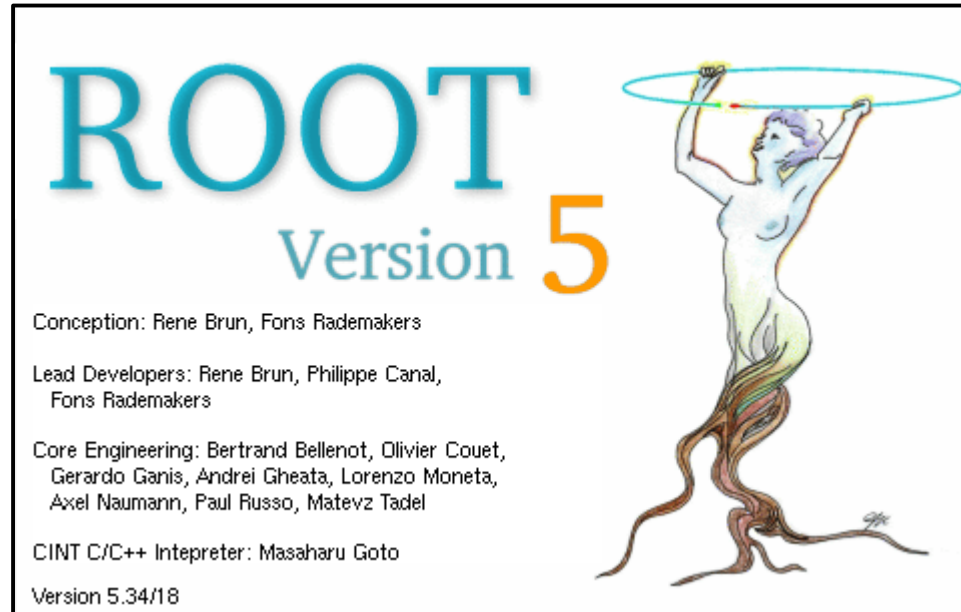


Introduction to ROOT



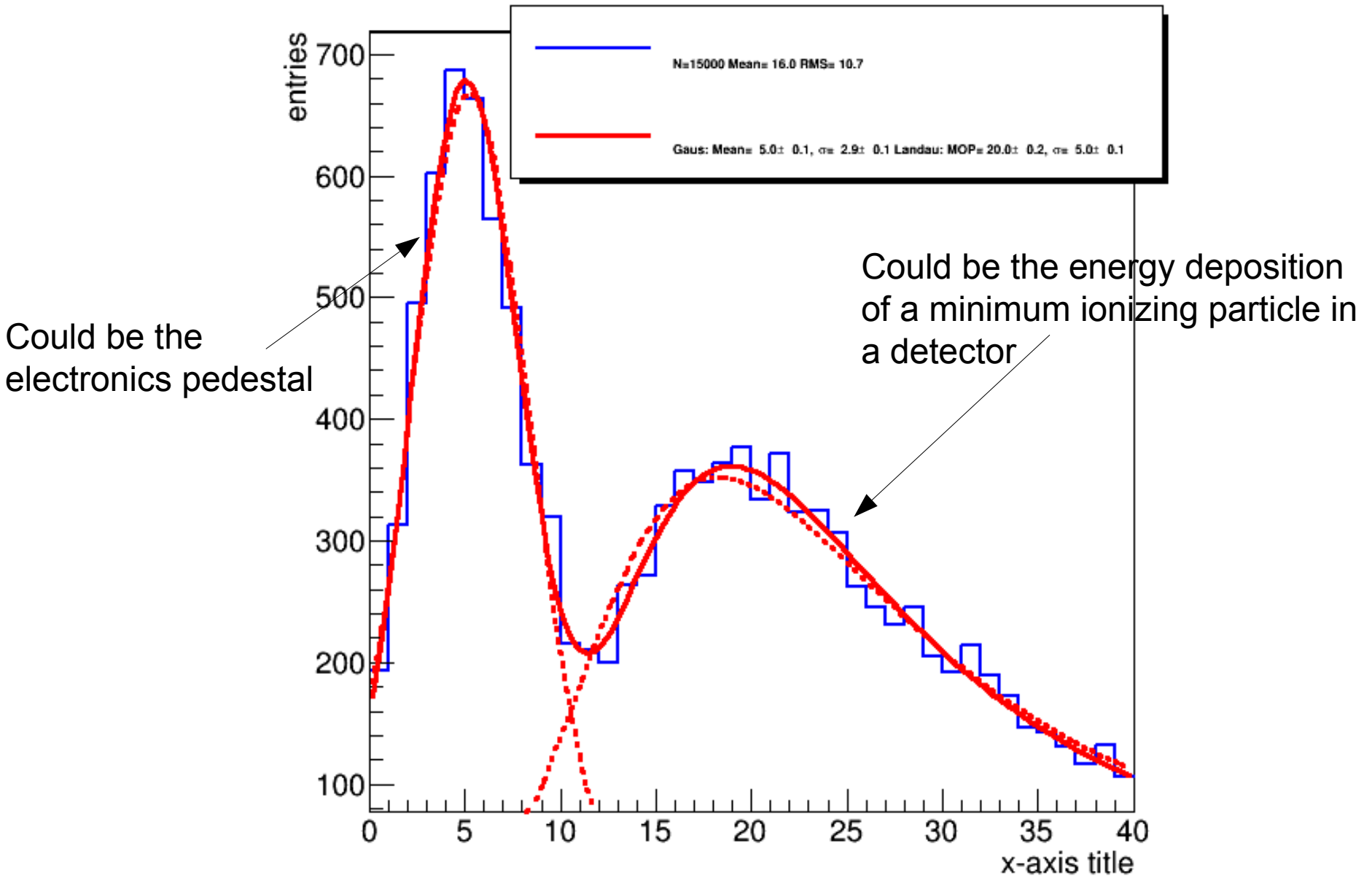
Fall 2014 - 2

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Exercise

- Fill a histogram randomly ($n \sim 10,000$) with a Landau distribution with a most probable value at 20 and a “width” of 5 (use the ROOT website to find out about the Landau function)
- Fill the same histogram randomly ($n \sim 5,000$) with a Gaussian distribution centered at 5 with a “width” of 3
- Write a compiled script with a fit function that describes the total histogram nicely (it might be a good idea to fit both peaks individually first and use the fit parameters for a combined fit)
- Add titles to x- and y-axis
- Include a legend of the histogram with number of entries, mean, and RMS values
- Add text to the canvas with the fitted function parameters
- Draw everything on a square-size canvas (histogram in blue, fit in red)
- Save as png, eps, and root file
- Email me your result: philipvd@hawaii.edu

Exercise



Solution exercise 1

```
#include<iostream>

#include<TH1D.h>
#include<TF1.h>
#include<TCanvas.h>
#include<TRandom.h>
#include<TStyle.h>
#include<TLegend.h>
#include<TROOT.h>
#include<TPaveText.h>

void exercisel()
{
  gROOT->Reset();
  TStyle * plain = new TStyle("plain","plain");
  plain->SetCanvasBorderMode(0);
  plain->SetPadBorderMode(0);
  plain->SetPadColor(0);
  plain->SetCanvasColor(0);
  plain->SetTitleColor(1);
  plain->SetStatColor(0);
  plain->SetTitleFillColor(0);

  gROOT->SetStyle("plain");
  gStyle->SetPalette(1);

  //create empty histogram
  TH1D * h = new TH1D("histo", "", 40,0,40);
  //disable display of histogram statistics
  h->SetStats(false);

  //fill with Landau distribution
  for(double i = 0; i < 10000; i++) h->Fill(gRandom->Landau(20,5));

  //fill with Gaus distribution
  for(double i = 0; i < 5000; i++) h->Fill(gRandom->Gaus(5,3));

  //define fit functions
  TF1 * FitFunc1 = new TF1("FitFunc1","[0]*TMath::Gaus(x,[1],[2])",0,40);
  TF1 * FitFunc2 = new TF1("FitFunc2","[0]*TMath::Landau(x,[1],[2])",0,40);
  TF1 * FitFuncCombined = new TF1("FitFunc2","[0]*TMath::Gaus(x,[1],[2])+[3]*TMath::Landau(x,[4],[5])",0,40);

  //fit both peaks individually with reasonable initial parameters and fitting range
  FitFunc1->SetParameters(1,3,4);
  h->Fit(FitFunc1,"0","","0,10);

  FitFunc2->SetParameters(1,17,7);
  h->Fit(FitFunc2,"0","","10,40);
```

Solution exercise 1 - continued

```
//use fit parameters as initial parameters for combined fit
FitFuncCombined->SetParameters(FitFunc1->GetParameter(0), FitFunc1->GetParameter(1), FitFunc1->GetParameter(2), FitFunc2->GetParameter(0), FitFunc2->GetParameter(1), FitFunc2->GetParameter(2));
h->Fit(FitFuncCombined,"0","");

//display what we did
TCanvas * c = new TCanvas("c_ref","c_title", 200,10,600,600);
c->SetLeftMargin(0.15);
c->SetRightMargin(0.04);
c->SetTopMargin(0.04);

//Legend
TLegend* Leg = new TLegend(0.3,0.8,0.99,0.99);
Leg->SetFillColor(0);
Leg->SetTextFont(62);

h->SetLineWidth(2);
h->SetLineColor(kBlue);
h->GetXaxis()->SetTitle("x-axis title");
h->GetYaxis()->SetTitleOffset(1.4);
h->GetYaxis()->SetTitle("entries");
h->Draw();

char text[400];
sprintf(text,"N=%5.0f Mean=%5.1f RMS=%5.1f", h->GetEntries(), h->GetMean(), h->GetRMS());
Leg->AddEntry(h,text,"l");

FitFunc1->SetLineStyle(2);
FitFunc1->SetLineColor(kRed);
FitFunc1->Draw("same");

sprintf(text,"Gaus: Mean=%5.1f#pm%5.1f, #sigma=%5.1f#pm%5.1f Landau: MOP=%5.1f#pm%5.1f, #sigma=%5.1f#pm%5.1f", FitFuncCombined->GetParameter(1),
FitFuncCombined->GetParError(1), FitFuncCombined->GetParameter(2), FitFuncCombined->GetParError(2), FitFuncCombined->GetParameter(4), FitFuncCombined->GetParError(4), FitFuncCombined->GetParameter(5), FitFuncCombined->GetParError(5));
Leg->AddEntry(FitFuncCombined,text,"l");

FitFunc2->SetLineStyle(2);
FitFunc2->SetLineColor(kRed);
FitFunc2->Draw("same");

FitFuncCombined->SetLineColor(kRed);
FitFuncCombined->Draw("same");

Leg->Draw();

//Save canvas
c->SaveAs("ex1.eps");
c->SaveAs("ex1.png");
c->SaveAs("ex1.root");
}
```

Projection

- Can be done interactively →
- extract projection from TH2 histogram

```
root [0] TH2D * h = new  
TH2D("histo", "", 40,0,40,40,0,40);
```

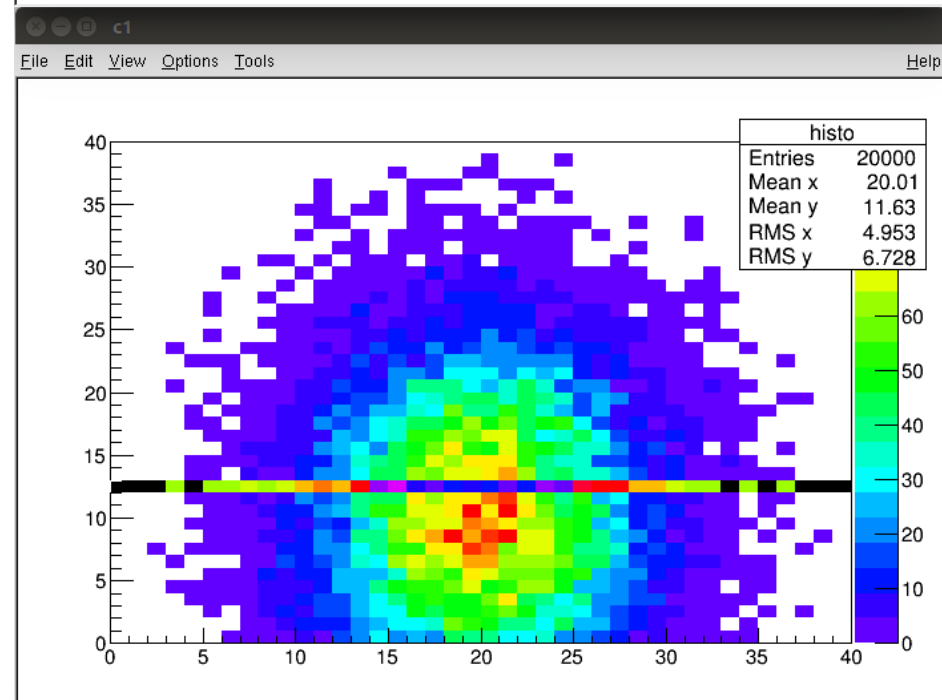
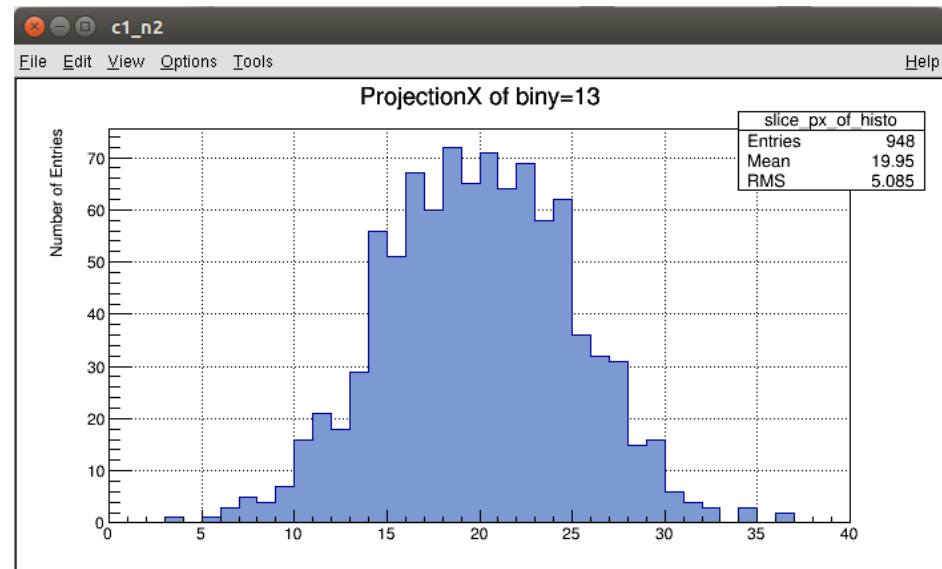
```
root [1] for(double i = 0; i <  
20000; i++) h->Fill(gRandom-  
>Gaus(20,5), gRandom->Gaus(10,8));
```

```
root [2] TH1D * proj = h-  
>ProjectionY(" ", 21,21);
```

```
root [3] proj->Draw();
```

Works also for x

Choose bin range

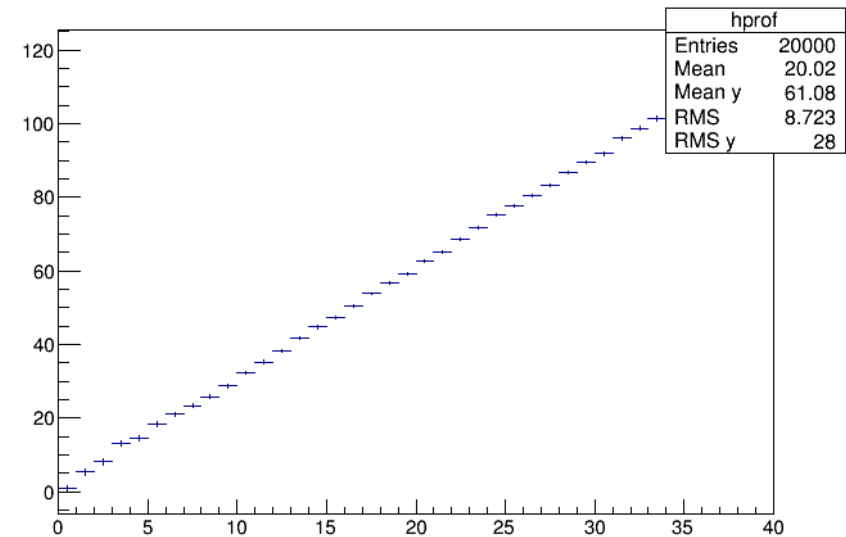
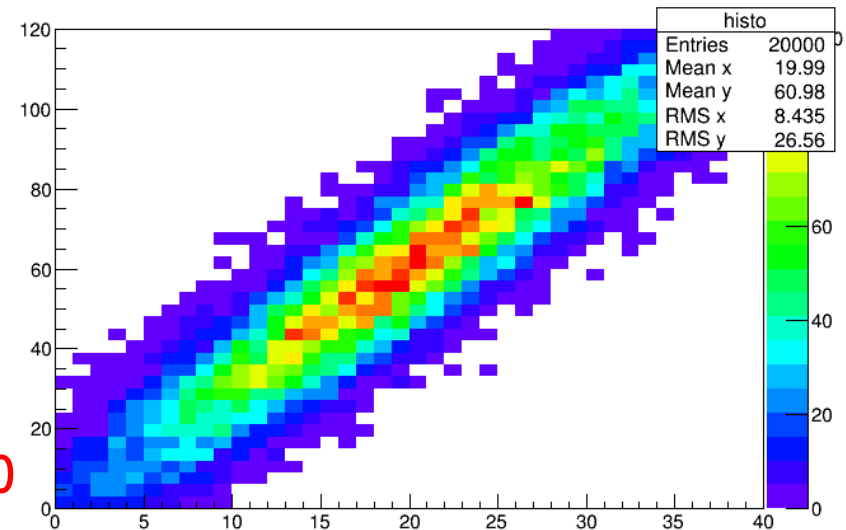


Profile

```
root [0] TH2D * h = new  
TH2D("histo", "",  
40,0,40,40,0,120);  
root [1] TProfile * hprof  
= new  
Tprofile("hprof", "",40,0,40  
);
```

```
root [2] for(double i = 0;  
i < 20000; i++) { double x  
= gRandom->Gaus(20,10);  
double y = gRandom-  
>Gaus(x*3+1,10); hprof-  
>Fill(x,y); h->Fill(x,y);}
```

```
root [3] hprof->Draw();  
root [4] h->Draw("colz")
```



The displayed error is by default the standard error on the mean
(i.e. the standard deviation divided by the \sqrt{n})

TMath and TRandom

- TRandom: periodicity = 10^9 (fast)
- TRandom1: periodicity = 10^{171} (slow)
- TRandom2: periodicity = 10^{26} (fast)
- TRandom3: periodicity = 10^{6000} (fast)

```
TRandom3 * ran = new TRandom3();
```

```
ran->SetSeed(0); //0 = computer clock
```

```
ran->Uniform(1,10);
```

```
ran->Gaus(2,5);
```


TMatrix – inversion example

```
#include<TMatrixD.h>
#include<TDecompSVD.h>
#include<TVectorD.h>
#include<TRandom.h>

void matrix(int Layers = 4)
{
    TMatrixD M(Layers, Layers);

    for(int m = 0; m < Layers; m++)
        for(int k = 0; k < Layers; k++) M[m]
            [k] = gRandom->Gaus(5,10);

    M.Print();

    //Calculate inverse of the matrix via
    singular value decomposition

    TDecompSVD * SVD = new TDecompSVD(M);

    TMatrixD U_T = SVD->GetU();
    U_T.T();

    TMatrixD V = SVD->GetV();

    TVectorD S = SVD->GetSig();
```

```
//invert S

TMatrixD S_inv(Layers,Layers);
for(int i = 0; i < Layers; i++)
    S_inv[i][i] = 1/S[i];

//multiply V S-1
TMatrixD VS_inv(Layers,Layers);

VS_inv.Mult(V,S_inv);

//calculate M-1
TMatrixD M_inv(Layers,Layers);

M_inv.Mult(VS_inv,U_T);

M_inv.Print();

//test
TMatrixD Test(Layers,Layers);
Test.Mult(M_inv,M);
Test.Print();
}
```

Cos² random isotropic distribution

```
TRandom3 * random = new TRandom3();
double phi = random->Uniform(0,2*TMath::Pi());

int plane = (rand()%6)+1;
double theta = acos(sqrt(random->Uniform(0,1)));
switch(plane)
{
  case 1:
  {
    s1 = random->Uniform(-limit,limit);
    s2 = random->Uniform(-limit,limit);
    s3 = limit;

    n1 = sin(theta)*cos(phi);
    n2 = sin(theta)*sin(phi);
    n3 = cos(theta);
  }
  break;
  case 2:
  {
    s1 = random->Uniform(-limit,limit);
    s2 = random->Uniform(-limit,limit);
    s3 = -limit;

    n1 = sin(theta)*cos(phi);
    n2 = -sin(theta)*sin(phi);
    n3 = -cos(theta);
  }
  break;
  case 3:
  {
    s1 = random->Uniform(-limit,limit);
    s2 = limit;
    s3 = random->Uniform(-limit,limit);

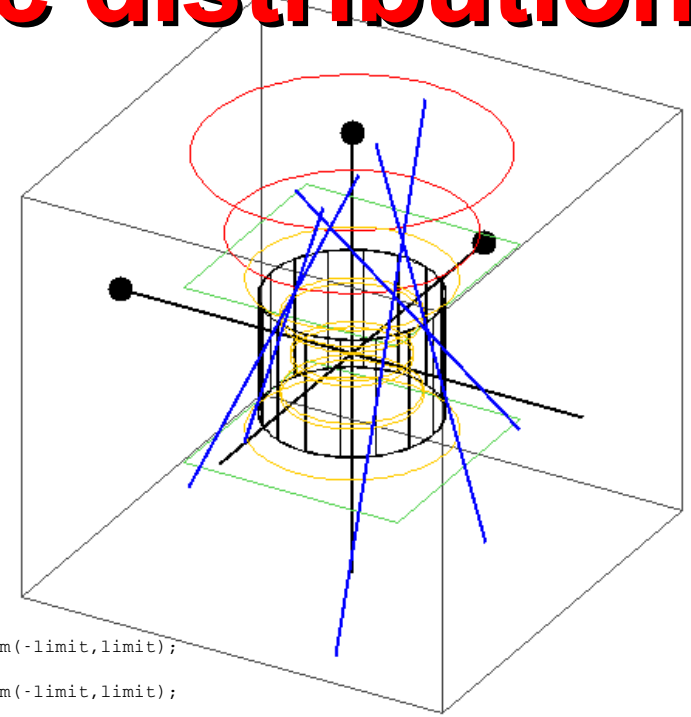
    n1 = sin(theta)*cos(phi);
    n2 = -cos(theta);
    n3 = sin(theta)*sin(phi);
  }
  break;
```

```
  case 4:
  {
    s1 = random->Uniform(-limit,limit);
    s2 = -limit;
    s3 = random->Uniform(-limit,limit);

    n1 = -sin(theta)*cos(phi);
    n2 = cos(theta);
    n3 = sin(theta)*sin(phi);
  }
  break;
  case 5:
  {
    s1 = limit;
    s2 = random->Uniform(-limit,limit);
    s3 = random->Uniform(-limit,limit);

    n1 = cos(theta);
    n2 = sin(theta)*cos(phi);
    n3 = sin(theta)*sin(phi);
  }
  break;
  case 6:
  {
    s1 = -limit;
    s2 = random->Uniform(-limit,limit);
    s3 = random->Uniform(-limit,limit);

    n1 = -cos(theta);
    n2 = -sin(theta)*cos(phi);
    n3 = sin(theta)*sin(phi);
  }
  break;
}
```



3D straight line fit

- Charged particle crosses several detectors as a straight line
- Imagine ~box-shaped detectors for charged particles arbitrarily rotated in x-y direction:

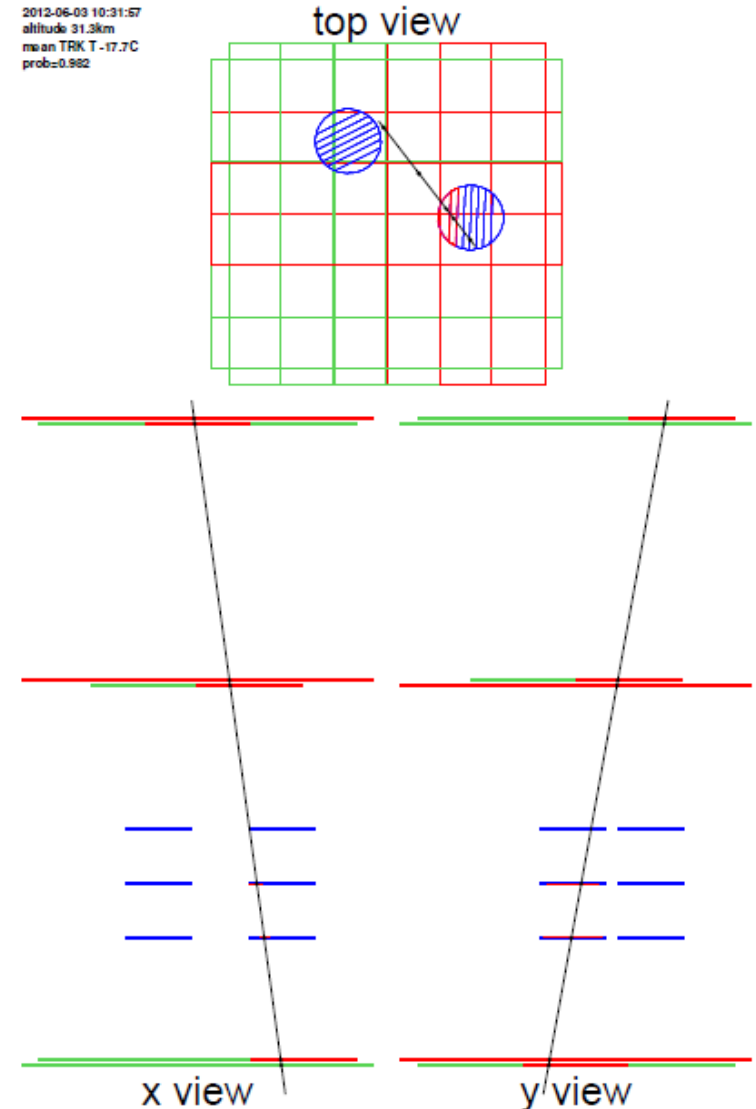
$$\vec{x} = \mathcal{R} \cdot \vec{u} \quad \text{with} \quad \mathcal{R} = \begin{pmatrix} \cos \alpha_{0,1} & -\sin \alpha_{0,1} & 0 \\ \sin \alpha_{0,1} & \cos \alpha_{0,1} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

- Covariance matrix of errors also has to be transformed
→ diagonal matrix is not any longer diagonal

$$\mathcal{U} = \mathcal{A} \cdot \mathcal{V} \cdot \mathcal{A}^T \quad \text{with} \quad \mathcal{V} = \begin{pmatrix} \sigma_u^2 & 0 & 0 \\ 0 & \sigma_v^2 & 0 \\ 0 & 0 & \sigma_w^2 \end{pmatrix} \quad \text{and} \quad \mathcal{A} = \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{pmatrix}$$

- Try to minimize the distance of the measured hits to the straight line fit, respecting the errors

$$\chi^2 = \sum_i \chi_i^2 = \sum_i \vec{\Delta}_i^T \mathcal{U}^{-1} \vec{\Delta}_i$$



Chi2 minimization with Minuit

Global definition of Minuit parameters

```
vector<vector<double> > MinuitHit, MinuitError;  
vector<double> MinuitAngle;
```

Chi2 calculation

```
double CalcChi2(double mx, double ax, double my, double ay)  
{  
    double chi2 = 0;  
    for(unsigned int i = 0; i < MinuitHit.size(); i++)  
    {  
        double x = MinuitHit.at(i).at(0); double y = MinuitHit.at(i).at(1);  
        double z = MinuitHit.at(i).at(2);  
        double alpha = MinuitAngle.at(i);  
        double sigmau = MinuitError.at(i).at(0); double sigmav =  
        MinuitError.at(i).at(1); double sigmaw = MinuitError.at(i).at(2);  
  
        double deltaxm = (mx*z+ax)-x; double deltaym = (my*z+ay)-y; double  
        deltazm = 0;  
  
        Chi2 += ...  $\chi^2 = \sum_i \chi_i^2 = \sum_i \vec{\Delta}_i^T \mathcal{U}^{-1} \vec{\Delta}_i$   
    }  
    return chi2;  
}
```

Chi2 minimization with Minuit

Fitting

```
MinuitHit = HitPos;  
MinuitError = HitError; ← errors in detector coordinates  
MinuitAngle = HitAngle;  
  
TMinuit Minuit(4); ← initialize 4 track parameters  
Minuit.SetFCN(TrackFitChi2); ← tell Minuit what to minimize
```

Fit and printout style

```
double Argument[10]; int Flag = 0;  
Argument[0] = -1;  
Minuit.mnexcm("SET Print",Argument,1,Flag);  
Argument[0] = 0;  
Minuit.mnexcm("SET NOWarnings",Argument,1,Flag);  
Argument[0] = 1;  
Minuit.mnexcm("SET ERR", Argument,1,Flag);
```

Set starting values and step sizes for parameters

```
double mx = 1000; double ax = 0;  
double my = 1000; double ay = 0;  
Minuit.mnparm(0, "mx", mx, 0.01, 0,0,Flag);  
Minuit.mnparm(1, "ax", ax, 0.01, 0,0,Flag);  
Minuit.mnparm(2, "my", my, 0.01, 0,0,Flag);  
Minuit.mnparm(3, "ay", ay, 0.01, 0,0,Flag);
```

```
Minuit.SetMaxIterations(500);  
Minuit.Migrad(); ← actual Minuit fit
```

Access fit parameters

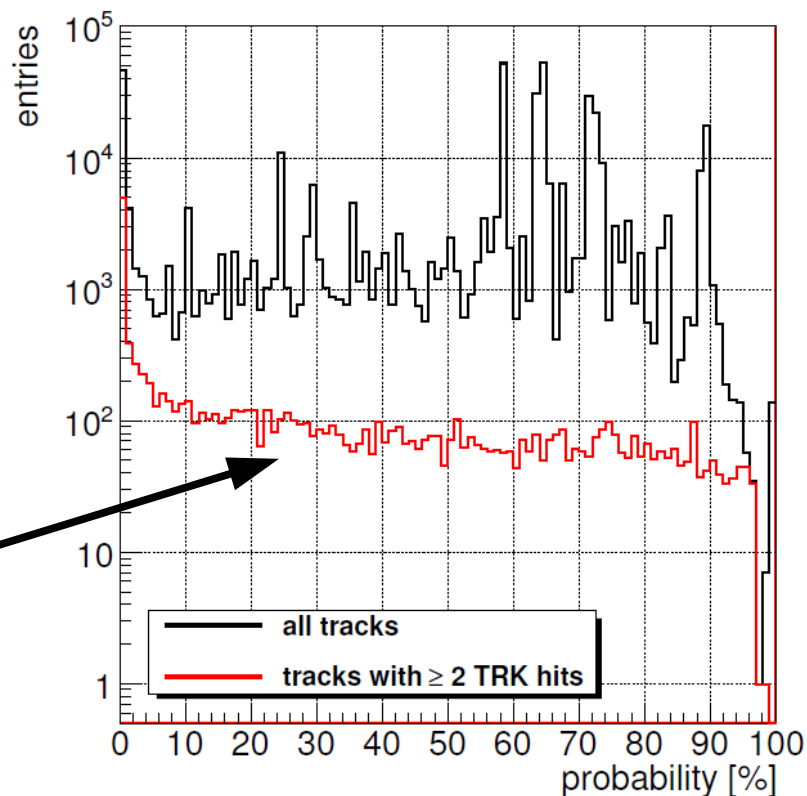
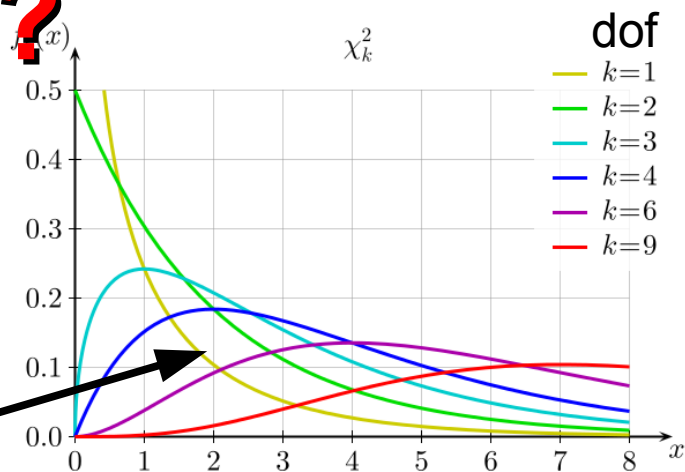
```
double emx, eax, emy, eay;  
Minuit.GetParameter(0, mx, emx);  
Minuit.GetParameter(1, ax, eax);  
Minuit.GetParameter(2, my, emy);  
Minuit.GetParameter(3, ay, eay);
```

How good is your fit?

- Check chi2 → many people claim that chi2 per degree of freedom has to be 1 for a good fit
 - Its just rule of thumb
 - Chi2 follow a known statistical distribution, different for each number of degrees of freedom
 - What to do when you have a varying number of fit values?
- Use the cumulative chi2 distribution as a function of chi2 and dof → should be uniform.

$$p = \int_{\chi^2}^{\infty} f(t, n) dt$$

TMath::Prob(chi2, dof)



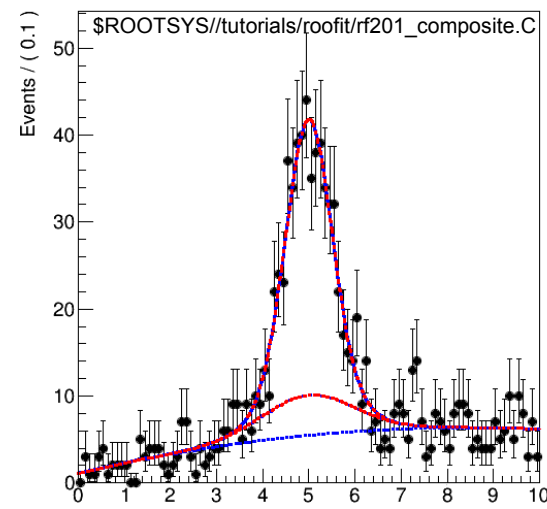
ROOTFIT

./configure --enable-roofit

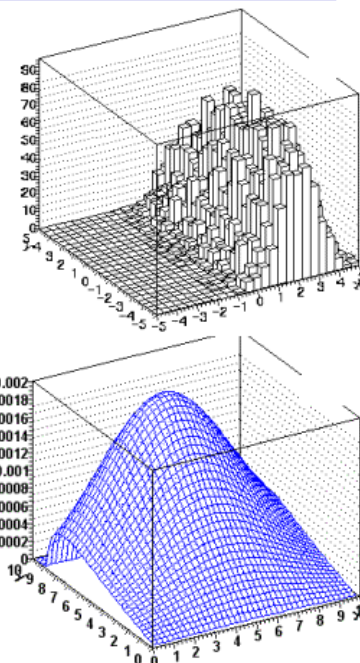
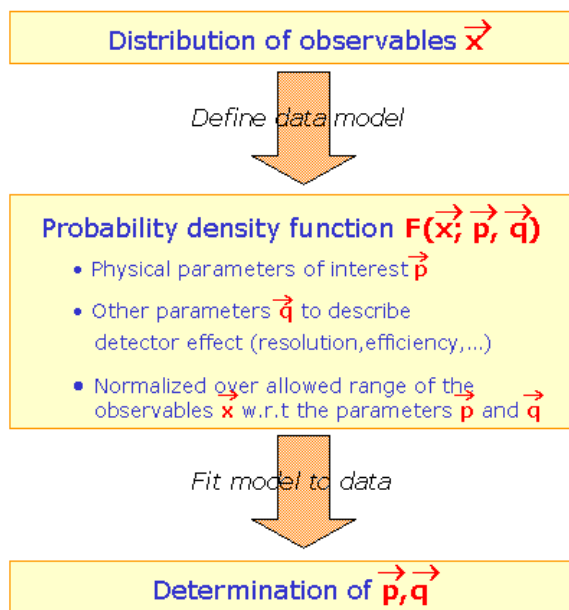
- The RooFit library provides a toolkit for modeling the expected distribution of events in a physics analysis
- core functionality of RooFit is to enable the modeling of 'event data' distributions, where each event is a discrete occurrence in time, and has one or more measured observables associated with it. Experiments of this nature result in datasets obeying Poisson (or binomial) statistics.

- Standard ROOT function framework clearly insufficient to handle such complicated functions
- Normalization of p.d.f. not always trivial to calculate
→ numeric integration techniques
- Simultaneous fit to control samples to account for detector performance

Example of composite pdf=(sig1+sig2)+bkg



RooFit purpose - Data Modeling & Analysis



<http://roofit.sourceforge.net/quicktour/first.html>

Read ASCII file

- read ascii file with two columns

```
#include<fstream>
#include<iostream>
#include<TH2D.h>

void ascii(char *filename)
{
    ifstream in(filename);

    if(!in.good()) cout<<" "<<filename<<" does not
    exist!"<<endl;
    else
    {
        TH2D * h_frac = new TH2D("frac", "", 30,-50,50, 50,0,3);

        double x, y;
        while(1)
        {
            in>>x>>y;

            if(in.eof()) break;
            else
            {
                cout<<x<<" "<<y<<endl;
                h_frac->Fill(x,y);
            }
        }
    }
    in.close();
}
```


Writing to file

```
> root -l
```

```
root [0] TFile * f = new  
TFile("test12.root","recreate")
```

```
root [1] TH1D * h = new TH1D("histo", "",  
100,0,1);
```

```
root [2] TF1 * f1 = new TF1("f1","Gaus(x,  
[0],[1])",-1000,1000);
```

```
root [3] f1->SetParameters(0.5,0.1);
```

```
root [4] h->FillRandom("f1", 5000);
```

```
root [5] h->Write()
```

```
root [10] f->Close();
```

After opening a root file every object inherited from TObject can be written to the file with a simple write statement.

Open saved TCanvas/TBrowser

- save TCanvas with TH1D

```
TCanvas * c = new TCanvas("c_ref",  
"c_title", 200,10,600,600);
```

```
TH1D * h = new TH1D("histo", "",  
100,0,1);
```

```
TF1 * f1 = new TF1("f1","Gaus(x,  
[0],[1])",-1000,1000);  
f1->SetParameters(0.5,0.1);
```

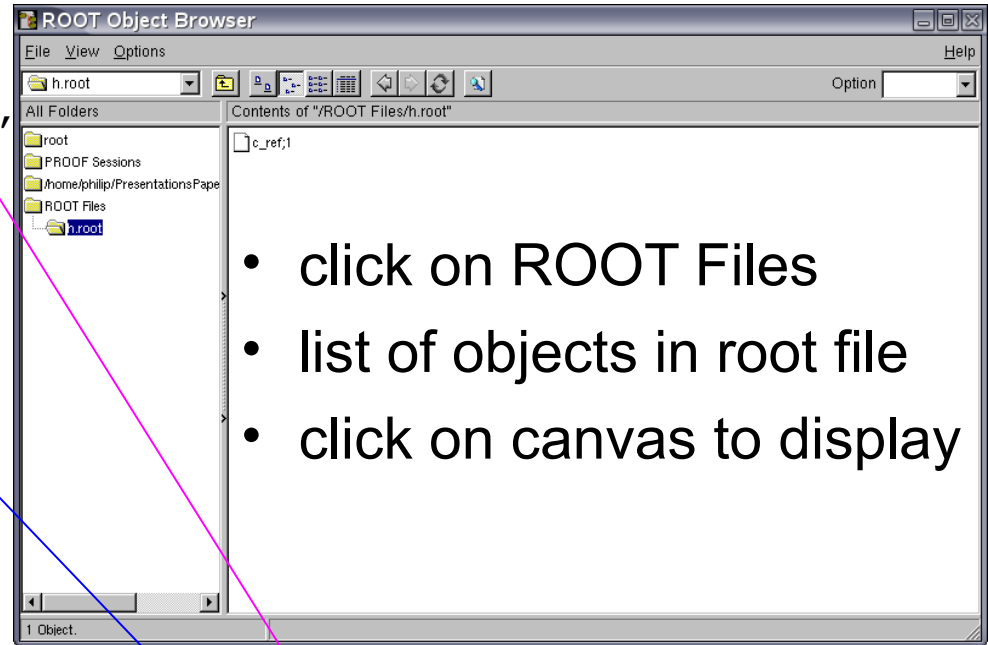
```
h->FillRandom("f1", 5000);
```

```
h->Draw();
```

```
c->SaveAs("h.eps");  
c->SaveAs("h.root");
```

- open the root file interactively

```
>root -l h.root  
[0]  
Attaching file h.root as _file0...  
[1]new TBrowser
```



- click on ROOT Files
- list of objects in root file
- click on canvas to display

- open root file from script

```
TFile * file = new TFile("h.root");
```

```
TCanvas * c1 = (TCanvas*)file  
->Get("c_ref");
```

```
TH1D * h1 = (TH1D*)c1  
->GetListOfPrimitives()  
->FindObject("histo");
```

```
file->Close();
```

Save and load TTree

```
void save_tree()
{
  TFile * f = new TFile("tree.root", "RECREATE");

  TTree * t = new TTree("data","");

  double x, y;
  int event;

  t->Branch("x", &x, "x/D");
  t->Branch("y", &y, "y/D");
  t->Branch("event", &event, "event/I");

  TRandom3 * ran = new TRandom3();
  ran->SetSeed(0);

  for(int i = 0; i < 1000; i++)
  {
    x = ran->Gaus(0.5,3);
    y = ran->Exp(1);
    event = i;

    t->Fill();
  }

  f->Write();
  f->Close();
}
```

- save variables and all kind of inherited TObjects in root files

```
void open_tree()
{
  TFile * f = new TFile("tree.root");

  TTree * t = (TTree*)f->Get("data");

  double x, y;
  int event;

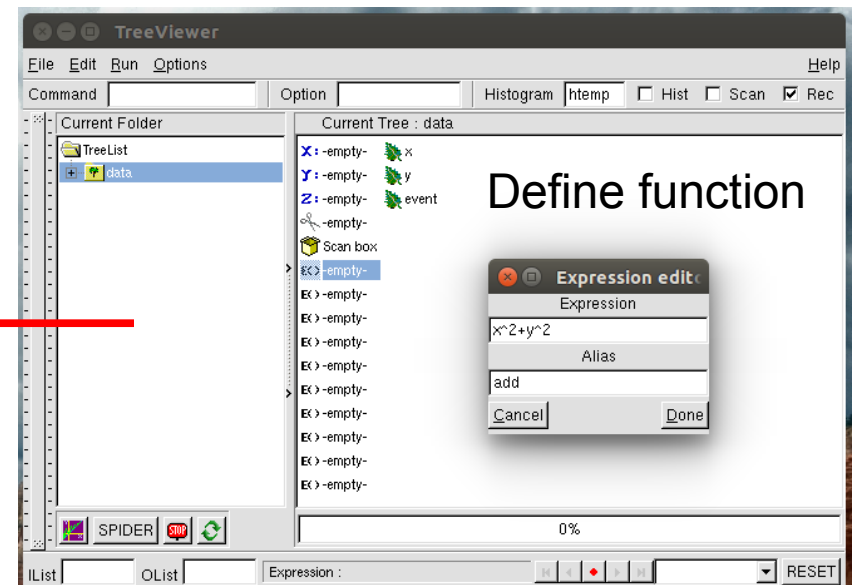
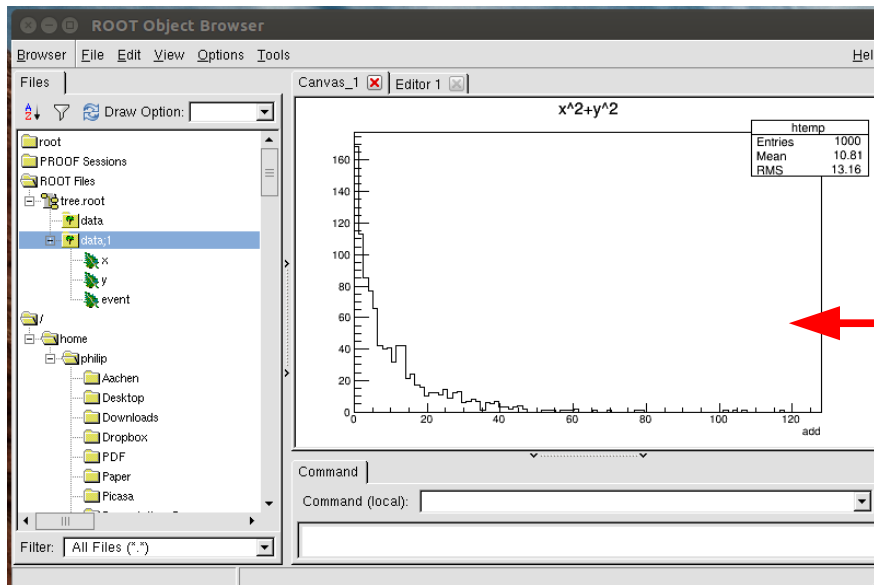
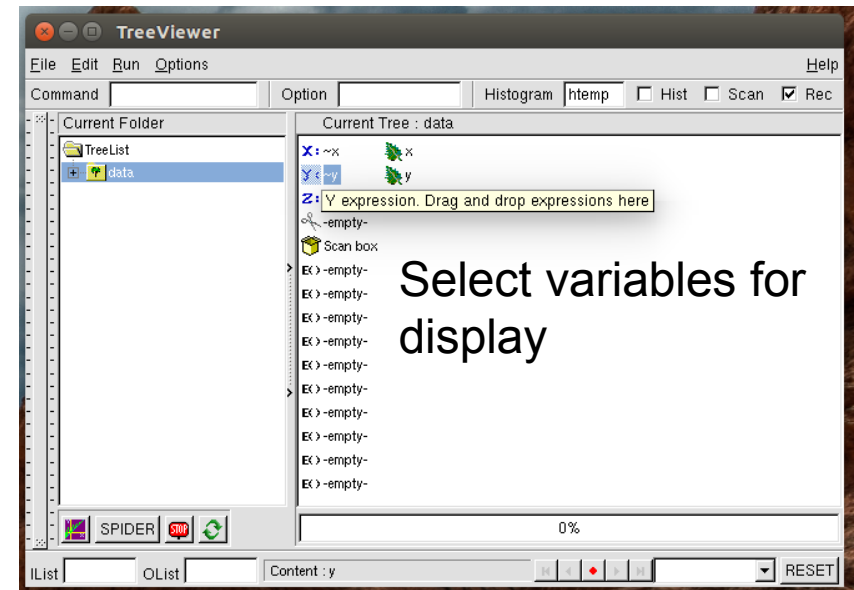
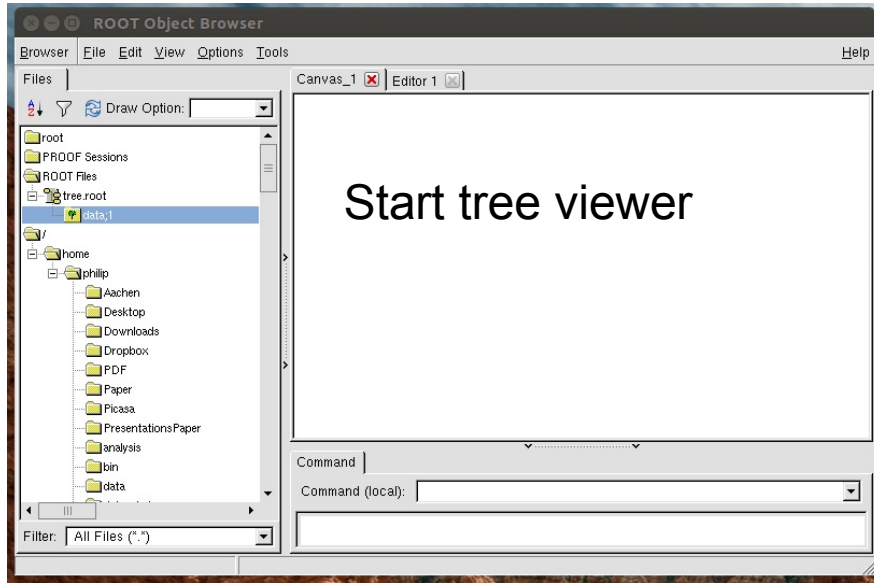
  t->SetBranchAddress("x", &x);
  t->SetBranchAddress("y", &y);
  t->SetBranchAddress("event", &event);

  for(Long64_t i = 0; i < t->GetEntriesFast(); i++)
  {
    t->GetEntry(i);
    cout<<event<<" "<<x<<" "<<y<<endl;
  }

  f->Close();
}

TH1D * h = new TH1D("h","",100,0,1);
h->Write("h");
```

Interactive tree viewer



TChain

```
TChain * TreeEvent = new TChain("Event");
```

```
int PrimaryParticlePdg = 0;  
double PrimaryParticleEnergy = 0;  
vector<int> * VertexTrackID = new vector<int>;
```

```
TreeEvent->SetBranchAddresses("PrimaryParticlePdg",  
&PrimaryParticlePdg);
```

```
TreeEvent->  
>SetBranchAddresses("PrimaryParticleEnergy",  
&PrimaryParticleEnergy);
```

```
TreeEvent->SetBranchAddresses("VertexTrackID",  
&VertexTrackID);
```

```
TreeEvent->Add("path-to-file/filename*123.root");
```

Chains ROOT files of same type together. You can use wildcards with *.

Standalone programs

- C++ program:

```
#include<TApplication.h>
#include<TCanvas.h>
#include<TH1D.h>
#include<TF1.h>
#include<TStyle.h>
#include<TROOT.h>
#include<stdlib.h>
```

```
int main(int argc, char * argv[])
{
    int n = atoi(argv[1]);
```

```
TApplication a("a", &argc, argv);
```

```
gROOT->Reset();
```

```
TStyle * plain = new TStyle("plain","plain");
plain->SetCanvasBorderMode(0);
plain->SetPadBorderMode(0);
plain->SetPadColor(0);
plain->SetCanvasColor(0);
plain->SetTitleColor(1);
plain->SetStatColor(0);
plain->SetTitleFillColor(0);
```

```
gROOT->SetStyle("plain");
```

```
TCanvas * c = new Tcanvas("c_ref","c_title",
    200,10,600,600);
```

```
TH1D * h = new TH1D("histo", "", 100,0,1);
```

```
TF1 * f1 = new TF1("f1","Gaus(x,[0],[1])",-1000,1000);
f1->SetParameters(0.5,0.1);
```

```
h->FillRandom("f1", n);
```

```
h->Draw();
```

```
a.Run();
```

```
return 0;
}
```

- Makefile:

```
ROOTLIBS      = $(shell root-config --libs)
```

```
all:           standalone
```

```
standalone: standalone.o
              g++ -o standalone standalone.o $(ROOTLIBS)
```

```
.cpp.o:        $<.cpp
              g++ -I${ROOTSYS}/include -c $<
```

```
clean:
              @rm -f *.o
```

```
>make
>standalone 10000
```

Create new class

- header file: class.hpp

```
#ifndef ROOTCLASS
#define ROOTCLASS

#include "TObject.h"

class root_class : public TObject
{
public:

    root_class();
    ~root_class();

    double get_var1();
    int get_var2();

    void set_var1(double var1);
    void set_var2(int var2);

private:

    double its_var1;
    int its_var2;

    ClassDef(root_class,1)
};

#endif
```

- function definitions: class.cpp

```
#include "class.hpp"

root_class::root_class()
{
    its_var1 = 5.3;
    its_var2 = 3;
}

root_class::~~root_class(){};

double root_class::get_var1(){return its_var1;}

int root_class::get_var2(){return its_var2;}

void root_class::set_var1(double var1){its_var1 = var1;}

void root_class::set_var2(int var2){its_var2 = var2;}
```

- link new class to root: linkdef.hpp

```
#ifdef __CINT__

#pragma link C++ class root_class+;

#endif
```

Save and read new class

- Makefile

```
ROOTLIBS      = $(shell root-config --libs)

all:          class

class: main_class.o class.o dict.o
      g++ -o class main_class.o class.o dict.o $
(ROOTLIBS)

dict.cpp: class.hpp class.cpp
      rootcint -f dict.cpp -c class.hpp linkdef.hpp

.cpp.o: $<.cpp
      g++ -I${ROOTSYS}/include -c $<

clean:
      @rm -f *.o dict.h dict.cpp
```

- excerpt of main file:
main_class.cpp

```
root_class * c1 = new root_class();

TFile * f1 = new TFile("root_class.root", "RECREATE");
TTree * t1 = new TTree("class1", "");
t1->Branch("c1", &c1);

for(int i = 0; i < 1000; i++)
{
    c1->set_var1(sqrt(double(i)));
    c1->set_var2(i-3);
    t1->Fill();
}

f1->Write();
f1->Close();

root_class * c2 = new root_class();
TChain * t2 = new TChain("class1");
t2->SetBranchAddresses("c1", &c2);
t2->Add("root_class.root");

for(Long64_t i = 0; i < t2->GetEntriesFast(); i++)
{
    t2->GetEntry(i);
    cout<<c2->get_var1()<<" "<<c2->get_var2()<<endl;
}
```


TThread

```
vector<TThread*> t_beta_ecal_rigidity_deuteron; ← create vector of thread pointers
```

```
vector<TH2D*> h_beta_ecal_rigidity_deuteron;
for(int i = 0; i < 4; i++)
{
    char text[400];
    sprintf(text, "beta_ecal_rigidity_deuteron_%d", i);
    h_beta_ecal_rigidity_deuteron.push_back(new TH2D(text, "",
    20,0.6,1,1000,0,1));

    sprintf(text, "thread_beta_ecal_rigidity_deuteron_%d", i);
    t_beta_ecal_rigidity_deuteron.push_back(new TThread(text,
    fill_beta_ecal_rigidity_deuteron, (void*)
    h_beta_ecal_rigidity_deuteron.at(i))); ← create threads, each thread
                                           fills a histogram
    t_beta_ecal_rigidity_deuteron.at(i) ->Run(); ← run threads
}

for(unsigned int i = 0; i < t_beta_ecal_rigidity_deuteron.size(); i++)
t_beta_ecal_rigidity_deuteron.at(i) ->Join(); ← wait until all threads are done

for(unsigned int i = 0; i < h_beta_ecal_rigidity_deuteron.size(); i++)
h_beta_ecal_rigidity_deuteron_total-
>Add(h_beta_ecal_rigidity_deuteron.at(i)); ← merge histograms
```

TThread

Terminal

Terminal

top - 19:27:20 up 2 days, 55 min, 6 users, load average: 5.36, 2.64, 1.41
Tasks: 256 total, 2 running, 254 sleeping, 0 stopped, 0 zombie
%Cpu(s): 98.6 us, 1.0 sy, 0.2 ni, 0.0 id, 0.0 wa, 0.0 hi, 0.2 si, 0.0 st
KiB Mem: 3714044 total, 3509624 used, 204420 free, 107544 buffers
KiB Swap: 3854332 total, 157564 used, 3696768 free. 2032932 cached Mem

PID	USER	PR	NI	VIRT	RES	SHR	S	%CPU	%MEM	TIME+	COMMAND
21359	work	20	0	532288	33328	17732	S	390.7	0.9	0:27.00	root.exe
3283	philip	20	0	722500	14836	9572	S	5.0	0.4	10:34.07	indicator-+
19466	philip	20	0	1604564	69288	31308	S	1.7	1.9	1:39.00	compiz
3267	philip	20	0	446732	9916	7452	S	1.0	0.3	0:29.23	indicator-+
1306	root	20	0	448932	93968	70584	S	0.7	2.5	15:03.83	Xorg
2463	root	35	15	29728	15752	948	S	0.7	0.4	0:43.06	preload
17196	philip	20	0	1236816	294832	25644	S	0.7	7.9	1:19.17	firefox
3138	philip	20	0	20232	784	760	S	0.3	0.0	0:13.59	syndaemon
3214	philip	20	0	360480	3876	3360	S	0.3	0.1	1:54.86	indicator-+
3895	philip	20	0	759032	11720	7776	S	0.3	0.3	1:11.86	psensor
12695	root	20	0	0	0	0	S	0.3	0.0	0:08.02	kworker/0:1
21357	work	20	0	24956	1736	1152	R	0.3	0.0	0:00.13	top
1	root	20	0	34100	2940	1300	S	0.0	0.1	0:02.80	init
2	root	20	0	0	0	0	S	0.0	0.0	0:00.01	kthreadd
3	root	20	0	0	0	0	S	0.0	0.0	0:00.57	ksoftirqd/0
5	root	0	-20	0	0	0	S	0.0	0.0	0:00.00	kworker/0:+
7	root	20	0	0	0	0	R	0.0	0.0	0:49.84	rcu_sched

c_beta_ecal_rigid

KiB Swap: 3854332 total, 157664 used, 3696668 free. 2032592 cached Mem

or of thread

, "",

i);
ext,

, each thread

ge: 3.99, 2.63, 1.45
d, 0 zombie
0.0 hi, 0.0 si, 0.0 st
108264 buffers
2032592 cached Mem

```
for(unsigned int i  
h_beta_ecal_rigid  
>Add(h_beta_ecal_r
```

PID	USER	PR	NI	VIRT	RES	SHR	S	%CPU	%MEM	TIME+	COMMAND
21414	work	20	0	309520	31620	17668	S	99.9	0.9	0:07.07	root.exe
3283	philip	20	0	722500	14836	9572	S	2.7	0.4	10:33.00	indicator-+
19466	philip	20	0	1604632	69292	31312	S	1.3	1.9	1:40.67	compiz
17196	philip	20	0	1236816	295080	25644	S	0.7	7.9	1:19.40	firefox
9	root	20	0	0	0	0	S	0.3	0.0	0:09.76	rcuos/1
1306	root	20	0	455404	98176	74620	S	0.3	2.6	15:04.89	Xorg

PROOF

The Parallel ROOT Facility, PROOF, is an extension of ROOT enabling interactive analysis of large sets of ROOT files in parallel on clusters of computers or many-core machines.

- PROOF stands for Parallel ROOT Facility
- It allows parallel processing of large amount of data. The output results can be directly visualised (e.g. the output histogram can be drawn at the end of the proof session).
- PROOF is NOT a batch system.
- The data which you process with PROOF can reside on your computer, PROOF cluster disks or grid.
- The usage of PROOF is transparent: you should not rewrite your code you are running locally on your computer.
- No special installation of PROOF software is necessary to execute your code: PROOF is included in ROOT distribution.

pyROOT

Add to .tcshrc (change accordingly for bash)

```
setenv PYTHONDIR /usr/include/python2.7
```

(← check which Python was used at compilation time)

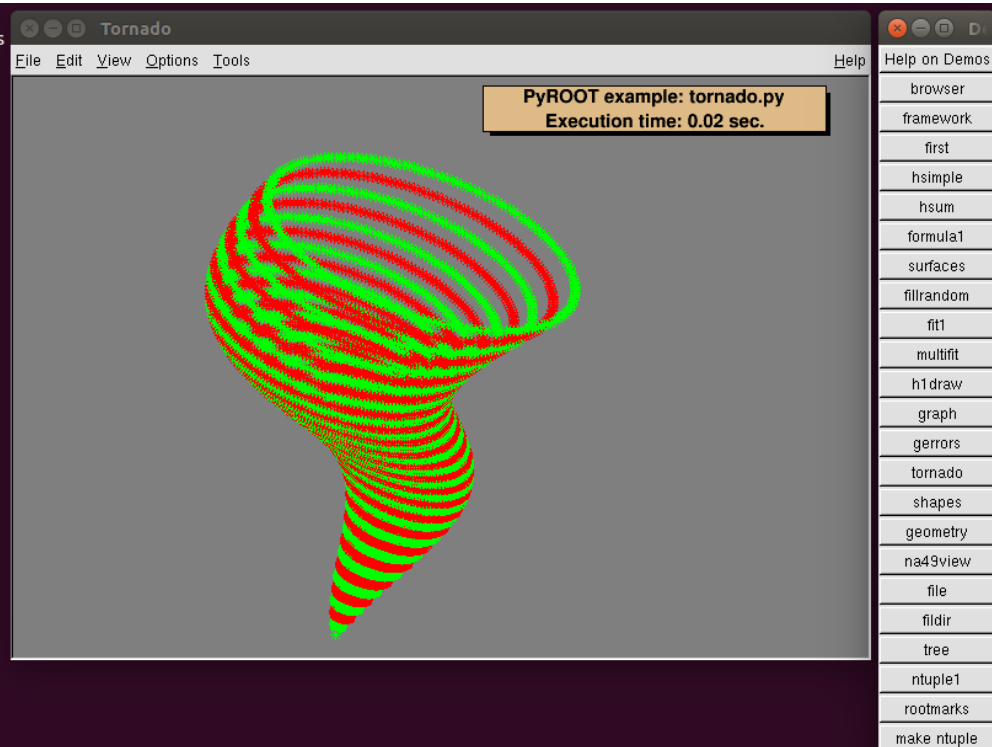
```
setenv LD_LIBRARY_PATH $ROOTSYS/lib:$PYTHONDIR/lib:$LD_LIBRARY_PATH
```

```
setenv PYTHONPATH $ROOTSYS/lib
```

Example:

```
>python $ROOTSYS/tutorials/pyroot/demo.py
```

```
[root]> python $ROOTSYS/tutorials/pyroot/demo.py
enter "q" to quit: fillrandom: Real Time = 0.22 seconds Cpu Time = 0.06 seconds
i 0 0.000000 1.986693
i 1 0.100000 2.955202
i 2 0.200000 3.894183
i 3 0.300000 4.794255
i 4 0.400000 5.646425
i 5 0.500000 6.442177
i 6 0.600000 7.173561
i 7 0.700000 7.833269
i 8 0.800000 8.414710
i 9 0.900000 8.912074
i 10 1.000000 9.320391
i 11 1.100000 9.635582
i 12 1.200000 9.854497
i 13 1.300000 9.974950
i 14 1.400000 9.995736
i 15 1.500000 9.916648
i 16 1.600000 9.738476
i 17 1.700000 9.463001
i 18 1.800000 9.092974
i 19 1.900000 8.632094
Error in <TFile::TFile>: file hsimple.root does not exist
Traceback (most recent call last):
  File "<string>", line 1, in <module>
  File "ntuple1.py", line 41, in <module>
    ntuple.SetLineColor(1)
AttributeError: 'TObject' object has no attribute 'SetLineColor'
TCanvas::Constructor:0: RuntimeWarning: Deleting canvas with same name: c1
tornado : Real Time = 0.03 seconds Cpu Time = 0.02 seconds
```



PyROOT

```
from ROOT import gROOT, TCanvas, TF1
```

```
gROOT.Reset()
```

```
c1 = TCanvas( 'c1', 'Example with  
Formula', 200, 10, 700, 500 )
```

```
#  
# Create a one dimensional function and  
draw it
```

```
#  
fun1 = TF1( 'fun1', 'abs(sin(x)/x)', 0,  
10 )
```

```
c1.SetGridx()
```

```
c1.SetGridy()
```

```
fun1.Draw()
```

```
c1.Update()
```

```
## wait for input to keep the GUI (which  
lives on a ROOT event dispatcher) alive
```

```
if __name__ == '__main__':
```

```
    rep = ''
```

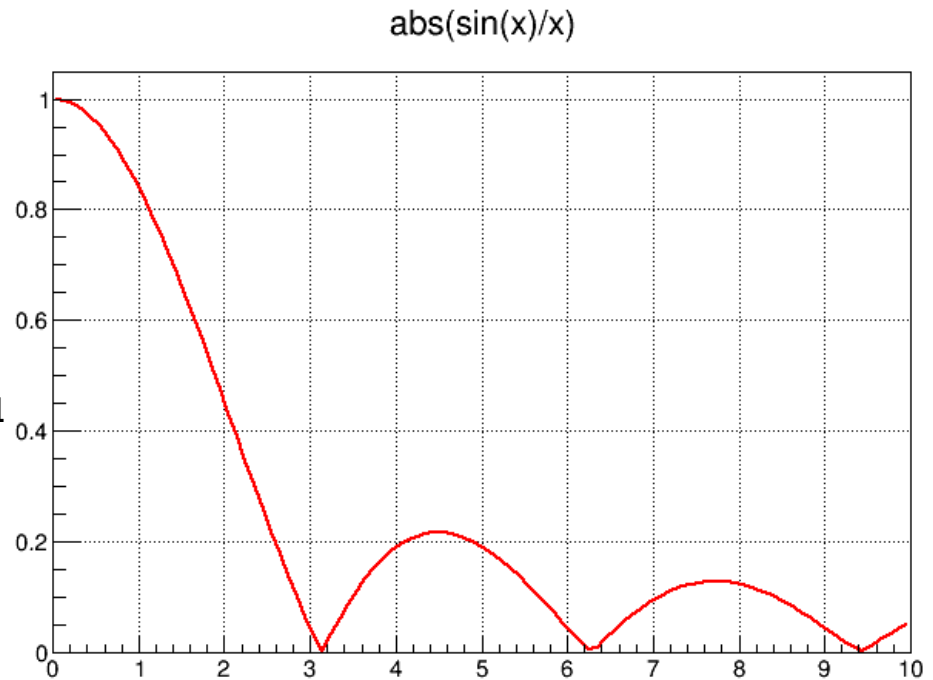
```
    while not rep in [ 'q', 'Q' ]:
```

```
        rep = raw_input( 'enter "q" to
```

```
quit: ' )
```

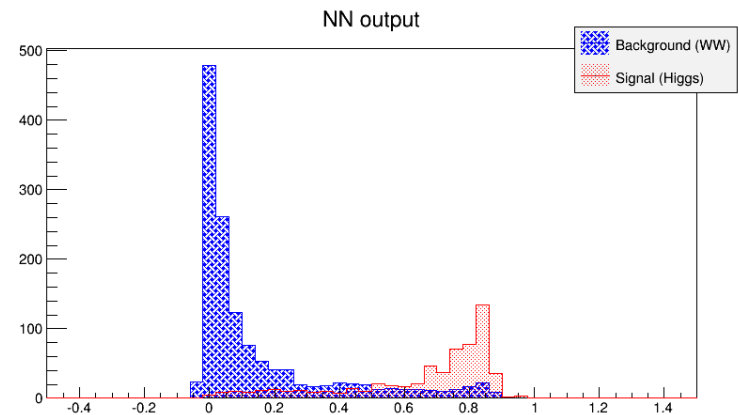
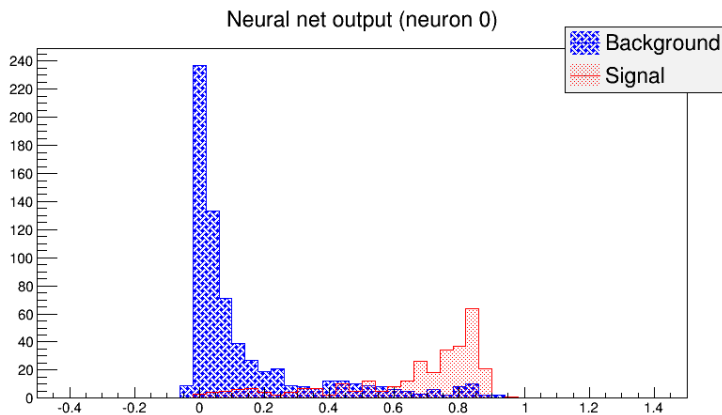
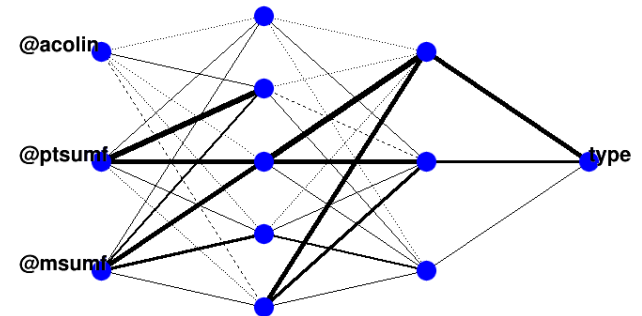
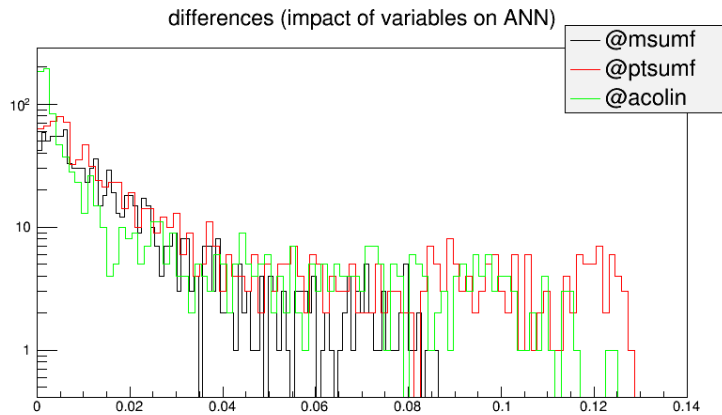
```
        if 1 < len(rep):
```

```
            rep = rep[0]
```



Neural network

\$ROOTSYS/tutorials/mlp/mlpHiggs.C

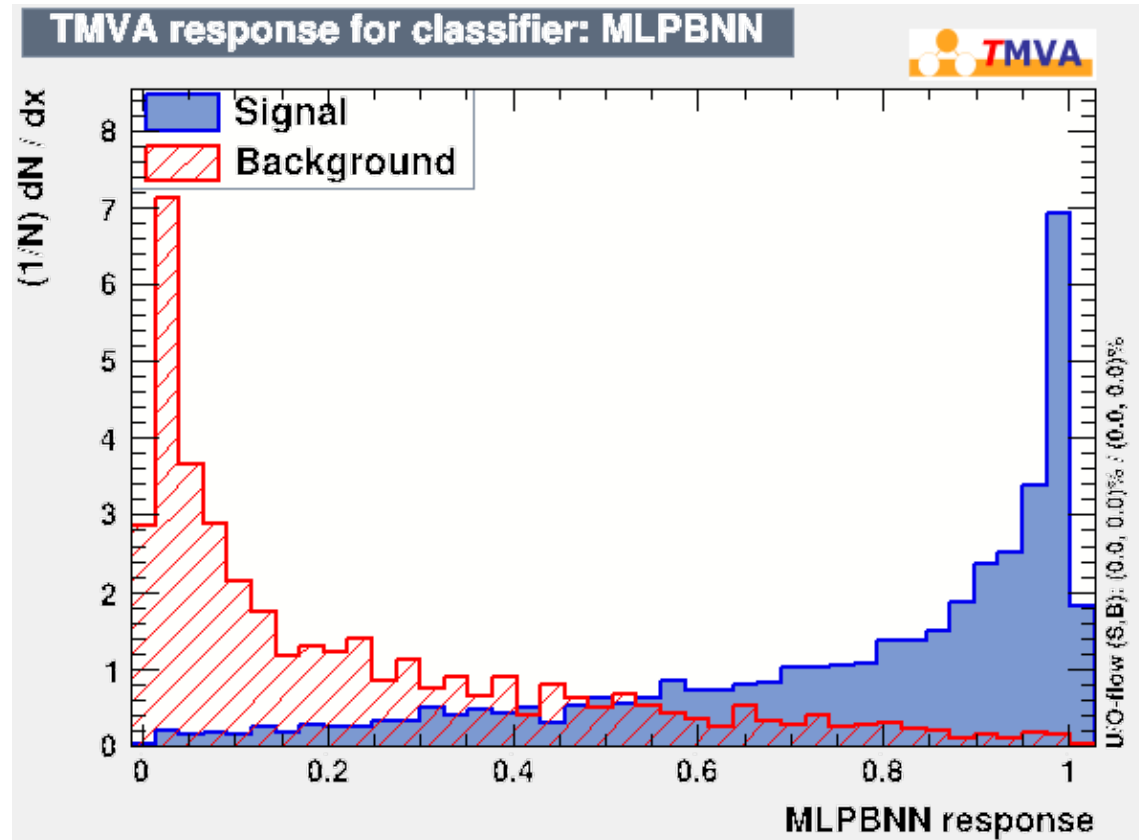


TMVA

TMVA is a ROOT-integrated toolkit for multivariate classification and regression analysis. TMVA performs the training, testing and performance evaluation of a large variety of multivariate methods.

supervised machine learning

1. Training phase:
train(build), test and evaluate
classifiers using data samples
with known signal and
background events
2. Application phase: use to
classify unknown data samples



Go to: `$ROOTSYS/bin/root/tmva/test`

```
run root -l TMVAClassification.C
```

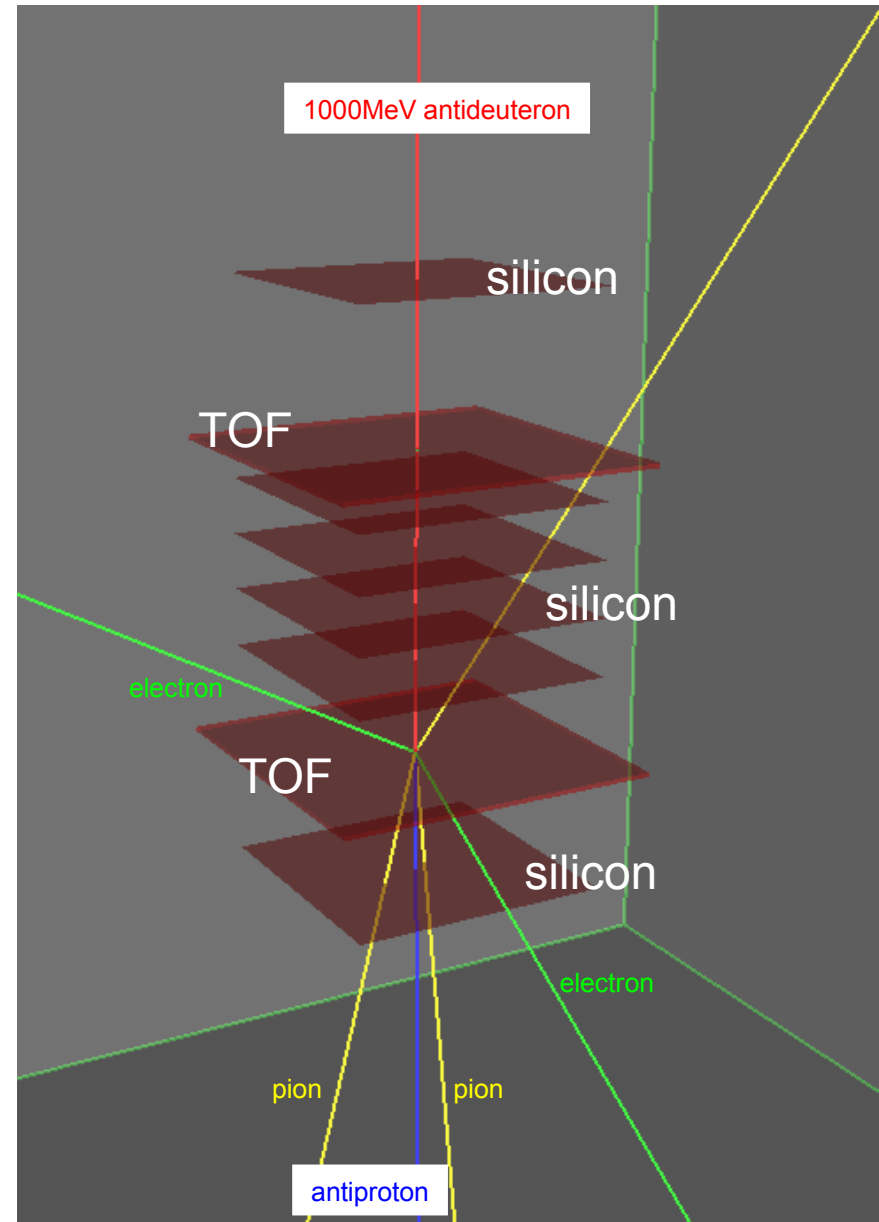
Integration to Geant4

Simulation of particle interactions with matter:

- Geant4 is also based on C++
- save simulation results as ROOT files
- Add FindROOT.cmake to build directory
- Add to CmakeLists.txt

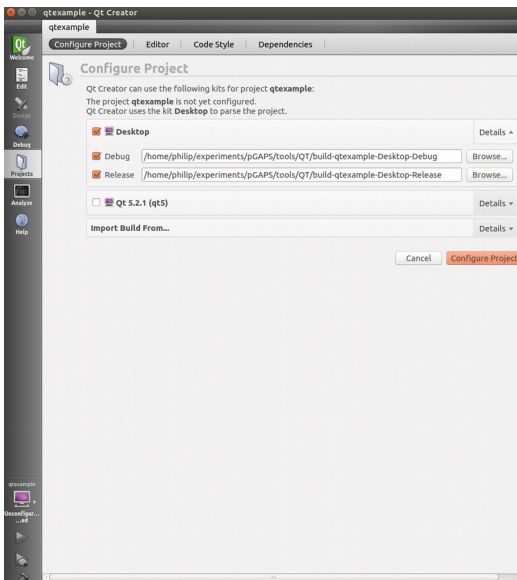
```
# Find ROOT
find_package(ROOT)

# Add ROOT's header paths
include_directories($
{ROOT_INCLUDE_DIR})
```



QT

```
>rm -r Builds/  
makefile  
qtexample.pro.user  
>qmake-qt4  
>qmake  
>qtcreator  
qtexample.pro &  
→ configure project
```



```
#include "MainWindow.h"
```

```
#include "TROOT.h"  
#include "TCanvas.h"  
#include "TH1.h"
```

```
MainWindow::MainWindow(QWidget* parent)  
: QDialog(parent)  
{
```

```
    setupUi(this);
```

```
    h = new TH1I("h", "", 100, -10, 10);
```

```
    gROOT->Reset();
```

```
    m_canvas = gPad->GetCanvas();
```

```
    connect(testButton, SIGNAL(clicked()), this,  
            SLOT(testButtonClicked()));  
}
```

```
MainWindow::~~MainWindow()  
{  
}
```

```
void MainWindow::testButtonClicked()  
{  
    h->FillRandom("gaus", 10000);  
    widget->cd();  
    h->Draw();  
    m_canvas->Modified();  
    m_canvas->Update();  
}
```

QT - .pro file

```
CONFIG           += qt debug
```

```
TEMPLATE         = app
```

```
INCLUDEPATH      += $(ROOTSYS)/include
```

```
LIBS             += $$system(root-config --cflags --libs) -lGQt
```

```
SOURCES          += main.cpp
```

```
HEADERS          += MainWidget.h
```

```
SOURCES          += MainWidget.cpp
```

```
FORMS            += MainForm.ui
```

```
# seperate source & build dirs
```

```
DESTDIR = ./Builds
```

```
OBJECTS_DIR = ./Builds/Temp
```

```
MOC_DIR = ./Builds/Temp
```

```
UI_DIR = ./Builds/Temp
```

```
RCC_DIR = ./Builds/Temp
```

MainForm.ui - qtexample - Qt Creator

Filter

- Layouts
 - Vertical Layout
 - Horizontal Layout
 - Grid Layout
 - Form Layout
- Spacers
 - Horizontal Spacer
 - Vertical Spacer
- Buttons
 - Push Button
 - Tool Button
 - Radio Button
 - Check Box
 - Command Link Button
 - Button Box
- Item Views (Model-Based)
 - List View
 - Tree View
 - Table View
 - Column View
- Item Widgets (Item-Based)
 - List Widget
 - Tree Widget
 - Table Widget
- Containers
 - Group Box
 - Scroll Area
 - Tool Box
 - Tab Widget
 - Stacked Widget
 - Frame
 - Widget
 - MdiArea
 - Dock Widget
- Input Widgets
 - Combo Box
 - Font Combo Box
 - Line Edit
 - Text Edit
 - Plain Text Edit
 - Spin Box

Object Class

- MainForm QWidget
- testButton QPush...ton
- widget QWidget

Filter

Property Value

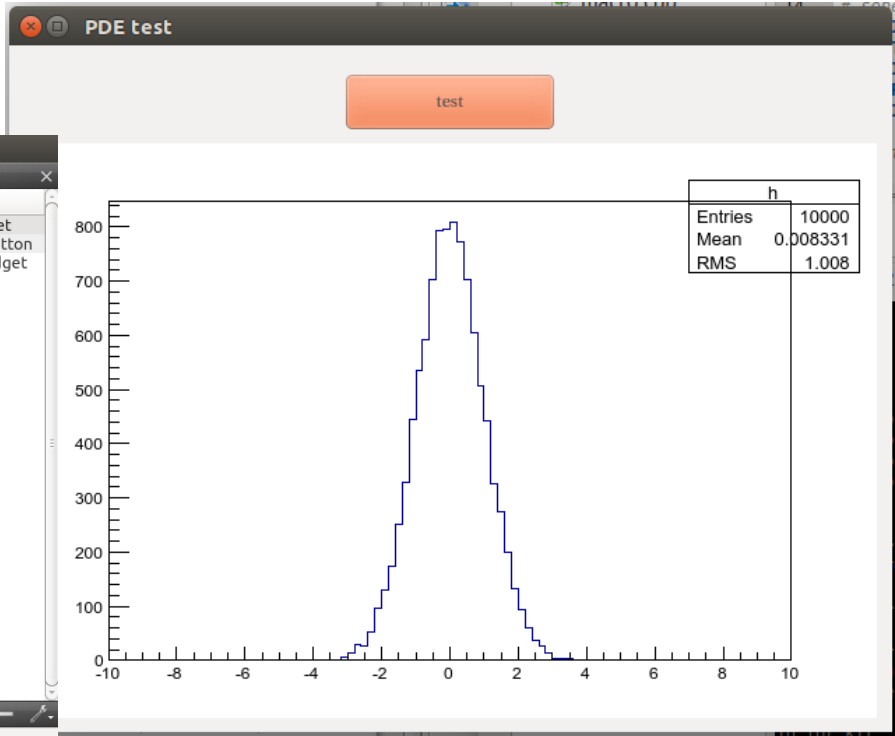
- QObject
 - objectName MainForm
- QWidget
 - windowModality NonModal
 - enabled ☒
 - geometry [(0, 0), 632 ...]
 - sizePolicy [Preferred, ...]
 - minimumSize 0 x 0
 - maximumSize 16777215 x..
 - sizeIncrement 0 x 0
 - baseSize 0 x 0
 - palette Inherited
 - font A [Ubuntu...]
 - cursor Arrow
 - mouseTracking ☐
 - focusPolicy NoFocus
 - contextMenuPo... DefaultCon...
 - acceptDrops ☐
 - windowTitle PDE test
 - windowIcon [Icon]

Name Used Text Shortc

Action Editor Signals & Slots Editor

Type to locate (Ctrl...

1 Issues 2 Search R... 3 Applicati... 4 Compile ... 5 QML/JS ...



QT online software example

