

## HYPERBOLIC DISCOUNTING NOTE

The aim is to produce a recursive expression that allows us to apply ADP methods to hyperbolic discounting. At this stage we just seek a recursive expression for lifetime value.

Lifetime value is given by

$$v(x) := \mathbb{E}_x \left[ r(X_0) + \alpha r(X_1) + \sum_{t \geq 2} \beta^t r(X_t) \right]$$

Pointwise this is

$$v = r + \alpha P r + \sum_{t \geq 2} (\beta P)^t r$$

We generalize to allow state-dependent discounting, taking  $J$  and  $K$  to be positive linear operators and writing

$$v = r + J r + \sum_{t \geq 2} K^t r \tag{1}$$

Rearranging gives

$$v = r + J r + K^2 r + K \sum_{t \geq 2} K^t r$$

Using (1) again gives

$$\begin{aligned} v &= r + J r + K^2 r + K(v - r - J r) \\ &= r - K r + J r - K J r + K^2 r + K v, \end{aligned}$$

or

$$v = (I - K)(r + J r) + K^2 r + K v$$

If  $r(K) < 1$ , then lifetime value is uniquely defined by this recursive expression.