5.0	0.0	0.1-Seconds
Shutdown Warning Time	1	600	0	Seconds
Post-Metering Green Time	0.1	60.0	0.0	0.1-Seconds
Default Action	Dark, R	est in Gre	en, Fixed I	Rate, Traffic Responsive,
	Emerge	ncy Gree	n, Skip	
Default Plan Number	1	10	none	
Default Rate	150	1800	none	
Vehicles per Green	1	6	none	Vehicles
HOV Lane	Yes, No	)		
Bus Lane	Yes, No	)		

Item	Min	Max	Special Value?	Units		
Plan Entry						
Metering Rate	150	1800	0	Vehicles per Hour		
Occupancy Threshold	0.5	99.9	0.0	0.1%		
Flow Rate Threshold	500	3600	0	Vehicles per Hour		
Speed Threshold	10	99	0	Miles per Hour		
Month	NC, Ja	NC, Jan, Feb, Mar, Apr, May, Jun., Jul, Aug, Sep, Oct,				
	Nov, D	ec ec				
Week	1	5	none	Week Number		
Day	Sun, M	Sun, Mon, Tue, Wed, Thu, Fri, Sat				
<b>Dependency Group</b>						
Signal Service Mode	MUTE	X, MUTI	EX2, Fixed	Offset, Fractional Offset,		
	None					
Green Offset Time	0.2	10.0	0.0	0.1-Seconds		
Minimum Fractional Offset Time	0.2	5.0	0.0	0.1-Seconds		

## **Appendix B: Preconfigured URMS I/O Layouts**

### I/O Preconfigured Layout Table Abbreviations

The following abbreviations are used in the URMS Preconfigured I/O Layouts tables.

#### **Inputs:**

NC Input is not configured Mainline lane n Leading detector MLn MTn Mainline lane n Trailing detector Opposite mainline lane n Leading detector **OLn** Opposite mainline lane n Trailing detector OTn Additional Detector number n Fn Pn Metered lane n Passage detector Metered lane n Queue detector Qn Metered lane n Demand detector Dn Input is not configured for use NC Rate Code Input n **RCn** 252 Failsafe Feedback Input

#### **Outputs:**

<b>I</b>				
NC	Outputs is Not Configured			
LGRNn	Metered Lane n Lower Green output			
GRNn	Metered Lane n Green output			
YELn	Metered Lane n Yellow output			
REDn	Metered Lane n Red output			
WARN01	Meter ON Warning Sign Solid – Non-Flashing/Flashing -			
	Global			
WARN02	Meter ON Warning Sign Non-Flashing/Flashing - Global			
WARN03	Meter ON Warning Sign Flashing - Global			
WARN04	Meter ON Warning Sign Alternate Flashing - Global			
WARNA1	Meter ON Warning Sign Non-Flashing – Dependency Group A			
WARNA2	Meter ON Warning Sign Flashing – Dependency Group A			
WARNA3	Meter ON Warning Sign Alternate Flashing – Dependency			
	Group A			
WARNB1	Meter ON Warning Sign Non-Flashing – Dependency Group B			
WARNB2	Meter ON Warning Sign Flashing – Dependency Group B			
WARNB3	Meter ON Warning Sign Alternate Flashing – Dependency			
,,,	Group B			
WARNC1	Meter ON Warning Sign Non-Flashing – Dependency Group C			
WARNC2	Meter ON Warning Sign Flashing – Dependency Group C			
WARNC3	Meter ON Warning Sign Alternate Flashing – Dependency			
,,,,	Group C			
GPn	General Purpose Output number n			
RCn	Rate Code n			

					URMS	Precor	nfigure	d I/O L	ayouts	3					
Configuration Code	Channel						Slo	t (I file	or Ou	tput)					
Code		1	2	3	4	5	6	7	8	9	10	11	12	13	14
	Umman	NO	NO	NO	NO	NO	NO	NO	NO	NO	NO	NO	NO	NO	NO
	Upper	NC	NC	NC NC	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC NC	NC
BLANK	Lower	NC	NC NC	NC NC	NC	NC	NC	NC	NC	NC	NC	NC NC	NC NC	NC NC	NC
	Red	NC NC	NC NC	NC NC						NC NC	NC NC	NC NC	NC NC	NC NC	NC NC
	Yellow				-										
	Green	NC	NC	NC		_	_	_	_	NC	NC	NC	NC	NC	NC
	Upper	D-1	F-1	Q1-1	F-7	F-12	F-4	F-8	F-10	OL-1	OL-3	OL-5	ML-5	ML-3	ML-1
	Lower	P-1	F-2	F-3	Q1-2	F-13	F-5	F-9	F-11	OL-2	OL-4	OL-6	ML-6	ML-4	ML-2
SATMS	Red	NC	NC	RED1						NC	NC	NC	NC	NC	NC
	Yellow	WARN01	NC	YEL1						NC	NC	NC	NC	NC	NC
	Green	NC	NC	GRN1						NC	NC	NC	NC	NC	NC
									Î					Î	
	Upper	D-1	Q1 -1	NC	NC	ML-1	ML-3	ML-5	NC	NC	NC	NC	D-2	Q2-1	D-3
SDRMS	Lower	P-1	F-1	NC	NC	ML-2	ML-4	ML-6	NC	NC	NC	NC	P-2	F-2	P-3
	Red	LGRN1	RED1	RED2						NC	RED3	NC	NC	NC	NC
	Yellow	WARN01	YEL1	YEL2						NC	YEL3	NC	NC	NC	NC
	Green	LGRN2	GRN1	GRN2						NC	GRN3	LGRN3	NC	NC	NC
		5 .	0.1.1											00.1	
	Upper	D-1	Q1 -1	252	NC	ML-1	ML-3	ML-5	NC	NC	INT-8	INT-2	D-2	Q2-1	D-3
11RC7	Lower	P-1	F-1	NC	NC	ML-2	ML-4	ML-6	NC	NC	INT-4	INT-1	P-2	F-2	P-3
TIKO	Red	LGRN1	RED1	RED2						NC NC	RED3	NC	NC	RC4	RC1
	Yellow	WARN01	YEL1	YEL2	-					NC	YEL3	NC	NC	RC8	NC
	Green	LGRN2	GRN1	GRN2						NC	GRN3	LGRN3	NC	NC	RC2
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	NC	OL-1	OL-2	OL-3	OL-4	OL-5	OL-6	NC
	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	MT-6	NC	OT-1	OT-2	OT-3	OT-4	OT-5	OT-6	NC
SDRMS 7.97 SDRMS 7.99	Red	NC	NC	NC						NC	NC	NC	NC	NC NC	NC
1.33	Yellow	NC	NC	NC						NC	NC	NC	NC	NC	NC
	Green	NC	NC	NC	1					NC	NC	NC	NC	NC	NC

URMS Preconfigured I/O Layouts															
Configuration Code	Channel						Slo	t (I file	or Ou	tput)					
Code		1	2	3	4	5	6	7	8	9	10	11	12	13	14
	Umman	D-1	01.1	NC	NC	ML-1	ML-2	ML-3	ML-4	NC	NC	NC	D-2	Q2-1	D-3
	Upper	D-1 P-1	Q1 -1 F-1	NC NC	NC	MT-1	MT-2	MT-3	MT-4	NC NC	NC	NC NC	P-2	F-2	D-3 P-3
D3TMS1	Lower Red	NC	NC	NC NC	INC	IVI I - I	IVI I -Z	W11-3	IVI I -4	NC	NC NC	NC NC	NC	NC	NC
	Yellow	NC	NC	NC						NC	NC	NC	NC	NC	NC
	Green	NC	NC	NC						NC	NC	NC	NC	NC	NC
	Groom	110	110	110						140	110	110	110	110	110
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	ML-7	ML-8	NC	D-1	Q1-1	D-2	Q2-1	D-3
	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	MT-6	MT-7	MT-8	NC	P-1	F-1	P-2	F-2	P-3
D6RMS1	Red	LGRN1	RED1	RED2						NC	RED3	NC	NC	NC	NC
	Yellow	WARN01	YEL1	YEL2						NC	YEL3	NC	NC	NC	NC
	Green	LGRN2	GRN1	GRN2						NC	GRN3	LGRN3	NC	NC	NC
					l				Î	Î	Ĭ _	_		Ī	
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	ML-7	ML-8	NC	D-1	Q1-1	NC	NC	D-2
D6RMS2	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	MT-6	MT-7	MT-8	NC	P-1	F-1	NC	F-2	P-2
	Red	LGRN1	RED1	RED2						NC	RED3	NC	NC	NC	NC
	Yellow	WARN01	YEL1	YEL2						NC	YEL3	NC	NC	NC	NC
	Green	LGRN2	GRN1	GRN2		_	_	_	_	NC	GRN3	LGRN3	NC	NC	NC
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	ML-7	OL-1	OL-2	OL-3	OL-4	OL-5	OL-6	OL-7
	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	MT-6	MT-7	OT-1	OT-2	OT-3	OT-4	OT-5	OT-6	OT-7
D6TMS1	Red	NC	NC	NC						NC	NC	NC	NC	NC	NC
	Yellow	NC	NC	NC						NC	NC	NC	NC	NC	NC
	Green	NC	NC	NC						NC	NC	NC	NC	NC	NC
											I				
	Upper	ML-1	ML-2	NC	NC	NC	NC	NC	ML-3	ML-4	NC	NC	NC	NC	NC
DetMea	Lower	MT-1	MT-2	NC	NC	NC	NC	NC	MT-3	MT-4	NC	NC	NC	NC	NC
D6TMS2	Red	NC	NC	NC						NC	NC	NC	NC	NC	NC
	Yellow	NC	NC	NC						NC	NC	NC	NC	NC	NC
	Green	NC	NC	NC						NC	NC	NC	NC	NC	NC

URMS Preconfigured I/O Layouts															
Configuration Code	Channel						Slo	t (I file	or Ou	tput)					
Code		1	2	3	4	5	6	7	8	9	10	11	12	13	14
	Upper	ML-1	ML-2	ML-3	NC	NC	NC	NC	ML-4	ML-5	ML-6	NC	NC	NC	NC
	Lower	MT-1	MT-2	MT-3	NC	NC	NC	NC	MT-4	MT-5	MT-6	NC	NC	NC	NC
D6TMS3	Red	NC	NC	NC						NC	NC	NC	NC	NC	NC
	Yellow	NC	NC	NC						NC	NC	NC	NC	NC	NC
	Green	NC	NC	NC						NC	NC	NC	NC	NC	NC
							Ī		T	I			l		
	Upper	D-1	F-1	Q1-1	F-7	F-12	F-4	F-8	F-10	OL-1	OL-3	OL-5	ML-5	ML-3	ML-1
	Lower	P-1	F-2	F-3	Q1-2	F-13	F-5	F-9	F-11	OL-2	OL-4	OL-6	ML-6	ML-4	ML-2
D7EMS1	Red	WARNB1	WARN01	WARNA1						NC	NC	NC	NC	NC	NC
	Yellow	WARNB2	WARN02	WARNA2						NC	NC	NC	NC	NC	NC
	Green	WARNB3	WARN03	WARNA3						NC	NC	NC	NC	NC	NC
	Hanar	D-1	F-1	Q1-1	F-7	F-12	F-4	F-8	F-10	OL-1	OL-3	OL-5	ML-5	ML-3	ML-1
	Upper	P-1	F-1 F-2	F-3	F-6	F-12 F-13	F-4 F-5	F-9							ML-2
WARN1	Lower	NC	NC	NC	F-0	F-13	F-0	F-9	F-11	OL-2	OL-4 NC	OL-6 NC	ML-6	ML-4 NC	NC
	Red Yellow	NC NC	NC NC	NC NC						NC NC	NC NC	NC NC	NC NC	NC NC	NC NC
		NC		NC NC						NC	NC	NC NC		NC NC	
	Green	NC	NC	INC						NC	I NC	NC	NC	NC NC	NC
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	ML-7	ML-8	F-1	F-3	F-5	F-7	F-9	F-11
	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	MT-6	MT-7	MT-8	F-2	F-4	F-6	F-8	F-10	F-12
TOS 53	Red	GP3	GP5	GP1						NC	NC	NC	NC	NC	NC
	Yellow	NC	GP7	GP2						NC	NC	NC	NC	NC	NC
	Green	GP4	GP6	NC						NC	NC	NC	NC	NC	NC
									1	1					
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	OL-1	OL-2	OL-3	OL-4	D-1	Q1-1	D-2	Q2-1
	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	MT-6	OT-1	OT-2	OT-3	OT-4	P-1	F-1	P-2	F-2
TOS 5C	Red	GP1	RED2	RED1						NC	NC	NC	NC	NC	NC
	Yellow	WARN01	YEL2	YEL1						NC	NC	NC	NC	NC	NC
	Green	GP2	GRN2	GRN1						NC	NC	NC	NC	NC	NC

URMS Preconfigured I/O Layouts															
Configuration Code	Channel						Slo	t (I file	or Ou	tput)					
Code		1	2	3	4	5	6	7	8	9	10	11	12	13	14
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	OL-1	OL-2	OL-3	OL-4	OL-5	OL-6	F-1	F-3
	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	MT-6	OT-1	OT-2	OT-3	OT-4	OT-5	OT-6	F-2	F-4
TOS 63	Red	GP3	GP5	GP1	WII T	WIT 0	IVI O	011	012	NC	NC	NC	NC	NC	NC
TOS C3	Yellow	NC	GP7	GP2						NC	NC	NC	NC	NC	NC
	Green	GP4	GP6	NC						NC	NC	NC	NC	NC	NC
			ı		1					ı			I		
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	OL-1	OL-2	OL-3	OL-4	OL-5	F-1	F-3	F-5	F-7
TOS 65 TOS C5	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	OT-1	OT-2	OT-3	OT-4	OT-5	F-2	F-4	F-6	F-8
TOS 66	Red	GP3	GP5	GP1						NC	NC	NC	NC	NC	NC
TOS C6	Yellow	NC	GP7	GP2						NC	NC	NC	NC	NC	NC
	Green	GP4	GP6	NC		_	_	_	_	NC	NC	NC	NC	NC	NC
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	ML-7	OL-1	OL-2	OL-3	OL-4	OL-5	OL-6	OL-7
	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	MT-6	MT-7	OT-1	OT-2	OT-3	OT-4	OT-5	OT-6	OT-7
TOS 69 TOS C9	Red	GP3	GP5	GP1	WII T	WIT 0	WIT 0	IVII 7	011	NC	NC	NC	NC	NC	NC NC
	Yellow	NC	GP7	GP2						NC	NC	NC	NC	NC	NC
	Green	GP4	GP6	NC						NC	NC	NC	NC	NC	NC
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	ML-7	ML-8	OL-1	OL-2	OL-3	OL-4	OL-5	OL-6
TOS 6A	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	MT-6	MT-7	MT-8	OT-1	OT-2	OT-3	OT-4	OT-5	OT-6
TOS CA	Red	GP3	GP5	GP1						NC	NC	NC	NC	NC	NC
	Yellow	NC	GP7	GP2						NC	NC	NC	NC	NC	NC
	Green	GP4	GP6	NC						NC	NC	NC	NC	NC	NC
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	ML-7	ML-8	OL-1	OL-2	OL-3	OL-4	F-1	F-3
	Lower	MT-1	MT-2	MT-3	MR-4	MT-5	MT-6	MT-7	MT-8	OT-1	OT-2	OT-3	OT-4	F-1	F-4
TOS 6C TOS CC	Red	GP3	GP5	GP1	IVII T	WITE	WIT-0	141.1-1	IVITO	NC	NC	NC	NC	NC	NC
103 00	Yellow	NC NC	GP7	GP2						NC	NC	NC	NC	NC	NC
	Green	GP4	GP6	NC						NC	NC	NC	NC NC	NC	NC

URMS Preconfigured I/O Layouts															
Configuration Code	Channel						S	Slot (I f	ile or (	Output)					
Code		1	2	3	4	5	6	7	8	9	10	11	12	13	14
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	OL-1	OL-2	OL-3	OL-4	OL-5	D-1	Q1-1	D-2	Q2-1
	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	OT-1	OT-2	OT-3	OT-4	OT-5	P-1	F-1	P-2	F-2
TOS 93 TOS A3	Red	LGRN1	RED2	RED1	1011 -	1011 0	011	012	0.0	WARN04	RED3	LGRN4	RED4	WARNB1	WARNA1
103 A3	Yellow	WARN01	YEL2	YEL1						WARN03	YEL3	GP2	YEL4	WARNB2	GP1
	Green	LGRN2	GRN2	GRN1						WARN02	GRN3	LGRN3	GRN4	NC	WARNA2
	1													<u> </u>	
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	D-1	Q1-1	D-2	Q2-1	D-3	Q3-1	D-4	Q4-1
TOS 95	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	MT-6	P-1	F-1	P-2	F-2	P-3	F-3	P-4	F-4
TOS 95	Red	LGRN1	RED2	RED1						WARN04	RED3	LGRN4	RED4	WARNB1	WARNA1
	Yellow	WARN01	YEL2	YEL1						WARN03	YEL3	GP2	YEL4	WARNB2	GP1
	Green	LGRN2	GRN2	GRN1						WARN02	GRN3	LGRN3	GRN4	NC	WARNA2
							1			_	l .		_	<u> </u>	_
	Upper	ML-1	ML-2	ML-3	ML-4	OL-1	OL-2	OL-3	OL-4	D-1	Q1-1	D-2	Q2-1	D-3	Q3-1
TOS 96	Lower	MT-1	MT-2	MT-3	MT-4	OT-1	OT-2	OT-3	OT-4	P-1	F-1	P-2	F-2	P-3	F-3
TOS A6	Red	LGRN1	RED2	RED1						WARN04	RED3	LGRN4	RED4	WARNB1	WARNA1
	Yellow	WARN01	YEL2	YEL1						WARN03	YEL3	GP2	YEL4	WARNB2	GP1
	Green	LGRN2	GRN2	GRN1		_	_	_	_	WARN02	GRN3	LGRN3	GRN4	NC	WARNA2
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	OL-1	OL-2	OL-3	OL-4	OL-5	D-1	Q1-1	BUS	NC
	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	OT-1	OT-2	OT-3	OT-4	OT-5	P-1	F-1	NC	F-2
TOS 99 TOS A9	Red	LGRN1	RED2	RED1						WARN04	RED3	LGRN4	RED4	WARNB1	WARNA1
	Yellow	WARN01	YEL2	YEL1						WARN03	YEL3	GP2	YEL4	WARNB2	GP1
	Green	LGRN2	GRN2	GRN1						WARN02	GRN3	LGRN3	GRN4	NC	WARNA2
	Upper	ML-1	ML-2	ML-3	ML-4	OL-1	OL-2	OL-3	OL-4	D-1	Q1-1	D-2	Q2-1	NC	NC
	Lower	MT-1	MT-2	MT-3	MT-4	OT-1	OT-2	OT-3	OT-4	P-1	F-1	P-2	F-2	NC	F-3
TOS 9A TOS AA	Red	LGRN1	RED2	RED1						WARN04	RED3	LGRN4	RED4	WARNB1	WARNA1
100 AA	Yellow	WARN01	YEL2	YEL1						WARN03	YEL3	GP2	YEL4	WARNB2	GP1
	Green	LGRN2	GRN2	GRN1						WARN02	GRN3	LGRN3	GRN4	NC	WARNA2

URMS Preconfigured I/O Layouts															
Configuration Code	Channel						5	Slot (I f	ile or C	Output)					
Code		1	2	3	4	5	6	7	8	9	10	11	12	13	14
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	OL-1	OL-2	OL-3	OL-4	OL-5	D-1	Q1-1	D-2	Q2-1
	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	OT-1	OT-2	OT-3	OT-4	OT-5	P-1	F-1	P-2	F-2
TOS 9C TOS AC	Red	GP1	RED2	RED1						NC	NC	NC	NC	NC	NC
	Yellow	WARN01	YEL2	YEL1						NC	NC	NC	NC	NC	NC
	Green	GP2	GRN2	GRN1						NC	NC	NC	NC	NC	NC
				ı									ı	1	
	Upper	ML-1	ML-2	ML-3	ML-4	ML-5	ML-6	ML-7	ML-8	D-2	Q2-1	Q2-3	D-1	Q1-1	Q1-3
	Lower	MT-1	MT-2	MT-3	MT-4	MT-5	MT-6	MT-7	MT-8	P-2	Q2-1	Q2-4	P-1	Q1-2	Q1-4
QTEST	Red	LGRN1	RED1	RED2						NC	NC	NC	NC	NC	NC
	Yellow	WARN01	YEL1	YEL2						NC	NC	NC	NC	NC	NC
	Green	LGRN2	GRN1	GRN2						NC	NC	NC	NC	NC	NC
													1		
	Upper	ML-1	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC
	Lower	MT-1	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC	NC
D6EMS1	Red	NC	NC	NC						NC	NC	NC	NC	NC	NC
	Yellow	WARN01	NC	NC						NC	NC	NC	NC	NC	NC
	Green	NC	NC	NC						NC	NC	NC	NC	NC	NC

## **Appendix C: Legacy Ramp Metering Software Support**

## SDRMS Support (Districts 3, 5, 6 and 11)

The URMS support the SDRMS Normal Poll, the GET and the SET memory communication packets.

### 1. SDRMS Metered Lane/Queue Parameters and their URMS Equivalents

URMS Metered Lane Parameters	SDRMS Parameters/Suggested Default Values
Dependency Group	А
Vehicles Per Green	PSEL
Lane Enabled	YES
Yellow Fail	0
Maximum Metering Rate	0
Minimum Metering Rate	0
Min Metering	5
Startup Alert	1.0
Startup Warning	1.0
Startup Green	FIRGR
Yellow	FIRYE
Startup Red	2.0
Min Green	MINGR
Max Green	MAXGR
Yellow	CYCLY
Min Red	MINRD
Demand Gap	1.0
Demand Red	DMRED
Shut Warn	5.0
Post Green	SINDLY
Shut Time	0
Min Non-Meter	5
Q VS. Shutdown	NO
Service Mode	MUTEX
GRN Offset Time	GOCTL
Fract Offset Time	GOTME
Shut Gap Time	0.0
Demand Mode	Enabled
Max Presence	0
No Activity	0
Erratic Count	0
Dep No Activity	0
Passage Mode	Enabled

Max Presence	0
No Activity	0
<b>Erratic Count</b>	0
Queue Usage	Priority
Q1 Standby Flag	No
Q2 Standby Flag	No
Q3 Standby Flag	No
Q4 Standby Flag	No
Default Action	Dark
Default Plan	1
Default Rate	900
Flow Limit	0
Occupancy Limit	0.0
Speed Limit	0
Override in Com	No

<b>URMS Queue Parameters</b>	SDRMS Parameters/Suggested
	<b>Default Values</b>
Queue Det. Mode	Disabled
Max Presence	0
No Activity	0
Erratic Count	0
Dep Max Pres	0
Dep No Activity	0
Adjust Mode	Fixed
Len Up Limit	0
Len Lwr Limit	0
Occ Up limit	20.0
Occ Lwr limit	10.0
Replacement Rate	900
Adjust Rate	50
Rate Iterations	5
Rate Delay	30
Adjust Level	0
Level Iterations	0
Level Delay	30

#### 2. SDRMS Polling Packet Emulation in the URMS

Bytes 3 and 4 of the central system normal polling request message are used to remotely activate the ramp meter and to clear certain system flags in the SDRMS software. In the URMS they are emulated as follows:

Byte 3 – Hold-on-Line/Rate Code

Bits 1-4 Metering Rate Code (0 to 15)

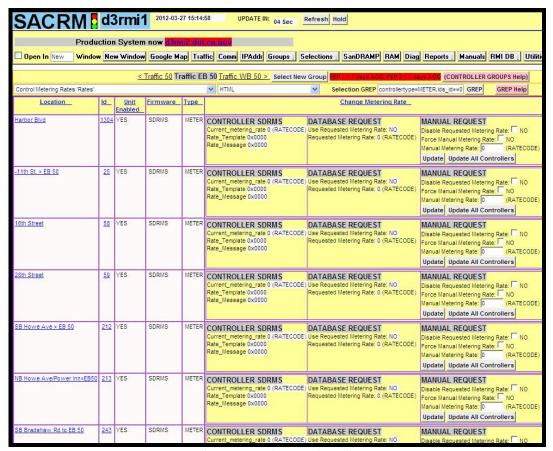
- Rate Code 0 Dark
- Rate Code 1 Rest in Green
- Rate Codes 2-15 Metering action will be set to fixed. Release Rate is determined from the plan 1 release rate for the selected plan level.
- Bit 5 Hold-on-Line (URMS switches to the Communications Command Source)
- Bit 6 Maximum rate code flag (not used)
- Bit 7 Controller maximum rate code override flag (not used)
- Bit 8 Not used in URMS/SDRMS

#### Byte 4 – Reset Control

- Bit 1 Clear Power Fail Count (Not Used Flags clear automatically)
- Bit 2 Clear Controller Alarm Flags (Not Used Flags clear automatically)
- Bit 3 Clear Ramp Detector Error Flags (Not Used Flags clear automatically)
- Bit 4 Clear Main Lane Detector Errors (Not Used Flags clear automatically)
- Bit 5 Clear Main Lane Data Areas (Not Used Flags clear automatically)
- Bit 6 Output Detector Reset Pulse (Send 500 MS pulse on the reset detector output)
- Bit 7 Not used in URMS/SDRMS
- Bit 8 Not used in URMS/SDRMS

#### 3. Remote Activation of Ramp Meters using RMIS

Remote activation using the RMIS is similar to that of the SDRMS program. The release rate of the URMS may be remotely set by selecting a rate code between 0 and 15 in the RMIS.



**RMIS Remote Activation Screen** 

The Rate Codes will have the following effect in the URMS:

Rate Code 0 – URMS communications action is set to Rest-in-Dark

Rate Code 1 – URMS communications action is set to Rest-in-Green

Rate Code 2 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 2 release rate.

Rate Code 3 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 3 release rate.

Rate Code 4 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 4 release rate.

Rate Code 5 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 5 release rate.

Rate Code 6 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 6 release rate.

Rate Code 7 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 7 release rate.

Rate Code 8 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 8 release rate.

Rate Code 9 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 9 release rate.

Rate Code 10 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 10 release rate.

Rate Code 11 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 11 release rate.

Rate Code 12 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 12 release rate.

Rate Code 13 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 13 release rate.

Rate Code 14 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 14 release rate.

Rate Code 15 – URMS communications action is set to Fixed Rate and the release rate is set to the Metering Plan 1 level 15 release rate.

### **SATMS Support (Districts 7 and 12)**

The URMS supports SATMS Normal Polls, Get and Set Memory and Set Time communication packets.

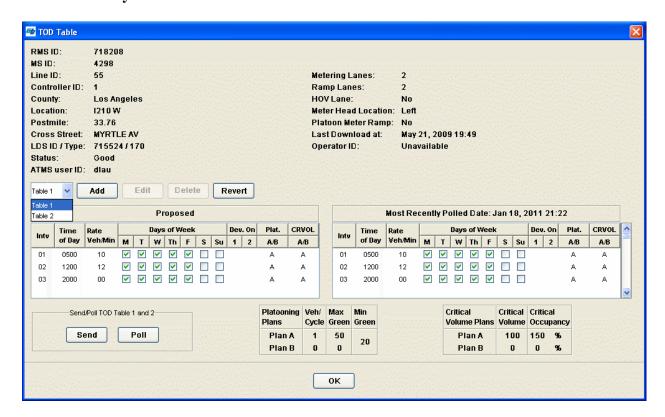
#### 1. SATMS Parameters and their URMS Equivalents

			URMS Front Panel Menu	
Address	SATMS 3.0	URMS	Location	Notes
080	CONT ID	Controller Address	7-1 or 7-2	READ FROM ATMS ONLY
081	FIRGR	Startup Green	1-5-2	
082	PLT YEL	Metering Yellow	1-5-3	
083	LNGYEL	Startup Yellow	1-5-2	
		Queue Lower		
084		Occupancy Limit	1-6-3	
		Queue Upper		
085	QTHRS	Occupancy Limit	1-6-3	
086	MXGRNA	Maximum Green	1-5-3	
087	MXGRNB	Not used in URMS		
088	CROCCA	Not used in URMS		
089	CROCCB	Not used in URMS		
08A	CRVOLA	Not used in URMS		
08B	CRVOLB	Not used in URMS		

08C	PSELA	Vehicles Per Green	1-5-1	READ FROM ATMS ONLY
08D	PSELB	Not used in URMS		
		Number of Metered		
08E	RLANES	Lanes	8-7	READ FROM ATMS ONLY
		Minimum Metering		
08F	GRNHLD	Time in minutes	1-5-2	
090	FMNL	Manual Rate - READ FROM ATMS ONLY	5-1	DARK - Will Report 0 Rest-in-Green will Report 1 Fixed or Traffic Responsive will report Meter Rate/60 * Number of Metered Lanes
091	FLSHR	Not used in URMS		
		Post Meter Green		
092	LASTGR	Time	1-5-4	
093	PHYSML	Number of Mainline Lanes -	8-7	READ FROM ATMS ONLY
094	PHYSOP	Number of Opposite Mainline Lanes	8-7	READ FROM ATMS ONLY
095	Q2THRS	Queue 2 Lower Occupancy Limit	1-6-6	
096	QON	Queue 2 Upper Occupancy Limit	1-6-6	
		Queue 2		
097	Q2ON	Adjustment Steps	1-6-7	
		Queue 2 Adjustment		Queue 2 Adjust Rate /60 *
098	QOFF	Rate	1-6-7	Number of Metered Lanes
099	Q2OFF	Not used in URMS		
09A		Not used in URMS		
09B	MINGRN	Minimum Green	1-5-3	
09C	CRSPEED	Queue Override (Speed)	1-5-A	
09D	Q1CYGRN	Queue Adjustment Steps	1-6-4	
		Absolute Maximum		Max Set Rate/60 * Number of
09E	Q1MAXSET	Metering Rate	1-5-1	Metered Lanes
		Queue Adjustment		Queue Adjust Rate/60 *
09F	RATESTP	Rate	1-6-4	Number of Metered Lanes
				SET from ATMS:  If Bit 1 is set to zero it will  disable all metered lanes. If Bit  1 is set to one it will enable all  metered lanes.
0F4		Metered Lane Enable	1-5-1	Get from ATMS:
017		TVICTOR EATIC ETIABLE	1 1 2 1	Section Ands.

		If metered lane 1 is disabled
		the URMS will return a zero.
		Otherwise it will return a 1.

#### 2. Time of Day Parameters



Time-of-Day and Day-of-Week parameters are set as requested by the ATMS. The URMS also has a "Holiday" day of week which is not supported by the ATMS and cannot be set from the ATMS. The Table number which refers to which Time-of-Day Table the controller will use to set it metering action, rate and plan will be set to the same number as day plan number for any requested ATMS interval. All other Time-of-Day table numbers will be set to zero. Zero indicates in the URMS that this plan number is not used. The HOV Active parameter which is used for part time HOV lanes will not be set by the ATMS, but can be set from the front panel by the operator if desired.

# Start	DAY OF WEEK	C ENTRY	HOV
Time	DOW	Tabl e	Acti ve
1 <05: 00> 2 12: 00 3 20: 00 4 00: 00 5 00: 00	. MTWTF . MTWTF . MTWTF	1 2 3 0 0	YES YES YES YES YES

Unlike SATMS, the URMS uses a separate Time-of Day table to tell the controller what action, rate and plan the controller should operate at. The action will be set to DARK whenever a rate of zero (0) veh/min is set by the ATMS. The action will be set to Rest in Green (greenball) whenever a rate of 1 veh/min is set by the ATMS. Last, the URMS shall set an action of Traffic Responsive whenever a rate of 2 veh/min or higher is set by the ATMS. The fixed release rate shall always be set to 900 and the plan number will always be set to the same number as the Time-of Day Table number.

I ane 1 2	TIME-OF-DA' Action <traffic res<br="">Traffic Res</traffic>	Rate sp> 900	PI an 1 1	
Press NEXT to view GP Outputs				

Metering plans are also different in URMS than in SATMS. For example the URMS does not use critical occupancy or volume. Instead traffic responsive metering uses a look of table that has 15 levels. Each level has a metering release rate and an occupancy, volume and speed threshold for each level.

When a time of data table is set by the ATMS, the URMS metering plan release rates for each level will by calculated by calculating the linearly interpolated value for each level where 900 is the maximum metering rate, and the ATMS Vehicles/Minute \* 60 shall be the minimum (level 15) metering rate. Occupancy, Volume and Speed threshold value will not be modified from the ATMS.

TRAFFIC RESPONSIVE METERING PLAN 1					
LEVEL	RATE	OCC%	VOL	SPEED	
1	900	10. 0	1000	0	
2	850	15. 0	1100	0	
3	800	20. 0	1300	0	
4	750	25. 0	1400	0	
5	700	30. 0	1700	0	
6	650	35. 0	1800	0	

#### 3. Other Traffic Data Collection

The URMS does not have specifically assigned data collection points such as a Collector Distributer. Instead the URMS uses generic additional detectors detection loops. If however a SATMS input configuration is selected under menu 8-7, by default the following assigns the first 12 additional detectors to it SATMS equivalent.

SATMS	URMS
SD1 (MLHOV)	Additional Detector 1
SD2 (OSHOV)	Additional Detector 2
SD3	Additional Detector 3
SD4	Additional Detector 4
SD5	Additional Detector 5
RAMP HOV	Additional Detector 6
CD ON	Additional Detector 7
CD OFF	Additional Detector 8
CD #1	Additional Detector 9
CD #2	Additional Detector 10
On Ramp	Additional Detector 11
Off Ramp	Additional Detector 12

### **TOS Support (District 4)**

The URMS supports the Get/Set Clock, Set HAR EMS, Get Detector Data and the Upload/Download packets for Global Parameters, Metered Lanes 1-4, Holiday/Special Event Table, Time-of-Day Table and Metering Plans 1-6.

#### 1. TOS Get/Set Packets and URMS Known Differences

#### a. General

- It takes a few seconds for the URMS to process requested configuration changes when receiving TOS Protocol packets. Thus is you download using the SDLC211.exe program and then immediately upload the configuration, not all items will have had time to be configured.
- TOS has occupancy stored as XX.XX%. URMS stores occupancy as XX.X%.
- Packet data in the spreadsheet is as seen by the controller. Thus packed data received is data received by the 2070 controller. And data sent is data sent by the 2070 controller.

#### b. Turning ON/OFF HAR

The URMS allows the setting of General Purpose outputs (which are used by URMS for HAR outputs) by selecting their on and off times in the Timebased control tables and time of day plan. TOS does not allow HARS to be enabled or disabled based on the time of day plan. Thus for ATMS HAR Commands the URMS will take the following actions.

- Changes associated Time of Day table for all 16 entries to turn the output to the commanded state.
- Also sets General Purpose Output 1 (HAR Sign) to have an ON time of 1.0 seconds/OFF time of 0.5 seconds and General Purpose Output 2 (HAR Radio) to be continuously on.
  Because the time of day tables are used to turn on the sign, it may take up to 1 minute between the commanded state and the URMS state. This is because time of day table is only checked at the beginning of each minute.

#### c. Globals (Block 0)

- day of week 1hour Stored but not used in URMS
- start\_hour\_1min Stored but not used in URMS
- day\_of\_week\_1min Stored but not used in URMS
- start hour 5min-- Stored but not used in URMS
- day\_of\_week\_5min- Stored but not used in URMS
- start\_hour\_1min- Stored but not used in URMS
- day\_of\_week\_1min- Stored but not used in URMS
- start\_hour\_5min- Stored but not used in URMS
- day\_of\_week\_5min- Stored but not used in URMS

#### d. Metered Lanes (Block 1 to 4)

- Maximum Rate of Increase Stored but not used
- Maximum Rate of Decrease Stored but not used
- Bus Enable Stored but not used
- Minimum Red Time Minimum Limit is 1.0 Seconds (TOS tries to set 0.5 seconds)
- Minimum Green Time Minimum Limit is 1.0 seconds (TOS tries to set 0.5 seconds)
- Passage release rate is stored in the URMS in Minutes. TOS has this value in seconds. While URMS does perform a conversion, both the SDLC211.exe test times (15 and 30 seconds) are less than a minute and thus are set to zero.
- URMS does not have a single shutdown time. Setting the shutdown time will change the rate
  of any time based table that has an action of DARK or REST-in-GREEN to the requested
  shutdown time.

#### e. Holidays (Block 5)

• All holidays will set the non-TOS Day of Week selection to SMTWTFS.

#### f. Time-of-Day (Block 6)

• When setting to Traffic Responsive Code D1 to D6 or E1 to E6, URMS will set Plan Number and report back F6 (Both Occupancy and Volume Data is used). If only Occupancy or Volume Data is desired for the Plan, the Plan can be set with only occupancy or volume thresholds. Setting traffic responsive is not checked using the SDLC211.exe program.

#### g. Metering Plans (Block 7 to 12)

- URMS has 15 Plan Levels while TOS has 16 Plan Levels. Metering Plan 16 is saved by the URMS in its configuration file, but at this time is not used.
- URMS does not allow a release rate of zero. The minimum release rate in URMS is currently 150 VPH.

### **IRIS Support (District 10)**

The URMS supports the IRIS Broadcast Traffic Data UDP packet. Get and Set memory packets are the same as those used in SDRMS.

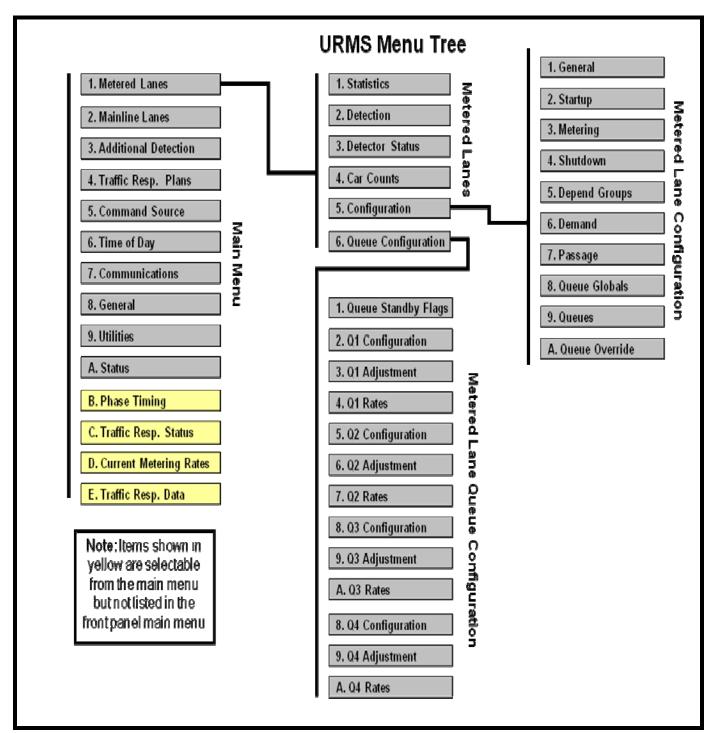
### **Rev8 Support (Districts 8 and 11)**

The URMS supports the Rev8 polling packet. When Rev8 polling packets are used however, if the RMIS receives a software version number other than, the RMIS automatically reverts to SDRMS polling. For this reason URMS will always return a software version and revision number of 8.00 when transmitting Rev8 polling data. Rev8 Get and Set memory packets are the same as those used in SDRMS.

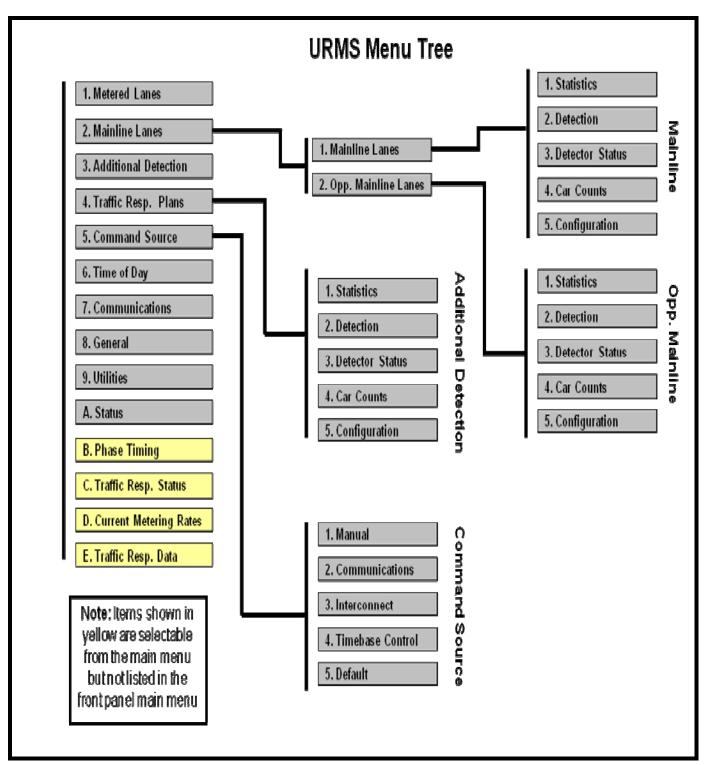
### **ORRMS5** Support (District 12)

The URMS does not currently support OCRMS5 polling; however support for OCRMS5 polling should be included in URMS 2.09. Get and Set memory packets are the same as those used in SATMS.

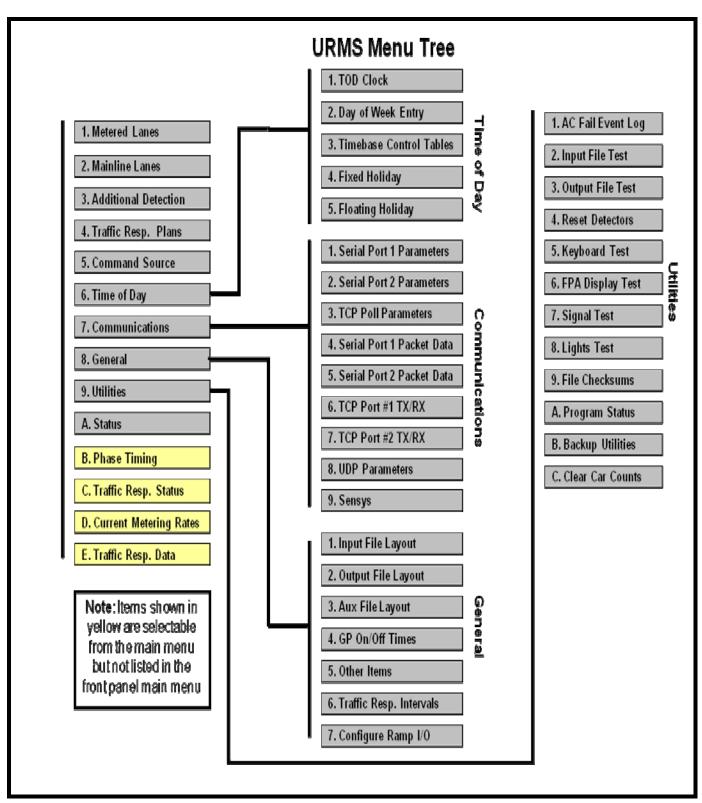
### **Appendix D: URMS Menu Tree**



Menu Tree (1 of 3)



Menu Tree (2 of 3)



Menu Tree (3 of 3)

# **Appendix E: URMS Troubleshooting Guide**

Controller has lost Ethernet	Go to menu item 7-6 and verify that the controller is		
Communication	receiving data.		
Communication	<ul> <li>If data NOT is being received:</li> <li>Go to menu 9-A and verify that the Serman module is running. If not then pull controller from service. URMS Application needs to be reinstalled.</li> <li>Verify Status light is ON on the 1B card. No light means that the controller is not connected to the network.</li> <li>Verify that the Rx light comes on at least once every 30 seconds. No Rx light may mean the controller is not being polled by the TMC or that poll requests are not being received.</li> <li>Verify port number is correct (7-3)</li> <li>Verify IP connection (Static for fiber, Dynamic for Wireless (7-3).</li> <li>Verify that the controller IP Address, Network Mask, Broadcast Address and Gateway are correct (7-3).  Note: Make sure you reboot controller after making any IP parameter changes.</li> <li>Set Reboot on loss of comm to ON (8-5).</li> <li>Reboot controller.</li> </ul>		
	If data IS being received but the packet type is unknown:  • Verify that the controller address is correct (7-3)  • May be a protocol issue. Contact David Wells to		
	update software.		
Controller has lost Serial	Go to menu item 7-4 or 7-5 and verify that the		
Communications (2/4 wire modem on a 2070-6A or 2070 -6B card)	controller is receiving data.		
	If data NOT is being received:		
	<ul> <li>Go to menu 9-A and verify that the Serman module is running. If not then pull controller from service. URMS Application needs to be re- installed.</li> </ul>		

- Verify that the 2070-6x modem installed in slot A2 and that the card power (bottom switch) is ON.
- Verify that the modem switches are set to FULL DUPLEX.
- Verify that the enable/disable switch is set to ENABLE.
- Verify that you are connected to the correct serial port. Serial port 1 is the upper position. Serial port 2 is the lower position.
- District 7 and 12 only. Verify if the CD light is ON on the 2070-6x card. No light means that the controller is not connected to the network.
- Verify that the Rx light comes on at least once every 30 seconds. No Rx light may mean the controller is not being polled by the TMC or that poll requests are not being received.
- Verify serial parameters are correct (7-1 or 7-2).
   Note: Make sure you reboot controller after making any serial parameter changes.
- Verify that you are using the correct type of modem card. 2070-6A is for 1200 BAUD modems only. 2070-6B is for 9600 BAUD modems only. You cannot use a 2070-6B card for 1200 BAUD operations.
- Reboot controller.

If data IS being received but the packet type is unknown:

- Verify that the controller address is correct (7-1 or 7-2)
- May be a protocol issue. Contact David Wells to update software.

If data IS being received and the controller is responding but the TMC shows packets are not being received correctly.

- Raise the RTS ON time
- Raise the RTS OFF time

For most locations it is also recommended to:

Set Reboot on loss of comm to ON (8-5).

Controller has lost Serial Communications (RS-232

Go to menu item 7-4 or 7-5 and verify that the controller is receiving data.

Communications on a 2070-6A or 2070	
Communications on a 2070-6A or 2070-6B card)	If data NOT is being received:  Go to menu 9-A and verify that the Serman module is running. If not then pull controller from service. URMS Application needs to be reinstalled.  Verify that the 2070-6x modem installed in slot A2 and that the card power (bottom switch) is ON.  Verify that the modem switches are set to FULL DUPLEX.  Verify that the enable/disable switch is set to DISABLE.  Verify that you are connected to the correct serial port. Serial port 1 is the upper position. Serial port 2 is the lower position.  Verify that the Rx light comes on at least once every 30 seconds. No Rx light may mean the controller is not being polled by the TMC or that poll requests are not being received.  Verify serial parameters are correct (7-1 or 7-2). Note: Make sure you reboot controller after making any serial parameter changes.  Reboot controller.  If data IS being received but the packet type is unknown:  Verify that the controller address is correct (7-1 or 7-2)  May be a protocol issue. Contact David Wells to update software.  If data IS being received and the controller is responding but the TMC shows packets are not being received correctly.  Raise the RTS ON time Raise the RTS OFF time
	Set Reboot on loss of comm to ON (8-5).
Packets sent on the serial port are echoing back (2 wire modem)  No data coming in from loops	Change dip switch #5 "Half Duplex Local Echo" on 2070-6x modem card to ON.  Verify data in coming in on the detector cards.
The data coming in from loops	Verify that the C1 Cable is installed

	Verify that the I/O setup is correct (8-1). If not correct go to menu 8-7 to select the proper configuration.  Note: Field I/O may have suffered from and internal hardware reset. If this happens the controller will not be able to read any inputs or send any outputs.  Reboot controller and upgrade to URMS 2.07 or later. URMS 2.07 will automatically recover from internal Field I/O hardware resets.
Outputs do not come on	Ensure the watchdog monitor is not tripped. Ensure that the load switches are fully inserted. Check that Police Lights and Police Control. Switches are ON (9-2) Verify that the controller is sending output signals to the field (9-3).  If Signals are being sent by the controller:
	<ul> <li>C1 cable loose or not installed.</li> <li>If Signals are NOT being sent by the controller:</li> <li>Check the output file configuration (8-2 and 8-3) to verify outputs are correctly configured. If they are not configured correctly go to menu 8-7 and select the proper configuration.</li> </ul>
	Perform a Raw Outputs Test (9-6) Reboot Controller
	Note: Field I/O may have suffered from and internal hardware reset. If this happens the controller will not be able to read any inputs or send any outputs.  Reboot controller and upgrade to URMS 2.07 or later. URMS 2.07 will automatically recover from internal Field I/O hardware resets.
Meter did not come out at correct Timebased time.	Verify the cabinet watchdog in not tripped. Verify that the circuit breakers are ON. Verify that the loads are properly inserted. Police Light and Police Control Switches (9-2) Verify that the controller is in Timebased Control (A) Check time/date (7-1) Check Time of Day Schedule (7-2) Check Timebased table (7-3) Check holiday tables (7-4, 7-5) Verify that the meter will meter traffic manually 5-1 and select fixed rate for each metered lane).

Metered lane cycling without any	Verify that the loop is not stuck on (1-3)
vehicles present	Verify that the Controller has detected an loop error
	condition (1-4)
	Verify that the Demand detector on NOT on recall (1-
	5-6)
Cannot change the I/O configuration in	Go to manual command source (5-1) and select
menu 8-7 because the controller is	DARK as the action for each metered lane. After
metering.	meter shuts down you will be able to change the I/O
	configuration.
Command Source shows ERR	Failsafe input has failed.
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### **Appendix F: Manual Activation of the URMS from the Front Panel**

## Manual Activation/Deactivation of the Universal Ramp Metering Software using the 2070 Controller Front Panel

1. If you see a screen that looks like this select 1 using the front panel keyboard.

Front Panel Manager

1-Universal Ramp Metering Software X.XX

2. If on the front panel you see a screen like this or have a blank screen press the enter [ENT] to go to the URMS main menu. Note that for a blank screen you may also have to adjust the contract knob to display text clearly after pressing the enter key.

ADVANCED TRANSPORTATION CONTROLLER

Universal Ramp Metering Software Version X. XX

California Department of Transportation Copyright (c) 1992-2008 by Caltrans 3. From the main menu select menu item 5 - command source

URMS VERSION X.XX - MAIN MENU

1-Metered Lanes 6-Time of Day
2-Mainline 7-Communications
3-Additional Detection 8-General
4-Traffic Resp. Plans 9-Utilities
5-Command Source A-Status

4. From the command source menu select menu item 1 – manual.

#### COMMAND SOURCE

- 1-Manual
- 2-Communi cations
- 3-Interconnect
- 4-Timebase Control
- 5-Defaul t
- 5. Enter the new metered lane action and if needed adjust rate and plan for each metered lane.

COMMAND SOURCE PRIORITY - MANUAL			
I ane	Action	Rate	PI an
1	<skip></skip>	900	1
2	SKIP	900	1

#### **Basic Data Entry**

#### • To shut the ramp meter down (Turn OFF the meter heads)

Press 1 [1] to select "Rest in Dark" and then press enter [ENT] for each metered lane.

• To put the meter into a Rest in Green metering state (Each metered lane's green head will be illuminated).

Press 2 [2] to select "Rest in Green" and then press enter [ENT] for each metered lane.

To put the meter into a Fixed Metering (Each metered lane's green head will be illuminated.

Press 3 [3] to select "Fixed Rate" and then press enter [ENT] for each metered lane. Then enter the selected the release rate for each metered lane press enter [ENT].

#### • To put the meter into a Traffic Responsive

Press 4 to select "*Traffic Responsive*" for each metered lane and then press enter [ENT] for each metered lane. Then select the plan number (if not plan number 1) and press enter [ENT] for each metered lane.

• To put the meter back into the regular time of day mode

Press 6 to select "Skip" for each metered lane and then press enter [ENT] for each metered lane.