Package ‘knitroR’

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Type Package

Title R integration of Knitro

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Description This package provides an R integration of knitro via Rcpp. Knitro has an excellent C++ implementation. This package passes user defined R functions on to the C++ interface. To use Knitro you need to have a valid license.

License GPL (>= 2)

Imports Rcpp (>= 0.11.3)

LinkingTo Rcpp

R topics documented:

knitro — *Call the knitro C++ interface*

Description

This function passes user defined R functions on to the C++ interface

Usage

```
knitro(objFun, objGrad = NULL, c_equality = NULL, c_inequality = NULL,
  jac = NULL, jacIndexCons = NULL, jacIndexVars = NULL, x0 = NA,
  lb = NULL, ub = NULL, optionsFile = "options.opt")
```

Arguments

`objFun`	is a scalar valued R function that returns the objective function
`objGrad`	is a vector-valued R function with the gradient
`c_equality`	is a vector-valued R function with equality constraints
`c_inequality`	is a vector-valued R function with inequality constraints
`jac`	is a vector with the content of the Jacobian (sparse)
`jacIndexCons`	refers to each element of jac and contains the number of the constraint it refers to. Indexing is C++ compatible, i.e. the first constraint has index 0
`jacIndexVars`	refers to each element of jac and contains the number of the variable it refers to. Indexing is C++ compatible, i.e. the first variable has index 0
`x0`	is a vector with starting values
`optionsFile`	is the path and filename of the options file. If it does not exist, the function will create it

Value

a list with the final estimates, the function value, and Knitro's exit status

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`knitroCpp` *Knitro C++ Wrapper*

Description

This function is the standard C++ wrapper around knitro. It defines the object `KTR_new` and defines a callback function that is used to evaluate the objective function, the constraints, and gradients. The only deviation from the standard C++ wrapper is to use `UserParam` to pass the original R functions on to the C++ callback function.

Usage

```
knitroCpp(fcts, startValues, num_equality_constraints,
  num_inequality_constraints, nnzJ, RjacIndexCons, RjacIndexVars, ub, lb,
  optionsFile)
```

Arguments

`fcts`	is an R list of functions that includes the `objFun`, `objGrad`, `c`, and `jac`.
`startValues`	is a vector of start values
`num_equality_constraints`	is an integer with the number of equality constraints in `c`
`num_inequality_constraints`	is an integer with the number of inequality constraints in `c`
`nnzJ`	is an integer with the number of non-zero objects in the Jacobian

`RjacIndexCons`	is a vector of length `nnzJ`. Each element contains the index of a particular constraint (i.e. the index of a row in the jacobian).
`RjacIndexVars`	is a vector of length `nnzJ`. Each element contains the index of a particular variable (i.e. the index of a column in the jacobian).
`ub`	a vector of upper bounds for each element in x0
`lb`	a vector lower bounds for each element in x0
`optionsFile`	the location of the options file

Value

A list with the vector that minimizes the objective function, the final function value, and Knitro's exit status

See Also

http://www.artelys.com/tools/knitro_doc/2_userGuide/gettingStarted/startCallableLibrary.html

`knitro_ms` *Call the knitro C++ interface using multiple start values*

Description

This is a multi start version of knitro(). Uses a matrix as startvalues where each row corresponds to one set of startvalues to be used. This version of multi-start gives the user more control over the start values than Knitro's built-in version of multi-start. If you want to use the built-in version of multi-start instead, you can do so via the options file.

Usage

```
knitro_ms(objFun, objGrad = NULL, c_equality = NULL, c_inequality = NULL,
  jac = NULL, jacIndexCons = NULL, jacIndexVars = NULL, x0 = NA,
  lb = NULL, ub = NULL, optionsFile = "options.opt")
```

Arguments

`objFun`	is a scalar valued R function that returns the objective function
`objGrad`	is a vector-valued R function with the gradient
`c_equality`	is a vector-valued R function with equality constraints
`c_inequality`	is a vector-valued R function with inequality constraints
`jac`	is a vector with the content of the Jacobian (sparse)
`jacIndexCons`	refers to each element of jac and contains the number of the constraint it refers to. Indexing is C++ compatible, i.e. the first constraint has index 0
`x0`	is a matrix with starting values
`optionsFile`	is the path and filename of the options file. If it does not exist, the function will create it
`jacIndexCons`	refers to each element of jac and contains the number of the variable it refers to. Indexing is C++ compatible, i.e. the first variable has index 0

Value

a list with the final estimates, the function value, and Knitro's exit status

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