# Homework 3: Multi-Agent Search

Please keep the title of each section and delete examples.

### Part I. Implementation (5%):

• Part 1:

```
result = self.selectBest(gameState, 0, 0)
   return result[1]
def selectBest(self, gameState, index, depth):
    if len(gameState.getLegalActions(index))=0 or depth=self.depth:
       return gameState.getScore(), "
       return self.max_value(gameState, index, depth)
       return self.min_value(gameState, index, depth)
def max_value(self, gameState, index, depth):
    v = float('-inf')
       successor = gameState.getNextState(index, a)
       successor_index = index + 1
successor_depth = depth
        if successor_index=gameState.getNumAgents():
           successor depth += 1
        cur_v = self.selectBest(successor, successor_index, successor_depth)[0]
```

```
min_value(state):
    get all legal actions and save into "actions"
    for each a in actions:
        let successor be the child state
            get the least value of selectBest(successor)
    return min_value and its action

"""

def min_value(self, gameState, index, depth):
    actions = gameState.getLegalActions(index)
    v = float('inf')
    min_a = ""
    for a in actions:
        successor = gameState.getNextState(index, a)
        successor_index = index + 1
        successor_depth = depth
        if successor_index = gameState.getNumAgents():
            successor_index = 0
            successor_depth += 1
            cur_v = self.selectBest(successor, successor_index, successor_depth)[0]
        if cur_v < v:
            v = cur_v
             max_a = a

    return v, min_a
    # End your code (Part 1)</pre>
```

#### Part 2:

#### • Part 3:

```
# Begin your code (Part 3)
# call function "selectBest"
result = self.selectBest(gameState, 0, 0)
return result[1]

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**selectBest(state):
no-actions: return score
pacman: return max-value(state)
ghost: return expected_value(state) # ghost will move stochastically

***

**def selectBest(self, gameState, index, depth):
    if len(gameState.getLegalActions(index)) = 0 or depth=self.depth:
        return self.evaluationFunction(gameState), "*
    if index=0: # pacman index = 0
        return self.max value(gameState, index, depth)
else: # expectionax-sphost index > 1
        return self.expected_value(gameState, index, depth)

****

***

**def max_value(self, gameState, index, depth):
    actions = gameState.getLegalActions(index)
    v = float('-inf')
    max_a = "
    for a in actions:
    successor = gameState.getNextState(index, a)
    successor = gameState.getNextState(index, a)
    successor_index = index + 1
    successor_index = gameState.getNumAgents():
    successor_index = gameState.getNumAgents():
    successor_depth + depth
    if successor_idex = 0
    successor_depth + 1
    cur_v = self.selectBest(successor, successor_index, successor_depth)[0]
    if cur_v > v:
        v = cur_v
        max_a = a
        return v, max_a
```

#### Part 4:

## Part II. Results & Analysis (5%):

