Package 'knitroR'

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Type Package	
Title R integration of Knitro	
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Description This package provides an R integration of knitro via Rcpp. Knitro has an excellent C++ implementation. This package passes user defined R functions on to the C++ interface. To use Knitro you need to have a valid license.	
License GPL (>= 2)	
Imports Rcpp (>= 0.11.3)	
LinkingTo Rcpp	
R topics documented: knitro	
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Description

This function passes user defined R functions on to the C++ interface

Usage

```
knitro(objFun, objGrad = NULL, c_equality = NULL, c_inequality = NULL,
jac = NULL, jacIndexCons = NULL, jacIndexVars = NULL, x0 = NA,
lb = NULL, ub = NULL, optionsFile = "options.opt")
```

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Arguments

objFun is a scalar valued R function that returns the objective function

objGrad is a vector-valued R function with the gradient

c_equality is a vector-valued R function with equality constraints
c_inequality is a vector-valued R function with inequality constraints
jac is a vector with the content of the Jacobian (sparse)

jacIndexCons refers to each element of jac and contains the number of the constraint it refers

to. Indexing is C++ compatible, i.e. the first constraint has index 0

jacIndexVars refers to each element of jac and contains the number of the variable it refers to.

Indexing is C++ compatible, i.e. the first variable has index 0

x0 is a vector with starting values

optionsFile is the path and filename of the options file. If it does not exist, the function will

create it

Value

a list with the final estimates, the function value, and Knitro's exit status

knitroCpp Knitro C++ Wrapper

Description

This function is the standard C++ wrapper around knitro. It defines the object KTR_new and defines a callback function that is used to evaluate the objective function, the constraints, and gradients. The only deviation from the standard C++ wrapper is to use UserParam to pass the original R functions on to the C++ callback function.

Usage

```
knitroCpp(fcts, startValues, num_equality_constraints,
  num_inequality_constraints, nnzJ, RjacIndexCons, RjacIndexVars, ub, lb,
  optionsFile)
```

Arguments

fcts is an R list of functions that includes the objFun, objGrad, c, and jac.

startValues is a vector of start values

num_equality_constraints

is an integer with the number of equality constraints in c

 ${\tt num_inequality_constraints}$

is an integer with the number of inequality constraints in c

nnzJ is an integer with the number of non-zero objects in the Jacobian

RjacIndexCons is a vector of length nnzJ. Each element contains the index of a particular con-

straint (i.e. the index of a row in the jacobian).

RjacIndexVars is a vector of length nnzJ. Each element contains the index of a particular vari-

able (i.e. the index of a column in the jacobian).

a vector of upper bounds for each element in x0
 a vector lower bounds for each element in x0

optionsFile the location of the options file

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Value

A list with the vector that minimizes the objective function, the final function value, and Knitro's exit status

See Also

http://www.artelys.com/tools/knitro_doc/2_userGuide/gettingStarted/startCallableLibrary.html

knitro_ms Call the knitro C++ interface using multiple start values

Description

This is a multi start version of knitro(). Uses a matrix as startvalues where each row corresponds to one set of startvalues to be used. This version of multi-start gives the user more control over the start values than Knitro's built-in version of multi-start. If you want to use the built-in version of multi-start instead, you can do so via the options file.

Usage

```
knitro_ms(objFun, objGrad = NULL, c_equality = NULL, c_inequality = NULL,
  jac = NULL, jacIndexCons = NULL, jacIndexVars = NULL, x0 = NA,
  lb = NULL, ub = NULL, optionsFile = "options.opt")
```

Arguments

is a scalar valued R function that returns the objective function
is a vector-valued R function with the gradient
is a vector-valued R function with equality constraints
is a vector-valued R function with inequality constraints
is a vector with the content of the Jacobian (sparse)
refers to each element of jac and contains the number of the constraint it refers to. Indexing is C++ compatible, i.e. the first constraint has index 0
is a matrix with starting values
is the path and filename of the options file. If it does not exist, the function will create it
refers to each element of jac and contains the number of the variable it refers to. Indexing is C++ compatible, i.e. the first variable has index 0

Value

a list with the final estimates, the function value, and Knitro's exit status

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