```
 \begin{array}{l} (Q,V,T,E,S,F) \\ Q \\ V \\ Y \\ E \\ P(Q \times \\ V \times \\ Q) \\ E \in \\ P(Q \times \\ Q) \\ S \subseteq \\ Q \\ F \subseteq \\ Q \\ S \text{tatePool} \end{array} 
  \begin{array}{c} \textbf{StatePool} \\ \textbf{StateSet} \\ \textit{aomain}(\textit{constintr}); \textit{classBitVec}//\textit{uesdmaxnumberbitsindata}, \textit{denotewidth}(\textit{domain}), [0, \textit{bits}_{i}n_{u}se) ==> [0, \textit{width}) \textit{intbit} \\ \end{array}
transition

re-
tion:
T \in Q \rightarrow P(V \times Q), T(p) = \{(a,q)|(p,a,q) \in T\}p
??
[abel; Statetransition_destination; classTransImplTransPair * data; classTrans: protectedTransIml
                  transition
\begin{array}{l} protected Tran\\ \textbf{relation}\\ E \in \\ P(Q \times \\ Q) \Rightarrow \\ E \in \\ Q \to \\ P(Q), E(p) = \\ \{q|(p,q) \in \\ E\} \epsilon pq \\ q_0 \\ q_1 \\ q_2 \\ q_3 \\ q_4 \\ q_1 \\ \{(q_0,a,q_1)\} \\ \{(q_1,b,q_2), (q_1)\} \\ \{(q_1,b,q_2), (q_1)\} \end{array}
\{(q_1,b,q_2),(q_1,c,q_3)\}
\{(q_1,b,q_2),(q_1,c,q_3)\}
the signatures of the transition relations:
T\in P(Q\times V\times Q)
T\in T\in P(Q\times V\times Q)
                    T \in
  Q
  \begin{array}{c} T \in \\ Q \times \\ V \rightarrow \\ P(Q) \\ T \in \\ P(V \times \\ Q) \\ T \in \\ Q \rightarrow \\ P(V \times \\ Q) \\ T \in \\ Q \rightarrow \\ P(V \times \\ Q) \\ \end{array}
  Q)
T(p) =
   \{(a,q):
 (\stackrel{\cdot}{p},\stackrel{\cdot}{a},\stackrel{\cdot}{q})\in T\}
  T \in P(Q \times V \times Q), T = Q
   \{(p, \underline{a}, q)\}
 T \in Q \rightarrow P(V \times Q), T(p) = Q \rightarrow P(V \times Q)
```

```
\begin{array}{l}Q), T(p) = \\ \{(a,q):\end{array}
                                                                   (p, a, q) \in T
T_{2}(T(p)) = 0
                                                               \pi_{2}(T(p)) = \{q|(p, a, q) \in T\}, \bar{\pi}_{2}(T(p)) = \{a|(p, a, q) \in T\}
Q_{map} : Q \in V, T(p) = \{(a, q) : \{(a, q) : \{(p, a, q) \in T\}\}
                                                         \{(a,q): \{(a,q): (p,a,q) \in T\} \}

Q_{map}(q) = \{a\}

Q_{map}: Q
(Q, V, T, E, S, F), M_0 = (Q_0, V_0, T_0, E_0, S_0, F_0), M_1 = (Q_1, V_1, T_1, E_1, S_1, F_1)
FA
FA
[M] = [Q]
(\cong)
                                                                             FA's
(\cong)
```

```
f(a) =

\begin{array}{l}
f(a) = \\
(f_d(a^R))^{R'} \\
B \\
f_d \circ \\
R(a) = \\
R' \circ \\
f(a) \Rightarrow \\
f(a
                        f_d(R(a)) \Rightarrow f_d(R(a)) \Rightarrow f_d(a^R) \Rightarrow f(a) \Rightarrow 
                              (f_d(a^R))^{R'}
                                 (m) [matrixof math nodes, rowsep =
                           2em, columnsep = 2em]AB \circ \circ; [->, font = ](m-
                                 1) edge node [auto] (m -
                        1-2)(m-1)
                           \begin{array}{c} 1) edgenode[auto,swap](m-2)\\ 2-(m-2)\\ \end{array}
                           f_d f_d f_d f_d f_d f_d f_d f_d
                              (\widehat{f}_d(a^R))^{R'})
                           C_{\cdot,RFA}(rfa(\$),rfa(E)) = C_{\cdot,RFA}(C_{\$,RFA},rfa(E)) = C_{\cdot,RFA}(C_{\$,RFA},rfa(E)) = C_{\cdot,RFA}(RFA)
                     C_{\cdot,RFA}(C_{\$,RFA},rfa(E)) = L_{RE}(\$E) = \{\$\}L_{RE}(E)
covert
EL_{FA}\circ convert\circ rfa(E) = V^{-1}L_{RE}(E)
convert(C_{\cdot,RFA}(C_{\$,RFA},rfa(E)) = rfa(E)
                              rfa(E)
                                 (m) [matrixof math nodes, rowsep =
                           \begin{array}{l} 2em, columnsep = \\ 2em] RERFA(\$, E)(rfa(\$), rfa(E)) L_{reg}\$ \cdot Erfa(\$) \cdot rfa(E); [-> \\ \end{array}
                                                    font =
                                 |(m-
                              1) edge node [auto] (m -
                           \frac{1-}{2}(m-
                                 \bar{1})edgenode[auto, swap]<sub>RE</sub>
                                 (m-2-5)(m-1-4)edgenode[auto, swap]
                              convert(C_{\cdot,RFA}(C_{\$,RFA},rfa(E)) =
                           rfa(E) usefuls \circ
                           \begin{array}{c} subset \\ D = \\ \emptyset, U = \\ S \end{array}
\begin{array}{l} S \\ \bigcup_{q \in u} \dot{T}(q, a) \\ (m)[matrix of math nodes, row sep = \\ 2em, column sep = \\ 2em]\{q_1, q_2\}\{T(q_1, a), T(q_2, a)\}; [->, font = \\ [(m-1)e^{d-1}] \\ [(m-1)e^{d-1}] \end{array}
                              \bar{1})edgenode[auto](m-
                           1) eagend 1-
2); \overrightarrow{d} :=
first \land
                                    O_{\cdots}(a)
```