

Computational Finance

Course notes

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The source code for this document (and many more) can be found at:
<https://github.com/jstringara/Latex-projects/tree/master/ARF>

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Chapter 1

Lecture 1:

1.1 Introduction

We will study Lévy processes and extend the Black and Scholes theory. We will depart from analytical formulas and use MonteCarlo techniques, partial differential equations, partial differential integral equations and Fast-Fourier transforms.

1.2 Black and Scholes

The Black and Scholes model is defined by the following stochastic differential equation:

$$\begin{cases} dS_t = \mu S_t dt + \sigma S_t dW_t \\ S_0 = s \end{cases}$$

Chapter 2

Lecture 2:

2.1 Poisson Process

In order to define the Poisson Processes we must first recall and explore the notions of:

- Exponential Random Variable
- Poisson Distribution

2.1.1 Exponential Random Variable

A random variable Y is said to be exponentially distributed with parameter $\lambda > 0$ if it has the following probability density function:

$$f_Y(y) = \lambda e^{-\lambda y} \mathbb{1}_{\mathbb{R}_+}(y)$$

or equivalently that it has the following cumulative distribution function:

$$F_Y(y) = 1 - e^{-\lambda y} \mathbb{1}_{\mathbb{R}_+}(y)$$

and we write $Y \sim \text{Exp}(\lambda)$.

Theorem 1 (Absence of Memory). *Let $T \geq 0$ be a random variable such that:*

$$\mathbb{P}(T > t + s | T > s) = \mathbb{P}(T > t) \quad \forall t, s > 0$$

then T can only be exponentially distributed.

In other words, the exponential distribution is the only continuous distribution with absence of memory.

Proof.

- (\Leftarrow) We start with $T \sim \text{Exp}(\lambda)$, then its pdf is:

$$f_T(y) = \lambda e^{-\lambda y} \mathbb{1}_{\mathbb{R}_+}(y)$$

Thus:

$$\begin{aligned} \mathbb{P}(T > t + s | T > s) &= \frac{\mathbb{P}(T > t + s)}{\mathbb{P}(T > s)} = \frac{\int_{t+s}^{\infty} \lambda e^{-\lambda y} dy}{\int_s^{\infty} \lambda e^{-\lambda y} dy} = \frac{e^{-\lambda(t+s)}}{e^{-\lambda t}} \\ &= e^{-\lambda s} = \int_s^{\infty} \lambda e^{-\lambda y} dy = \mathbb{P}(T > s) \end{aligned}$$

- (\Rightarrow) We define $g(t) = \mathbb{P}(T > t)$, then thanks to the hypothesis we get:

$$g(t + s) = \mathbb{P}(T > t + s) = \mathbb{P}(T > t + s | T > t) \mathbb{P}(T > t) = \mathbb{P}(T > s) \mathbb{P}(T > t) = g(s)g(t)$$

Now, g is decreasing and right continuous thanks to the definition of a CDF.

Theorem. *The function $g(t) = e^{-\lambda t}$ is the only function that satisfies the two requirements above.*

Thus:

$$\mathbb{P}(T \leq t) = 1 - \mathbb{P}(T > t) = 1 - g(t) = 1 - e^{-\lambda t} \implies T \sim \text{Exp}(\lambda)$$

□

2.1.2 Poisson Distribution

Let N be a random variable with integer values, then N is said to be Poisson distributed with parameter $\lambda > 0$ if it has the following probability mass function:

$$\mathbb{P}(N = n) = \frac{\lambda^n}{n!} e^{-\lambda} \mathbb{1}_{\mathbb{N}}(n)$$

and we write $N \sim \text{Pois}(\lambda)$. Its moment generating function is given by:

$$M_N(u) = \mathbb{E}[e^{uN}] = e^{\lambda(e^u - 1)}$$

We will now create a sort of "bridge" between the exponential distribution and the Poisson distribution.

Counting Process

Theorem 2 (Counting Process). *Let $\{\tau_n\}$ be a sequence of iid random variables with exponential distribution with parameter $\lambda > 0$, then $\forall t > 0$, we define:*

$$N_t = \inf_t \left\{ n \geq 0 : \sum_{i=1}^{n+1} \tau_i > t \right\}$$

Then we can say that N_t is a Poisson distributed random variable with parameter λt . Hence:

$$\mathbb{P}(N_t = n) = \frac{(\lambda t)^n}{n!} e^{-\lambda t} \mathbb{1}_{\mathbb{N}}(n)$$

Remark 3. For us the sequence $\{\tau_n\}$ will be a sequence of inter-arrival times, i.e. the time between two consecutive jumps of the process. N_t is called the **counting process**. It counts the number of jumps of the process up to time t .

Proof. Let us define the process $T_n = \sum_{i=1}^n \tau_i$. Now, since $\tau_i \sim \text{Exp}(\lambda)$, then we have that the PDF of T_n is:

$$P_n(t) = \lambda e^{-\lambda t} \frac{(\lambda t)^{n-1}}{(n-1)!} \mathbb{1}_{\mathbb{R}_+}(t)$$

thus:

$$\begin{aligned} \mathbb{P}(T_{n+1} > t) &= \int_t^\infty P_{n+1}(s) ds = 1 - \overbrace{\int_0^t P_{n+1}(s) ds}^{\mathbb{P}(T_{n+1} \leq t)} = 1 - \int_0^t \underbrace{\lambda e^{-\lambda s}}_f \underbrace{\frac{(\lambda s)^n}{n!}}_{g'} ds \\ \text{integrating by parts} &= 1 + \underbrace{e^{-\lambda t}}_f \underbrace{\frac{(\lambda t)^n}{n!}}_g - \int_0^t \underbrace{e^{-\lambda s}}_f \underbrace{\frac{(\lambda s)^n}{n!}}_{g'} n ds \\ &= 1 + e^{-\lambda t} \frac{(\lambda t)^n}{n!} - \int_0^t \lambda e^{-\lambda s} \frac{(\lambda s)^{n-1}}{(n-1)!} ds \\ &= 1 + e^{-\lambda t} \frac{(\lambda t)^n}{n!} - \mathbb{P}(T_n < t) = e^{-\lambda t} \frac{(\lambda t)^n}{n!} + \mathbb{P}(T_n \geq t) \end{aligned}$$

Hence we can write:

$$\mathbb{P}(N_t = t) = \mathbb{P}(T_{n+1} > t) - \mathbb{P}(T_n \geq t) = e^{-\lambda t} \frac{(\lambda t)^n}{n!}$$

thus $N_t \sim \text{Pois}(\lambda t)$. □

Remark 4.

1. If $Y_1 \sim \text{Pois}(\lambda_1)$ and $Y_2 \sim \text{Pois}(\lambda_2)$ are independent, then $Y_1 + Y_2 \sim \text{Pois}(\lambda_1 + \lambda_2)$.
2. If $Y \sim \text{Pois}(\lambda)$, then we can divide it into:

$$Y = \sum_{i=1}^n Y_i \quad \text{where } Y_i \sim \text{Pois}\left(\frac{\lambda}{n}\right)$$

TODO: ask if the definition is done with \geq or $>$ in the indicator function.

Definition 5 (Poisson Process (PP)). Let $\{T_n\}$ be a sequence of iid random variables with exponential distribution with parameter $\lambda > 0$, and $T_n = \sum_{i=1}^n \tau_i$, then:

$$N_t = \sum_{n=1}^{\infty} \mathbb{1}_{\{t > T_n\}}$$

is called a Poisson Process with intensity λ .

Properties 6.

- $N_t \sim \text{Pois}(\lambda t)$ if $t > 0$.
- N_t is a Cadlag process. Hence it is right continuous and has left limits.
- its characteristic function can be computed as:

$$\Phi_{N_t}(u) = \mathbb{E}[e^{iuN_t}] = e^{\lambda t(e^{iu} - 1)}$$

We also call $\psi_{N_t}(u) = \lambda t(e^{iu} - 1)$ the characteristic exponent of N_t .

- N_t has independent increments, i.e. $\forall t_1, \dots, t_n$, we have that:

$$N_{t_n} - N_{t_{n-1}} \perp\!\!\!\perp \dots \perp\!\!\!\perp N_{t_2} - N_{t_1} \perp\!\!\!\perp N_{t_1} - \cancel{N_0} \xrightarrow{0}$$

We have so far defined the Weiner process, the Poisson process and we will at this point move onto the compound Poisson process and the compensated Poisson process. We will now see that the Poisson process is a special case of the compound Poisson process.

Let us take a family of iid random variables $\{Y_n\}$ and a sequence of iid random variables $\{\tau_n\}$ with exponential distribution of parameter $\lambda > 0$. Just like we did above we can define the process $T_n = \sum_{i=1}^n \tau_i$ and the counting process $N_t = \sum_{n=1}^{\infty} \mathbb{1}_{\{t \geq T_n\}}$. Now we move on to define the compound Poisson process.

Definition 7 (Compound Poisson Process (CPP)). Let $\{Y_n\}$ be a sequence of iid random variables and $\{\tau_n\}$ be a sequence of iid random variables with exponential distribution of parameter $\lambda > 0$. Let also these two families be independent, such that $Y_i \perp\!\!\!\perp N_t = \sum_{n=1}^{\infty} \mathbb{1}_{\{t \geq T_n\}}$. Then we define the compound Poisson process as:

$$Y_t = \sum_{n=1}^{\infty} Y_n \mathbb{1}_{\{t \geq T_n\}}$$

Given a compound Poisson process Y_t , we can represent graphically its path as a step function, where the jump sizes are given by the values of Y_n and the time elapsed between two consecutive jumps is given by τ_n .

TODO: add graph of a step function with the jumps and the time elapsed between them.

One unsatisfactory aspect of the Poisson process is that it is not a Martingale. Indeed, take any two times s and t such that $s < t$, then:

$$\mathbb{E}[N_t | N_s] = \mathbb{E}[N_t - N_s + N_s | N_s] = \mathbb{E}[N_t - N_s | N_s] + N_s = \mathbb{E}[N_t - N_s] + N_s = \lambda(t - s) + N_s \neq N_s$$

Definition 8. Let N_t be a Poisson process with intensity $\lambda > 0$, then the compensated Poisson process is defined as:

$$\tilde{N}_t = N_t - \lambda t$$

This is no longer a counting process since (due to the λt term) it is not strictly integer valued. However, it is a Martingale. Indeed by the same reasoning as above we have that:

$$\mathbb{E}[\tilde{N}_t | \tilde{N}_s] = \mathbb{E}[\tilde{N}_t - \tilde{N}_s | \tilde{N}_s] + \tilde{N}_s = \mathbb{E}[\tilde{N}_t - \tilde{N}_s] + \tilde{N}_s = 0 + \tilde{N}_s = \tilde{N}_s$$

Theorem 9 (Uniqueness of the Poisson Process). Let N_t be a counting process with intensity $\lambda > 0$, with integer values and independent and stationary increments then it can only be a Poisson process.

TODO: check definition of stationarity.

Definition 10 (Stationary). Let X_t be a stochastic process, then we say that it is stationary if $\forall t_1, \dots, t_n$ and $\forall h > 0$ we have that:

$$(X_{t_1}, \dots, X_{t_n}) \sim (X_{t_1+h}, \dots, X_{t_n+h})$$

Recall. For the Weiner process we have that $W_t \sim \mathcal{N}(0, t) \stackrel{L}{=} \sqrt{t}\mathcal{N}(0, 1)$. Thus simulating a Weiner process is rather simple as it only requires to simulate a normal random variable of mean 0 and variance 1. On the other hand, for the Poisson process we have:

- $\{\tau_n\}$ iid $\text{Exp}(\lambda)$
- $N_t \sim \text{Pois}(\lambda t)$

if we want to simulate a Poisson process we need to simulate either the inter-arrival times themselves or directly the counting process.

- The first method, that of simulating is called **Countdown Sampling**. And can be achieved in MATLAB with the following code:

```

1  % Countdown Simulation
2  lambda = 2;
3  t = 1;
4  tau = icdf('Exponential', rand, 1/lambda);
5  while (sum(tau) < t) %this is just the condition that we are before T
6  tau_temp = icdf('Exponential', rand, 1/lambda) #?????????
7  tau = [tau, tau_temp];
8  end
9  Nt = length(tau)-1;
10 T = cumsum(tau);
11 T = T(1:end-1); %the last time is beyond T

```

TODO: finish the coding part

Chapter 3

lecture 3: 19/09

3.1 Lèvy processes

In quite simple words a Lèvy process is a stochastic process with independent and stationary increments. We will see that this is a very strong property and useful property that allows us to model many phenomena. In particular we will try to model stocks prices of the form $S_t = S_0 e^{rt + X_t}$ where X_t is a Lèvy process.

Example.

1. Brownian motion W_t
2. $-\frac{\sigma}{2}t + \sigma W_t$

Definition 11 (Lèvy process). Let X_t be a Cadlag stochastic process, such that $X_0 = 0$. We say that X_t is a Lèvy process if it satisfies the following properties:

- i X_t has independent increments, i.e. for $0 \leq t_1 < t_2 < \dots < t_n$ we have that:

$$X_{t_1} - \overset{0}{X_0} \perp\!\!\!\perp X_{t_2} - X_{t_1} \perp\!\!\!\perp \dots \perp\!\!\!\perp X_{t_n} - X_{t_{n-1}}$$

- ii X_t has stationary increments, i.e. $\forall t, s > 0$ we have that:

$$X_{t+s} - X_t \stackrel{L}{=} X_s$$

- iii X_t has stochastic continuity, i.e. $\forall \varepsilon > 0$ we have that:

$$\lim_{h \rightarrow 0} \mathbb{P}(|X_{t+h} - X_t| > \varepsilon) = 0$$

This last property ensures that the process is continuous in probability. In other words that there are no jumps in the distribution of the jump times. No single instant is more likely than all others to be a jump time. We have no way of knowing with any probability when the processes' next jump will occur.

Properties 12.

- **Infinite divisibility:** X_t is infinitely divisible, i.e. $\forall n \in \mathbb{N}, \forall t > 0$ we have that:

$$X_t = \sum_{i=1}^n \hat{X}_i \quad \hat{X}_i = X_{i \cdot t/N} - X_{(i-1) \cdot t/N} \text{ iid}$$

Thus, we can break the process into an infinite (but countable) number of independent increments.

- **Characteristic function and exponent:**

$$\Phi_{X_t}(u) = \mathbb{E}[e^{iuX_t}] = e^{t\Psi(u)}$$

where $\Psi(u)$ is the characteristic exponent of the process. The function $t \mapsto \Phi_{X_t}$ is the characteristic function of

$$\Phi_{X_{t+s}}(u) = \Phi_{X_t}(u) \cdot \Phi_{X_s}(u)$$

Indeed:

$$\begin{aligned}\Phi_{X_{t+s}}(u) &= \mathbb{E}[e^{iuX_{t+s}}] = \mathbb{E}[e^{iu(X_t - X_s)} \cdot e^{iuX_s}] \\ \text{thanks to independence} &= \mathbb{E}[e^{iu(X_t - X_s)}] \cdot \mathbb{E}[e^{iuX_s}] = \Phi_{X_{t+s} - X_s}(u) \cdot \Phi_{X_s}(u) \\ \text{thanks to stationarity} &= \Phi_{X_t}(u) \cdot \Phi_{X_s}(u)\end{aligned}$$

Remark 13. The PP is the only Counting process which is also a Lèvy process. On the other hand the CPP is the only Lèvy process with piecewise constant trajectories. Indeed we may recall that $X_t = \sum_{i=1}^N Y_i$ where Y_i are iid random variables. Thus, if we make the choice $Y_i = 1$ we get the PP. Furthermore the characteristic function of X_t depends entirely on the distribution of Y_i :

$$\begin{aligned}\Phi_{X_t}(u) &= \mathbb{E}[e^{iuX_t}] = e^{t\lambda \int_{\mathbb{R}^d} (e^{iuy} - 1) \cdot f(dy)} \\ \implies \Psi_{X_t}(u) &= \lambda \int_{\mathbb{R}^d} (e^{iuy} - 1) \cdot f(dy)\end{aligned}$$

where f is the distribution of Y_i . Furthermore if Y_i is Lebesgue integrable then $f(dy) = k(y)dy$.

Proof.

$$\begin{aligned}\mathbb{E}[e^{iuX_t}] &= \mathbb{E}[\mathbb{E}[e^{iuX_t} | N_t]] = \mathbb{E}\left[\mathbb{E}\left[e^{iu \sum_{i=1}^{N_t} Y_i}\right]\right] = \mathbb{E}[\mathbb{E}[e^{iuN_t Y_i} | N_t]] \\ &= \mathbb{E}\left[\left(\mathbb{E}[e^{iuY_i}]\right)^{N_t}\right] = \mathbb{E}[\Phi_{Y_i}^{N_t}(u)] = \sum_{n=0}^{\infty} \Phi_{Y_i}^n(u) \cdot \mathbb{P}(N_t = n) \\ &= \sum_{n=0}^{\infty} \Phi_{Y_i}^n(u) \cdot \frac{(\lambda t)^n}{n!} e^{-\lambda t} = e^{-\lambda t} \cdot e^{\Phi_{Y_i}(u) \cdot \lambda t} = e^{\lambda t (\Phi_{Y_i}(u) - 1)}\end{aligned}$$

Thanks to the independence of the Y_i and the Taylor expansion of the exponential function. Now:

$$\Phi_{Y_i}(u) = \mathbb{E}[e^{iuY_i}] = \int_{\mathbb{R}^d} e^{iuy} \cdot f(dy) = \int_{\mathbb{R}^d} e^{iuy} \cdot k(y)dy$$

Hence, by substituting in the previous equation we get:

$$\Phi_{X_t}(u) = e^{\lambda t (\int_{\mathbb{R}^d} e^{iuy} \cdot k(y)dy - 1)} = e^{\lambda t (\int_{\mathbb{R}^d} e^{iuy} \cdot k(y)dy - \int_{\mathbb{R}^d} 1 \cdot k(y)dy)}$$

thus, thanks to the fact that $k(y)$ is a distribution function, we ultimately get:

$$\Phi_{X_t}(u) = e^{\lambda t \int_{\mathbb{R}^d} (e^{iuy} - 1) \cdot k(y)dy}$$

□

Sometimes we encounter the notation $\nu(dy) = \lambda k(y)dy = \lambda f(dy)$. This is called the **Lèvy measure** of the process.

Definition 14 (Lèvy measure of a CPP). Let A be a Borel set in \mathbb{R}^d . We define the following quantities:

$$\begin{aligned}\Delta X_t &= X_t - X_{t-} \\ X_{t-} &= \lim_{s \rightarrow t-} X_s\end{aligned}$$

Where ΔX_t is the jump size of the process at time t . Then:

$$\nu(A) = \mathbb{E}[\#\{t \in [0, 1] : \Delta X_t \neq 0, \Delta X_t \in A\}]$$

This is the average number of time in a unitary time interval in which a jump occurs in the set A .

Definition 15 (Random Measure). While ν is a deterministic measure on the set of Borel sets of \mathbb{R}^d , we can define the following random measure:

$$J_X(B) = \#\{(t, \Delta X_t) \in B\} \quad \forall B \text{ open set in } [0, +\infty) \times \mathbb{R}^d$$

This a random variable of the number of jumps times and jump sizes in the set B .

Application. Let X_t be a CPP.

$$X_t = \sum_{i=1}^{N_t} Y_i = \sum_{s \in [0, t]} \Delta X_s = \int_{[0, t] \times \mathbb{R}^d} x \cdot J_X(ds \times dx)$$

J_X is a Poisson Random Measure with intensity $\nu(ds)dt = \lambda f(x)dxdt$.

3.2 Exponential Lévy processes

In our framework we will model stocks and other processes as exponential Lévy processes of the form:

$$S_t = S_0 e^{rt + X_t}$$

where X_t is a Lévy process. Indeed, different choices of X_t will lead to different models. For example:

- $X_t = -\sigma^2/2t + \sigma W_t$ is the Black-Scholes model under the risk-neutral measure \mathbb{Q} .
- $X_t = \sum_{i=1}^{N_t} Y_i$ yields us the Compound Poisson Process model. The problem is that since this model is piecewise constant, it cannot capture the continuous variation of the stock prices on the real market.
- $X_t = \delta t + \sigma W_t + \sum_{i=1}^{N_t} Y_i$ yields us with a jump-diffusion model (either Merton or Kou). We will see later how δ shall be chosen in order to fit with the risk-neutral measure \mathbb{Q} .

Merton and Kou models

- **Merton model:** $Y_i \sim \mathcal{N}(\mu_j, \delta_j^2)$ hence we have a total of 4 parameters $\sigma, \lambda, \mu_j, \delta_j$. μ_j and δ_j are the mean and variance of the jumps size.
- **Kou model:**

$$Y_i = \begin{cases} \text{Exp}(\lambda^+) & \text{with probability } p \\ -\text{Exp}(\lambda^-) & \text{with probability } 1-p \end{cases}$$

Hence we have a total of 5 parameters $\sigma, \lambda, p, \lambda^+, \lambda^-$.

3.3 Choice of δ

Let us recall that we are under the \mathbb{Q} measure if we have that:

$$\begin{aligned} \mathbb{E}^{\mathbb{Q}} [S_t \cdot e^{-rt}] &= S_0 \\ \implies S_0 \mathbb{E}[e^{X_t}] &= S_0 \cdot \Phi_{X_t}(-i) \end{aligned}$$

Thus we must choose δ such that:

$$\Phi_{X_t}(-i) = 1 \iff \Psi_{X_t}(-i) = 0$$

in order to satisfy the risk-neutral measure condition. Thus δ is not a parameter of the model that we can freely choose but must be calibrated from the market in order to adhere to the risk-neutral measure.

3.4 Lévy-Itô decomposition

So far we have encountered three types of Lévy processes:

- Continuous, the family of Brownian motions.
- Finite variation, the Compound Poisson Process, which is unique.
- Jump-diffusion processes.

But not all Lévy processes are these types. This depends on whether ν can be well defined. TODO: add picture of how to divide up Lévy processes. For example:

$$\nu((2, 3)) = +\infty \implies \mathbb{E}[\#\{t \in [0, 1] : \Delta X_t \neq 0, \Delta X_t \in (2, 3)\}] = +\infty$$

This is clearly not a Cadlag process. We have infinite activity in the interval $(2, 3)$. In other words we have an infinite number of terms in the summation $\sum \Delta X_t$.

Definition 16 (Lévy-Itô decomposition). Let $(X_t)_{t \geq 0} \in \mathbb{R}^d$ be a Lévy process. Let ν be its Lévy measure. Then:

- ν is a Radon measure in $\mathbb{R}^d \setminus \{0\}$. In other words any compact set in $\mathbb{R}^d \setminus \{0\}$ is measurable.
-

$$\int_{x \in \mathbb{R}^d: |x| \geq 1} \nu(dx) < +\infty$$

iii)

$$\int_{x \in \mathbb{R}^d: |x| < 1} |x|^2 \nu(dx) < +\infty$$

TODO: missed comment from professor

iv) We can define a triplet (γ, A, ν) such that:

$$X_t = \gamma t + B_t + X_t^l + \lim_{\varepsilon \rightarrow 0} \hat{X}_t^\varepsilon$$

where:

- B_t is a Brownian motion with variance-covariance matrix A .
-

$$X_t^l = \sum_{\substack{s \in [0, t] \\ |\Delta X_s| \geq 1}} = \int_{[0, t] \times \{x \geq 1\}} x \cdot J_X(ds \times dx)$$

- We have the Compound Poisson process with jumps in $(\varepsilon, 1)$:

$$X_t^\varepsilon = \sum_{\substack{s \in [0, t] \\ \varepsilon < |\Delta X_s| < 1}} \Delta X_s$$

Thus we get the respective compensated process:

$$\begin{aligned} \hat{X}_t^\varepsilon &= \sum_{\substack{s \in [0, t] \\ \varepsilon < |\Delta X_s| < 1}} \Delta X_s - t \int_{\varepsilon < |x| < 1} x \nu(dx) \\ &= \int_{[0, t] \times \{\varepsilon < |x| < 1\}} x \cdot (J_X(ds \times dx) - \nu(dx)ds) \end{aligned}$$

Indeed we have that:

$$\begin{aligned} \int_{x \in \mathbb{R}^d: |x| < 1} |x|^2 \nu(dx) < +\infty &\implies \lim_{\varepsilon \rightarrow 0^+} \hat{X}_t^\varepsilon < +\infty \\ \int_{x \in \mathbb{R}^d: |x| < 1} |x|^2 \nu(dx) < +\infty &\not\implies \lim_{\varepsilon \rightarrow 0^+} X_t^\varepsilon < +\infty \end{aligned}$$

Thanks to Martingality and the Central Limit Theorem.

Example (One-dimensional case, from Jump-diffusion to Levy decomposition). Since we are starting from a jump-diffusion process, we have that:

$$X_t = \delta_t + \sigma W_t + \sum_{s \in [0, t]} \Delta X_s \longrightarrow \sum_{s \in [0, t]} \Delta X_s = \begin{cases} \int_{|x| \geq 1} \nu(dx) < +\infty \\ \int_{|x| < 1} \nu(dx) < +\infty \end{cases}$$

Clearly we have that $A = \sigma^2$. The Levy-Itô decomposition is:

$$X_t = \delta t + \sigma W_t + \sum_{\substack{s \in [0, t] \\ |\Delta X_s| \geq 1}} \Delta X_s + \lim_{\varepsilon \rightarrow 0^+} \hat{X}_t^\varepsilon$$

Now, let X_t be a Jump-Diffusion model: TODO (missed something)

$$X_t = \gamma t + \sigma W_t + \sum_{\substack{s \in [0, t] \\ |\Delta X_s| \geq 1}} \Delta X_s + \lim_{\varepsilon \rightarrow 0^+} \left[\sum_{\substack{s \in [0, t] \\ \varepsilon < |\Delta X_s| < 1}} \Delta X_s - t \int_{\varepsilon < |x| < 1} x \nu(dx) \right]$$

We can write since when $|\Delta X_s| < 1$ we have that:

$$\int_{|x| < 1} \nu(dx) < +\infty \implies \int_{|x| < 1} x \nu(dx) < +\infty$$

Thus we can write:

$$\begin{aligned}
&= \gamma t + \sigma W_t + \sum_{\substack{s \in [0, t] \\ |\Delta X_s| \geq 1}} \Delta X_s + \sum_{\substack{s \in [0, t] \\ |\Delta X_s| < 1}} \Delta X_s - t \int_{|x| < 1} x \nu(dx) \\
&\quad \underbrace{= t \left(\gamma - \int_{|x| < 1} x \nu(dx) \right)}_{\delta} + \sigma W_t + \sum_{s \in [0, t]} \Delta X_s
\end{aligned}$$

Definition 17 (Levy-Khincin formula). Let X_t be a Lèvy process with Lèvy-Itô decomposition (γ, A, ν) . Then:

$$\Phi_{X_t}(u) = \mathbb{E}[e^{iuX_t}] = e^{t\Psi_{X_t}(u)}$$

where:

$$\Psi_{X_t}(u) = iu \cdot \gamma - \frac{1}{2} u^T A u + \int_{\mathbb{R}^d} (e^{iu \cdot x} - 1 - iu \cdot x \mathbb{1}_{|x| \leq 1}) \nu(dx)$$

Proof. Thanks to the Lèvy-Itô decomposition we have that:

$$X_t = \underbrace{\gamma t + B_t}_{X_t^\varepsilon, \text{ continuous}} + \underbrace{X_t^l + \lim_{\varepsilon \rightarrow 0^+} \hat{X}_t^\varepsilon}_{X_t^j, \text{ jump}}$$

Thus we can split the characteristic function into two parts thanks to the fact that the continuous and jumping parts are independent:

$$\Phi_{X_t}(u) = \mathbb{E}[e^{iuX_t^c}] \cdot \mathbb{E}[e^{iuX_t^j}]$$

We shall now analyze them separately. For X_t^c we have that:

$$\mathbb{E}[e^{iuX_t^c}] = \mathbb{E}[e^{iu\gamma t} \cdot e^{iuB_t}] = e^{iu\gamma t} \cdot \mathbb{E}[e^{iuB_t}] = e^{iu\gamma t} \cdot e^{-\frac{1}{2} t u^T A u}$$

Let us now analyze X_t^j , but first let us fix the value of ε :

$$\begin{aligned}
X_t^{\varepsilon, j} &= \sum_{|\Delta X_s| \geq 1} \Delta X_s + X_t^\varepsilon \\
X_t^j &= \lim_{\varepsilon \rightarrow 0^+} X_t^{\varepsilon, j}
\end{aligned}$$

With a fixed value for ε we can observe that $X_t^{\varepsilon, j}$ is a CPP. Thus:

$$\begin{aligned}
\mathbb{E}[e^{iuX_t^j}] &= \lim_{\varepsilon \rightarrow 0^+} \mathbb{E}[e^{iuX_t^{\varepsilon, j}}] = \lim_{\varepsilon \rightarrow 0^+} \mathbb{E} \left[e^{iu \cdot \left(\sum_{\varepsilon < |\Delta X_s|} -t \int_{\varepsilon < |x| < 1} x \nu(dx) \right)} \right] \\
&\quad \lim_{\varepsilon \rightarrow 0^+} \mathbb{E} \left[e^{iu \sum_{|\Delta X_s| \geq 1} \Delta X_s} \right] \cdot \mathbb{E} \left[e^{iu \left(\sum_{\varepsilon < |\Delta X_s| < 1} \Delta X_s - t \int_{\varepsilon < |x| < 1} x \nu(dx) \right)} \right] \\
\text{using the CPP properties} \quad &\lim_{\varepsilon \rightarrow 0^+} \mathbb{E} \left[e^{t \int_{|x| \geq 1} (e^{iu \cdot x} - 1) \nu(dx)} \right] \cdot e^{t \left(\int_{\varepsilon < |x| < 1} (e^{iu \cdot x} - 1) \nu(dx) - \int_{\varepsilon < |x| < 1} iu \cdot x \nu(dx) \right)} \\
&\quad \lim_{\varepsilon \rightarrow 0^+} \mathbb{E} \left[e^{t \int_{|x| \geq 1} (e^{iu \cdot x} - 1) \nu(dx)} \right] \cdot e^{t \int_{\varepsilon < |x| < 1} (e^{iu \cdot x} - 1 - iu \cdot x) \nu(dx)} \\
&\quad \lim_{\varepsilon \rightarrow 0^+} \mathbb{E} \left[e^{t \int (e^{iu \cdot x} - 1 - iu \cdot x \mathbb{1}_{\varepsilon < |x| < 1}) \nu(dx)} \right]
\end{aligned}$$

Now, if we let $\varepsilon \rightarrow 0^+$ we get:

$$\mathbb{E}[e^{iuX_t^j}] = e^{t \int (e^{iu \cdot x} - 1 - iu \cdot x \mathbb{1}_{|x| < 1}) \nu(dx)}$$

□

Property 18 (Splitting the integral in the Levy-Khincin formula).

$$\lim_{\varepsilon \rightarrow 0^+} \hat{X}_t^\varepsilon = \lim_{\varepsilon \rightarrow 0^+} \int_{\{\varepsilon < |x| < 1\} \times [0, t]} x \cdot (J_X(ds \times dx) - \nu(dx) ds)$$

For a general Levy process this is finite $(+\infty)$. Under certain conditions we are able to split the integral into two parts:

$$\left. \begin{aligned} \int_{|x| > 1} \nu(dx) &< +\infty \text{ finite activity} \\ \int_{|x| \leq 1} |x| \nu(dx) &< +\infty \text{ finite variation} \end{aligned} \right\} \implies \lim_{\varepsilon \rightarrow 0^+} \int_{\varepsilon < |x| < 1} x \nu(dx) < +\infty$$

TODO unsure about this, check with professor about the integrals before the brackets.

Let us formally define what variation actually consists of:

Definition (Total variation). Let $f : [a, b] \rightarrow \mathbb{R}^d$ be a function. We define the total variation of f as:

$$\sup_{a=t_0 < \dots < t_n=b} \sum_{i=1}^n |f(t_i) - f(t_{i-1})| \quad n \in \mathbb{N}$$

In plainer words, the total variation is the supremum of the sum of the "jumps" of the function over all possible partitions of its domain. Furthermore a function is said to be of bounded variation if its total variation is finite.

Theorem (Finite variation Levy process). *Let X_t be a Levy process with Levy-Itô decomposition (γ, A, ν) . Then X_t is of finite variation if and only if:*

$$\int_{|x| \leq 1} |x| \nu(dx) < +\infty \text{ and } A = 0$$

This yields us the following hierarchy of Levy processes (with respect to their variation):

$$\begin{aligned} \int_{|x| \leq 1} \nu(dx) < +\infty &\rightarrow \text{CPP} \\ \int_{|x| \leq 1} |x| \nu(dx) < +\infty &\rightarrow \text{Finite variation} \\ \int_{|x| \leq 1} |x|^2 \nu(dx) < +\infty &\rightarrow \text{General Levy process} \end{aligned}$$

Let us also observe that only the first two are of bounded variation, and thus can have their integral limit split into two parts.

Chapter 4

Lecture 4

4.1 Subordinator process

In this lecture we will talk about the subordinator process. In very general terms a subordinator is a process that is increasing in time and that we use to sub-index another process. In other words we use it to change the "speed" of the flow information and of the process. We will see that the subordinator process is a very useful tool in the study of Lévy processes.

We will start by stating the formal definition of a subordinator process.

Definition 19 (Subordinator process). Let X_t be a Lévy process. We say that X_t is a subordinator process if and only if it satisfies all of the following conditions:

- 1) $X_t \geq 0$ for all $t \geq 0$ almost surely.
- 2) $\exists \bar{t} > 0$ such that $X_{\bar{t}} \geq 0$ almost surely.
- 3) X_t is not decreasing.
- 4) Given that the Lévy decomposition of X_t is (γ, A, ν) , then:
 - $\nu((-\infty, 0)) = 0$. In other words, the Lévy measure of X_t is zero in the negative real line. This is equivalent to saying that the process X_t does not have negative jumps.
 - $A = 0$. In other words, the process X_t does not have a continuous (Brownian Motion) component.
 - $b = \gamma - \int_{|x| \leq 1} x \nu(dx) > 0$. In other words the drift of the process X_t is non-negative. Recall that $\int_{|x| \leq 1} x \nu(dx)$ is the compensator process.
 - $\int_{|x| \leq 1} x \nu(dx) < +\infty$. In other words, the compensator process is finite.

Remark. Note that the fourth condition is equivalent to saying that X_t is a finite variation Lévy process with and non-negative drift ($b > 0$) and no negative jumps ($\nu((-\infty, 0)) = 0$).

Theorem 20. *The conditions above are equivalent to one another.*

Proof.

- 1) \implies 2): This is trivial. If $X_t \geq 0$ for all $t \geq 0$ then $X_{\bar{t}} \geq 0$ for some $\bar{t} > 0$.
- 3) \implies 1): This is also trivial. By assumption X_t is not decreasing and since it is Lévy $X_0 = 0$ almost surely, then $X_t \geq 0$ for all $t \geq 0$ almost surely.
- 2) \implies 3): By hypothesis of 2) we know that $\exists \bar{t} > 0$ such that $X_{\bar{t}} \geq 0$ almost surely. Let us now take $n \in \mathbb{N}$, then we rewrite $X_{\bar{t}}$ as follows:

$$X_{\bar{t}} = \underbrace{X_{\bar{t}} - X_{\frac{\bar{t}(n-1)}{n}}}_{\geq 0} + \underbrace{X_{\frac{\bar{t}(n-1)}{n}} - X_{\frac{\bar{t}(n-2)}{n}}}_{\geq 0} + \cdots + \underbrace{X_{\frac{2\bar{t}}{n}} - X_{\frac{\bar{t}}{n}}}_{\geq 0} + \cancel{X_0} \overset{0}{\nearrow} \geq 0$$

Thus since by the assumption on X_t being a Lévy process we know that the increments are iid, this becomes a sum of iid random variables, that is it is equal to n times the same random variable. Furthermore since we know that $X_{\bar{t}} \geq 0$ almost surely, then we know that each increment must be non-negative. Hence:

$$\implies \left(X_{\frac{\bar{t}i}{n}} - X_{\frac{\bar{t}(i-1)}{n}} \right) \geq 0 \quad \forall i \in \{1, \dots, n\}$$

This can easily extended to be of the form:

$$(X_{tp} - X_{tq}) \geq 0 \quad \forall p > q \in \mathbb{Q}$$

Furthermore since the set \mathbb{Q} is dense in the set of reals \mathbb{R} this can be even further be extended to be of the form:

$$(X_t - X_s) \geq 0 \quad \forall t > s \in \mathbb{R}$$

So far we have thus proved that the first 3 conditions are equivalent among each other, now we will pass on to prove that the fourth condition is equivalent to the third.

- 4) \implies 3): We can easily see that:

$$\int_{|x| \leq 1} x \nu(dx) < +\infty \implies X_t = bt + A \cdot B_t + \sum_{s \in [0, t]} \Delta X_s$$

Furthermore since we have that $\nu((-\infty, 0)) = 0$ then we know that $\Delta X_s \geq 0$ almost surely. Thus we can conclude that X_t is not decreasing since it is a sum of non-negative random variables.

- 3) \implies 4): In order to prove this last result we need a further theorem.

Theorem. *Let f be a C  dl  g function and not-decreasing. Then f is also of finite variation.*

Now, we also know that a L  vy process that is of finite variation also has that:

$$X_t \text{ FV} \implies A = 0, \int_{|x| \leq 1} |x| \nu(dx) < +\infty$$

These conditions thus lead us to conclude that:

$$X_t = bt + \sum_{s \in [0, t]} \Delta X_s \text{ is not decreasing} \iff \begin{cases} b > 0 \\ \Delta X_s \geq 0 \text{ a.s.} \end{cases} \iff \nu((-\infty, 0)) = 0$$

□

4.2 How to construct a subordinator process

We will now go on to see how a subordinator process can be constructed at will.

Theorem 21. *Let X_t be a L  vy process in \mathbb{R}^d (with $d \geq 1$) with L  vy-It   decomposition (γ, A, ν) . Let also $f : \mathbb{R}^d \mapsto \mathbb{R}_+$ such that $f(x) = O(|x|^2)$ in a neighborhood of 0. Then:*

$$S_t = \sum_{\substack{s \in [0, t] \\ \Delta X_s \neq 0}} f(\Delta X_s)$$

is a subordinator process.

Before proving this theorem let us make a few remarks and observations:

Remark. Note that in this theorem we have only used ν but have not used A or γ at all.

Remark 22. Let us note that from the L  vy-Khintchine formula, we know that given (γ, A, ν) we can easily write the characteristic exponent:

$$\Psi_{X_s}(z) = i\gamma^T \cdot z - \frac{1}{2} z^T A z + \int_{\mathbb{R}^d} \left(e^{iz^T x} - 1 - iz^T x \mathbb{1}_{|x| \leq 1} \right) \nu(dx)$$

Where we divide small (i.e. $|x| \leq 1$) and large (i.e. $|x| > 1$) jumps. Furthermore if we know that $\int_{|x| \leq 1} |x| \nu(dx) < +\infty$ then:

$$\Psi_{X_s}(z) = i\gamma_c^T \cdot z - \frac{1}{2} z^T A z + \int_{\mathbb{R}^d} \left(e^{iz^T x} - 1 \right) \nu(dx)$$

Where γ_c is:

$$\gamma_c = \gamma - \int_{|x| \leq 1} x \nu(dx)$$

Or we could also write:

$$\Psi_{X_s}(z) = i\gamma_{\hat{C}}^T \cdot z - \frac{1}{2}z^T A z + \int_{\mathbb{R}^d} \left(e^{iz^T x} - 1 - iz^T x \right) \nu(dx)$$

with the alternative choice of $\gamma_{\hat{C}}$:

$$\gamma_{\hat{C}} = \gamma + \int_{|x|>1} x \nu(dx)$$

Let us notice that the $\int_{|x|\leq 1} |x| \nu(dx)$ term only appears in the drift. It is rather easy to take a function $g : \mathbb{R}^d \mapsto \mathbb{R}$ such that:

$$\begin{aligned} g(x) &= O(|x|) \text{ for } |x| \rightarrow 0 \\ g(x) &= O\left(\frac{1}{|x|}\right) \text{ for } |x| \rightarrow \infty \end{aligned}$$

Then we can write the characteristic exponent as:

$$\begin{aligned} \Psi_{X_s}(z) &= i\hat{\gamma}^T \cdot z - \frac{1}{2}z^T A z + \int_{\mathbb{R}^d} \left(e^{iz^T x} - 1 - iz^T x g(x) \right) \nu(dx) \\ \text{with } \hat{\gamma} &= \gamma - \int_{\mathbb{R}^d} x (\mathbb{1}_{|x|\leq 1} + g(x)) \nu(dx) \end{aligned}$$

Thus we can freely choose g as we wish and we will still have a valid characteristic exponent. This is a very useful property that we will use later on.

Let us also see a few examples of g that we can use:

- $g(x) = \mathbb{1}_{|x|\leq 1}$
- $g(x) = \mathbb{1}_{|x|\leq \varepsilon}$ for some $\varepsilon > 0$

Finally we move on to the proof of the theorem.

Proof. Since f is a non-negative function, then we know that S_t is non-decreasing. All we need to prove is that S_t is a Lévy process. This is equivalent to proving that S_t respects the following properties:

- S_t is right-continuous.
- S_t is left-limited.
- $S_0 = 0$.
- S_t has independent increments.
- S_t is stochastically continuous.

Recall that S_t is defined as:

$$S_t = \sum_{\substack{s \in [0, t] \\ \Delta X_s \neq 0}} f(\Delta X_s)$$

Where X_t is a Lévy process and f is a non-negative function such that $f(x) = O(|x|^2)$ in a neighborhood of 0.

From the definition, since t is included into the sum, we can quite trivially conclude that S_t is right-continuous. Furthermore, by the same logic on the definition, we can conclude that $S_0 = 0$. It also has independent increments since it is a sum of independent increments of X_t , and by the same logic it is also stochastically continuous. What we really need to prove is that the process is left-limited. This entails the two following properties:

$$\begin{aligned} \int_{|x|>1} \nu_S(dx) &< +\infty \\ \int_{|x|\leq 1} |x|^2 \nu_S(dx) &< +\infty \end{aligned}$$

By the hypothesis that X_t be a Lévy process we know that:

$$\int_{|x|\leq 1} |x|^2 \nu_X(dx) < +\infty$$

And we want to pass to:

$$\int_{|x| \leq 1} |x|^2 \nu_S(dx) < +\infty$$

Which is also equivalent to asking that:

$$\int_{|x| \leq \varepsilon} |x|^2 \nu_S(dx) < +\infty \quad \forall \varepsilon > 0$$

Again, from the hypothesis that $f(x) = O(|x|^2)$ in a neighborhood of 0 we have that:

$$\forall C > 0 \exists \varepsilon > 0 \quad f(\Delta X_s) \leq C |\Delta X_s|^2 \quad \text{if } |\Delta X_s| \leq \varepsilon$$

□