

# John Yaklin

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## Objective

Multi-disciplinary engineer seeking opportunities in advanced manufacturing equipment / process R&D

## Education

<b>University of Illinois Urbana-Champaign</b>	December 2025 (expected graduation)
Bachelor of Science in mechanical engineering	GPA 4.0 / 4.0
<ul style="list-style-type: none"><li>• Relevant coursework – industrial control systems, nanomanufacturing, plasma physics</li><li>• Admission to Master of Engineering program</li></ul>	
<b>Black Hawk College – Moline, IL</b>	June 2021 – May 2023
Associate of Science in mechanical engineering	GPA 4.0 / 4.0

## Experience

<b>TSMC</b> , Dry Etch Equipment Engineer Intern – Phoenix, AZ	May 2025 – August 2025
<ul style="list-style-type: none"><li>• Developed a plasma etcher coolant level monitoring system, preventing \$25K / yr wafer scrap</li><li>• Deployed troubleshooting strategy to cut coolant loss by 75%, saving \$10K / yr and increasing uptime</li><li>• Applied ROS, Docker, and shell scripting to create sensor testing and data visualization tools</li></ul>	
<b>iRobotics</b> , Roboticist – Urbana, IL	September 2023 – present
<ul style="list-style-type: none"><li>• Designed, built, and tested a custom high-load bearing for combat robots</li><li>• Developed printed circuit boards for precision motor control and data collection</li><li>• Wrote custom motion control systems in embedded C for AVR and STM32 microcontrollers</li></ul>	

## **FIRST Tech Challenge**

Engineering Lead – Bettendorf, IA	April 2020 – June 2023
<ul style="list-style-type: none"><li>• Led team of 15 in designing, building, programming, and testing 14 unique robots</li><li>• Identified bottlenecks and drove improvements to design, fabrication, and testing procedures</li><li>• Applied TRIZ (Russian theory of inventive problem solving) to create rigorous solutions</li></ul>	
Roboticist – Bettendorf, IA	May 2018 – June 2023
<ul style="list-style-type: none"><li>• Fabricated and tested hundreds of 3D printed, sheet metal, and composite parts</li><li>• Optimized designs for record-setting &lt;2s task cycles and &lt;5m maintenance cycles</li><li>• Documented design process in an engineering notebook</li></ul>	

## Projects

- Developed dielectric mirror optic simulator in Python for solar energy applications
- Researched low temperature PVD processes for dielectric layers on low cost polymer substrate

## Skills

### **Computer Aided Design**

- Creo, Onshape, AutoCAD, nTop (optimization), Moldflow (injection molding), KiCad (circuit design)

### **Software / System Modeling**

- Python, Java, Bash, Arduino, MATLAB, Excel, C (embedded system software), Git (version control)

## Awards

- Helped robotics team earn #1 award in state for 4 consecutive years, top 1% worldwide