WROCLAW UNIVERSITY OF TECHNOLOGY
DEPARTMENT OF ELECTRONICS

Field: Electronics
Speciality: Advanced Applied Electronics

Numerical Methods: Eigenproblems

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Chapter 1

Solution to the given problems

(Problems 1, 3, 4 and 7 are solved analytically, without using any of selected algorithms. Result are checked with built-in Octave/Matlab function.)

Problem 1 - Compute the eigenpairs of the matrices. Verify that trace equals to eigenvalues sum and the determinant to their product. Which matrix is singular?

To find eigenvalues, the following calculations will be used:
$Ax - \lambda x = 0$
$(A - \lambda I)x = 0$
$det(A - \lambda I) = 0$ Then the characteristic polynomial can be determined. It's roots are the eigenvalues.

Matrix A1

$$A_1 = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$det \begin{bmatrix} 1-\lambda & 0 & 0 \\ 2 & 1-\lambda & 0 \\ 0 & 0 & 3-\lambda \end{bmatrix} = (1-\lambda)(1-\lambda)(3-\lambda)$$

$For \lambda = 1:$
$\begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \ => \begin{matrix} 2x_1 = 0 \\ 2x_3 = 0 \\ (no\ x_2\ formula) \end{matrix} \ => x = \begin{bmatrix} 0 \\ t \\ 0 \end{bmatrix}$
$For \lambda = 3:$
$\begin{bmatrix} -2 & 0 & 0 \\ 2 & -2 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \ => \begin{matrix} -2x_1 = 0 \\ 2x_1 - 2x_2 = 0 \\ (no\ x_3\ formula) \end{matrix} \ => x = \begin{bmatrix} 0 \\ 0 \\ t \end{bmatrix}$
$tr(A) = 1 + 1 + 3 = 5$
$\sum \lambda = 1 + 1 + 3 = 5$

$det(A) = 1 \cdot 1 \cdot 3 = 3$
$\prod \lambda = 1 \cdot 1 \cdot 3 = 3$
Matrix determinant is non–zero, so the matrix is not singular.

Matrix A2

$$A_2 = \begin{bmatrix} 0 & -2 & 1 \\ 1 & 3 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$det \begin{bmatrix} 0-\lambda & -2 & 1 \\ 1 & 3-\lambda & -1 \\ 0 & 0 & 1-\lambda \end{bmatrix} = (Sarrus\ theorem =>)(1-\lambda)(1-\lambda)(3-\lambda) =$$

$$= (-\lambda)(3-\lambda)(1-\lambda) - (-2)(1-\lambda) = (1-\lambda)(\lambda^2 - 3\lambda + 2)$$

$For \lambda = 1:$
$$\begin{bmatrix} -1 & -2 & 1 \\ 1 & 2 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \ => \begin{matrix} -x_1 - 2x_2 + x_3 = 0 \\ x_1 + 2x_2 - x_3 = 0 \end{matrix} => x = \begin{bmatrix} -2v_2 + v_3 \\ v_2 \\ v_3 \end{bmatrix}$$

$For \lambda = 2:$
$$\begin{bmatrix} -2 & -2 & 1 \\ 1 & 1 & -1 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \ => \begin{matrix} -2x_1 - 2x_2 + x_3 = 0 \\ x_1 + x_2 - x_3 = 0 \\ (-x_3 = 0) \end{matrix} => x = \begin{bmatrix} v \\ -v \\ 0 \end{bmatrix}$$

$tr(A) = 3 + 1 = 4$
$\sum \lambda = 1 + 1 + 2 = 4$

$det(A) = 2$
$\prod \lambda = 1 \cdot 1 \cdot 2 = 2$
Matrix determinant is non–zero, so the matrix is not singular.

Matrix A3

$$A_3 = \begin{bmatrix} 4 & 1 & 0 \\ 1 & 4 & 1 \\ 0 & 1 & 4 \end{bmatrix}$$

$$deA_3 = \begin{bmatrix} 4-\lambda & 1 & 0 \\ 1 & 4-\lambda & 1 \\ 0 & 1 & 4-\lambda \end{bmatrix} t = (Sarrus\ theorem =>)(4-\lambda)(4-\lambda)(4-\lambda) - (4-\lambda) - (4-\lambda) =$$

$$= (4-\lambda)(\lambda^2 - 8\lambda + 14) = (4-\lambda)(\lambda - (4+\sqrt{2}))(\lambda - (4-\sqrt{2}))$$

$For \lambda = 4:$
$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \ => \begin{matrix} -x_1 - 2x_2 + x_3 = 0 \\ x_1 + 2x_2 - x_3 = 0 \end{matrix} => x = \begin{bmatrix} -2v_2 + v_3 \\ v_2 \\ v_3 \end{bmatrix}$$

$For \lambda = 4 + \sqrt{2}:$
$$\begin{bmatrix} -\sqrt{2} & 1 & 0 \\ 1 & -\sqrt{2} & -1 \\ 0 & 1 & -\sqrt{2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \ => \begin{matrix} -\sqrt{2}x_1 + x_2 = 0 \\ x_1 - \sqrt{2}x_2 + x_3 = 0 \\ x_2 - \sqrt{2}x_3 = 0 \end{matrix} => x = \begin{bmatrix} v \\ \sqrt{2}v \\ v \end{bmatrix}$$

$For \lambda = 4 - \sqrt{2}:$
$$\begin{bmatrix} \sqrt{2} & 1 & 0 \\ 1 & \sqrt{2} & -1 \\ 0 & 1 & \sqrt{2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \ => \begin{matrix} \sqrt{2}x_1 + x_2 = 0 \\ x_1 + \sqrt{2}x_2 + x_3 = 0 \\ x_2 + \sqrt{2}x_3 = 0 \end{matrix} => x = \begin{bmatrix} v \\ -\sqrt{2}v \\ v \end{bmatrix}$$

$tr(A) = 4 + 4 + 4 = 12$
$\sum \lambda = 4 + 4 + \sqrt{2} + 4 - \sqrt{2} = 12$

$det(A) = 56$
$\prod \lambda = 4 \cdot (4 + \sqrt{2}) \cdot (4 + \sqrt{2}) = 4 \cdot (4^2 - (\sqrt{2})^2) = 4 \cdot 14 = 56$
Matrix determinant is non–zero, so the matrix is not singular.

Matrix A4

$$A_4 = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \\ 13 & 14 & 15 & 16 \end{bmatrix} \begin{matrix} R2 - 2R1 \\ R3 - R1 \\ = \\ R4 - 4R1 \end{matrix} \begin{bmatrix} 1 & 2 & 3 & 4 \\ 3 & 2 & 1 & 0 \\ 6 & 4 & 2 & 0 \\ 9 & 6 & 3 & 0 \end{bmatrix} \begin{matrix} R3 - 2R2 \\ = \\ R4 - 3R2 \end{matrix} \begin{bmatrix} 1 & 2 & 3 & 4 \\ 3 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

det(A) = 0, so matrix is singular.

Now calculating the eigenvalues:

$$\begin{bmatrix} 1-\lambda & 2 & 3 & 4 \\ 5 & 6-\lambda & 7 & 8 \\ 9 & 10 & 11-\lambda & 12 \\ 13 & 14 & 15 & 16-\lambda \end{bmatrix} => \begin{matrix} \lambda_1 = 0 \\ \lambda_2 = 0 \\ \lambda_3 = 17 + 3\sqrt{41} \\ \lambda_4 = 17 - 3\sqrt{41} \end{matrix}$$

$tr(A) = 1 + 6 + 11 + 16 = 34 = 12$
$\sum \lambda = 0 + 0 + 17 + 3\sqrt{41} + 17 - 3\sqrt{31} = 34$

$det(A) = 0$
$\prod \lambda = 0$
Matrix determinant is zero, so the matrix is singular.

Problem 2: Compute the largest and the smallest eigenvalue to the following matrix, using the scaled power algorithm and the shifted inverse power algorithm, respectively:

$$\mathbf{A} = \begin{bmatrix} 4 & 2 & 0 & 0 \\ 1 & 4 & 1 & 0 \\ 0 & 1 & 4 & 1 \\ 0 & 0 & 2 & 4 \end{bmatrix}$$

To compute the required values, the Scaled Power algorithm (Alg.1) and the shift inverse Power algorithm (Alg.2) were coded.

The task solution was designed in the following Octave code:

```
A = [4 2 0 0; 1 4 1 0; 0 1 4 1; 0 0 2 4]
iterations = 10;
#computing the biggest and smallest eigenpairs

disp(['Eigenproblems using Power methods:'])

[eigenvalueMAX, eigenvectorMAX] = scaledpower(A, iterations)
[eigenvalueMIN, eigenvectorMIN] = inversepower(A, iterations)
```

That gave the results:

```
>> task2
A =

   4   2   0   0
   1   4   1   0
   0   1   4   1
   0   0   2   4

Eigenproblems using Power methods:
eigenvalueMAX =  5.9972
eigenvectorMAX =

   0.53305
   0.51621
   0.48242
   0.46547

eigenvalueMIN =  2.0000
eigenvectorMIN =

  -0.50266
   0.50132
  -0.49866
   0.49734
```

As it can be compared, after 10 iterations they are quite correct approximation of the exact values:

```
>> [lambdas, vectors] = eig(A)
lambdas =

  -0.50000  -0.63246   0.50000  -0.63246
   0.50000   0.31623   0.50000  -0.31623
  -0.50000   0.31623   0.50000   0.31623
   0.50000  -0.63246   0.50000   0.63246

vectors =

Diagonal Matrix

   2.0000        0        0        0
        0   3.0000        0        0
        0        0   6.0000        0
        0        0        0   5.0000
```

Problem 3: Solve the differential equation:

$$\frac{d\mathbf{u}}{dt} = \mathbf{P}\mathbf{u} \text{ with } \mathbf{u}_0 = \begin{bmatrix} 8 \\ 5 \end{bmatrix} \text{ and } \mathbf{P} = \begin{bmatrix} 4 & -5 \\ 2 & -3 \end{bmatrix}.$$

Solution of the differential equation has the following form:

$$u = \alpha \cdot exp\{\lambda t\}$$

So in this particular case we are looking for:
$u_1 = \alpha_1 \cdot exp\{\lambda_1 t\}$
$u_2 = \alpha_2 \cdot exp\{\lambda_2 t\}$

$$\begin{bmatrix} 4 & -5 \\ 2 & -3 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} = \lambda \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix}$$

Now, we are calculating the eigenvalues:

$$det \begin{bmatrix} 4-\lambda & -5 \\ 2 & -5-\lambda \end{bmatrix} = (4-\lambda)(-3-\lambda)+10 = -12-4\lambda+3\lambda+\lambda^2+10 = \lambda^2 = \lambda-2 = (\lambda-2)(\lambda+1)$$

$For \lambda = 2:$

$$\begin{bmatrix} 2 & -5 \\ 2 & -5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 => \begin{matrix} 2x_1 - 5x_2 = 0 \\ so \; 2x_1 = 5x_2 \end{matrix} \quad => x = \begin{bmatrix} 5t \\ 2t \end{bmatrix}$$

$For \lambda = -1$:

$$\begin{bmatrix} 5 & -5 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 => \begin{matrix} 5x_1 = 5x_2 \\ so \; x_1 = x_2 \end{matrix} \quad => x = \begin{bmatrix} t \\ t \end{bmatrix}$$

And now the solution is in the following form:

$$u = c_1 exp\{2t\} \begin{bmatrix} 5 \\ 2 \end{bmatrix} + c_2 exp\{-t\} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Using initial condition the c values will be calculated (assuming eigenvector for t=1).

$$\begin{bmatrix} 5 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 8 \\ 5 \end{bmatrix} => \begin{matrix} 5c_1 + c_2 = 8 \\ 2c_1 + c_2 = 5 \end{matrix} => \begin{matrix} c_1 = 1 \\ c_2 = 3 \end{matrix}$$

Assembling all calculations, the solution to the differential equation is:

$$u = 1 \cdot exp\{2t\} \begin{bmatrix} 5 \\ 2 \end{bmatrix} + 3 \cdot exp\{-t\} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Problem 4: Find $\mathbf{A}^{100}$ by diagonalizing $\mathbf{A} = \begin{bmatrix} 4 & 3 \\ 1 & 2 \end{bmatrix}$.

Matrix can be diagonalized, if it has an inverse. So at first the determinant must be non-zero.

$det(A) = 4 \cdot 2 - 3 \cdot 1 = 5$

The eigenvalues need to be calculated

$$det \begin{bmatrix} 4-\lambda & 3 \\ 1 & 2-\lambda \end{bmatrix} = (4-\lambda)(2-\lambda) - 3 = 8 - 4\lambda - 2\lambda + \lambda^2 - 3 = (\lambda - 1)(\lambda - 5)$$

$For \lambda = 1$:

$$\begin{bmatrix} 3 & 3 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 => \begin{matrix} 3x_1 + 3x_2 = 0 \\ x_1 = -x_2 \end{matrix} \quad => x_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$For \lambda = 5$:

$$\begin{bmatrix} -1 & 3 \\ 1 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 => \begin{matrix} -x_1 + 3x_2 = 0 \\ x_1 - 3x_2 = 0 \end{matrix} \quad => x_1 = 3x_2 => x_2 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

Now to calculate A^{100} we will use the following formula:

$$A^{100} = X\Lambda^k X^{-1}$$

And to calculate Λ itself:

$$\Lambda = X^{-1}AX$$

The matrices:

$$X = \begin{bmatrix} 1 & 3 \\ -1 & 1 \end{bmatrix} \qquad X^{-1} = \begin{bmatrix} 0.25 & -0.75 \\ 0.25 & 0.25 \end{bmatrix} \qquad \Lambda = \begin{bmatrix} 1 & 0 \\ 0 & 5 \end{bmatrix}$$

And the final calculation:

$$A^{100} = X\Lambda^{100}X^{-1} = \begin{bmatrix} 1 & 3 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 5 \end{bmatrix}^{100} \begin{bmatrix} 0.25 & -0.75 \\ 0.25 & 0.25 \end{bmatrix} = \begin{bmatrix} 5.9165e+69 & 5.9165e+69 \\ 1.9722e+69 & 1.9722e+69 \end{bmatrix}$$

Problem 5: Show that the matrix $\mathbf{A} = \begin{bmatrix} 2 & 1 & 1 \\ 2 & 1 & -2 \\ -1 & 0 & -2 \end{bmatrix}$ is not diagonalizable.

Matrix is diagonalizable if:

- can be inverted,
- has n linearly independent eigenvectors,
- surely is diagonalizable if has n distinct eigenvalues.

$$det \begin{bmatrix} 2 & 1 & 1 \\ 2 & 1 & -2 \\ -1 & 0 & -2 \end{bmatrix} = 3$$

Determinant is not equal to zero, so matrix has an inverse.

Using coded "basic QR iteration" (Algorithm 3) we will search eigenvalues and eigenvectors.

```
[l,v] = iterqr(A, 100000)
A =
2    1    1
2    1   -2
-1    0   -2

l =
Diagonal Matrix

3.0000    0          0
0        -1.0000     0
0         0         -1.0000


v =
0.63500     0.40825     0.40825
0.76200    -0.81650    -0.81650
-0.12700   -0.40825    -0.40825
```

The calculations show, that the eigenvalues are not distinct – there is a possibility that diagonal do not exists.
To be completely sure, the eigenspace has to be estimated. Looking at the eigenvectors value, we can see that two of them are equal. Therefore they are linearly dependent.

The conclusion is that the diagonal of the presented matrix does not exist.

Problem 6: Compute the eigenpairs for the matrix $\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 2 & 3 \\ 0 & 2 & 3 & 2 \\ 0 & 0 & 3 & 4 \end{bmatrix}$.

The following matlab code (with coded algorithms) was used to perform computations:

```
A =     [1 2 3 4;
          1 2 2 3;
          0 2 3 2;
          0 0 3 4];

disp(['Matlab embedded eig()'])
[lambda, vector] = eig(A)
disp(['QR iteration'])
[lambda, vector] = iterqr(A,100)
disp(['Single shift QR'])
[lambda, vector] = iterqr_shift(A,100)
```

```
>> task6
Matlab embedded eig()
lambda =

   0.74474 + 0.00000i  -0.14294 - 0.34106i  -0.14294 + 0.34106i   0.62708 + 0.00000i
  -0.31659 + 0.00000i  -0.24192 - 0.41028i  -0.24192 + 0.41028i   0.51252 + 0.00000i
   0.46560 + 0.00000i  -0.51511 + 0.18917i  -0.51511 - 0.18917i   0.43021 + 0.00000i
  -0.35826 + 0.00000i   0.57903 + 0.00000i   0.57903 - 0.00000i   0.39877 + 0.00000i

vector =

Diagonal Matrix

   0.10114 + 0.00000i                    0                    0                    0
                    0   1.33118 + 0.98013i                    0                    0
                    0                    0   1.33118 - 0.98013i                    0
                    0                    0                    0   7.23650 + 0.00000i

QR iteration
orig =

   1   2   3   4
   1   2   2   3
   0   2   3   2
   0   0   3   4

lambda =

Diagonal Matrix

   7.23650         0         0         0
         0   1.15917         0         0
         0         0   1.50319         0
         0         0         0   0.10114

vector =

   0.627075  -0.277054  -0.052468  -0.726130
   0.512520  -0.506149  -0.234799   0.652691
   0.430210   0.778808  -0.443899   0.106445
   0.398773   0.245991   0.863174   0.188147

Single shift QR
lambda =

Diagonal Matrix

   7.23650         0         0         0
         0   0.10114         0         0
         0         0   1.33118         0
         0         0         0   1.33118

vector =

   0.62708  -0.55533   0.31195   0.44842
   0.51252   0.53881  -0.57101   0.34778
   0.43021  -0.33234  -0.38249  -0.74711
   0.39877   0.53930   0.65600  -0.34613
```

As the results show - the eigenvalues are all the same in case of every method that was used. According to the eigenvectors, only the dominant one match one each other.
It can be a matter of fact, that the solutions are iterative and only approximate.

Now, we can also perform some computations (as it was stated in previous report - each try is a 1000 round loop).

```
Matlab embedded eig()
Elapsed time is 0.016705 seconds.
QR iteration
Elapsed time is 5.19331 seconds.
Single shift QR
Elapsed time is 5.3176 seconds.
```

There is a huge difference between first algorithm (embedded) and the coded QR's. It is certainly the effect of using coded by author QR factorization.

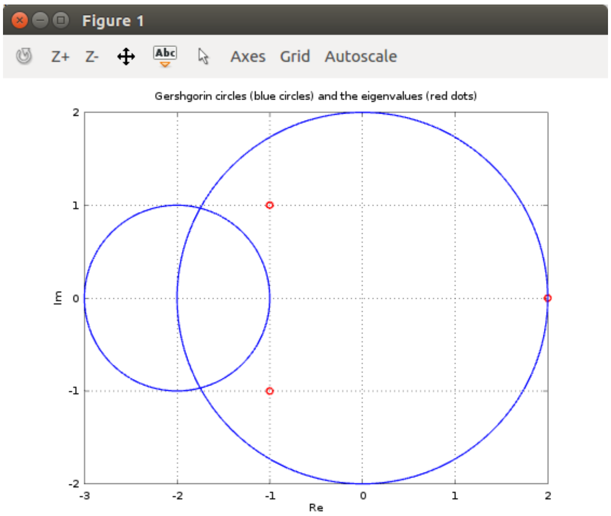
Performing simple test (changing QR factoriation to matlab embedded inside coded algorithm) will show the truth. And in fact it is, as expected – much shorter execution time:

```
Matlab embedded eig()
Elapsed time is 0.0244899 seconds.
QR iteration
Elapsed time is 0.185272 seconds.
Single shift QR
Elapsed time is 0.28676 seconds.
```

Problem 7 - Draw the Gershgorin discs and determine the location of the eigenvalues for the matrices. Then compute an approximate eigensystem.

$$\mathbf{A}_1 = \begin{bmatrix} -2 & -1 & 0 \\ 2 & 0 & 0 \\ 0 & 0 & 2 \end{bmatrix}, \qquad \mathbf{A}_2 = \begin{bmatrix} 5 & 1 & 1 \\ 0 & 6 & 1 \\ 0 & 0 & -5 \end{bmatrix}, \qquad \mathbf{A}_3 = \begin{bmatrix} 5.2 & 0.6 & 2.2 \\ 0.6 & 6.4 & 0.5 \\ 2.2 & 0.5 & 4.7 \end{bmatrix},$$

The Gershgorin circles are based on matrices:
- circles centers are indicated by the numbers on main diagonal,
- item circle radius is the sum of the remaining elements in the current row.



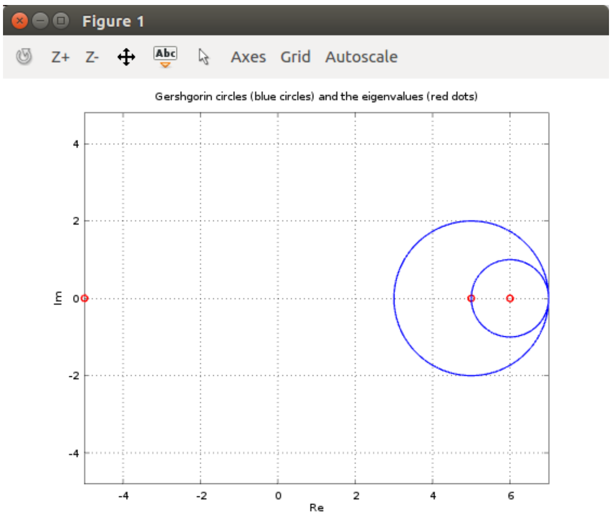


Figure 1.1 Matrix A1 and A2

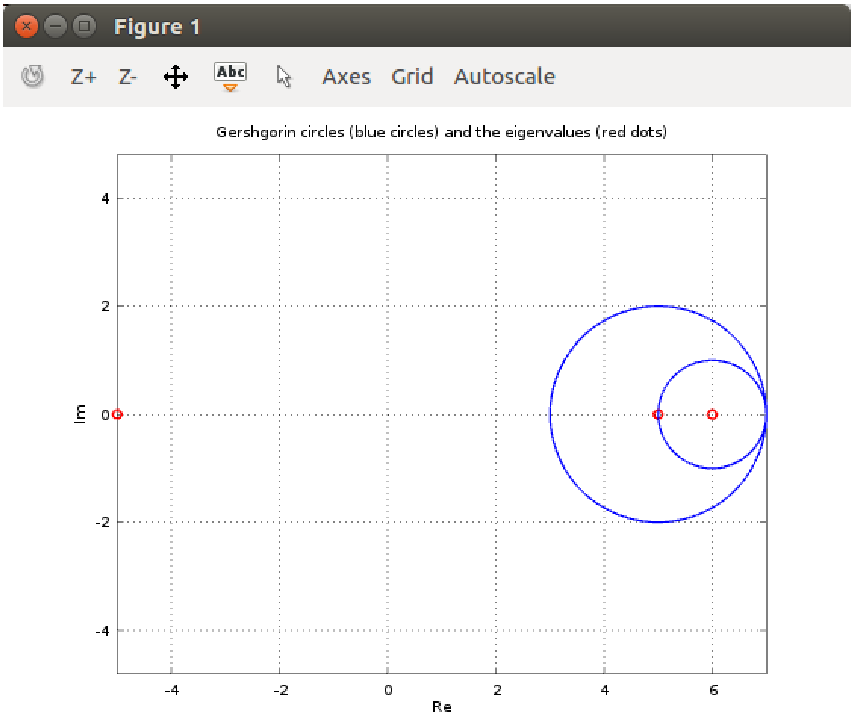


Figure 1.2 Matrix A3

Chapter 2

Listings of algorithms

2.1 Coded selected algorithms

Algorithm 1 - Scaled Power algorithm
It calculates the dominant eigenvalue and eigenvector.

```
function [lambda, vector] = scaledpower(A, iterations)

[n,n] = size(A);

q_prev = rand(n,1);
q_prev = q_prev/norm(q_prev);

lambda = [];
q = [];

for i = 1:iterations
z = A * q_prev;
q = z/norm(z);
q_prev = q;
endfor

#calculating Rayleigh quotient
lambda = (q'*A*q)/(q'*q);
vector = q;
endfunction
```

Algorithm 2 - Inverse Power algorithm
In contrary to previous one - the result is the least significant eigenpair.

```
function [lambda, vector] = inversepower(A, iterations)

[n,n] = size(A);

q_prev = rand(n,1);
q_prev = q_prev/norm(q_prev);
alpha = 1;
I = eye(n);
q = [];
v=[];
for i = 1:iterations

v = inv(A - alpha*I)*q_prev;
q = v/norm(v);
q_prev = q;
endfor

lambda = (q'*A*q)/(q'*q);
vector = q;

endfunction
```

Algorithm 3 - Basic QR iterations
Algorithm calculates the eigenvalue and eigenvectors (based on all Q product).

```
function [lambda, vector] = iterqr(A, iterations)

[n,n] = size(A);
Qproduct = eye(n,n);

for i = 1:iterations
[Q,R] = QRgivens_lecture(A);     #calculating QR
A = R*Q;                         # assigning next step A

Qproduct = Qproduct*Q;           # eigenvectors are product of all Qs

endfor

lambda = diag(diag(A));
vector = Qproduct;

endfunction
```

Algorithm 4 - Shift QR algorithm
Algorithm calculates the eigenvalue and eigenvectors (based on all Q product).

```
function [lambda, vector] = iterqr_shift(A, iterations)

[n,n] = size(A);

Qproduct = eye(n);
I = eye(n);


for i = 1:iterations
s = A(n,n);                        #choose the element for shift
shift = s*I;                       #create shifting diagonal

[Q,R] = QRgivens_lecture(A-shift);#apply QR factorization
A = R*Q+shift;

Qproduct = Qproduct*Q;             #multiply Q product by new Q

endfor

lambda = diag(diag(A));
vector = Qproduct;
endfunction
```

Bibliography

[1] Björck, Åke. Numerical methods for least squares problems. Society for Industrial and Applied Mathematics, 1996.

[2] Golub, Gene H., and Charles F. Van Loan. "Matrix computations, 3rd." (1996).

[3] Transforming a matrix to reduced row echelon form, http://www.di-mgt.com.au/matrixtransform.html

[4] Zdunek R., Numerical Methods - lecture slides.