

NOTE ON ERROR FUNCTIONS

This note motivates the usage of various common **error functions** used to train **Neural Networks**.

As a general guiding principle, we keep the overarching goal in mind (we are taking a probabilistic viewpoint here). We would like to use Neural Networks in the context of learning the joint distribution of **data** and **target values**.

$$p(x, t) = p(t|x) p(x)$$

The motivation for most error functions is to learn the **MLE**, using the model we train as an approximation to $p(t|x)$.

In other words, we use the following framework. We have some **training data** $\{x^n, t^n\}$, and we want to *maximize*,

$$\mathcal{L} = \prod_n p(x^n, t^n) = \prod_n p(t^n|x^n) p(x^n)$$

Using the fact that a monotonous transformation does not change the argument of the $\arg\max_x(f(x))$ function, and the fact that $\arg\max_x(f(x)) = \arg\min_x(-f(x))$ we can focus our efforts on,

$$\min$$

$$= - \sum_n \ln p(t^n|x^n) - \sum_n \ln p(x^n)$$

$$\min$$

Where we have no impact on $p(x^n)$, hence we can reduce the problem to,

$$\min$$

$$E = - \sum_n \ln p(t^n|x^n)$$

$$\min$$

Where we simplify notation by using E as our error function.

Now, the idea is to consider the **conditional probability** $p(t^n|x^n)$ as constructed by our **Neural Network**.

Remark: The setting just described is in fact not limited to Neural Network models

SUM OF SQUARES ERROR

Take c target variables t_k where $k = 1, \dots, c$ and assume that $p(t_i) \neq p(t_j) \forall i \neq j$.

Moreover, assume that $t_k = h_k(x) + \epsilon$, where $\epsilon \sim N(0, \sigma^2)$

Our goal is to approximate the function $h_k(x)$, with a **Neural Network**, where we express the outputs as $y_k(x; w)$, w representing the weight parameters.

The resulting likelihood function is,

$$\mathcal{L} = \prod_k \prod_n \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{(y_k(x; w) - t_k)^2}{2\sigma^2}\right\}$$

Taking the log and omitting terms independent of w , we end with,

$$\begin{aligned} E &= \frac{1}{2\sigma^2} \sum_n \sum_k (y_k(x; w) - t_k)^2 + N \ln \sigma + \frac{N}{2} \ln 2\pi \\ &\Leftrightarrow \frac{1}{2} \sum_n \sum_k (y_k(x; w) - t_k)^2 \\ &\Leftrightarrow \frac{1}{2} \sum_n \|y(x; w) - t\|^2 \end{aligned}$$

DERIVATIVES

Choosing as an output function $y = a$ (**linear output activation**), we get the following,

$$\begin{aligned} \frac{\partial E}{\partial a} &= \frac{\partial E}{\partial y} \frac{\partial y}{\partial a} \\ &= (y - t) \end{aligned}$$

MINKOWSKI ERROR

Now considering the same setting as for the *sum of squares error*, but exchanging the **error distribution** to the more general,

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$$p(\epsilon) = \frac{R \beta^{\frac{1}{R}}}{2 \Gamma(\frac{1}{R})} \exp - \beta |\epsilon|^R$$

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Using the same procedure as above, we arrive at,

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$$E = \sum_n \sum_k |y_k(x^n; w) - t_k|^R$$

\$\$

Which is known as the **Minkowski R Error**.

Derivatives

It is worthwhile to note the general form of it's derivative with respect to an a weight w_{ji} ,

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$$\frac{\partial E}{\partial w_{ji}} = \sum_n \sum_k |y_k(x^n; w) - t_k|^{R-1} \text{sgn}(y_k(x^n; w) - t_k) \frac{\partial y_k}{\partial w_{ji}}$$

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CROSS ENTROPY FOR TWO CLASSES

Switching perspective from **regression problems** to **classification problems**, in other words, assuming a different kind of **data generating process**, we consider $p(t|x) = y(x;w)^t (1 - y(x;w))^{1-t}$ (we model the data as deriving from a *bernoulli process*).

Now this provides a **likelihood function** of the following kind,

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$$\mathcal{L} = \prod_n (y(x^n;w))^{t^n} (1 - y(x^n;w))^{1-t^n}$$

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Now, denoting $y(x^n;w)$ as y^n for simplicity, this leads us to an error function of the form,

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$$E = - \sum_n t^n \ln y^n + (1 - t^n) \ln (1 - y^n)$$

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which is known as the **cross entropy**.

Derivatives

We get,

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$$\frac{\partial E}{\partial y^n} = \frac{y^n - t^n}{y^n(1 - t^n)}$$

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choosing as **output activation function** the **sigmoid activation** (justified below),

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$$y = g(a) = \frac{1}{1 + \exp(-a)}$$

\$\$

where,

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$$g'(a) = g(a)(1 - g(a))$$

\$\$

we get, for the **output node** a ,

\$\$ \begin{align}

$$\frac{\partial E}{\partial a^n} = \frac{\partial E}{\partial y^n} y^n (1 - y^n) \backslash$$

$$= \frac{(y^n - t^n)}{y^n(1 - t^n)} y^n(1 - y^n) \backslash$$

$$= (y^n - t^n)$$

\end{align}

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Remark of sigmoid activation functions

Consider, a classification problem, for which we have,

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$$p(z|C_k) = \exp \big(A(\theta_k) + B(z, \phi) + \theta_k^T z \big)$$

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so in words, the distribution of the target variable z , conditioned on the *class* k , comes from the **exponential family**.

Then,

$$p(C_1 | z) = \frac{p(z|C_1)P(C_1)}{p(z|C_1)P(C_1) + p(z|C_2)P(C_2)} = \frac{1}{1 + \exp(-a)}$$

where,

$$\begin{aligned} a &= \ln \frac{p(z|C_1)P(C_1)}{p(z|C_2)P(C_2)} \\ w &= \theta_1 - \theta_2 \\ w_0 &= A(\theta_1) - A(\theta_2) + \ln \frac{P(C_1)}{P(C_2)} \end{aligned}$$

Remark on consistency of cross entropy

Consider the setting in which we approach infinite data, then writing

$$\begin{aligned} \lim_{n \rightarrow \infty} E &= \lim_{N \rightarrow \infty} -\frac{1}{N} \sum_n t^n \ln y^n + (1 - t^n) \ln (1 - y^n) \\ &= -\int \big[t \ln y(x) + (1 - t) \ln (1 - y(x)) \big] p(t|x) p(x) dt dx \end{aligned}$$

Denoting,

$$\langle t|x \rangle = \int t p(t|x) dt$$

We have,

$$\lim_{n \rightarrow \infty} E = -\int \big(\langle t|x \rangle \ln y(x) + (1 - \langle t|x \rangle) \ln (1 - y(x)) \big) p(x) dx$$

Which has a *minimum* at

$$y(x) =$$

Now noting that,

$$p(t|x) = \delta_0(t-1)P(C_1|x) + \delta_0(t)P(C_2|x)$$

We can conclude that,

$$y(x) = P(C_1|x)$$

Remark on multiple independent attributes

If we have multiple independent attributes, we can trivially generalize our approach,

Our new *likelihood* is,

$$p(t|x) = \prod_k p(t_k|x) = \prod_k y_k^{t_k} (1 - y_k)^{1-t_k}$$

With corresponding *error function*,

$$E = - \sum_n \sum_k t_k^n \ln(y_k^n) + (1 - t_k^n) \ln(1 - y_k^n)$$

Where we will find a *minimum* corresponding to,

$$y_k(x) = P(C_k|x)$$

CROSS ENTROPY FOR MULTIPLE CLASSES

If we have more than two classes for the target variable, we can express our distribution of the targets given data as follows,

$$p(t^n|x^n) = \prod_{k=1}^c (y_k^n)^{t_k^n}$$

which leads us to the **error function**,

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$$\min_w E = - \sum_{n=1}^N \sum_{k=1}^c t_k^n \ln(y_k^n)$$

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Now for the **output activation function** we pick,

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$$y_k = \frac{\exp a_k}{\sum_{k'} \exp a_{k'}}$$

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We can motivate this choice of activation function by considering the following calculation.

Assuming that $p(z | C_k)$ comes from an **exponential family**, that is

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$$p(z|C_k) = \exp \big(A(\theta_k) + B(z, \phi) + \theta_k^T z \big)$$

\$\$

then applying Bayes theorem,

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$$p(C_k | z) = \frac{p(z|C_k)P(C_k)}{\sum_{k'} p(z|C_{k'})} = \frac{\exp a_k}{\sum_{k'} \exp a_{k'}}$$

\$\$

where,

\$\$\begin{align}

$$a_k = w_k^T z + w_{k_0}$$

$$w_k = \theta_k$$

$$w_{k_0} = A(\theta_k) + \ln P(C_k)$$

\end{align}

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DERIVATIVES

We get,

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\begin{align}

$$\frac{\partial E^n}{\partial y_k} = - \frac{t_{k'}}{y_{k'}} \backslash$$

$$\frac{\partial y_{k'}}{\partial a_k} = y_{k'} \delta_{kk'} - y_{k'} y_k$$

\end{align}

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Now that implies that,

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$$\begin{aligned} \frac{\partial E^n}{\partial a_k} &= \sum_{k'} \frac{\partial E^n}{\partial y_{k'}} \frac{\partial y_{k'}}{\partial a_k} \\ &= \sum_{k'} \frac{-t_{k'}}{y_{k'}} (y_{k'} \delta_{kk'} - y_{k'} y_k) \\ &= \sum_{k'} -t_{k'} \delta_{kk'} + t_{k'} y_k \\ &= -t_k + \sum_{k'} t_{k'} y_k \\ &= y_k - t_k \end{aligned}$$

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JUSTIFICATION VIA ENTROPY

First, consider the *definition* of **differential entropy**,

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$$S = - \int p(x) \ln p(x) \, dx$$

\$\$

If we take a *random variable* α , then the amount of information to transmit the value of α is $-\ln p(\alpha_k)$ if $\alpha = \alpha_k$.

The *expected amount of information* needed to transmit the value of α is given by,

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$$S(x) = - \sum_k p(\alpha_k) \ln p(\alpha_k)$$

\$\$

We usually don't know $p(x)$ and need to encode our message under the assumption of some (hopefully closely) approximating distribution $q(x)$. Under $q(x)$ the information needed to encode x is then $-\ln q(x)$.

The average information needed to encode x is then the **cross-entropy**,

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- $\int p(x) \ln q(x) \, dx$
- \$\$

Note the following connection, to the **expected loss** under a model, when we use $-\ln \mathcal{L}$ as the **loss function**.

$$\begin{aligned} \mathcal{E}[-\ln \mathcal{L}] &= -\lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n=1}^N \ln \tilde{p}(x^n) \\ &= -\int p(x) \ln \tilde{p}(x) dx \end{aligned}$$

Now assuming our α to be a *discrete random variable*, we get,

$$\bullet \sum_k P(\alpha_k) \ln Q(\alpha_k)$$

Where we want to learn $Q(\cdot)$ so as to minimize the expression. In our usual notation, we express $Q(\alpha_k)$, as learned by our **Neural Network**, with $y_k(x; w)$ and simplified as y_k .

Expressing $P(\alpha_k)$ as t_k , this leaves us with,

$$\bullet \sum_{k=1}^c t_k \ln y_k(x)$$

And operationally,

$$\min_w E = -\sum_{n=1}^N \sum_{k=1}^c t_k \ln y_k(x)$$

Which is exactly the **cross entropy**.

GENERAL REMARK

In the preceding derivations, one of the discoveries, is that there exist *good* combinations of *error functions* and *output activation functions*, s.t.,

$$\frac{\partial E^n}{\partial a_k} = (y_k^n - t_k^n)$$

The combinations that we have observed, are the following:

1. Linear output activation <-> Squared error loss (Regression)
2. Sigmoid output activation <-> Cross entropy loss (2-Class Classification)
3. Softmax output activation <-> Cross entropy loss (k-Class Classification)

One can consider these *natural pairs*. This is a remarkable finding, but not explored further here.

GENERAL CONDITIONS FOR OUTPUTS TO BE TREATED AS PROBABILITIES

Consider in general a cost function of the following kind,

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$$E^n = \sum_{k=1}^c f(y_k^n, t_k^n) = \sum_{k=1}^c f(|y_k^n - t_k^n|)$$

\$\$

In the limit of infinite data we get,

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$$\langle E \rangle = \sum_{k=1}^c \iint f(|y_k - t_k|) p(t|x) p(x) dt dx$$

\$\$

where,

\$\$

$$p(t|x) = \prod_{m=1}^c \text{bigg}(\sum_{l=1}^c \delta(t_m - \delta_{ml}) P((C_l | x))\text{bigg})$$

\$\$

So we can write,

\$\$

$$\begin{aligned}
& \langle E \rangle = \sum_{k=1}^c \int f(y_k - t_k) \prod_{m=1}^c \bigg(\sum_{l=1}^c \delta(t_m - \delta_{ml}) P((C_l | x)) \bigg) p(x) \, dt \, dx \\
& = \sum_{k=1}^c \int f(y_k - t_k) \prod_{m \neq k} \bigg(\sum_{l=1}^c \delta(t_m - \delta_{ml}) P((C_l | x)) \bigg) \bigg(\sum_{l=1}^c \delta(t_k - \delta_{kl}) P((C_l | x)) \bigg) p(x) \, dt \, dx \\
& = \sum_{k=1}^c \int f(y_k - t_k) \bigg(\sum_{l=1}^c \delta(t_k - \delta_{kl}) P((C_l | x)) \bigg) p(x) \, dt \, dx \\
& = \sum_{k=1}^c \int f(y_k - 1) P(C_k | x) + f(y_k) (1 - P(C_k | x)) \, p(x) \, dx
\end{aligned}$$

$\end{aligned}$
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Note, the tricky part is to realize that (from step 2 to step 3),

$$\begin{aligned}
& \int \prod_{m \neq k} \bigg(\sum_{l=1}^c \delta(t_m - \delta_{ml}) P((C_l | x)) \bigg) \, dt \\
& = 1
\end{aligned}$$

$\$$

If our goal is to *minimize the average error per pattern*, we can use the following argument to adhere to this.

Applying some **calculus of variations** (I don't have any background in that so I can only show the step), we want the *functional derivative*,

$$\frac{\delta \langle E \rangle}{\delta y_k(x)} = -f'(1 - y_k) P(C_k | x) + f'(y_k) [1 - P(C_k | x)] = 0$$

$\$$

So,

$$\frac{f'(1 - y_k)}{f'(y_k)} = \frac{1 - P(C_k | x)}{P(C_k | x)}$$

$\$$

Since we want $y_k(x) = P(C_k | x)$ (our functions should represent *posterior probabilities*), this implies,

$$\frac{f'(1 - y)}{f'(y)} = \frac{1 - y}{y}$$

$\$$

Solutions for which adhere to the following condition,

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$$f(y) = \int y^r (1-y)^{r-1} dy$$

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Hence, if we use **error functions** that satisfy $f(y) = \int y^r (1-y)^{r-1} dy$, we can treat the outputs y_k as *posterior probabilities over classes given the data*.

Remarks,

- For $r = 1$ we get $f(y) = \frac{y^2}{2}$ the **squared error**
- For $r = 2$ we get $f(y) = -\ln(1-y)$ which can be shown to be the **cross entropy**