

Chapter 1

Finite automata minimization algorithms

1.1 Introduction

1.2 Brzozowski's algorithm

ε -free FA: $M_0 = (Q_0, V, T_0, \emptyset, S_0, F_0)$

to be minimized DFA: $M_2 = (Q_2, V, T_2, \emptyset, S_2, F_2)$

intermediate NFA: $M_1 = (Q_1, V, T_1, \emptyset, S_1, F_1)$

$$\text{NFA: } M_1 \rightarrow \text{DFA: } M_2, M_2 = \text{useful}_s \circ \text{subseopt}(M_1)$$

$$q_0, q_1 \in Q_1, Q_2 \subseteq \mathbb{P}(Q_1), \forall p \in Q_2, p = (q_0, q_1)$$

$$\vec{L}_{M_2}(p) = \vec{L}_{M_1}(q_0) \cup \vec{L}_{M_1}(q_1)$$

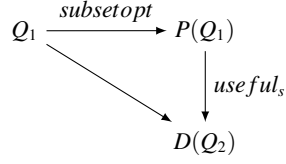
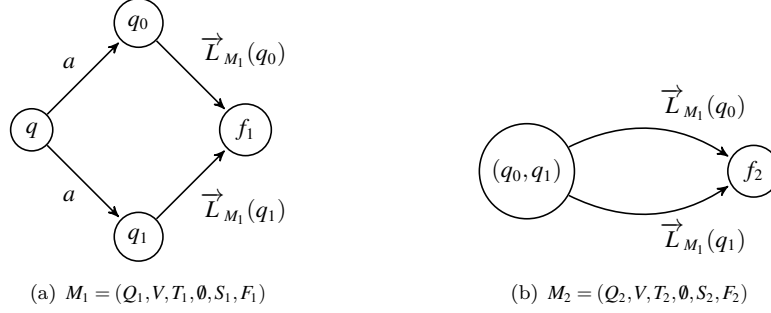
$$\Rightarrow$$

$$\vec{L}_{M_2}(p) = \bigcup_{q \in p} \vec{L}_{M_1}(q)$$

$$\Rightarrow$$

1.3 Minimization by equivalence of states

Let $M = (Q, V, T, F)$ be a deterministic finite automaton, where Q is a finite set of states, V is a finite set of input symbols, T is a mapping from $Q \times V$ into Q , and $F \subseteq Q$ is the set of final states. No initial state is

图 1.1: $M_2 = suseful_s \circ subsetopt(M_1)$ 图 1.2: $M_2 = suseful_s \circ subsetopt(M_1)$

specified since it is of no importance in what follows. The mapping T is extended to $T \times V^*$ in the usual manner where V^* denotes the set of all finite strings (including the empty string ϵ) of symbols from I .

Definition 1.1 (equivalent states). States s and t are said to be equivalent if for each $x \in V^*$, $T(s, x) \in F$ if and only if $T(t, x) \in F$.

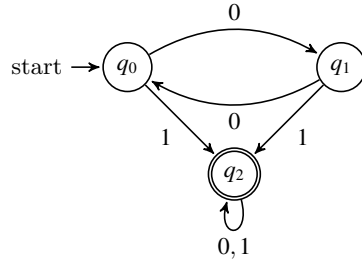
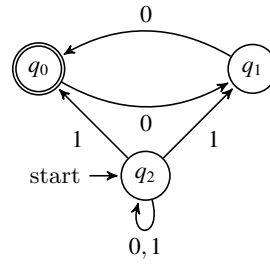
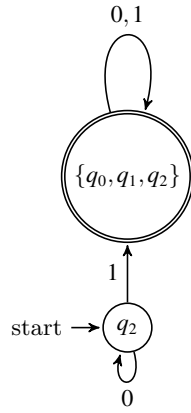
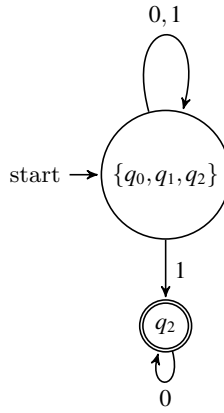
Example 1.1. Consider the automaton with $Q = \{a, b, c, d, e\}$, $V = 0, 1$, $F = \{d, e\}$, and T is given by the arcs of diagram of Fig. (1.7).

$\{a, b\}$ is not equivalent, since $T(a, 0) \in F$ but $T(b, 0) \notin F$.

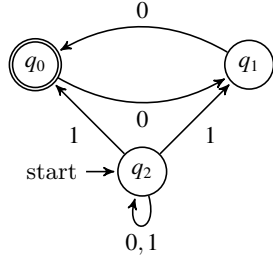
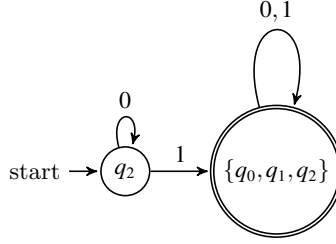
$\{d, e\}$ is not equivalent, since $T(d, 0) \in F$ but $T(e, 0) \notin F$

Sets of equivalent states: $\{a, c\}, \{b\}, \{d\}, \{e\}$

□

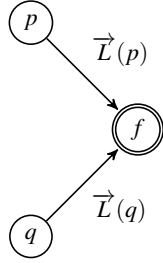
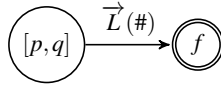
(a) $M_0 = (Q_0, V, T_0, \emptyset, S_0, F_0)$ (b) $M_0^R = (Q_0, V, T_0, \emptyset, S_0, F_0)^R = (Q_0, V, T^R, \emptyset, F_0, S_0)$ (c) $useful_s \circ subsetopt \circ R(M_0)$ (d) $M_1 = R \circ useful_s \circ subsetopt \circ R(M_0)$ 图 1.3: $M_1 = R \circ useful_s \circ subsetopt \circ R(M_0)$

start: $U = \{q_2\}$
 $u = q_2 : T(q_2, 0) = \{q_2\}, T(q_2, 1) = \{q_0, q_1, q_2\}$
 add new start to D , $D = \{q_2, \{q_0, q_1, q_2\}\}$
 $u = \{q_0, q_1, q_2\} : T(\{q_0, q_1, q_2\}, 0) = T(q_0, 0) \cup T(q_1, 0) \cup T(q_2, 0) = \{q_1\} \cup \{q_0\} \cup \{q_2\} = \{q_0, q_1, q_2\}$
 $T(\{q_0, q_1, q_2\}, 1) = T(q_0, 1) \cup T(q_1, 1) \cup T(q_2, 1) = \emptyset \cup \emptyset \cup \{q_0, q_1, q_2\} = \{q_0, q_1, q_2\}$

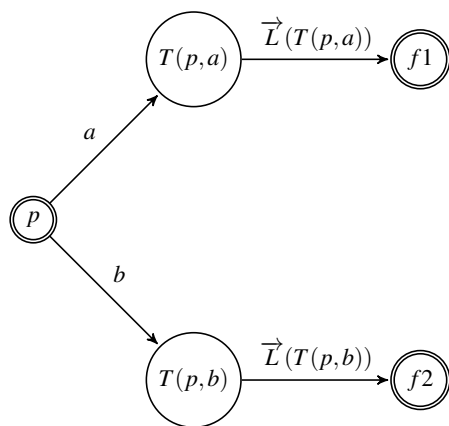
(a) M (b) $useful_s \circ subsetopt(M)$ 图 1.4: $useful_s \circ subsetopt(M)$

Equivalence relation $E \subseteq Q \times Q$

$(p, q) \in E \equiv (\vec{L}(p) = \vec{L}(q))$

(a) $(p, q) \in E$ (b) $(p, q) \in E$ 图 1.5: Equivalence relation $E \subseteq Q \times Q$

$$\vec{L}(p) = \bigcup_{a \in V} (\{a\} \cdot \vec{L}(T(p, a)) \cup \{\varepsilon \mid p \in F\})$$

图 1.6: $L(p)$

$\{a,b\}, \{d,e\}$ is not equivalent states.

Sets of equivalent states: $\{a,c\}, \{b\}, \{d\}, \{e\}$

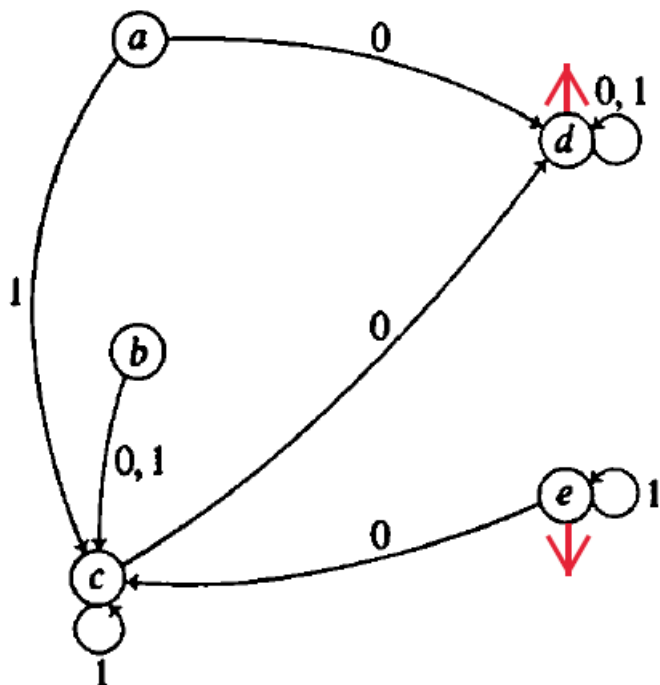


图 1.7: Finite state automaton