Formal Grammar Definition



Tokens

Characters

- Cpening Bracket
- : Closing Bracket
- :: Colon
- ; : Semicolon
- , : Comma
- : Pipe

Keywords

- $Robot_R$
- vars
- procs
- *if*
- then
- else
- while
- *do*
- repeat

Commands

- $\bullet \ assign To$
- goto
- move
- turn
- face

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- *put*
- pick
- \bullet moveToThe
- $\bullet \ move In Dir$
- \bullet jumpToThe
- jumpInDir
- *nop*

Conditions

- facing
- \bullet canPut
- canPick
- $\bullet \ \ can Move In Dir$
- $\bullet \ \ can Jump In Dir$
- $\bullet \ \ can Move To The$
- $\bullet \ can Jump To The$
- *not*

Special Words

- *north*
- south
- \bullet east
- west
- front
- right
- \bullet left
- back
- around
- chips
- balloons

Others (see implementation)

- $\langle name \rangle$: Identifiers • $\langle number \rangle$: Numbers
- $\langle illegal \rangle$: Illegal Character
- $\langle EoF \rangle$: End Of File

Variables

- ullet $\langle Program
 angle$: A Program for the Robot
- $\langle Vars \rangle$: Declaration of Variables
- $\langle Procs \rangle$: Procedure Declaration
- $\langle Proc \rangle$: Procedure Definition
- $\langle Block \rangle$: Block of Instructions
- $\langle Instructions \rangle$: Instructions separated by Semicolons
- $\langle Instruction \rangle$: Instruction Structure
- $\langle Control \rangle$: Control Structure
- $\langle Cond \rangle$: Conditional Structure
- $\langle Loop \rangle$: Loop Structure
- $\langle Repeat
 angle$: RepeatTimes Structure
- $\langle Call \rangle$: Procedure Call
- $\langle Cmd \rangle$: Command
- $\langle Cnd \rangle$: Condition
- $\langle NameList \rangle$: Names separated by Commas
- $\langle ArgsList \rangle$: Arguments separated by Commas
- ullet $\langle Arg
 angle$: Argument Structure

Production Rules

The initial symbol is $\langle Program \rangle$

Terminals (tokens) are shown in *blue*.

Non-Terminals (variables) are shown in black.

BNF notation is shown in *red*:

→ : represents a production rule.

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- ()? : means optional.
- ()* : means zero or more.
- : means OR.

General

```
• \langle Program \rangle \rightarrow Robot\_R (\langle Vars \rangle)? (\langle Procs \rangle)? \langle Block \rangle \langle EoF \rangle
• \langle Vars \rangle \rightarrow vars \langle NameList \rangle
• \langle Procs \rangle \rightarrow procs \langle Proc \rangle (\langle Proc \rangle) *
• \langle Proc \rangle \rightarrow \langle name \rangle [ | (\langle NameList \rangle)? | \langle Instructions \rangle ]
• \langle Block \rangle \rightarrow [\langle Instructions \rangle]
• \langle Instructions \rangle \rightarrow \langle Instruction \rangle (; \langle Instruction \rangle)*
• \langle Instruction \rangle \rightarrow \langle Cmd \rangle \mid \langle Control \rangle \mid \langle Call \rangle
• \langle Control \rangle \rightarrow \langle Cond \rangle \mid \langle Loop \rangle \mid \langle Repeat \rangle
• \langle Cond \rangle \rightarrow if : \langle Cnd \rangle \ then : \langle Block \rangle \ else : \langle Block \rangle
• \langle Loop \rangle \rightarrow while : \langle Cnd \rangle do : \langle Block \rangle
• \langle Repeat \rangle \rightarrow repeat : \langle Arg \rangle \langle Block \rangle
• \langle Call \rangle \rightarrow \langle name \rangle : (\langle ArgsList \rangle)?
• \langle NameList \rangle \rightarrow \langle name \rangle (, \langle name \rangle)*
• \langle ArgsList \rangle \rightarrow \langle Arg \rangle (, \langle Arg \rangle)*
```

Commands

• $\langle Cmd \rangle \rightarrow assignTo : \langle number \rangle$, $\langle name \rangle$

• $\langle Arg \rangle \rightarrow \langle name \rangle \mid \langle number \rangle$

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 \begin{array}{l} \bullet \ \langle Cmd \rangle \rightarrow goto \ : \ \langle Arg \rangle \ , \ \langle Arg \rangle \\ \bullet \ \langle Cmd \rangle \rightarrow move \ : \ \langle Arg \rangle \\ \bullet \ \langle Cmd \rangle \rightarrow turn \ : \ (\ left \ | \ right \ | \ around \ ) \\ \bullet \ \langle Cmd \rangle \rightarrow face \ : \ (\ north \ | \ south \ | \ east \ | \ west \ ) \\ \bullet \ \langle Cmd \rangle \rightarrow put \ : \ \langle Arg \rangle \ , \ (\ balloons \ | \ chips \ ) \\ \bullet \ \langle Cmd \rangle \rightarrow pick \ : \ \langle Arg \rangle \ , \ (\ balloons \ | \ chips \ ) \\ \bullet \ \langle Cmd \rangle \rightarrow moveToThe \ : \ \langle Arg \rangle \ , \ (\ front \ | \ right \ | \ left \ | \ back \ ) \\ \bullet \ \langle Cmd \rangle \rightarrow moveInDir \ : \ \langle Arg \rangle \ , \ (\ north \ | \ south \ | \ west \ | \ east \ ) \\ \bullet \ \langle Cmd \rangle \rightarrow jumpInDir \ : \ \langle Arg \rangle \ , \ (\ north \ | \ south \ | \ west \ | \ east \ ) \\ \bullet \ \langle Cmd \rangle \rightarrow jumpInDir \ : \ \langle Arg \rangle \ , \ (\ north \ | \ south \ | \ west \ | \ east \ ) \end{array}
```

Conditions

• $\langle Cmd \rangle \rightarrow nop$:

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• \langle Cnd \rangle \rightarrow facing : (north \mid south \mid east \mid west)
• \langle Cnd \rangle \rightarrow canPut : \langle Arg \rangle, (balloons \mid chips)
• \langle Cnd \rangle \rightarrow canPick : \langle Arg \rangle, (balloons \mid chips)
• \langle Cnd \rangle \rightarrow canMoveInDir : \langle Arg \rangle, (north \mid south \mid west \mid east)
• \langle Cnd \rangle \rightarrow canJumpInDir : \langle Arg \rangle, (north \mid south \mid west \mid east)
• \langle Cnd \rangle \rightarrow canJumpInDir : \langle Arg \rangle, (front \mid right \mid left \mid back)
• \langle Cnd \rangle \rightarrow canJumpToThe : \langle Arg \rangle, (front \mid right \mid left \mid back)
• \langle Cnd \rangle \rightarrow not : \langle Cnd \rangle
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