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 * @file
               SourceCompressor.cpp
 * @synopsis
               Klassen-Definition SourceCompressor
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 * @author
 * @date
               2005-04-14
#include "SourceCompressor.h"
#include "Exception.h"
// {{{ Konstruktoren, Destruktor
// ----- //
/// Default-Konstruktor
SourceCompressor::SourceCompressor(void)
    throw FileNotReadableException("Keine Quelldatei angegeben.");
/// Konstruktor: Streams an Ouelldatei binden
SourceCompressor::SourceCompressor (string src) :
   mSrcFilestream(src.c_str(), ios::in),
   mDestFilename(src.substr(0, src.find("."))+" out.c"),
   mDestFilestream (mDestFilename.c str(), ios::out),
   mOutBuffer()
   mSrcFilename = src:
   if (!mSrcFilestream.good())
       throw FileNotReadableException("Kann Ouelldatei nicht zum Lesen oeffnen.");
   if (!mDestFilestream.good())
       throw FileNotWriteableException ("Kann Zieldatei nicht zum Schreiben oeffnen.
");
   buildControlMatrix();
/// Destruktor: Dateistroeme schliessen
SourceCompressor::~SourceCompressor ()
   mSrcFilestream.close();
   mDestFilestream.close();
//-----//
// }}}
// {{{ SourceCompressor::compress ()
/// Durchfuehrung der Kompression
void SourceCompressor::compress (void)
   AutData currentState = STATE_BASE;
   map <char, CharGroup> CharGroupCache;
   char c:
   while (true)
       this->mSrcFilestream.get(c);
       /// Zeichengruppe ermitteln, zunaechst Cache durchsuchen
       CharGroup currentCharGroup;
       map <char, CharGroup>::iterator CharGroupIt;
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currentCharGroup = CGROUP\_EOF; /// EOF passt nicht in char!

if (mSrcFilestream.eof())

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else if ((CharGroupIt = CharGroupCache.find(c)) !=
                  CharGroupCache.end())
            currentCharGroup = CharGroupIt->second; /// Aus Cache
        else
            currentCharGroup = this->findCharGroup(c);
            CharGroupCache[c] = currentCharGroup;
        /// Aktion bestimmen. Falls undefiniert, Standard benutzen
        AutData currentAction =
            (controlMatrix[currentState][currentCharGroup][1] == UNDEF) ?
             controlMatrix[currentState][CGROUP_SONST][1] :
             controlMatrix[currentState][currentCharGroup][1];
        /// Folgezustand ermitteln. Falls undefiniert, Standard benutzen
        AutData nextState =
            (controlMatrix[currentState][currentCharGroup][0] == UNDEF) ?
             controlMatrix[currentState][CGROUP SONST][0]:
             controlMatrix[currentState][currentCharGroup][0];
        nextState = (nextState == UNDEF) ? currentState : nextState;
        currentState = nextState:
        /// Aktion durchfuehren
        this->performAction(int(currentAction), c);
        /// Abbruchbedingung
        if (mSrcFilestream.eof()) break;
   cerr << endl << "==> Ausgabe in Datei " << mDestFilename << " erfolgreich beende
t." << endl;
// }}}
// {{{ SourceCompressor::buildControlMatrix ()
/// Aufbau der Steuermatrix
void SourceCompressor::buildControlMatrix (void)
    /// Aufbau der Steuermatrix:
    /// controlMatrix[Zustand][Zeichen-/Zeichengruppe][0] = <Folgezustand>
    /// controlMatrix[Zustand][Zeichen-/Zeichengruppe][1] = <Aktion>
    /// Anz. Zustaende: 13, Anzahl Zeichengruppen: 12
    controlMatrix.resize(13);
    for (unsigned int state = 0; state < controlMatrix.size(); state++)</pre>
        controlMatrix[state].resize(12);
        for (unsigned int chargroup = 0;
             chargroup < controlMatrix[state].size();</pre>
             chargroup++)
            controlMatrix[state][chargroup].resize(2, UNDEF);
    // {{{ Befuellung der Steuermatrix
    // {{{ Zustand: BASE
    controlMatrix[STATE_BASE][CGROUP_BU][0]
                                                = STATE NAME:
    controlMatrix[STATE_BASE][CGROUP_BU][1]
                                                = ACTION STO:
    controlMatrix[STATE BASE][CGROUP ZI][0]
                                                = STATE ZAHL;
    controlMatrix[STATE_BASE][CGROUP_ZI][1]
                                                = ACTION STO;
    controlMatrix[STATE_BASE][CGROUP_SZ][0]
                                                = STATE_SZF;
    controlMatrix[STATE BASE][CGROUP SZ][1]
                                                = ACTION STO;
    controlMatrix[STATE_BASE][CGROUP_WZ][0]
                                                = STATE_BASE;
    controlMatrix[STATE_BASE][CGROUP_APO][0]
                                                = STATE ZK:
    controlMatrix[STATE_BASE][CGROUP_APO][1]
                                                = ACTION_STO;
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controlMatrix[STATE BASE][CGROUP OUOT][0] = STATE STRING:
controlMatrix[STATE_BASE][CGROUP_QUOT][1] = ACTION_STO;
controlMatrix[STATE BASE][CGROUP SLASH][0] = STATE KO OM;
controlMatrix[STATE BASE][CGROUP SLASH][1] = ACTION STO;
controlMatrix[STATE_BASE][CGROUP_AST][0]
                                            = STATE_SZF;
controlMatrix[STATE_BASE][CGROUP_AST][1]
                                           = ACTION_STO;
controlMatrix[STATE BASE][CGROUP BSLASH][0] = STATE SZF;
controlMatrix[STATE_BASE][CGROUP_BSLASH][1] = ACTION_STO;
controlMatrix[STATE_BASE][CGROUP_EOF][1]
                                          = ACTION_OUT;
// 111
// {{{ Zustand: ZK
controlMatrix[STATE_ZK][CGROUP_BSLASH][0]
                                           = STATE ZKE;
controlMatrix[STATE ZK][CGROUP SONST][0]
                                            = STATE ZKW;
controlMatrix[STATE_ZK][CGROUP_SONST][1]
                                            = ACTION_STO;
controlMatrix[STATE_ZK][CGROUP_EOF][1]
                                            = ACTION OUT:
// }}}
// {{{ Zustand: ZKE
controlMatrix[STATE ZKE][CGROUP SONST][0]
                                           = STATE ZKW:
controlMatrix[STATE_ZKE][CGROUP_SONST][1]
                                           = ACTION STO;
controlMatrix[STATE ZKE][CGROUP EOF][1]
                                            = ACTION OUT;
// }}}
// {{{ Zustand: ZKW
controlMatrix[STATE ZKW][CGROUP APO][0]
                                            = STATE BASE;
controlMatrix[STATE_ZKW][CGROUP_APO][1]
                                            = ACTION STOOUT;
controlMatrix[STATE_ZKW][CGROUP_EOF][1]
                                            = ACTION OUT;
// }}}
// {{{ Zustand: KO?
controlMatrix[STATE KO OM][CGROUP SLASH][0] = STATE KO;
controlMatrix[STATE_KO__QM][CGROUP_SLASH][1] = ACTION_CLEAR;
controlMatrix[STATE_KO_QM][CGROUP_AST][0] = STATE_AST_KO;
controlMatrix[STATE_KO__QM][CGROUP_AST][1] = ACTION_CLEAR;
controlMatrix[STATE_KO__QM][CGROUP_ZI][0]
                                          = STATE_ZAHL;
controlMatrix[STATE_KO__QM][CGROUP_ZI][1]
                                           = ACTION_OUTSTO;
controlMatrix[STATE_KO__QM][CGROUP_BU][0]
                                           = STATE NAME;
controlMatrix[STATE KO OM][CGROUP BU][1] = ACTION OUTSTO;
controlMatrix[STATE_KO__QM][CGROUP_SONST][0] = STATE_BASE;
controlMatrix[STATE_KO__QM][CGROUP_SONST][1]= ACTION_STOOUT;
controlMatrix[STATE_KO__QM][CGROUP_EOF][1] = ACTION_OUT;
controlMatrix[STATE_KO__QM][CGROUP_SZ][0] = STATE_SZF;
controlMatrix[STATE_KO__QM][CGROUP_SZ][1] = ACTION_STO;
// }}}
// {{{ Zustand: KO
controlMatrix[STATE_KO][CGROUP_SONST][0]
                                            = STATE_KO;
controlMatrix[STATE_KO][CGROUP_EOL][0]
                                            = STATE_BASE;
controlMatrix[STATE_KO][CGROUP_EOF][1]
                                            = ACTION OUT;
// }}}
// {{{ Zustand: *KO
controlMatrix[STATE_AST__KO][CGROUP_AST][0]
                                                = STATE_KOE__QM;
controlMatrix[STATE_AST__KO][CGROUP_SONST][0]
                                               = STATE_AST__KO;
controlMatrix[STATE_AST__KO][CGROUP_EOF][1]
                                                = ACTION OUT;
// }}}
// {{{ Zustand: KOE?
controlMatrix[STATE_KOE__QM][CGROUP_SLASH][0]
                                                = STATE BASE;
controlMatrix[STATE_KOE_QM][CGROUP_SONST][0]
                                                = STATE_AST__KO;
controlMatrix[STATE_KOE__QM][CGROUP_EOF][1]
                                                = ACTION OUT:
// }}}
// {{{ Zustand: ZAHL
controlMatrix[STATE ZAHL][CGROUP ZI][0]
                                            = STATE ZAHL;
controlMatrix[STATE ZAHL][CGROUP ZI][1]
                                            = ACTION STO;
controlMatrix[STATE_ZAHL][CGROUP_SZ][0]
                                            = STATE SZF:
controlMatrix[STATE_ZAHL][CGROUP_SZ][1]
                                            = ACTION_OUTSTO;
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controlMatrix[STATE_ZAHL][CGROUP_SONST][1] = ACTION_OUT;
    controlMatrix[STATE ZAHL][CGROUP EOF][1]
                                                = ACTION OUT:
    // }}}
    // {{{ Zustand: SZF
    controlMatrix[STATE SZF][CGROUP BU][0]
                                                = STATE NAME:
    controlMatrix[STATE_SZF][CGROUP_BU][1]
                                                = ACTION_OUTSTO;
    controlMatrix[STATE_SZF][CGROUP_ZI][0]
                                                = STATE_ZAHL;
    controlMatrix[STATE_SZF][CGROUP_ZI][1]
                                                = ACTION OUTSTO;
    controlMatrix[STATE SZF][CGROUP SZ][0]
                                                = STATE SZF;
    controlMatrix[STATE_SZF][CGROUP_SZ][1]
                                                = ACTION_STO;
    controlMatrix[STATE_SZF][CGROUP_WZ][0]
                                                = STATE_SZF;
    controlMatrix[STATE SZF][CGROUP WZ][1]
                                                = ACTION NOOP;
    controlMatrix[STATE_SZF][CGROUP_APO][0]
                                                = STATE_ZK;
    controlMatrix[STATE_SZF][CGROUP_APO][1]
                                                = ACTION OUTSTO:
    controlMatrix[STATE SZF][CGROUP QUOT][0]
                                                = STATE STRING;
    controlMatrix[STATE_SZF][CGROUP_QUOT][1]
                                                = ACTION OUTSTO;
    controlMatrix[STATE_SZF][CGROUP_SONST][0]
                                                = STATE BASE;
    controlMatrix[STATE SZF][CGROUP SONST][1]
                                                = ACTION OUT;
    controlMatrix[STATE_SZF][CGROUP_SLASH][0]
                                                = STATE KO OM;
                                                = ACTION_OUTSTO;
    controlMatrix[STATE_SZF][CGROUP_SLASH][1]
    controlMatrix[STATE SZF][CGROUP EOL][0]
                                                = STATE SZF;
    controlMatrix[STATE SZF][CGROUP EOL][1]
                                                = ACTION NOOP;
    controlMatrix[STATE_SZF][CGROUP_EOF][1]
                                                = ACTION OUT;
    // }}}
    // {{{ Zustand: NAME
    controlMatrix[STATE_NAME][CGROUP_BU][0]
                                                = STATE_NAME;
    controlMatrix[STATE_NAME][CGROUP_BU][1]
                                                = ACTION STO:
    controlMatrix[STATE_NAME][CGROUP_ZI][0]
                                                = STATE NAME;
    controlMatrix[STATE NAME][CGROUP ZI][1]
                                                = ACTION STO;
    controlMatrix[STATE_NAME][CGROUP_SZ][0]
                                                = STATE_SZF;
    controlMatrix[STATE_NAME][CGROUP_SZ][1]
                                                = ACTION_OUTSTO;
    controlMatrix[STATE NAME][CGROUP AST][0]
                                                = STATE SZF;
    controlMatrix[STATE_NAME][CGROUP_AST][1]
                                                = ACTION_OUTSTO;
    controlMatrix[STATE_NAME][CGROUP_WZ][0]
                                                = STATE_BASE;
    controlMatrix[STATE NAME][CGROUP WZ][1]
                                                = ACTION OUT;
    controlMatrix[STATE NAME][CGROUP EOL][0]
                                                = STATE BASE;
    controlMatrix[STATE_NAME][CGROUP_EOL][1]
                                                = ACTION_OUT;
    controlMatrix[STATE_NAME][CGROUP_EOF][1]
                                                = ACTION_OUT;
    controlMatrix[STATE_NAME][CGROUP_SLASH][0]
                                                = STATE_KO__QM;
    controlMatrix[STATE_NAME][CGROUP_SLASH][1] = ACTION_OUTSTO;
    // }}}
    // {{{ Zustand: STRING
    controlMatrix[STATE_STRING][CGROUP_QUOT][0] = STATE_BASE;
    controlMatrix[STATE_STRING][CGROUP_QUOT][1] = ACTION_STOOUT;
    controlMatrix[STATE_STRING][CGROUP_SONST][0] = STATE_STRING;
    controlMatrix[STATE STRING][CGROUP SONST][1] = ACTION STO;
    controlMatrix[STATE_STRING][CGROUP_EOF][1] = ACTION_OUT;
    // }}}
    // }}}
// }}}
// {{{ SourceCompressor::findCharGroup ()
/// Zeichengruppe eines Eingabezeichens ermitteln
SourceCompressor::CharGroup SourceCompressor::findCharGroup (char c) const
    switch (c)
        case '\n':
        case ' \ r':
            return CGROUP_EOL;
        case '\\':
            return CGROUP_BSLASH;
        case '*':
            return CGROUP_AST;
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        case '/':
           return CGROUP_SLASH;
        case '\'':
           return CGROUP APO;
        case '\"':
           return CGROUP_QUOT;
       case ' ':
        case '\t':
           return CGROUP_WZ;
        default:
           string sTemp;
           sTemp = c;
            /// Weitere Untersuchung: Buchstaben. Ziffer, Sonderzeichen
           if (isalpha(c) || c == '_')
               return CGROUP_BU;
            else if (isdigit(c))
               return CGROUP_ZI;
           else if (sTemp.find_first_of(string(":.+-=;,[](){}&<>%?~#")) != string::
npos)
               return CGROUP_SZ;
           return CGROUP_SONST;
// }}}
// {{{ SourceCompressor::performAction ()
/// Aktion durchfuehren
void SourceCompressor::performAction (const int action, char& c)
    switch (action)
       case ACTION STO:
                               /// Zeichen in Buffer einfuegen
           mOutBuffer += c;
           break;
        case ACTION OUT:
                               /// Buffer ausgeben
           mDestFilestream << mOutBuffer << endl;
           if (mShowOnScreen) cout << mOutBuffer << endl;</pre>
           mOutBuffer.clear();
           break;
        case ACTION_OUTSTO:
                               /// Buffer ausgeben + Zeichen speichern
           mDestFilestream << mOutBuffer << endl;
           if (mShowOnScreen) cout << mOutBuffer << endl;</pre>
           mOutBuffer.clear();
           mOutBuffer += c;
           break;
        case ACTION_STOOUT:
                               /// Zeichen speichern + Buffer ausgeben
           mOutBuffer += c;
           mDestFilestream << mOutBuffer << endl;</pre>
           if (mShowOnScreen) cout << mOutBuffer << endl;</pre>
           mOutBuffer.clear();
           break;
        case ACTION_CLEAR:
           mOutBuffer.clear(); /// Buffer leeren
           break;
       case ACTION_NOOP:
                               /// keine Aktion
       default:
           break;
    return;
// }}}
              -----//
// }}}
/* vim: set expandtab tabstop=4 shiftwidth=4 softtabstop=4 foldmethod=marker: */
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