

A Dirichlet Process Mixture Model for Spherical Data

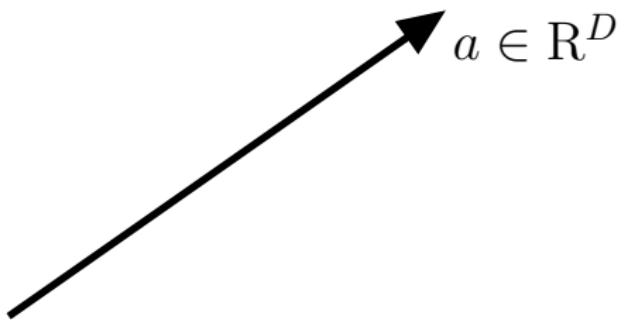
Julian Straub

Jason Chang, Oren Freifeld, John W. Fisher III
Massachusetts Institute of Technology

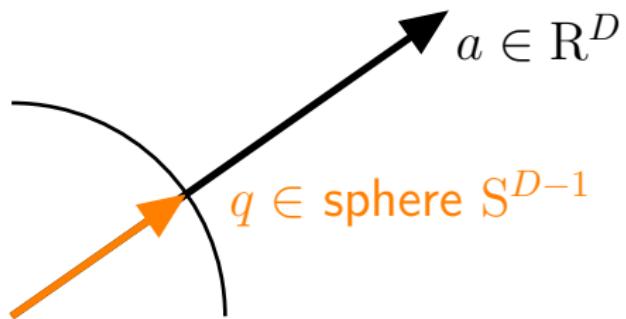
September 22, 2017



Data on the Sphere = Directional Data

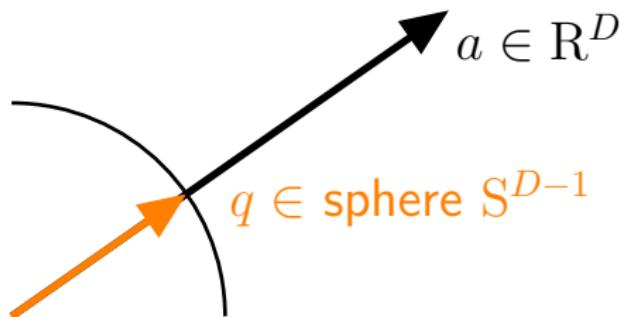


Data on the Sphere = Directional Data



$$a = q\|a\|_2$$

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Interested in:

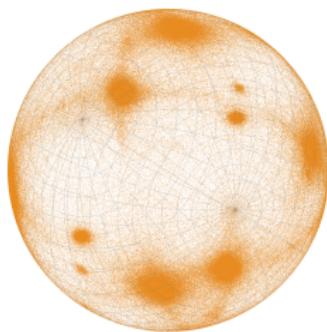
directional data = data on the sphere S^{D-1}
 \Rightarrow all information contained in direction q

Native Directional Data



Examples of directional data ($\|a\|_2 = 1$):

- surface normals [Furukawa 2009, Holz 2011, Straub 2014]



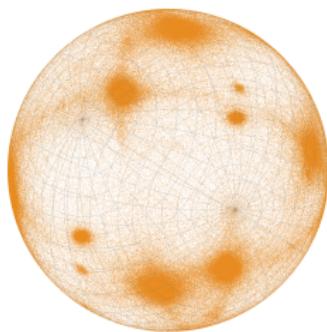
[Straub 2014]

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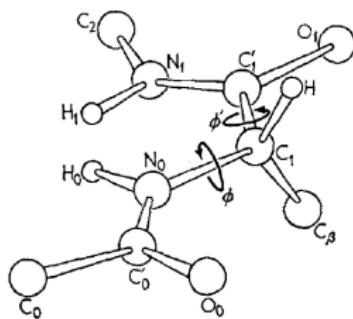


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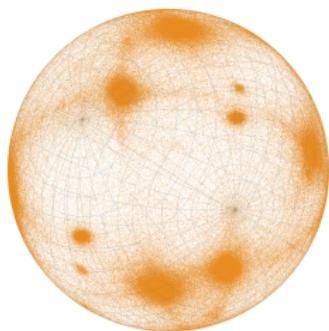


[Ramachandran 1965]

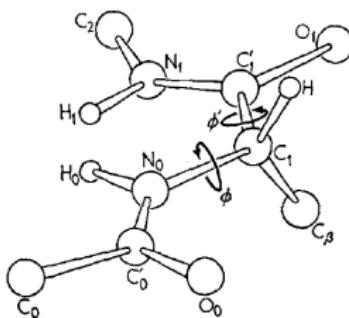
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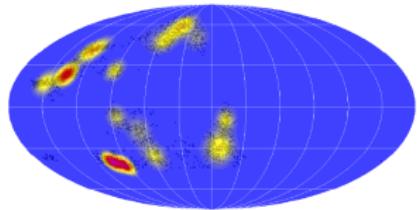
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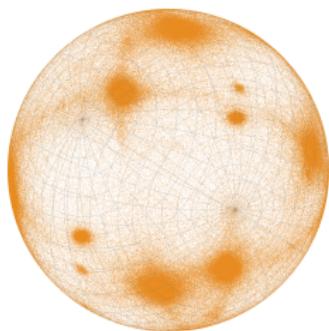


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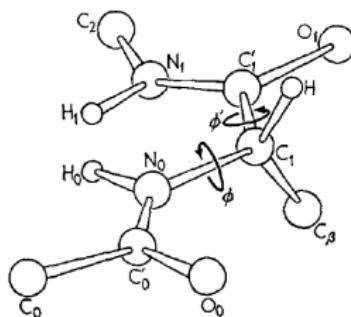
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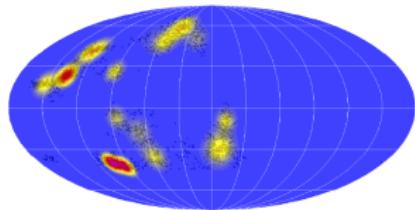
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- quaternions representing 3D rotations [Choe 2006]



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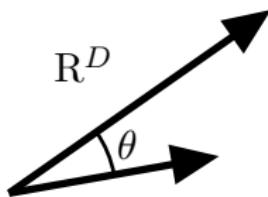
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Euclidean Data Treated as Directional Data



have Euclidean data and use angular deviation for comparison

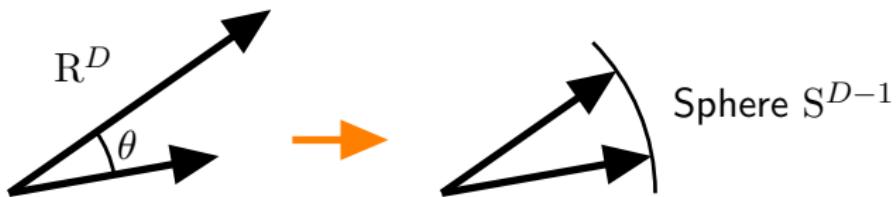
$$(\text{cosine distance } \cos(\theta) = \frac{a^T}{\|a\|_2} \frac{b}{\|b\|_2})$$



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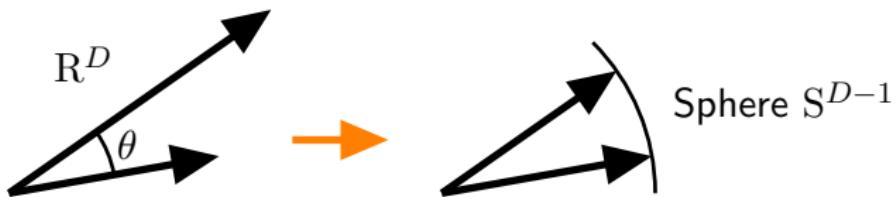
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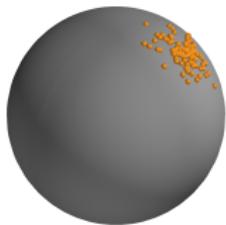


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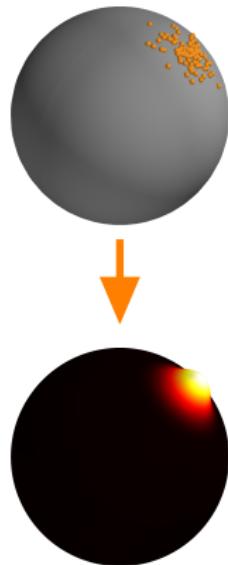
Representative examples:

- semantic word vectors (word2vec) [Mikolov 2013]
- word frequency counts [Dhillon 2001, Strehl 2000]
- gene expression data [Banerjee 2005]

Distributions on the Sphere

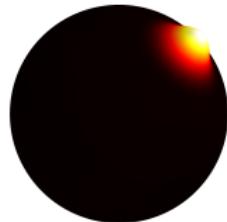
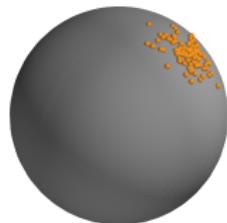


Distributions on the Sphere



von-Mises-Fisher (vMF)
Kent, Bingham

Distributions on the Sphere

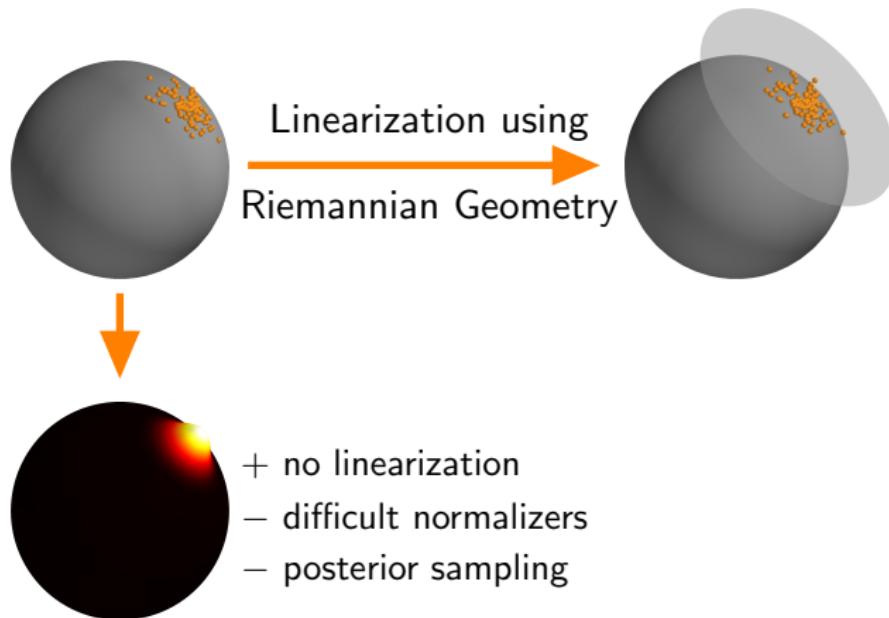


- + no linearization
- difficult normalizers
- posterior sampling

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Kent, Bingham

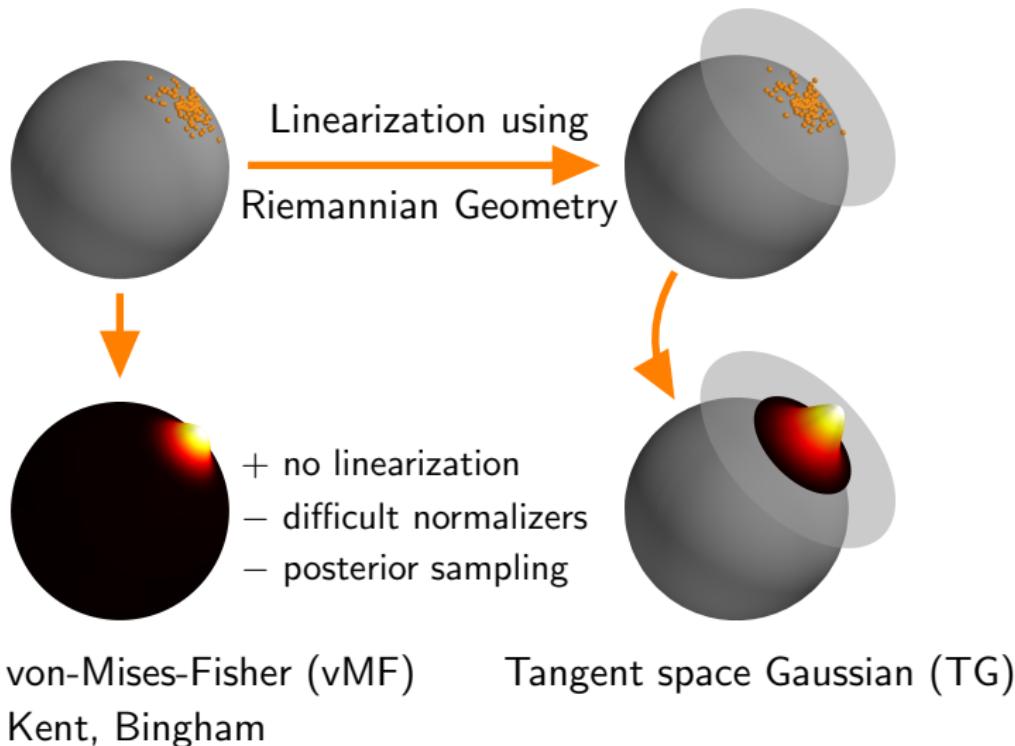
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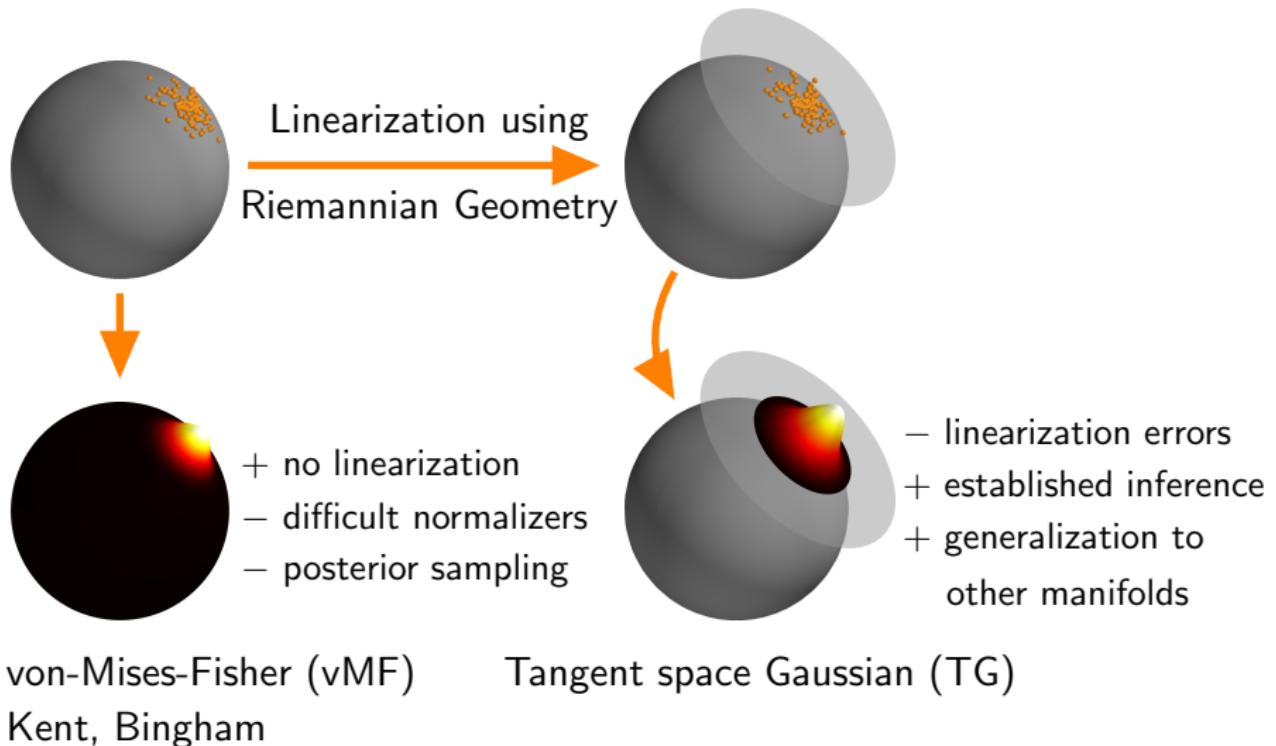
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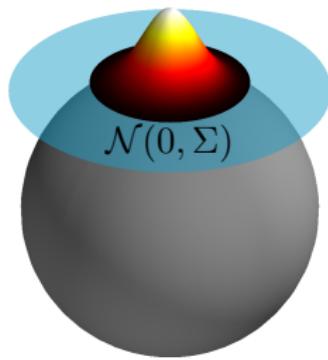


Tangent Space Gaussian via Riemannian Geometry



Tangent space Gaussian (TG)

(see Pennec 1999)



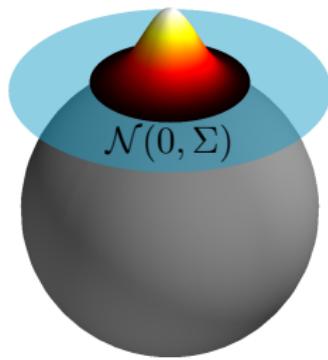
mean $\mu \in S^{D-1}$

covariance Σ in tangent space

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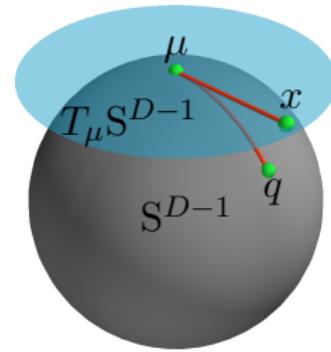


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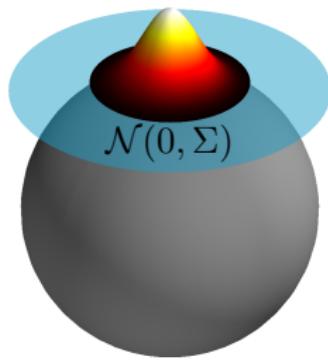


$x = \text{Log}_\mu(q)$ logarithm map
 $q = \text{Exp}_\mu(x)$ exponential map

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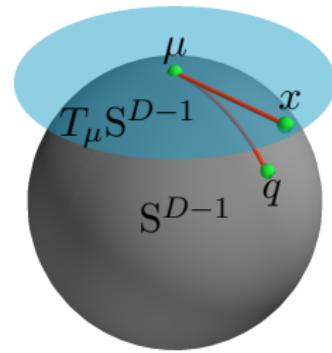


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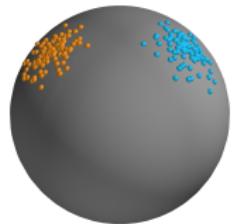
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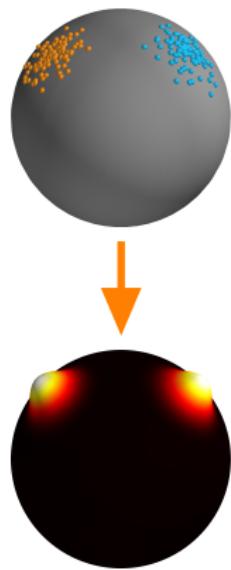
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$$q \sim \mathcal{N}(\text{Log}_\mu(q); 0, \Sigma)$$

Mixture Models on the Sphere

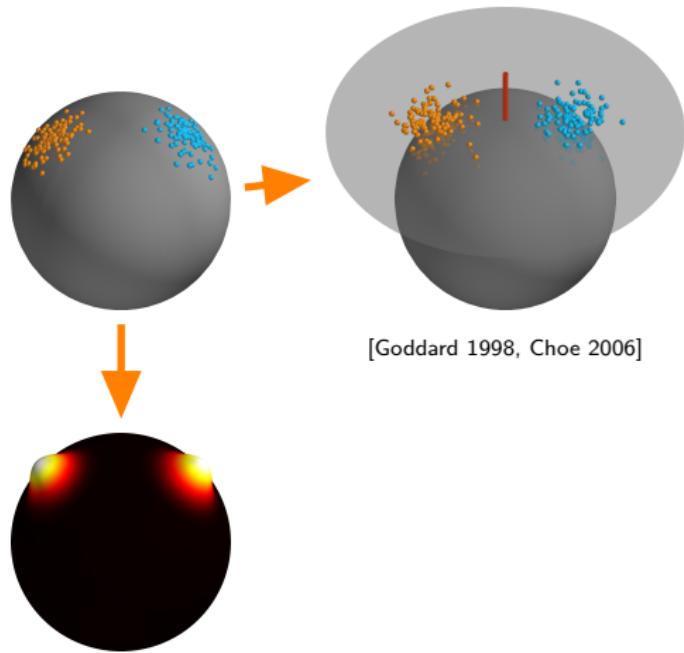


Mixture Models on the Sphere



[Peel 2001, Bangert 2010]

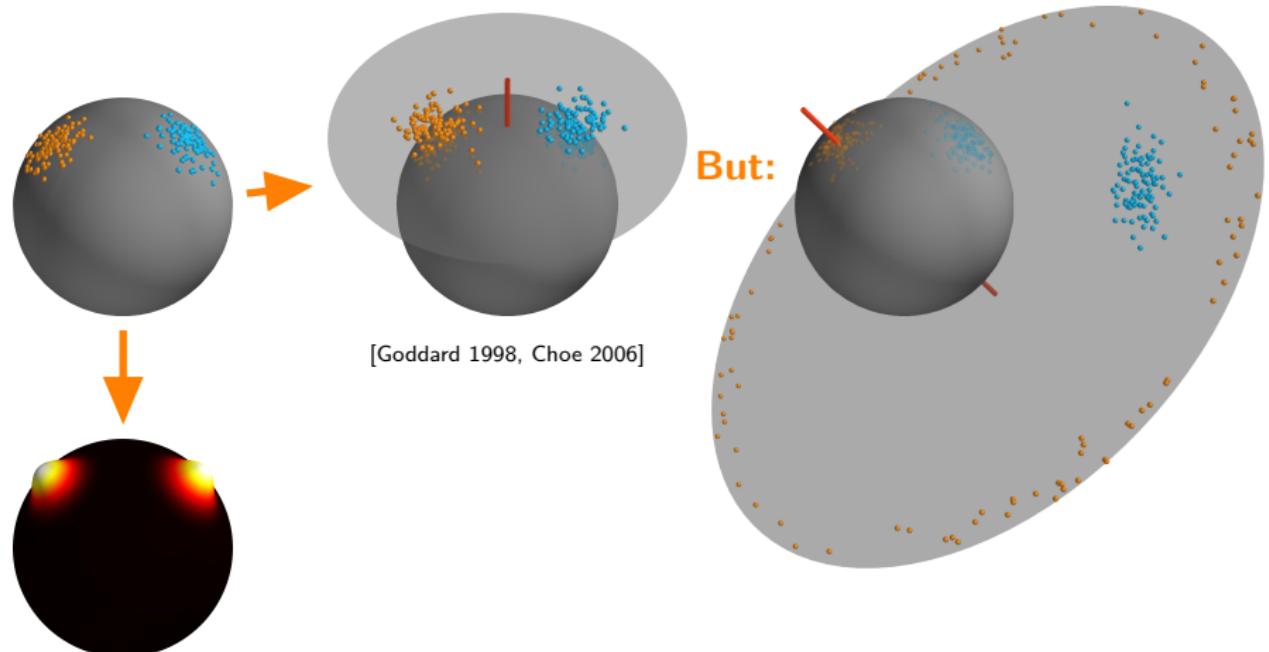
Mixture Models on the Sphere



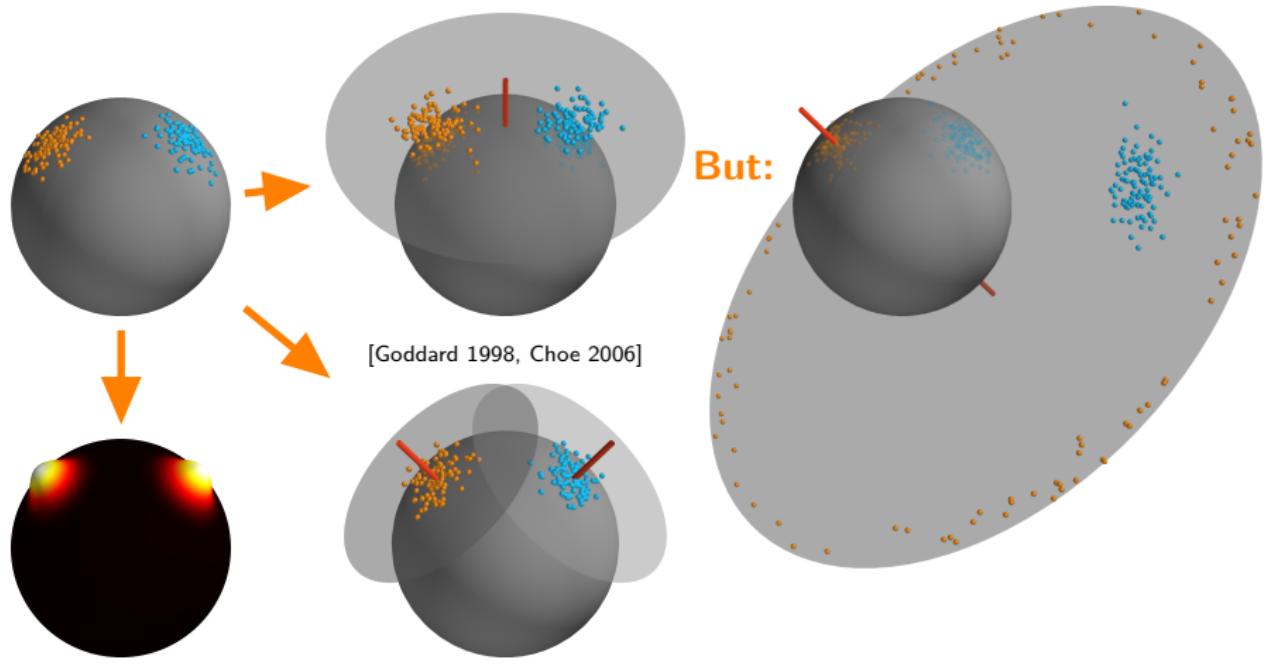
[Goddard 1998, Choe 2006]

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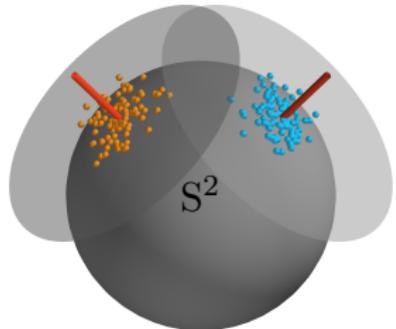
[Feiten 2013, Simo-Serra 2014]

Dirichlet Process Tangent Gaussian Mixture Model



Goals:

- flexible mixture model for directional data
- anisotropic component distributions
- efficient manifold-respecting inference

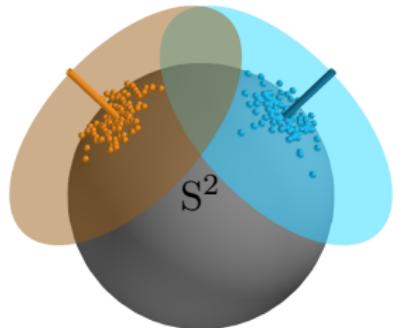


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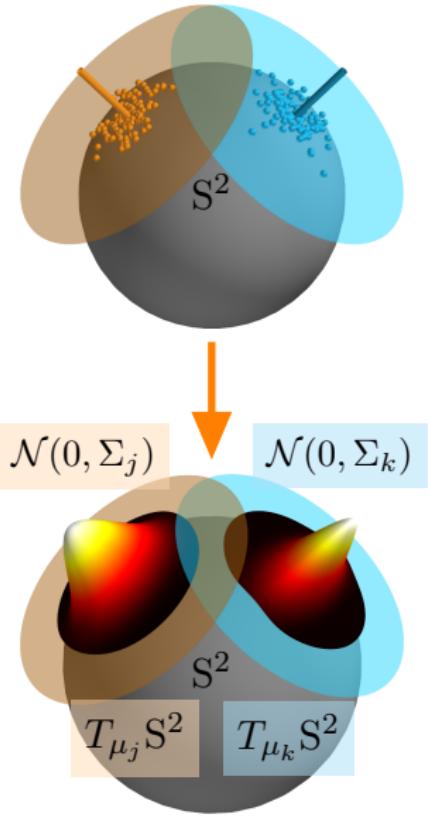


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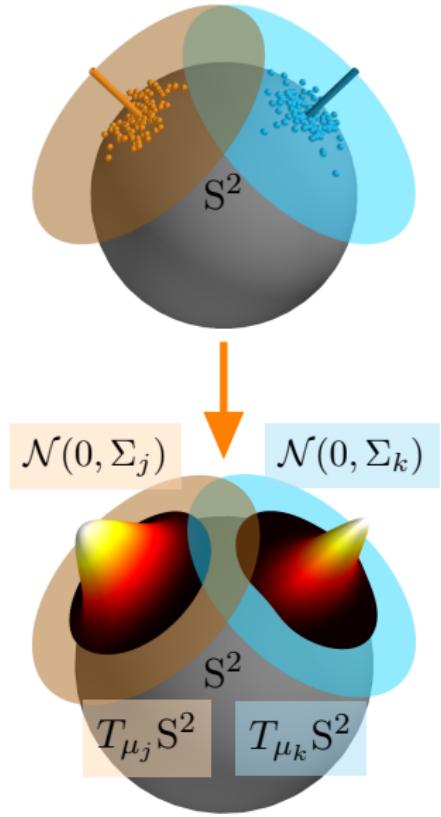


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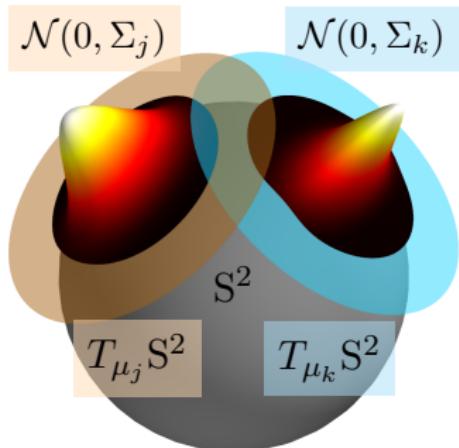
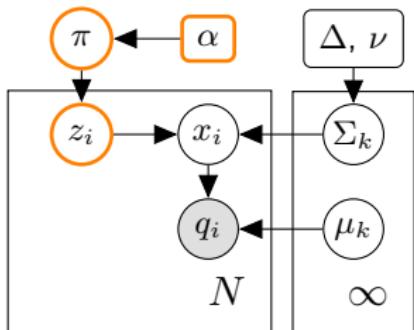
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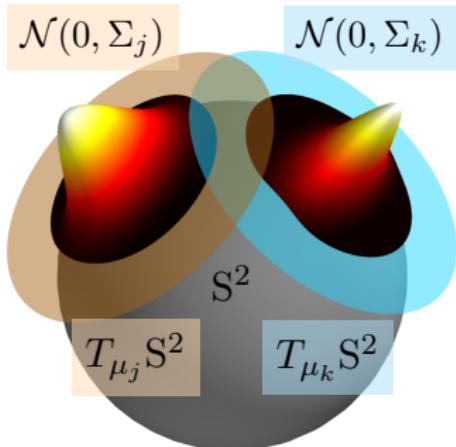
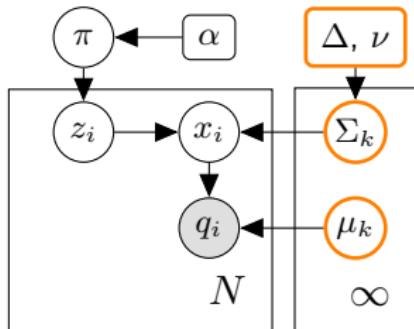
DP-TGMM Generative Model



$$\pi \sim \text{GEM}(1, \alpha)$$

$$z_i \sim \text{Cat}(\pi)$$

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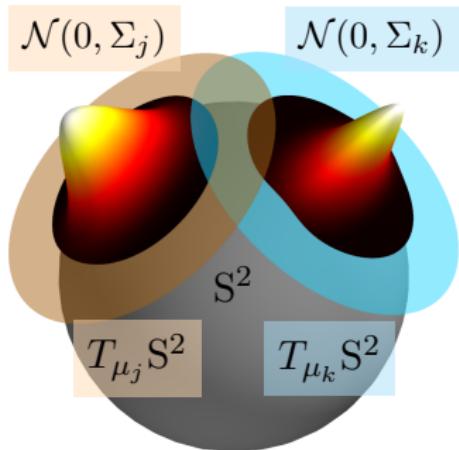
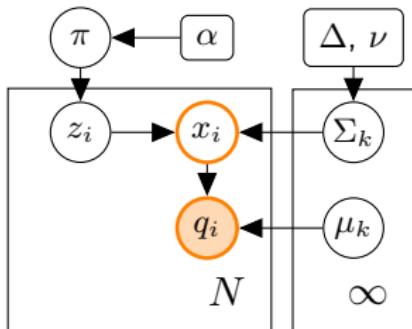
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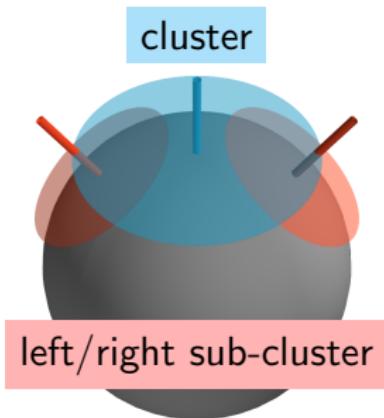
restricted Gibbs sampler with Metropolis-Hastings split/merge proposals

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1: z  $\leftarrow 1$ ,  $K \leftarrow 1$ 
2: for  $t \in \{1, \dots, T\}$  do
3:   sample parameters
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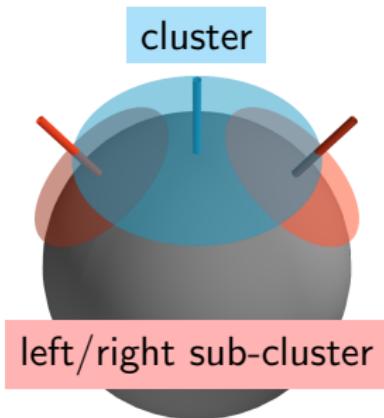


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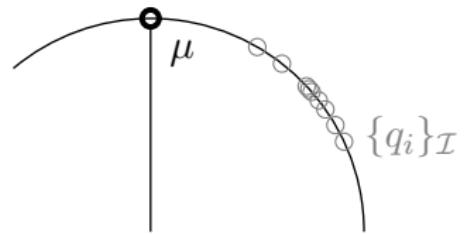
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- efficient manifold-aware inference

Efficient Manifold-aware Inference



Problem: inference requires frequent computation of sufficient statistics of $\{q_i\}_{\mathcal{I}}$ in $T_{\mu}S^{D-1}$, where μ changes each iteration.

$$S_{\mu} = \sum_{i \in \mathcal{I}} \text{Log}_{\mu}(q_i) \text{Log}_{\mu}(q_i)^T$$

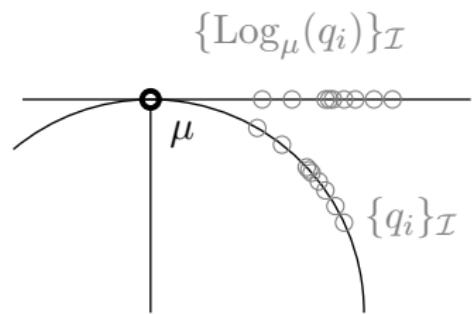


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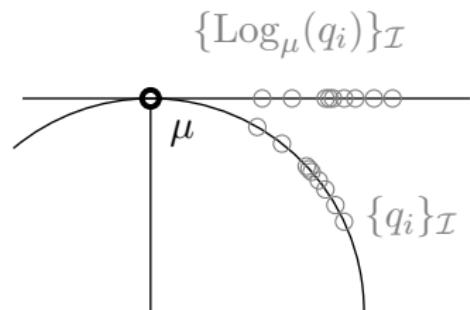
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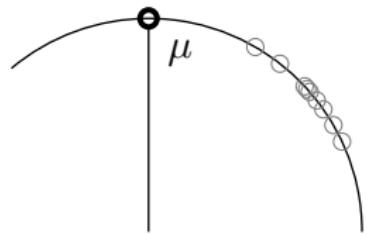


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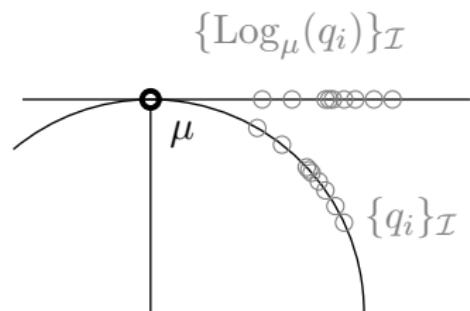
Solution: approximate S_{μ} using Karcher mean \tilde{q} of data [Karcher 1977]



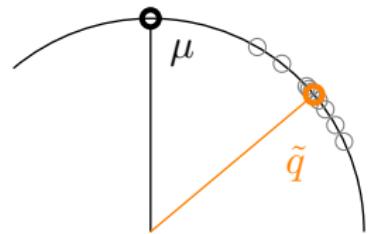
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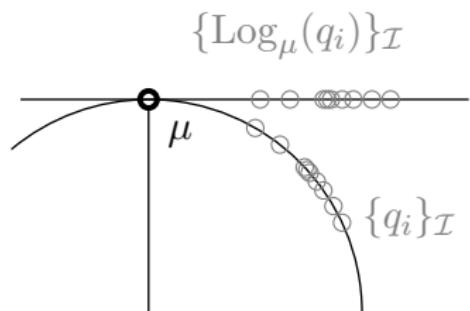
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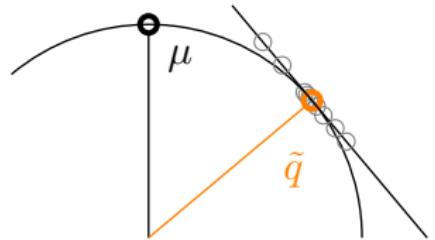
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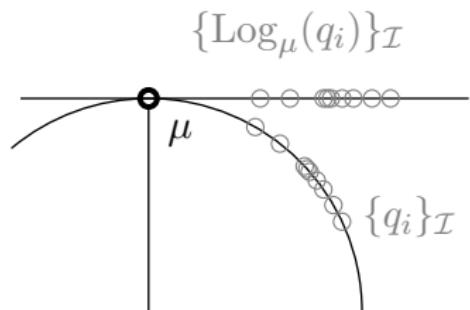
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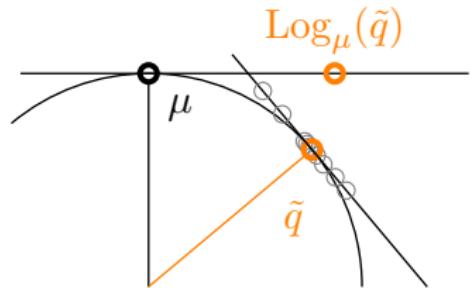
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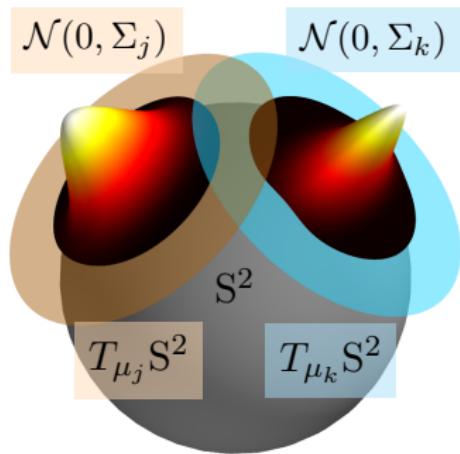
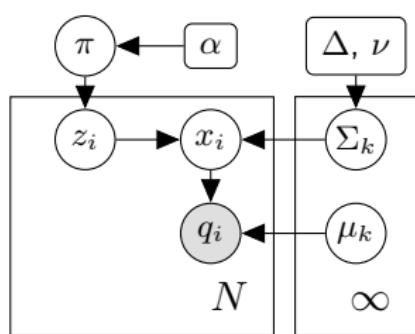
$$S_{\mu} \approx S_{\tilde{q}} + N \text{Log}_{\mu}(\tilde{q}) \text{Log}_{\mu}(\tilde{q})^T$$



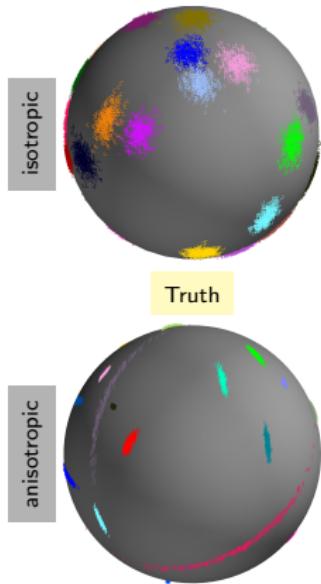
DP-TGMM Recap

Approach and Contributions:

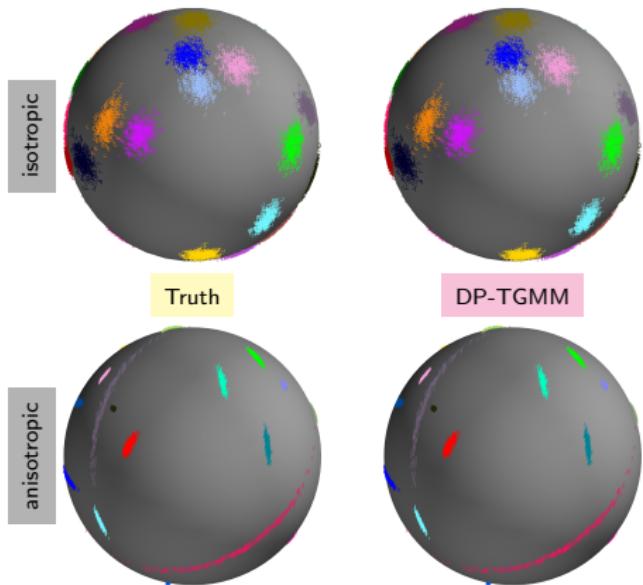
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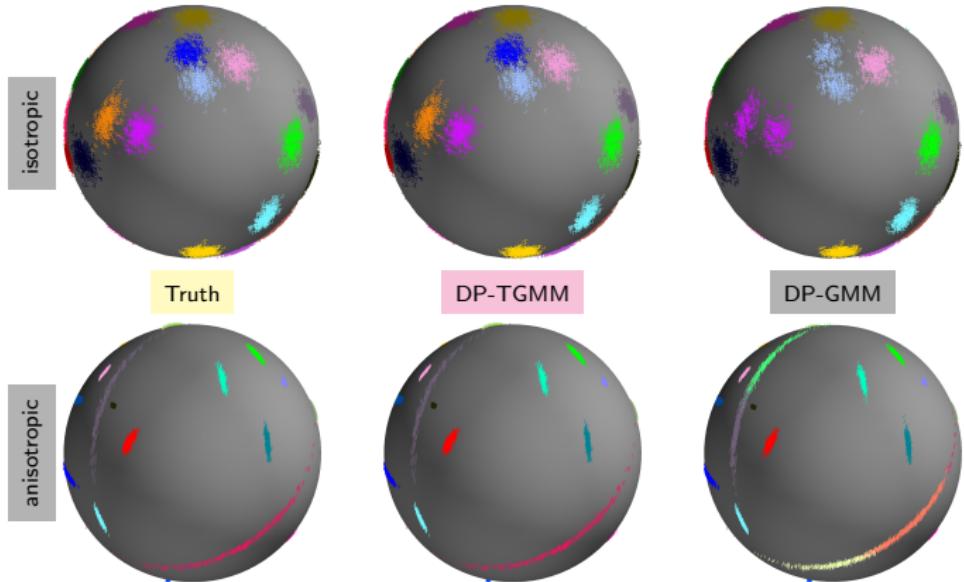
Synthetic Data – Number of Clusters



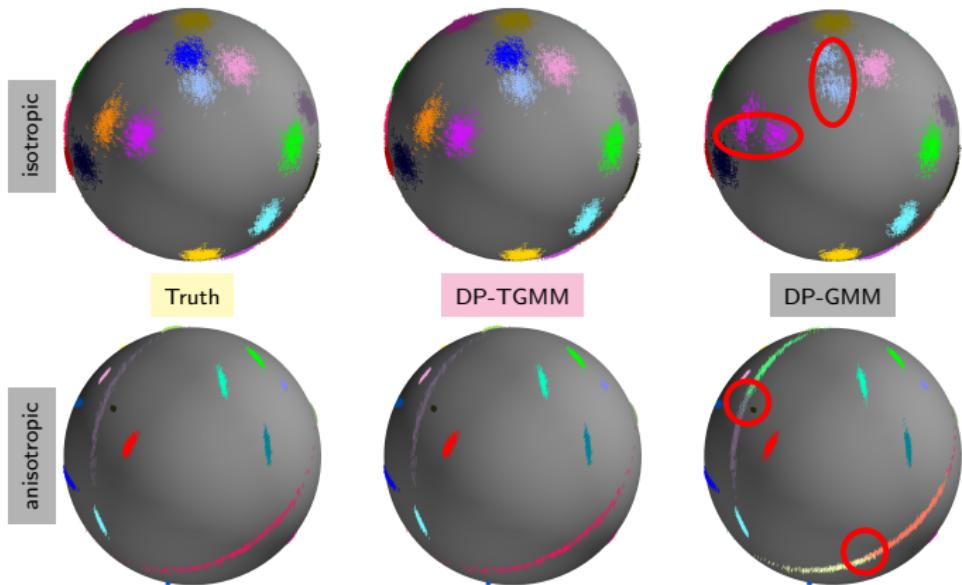
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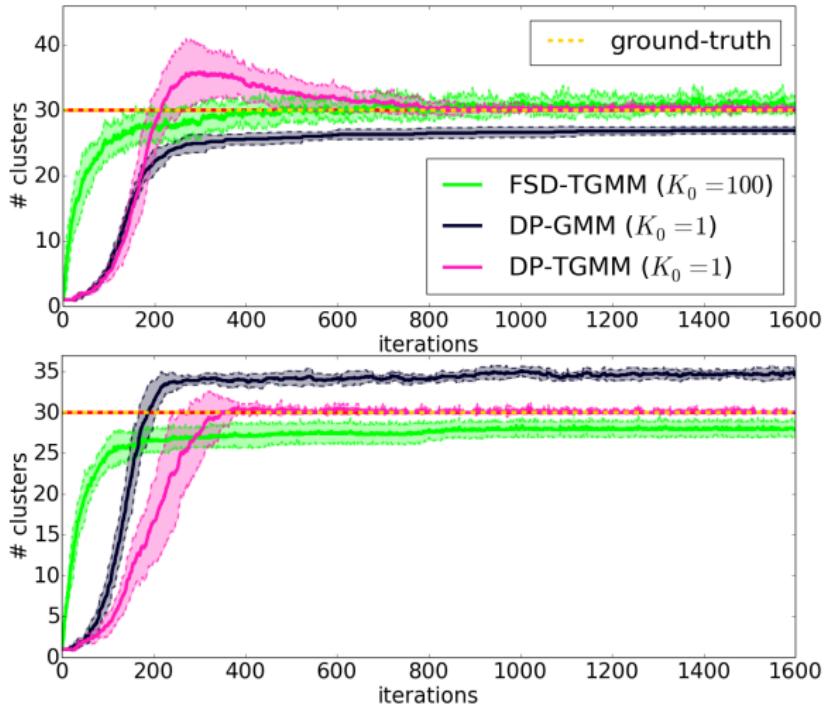
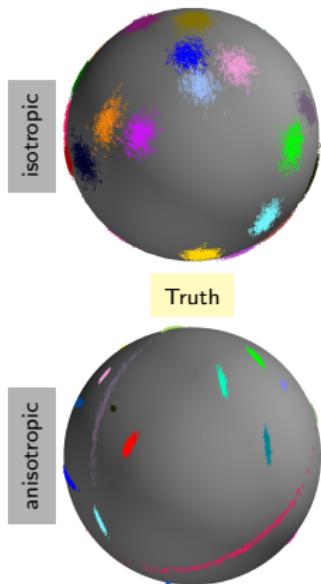
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Synthetic Data – Number of Clusters



Semantic Word Vectors (word2vec)



word $\xrightarrow{\text{word2vec}}$ embedding space (here 20D) [Mikolov et al. 2013]

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semantically similar words have small angular deviation

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“finance”	“music”	“religion”	“leisure”	“government”	“food”
funding	symphonic	orthodoxy	malls	parliamentary	tomatoes
prospective	operatic	orthodox	hotels	enacted	edible
loans	soloists	evangelical	dining	parliament	fruit
financing	orchestral	christians	nightlife	delegation	meats
funds	music	primacy	outdoor	unanimously	meat
contracts	waltz	preaching	upscale	granting	vegetables
compensation	trios	doctrines	shopping	mandate	juice
regulations	lute	rabbis	restaurants	constitutional	baked
assets	soloist	clergy	taverns	citizenship	corn
investors	flute	catholicism	shops	committee	tasting

Semantic Word Vectors (word2vec) – Covariances



condition number $\kappa = \frac{\max \text{eig}(\Sigma)}{\min \text{eig}(\Sigma)}$ for each inferred cluster



$\kappa > 1 \Rightarrow$ anisotropic covariance



$\kappa = 1 \Rightarrow$ isotropic covariance

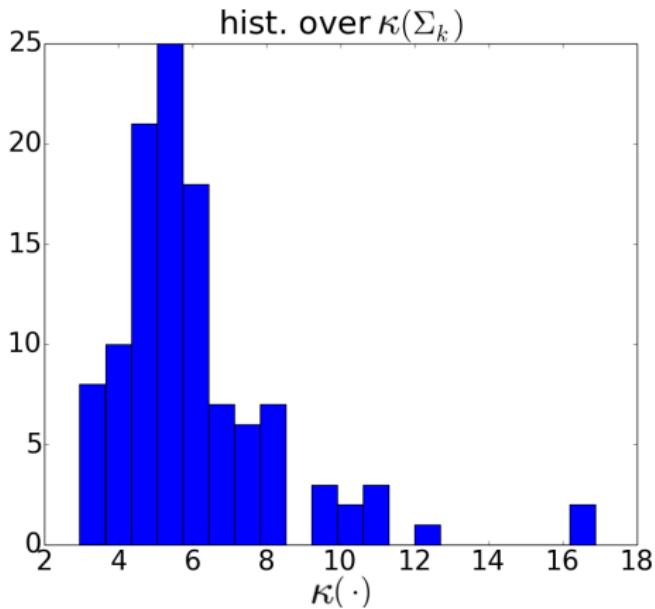
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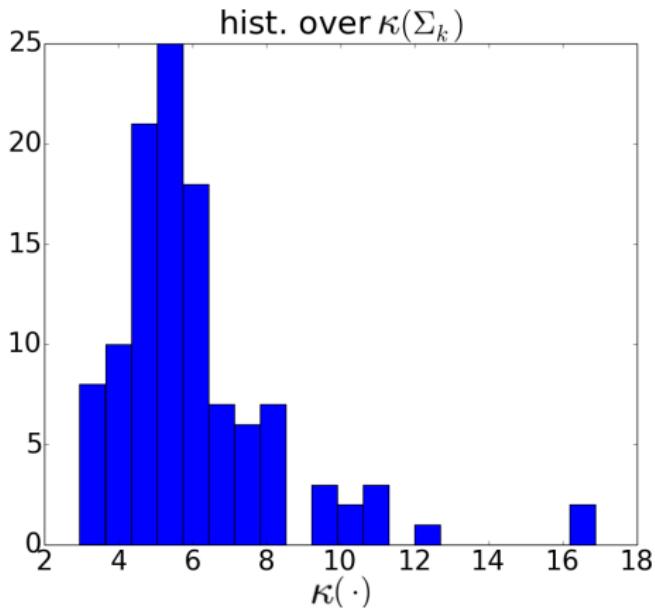
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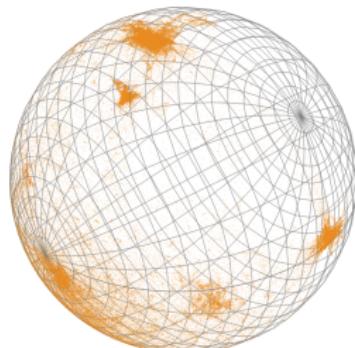
\Rightarrow inferred clusters are anisotropic

Directional Segmentation

directional scene segmentation = clustering of scene's surface normals



image of scene



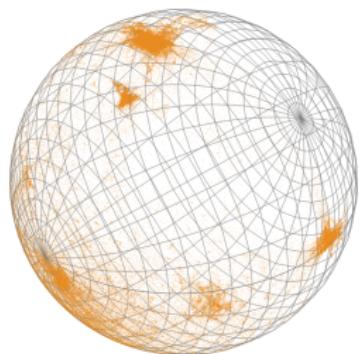
surface normals

Directional Segmentation

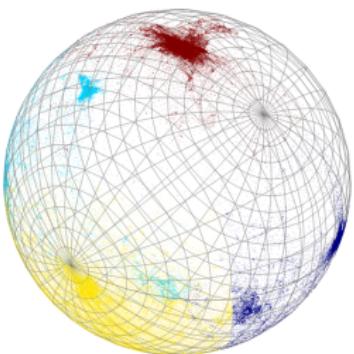
directional scene segmentation = clustering of scene's surface normals



image of scene



surface normals



surface normal clustering

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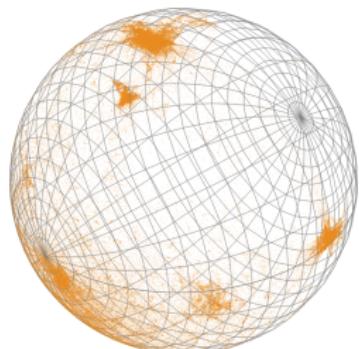
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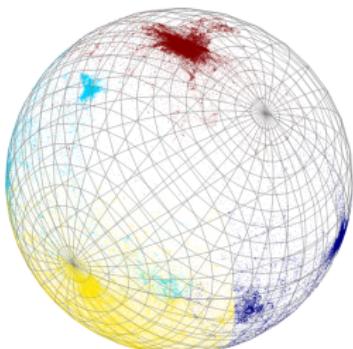
image of scene



directional segmentation



surface normals



surface normal clustering

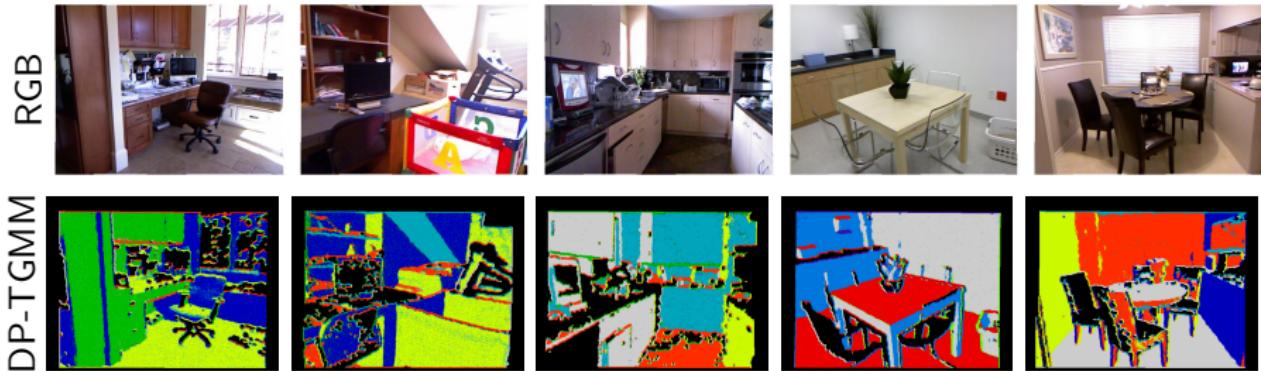
Directional Segmentation of NYU RGB-D Dataset



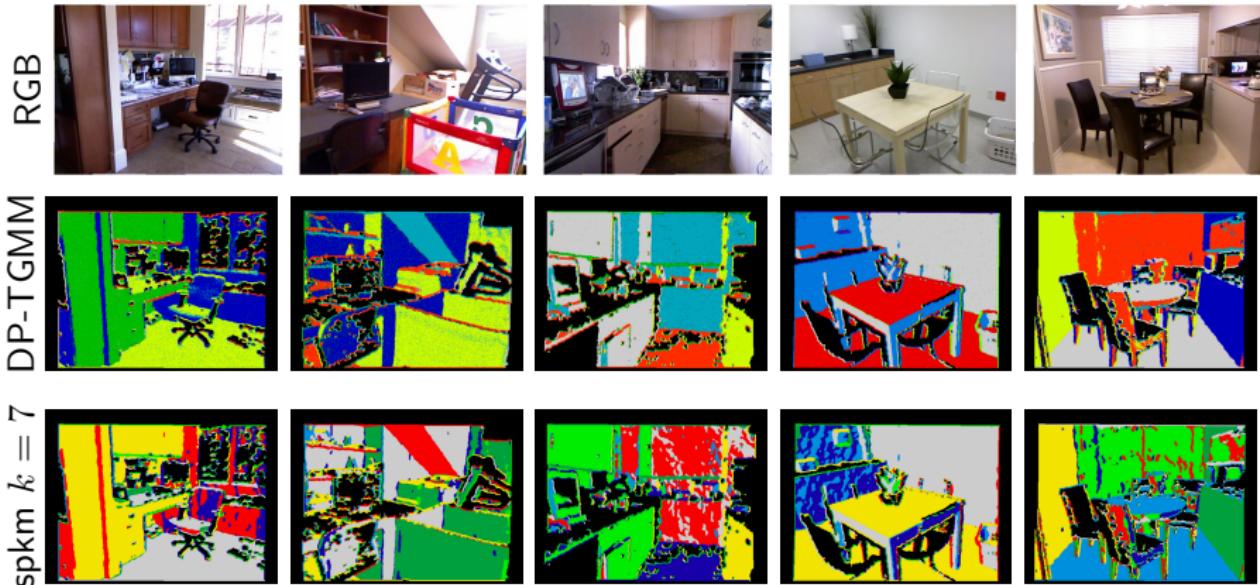
RGB



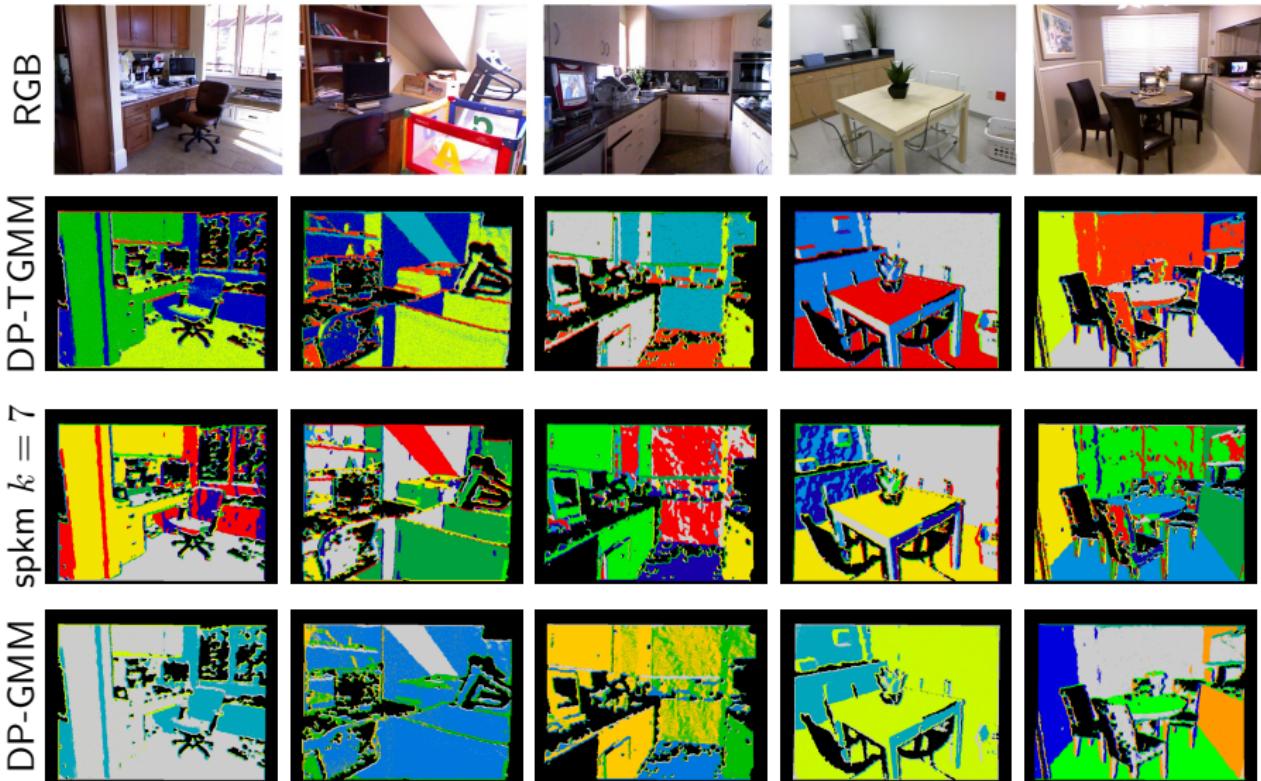
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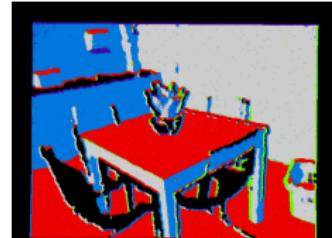
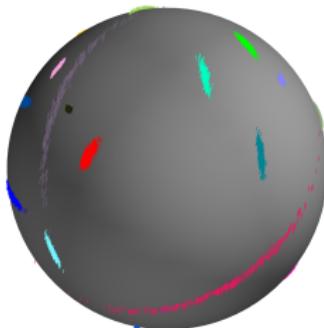
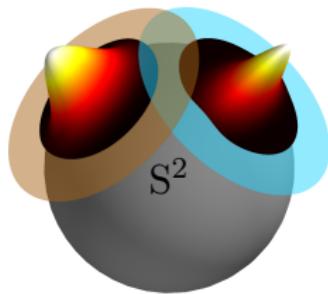
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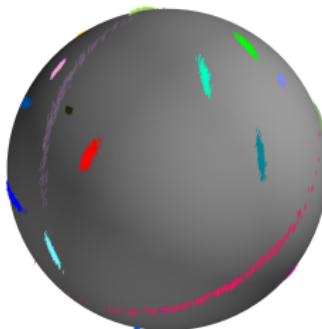
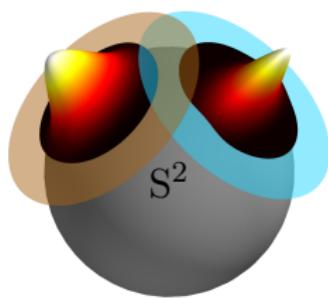


Conclusion



- Bayesian nonparametric mixture model for directional data
- anisotropic component distributions on the sphere
- efficient manifold-aware MCMC inference

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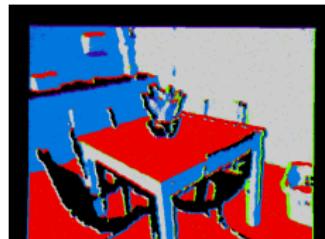
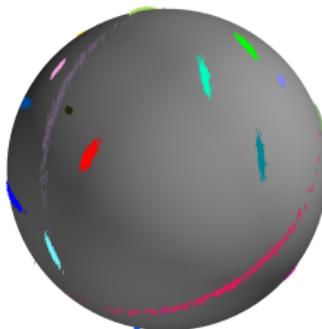
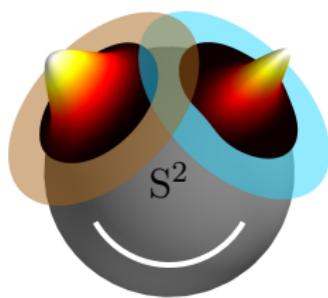


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Future work:

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- hierarchical models

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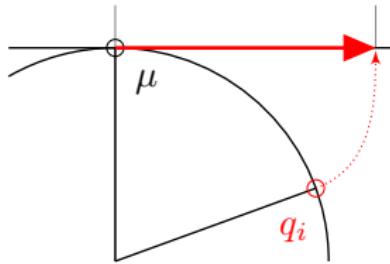
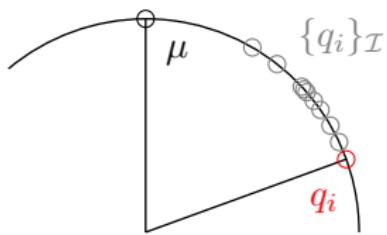
Future work:

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links to paper, slides and code are at <http://people.csail.mit.edu/jstraub/>

Efficient Manifold-aware Inference

Problem: inference requires frequent mapping $\{q_i\}_{\mathcal{I}}$ into $T_{\mu}S^{D-1}$, where μ changes each iteration.

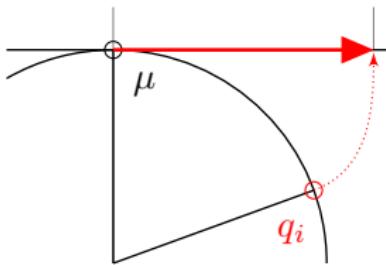
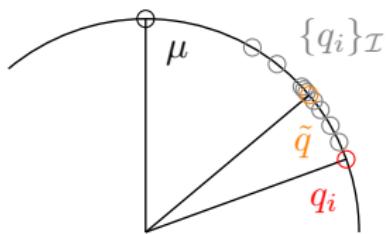


$$\text{Log}_{\mu}(q_i)$$

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Solution: approximate $\text{Log}_{\mu}(q)$ using Karcher mean [Karcher 1977] \tilde{q} of data

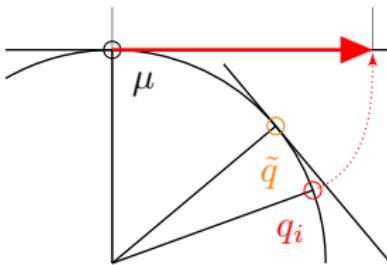
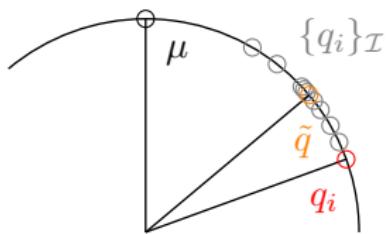


$$\tilde{q} = \arg \min_{p \in S^{D-1}} \sum_{i \in \mathcal{I}} \arccos^2(p^T q_i) \quad \text{Log}_{\mu}(q_i)$$

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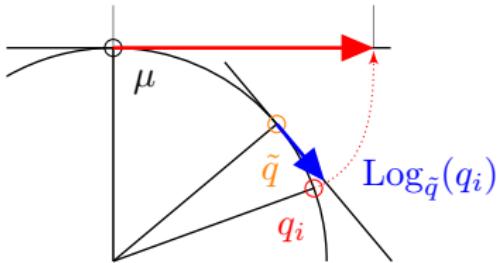
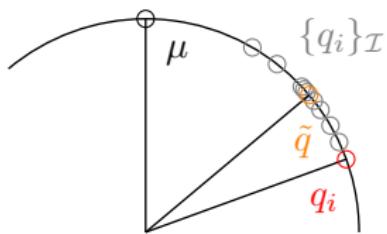


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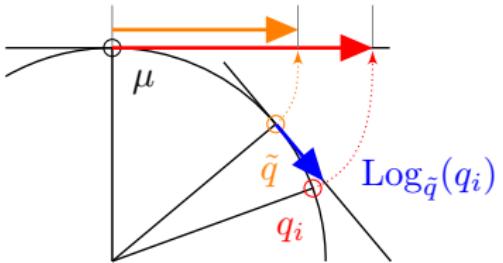
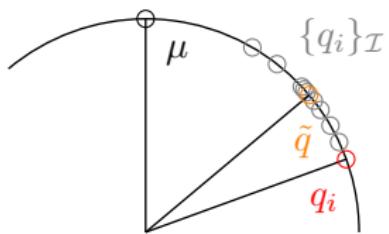


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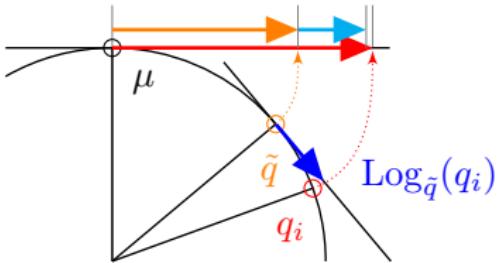
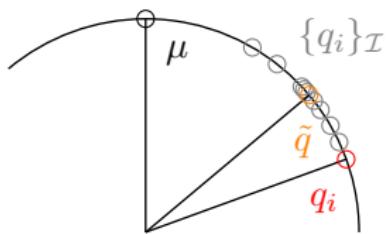
$$\text{Log}_{\mu}(q_i) \approx \text{Log}_{\mu}(\tilde{q})$$

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$$\tilde{q} = \arg \min_{p \in S^{D-1}} \sum_{i \in \mathcal{I}} \arccos^2(p^T q_i) \quad \text{Log}_{\mu}(q_i) \approx \text{Log}_{\mu}(\tilde{q}) + R_{\tilde{q}}^{\mu} \text{Log}_{\tilde{q}}(q_i)$$