Lab #1

Similarity Transformation

Image 1:

Linear Parameters:

A: 84.03117383330671 B: 0.005791291298088197

Non-Linear Parameters:

delta X: 10254.288911500238
delta Y: -10378.775218001623
scale: 84.03117403286988
theta: 6.89183671336947e-05

Residuals: (rx, ry)

Residuals:	
[[1.85042661	-0.27334797]
[-0.68446068	0.81535776]
[-0.62944383	0.67161202]
[-0.78444016	-1.04554209]
[0.79740163	1.16437559]
[-0.71547267	-0.53834041]
[0.0604022	0.3044985]
[0.10558689	-1.0986134]]

RSME:

x RMS 0.8708227782471497 y RMS 0.8084707794736097

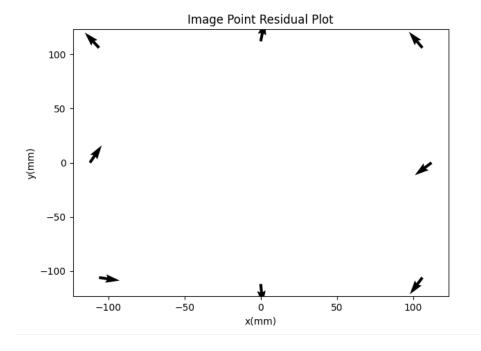


Image 2:

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Linear Parameters:

A: 84.02961711056915 B: -0.05599326995735865

Residuals: (rx, ry)

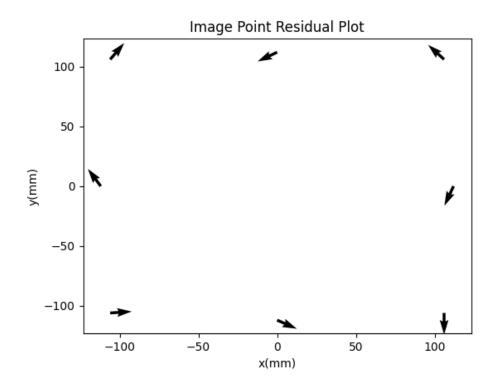
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ı	Residuals:	
ı	[[0.96620006	0.06589187]
	[-0.80020168	0.72617893]
	[0.58490841	0.68100576]
	[0.00129405	-0.8051853]
	[-0.52819286	0.70949242]
	[-0.38978239	-0.83333601]
	[-0.51968215	-0.2449174]
	[0.68545656	-0.29913027]]

Non-Linear Parameters:

delta X: 10260.788531573624
delta Y: -10385.149961133862
scale: 84.02963576616963
theta: -0.0006663515031399287

RSME:

x RMS 0.6211705711851453 y RMS 0.6114594881174636



Affine Transformation

Image 1:

Linear Parameters:

A: 84.0376645345848
B: -0.0021168248123863975
C: 0.00946550579867278
D: 84.02468309158996

Residuals: (rx, ry)

Residuals:	
[[0.77290775	0.02520836]
[0.39305353	0.51679452]
[-0.92798058	-0.40590589]
[-0.48587194	0.03198078]
[0.07041988	0.752844]
[0.01150161	-0.12682591]
[0.4719517	-0.42246576]
[-0.30598195	-0.37163009]]

Non-Linear Parameters:

delta X: 10254.288862572017 delta Y: -10378.775192131347 theta: 0.00011263408866805789 Scale X: 84.03766506765412 Scale Y: 84.02468311825443 delta: 8.744119612681325e-05

RSME:

x RMS 0.5208828517294353 y RMS 0.408187999682545

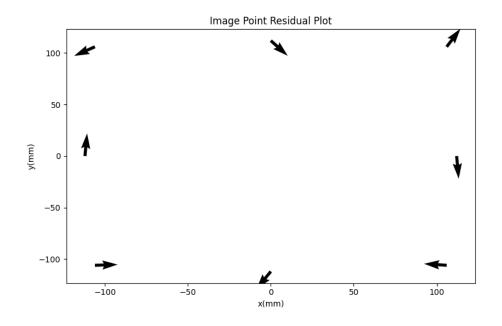
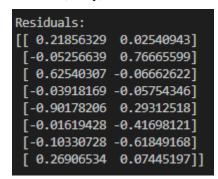


Image 2:

Linear Parameters:

A: 84.03295263417834 B: 0.05971084808390614 C: -0.05227586039988097 D: 84.02628161507539

Residuals: (rx, ry)

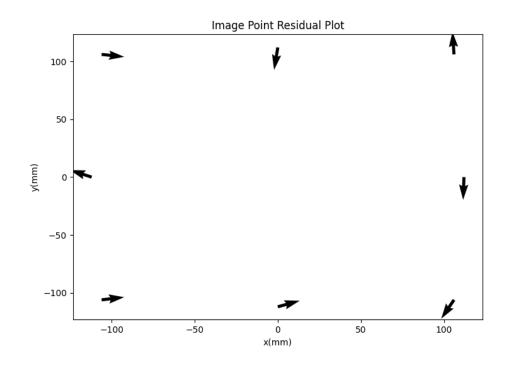


Non-Linear Parameters:

delta X: 10260.788494996665 delta Y: -10385.149955156652 theta: -0.000622087550392181 Scale X: 84.03296889425984 Scale Y: 84.02630283096678 delta: 8.853342301314178e-05

RSME:

x RMS 0.4092277818254644 y RMS 0.39433933547086514



Projective Transformation

Image 1:

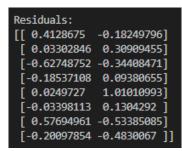
Linear Parameters:

```
A: 84.0391280093
B: 0.0014697340292997296
C: 0.007984370049809897
D: 84.02105344953287
```

Non-Linear Parameters:

```
delta X: 10254.393843649943
delta Y: -10378.517907639103
theta: 9.500776858254347e-05
Scale X: 84.0391283885886
Scale Y: 84.0210534623875
delta: 0.00011250021802002426
out of plane inclination: (1.4270727798516153e-07, 3.4975702409456824e-07)
```

Residuals: (rx, ry)



RSME:

x RMS 0.34905140247539196 y RMS 0.47587615934126515

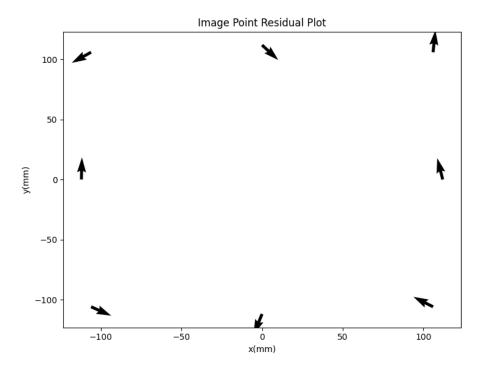


Image 2:

Linear Parameters:

```
A: 84.03419231019731
B: 0.05901736731686125
C: -0.053530451812230595
D: 84.02698344363786
```

Non-Linear Parameters:

```
delta X: 10260.877337342234

delta Y: -10385.199726052404

theta: -0.0006370079023800215

Scale X: 84.0342093598583

Scale Y: 84.02700416941589

delta: 6.535406747198951e-05

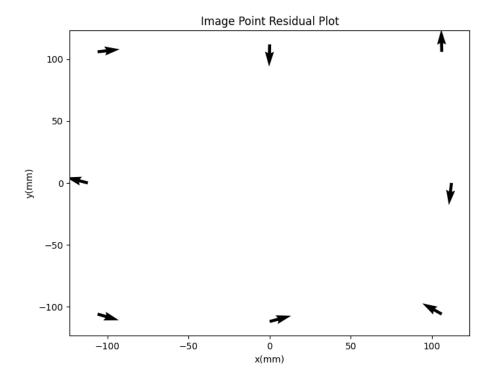
out of plane inclination: (1.2081137997855054e-07, -6.75840988384234e-08)
```

Residuals: (rx, ry)

Residuals: [[0.25710905 -0.07458177] [-0.01401394 0.66666561] [0.5364645 0.0615931] [-0.12811822 0.0706746] [-0.94028663 0.24343158] [-0.05470349 -0.46668055] [-0.01441198 -0.59702405] [0.35796071 0.09592149]]

RSME:

x RMS 0.4162308392264894 y RMS 0.3710596984280994



Questions:

1. For each of the Tasks above, are there any noticeable patterns in the residuals for any of the transformations and for any of the images?

The RMS of the residuals (rx, ry) decrease comparing the similarity transformation to affine transformation to projective transformation.

2. Do the two images have comparable transformation parameters in each of the above tasks? If no, why would there be differences in the derived transformation values?

Between the two images for each transformation, their linear and non-linear parameters are fairly close to each other.

3. Given the results from Tasks 1, 2 and 3, which transformation should be used for observations from this camera/comparator system? Justify your answer and explain your reasoning.

Since the projective transformation has the smallest values in residual RMS, it would be the best transformation used for observations from this camera/comparator system. In general, projective transformation provides more information than similarity and affine transformations. Similarity transformations only has delta x and y, rotation, and scale. Affine transformations has delta x and y as well, scale in x and y, rotation, and non-orthogonality of comparator axes. Projective transformations has the same information as affine transformations but with two additional parameters, out-of-plane inclinations.