

+ Real-Time Interactive Segmentation with Superpixel Pre-Segmentation

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+ Outline

- Introduction
 - Interactive Image Segmentation
 - Graph Cut Segmentation
 - Superpixel
- Proposed Method
- Experimental Results
- Discussion
- Conclusion and Future Work

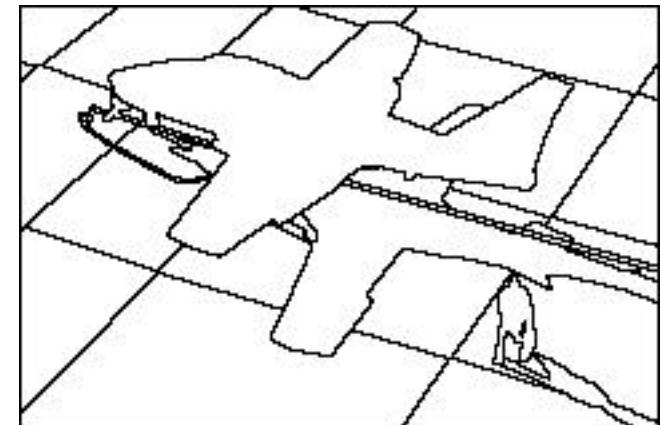
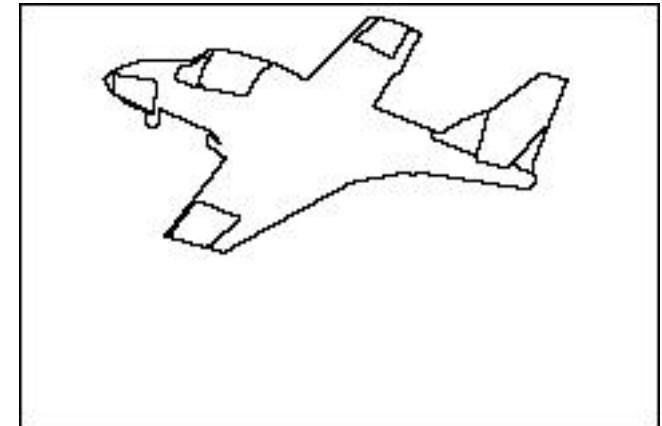
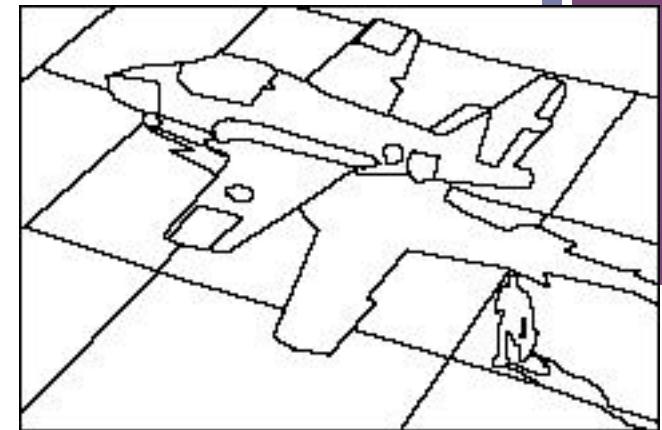
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Image Segmentation

- Unsupervised segmentation
- Semi-supervised segmentation
(Interactive Segmentation)
- (almost completely) Manual segmentation

+ Image Segmentation

■ Unsupervised segmentation



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Image Segmentation

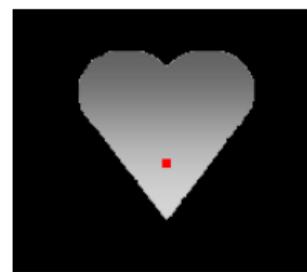
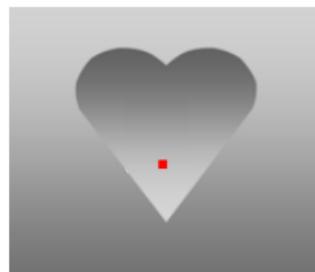
■ Interactive Segmentation





Interactive Segmentation

■ Different Ways of User Interaction





Interactive Segmentation

■ Different Ways of User Interaction

- provide function for correction at a finer scale
- apply matting technique along segmentation border



Red marker: background

White marker: foreground

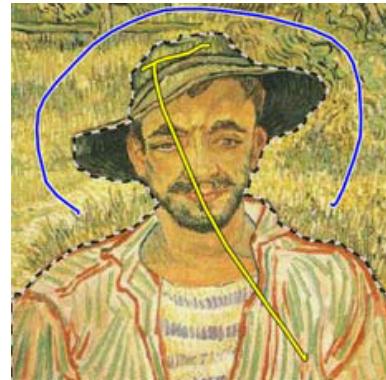
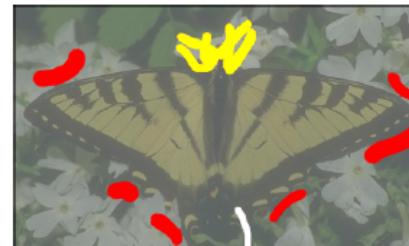
Yellow marker: trimap for matting



Interactive Segmentation

■ Different Ways of User Interaction

- provide function for correction at a finer scale
- apply matting technique along segmentation border



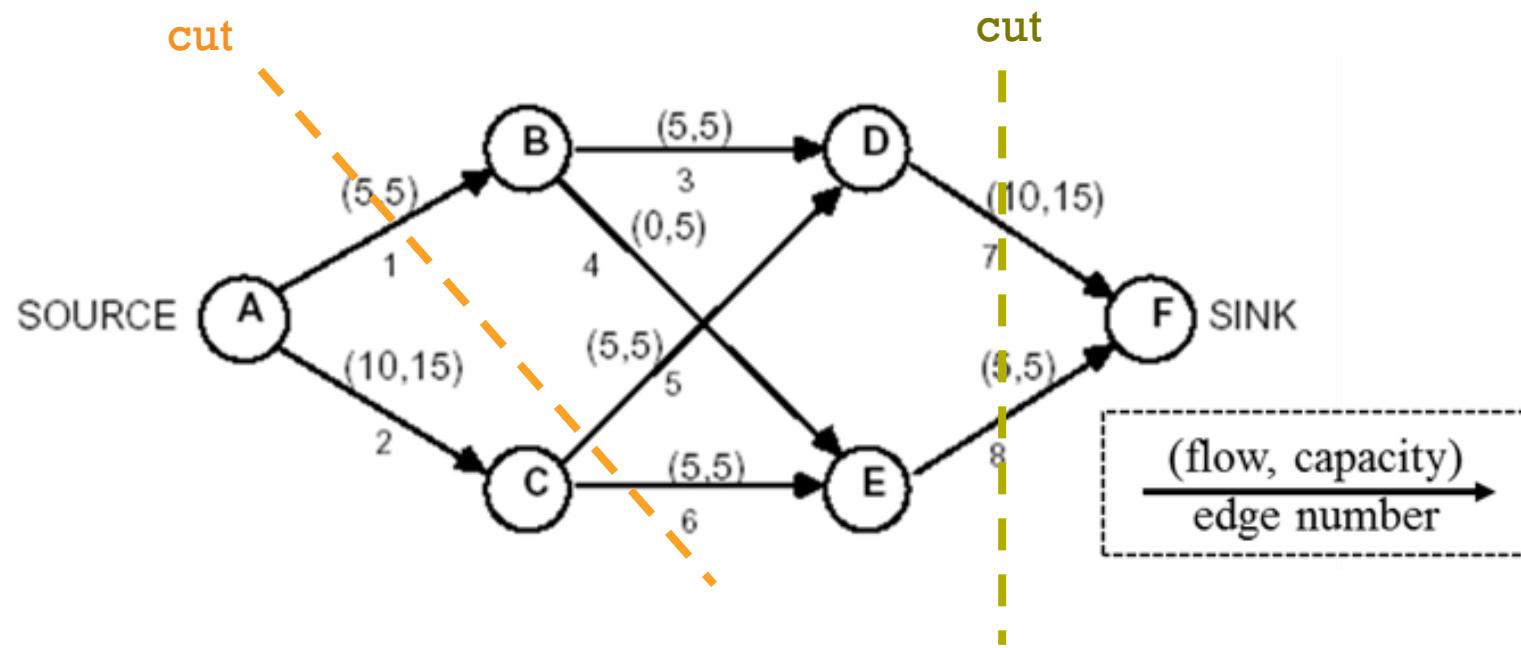
Yellow marker: foreground
Blue marker: background



Interactive Segmentation

■ Graph Cut Based Interactive Segmentation

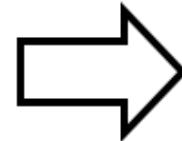
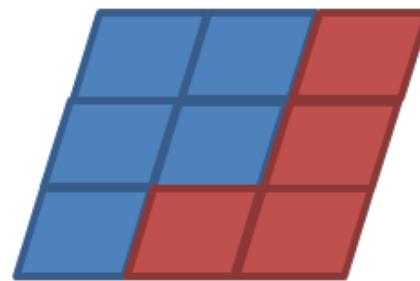
- Graph $G = (V, E)$ -- V : vertex set, E : edge set
- Flow Network : additional vertex S (source) and T (sink)
- Max-Flow/Min-Cut Algorithm



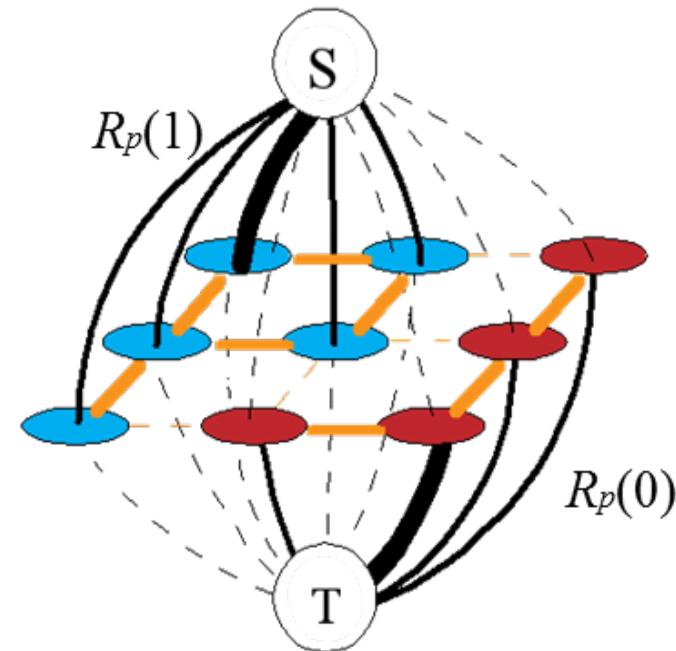


Graph Cut Based Interactive Segmentation

- Graph $G = (V, E)$ -- V : vertex set, E : edge set
- Flow Network : additional vertex S (source) and T (sink)
- Max-Flow/Min-Cut Algorithm



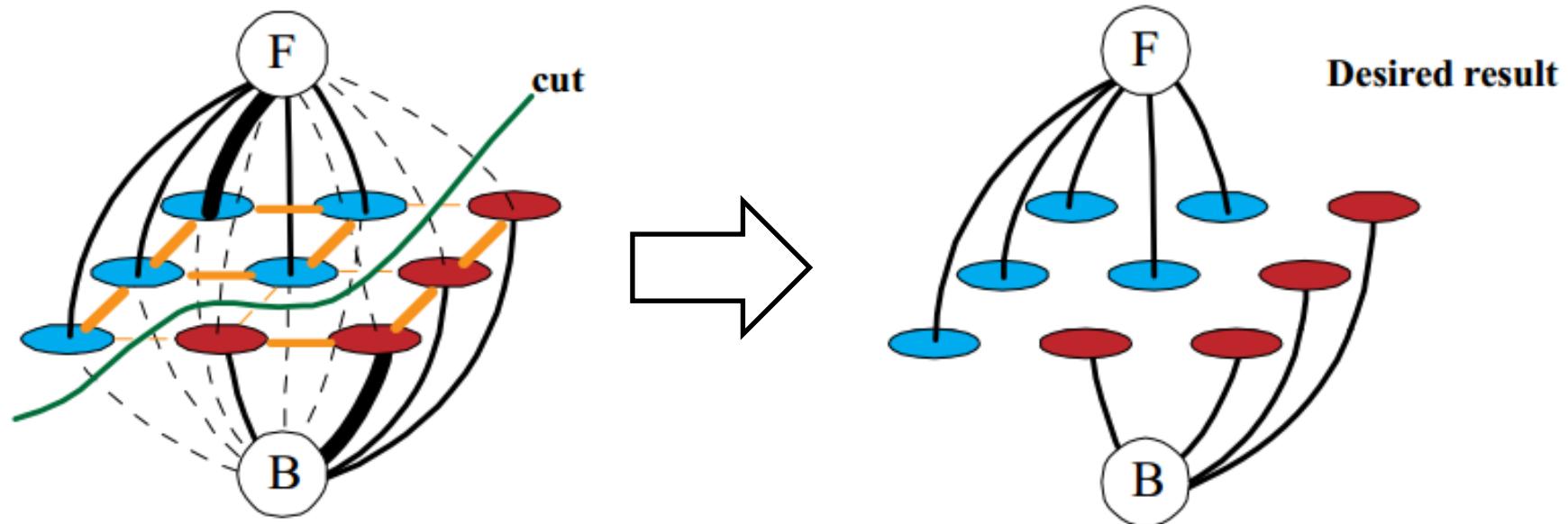
Original Image





Graph Cut Based Interactive Segmentation

- Graph $G = (V, E)$ -- V : vertex set, E : edge set
- Flow Network : additional vertex S (source) and T (sink)
- Max-Flow/Min-Cut Algorithm





Graph Cut Based Interactive Segmentation

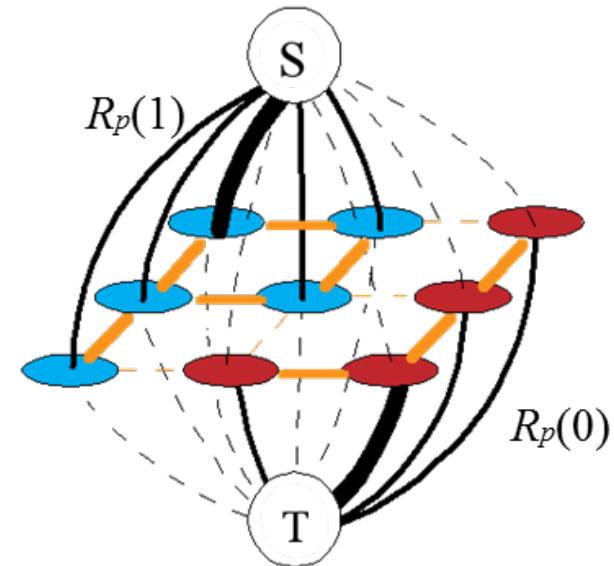
- solve the labeling problem by minimizing the energy function.

$$E(L) = \sum_p R_p(l_p) + \lambda \cdot \sum_{\{p,q\} \in N} B_{p,q} \cdot \delta(l_p, l_q)$$

- $R_p(l_p)$: regional term
- $B_{p,q}$: boundary term
- l_p : label of node p

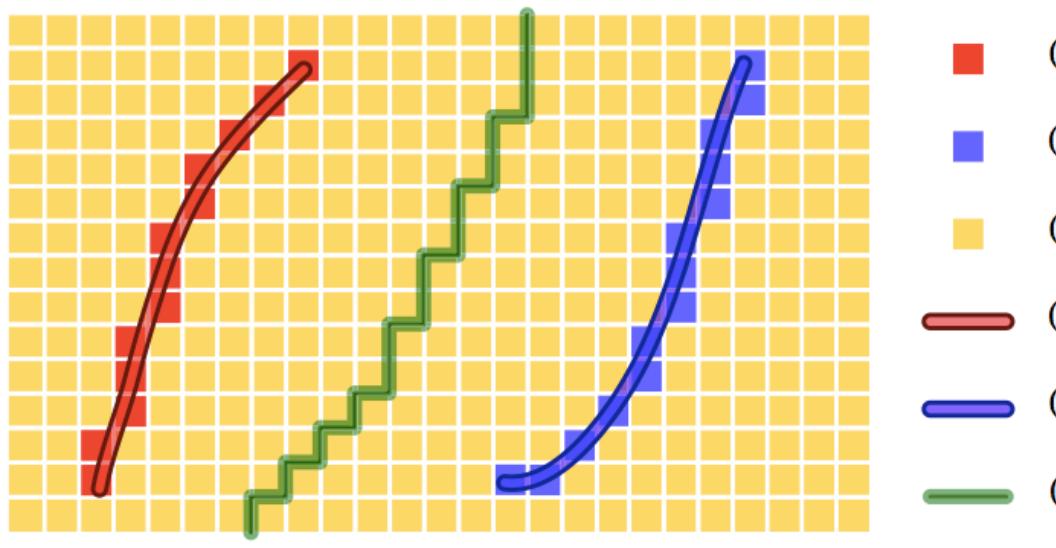
$$\delta(l_p, l_q) = \begin{cases} 1 & \text{if } l_p \neq l_q \\ 0 & \text{if } l_p = l_q \end{cases}$$

- N : neighborhood





Graph Cut Based Interactive Segmentation



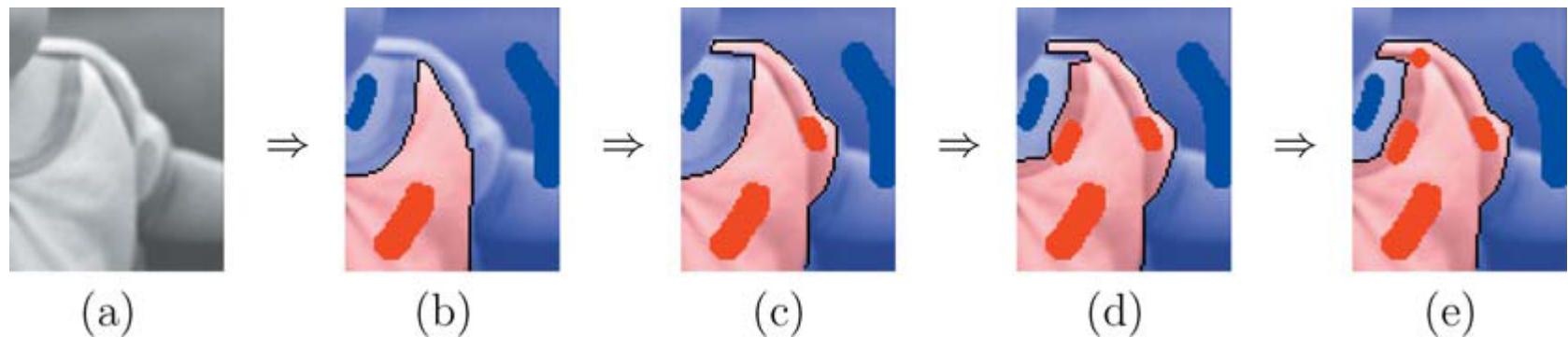
(a) Foreground seeds \mathcal{F}
(d) Foreground marker

(b) Background seeds \mathcal{B}
(e) Background marker

(c) Uncertain regions \mathcal{U}
(f) Graph cut result

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Graph Cut Based Interactive Segmentation



Red marker: foreground

Blue marker: background



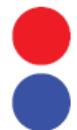
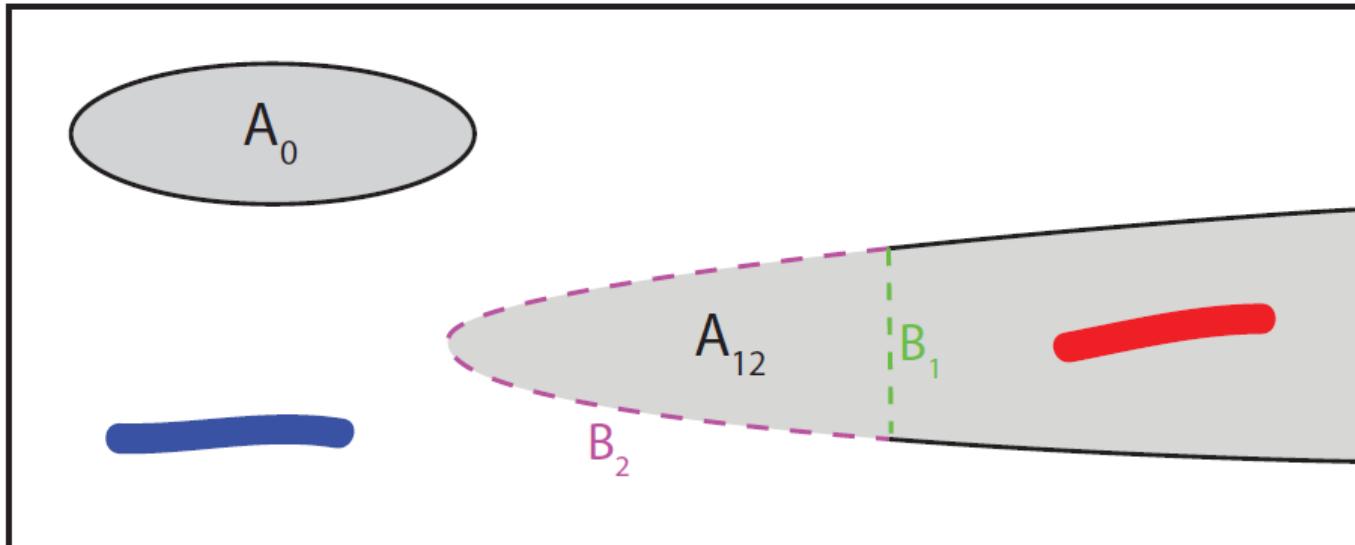
Graph Cut Based Interactive Segmentation

■ Issues in Graph Cut Algorithm

■ Shrinking Bias

$$E(L) = \sum_p R_p(l_p) + \lambda \cdot \sum_{\{p,q\} \in N} B_{p,q} \cdot \delta(l_p, l_q)$$

λ is a magical constant



Foreground Stroke



Background Stroke

— - - - Shortcut B_1

- - - - Desired Boundary B_2

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Graph Cut Based Interactive Segmentation

- Issues in Graph Cut Algorithm
 - Shrinking Bias





Graph Cut Based Interactive Segmentation

- Issues in Graph Cut Algorithm
 - Shrinking Bias
 - Vulnerability to Noise
 - Efficiency



Graph Cut Based Interactive Segmentation

- Extensions of Graph Cut Algorithm
 - Interactive based
 - Shape prior based
 - Speed-up based



Superpixel

- Definition: a perpetually uniform region in the image





Superpixel

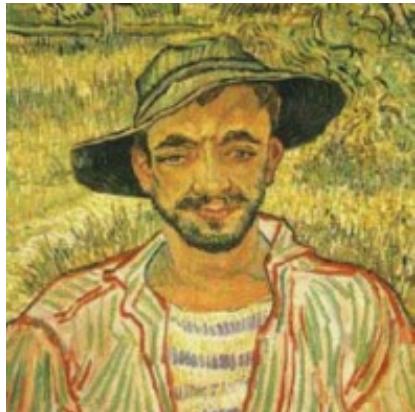
■ Evaluated by :

- Boundary Recall: measures the percentage of the natural boundaries recovered by the superpixel boundaries
- Undersegmentation Error: compares segment areas to measure to what extend superpixels flood over the ground truth segment borders.
- Running Time

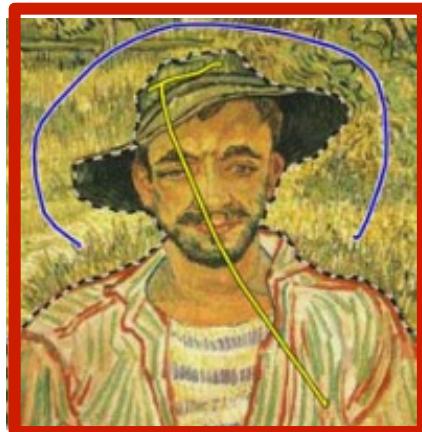


Interactive Segmentation

■ Lazy Snapping [Li et al. 2004]



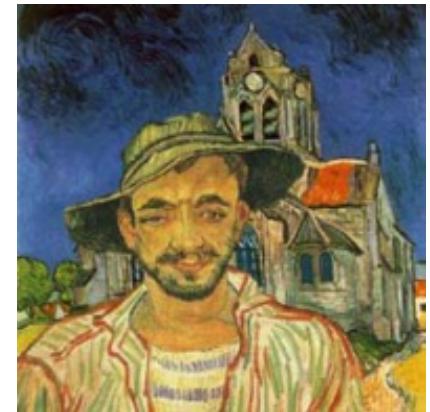
(a) Input image



(b) Object Marking



(c) Boundary editing

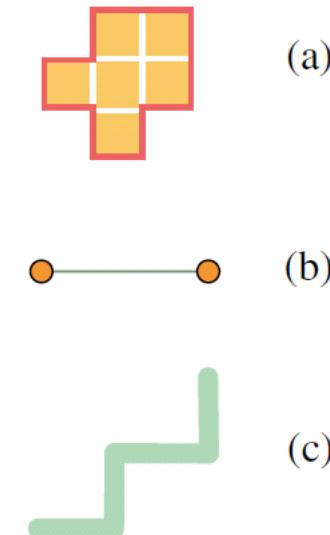
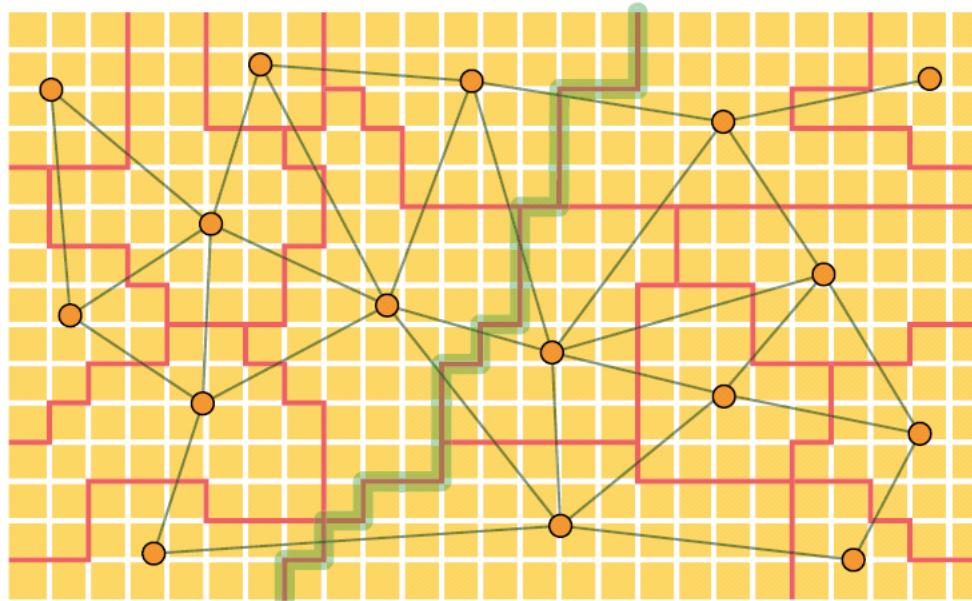


(d) Output composition



Interactive Segmentation

- Lazy Snapping [Li et al. 2004]
- Use watershed to do pre-segmentation





Proposed Method

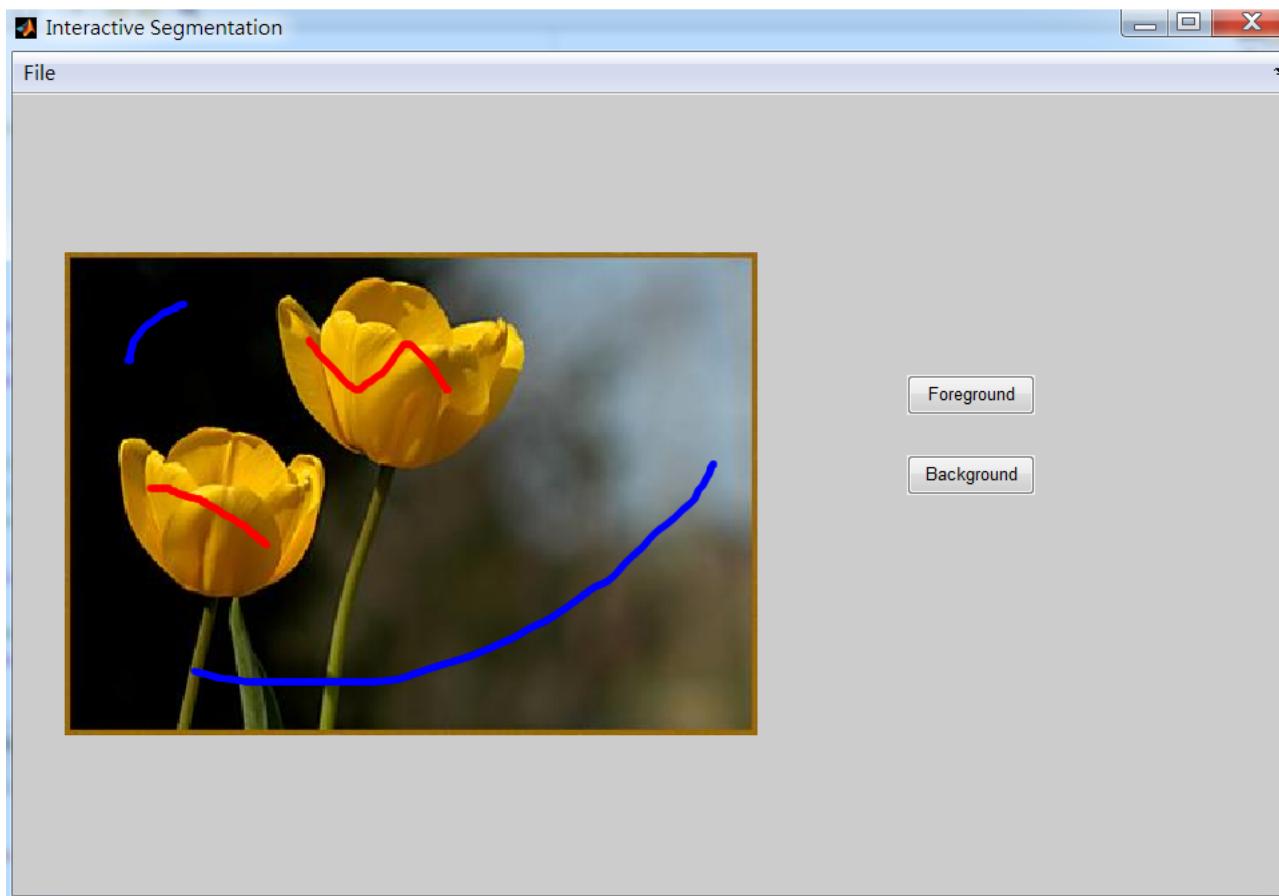
■ Observation

- User experience values short response time
- Adopt superpixel pre-segmentation :
 - should use superpixel method with higher quality



Proposed Method

■ Prototype UI



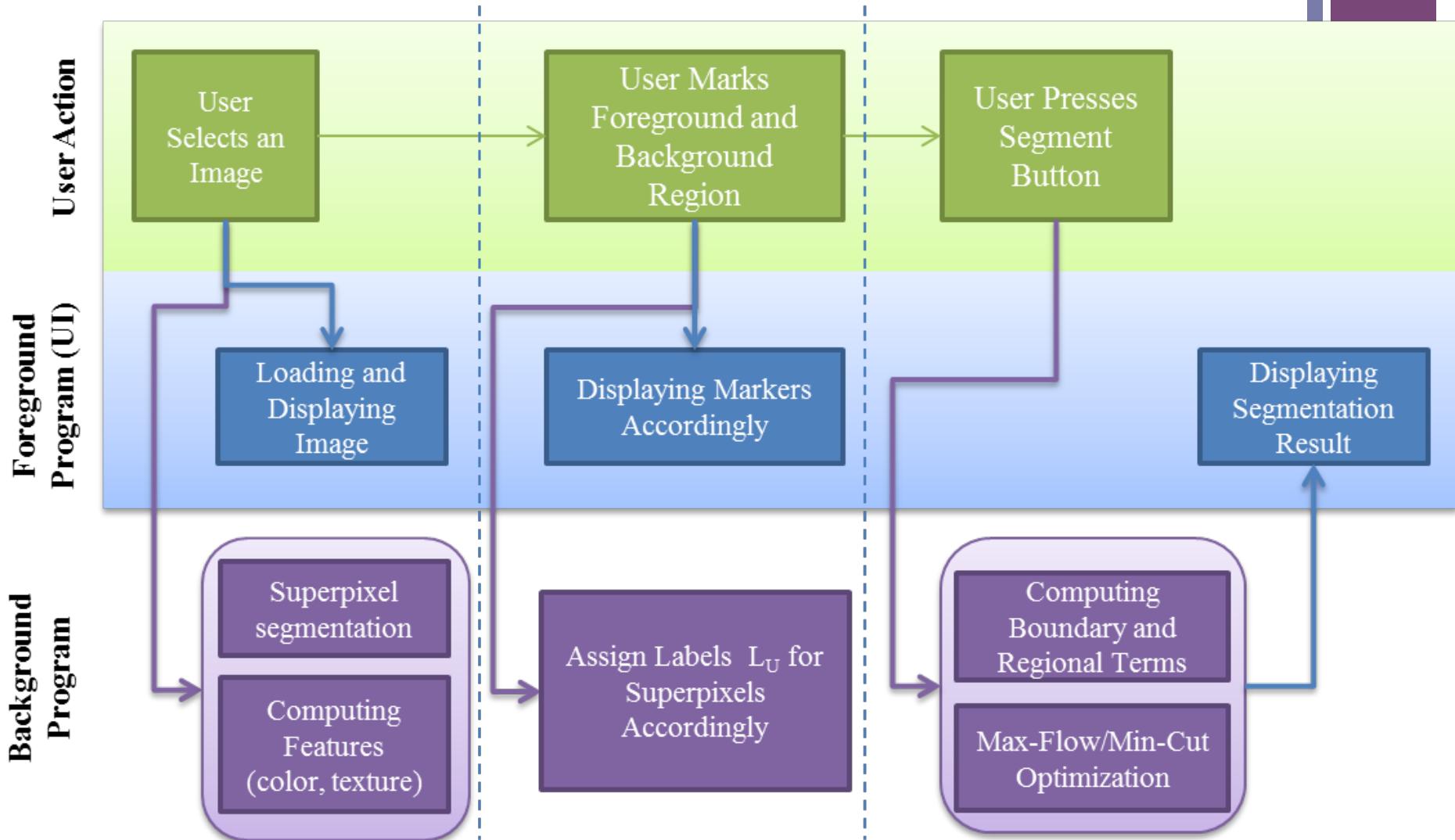


Proposed Method



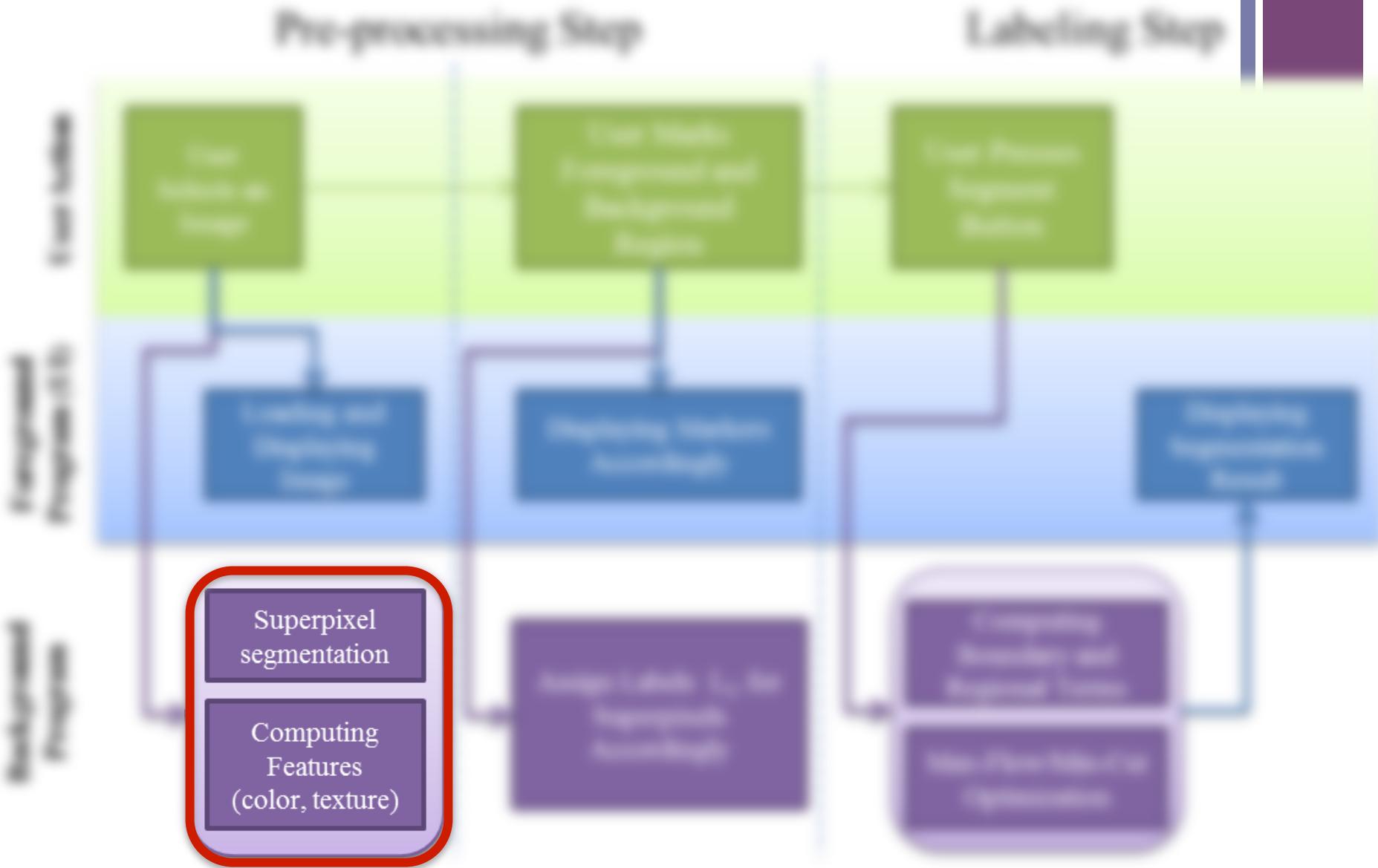
Pre-processing Step

Labeling Step





Proposed Method



Proposed Method

Superpixel
segmentation

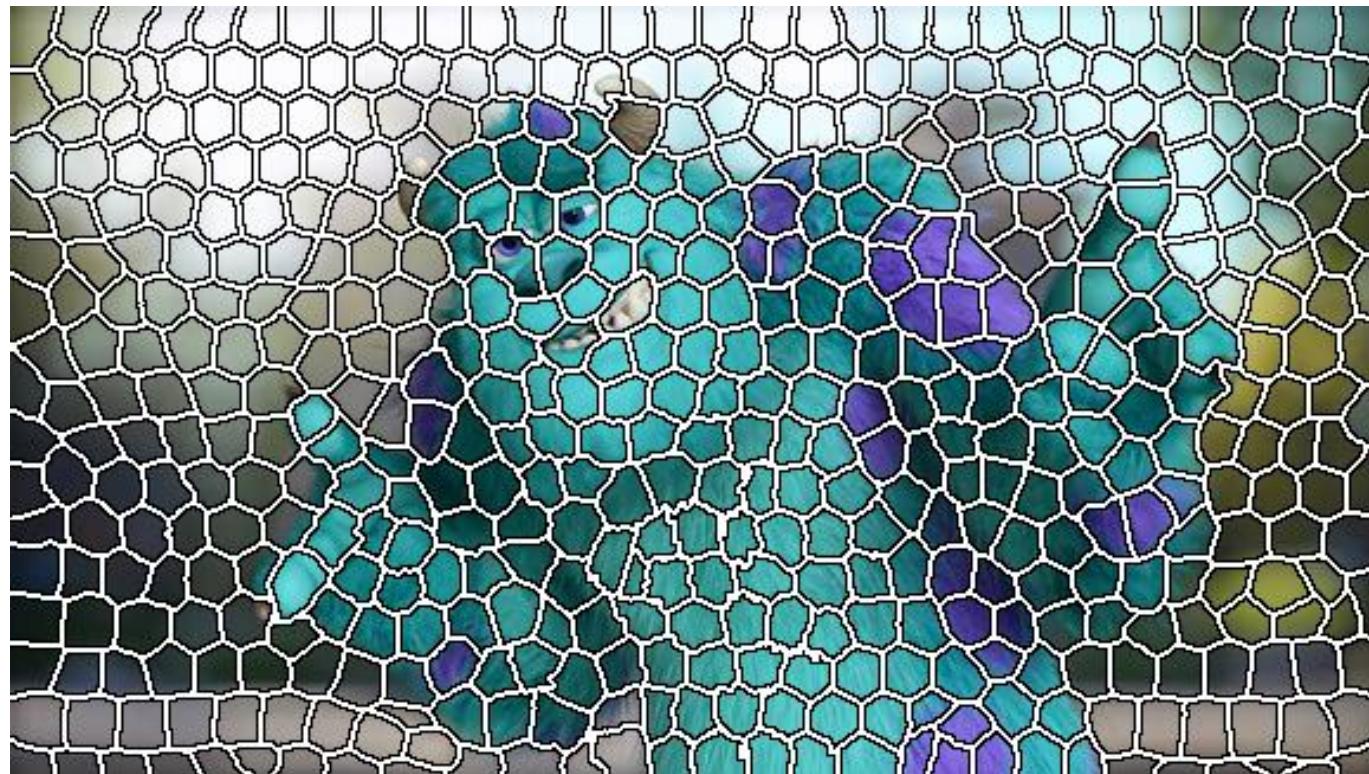
- Desired property
 - Given superpixel number control
 - Produce superpixels of similar size
 - Short processing time
- Consider all the factors above, SLIC (SLICO) and ERS would be our best candidates.

Proposed Method

Superpixel
segmentation

- Candidates

- Simple Linear Iterative Clustering – Zero (SLICO)



Proposed Method

Superpixel
segmentation

■ Candidates

■ Simple Linear Iterative Clustering – Zero (SLIC0)



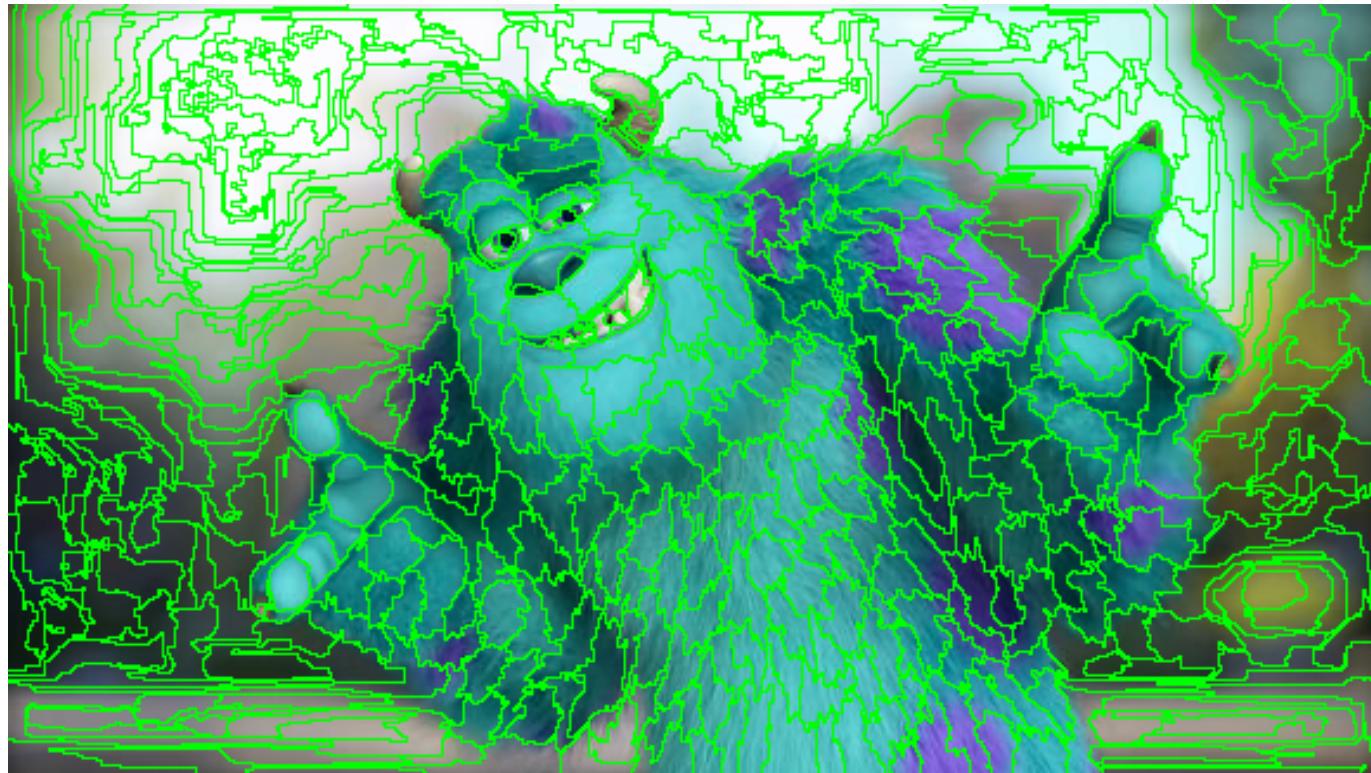
Proposed Method

Superpixel
segmentation

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■ Candidates

- Entropy Rate Superpixel (ERS)

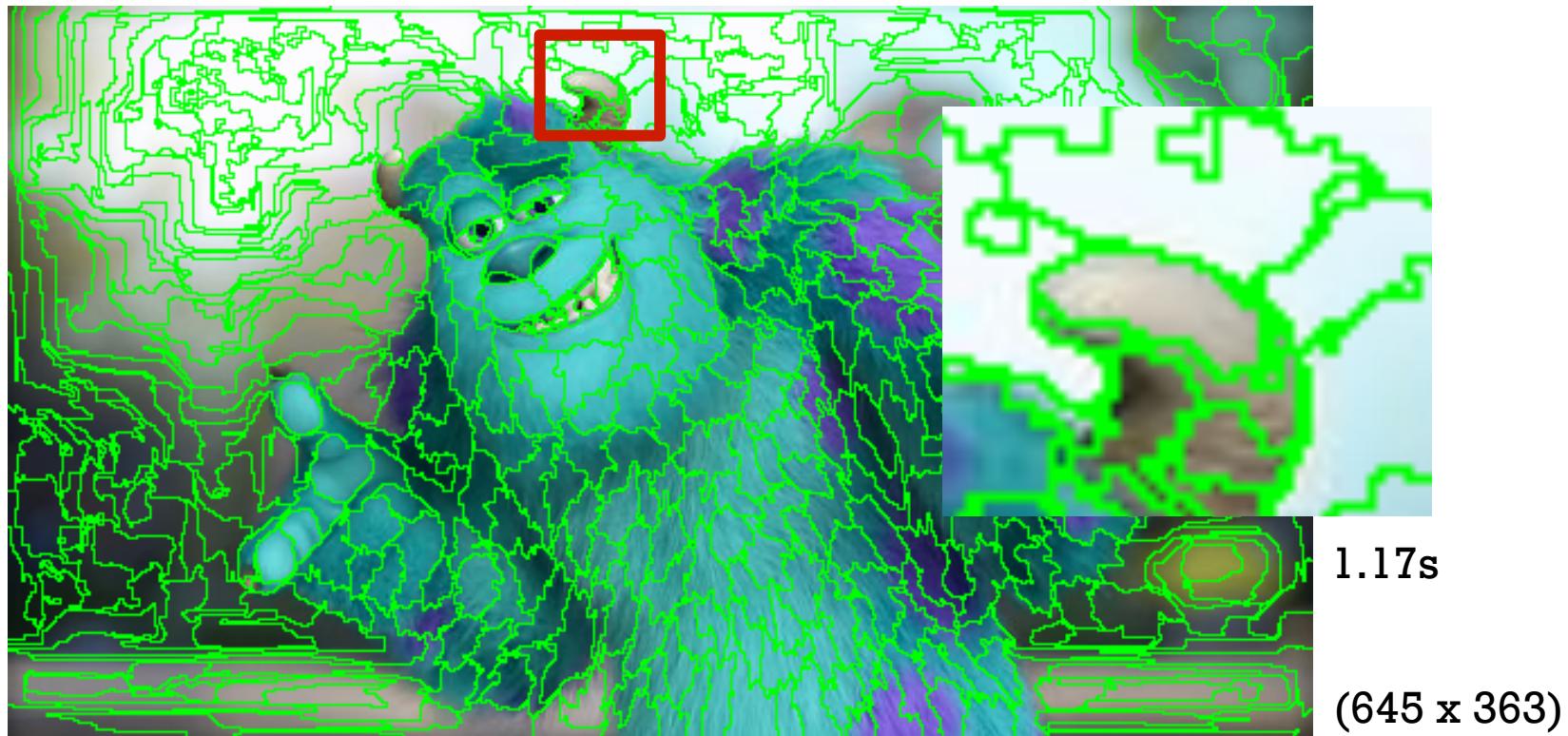


Proposed Method

Superpixel
segmentation

Candidates

Entropy Rate Superpixel (ERS)



Proposed Method

Compute
Features
(color, texture)

■ Color Feature

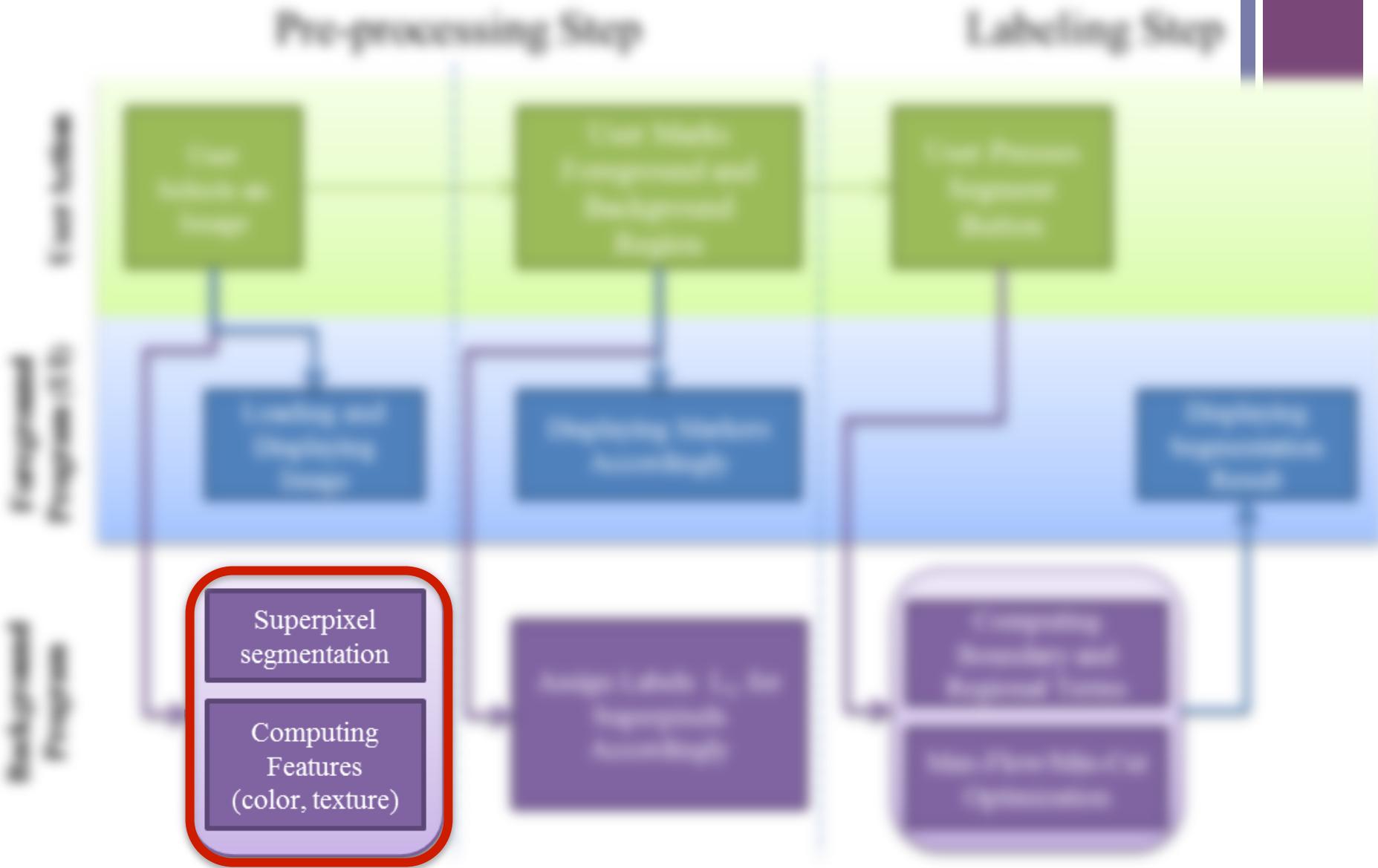
- mean value in LAB space (dim = 3)

■ Texture Feature

- mean value of Log-Gabor response
- scale = 2, orientation = 4 (dim = 8)

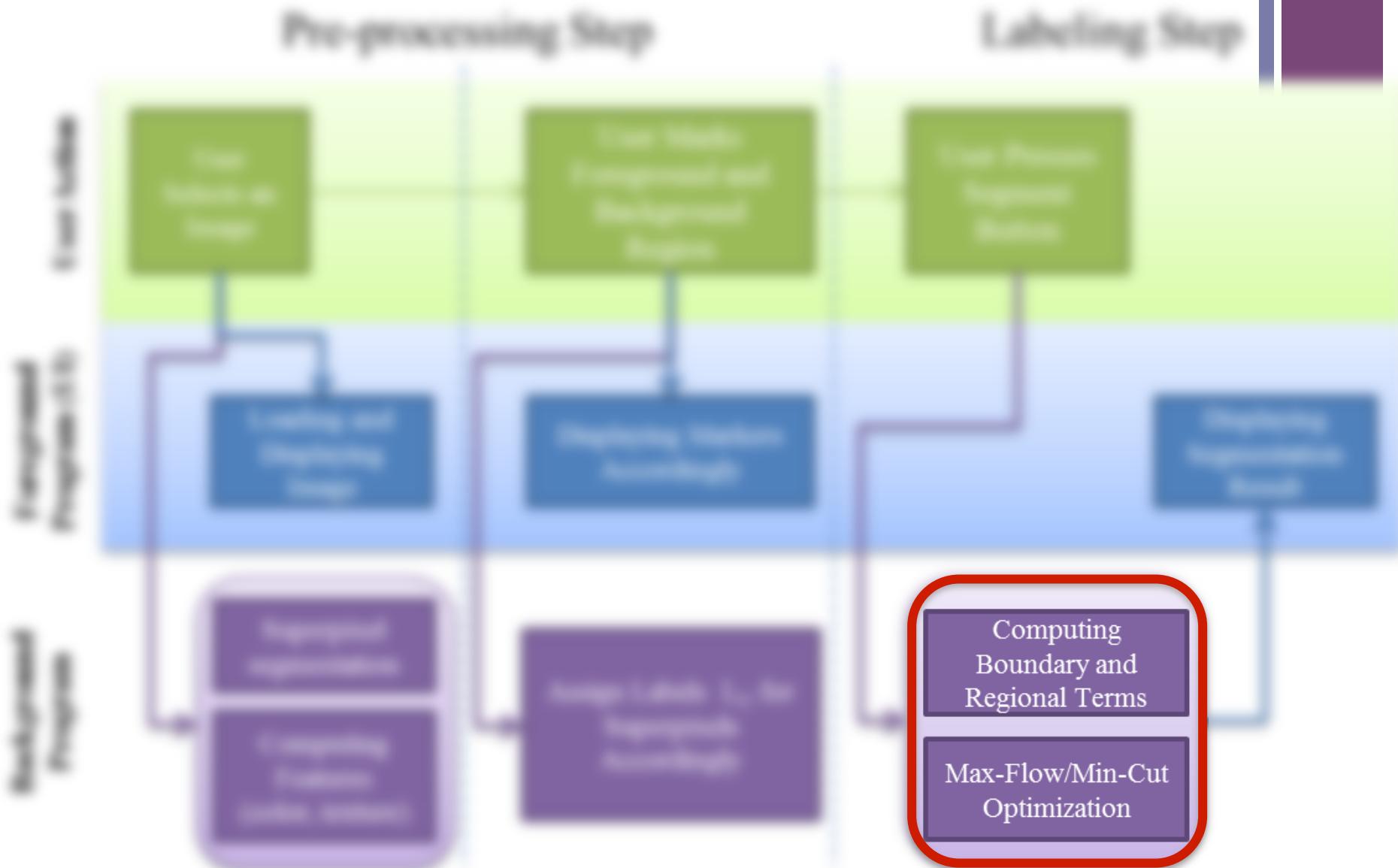


Proposed Method





Proposed Method



Proposed Method

Compute
B and *R*

■ Define Regional Term in Graph Cut Algorithm

$$E(L) = \sum_p R_p(l_p) + \lambda \cdot \sum_{\{p,q\} \in N} B_{p,q} \cdot \delta(l_p, l_q)$$

■ Color distance

$$dC \downarrow j \uparrow F = \min_{\tau} n \| C(j) - C \downarrow n \uparrow F \|$$

$$dC \downarrow j \uparrow B = \min_{\tau} n \| C(j) - C \downarrow n \uparrow B \|$$

- $C(j)$: mean [lab] value of superpixel j
- $C \downarrow n \uparrow F$: mean [lab] value of foreground superpixel j

■ Texture distance

$$dT \downarrow j \uparrow F = \min_{\tau} n \| T(j) - T \downarrow n \uparrow F \|$$

$$dT \downarrow j \uparrow B = \min_{\tau} n \| T(j) - T \downarrow n \uparrow B \|$$

- $C(j)$: mean Log-Gabor value of superpixel j
- $T \downarrow n \uparrow F$: mean Log-Gabor value of foreground superpixel j



Proposed Method

Compute
 B and R

■ Define Regional Term in Graph Cut Algorithm

$$E(L) = \sum_p R_p(l_p) + \lambda \cdot \sum_{\{p,q\} \in N} B_{p,q} \cdot \delta(l_p, l_q)$$

Label 1 : foreground
Label 0 : background

$$l_i = 1$$

$$l_i = 0$$

$$i \in F$$

$$0$$

$$\infty$$

$$i \in B$$

$$\infty$$

$$0$$

$$i \in U$$

$$\frac{dC_i^F}{dC_i^F + dC_i^B} + \frac{dT_i^F}{dT_i^F + dT_i^B} \cdot \alpha$$

$$\frac{dC_i^B}{dC_i^F + dC_i^B} + \frac{dT_i^B}{dT_i^F + dT_i^B} \cdot \alpha$$

- B : background
- F : foreground
- $U = V \setminus \{F \cup B\}$

- dC : color distance
- dT : texture distance

Proposed Method

Compute
 B and R

■ Define Boundary Term in Graph Cut Algorithm

$$E(L) = \sum_p R_p(l_p) + \lambda \cdot \sum_{\{p,q\} \in N} B_{p,q} \cdot \delta(l_p, l_q)$$

$$B_{p,q} = \frac{1}{\|C(p) - C(q)\|^2 + 1} \quad [\text{Li et al. 2004}]$$

- $R_p(l_p)$: regional term
- $B_{p,q}$: boundary term
- l_p : label of node p

$$\delta(l_p, l_q) = \begin{cases} 1 & \text{if } l_p = l_q \\ 0 & \text{if } l_p \neq l_q \end{cases}$$

Proposed Method

Max-Flow/Min-Cut
Optimization

- Max-Flow/Min-Cut Optimization
 - [Boykov & Kolmogorov 2004]

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Experimental Results

■ Motivation Revisited



*Node Ratio = #pixels/
#superpixels*



Ideal



Ours



Experimental Results

Motivation Revisited



step image size	Superpixel (Node Ratio = 100)	Computing Features	B & R	Max-Flow/ Min-Cut	Total Delay
645x363	0.182s (1.17)	1.217s	0.044s	0.018s	0.062s

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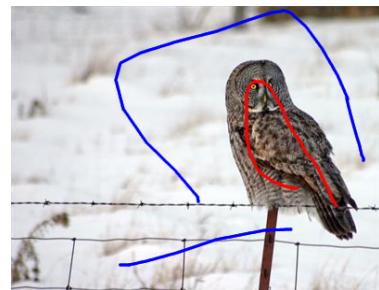
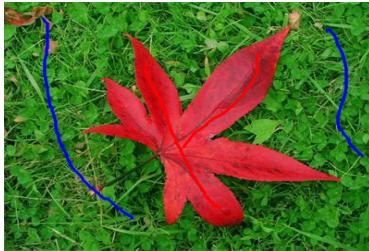
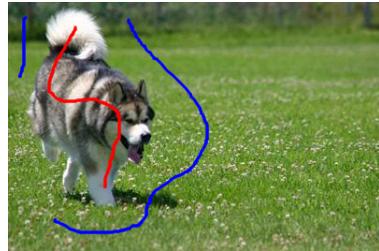
Experimental Results



step image size	Superpixel (Node Ratio = 200)	Feature extraction	B & R	Graph Cut	Total Delay
1024x768	0.896s (4.96)	1.021s	0.120s	0.053s	0.173s

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Experimental Results





Experimental Results

■ Time Delay Comparison with Lazy Snapping

Li et al. [2004]

Image Size	Node Ratio	Response Time	Response Time without Pre-segmentation
408x600	11	0.12	0.57s
440x800	11	0.21	1.39s
1024x768	21	0.25	1.82s
1147x768	19	0.22	3.56s

Ours

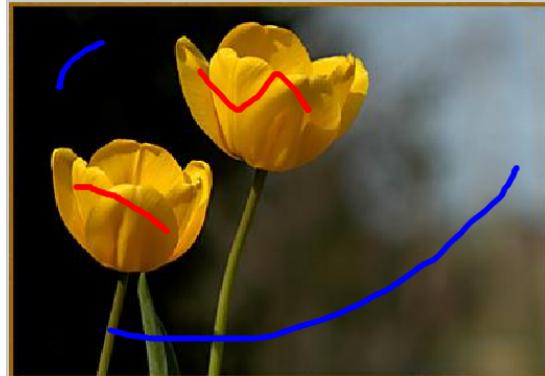
Image Size	Node Ratio	Response Time
645x363	100	0.062s
1024x768	200	0.173s



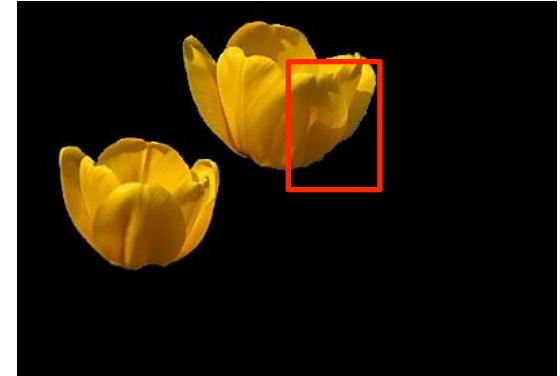
Experimental Results

■ Visual Comparison with Lazy Snapping

■ Object has distinct color to background



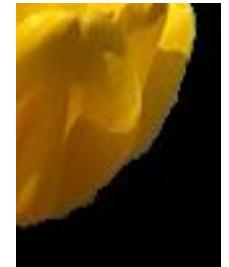
[Li et al. 2004]



Ours



(SLICO,
Node Ratio
= 300)

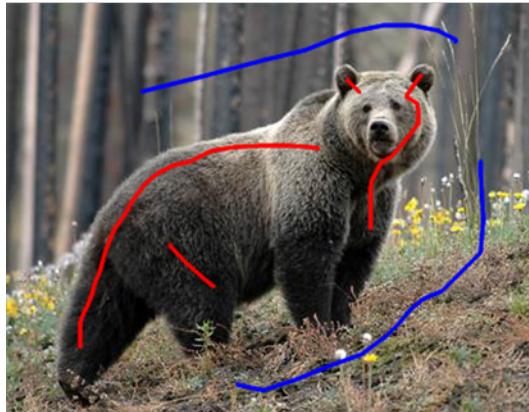




Experimental Results

■ Visual Comparison with Lazy Snapping

■ Object has similar color to background



[Li et al. 2004]



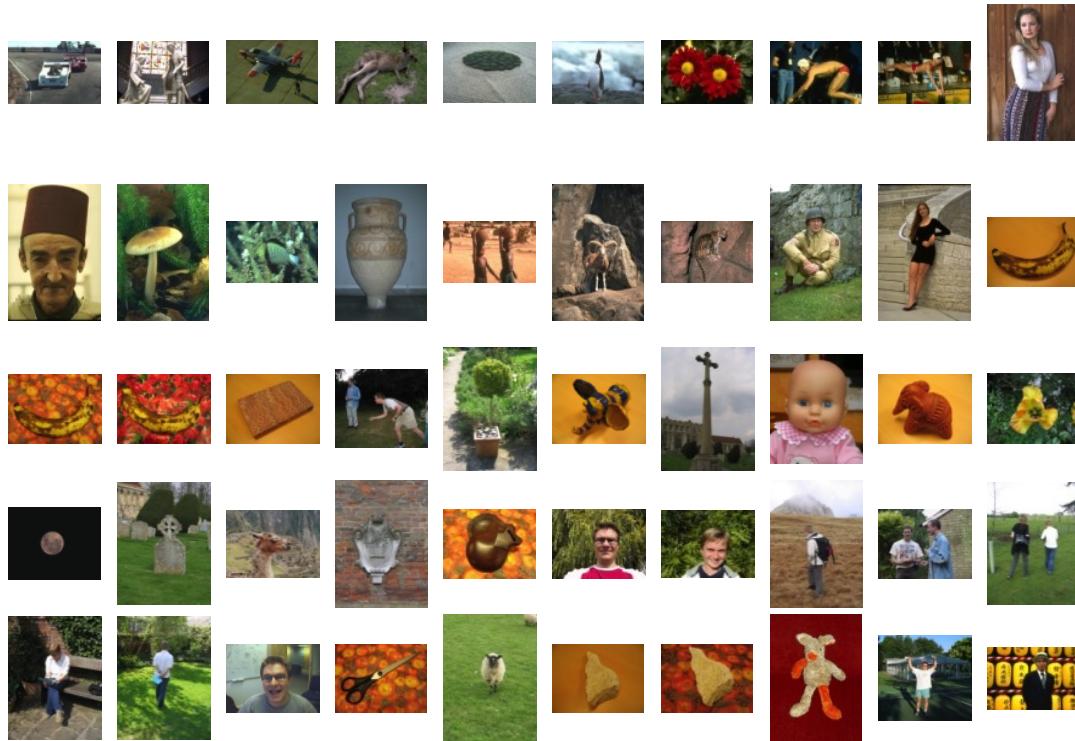
Ours

(SLICO,
Node Ratio = 300)



Experimental Results

■ GrabCut Database [Rother et al. 2004]

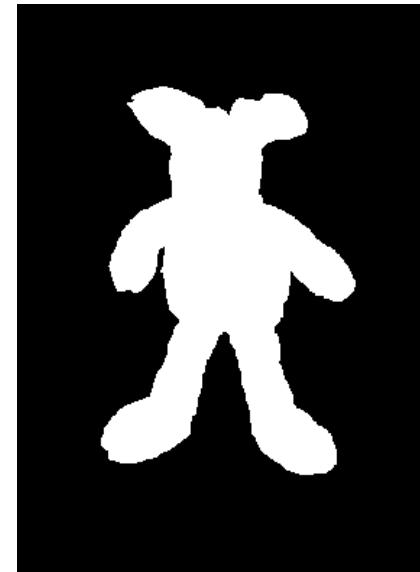




Experimental Results

■ GrabCut Database [Rother et al. 2004]

■ *Error Rate = #misclassified pixels/#unknown area pixels*





Experimental Results

- GrabCut Database [Rother et al. 2004]
 - *Error Rate = #misclassified pixels/#unknown area pixels*
 - *Achievable Segmentation Error(ASE)*
=the lowest error rate we can achieve based on superpixel segmentation result
 - *Node Ratio = #pixels/#superpixels*



Experimental Results

Segmentation Model	Error Rate(%)	Response Time
Li et al. (Lazy Snapping) [2004]	15.1	*0.005s-1.129s, mean 0.339
Grady (Random Walker) [2006]	10.9	0.15s - 0.83s, mean 0.47s (C++ with MATLAB wrapper)
Couprise et al. (Powerful Watershed) [2009]	10.4	0.12s - 0.36s, mean 0.25s (C++)
Our Method without using texture information (ERS, Node Ratio = 100)	8.2	-
Proposed Method (ERS, Node Ratio = 100)	7.7	0.020s – 0.101s, mean 0.058s (C++/MATLAB)
Graph Cut (Vicente et al.) [2008]	6.7	-
Duchenne et al. (Segmentation by Transduction) [2008]	5.4	2s – 3mins (C++)
Price et al. (Geodesic Graph Cut) [2010]	4.8	0.2s – 2.6s (C++)



Experimental Results



Trimap



Li et al. [2004]



Duchenne et al. [2008]



Grady [2008]



Couprie et al. [2009]



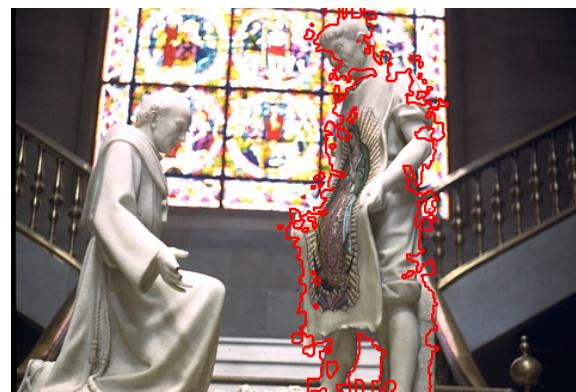
Proposed Method



Experimental Results



Trimap



Li et al. [2004]



Duchenne et al. [2008]



Couprie et al. [2009]



Grady [2006]



Proposed Method



Experimental Results



Trimap



Li et al. [2004]



Duchenne et al. [2008]



Couprie et al. [2009]



Grady [2006]



Proposed Method



Experimental Results



Trimap



Li et al. [2004]



Duchenne et al. [2008]



Couprie et al. [2009]



Grady [2006]



Proposed Method

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Experimental Results



Proposed
Method

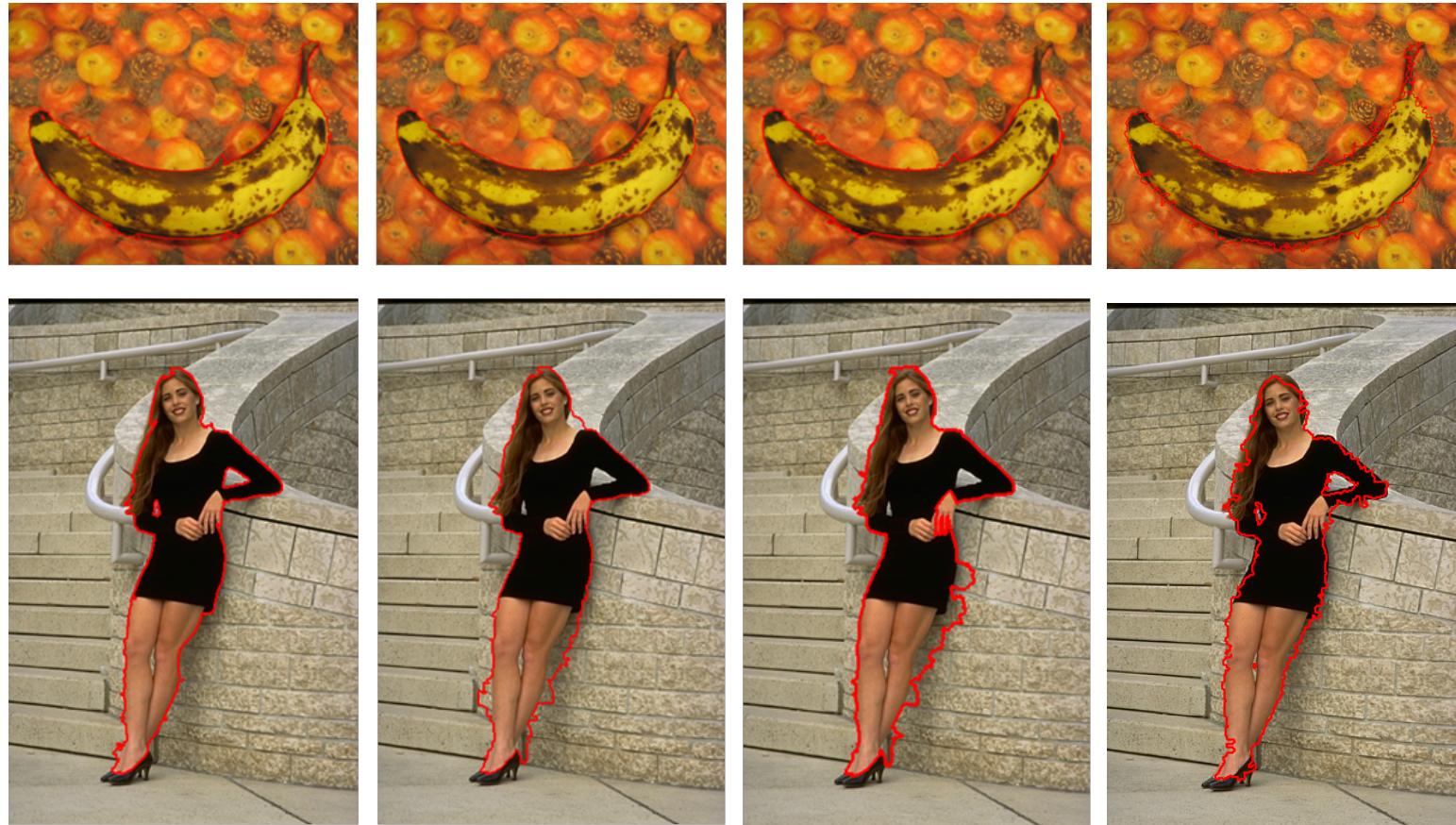
Grady [2008]

Couprie et al. [2009]

Li et al. [2004]



Experimental Results



Proposed
Method

Grady [2008]

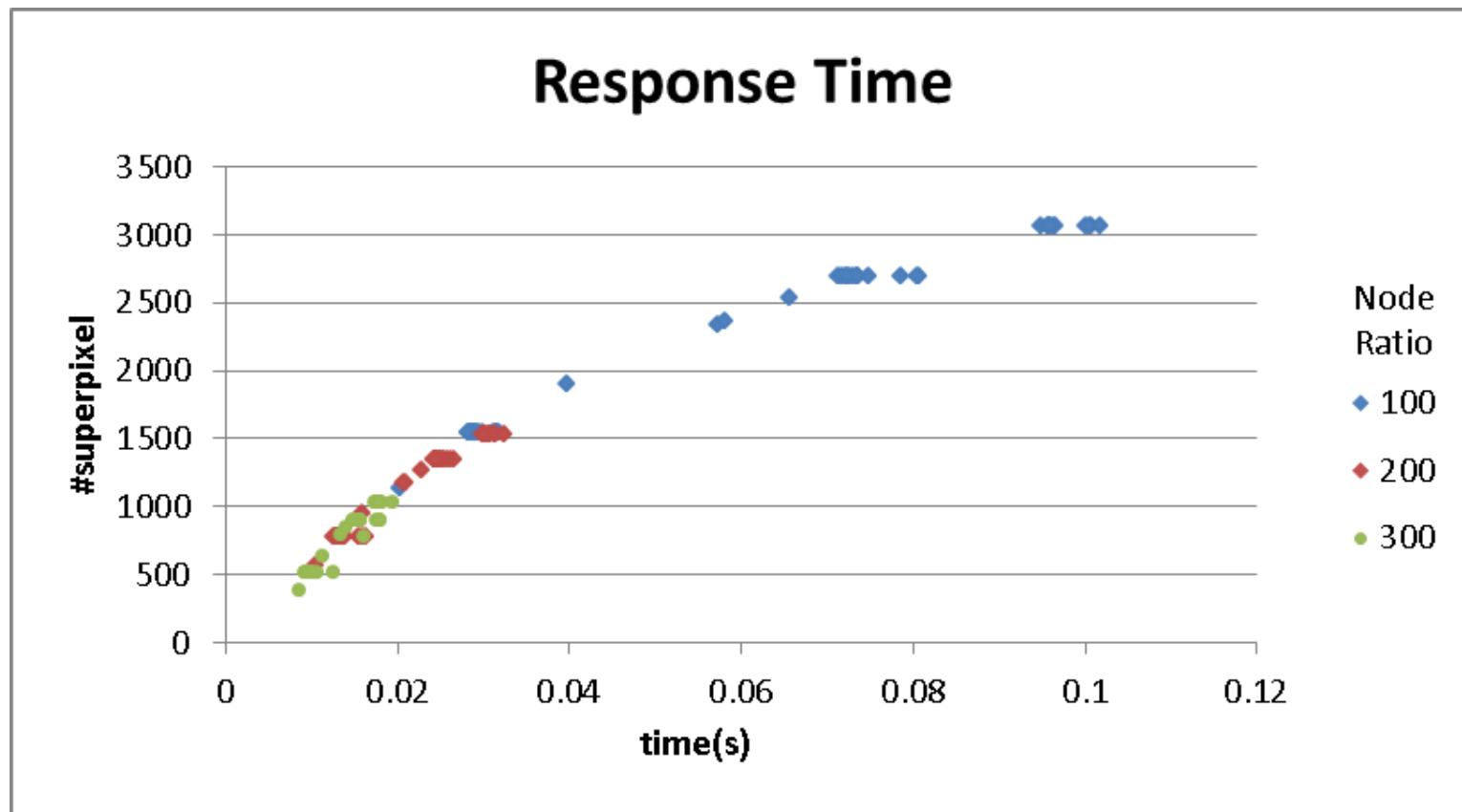
Couprie et al. [2009]

Li et al. [2004]



Discussion

■ Processing Time

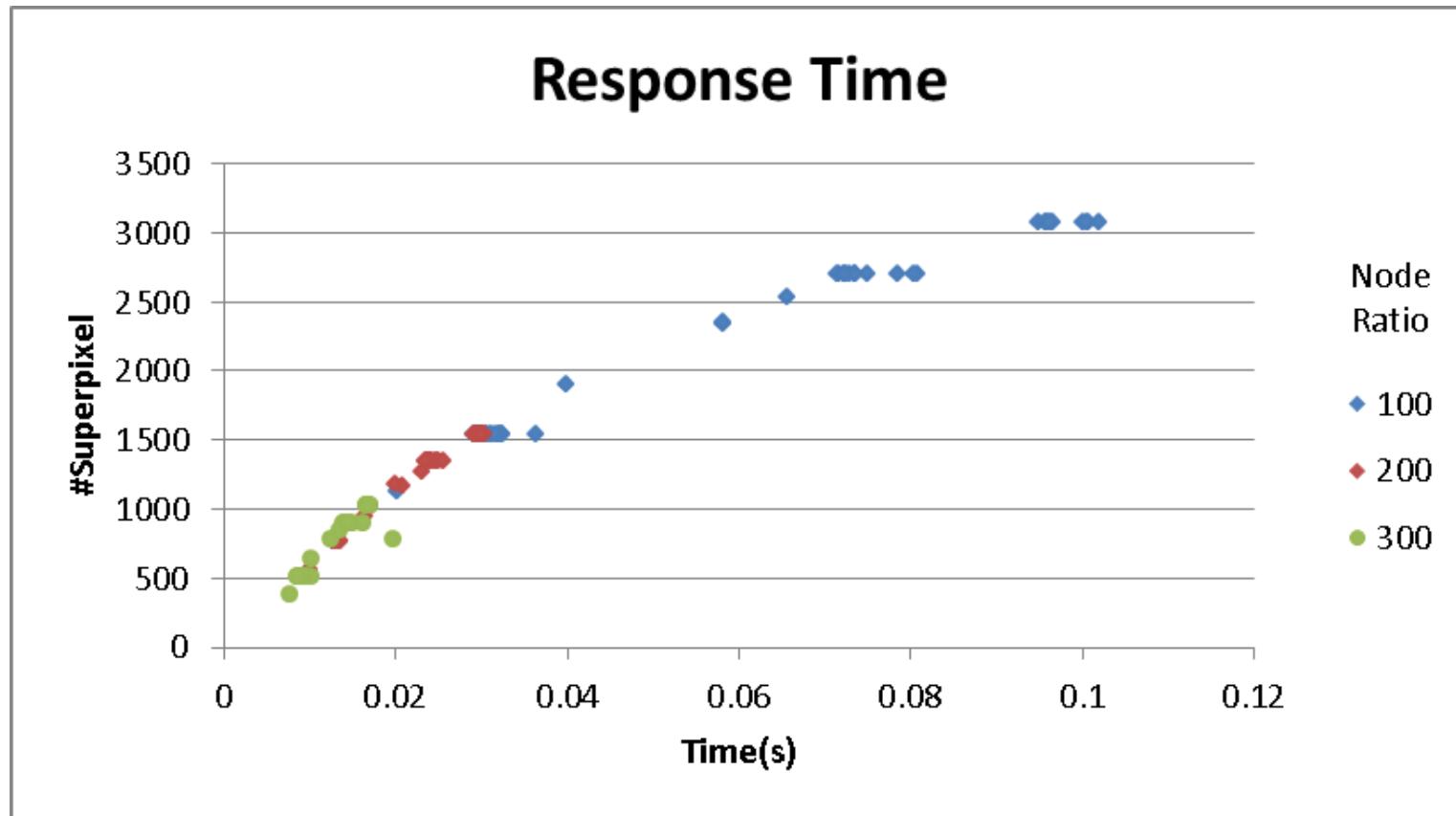


with ERS pre-segmentation



Discussion

■ Processing Time



with SLICO pre-segmentation



Discussion

■ Processing Time

■ Pre-processing time (in seconds)

Process	Node Ratio	100	200	300
SLICO	Pre-segmentation	0.291	0.375	0.457
	Computing Features	1.249	1.043	0.856
	Preprocessing	1.540	1.418	1.313
ERS	Pre-segmentation	1.392	1.414	1.512
	Computing Features	1.117	0.817	0.717
	Preprocessing	2.509	2.231	1.289



Discussion

■ Achievable Segmentation Error (ASE)

Algorithm	Node Ratio	100	200	300
EBS	ASE	4.9387	6.0141	6.6641
	Proposed Method	7.7543	8.1311	8.3464
SLICO	ASE	6.0416	6.8367	7.8556
	Proposed Method	8.4763	9.1628	9.9610



Discussion

■ Graph Cut Segmentation Issues Revisited

■ Shrinking Bias



Proposed
Method



Trimap



Grady [2008]



Couprie et al. [2009]



Discussion

■ Graph Cut Segmentation Issues Revisited

■ Vulnerability to Noise

	Original	Add Gaussian noise with mean=0, variance = 0.001	Add Gaussian noise with mean=0, variance = 0. 01
Proposed Method	7.7	7.9	8.6
Grady	10.9	11.3	12.3
Couprise et al.	10.4	11.5	12.5

■ Efficiency



Conclusion

- We propose a framework that could further shorten interactive segmentation response time while maintaining satisfying quality.
- We propose using superpixel methods with better segmentation quality such as SLICO or ERS instead of watershed.
- We propose a region term for max-flow/min-cut optimization which uses the Log-Gabor texture feature to stabilize the quality of segmentation.

Future Work

- Efficiency:
 - Improve our implementation
- Solve Shrinking Bias Issue:
 - Adaptively adjust weight between regional and boundary term
 - Combine other interactive segmentation theory such as geodesic segmentation

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Thank You

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