## Mathematics of Program Construction 2019 Porto, Portugal

## Verified Self-Explaining Computation

Jan Stolarek<sup>1,2</sup> James Cheney<sup>1,3</sup>

<sup>1</sup>University of Edinburgh, UK

<sup>2</sup>Lodz University of Technology, Poland <sup>3</sup>The Alan Turing Institute, UK

```
input state: [x \mapsto 1, y \mapsto 0, z \mapsto 2]
```

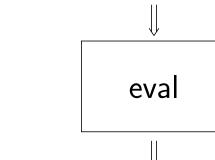
```
if (y = 1) then \{ y := x + 1 \}
           else { y := y + 1 };
z := z + 1
```

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input state: [x \mapsto 1, y \mapsto 0, z \mapsto 2]

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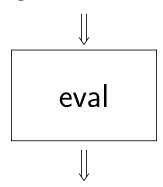


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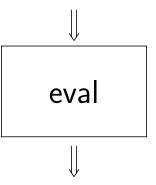
expected:  $[x \mapsto 1, y \mapsto 2, z \mapsto 3]$ 

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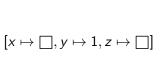
z := z + 1
```



expected: 
$$[x \mapsto 1, y \mapsto 2, z \mapsto 3]$$
  
actual:  $[x \mapsto 1, y \mapsto 1, z \mapsto 3]$ 

# Debugger

## Slicing



```
[x \mapsto \square, y \mapsto 0, z \mapsto \square]
          if (y = 1) then \{ \square \}
                            else \{ y := y + 1 \}; \square
backward slicing
```

$$[x \mapsto \square, y \mapsto 1, z \mapsto \square]$$

```
[x \mapsto \square, y \mapsto 0, z \mapsto \square]
                  if (y = 1) then \{ \bigcap \}
                                       else \{ y := y + 1 \}; \square
      backward slicing
                                                                    forward slicing
[x \mapsto \square, y \mapsto 1, z \mapsto \square]
                                                             [x \mapsto \square, y \mapsto 1, z \mapsto \square]
```

Consider these two extreme cases of backward slicing behaviour:

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  - **consistency**: backward slicing retains code required to produce output we are interested in.
  - minimality: backward slicing produces the smallest partial program and partial input state that suffice to achieve consistency.

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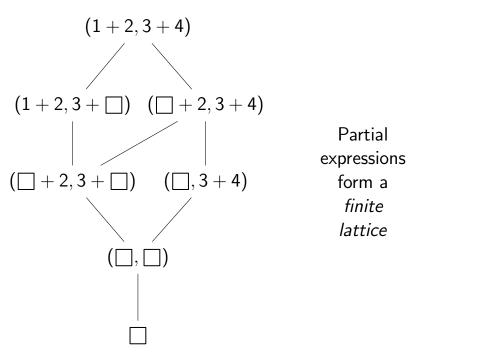
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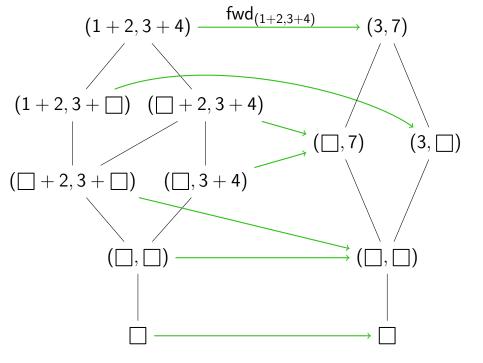
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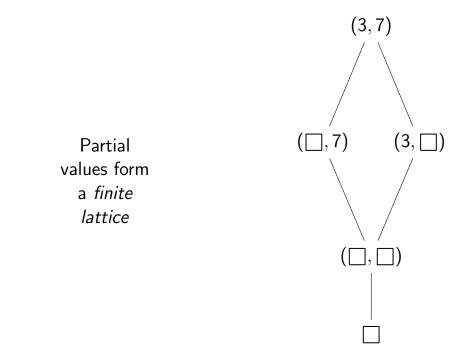
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#### Our contributions:

- minimal and consistent slicing for an imperative language
- proofs formalised in Coq
- a different proof strategy







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$$(P, \sqsubseteq_P), \quad (Q, \sqsubseteq_Q), \quad f: P \to Q, \quad g: Q \to P$$

f and g form a Galois connection (written  $f \dashv g$ ) when

$$f(p) \sqsubseteq_Q q \iff p \sqsubseteq_Q g(q)$$

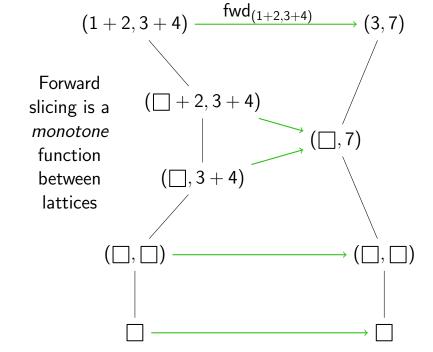
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```
bwd: values_{\square} \rightarrow expressions_{\square}, \quad fwd: expressions_{\square} \rightarrow values_{\square}
```

bwd and fwd form a Galois connection (written  $bwd \dashv fwd$ ) when

 $bwd(slicing\ criterion) \sqsubseteq expr_{\square} \iff slicing\ criterion \sqsubseteq fwd(expr_{\square})$ 

Given a monotone forward slicing function fwd there exists a backward slicing function bwd such that bwd  $\dashv$  fwd.



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The choice of fwd uniquely determines bwd.

In order to prove that bwd ⊢ fwd we need to show that:

- both fwd and bwd are monotone
- deflation property holds:

$$\forall_{q \in Q} \ f(g(q)) \sqsubseteq_Q q$$

inflation property holds:

$$\forall_{p \in P} \ p \sqsubseteq_P g(f(p))$$

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- both fwd and bwd are monotone
- deflation property holds:

$$\forall \ \mathsf{bwd}(\mathsf{fwd}(\mathsf{expr}_{\square})) \sqsubseteq \mathsf{expr}_{\square}$$

inflation property holds:

 $\forall$  slicing criterion  $\sqsubseteq$  fwd(bwd(slicing criterion))

## Our formalisation strategy:

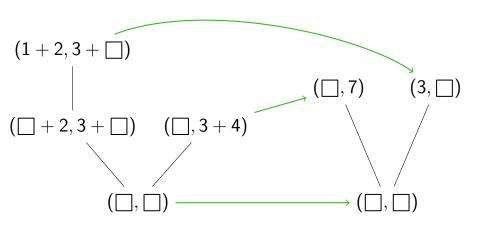
- prove that any functions fulfilling conditions (1)-(3) form a Galois connection
- show that our definitions of forward and backward slicing fulfil conditions (1)-(3)

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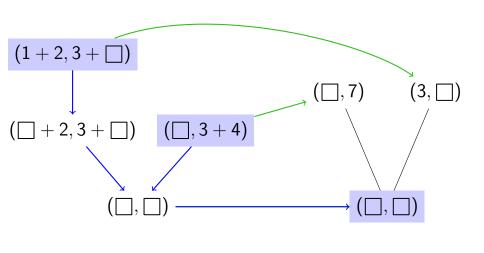
Possible to rely on meet and join preservation instead of monotonicity.

## Forward slicing preserves meets



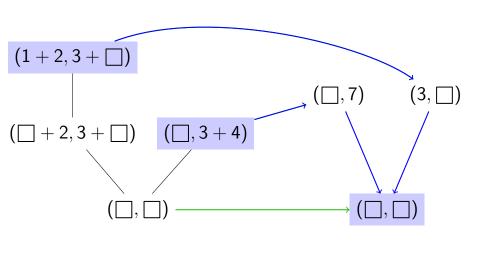
$$fwd(x \sqcap y) = fwd(x) \sqcap fwd(y)$$

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$$a ::= n \mid x \mid a_1 + a_2 \mid a_1 - a_2 \mid a_1 \cdot a_2$$

```
egin{array}{lll} a & ::= & n \mid x \mid a_1 + a_2 \mid a_1 - a_2 \mid a_1 \cdot a_2 \ b & ::= & {\sf true} \mid {\sf false} \mid a_1 = a_2 \mid a_1 \leq a_2 \mid \neg b \mid b_1 \wedge b_2 \end{array}
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```

Forward slicing: notation

$$T :: \mu, e \nearrow v$$

#### Notation:

- T :: execution trace
- ullet  $\mu$  partial state
- e partial program (expression or command)
- v slicing result ( $\mu'$  for commands)

# Forward slicing: expressions

$$\frac{T_1 :: \mu, a_1 \nearrow v_1 \qquad T_2 :: \mu, a_2 \nearrow v_2}{T_1 + T_2 :: \mu, a_1 + a_2 \nearrow v_1 +_{\mathbb{N}} v_2} \quad v_1, v_2 \neq \square$$

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# Forward slicing: expressions

$$\overline{x(v_a) :: \mu, x \nearrow \mu(x)}$$

Important that we read x from  $\mu$  and not  $v_a$  from a trace; we can't assume  $\mu(x)=v_a$ .

$$\frac{T_a :: \mu, a \nearrow v_a}{x := T_a :: \mu, x := a \nearrow \mu[x \mapsto v_a]}$$

$$\overline{x := T_a :: \mu, \Box \nearrow \mu[x \mapsto \Box]}$$

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$$\frac{T_1 :: \mu, \square \nearrow \mu' \qquad T_2 :: \mu', \square \nearrow \mu''}{T_1 \;; \; T_2 :: \mu, \square \nearrow \mu''}$$

$$\frac{T_1 :: \mu, \square \nearrow \mu'}{\text{if}_{\mathsf{true}} \ T_b \ \mathsf{then} \ \{ \ T_1 \ \} :: \mu, \square \nearrow \mu'}$$

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Backward slicing: notation

$$T :: \mu, \mathbf{v} \searrow \mu', \mathbf{e}$$

#### Notation:

- T :: execution trace
- $\mu$ ,  $\nu$  slicing criterion (only  $\mu$  for commands)
- $\bullet$   $\mu', e$  reconstructed partial program (state + code)

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#### Also:

- ullet  $arnothing_{\mu}$  all variables map to  $\square$ , same domain as  $\mu$
- Ø empty state (no variables)

Backward slicing: base cases

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# Backward slicing: variable assignments

$$\overline{x := T_a :: \mu[x \mapsto \Box] \searrow \mu[x \mapsto \Box], \Box}$$

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$$\overline{x := T_a :: \mu[x \mapsto \Box] \setminus \mu[x \mapsto \Box], \Box}$$

$$\frac{T_a :: v_a \searrow \mu_a, a}{x := T_a :: \mu[x \mapsto v_a] \searrow \mu_a \sqcup \mu[x \mapsto \Box], x := a} \quad v_a \neq \Box$$

## Backward slicing: conditionals

$$\frac{\mathcal{T}_1 :: \mu \searrow \mu', c_1 \qquad \mathcal{T}_b :: \mathtt{true} \searrow \mu_b, b}{\mathtt{if}_{\mathtt{true}} \ \mathcal{T}_b \ \mathtt{then} \ \{ \ \mathcal{T}_1 \ \} :: \mu \searrow \mu' \sqcup \mu_b, \mathtt{if} \ b \ \mathtt{then} \ \{ \ c_1 \ \} \ \mathtt{else} \ \{ \ \Box \ \}} \quad c_1 \neq \Box$$

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 $\overline{\text{while}_{\text{false}} \ T_b :: \mu \searrow \mu, \square}$ 

$$\frac{T_{w} :: \mu \searrow \mu_{w}, \square \qquad T_{c} :: \mu_{w} \searrow \mu_{c}, c \qquad T_{b} :: \mathtt{true} \searrow \mu_{b}, b}{\mathtt{while}_{\mathtt{true}} \ T_{b} \ \mathtt{do} \ \{ \ T_{c} \ \}; \ T_{w} :: \mu \searrow \mu_{c} \sqcup \mu_{b}, \mathtt{while} \ b \ \mathtt{do} \ \{ \ c \ \}} \quad c \neq \square$$

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- slicing defined as a (dependent) function; takes evaluation evidence; refine tactic used to construct evidence
- proofs of monotonicity, inflation, and deflation for defined slicing functions

### Summary

We have developed a slicing algorithm for imperative programs based on Galois connections and formalised it in Coq.

#### More in the paper:

- full rules for forward and backward slicing
- extended example involving loops
- details of Coq formalisation

#### Future work:

formalisation of a full-scale language

Implementation available at:

https://bitbucket.org/jstolarek/gc\_imp\_slicing

# Mathematics of Program Construction 2019 Porto, Portugal

## Verified Self-Explaining Computation

Jan Stolarek<sup>1,2</sup> James Cheney<sup>1,3</sup>

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Minimality:

$$\mathsf{bwd}_e(v') = \bigcap \{e' \mid v' \sqsubseteq \mathsf{fwd}_e(e')\}$$