$$rf(F,T)$$

(1)

$$\times$$
$$\delta \quad\quad F$$
$$\pi_{e_1,\ldots,e_n}$$
$$Scan_{T \to t_2}$$

(2)
$$r_2(R,T)$$

(3)
$$\bowtie_c$$
$$r_2(R,T) \quad\quad S$$

(4)
$$\bowtie_c$$
$$r_2(R,T) \quad r_2(S,T)$$

(5)
$$Scan_{F_e(e_1,\ldots,e_n)}$$
$$\delta$$
$$\pi_{e_1,\ldots,e_n}$$
$$Scan_{T \to t_2}$$