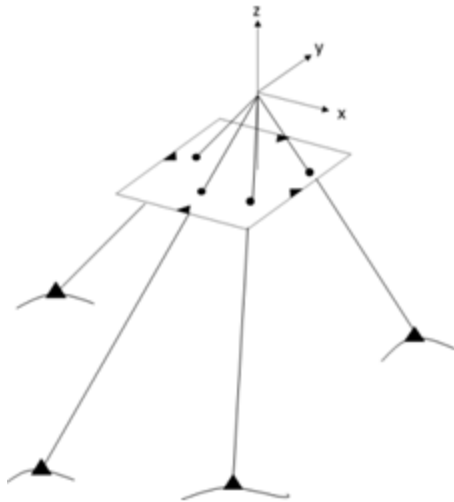
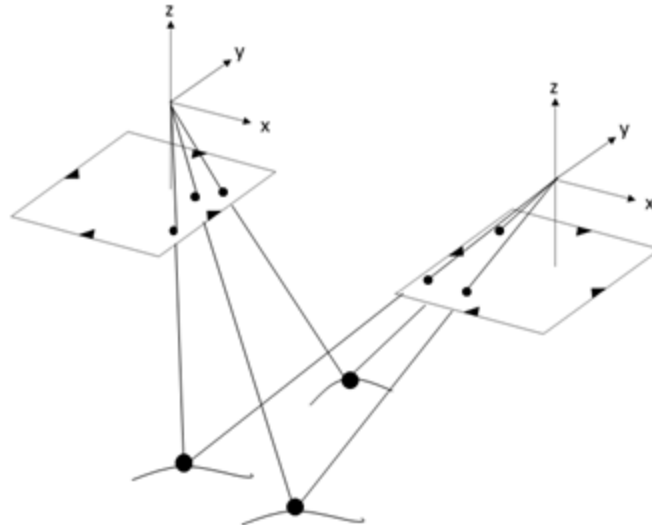


Indirect Image Orientation



Single image



Stereo image pair

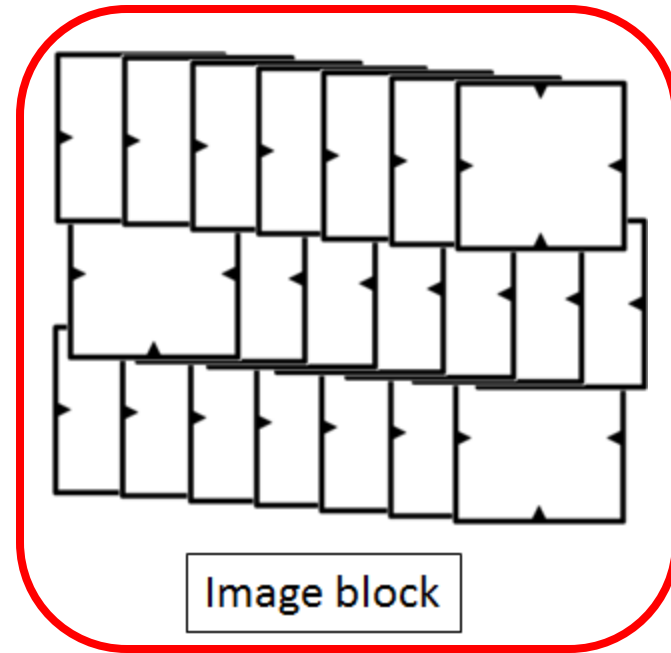


Image block

Indirect image orientation

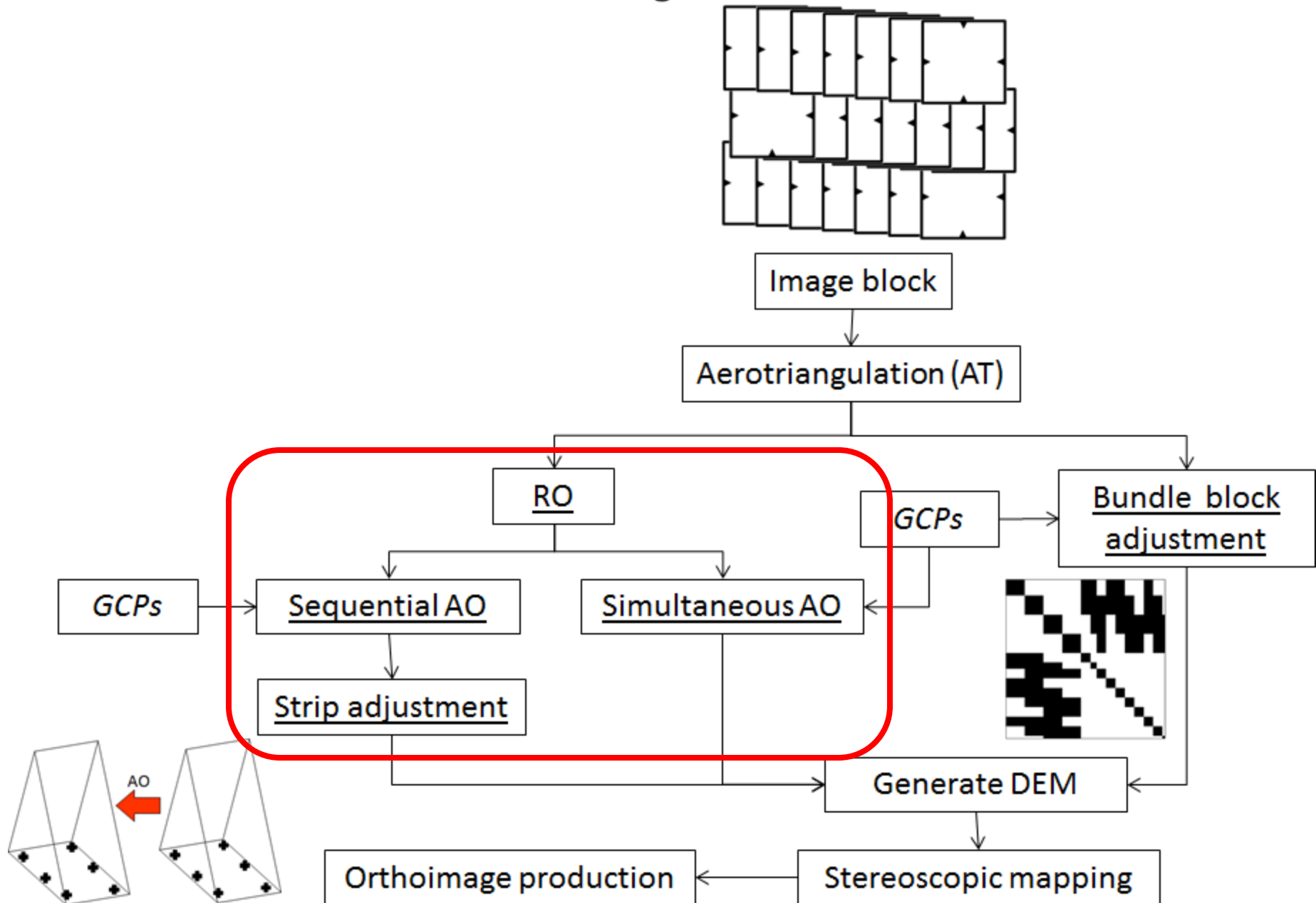
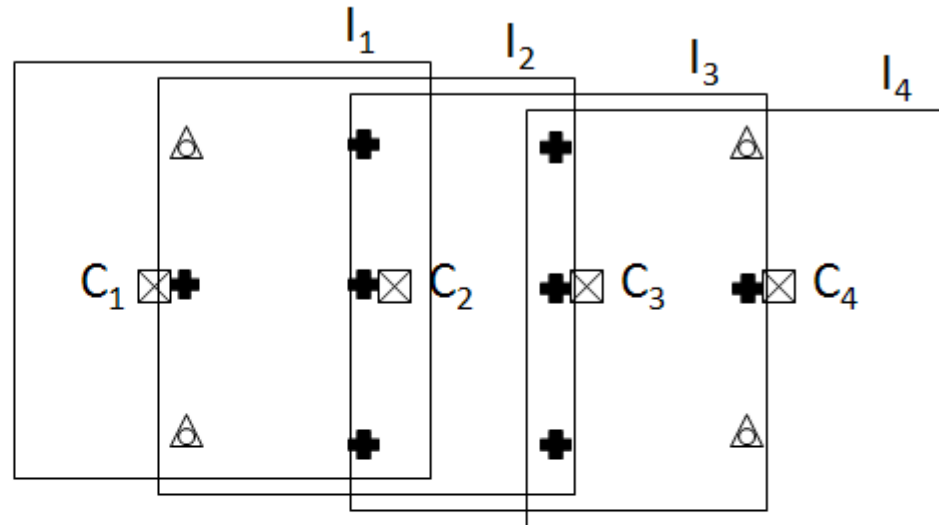


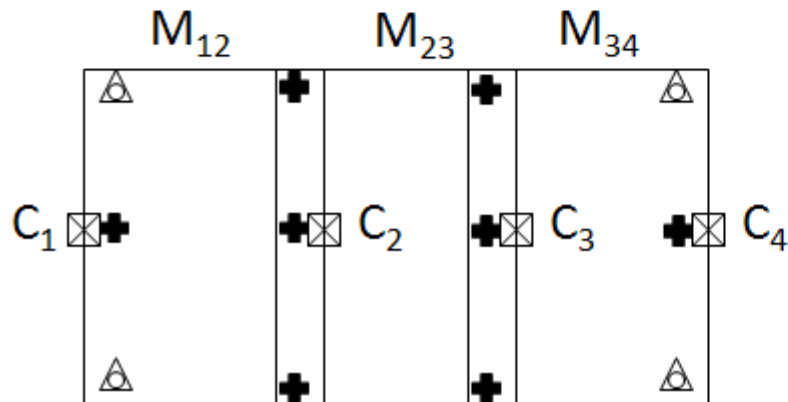
Image Layout for Examples

- ⊠ PC
- ⊕ Pass Point
- △ 3-D Control Point

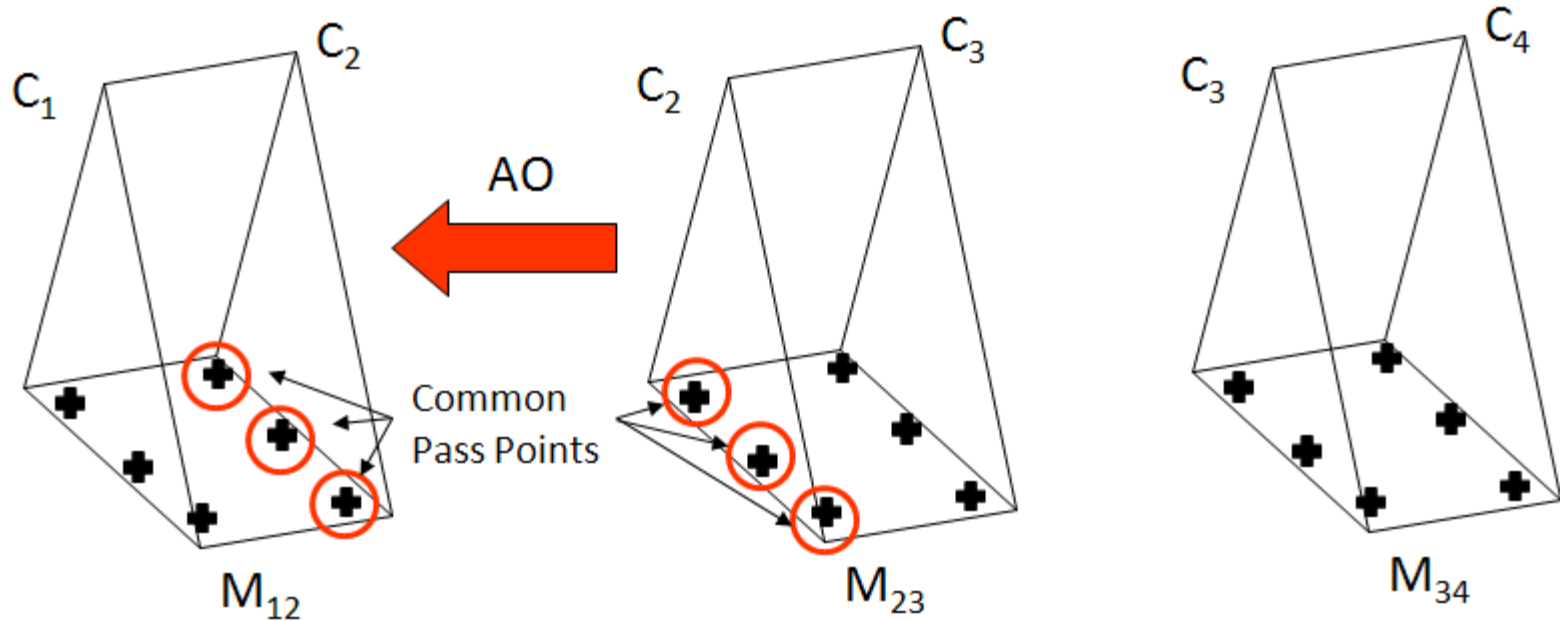
Image Layout



Model Definition



Sequential Construction

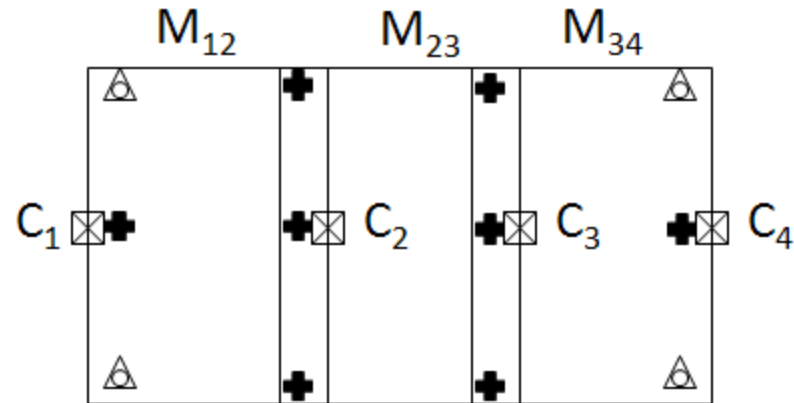


Simultaneous Transformations

⊠ PC

⊕ Pass Point

△ 3-D Control Point



Observations	GCPs	4 x 3	12
	Tie points—ground	6 x 3	18
	Tie-points—PCs	2 x 3	6
	Total		36
Unknowns			
	AO parameters	3 x 7	21
Redundancy			15

Summary of Equations

- ▶ Simultaneous transformations

- ▶ 3D GCP g in model M_{ij}

$$\vec{r}_g^o = \lambda_{ij} M_{ij} \vec{r}_{g_{ij}}^m + \vec{t}_{ij}$$

- ▶ Tie point h in models M_{ij} and M_{jk}

$$\begin{aligned} \vec{r}_{h_{ij}}^o - \vec{r}_{h_{jk}}^o &= 0 \\ \lambda_{ij} M_{ij} \vec{r}_{h_{ij}}^m + \vec{t}_{ij} - \lambda_{jk} M_{jk} \vec{r}_{h_{jk}}^m - \vec{t}_{jk} &= 0 \end{aligned}$$

- ▶ PC c in models M_{ij} and M_{jk}

$$\begin{aligned} \vec{r}_{c_{ij}}^o - \vec{r}_{c_{jk}}^o &= 0 \\ \lambda_{ij} M_{ij} \vec{r}_{c_{ij}}^m + \vec{t}_{ij} - \lambda_{jk} M_{jk} \vec{r}_{c_{jk}}^m - \vec{t}_{jk} &= 0 \end{aligned}$$