

Stationarity and Ergodicity of Equilibrium Price Processes

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Outline

Iterated Random Maps

The Commodity Pricing Model

Exact Sampling



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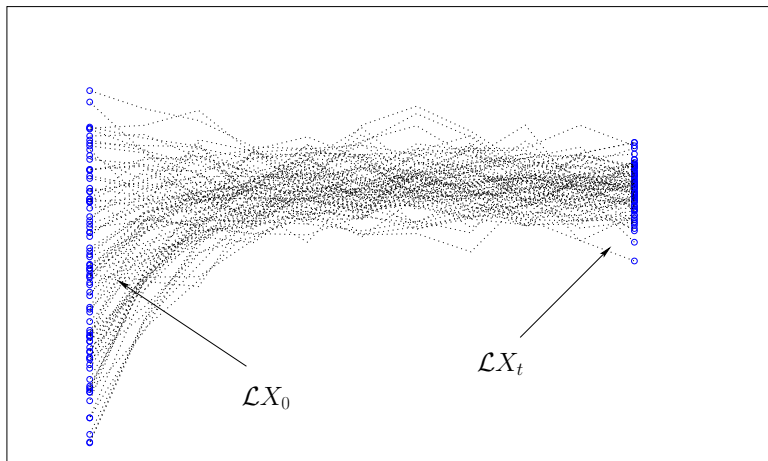
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Let $\mathcal{L}X_t$ be the distribution of X_t .

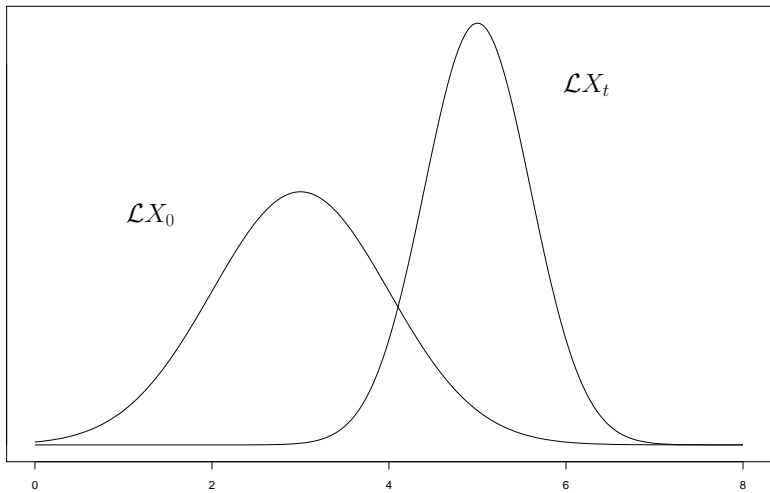


state space



time





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$$\mathcal{L}X_{t-1} = \psi^* \implies \mathcal{L}X_t = \psi^*$$



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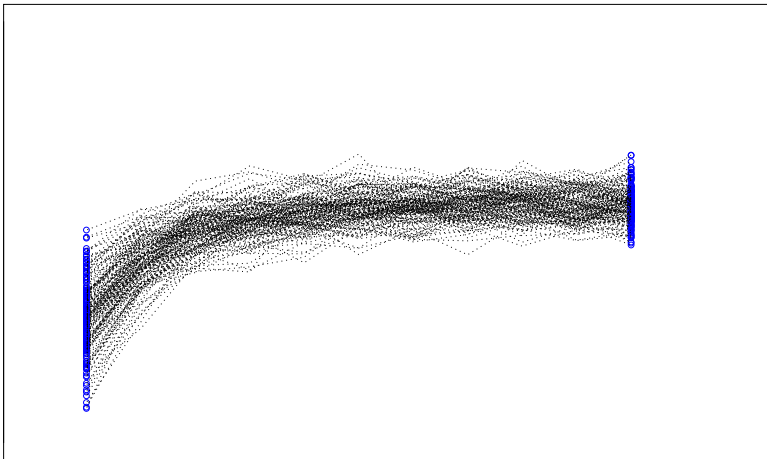
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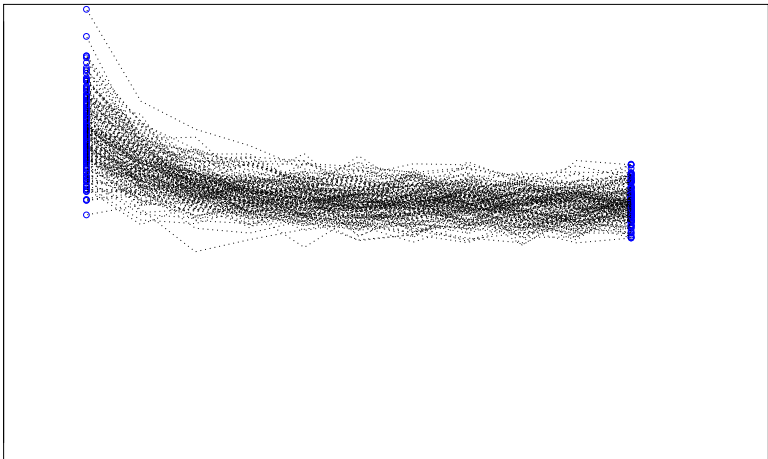
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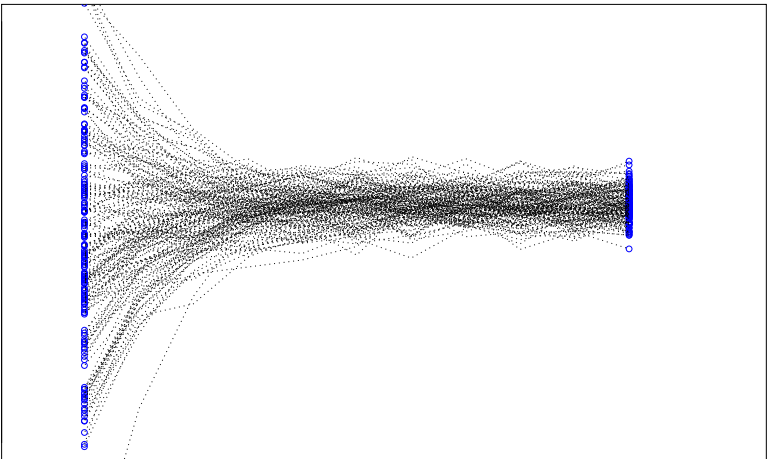
$$\psi^* = \mathcal{L}X_0 = \mathcal{L}X_1 = \mathcal{L}X_2 = \dots$$

Call ψ^* **globally stable** if $\mathcal{L}X_t \rightarrow \psi^*$ independent of X_0 .









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- ▶ To study the equilibrium.
- ▶ Simulation-based econometrics.



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- ▶ Exposit Samuelson's model, and
- ▶ show how to sample from its stationary distribution.



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Single commodity.



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Distribution of ξ_t is φ .

Spot price is p_t .



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Easy to show that there is a maximal state \bar{s} .



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Profit maximization (PM) requires

$$I_t = 0 \text{ whenever } \alpha \mathbf{E}_t p_{t+1} < p_t$$



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Equilibrium consumption: $C(x) = D(p^E(x))$

Equilibrium investment: $I(x) = x - D(p^E(x))$



Relationship to growth theory:



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Equilibrium investment function I is the solution to

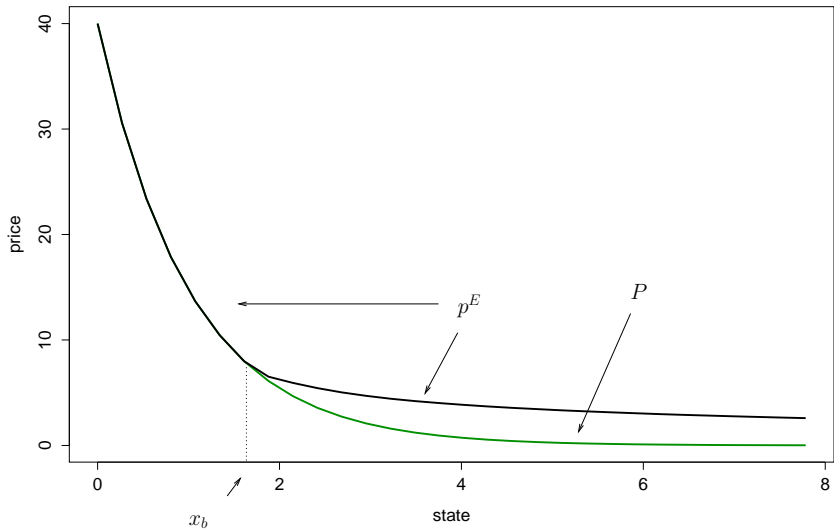
$$\max_i \mathbf{E} \left[\sum_{t=0}^{\infty} U(X_t - i(X_t)) \right]$$

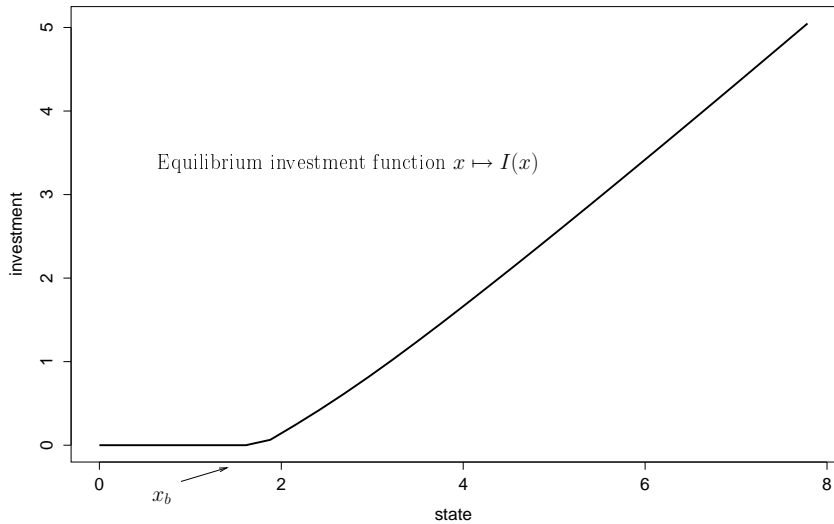
subject to

$$X_{t+1} = \alpha i(X_t) + \xi_{t+1}$$

when U is chosen to satisfy $U' = P = D^{-1}$.







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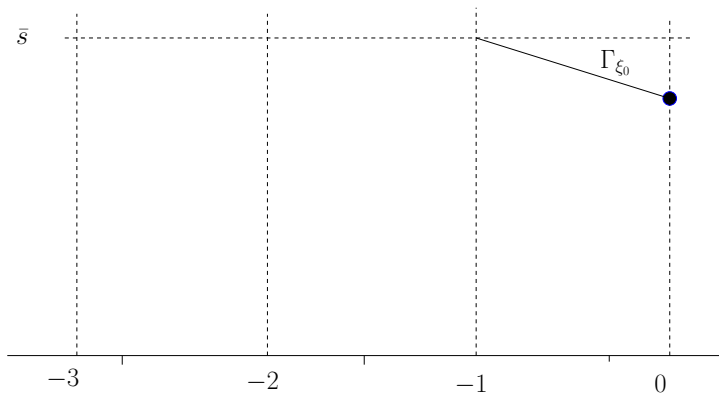
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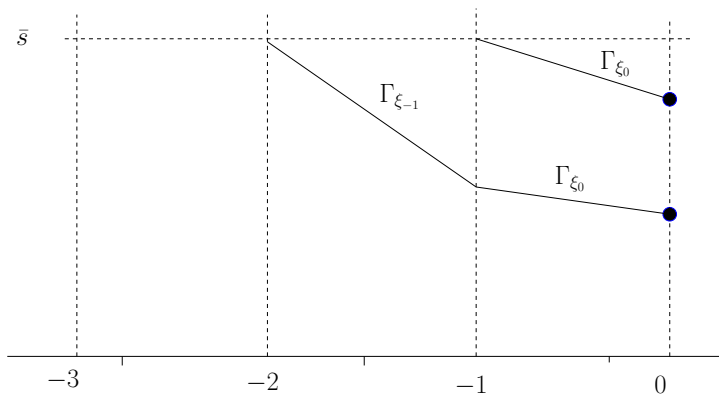
Remarkably, we can do this in **finite** time.



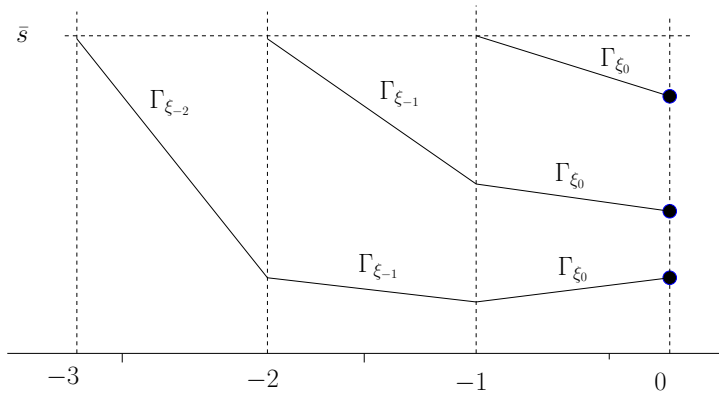
Harvests: (ξ_0)



Harvests: (ξ_{-1}, ξ_0)



Harvests: $(\xi_{-2}, \xi_{-1}, \xi_0)$



Two important properties of paths:

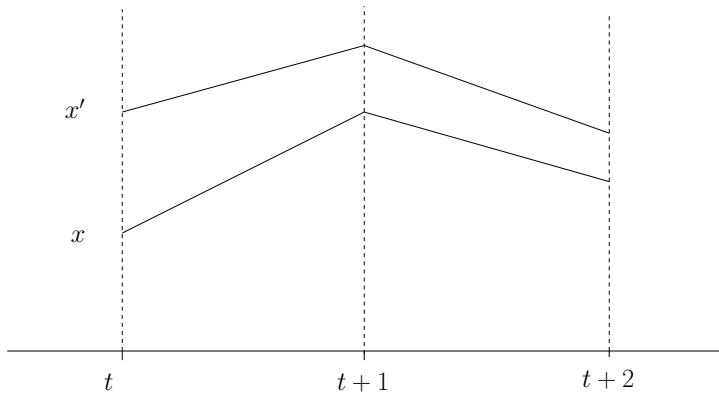


Two important properties of paths:

- Monotonicity: $x \leq x'$ implies

$$\alpha I(x) + z \leq \alpha I(x') + z$$

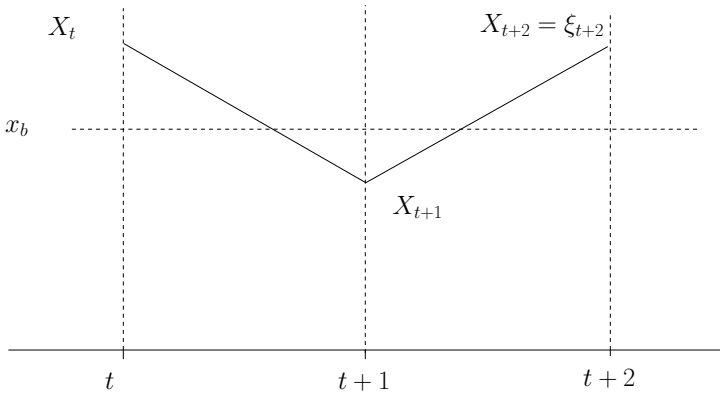


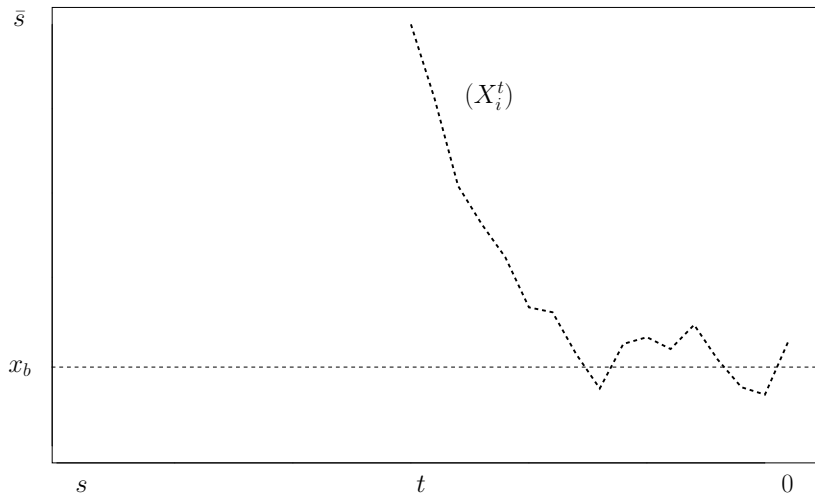


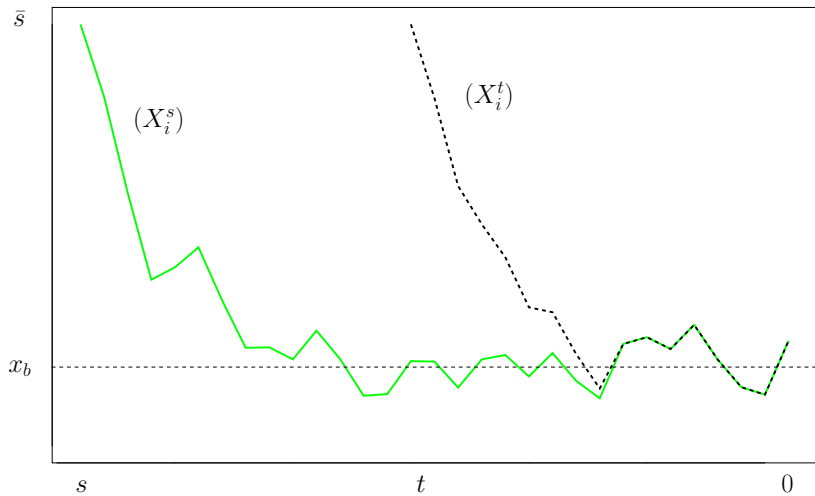
- Non-interiority: $x \leq x_b$ implies

$$\alpha I(x) + z = z$$









```

set  $t = C = 0$  ; set  $X = \bar{s}$  ; set  $Z = ()$  ;
repeat
| draw  $\xi_t \sim \varphi$  and append to list  $Z$  ;
| for  $i$  in  $t, \dots, 0$  do           // iterate until time zero
| | set  $X = \Gamma_{\xi_i}(X)$  ;
| | if  $X \leq x_b$  and  $i < 0$  then set  $C = 1$  ;
| end
| if  $C = 1$  then break ;           // coupling successful
| else
| | set  $t = t - 1$  ;
| | set  $X = \bar{s}$  ;
| end
end
return  $X$ 

```



