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Assigned Tasks

Main: done

Bonus Options: not attempted

Scheduler Definition (scheduler.H): defines helper utilities (ThreadNode and queue) for use in Scheduler implementation

```
struct ThreadNode {
   Thread* thread;
   ThreadNode* next;
   ThreadNode(Thread* _thread) {
      thread = _thread;
       next = NULL;
class queue ₹
   ThreadNode* head;
   ThreadNode* tail;
   queue();
   void add(Thread* _thread);
   Thread* pop();
    void remove(Thread* _thread);
   bool isEmpty();
   queue readyQueue;
   Thread* currentThread;
   Scheduler();
    /* Setup the scheduler. This sets up the ready queue, for example.
      end of quantum handler is installed in the constructor as well. */
      the CPU, and calls the dispatcher function defined in 'Thread.H' to
   virtual void resume(Thread* _thread);
   \slash {\rm *Add} the given thread to the ready queue of the scheduler. This is called
   virtual void add(Thread* _thread);
   virtual void terminate(Thread* _thread);
      of the thread.
```

Scheduler Implementation (scheduler.C): The queue helper class is implemented first...

```
queue::queue() {
    head = nullptr;
    tail = nullptr;
void queue::add(Thread* _thread) {
   ThreadNode* newNode = new ThreadNode(_thread);
    if (head == nullptr) {
       head = newNode;
       tail = newNode;
       tail->next = newNode;
       tail = newNode;
Thread* queue::pop() {
   if (head == nullptr) {
    Thread* _thread = head->thread;
   ThreadNode* temp = head;
   head = head->next;
   if (head == nullptr) {
     tail = nullptr;
    delete temp;
    return _thread;
void queue::remove(Thread* _thread) {
   ThreadNode* current = head;
    ThreadNode* previous = nullptr;
    while (current != nullptr) {
       if (current->thread == _thread) {
          if (previous == nullptr) {
             head = current->next;
           } else {
             previous->next = current->next;
           if (current == tail) {
            tail = previous;
           delete current;
       previous = current;
       current = current->next;
bool queue::isEmpty() {
   return head == nullptr;
```

... followed by the Scheduler class itself using the queue class:

```
Scheduler::Scheduler() {
    currentThread = nullptr;
}

void Scheduler::yield() {
    if (!readyQueue.isEmpty()) {
        currentThread = readyQueue.pop();
        Thread::dispatch_to(currentThread);
    }
}

void Scheduler::resume(Thread* _thread) {
    readyQueue.add(_thread);
}

void Scheduler::add(Thread* _thread) {
    readyQueue.add(_thread);
}

void Scheduler::terminate(Thread* _thread) {
    readyQueue.remove(_thread);
}
```

Thread changes (thread.C): Implemented the thread_shutdown function

- (Uses a static scheduler variable (set in kernel.C) to access it)
- Releases the current thread
- Terminates current thread in the scheduler (removes it from the queue)
- Yields to the scheduler (to resume the next thread in the queue and continue as normal)

```
static void thread_shutdown() {
   /* This function should be called when the thread returns from the thread function.
   assert(current_thread != 0);
   current_thread->Release();
   Console::puts("Thread ");
   Console::puti(current_thread->ThreadId());
   Console::puts(" is terminating.\n");
   Scheduler *scheduler = current_thread->get_scheduler();
   assert(scheduler != nullptr);
   scheduler->terminate(current_thread);
  Console::puts("Thread ");
   Console::puti(current_thread->ThreadId());
   Console::puts(" is terminated.\n");
  scheduler->yield();
   Console::puts("Thread ");
   Console::puti(current_thread->ThreadId());
   Console::puts(" is terminated and yielded.\n");
```

TESTING

I relied on the test framework provided in kernel.C, which revealed a bug along the way that took a while to figure out (I wasn't quite yielding correctly). I added some extra print statements along the way as I was debugging.