view\_frames Result Recorded at time: 749.867 world Broadcaster: /map2world Average rate: 50.040 Hz Most recent transform: 749.882 ( -0.015 sec old) Buffer length: 4.976 sec map Broadcaster: /hector\_mapping Average rate: 11.897 Hz Most recent transform: 749.540 (0.327 sec old) Buffer length: 4.875 sec odom Broadcaster: /odom\_node Average rate: 50.202 Hz Most recent transform: 749.851 (0.016 sec old) Buffer length: 4.960 sec base\_footprint

Broadcaster: /roundbot/robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (749.867 sec old) Buffer length: 0.000 sec base\_link

Broadcaster: /roundbot/robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (749.867 sec old) Buffer length: 0.000 sec

Average rate: 10000.000 Hz Most recent transform: 0.000 (749.867 sec old) Buffer length: 0.000 sec

Broadcaster: /roundbot/robot\_state\_publisher

Broadcaster: /roundbot/robot\_state\_publisher Average rate: 25.202 Hz Most recent transform: 749.865 ( 0.002 sec old)

Buffer length: 4.960 sec

Broadcaster: /roundbot/robot\_state\_publisher Average rate: 25.202 Hz Most recent transform: 749.865 (0.002 sec old)

Buffer length: 4.960 sec

right\_wheel

laser\_rear

left\_wheel

laser\_front