

Making ML Polymorphism More Ad Hoc

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Abstract

This report is an outline on the denotational semantics of type classes in Haskell98, which is currently being prepared for submission to a journal. The intention is to present sufficient detail so that members of the Programatica team get an up-to-date view of our approach to overloading and so that we can get useful feedback.

1 Introduction

Type classes have proven to be a useful and expressive feature for data and program abstraction in Haskell and they quickly gained popularity within the Haskell community. However, despite having been the subject of study since the late 1980's, type classes remain something of a mystery to the programming languages community at large. This is a shame and the purpose of this article is to remedy this situation. While our intent is mainly to provide a suitable model of Haskell98 for Programatica[], another motivation for the current work is to render one of Haskell98's most innovative and expressive features comprehensible to language researchers.

Why might type classes be difficult to comprehend? One possible answer is that type classes are not “first-class” citizens of Haskell. While they appear as part of the surface syntax of the language, but they are treated more as syntactic sugar. Up to now, classes have been viewed as constructs that mysteriously disappear through the use of the dictionary-passing translation[]. The dictionary-passing translation (DPT), while a perfectly reasonable means of *implementing* Haskell type classes, simply does not suffice as an abstract definition of classes in Haskell. Why? Such reliance on the DPT disconnects the surface syntax of Haskell, and the confusion of the programming languages community can be reasonably attributed to this shortcoming in the presentation of Haskell.

What separates the approach advocated here from previous attempts [3, 18, 6, 19] is that we do not view type classes as second class citizens. Rather, we treat them as full members of the Haskell language. As such, we must give type classes The starting point for this work is

2 Foundation for Haskell Polymorphism

The meaning of the ML identity function $(\lambda x.x)$ is:

$$\{ \langle \tau \rightarrow \tau, \text{id}_{D_\tau} \rangle \mid \tau \in \mathbf{Type} \}$$

where \mathbf{Type} is the set of simple (ground) types and D_τ is the meaning of τ (a type-frame). Here, id_{D_τ} is a continuous function from D_τ to D_τ .

Using Ohori's model of polymorphism [11, 12], we denote the type classes as set functions from a suitable subset of \mathbf{Type} to type frames:

$$\llbracket \mathbf{Eq} \rrbracket = \{ \langle \text{Int} \rightarrow \text{Int} \rightarrow \text{Bool}, \text{eqInt} \rangle, \langle \text{Float} \rightarrow \text{Float} \rightarrow \text{Bool}, \text{eqFloat} \rangle, \dots \}$$

Now consider what the meaning of the term:

$$e = (\emptyset \mid \emptyset \vdash \lambda x. x == x : \forall a. \mathbf{Eq} a \Rightarrow a \rightarrow \text{Bool})$$

where “ \emptyset ” refers to empty constraints.

Just as with Core-ML, the meaning of e will be defined in terms of the set of its ground instances:

$$\left\{ \begin{array}{c} \mathcal{M}[(\emptyset \mid \emptyset \vdash \lambda x. x == x : \mathbf{Eq} \text{Int} \Rightarrow \text{Int} \rightarrow \text{Bool})]^{oml}, \\ \vdots \end{array} \right\}$$

These, in turn, will be defined in terms of translations into an explicitly-typed, simply-typed language analogous to $T\Lambda$:

$$\left\{ \begin{array}{c} \mathcal{M}[(\emptyset \mid \emptyset \vdash \lambda(x : \text{Int}). (x : \text{Int})(== : \text{Int} \rightarrow \text{Int} \rightarrow \text{Bool})(x : \text{Int}) : \dots)], \\ \vdots \end{array} \right\}$$

Note that there is now sufficient type information at the call site of $(==)$ to give its denotation:

$$\mathcal{M}[(== : \text{Int} \rightarrow \text{Int} \rightarrow \text{Bool})]\varepsilon = \llbracket \mathbf{Eq} \rrbracket (\text{Int} \rightarrow \text{Int} \rightarrow \text{Bool}) = \text{eqInt}$$

Recall that $\llbracket \mathbf{Eq} \rrbracket$ is a set function, so the above application makes sense. But most importantly, no dictionary-passing translation is needed!

3 What are Constructor Classes?

Constructor classes like **Eq**, **Ord**, and **Show** play two related rôles in the definition of Haskell and we explore them here in the context of OML. In the type system, a class C is a predicate on \mathbf{Type} . A class C is also a set of overloaded methods. As it turns out, Ohori's semantics of ML polymorphism is a natural setting for describing both aspects of constructor classes, and this is the subject of this section.

Firstly, a class C is a logical predicate on \mathbf{Type} (see the rule $(\Rightarrow E)$ in Figure ??) and, as such, is modeled in the conventional way by a subset of \mathbf{Type} . This subset, defined inductively from the instance declarations, determines the types for which the methods of class C must be defined.

The constructor classes also are sets of *instances*, where instances are denotations (or, more generally, n-tuples of denotations) in the sense of Definition ???. Generally, a class C contains multiple methods, If a program has class definitions C_1, \dots, C_n , then the instances are products of the form:

$$(\Pi \tau \in p_1.D_\tau) \times \dots \times (\Pi \tau \in p_n.D_\tau)$$

for $p_i \subseteq \text{Type}$. The precise relationship

3.1 A motivating example

Consider the class **Eq** as defined below:

```
class Eq a where (==) : a → a → Bool
instance Eq Int where (==) = eqInt           { base case }
instance (Eq a, Eq b) ⇒ Eq (a × b) where     { ind. case }
  (⟨x, y⟩ == ⟨u, v⟩) = (x == u) && (y == v)
```

We view these instance declarations as an inductive definition of **Eq** as a predicate on **Type**. The instance (Eq Int) is the base case of the definition while $(\text{Eq } a, \text{Eq } b \Rightarrow \text{Eq } (a \times b))$ is the inductive case. What follows is an example of how the interpretation of **Eq** is determined:

$$\begin{aligned} \lceil \text{Eq} \rceil_0 &= \{ \tau \in \text{Type} \mid \exists s. (s \text{ Int}) = \text{Int} \} = \{ \text{Int} \} \\ \lceil \text{Eq} \rceil_{(n+1)} &= \{ \tau \in \text{Type} \mid \exists s. (s \langle a \times b \rangle) = \tau \wedge (s a \in \lceil \text{Eq} \rceil_n \wedge (s b \in \lceil \text{Eq} \rceil_n)) \} \\ \mathcal{I}(\text{Eq}) &= \bigcup_{n < \omega} \lceil \text{Eq} \rceil_n \end{aligned}$$

where s ranges over ground substitutions. Note that $\mathcal{I}(\text{Eq})$ is just the set you think it is. More importantly, $\mathcal{I}(\text{Eq})$ specifies the set of types at which the overloaded variable “==” must be defined. The set $\mathcal{I}(\text{Eq})$ plays the same rôle that the set $(\text{TP}(\mathcal{A}, \Sigma \triangleright e : \rho))$ plays in the Core-ML semantics (see Definition ???).

The example of **Eq** may be generalised as:

$$\begin{aligned} \lceil C_1, \dots, C_n \rceil_0 &= \{ \langle \tau_1^*, \dots, \tau_n^* \rangle \in \text{Type}^n \mid (C_j \tau_k^j) \in \text{Base}(C_j), \\ &\quad \tau_k^* = s \tau_k^j, \\ &\quad s \text{ is a binding} : \{ \alpha_k \} \rightarrow \text{Type} \} \\ \lceil C_1, \dots, C_n \rceil_{(l+1)} &= \{ \langle \tau_1^*, \dots, \tau_n^* \rangle \in \text{Type}^n \mid (\pi_m^j \Rightarrow C_j \tau_k^j) \in \text{Induct}(C_j), \\ &\quad s \text{ satisfies } \lceil \pi_m^j \rceil_l, \\ &\quad \tau_k^* = s \tau_k^j, \\ &\quad s \text{ is a binding} : \{ \alpha_1, \dots, \alpha_n \} \rightarrow \text{Type} \} \\ \mathcal{I}(C_1, \dots, C_n) &= \bigcup_{k < \omega} \lceil C_1, \dots, C_n \rceil_k \\ \mathcal{I}(C_i) &= \text{proj}_i \left(\bigcup_{k < \omega} \lceil C_1, \dots, C_n \rceil_k \right) \end{aligned}$$

4 Making ML Polymorphism More Ad-Hoc

In this section, we present a precise syntax and type system for class and their instances. By doing so, we make type classes as first-class citizens of Haskell, and, as such, deserving of a denotational semantics.

4.1 Types for Classes and Instances

The source language is described below in Definitions 1 and 2. We will give meanings to finite sequences of class implementations:

$$classimpl_1 ; \dots ; classimpl_n$$

A *class implementation* is a class declaration for a particular C gathered together with each of its instance declarations. It is assumed in the above sequence that any class symbol C is defined by at most one class implementation. Organising the syntax as such simplifies the denotational specification of classes along the lines of Section 3.1.

Definition 1 [Type Language] Based on Figure 1 of Hall[3]. The main difference is the inclusion of types for classes and instances. Below, it is assumed that $(n \geq 0)$.

Type variable	α, β
Type constructor	T
Class name	C
Monotype ($n = \text{arity}(T)$)	$\tau ::= \alpha \mid T \tau_1 \dots \tau_n \mid \tau' \rightarrow \tau$
Predicates	$\theta ::= C_1 \alpha_1, \dots, C_n \alpha_n$
Saturated predicates	$\phi ::= C_1 \tau_1, \dots, C_n \tau_n$
Qualified type	$\rho ::= \phi \Rightarrow \tau$
Polymorphic type	$\sigma ::= \forall \alpha_1 \dots \alpha_n. \theta \Rightarrow \tau$
Class/Instance types	$\gamma ::= \{ \mid v_1 : \forall \vec{\alpha}_1. \tau_1, \dots, \forall \vec{\alpha}_n. \tau_n \}$

Definition 2 [Source Language] Based on Figure 2 of Hall[3]. Assume $(m, n, k \geq 0)$ below.

Class implementation for C

$$classimpl ::= classdecl ; instdecl_1 ; \dots ; instdecl_m$$

where $classdecl$ and $instdecl_i$ are class and instance declarations for C .

Class declaration for C

$$classdecl ::= \text{class } (C_1 \alpha, \dots, C_n \alpha) \Rightarrow C \alpha \text{ where } \gamma$$

Instance declaration for C

$$instdecl ::= \text{instance } (C_1 \alpha_1, \dots, C_m \alpha_m) \Rightarrow C (T \beta_1 \dots \beta_k) \text{ where } binds$$

where $\{\alpha_1, \dots, \alpha_m\} \subseteq \{\beta_1, \dots, \beta_k\}$.

Binding records

$$binds ::= \{ \mid var_1 = exp_1, \dots, var_n = exp_n \}$$

Expressions

$$exp ::= var \mid \lambda var. exp \mid exp \ exp' \mid \text{let } var = exp' \text{ in } exp$$

Haskell Concrete Syntax

Class/Instance Type

Single Methods

<code>class Eq a where (==) :: a -> a -> Bool</code>	$: \forall \alpha. \text{Eq } \alpha \Rightarrow \{ \{ (==) : \alpha \rightarrow \alpha \rightarrow \text{Bool} \} \}$
<code>instance Eq Int where (==) = primEqInt</code>	$: \{ \} \Rightarrow \{ \{ (==) : \text{Int} \rightarrow \text{Int} \rightarrow \text{Bool} \} \}$
<code>instance Eq a => Eq [a] where [] == [] = True (x:xs) == (y:ys) = x==y && xs==ys _ == _ = False</code>	$: \forall \alpha. \text{Eq } \alpha \Rightarrow \{ \{ (==) : [\alpha] \rightarrow [\alpha] \rightarrow \text{Bool} \} \}$
<code>instance (Eq a, Eq b) => Eq (a,b) where (x,y) == (u,v) = (x==u) && (y==v)</code>	$: \forall \alpha, \beta. \text{Eq } \alpha, \text{Eq } \beta \Rightarrow \{ \{ (==) : (\alpha \times \beta) \rightarrow (\alpha \times \beta) \rightarrow \text{Bool} \} \}$

Multiple Methods

<code>class Monad m where return :: a -> m a (>>=) :: m a -> (a -> m b) -> m b</code>	$: \forall m. \text{Monad } m \Rightarrow \{ \{ \text{return} : \forall \alpha. \alpha \rightarrow m \alpha, (>>=) : \forall \alpha, \beta. \alpha \rightarrow (\alpha \rightarrow m \beta) \rightarrow m \beta \} \}$
<code>instance Monad Maybe where Just x >>= k = k x Nothing >>= k = Nothing return = Just</code>	$: \{ \} \Rightarrow \{ \{ \text{return} : \forall \alpha. \alpha \rightarrow \text{Maybe } \alpha, (>>=) : \forall \alpha, \beta. \text{Maybe } \alpha \rightarrow (\alpha \rightarrow \text{Maybe } \beta) \rightarrow \text{Maybe } \beta \} \}$
<code>instance Monad [] where (x:xs) >>= f = f x ++ (xs >>= f) [] >>= f = [] return x = [x]</code>	$: \{ \} \Rightarrow \{ \{ \text{return} : \forall \alpha. \alpha \rightarrow [\alpha], (>>=) : \forall \alpha, \beta. [\alpha] \rightarrow (\alpha \rightarrow [\beta]) \rightarrow [\beta] \} \}$

Superclasses

<code>class Monad m => MonadPlus m where mzero :: m a mplus :: m a -> m a -> m a</code>	$: \forall m. \text{Monad } m, \text{MonadPlus } m \Rightarrow \{ \{ \text{return} : \forall \alpha. \alpha \rightarrow m \alpha, (>>=) : \forall \alpha, \beta. \alpha \rightarrow (\alpha \rightarrow m \beta) \rightarrow m \beta \} \oplus \{ \{ \text{mzero} : \forall \alpha. m \alpha, \text{mplus} : \forall \alpha. m \alpha \rightarrow m \alpha \rightarrow m \alpha \} \}$
<code>instance MonadPlus Maybe where mzero = Nothing Nothing 'mplus' ys = ys xs 'mplus' ys = xs</code>	$: \{ \} \Rightarrow \{ \{ \text{return} : \forall \alpha. \alpha \rightarrow \text{Maybe } \alpha, (>>=) : \forall \alpha, \beta. \text{Maybe } \alpha \rightarrow (\alpha \rightarrow \text{Maybe } \beta) \rightarrow \text{Maybe } \beta \} \oplus \{ \{ \text{mzero} : \forall \alpha. \text{Maybe } \alpha, \text{mplus} : \forall \alpha. \text{Maybe } \alpha \rightarrow \text{Maybe } \alpha \rightarrow \text{Maybe } \alpha \} \}$
<code>instance MonadPlus [] where mzero = [] mplus = ++</code>	$: \{ \} \Rightarrow \{ \{ \text{return} : \forall \alpha. \alpha \rightarrow [\alpha], (>>=) : \forall \alpha, \beta. [\alpha] \rightarrow (\alpha \rightarrow [\beta]) \rightarrow [\beta] \} \oplus \{ \{ \text{mzero} : \forall \alpha. [\alpha], \text{mplus} : \forall \alpha. [\alpha] \rightarrow [\alpha] \rightarrow [\alpha] \} \}$

Figure 1: Giving record types to Haskell classes and instances. Here the \oplus type operator combines to record types with distinct labels. The `Eq` class is an example of a class with one method, while the `Monad` class has multiple methods. The `MonadPlus` class illustrates how *superclass* definitions affect the type of the class.

4.1.1 Summary of Record Syntax from Standard ML

We need type rules for the record constructs introduced in Definitions 1 and 2, and, for these, we turn to Standard ML [9] for inspiration. This is appropriate as the record types are all known statically. We also include a record selector “.” in the basic syntax for simplicity and base its type rule on [14].

The following definition summarizes the treatment of records in ML. Below, C is a type context (the exact structure of which is unimportant here) and ϱ is a record type (i.e., a “ $\{\langle tyrow \rangle\}$ ”). Note that ϱ may also be viewed as a (finite) set map in $Label \xrightarrow{\text{fin}} MLtypes$.

Definition 3 [Record expressions & types in Standard ML]

Atomic expressions	$atexp ::= \dots \mid \{\langle exprow \rangle\} \mid \dots$
Expression rows	$exprow ::= \dots \mid lab=exp \langle, exprow \rangle \mid \dots$
Types	$ty ::= \dots \mid \{\langle tyrow \rangle\} \mid \dots$
Type rows	$tyrow ::= \dots \mid lab:ty \langle, tyrow \rangle \mid \dots$
$\frac{C \vdash exp:t}{C \vdash lab=exp:\{\langle lab:exp \rangle\}} \quad \frac{C \vdash exp:t \quad C \vdash exprow:\varrho}{C \vdash lab=exp, exprow:\{\langle lab:exp \rangle\} \oplus \varrho}$	
$\frac{}{C \vdash \{\langle \rangle\}:\{\langle \rangle\}} \quad \frac{C \vdash exprow:\varrho}{C \vdash \{\langle exprow \rangle\}:\varrho} \quad \frac{C \vdash exp:\{\langle l_0:t_0, \dots, l_n:t_n \rangle\}}{C \vdash exp.l_j:t_j}$	

4.2 A type rule for class declarations

Definition 4 (Putative Type Rule for Class Declarations) *Let each $classdecl_i$ below be a class declaration for C_i . We introduce a relation (\hookrightarrow) between class declarations and record types which determines the precise record structure corresponding to a class.*

$$\frac{classdecl_1 \hookrightarrow \forall \alpha_1. \gamma_1 \dots classdecl_n \hookrightarrow \forall \alpha_n. \gamma_n}{(\text{class } (C_1\alpha, \dots, C_n\alpha) \Rightarrow C\alpha \text{ where } \gamma) \hookrightarrow \forall \alpha. \gamma_1[\alpha_1/\alpha] \oplus \dots \oplus \gamma_n[\alpha_n/\alpha] \oplus \gamma}$$

4.3 Type inference for Classes & Instances

What follows is an informal derivation of the type of the list instance for the **Eq** class. We use rules for records along the lines of Standard ML (Definition 3). Also, we include a new environment for the types of instance methods in the typing judgements. The intent is to motivate general inference rules for classes and instances.

In the following, let *eqList* stand for the following term:

```

\ x -> \ y -> case (x,y) of
                ([],[]) -> True
                (u:us,v:vs) -> u==v && us==vs
                (_,_) -> False

```

The idea is to show how type judgements such as:

`instance Eq a => Eq [a] where (==)=eqList : $\forall \alpha. Eq \alpha \Rightarrow \{\langle == \rangle : [\alpha] \rightarrow [\alpha] \rightarrow Bool\}$`

may be plausibly derived.

Class definitions (without superclass constraints) are viewed as being little more than syntactic sugar for a particular overloaded, record type:

$$\text{class Eq a where } (==) :: a \rightarrow a \rightarrow \text{Bool} : \forall \alpha. \text{Eq } \alpha \Rightarrow \{ | (==) : \alpha \rightarrow \alpha \rightarrow \text{Bool} | \}$$

The following is a plausible derivation of the list instance of **Eq**.

$$\frac{\frac{\frac{\text{cont'd below}}{\emptyset \mid == : \alpha \rightarrow \alpha \rightarrow \text{Bool}, == : [\alpha] \rightarrow [\alpha] \rightarrow \text{Bool} \mid \emptyset \vdash \text{eqList} : \{ | (==) : [\alpha] \rightarrow [\alpha] \rightarrow \text{Bool} | \}} \quad (iv)}{\text{Eq } \alpha \mid == : \alpha \rightarrow \alpha \rightarrow \text{Bool}, == : [\alpha] \rightarrow [\alpha] \rightarrow \text{Bool} \mid \emptyset \vdash \text{eqList} : \text{Eq } \alpha \Rightarrow \{ | (==) : [\alpha] \rightarrow [\alpha] \rightarrow \text{Bool} | \}} \quad (iii)}{\frac{\emptyset \vdash \text{instance Eq a} \Rightarrow \text{Eq [a] where } (==) = \text{eqList} : \text{Eq } \alpha \Rightarrow \{ | (==) : [\alpha] \rightarrow [\alpha] \rightarrow \text{Bool} | \}}{\emptyset \vdash \text{instance Eq a} \Rightarrow \text{Eq [a] where } (==) = \text{eqList} : \forall \alpha. \text{Eq } \alpha \Rightarrow \{ | (==) : [\alpha] \rightarrow [\alpha] \rightarrow \text{Bool} | \}} \quad (i)} \quad (ii)$$

Comments:

- (i) Polymorphism rule. Nothing new here.
- (ii) Here, the presence of two overloaded types, α and $[\alpha]$, are expanded into the *method environment* M . In a judgement $(P \mid M \mid \Sigma \vdash e : \sigma)$, the environments P and Σ are class constraints and variable typings, respectively, as in OML. M binds method names to the particular type instances corresponding to $\text{Eq } \alpha$ and $\text{Eq } [\alpha]$.
- (iii) This is just $(\Rightarrow E)$.

$$\frac{\frac{\frac{\frac{\emptyset \mid M == \mid \mathbf{x}, \mathbf{y}, \mathbf{us}, \mathbf{vs} : [\alpha], \mathbf{u}, \mathbf{v} : \alpha \vdash \mathbf{u} == \mathbf{v} : \text{Bool}}{\emptyset \mid M == \mid \mathbf{x}, \mathbf{y}, \mathbf{us}, \mathbf{vs} : [\alpha], \mathbf{u}, \mathbf{v} : \alpha \vdash \mathbf{us} == \mathbf{vs} : \text{Bool}} \quad \text{(remaining subgoals)}}{\emptyset \mid M == \mid \mathbf{x}, \mathbf{y}, \mathbf{us}, \mathbf{vs} : [\alpha], \mathbf{u}, \mathbf{v} : \alpha \vdash \mathbf{u} == \mathbf{v} \ \&\& \ \mathbf{us} == \mathbf{vs} : \text{Bool}} \quad (vi)}{\frac{\emptyset \mid M == \mid \mathbf{x} : [\alpha], \mathbf{y} : [\alpha] \vdash \text{case } (\mathbf{x}, \mathbf{y}) \text{ of } br_1 ; br_2 ; br_3 : \text{Bool}}{\emptyset \mid == : \alpha \rightarrow \alpha \rightarrow \text{Bool}, == : [\alpha] \rightarrow [\alpha] \rightarrow \text{Bool} \mid \emptyset \vdash \text{eqList} : \{ | (==) : [\alpha] \rightarrow [\alpha] \rightarrow \text{Bool} | \}} \quad (v)} \quad (iv)$$

Comments:

- (iv) This is $(\lambda I) \times 2$. Nothing new here. We abbreviate the method environment by $M ==$. Also, the record type has mysteriously disappeared.
- (v) This shows the only interesting case of the br_2 case branch. The extraction of the types of pattern variables \mathbf{u} , \mathbf{v} , \mathbf{us} and \mathbf{vs} is elided.
- (vi) The remaining subgoals follow by “function” application of $==$.

4.4 Type Rule for Instances

$$\frac{\begin{array}{l} FTV(\tau_i) \subseteq \{\alpha_1, \dots, \alpha_k\} = FTV(\tau) \\ (m : \forall \beta. C\beta \Rightarrow \sigma') \in VE \\ TE \vdash EE' \cup \{C_1\tau_1, \dots, C_n\tau_n\}; VE \vdash e : [\tau/\beta]\sigma' \\ \overbrace{TE; EE' \cup \{\forall \alpha_1, \dots, \alpha_k. (C_1\tau_1, \dots, C_n\tau_n) \vdash C\tau\}}^{EE'}; VE \vdash prog : \\ TE; EE' \cup \{\forall \alpha. C\alpha \vdash C_i\alpha\}; VE \vdash prog : \end{array}}{A \vdash \text{instance } (C_1\tau_1, \dots, C_n\tau_n) \Rightarrow C\tau \text{ where } \{m_1 = e_1 \dots m_k = e_k\} : \forall \alpha_1 \dots \alpha_h. \theta \Rightarrow C\tau}$$

```

data Seq a = Nil | SCons (a,Seq (a,a))

size :: (Seq a) -> Int
size s = if (isNil s) then 0 else (1 + (2 * (size (stl s))))
  where stl (Scons(x,xs)) = xs
        isNil Nil         = True
        isNil (SCons _)   = False

```

Figure 2: From Okasaki [13], p. 142: a useful poly-rec function!

5 Overloading with Polymorphic Recursion

Remark 1 [Modeling Parametric Polymorphism] Consider the term polymorphic (but not polymorphic recursive) term *length*:

$$\begin{aligned}
 \text{length} & : [a] \rightarrow \text{Int} \\
 \text{length} & = \lambda l. \text{case } l \{ [] \rightarrow 0 ; (x : xs) \rightarrow 1 + (\text{length } xs) \}
 \end{aligned}$$

Within Ohori’s framework, this should denote the following set:

$$\{ \langle \tau, \text{len}_\tau \rangle \mid \tau = [\text{Int}] \rightarrow \text{Int}, \dots \}$$

where each len_τ is defined as:

$$\text{len}_\tau = \text{fix}_\tau (\lambda \text{length}. \lambda l. \text{case } l \{ [] \rightarrow 0 ; (x : xs) \rightarrow 1 + (\text{length } xs) \})$$

Note that fix_τ is the least fixed point on the pointed cpo D_τ .

Remark 2 [Modeling Polymorphic Recursion] Consider now the term polymorphic recursive term *foo*:

$$\begin{aligned}
 \text{foo} & : [a] \rightarrow \text{Bool} \\
 \text{foo} & = \lambda x. (\text{null } x) \ \&\& \ (\text{foo } [x])
 \end{aligned}$$

One might be tempted to view this definition as shorthand for the following:

$$\text{foo} = \text{fix} (\lambda \text{foo}. \lambda x. (\text{null } x) \ \&\& \ (\text{foo } [x])) \quad (\dagger)$$

But, where does this *fix* live? Intuitively, here’s the problem: if the “input *foo*” (i.e., “ $\text{fix} (\lambda \text{foo} \dots)$ ”) lives in $D_{[\tau]}$, then the “output *foo*” (i.e., “ $(\text{foo } [x])$ ”) lives in $D_{[[\tau]]}$. The above definition does not make sense in any particular type frame.

5.1 The Haskell Frame \mathcal{P}

So, what to do? Luckily, any frame in which the D_τ are pointed cpos can be extended to a pointed cpo over the indexed sets $\Pi \tau \in S. |D_\tau|$ used to denote polymorphic terms. This yields a least

Theorem 1 Let $\langle \mathcal{D}, \bullet, \sqsubseteq, \sqcup \rangle$ be a pcpo-frame and S be a set of ground type expressions. Then, $\Pi \tau \in S. |D_\tau|$ is a pointed cpo where:

- for any $f, g \in (\Pi \tau \in S. |D_\tau|)$, $f \sqsubseteq g \Leftrightarrow$ for all $\tau \in S$, $f\tau \sqsubseteq_\tau g\tau$, and
- the bottom element is $\perp_S \triangleq \{ \langle \tau, \perp_\tau \rangle \mid \tau \in S \}$

Proof of Theorem 1. To show that \sqsubseteq and \perp_S as above define a pointed, complete partial order on $\Pi \tau \in S. |D_\tau|$. Assume $X, X_i \in \Pi \tau \in S. |D_\tau|$. That \sqsubseteq is reflexive, anti-symmetric, and transitive follows directly from the fact the each \sqsubseteq_τ is so. Similarly, \perp_S is the least element of $\Pi \tau \in S. |D_\tau|$ because, for any $\tau \in \mathbf{Type}$, so is $\perp_S \tau = \perp_\tau$. Let $X_0 \sqsubseteq X_1 \sqsubseteq \dots$ be a directed chain. To show: $\bigsqcup X_i$ exists. Let $U \triangleq \{ \langle \tau, u_\tau \rangle \mid \tau \in S \text{ \& } u_\tau = \bigsqcup_\tau (X_i \tau) \}$. Clearly, $X_i \sqsubseteq U$ and $U \in (\Pi \tau \in S. |D_\tau|)$. Say there is a $V \in (\Pi \tau \in S. |D_\tau|)$ such that $V \sqsubset U$ and $X_i \sqsubseteq V$. Then, for some $\tau \in \mathbf{Type}$, $V\tau \sqsubset U\tau$ and $X_i \tau \sqsubseteq V\tau$. $\therefore \bigsqcup_\tau (X_i \tau)$ is not the lub of the directed chain $X_0 \tau \sqsubseteq_\tau X_1 \tau \dots$ in $|D_\tau|$. \dashv . So, every directed chain within $(\Pi \tau \in S. |D_\tau|)$ has a least upper bound in $(\Pi \tau \in S. |D_\tau|)$.

Note that, because $(\Pi \tau \in S. |D_\tau|)$ is a pointed cpo, we may define continuous functions and fixpoints over it in the standard way [1, 2, 15]. A function $f : (\Pi \tau \in S. |D_\tau|) \rightarrow (\Pi \tau \in T. |D_\tau|)$ is **continuous** when $f(\bigsqcup_S X_i) = \bigsqcup_T (f X_i)$. Given a continuous endofunction f , its least fixed point of is given by:

$$\text{fix}(f) = \bigsqcup_S (f^n \perp_S) \text{ for } n < \omega \text{ \& } f : (\Pi \tau \in S. |D_\tau| \rightarrow \Pi \tau \in S. |D_\tau|) \rightarrow (\Pi \tau \in S. |D_\tau|),$$

5.1.1 The inevitable cardinality question

How big are these $(\Pi \tau \in S. |D_\tau|)$? The answer, made precise by the theorem below, is “just as big as the D_τ ”:

Theorem 2 If $\text{card } \mathbf{Type} = \aleph_0$, then $\text{card}(\mathbf{Type} \rightarrow |D_\tau|) \leq \max(\aleph_0, \text{card}|D_\tau|)$.

Proof. Observe first that $(\Pi \tau \in \mathbf{Type}. |D_\tau|) \subseteq \mathbf{Type} \times |D_\tau|$. Now by cardinal arithmetic (see Kaplan-sky [7], Theorem 16, for example), $\text{card}(\mathbf{Type} \times |D_\tau|) = \max(\aleph_0, \text{card}|D_\tau|)$.

5.2 Polymorphic Recursion

5.2.1 ML/1' : a “syntax-oriented” version of ML/1

Definition 5 [Instantiations] Let $\tau, \tau' \in \mathbf{T}_0$ and $\vec{\alpha} = \alpha_1 \dots \alpha_n$ for some $n \geq 0$. We say that τ' is an *instantiation* of $\forall \vec{\alpha}. \tau$ for substitution s (written $(\forall \vec{\alpha}. \tau) \preceq_s \tau'$), if, and only if, for some $\tau_1 \dots \tau_n$ in \mathbf{T}_0 ,

$$\tau' = \tau \left[\underbrace{\alpha_1 \mapsto \tau_1, \dots, \alpha_n \mapsto \tau_n}_s \right]$$

Definition 6 [Alternate Type System for Polymorphic Recursion] from Kfoury, Tiuryn, and Urzyczyn [8]. The rules GEN, APP, ABS, and LET are identical to those of ML/1.

$$M ::= x \mid (M \ N) \mid (\lambda x.M) \mid (\text{let } x = N \text{ in } M) \mid (\text{pfix } x.M)$$

$$\begin{array}{ll} \text{(Open Types } \mathbf{T}_0) & \tau ::= \alpha \mid (\tau \rightarrow \tau') \\ \text{(Universal Types } \mathbf{T}_1) & \sigma ::= \forall \alpha. \sigma \mid \tau \end{array}$$

$$\begin{array}{ll} \text{VAR} & \frac{\Gamma(x) = \sigma, \sigma \preceq \tau}{\Gamma \vdash x : \sigma} \quad \text{APP} \quad \frac{\Gamma \vdash M : \tau \rightarrow \tau' \quad \Gamma \vdash N : \tau}{\Gamma \vdash (M \ N) : \tau'} \\ \text{GEN} & \frac{\Gamma \vdash M : \sigma}{\Gamma \vdash M : \forall \alpha. \sigma} \ (\alpha \notin FV(\Gamma), \alpha \in FV(\sigma)) \quad \text{ABS} \quad \frac{\Gamma, x : \tau \vdash M : \tau'}{\Gamma \vdash (\lambda x.M) : \tau \rightarrow \tau'} \\ \text{PFX} & \frac{\Gamma, x : \forall \vec{\alpha}. \tau' \vdash M : \tau'}{\Gamma \vdash \text{pfix } x.M : \tau} \ (\forall \vec{\alpha}. \tau' \preceq \tau, \vec{\alpha} \notin FV(\Gamma)) \quad \text{LET} \quad \frac{\Gamma \vdash N : \sigma' \quad \Gamma, x : \sigma' \vdash M : \sigma}{\Gamma \vdash (\text{let } x = N \text{ in } M) : \sigma} \end{array}$$

Below is the derivation of **size** in ML/1'.

$$\begin{array}{c} \frac{\Gamma_2(\text{size}) = \forall \alpha. (\text{Seq } \alpha) \rightarrow \text{Int} \quad \forall \alpha. (\text{Seq } \alpha) \rightarrow \text{Int} \preceq_s \text{Seq}(\alpha \times \alpha) \rightarrow \text{Int} \quad s = [\alpha \mapsto \alpha \times \alpha]}{\Gamma_2 \vdash \text{size} : \text{Seq}(\alpha \times \alpha) \rightarrow \text{Int}} \text{VAR} \quad \frac{\dots}{\Gamma_2 \vdash (\text{stl } s) : \alpha \times \alpha} \\ \frac{\dots}{\Gamma_2 \vdash \text{size } (\text{stl } s) : \text{Int}} \delta_* \quad \frac{\dots}{\Gamma_2 \vdash 2 * (\text{size } (\text{stl } s)) : \text{Int}} \delta_+ \\ \frac{\dots \quad \dots \quad \Gamma_2 \vdash 1 + (2 * (\text{size } (\text{stl } s))) : \text{Int}}{\Gamma_1, s : (\text{Seq } \alpha) \vdash \text{if } (\text{isNil } s) \text{ then } 0 \text{ else } (1 + (2 * (\text{size } (\text{stl } s)))) : \text{Int}} \delta_{\text{if}} \\ \frac{\Gamma_1, s : (\text{Seq } \alpha) \vdash \text{if } (\text{isNil } s) \text{ then } 0 \text{ else } (1 + (2 * (\text{size } (\text{stl } s)))) : \text{Int}}{\Gamma_1 \vdash \lambda s. \text{if } (\text{isNil } s) \text{ then } 0 \text{ else } (1 + (2 * (\text{size } (\text{stl } s)))) : (\text{Seq } \alpha) \rightarrow \text{Int}} \text{ABS} \\ \frac{\Gamma_1 \vdash \text{pfix } \text{size}. \lambda s. \text{if } (\text{isNil } s) \text{ then } 0 \text{ else } (1 + (2 * (\text{size } (\text{stl } s)))) : (\text{Seq } \alpha) \rightarrow \text{Int}}{\Gamma_0 \vdash \text{pfix } \text{size}. \lambda s. \text{if } (\text{isNil } s) \text{ then } 0 \text{ else } (1 + (2 * (\text{size } (\text{stl } s)))) : (\text{Seq } \alpha) \rightarrow \text{Int}} \text{PFX}(\alpha) \\ \frac{\Gamma_0 \vdash \text{pfix } \text{size}. \lambda s. \text{if } (\text{isNil } s) \text{ then } 0 \text{ else } (1 + (2 * (\text{size } (\text{stl } s)))) : (\text{Seq } \alpha) \rightarrow \text{Int}}{\Gamma_0 \vdash \text{pfix } \text{size}. \lambda s. \text{if } (\text{isNil } s) \text{ then } 0 \text{ else } (1 + (2 * (\text{size } (\text{stl } s)))) : \forall \alpha. (\text{Seq } \alpha) \rightarrow \text{Int}} \text{GEN}(\alpha) \end{array}$$

where

$$\begin{array}{ll} \Gamma_0 & = \{ \text{isNil} : \forall \alpha. (\text{Seq } \alpha) \rightarrow \text{Bool}, \text{stl} : \forall \alpha. \text{Seq } \alpha \rightarrow \text{Seq}(\alpha \times \alpha), +, * : \text{Int} \rightarrow \text{Int} \rightarrow \text{Int} \} \\ \Gamma_1 & = \Gamma_0, \text{size} : \forall \alpha. (\text{Seq } \alpha) \rightarrow \text{Int} \\ \Gamma_2 & = \Gamma_1, s : (\text{Seq } \alpha) \end{array}$$

6 Related Work

Comment on [10, 8, 4, 3] and also on Schwartzbach's excellent note [16]. Furthermore, on [5, 18, 17].

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