

Basic-10

BASIC to IC10 MIPS Compiler
for Stationeers

User Manual & Language Reference

Version 1.9.1

December 2025

Table of Contents

- 1. Introduction
- 2. Getting Started
- 3. Language Reference
 - 3.1 Variables & Constants
 - 3.2 Operators
 - 3.3 Control Flow
 - 3.4 Loops
 - 3.5 Subroutines
- 4. Device Operations
- 5. Built-in Functions
- 6. IC10 MIPS Reference
- 7. Example Programs
- 8. Tips & Best Practices
- Appendix A: Device Properties
- Appendix B: Color Constants

1. Introduction

What is Basic-10?

Basic-10 is a BASIC to IC10 compiler designed for the game Stationeers. It allows you to write programs in a beginner-friendly BASIC dialect, which are then compiled to IC10 MIPS assembly code that runs on the game's programmable Integrated Circuit (IC) chips.

Why Use Basic-10?

- Write readable, maintainable code instead of low-level assembly
- Automatic register allocation - no manual register management
- Built-in functions for math, timing, and device operations
- Real-time syntax checking and error highlighting
- Integrated simulator for testing without the game
- One-click deployment to Stationeers scripts folder

IC10

IC10 is the assembly language used by Integrated Circuits in Stationeers. Each IC chip has:

- 16 general-purpose registers (r0-r15)
- 6 device connection pins (d0-d5)
- A 512-value stack for temporary storage
- A maximum of 128 lines of code

Basic-10 handles all the complexity of register allocation and generates optimized IC10 code that fits within these constraints.

2. Getting Started

Your First Program

Here is a simple program that blinks a light on and off:

```
# My first IC10 program - Blink a light
ALIAS light d0      # Connect a light to pin d0

main:
    light.On = 1    # Turn light on
    SLEEP 1         # Wait 1 second
    light.On = 0    # Turn light off
    SLEEP 1         # Wait 1 second
    GOTO main       # Repeat forever
END
```

Understanding the Code

- Lines starting with # are comments (ignored by compiler)
- ALIAS creates a friendly name for device pins (d0-d5)
- main: is a label - a named location in your code
- SLEEP pauses execution for the specified seconds
- GOTO jumps to a label
- END marks the end of your program

The

Almost every IC10 program uses a main loop that runs continuously. This is essential because IC chips need to constantly monitor sensors and update device states.

```
main:
    # Read sensors and make decisions
    VAR temp = sensor.Temperature
    IF temp > 300 THEN
        heater.On = 0
    ENDIF

    YIELD          # IMPORTANT: Let game process
    GOTO main      # Loop back
END
```

IMPORTANT: Always include YIELD or SLEEP in your loops! Without it, your program will freeze the game due to infinite loop detection.

Connecting Devices

IC chips have 6 device pins (d0-d5). Connect devices in-game using cables, then reference them in your code with ALIAS:

```
ALIAS sensor d0      # Gas sensor on pin 0
ALIAS heater d1      # Wall heater on pin 1
```

```
ALIAS display d2      # LED display on pin 2

# Now use the friendly names
VAR temp = sensor.Temperature
heater.On = 1
display.Setting = 42
```

3. Language Reference

3.1 Variables & Constants

Variable Declaration

```
VAR temperature = 0      # Declare with initial value
VAR count               # Declare (defaults to 0)
LET x = 5               # Alternative syntax
x = 42                  # Reassign value
```

Constants

```
CONST MAX_TEMP = 373.15  # Named constant (cannot change)
DEFINE TARGET_PRESSURE 101 # IC10-style define (no = sign)
```

Arrays

```
DIM values(10)           # Declare array of 10 elements
values(0) = 100          # Set first element
VAR x = values(0)        # Read element
```

3.2 Operators

Arithmetic Operators

Operator	Description	Example	IC10
<code>a + b</code>	Addition	<code>x = 5 + 3</code>	add
<code>a - b</code>	Subtraction	<code>x = 10 - 4</code>	sub
<code>a * b</code>	Multiplication	<code>x = 3 * 4</code>	mul
<code>a / b</code>	Division	<code>x = 10 / 2</code>	div
<code>a MOD b</code>	Modulo	<code>x = 10 MOD 3</code>	mod
<code>a ^ b</code>	Power	<code>x = 2 ^ 3</code>	exp+log
<code>-a</code>	Negation	<code>x = -value</code>	sub

Compound Assignment Operators (v1.9.0)

Operator	Equivalent	Description	IC10
<code>x += n</code>	<code>x = x + n</code>	Add and assign	add
<code>x -= n</code>	<code>x = x - n</code>	Subtract and assign	sub
<code>x *= n</code>	<code>x = x * n</code>	Multiply and assign	mul
<code>x /= n</code>	<code>x = x / n</code>	Divide and assign	div

Increment/Decrement Operators (v1.9.0)

Operator	Description	Example
<code>++x</code>	Prefix increment (returns new)	<code>y = ++x # x=11, y=11</code>
<code>x++</code>	Postfix increment (returns old)	<code>y = x++ # x=11, y=10</code>
<code>--x</code>	Prefix decrement (returns new)	<code>y = --x # x=9, y=9</code>
<code>x--</code>	Postfix decrement (returns old)	<code>y = x-- # x=9, y=10</code>

Comparison Operators

Operator	Description	Example
<code>=</code> or <code>==</code>	Equal to	<code>IF x = 5 THEN</code>
<code><></code> or <code>!=</code>	Not equal to	<code>IF x <> 0 THEN</code>
<code><</code>	Less than	<code>IF temp < 300 THEN</code>
<code>></code>	Greater than	<code>IF pressure > 100 THEN</code>
<code><=</code>	Less than or equal	<code>IF charge <= 0.2 THEN</code>
<code>>=</code>	Greater than or equal	<code>IF ratio >= 0.21 THEN</code>

Logical Operators

Operator	Description	Example
<code>a AND b</code>	Logical AND	<code>IF a > 0 AND b > 0</code>
<code>a OR b</code>	Logical OR	<code>IF error OR warning</code>
<code>NOT a</code>	Logical NOT	<code>IF NOT active THEN</code>

Bitwise Operators

Operator	Description	IC10
a & b or BAND(a,b)	Bitwise AND	and
a b or BOR(a,b)	Bitwise OR	or
a ^ b or BXOR(a,b)	Bitwise XOR	xor
~a or BNOT(a)	Bitwise NOT	nor
a << n or SHL(a,n)	Shift left	sll
a >> n or SHR(a,n)	Shift right	srl

Bit shift example:

```
VAR a = 1
VAR b = a << 4    # b = 16 (shift left 4 bits)
VAR c = 16 >> 2    # c = 4 (shift right 2 bits)
VAR d = 5 ^ 3      # d = 6 (XOR: 101 ^ 011 = 110)
```

3.3 Control Flow

IF...THEN...ELSE...ENDIF

```
IF temperature > 300 THEN
    heater.On = 0
ELSEIF temperature < 290 THEN
    heater.On = 1
ELSE
    # Temperature is acceptable
ENDIF
```

SELECT CASE

```
SELECT CASE mode
    CASE 0
        # Handle mode 0
    CASE 1
        # Handle mode 1
    DEFAULT
        # Default handling
END SELECT
```

Labels and GOTO

```
main:
    # Main program code
    YIELD
    GOTO main      # Jump back to main

errorHandler:
    # Handle errors
    GOTO main
```


3.4 Loops

WHILE...WEND

```
WHILE temperature > 300
    heater.On = 0
    YIELD
WEND
```

FOR...NEXT

```
FOR i = 1 TO 10
    display.Setting = i
    YIELD
NEXT i

FOR j = 10 TO 0 STEP -1
    # Countdown
NEXT j
```

DO...LOOP

```
DO
    pump.On = 1
    YIELD
LOOP UNTIL pressure > 100
```

Loop Control: BREAK and CONTINUE

```
# BREAK - exit loop immediately
WHILE 1
    IF done THEN BREAK
    YIELD
WEND

# CONTINUE - skip to next iteration
FOR i = 1 TO 10
    IF i MOD 2 = 0 THEN CONTINUE
    # Only processes odd numbers
NEXT i
```

3.5 Subroutines

GOSUB and RETURN

```
main:
    GOSUB ReadSensors
    GOSUB UpdateOutputs
    YIELD
    GOTO main

ReadSensors:
    temp = sensor.Temperature
```

```
    pressure = sensor.Pressure  
    RETURN
```

```
UpdateOutputs:  
    display.Setting = temp  
    RETURN
```

SUB and FUNCTION

```
SUB UpdateDisplay  
    display.Setting = temp  
END SUB  
  
FUNCTION Clamp(val, minVal, maxVal)  
    IF val < minVal THEN RETURN minVal  
    IF val > maxVal THEN RETURN maxVal  
    RETURN val  
END FUNCTION  
  
# Usage  
CALL UpdateDisplay  
VAR safe = Clamp(input, 0, 100)
```

4. Device Operations

Device Pins

Each IC chip has 6 device pins (d0-d5) plus a self-reference (db). Use ALIAS to give devices friendly names:

```
ALIAS sensor d0      # Device on pin 0
ALIAS pump d1        # Device on pin 1
ALIAS chip THIS      # The IC chip itself (db)
```

Reading Device Properties

```
VAR temp = sensor.Temperature
VAR pressure = sensor.Pressure
VAR isOn = heater.On
VAR charge = battery.Charge
```

Writing Device Properties

```
heater.On = 1          # Turn on
pump.Setting = 100     # Set target
display.Setting = temp # Show value
door.Open = 0          # Close door
```

Slot Operations

Many devices have slots (inventories) you can access:

```
VAR hash = device.Slot(0).OccupantHash
VAR qty = device.Slot(0).Quantity
VAR occupied = device.Slot(0).Occupied
```

Named Device References

Bypass the 6-pin limit by referencing devices by their prefab name. This uses batch operations to find devices on the network:

```
DEVICE sensor "StructureGasSensor"
DEVICE furnace "StructureFurnace"

# Use like regular aliases
VAR temp = sensor.Temperature
furnace.On = 1
```

Batch Operations

Read from or write to ALL devices of a type at once:

```
DEFINE SENSOR_HASH -1234567890

# Batch read modes: 0=Average, 1=Sum, 2=Min, 3=Max
VAR avgTemp = BATCHREAD(SENSOR_HASH, Temperature, 0)
```

```
VAR totalPower = BATCHREAD(BATTERY_HASH, PowerGeneration, 1)

# Write to all devices
BATCHWRITE(LIGHT_HASH, On, 1) # Turn on all lights
```

5. Built-in Functions

Math Functions

Function	Description	Example
ABS(x)	Absolute value	ABS(-5) = 5
SQRT(x)	Square root	SQRT(16) = 4
MIN(a,b)	Minimum value	MIN(5, 3) = 3
MAX(a,b)	Maximum value	MAX(5, 3) = 5
CEIL(x)	Round up	CEIL(3.2) = 4
FLOOR(x)	Round down	FLOOR(3.8) = 3
ROUND(x)	Round nearest	ROUND(3.5) = 4
TRUNC(x)	Truncate	TRUNC(3.9) = 3
SGN(x)	Sign (-1,0,1)	SGN(-5) = -1
RND()	Random 0-1	RND() = 0.xxx

Trigonometry (angles in radians)

Function	Description	Example
SIN(x)	Sine	SIN(0) = 0
COS(x)	Cosine	COS(0) = 1
TAN(x)	Tangent	TAN(0) = 0
ASIN(x)	Arc sine	ASIN(1) = 1.57
ACOS(x)	Arc cosine	ACOS(0) = 1.57
ATAN(x)	Arc tangent	ATAN(1) = 0.785
ATAN2(y,x)	2-arg arctangent	ATAN2(1, 1) = 0.785

Exponential & Logarithmic

Function	Description	Example
EXP(x)	e raised to x	EXP(1) = 2.718
LOG(x)	Natural logarithm	LOG(2.718) = 1

Control Functions

Function	Description	Example
YIELD	Pause 1 game tick	YIELD
SLEEP n	Pause n seconds	SLEEP 0.5
WAIT(n)	Same as SLEEP	WAIT(1)
END	Stop execution	IF error THEN END

Stack Operations

PUSH value	# Push to stack
POP variable	# Pop from stack
PEEK variable	# Read top without removing

6. IC10 MIPS Reference

This reference shows the IC10 assembly instructions that your BASIC code compiles to. Understanding these helps with debugging and optimization.

Registers

- r0-r15: General purpose registers (16 total)
- sp: Stack pointer
- ra: Return address (for subroutines)
- d0-d5: Device references
- db: IC housing device (self)

Mat

Instruction	Meaning	Description
add r0 r1 r2	$r0 = r1 + r2$	Addition
sub r0 r1 r2	$r0 = r1 - r2$	Subtraction
mul r0 r1 r2	$r0 = r1 * r2$	Multiplication
div r0 r1 r2	$r0 = r1 / r2$	Division
mod r0 r1 r2	$r0 = r1 \% r2$	Modulo
sqrt r0 r1	$r0 = \text{sqrt}(r1)$	Square root
abs r0 r1	$r0 = r1 $	Absolute value
round r0 r1	$r0 = \text{round}(r1)$	Round
floor r0 r1	$r0 = \text{floor}(r1)$	Round down
ceil r0 r1	$r0 = \text{ceil}(r1)$	Round up
min r0 r1 r2	$r0 = \text{min}(r1, r2)$	Minimum
max r0 r1 r2	$r0 = \text{max}(r1, r2)$	Maximum

Logic & Bitwise

Instruction	Meaning	Description
and r0 r1 r2	$r0 = r1 \& r2$	Bitwise AND
or r0 r1 r2	$r0 = r1 r2$	Bitwise OR
xor r0 r1 r2	$r0 = r1 \wedge r2$	Bitwise XOR
nor r0 r1 r2	$r0 = \sim(r1 r2)$	NOR
sll r0 r1 r2	$r0 = r1 \ll r2$	Shift left
srl r0 r1 r2	$r0 = r1 \gg r2$	Shift right
sra r0 r1 r2	$r0 = r1 \ggg r2$	Arithmetic shift

Comparison (Set Instructions)

Instruction	Meaning	Description
slt r0 r1 r2	$r0 = (r1 < r2)$	Set if less than
sgt r0 r1 r2	$r0 = (r1 > r2)$	Set if greater
sle r0 r1 r2	$r0 = (r1 \leq r2)$	Set if less/equal
sge r0 r1 r2	$r0 = (r1 \geq r2)$	Set if greater/equal
seq r0 r1 r2	$r0 = (r1 == r2)$	Set if equal
sne r0 r1 r2	$r0 = (r1 != r2)$	Set if not equal
seqz r0 r1	$r0 = (r1 == 0)$	Set if zero
snez r0 r1	$r0 = (r1 != 0)$	Set if not zero

Branching & Jumps

Instruction	Meaning	Description
j label	goto label	Unconditional jump
jal label	call label	Jump and link
jr r0	goto r0	Jump to register
beq r0 r1 lbl	if $r0 == r1$ goto	Branch if equal
bne r0 r1 lbl	if $r0 != r1$ goto	Branch if not equal
blt r0 r1 lbl	if $r0 < r1$ goto	Branch if less
bgt r0 r1 lbl	if $r0 > r1$ goto	Branch if greater
beqz r0 lbl	if $r0 == 0$ goto	Branch if zero
bnez r0 lbl	if $r0 != 0$ goto	Branch if not zero

Device Operations

Instruction	Meaning	Description
l r0 d0 Prop	$r0 = d0.Prop$	Load from device
s d0 Prop r0	$d0.Prop = r0$	Store to device
ls r0 d0 s Prop	$r0 = d0.Slot(s).P$	Load slot prop
lb r0 h Prop m	batch read	Load batch
sb h Prop r0	batch write	Store batch

Special Instructions

Instruction	Meaning	Description
move r0 r1	$r0 = r1$	Copy value
yield	pause 1 tick	Yield execution
sleep r0	pause r0 sec	Sleep for time
push r0	$stack.push(r0)$	Push to stack
pop r0	$r0 = stack.pop()$	Pop from stack
hcf	halt	Halt and catch fire

7. Example Programs

Thermostat with Hysteresis

Maintains temperature with dead-band to prevent rapid cycling:

```
ALIAS sensor d0
ALIAS heater d1

CONST TARGET = 293      # 20C in Kelvin
CONST TOLERANCE = 2

main:
    VAR temp = sensor.Temperature

    IF temp < TARGET - TOLERANCE THEN
        heater.On = 1
    ELSEIF temp > TARGET + TOLERANCE THEN
        heater.On = 0
    ENDIF

    YIELD
    GOTO main

END
```

Solar Panel Tracker

Automatically positions solar panels to track the sun:

```
ALIAS panel d0

main:
    VAR angle = panel.SolarAngle
    panel.Horizontal = angle
    panel.Vertical = 60

    YIELD
    GOTO main

END
```

Battery Monitor with Backup

Activates generator when battery is low:

```
ALIAS battery d0
ALIAS generator d1
ALIAS display d2

CONST LOW = 0.20
CONST HIGH = 0.90
```

```
main:
    VAR charge = battery.Charge

    IF charge < LOW THEN
        generator.On = 1
    ELSEIF charge > HIGH THEN
        generator.On = 0
    ENDIF

    display.Setting = charge * 100
    YIELD
    GOTO main
END
```

Counter with Compound Assignment

Demonstrates v1.9.0 compound operators:

```
ALIAS display d0
ALIAS button d1

VAR count = 0
VAR lastBtn = 0

main:
    VAR btn = button.Setting

    IF btn = 1 AND lastBtn = 0 THEN
        count += 1    # Compound assignment
    ENDIF

    lastBtn = btn
    display.Setting = count

    YIELD
    GOTO main

END
```

Bit Flags for Status Display

Uses bit shifts for compact status:

```
ALIAS sensor d0
ALIAS display d1

VAR status = 0

main:
    status = 0

    IF sensor.Power > 0 THEN
        status = status | (1 << 0)
    ENDIF
    IF sensor.Temperature > 250 THEN
        status = status | (1 << 1)
    ENDIF
    IF sensor.Pressure > 80 THEN
        status = status | (1 << 2)
    ENDIF

    display.Setting = status
    YIELD
    GOTO main

END
```

8. Tips & Best Practices

Always Use YIELD

Every loop must contain YIELD or SLEEP. Without it, the game will detect an infinite loop and halt your program.

```
# BAD - will crash
WHILE 1
    # no yield!
WEND

# GOOD
WHILE 1
    YIELD
WEND
```

Cache Device Reads

Each device read takes time. Read once and reuse:

```
# BAD - reads 3 times
IF sensor.Temperature > 100 THEN
ELSEIF sensor.Temperature > 50 THEN
ENDIF

# GOOD - reads once
VAR temp = sensor.Temperature
IF temp > 100 THEN
ELSEIF temp > 50 THEN
ENDIF
```

Use Hysteresis

Prevent rapid on/off switching by adding a dead-band around your target value:

```
CONST TARGET = 100
CONST TOLERANCE = 5

IF value < TARGET - TOLERANCE THEN
    device.On = 1
ELSEIF value > TARGET + TOLERANCE THEN
    device.On = 0
ENDIF
```

Use Constants for Magic Numbers

```
# BAD
IF temp > 373.15 THEN

# GOOD
CONST BOILING_POINT = 373.15
```

```
IF temp > BOILING_POINT THEN
```

Bit Shifts for Efficiency

Use bit shifts for power-of-2 multiplication/division:

```
x = x << 1    # Same as x * 2
x = x >> 2    # Same as x / 4

# Set/clear/check flags
flags = flags | (1 << n)    # Set bit n
flags = flags & ~(1 << n)   # Clear bit n
isSet = (flags >> n) & 1    # Check bit n
```

Appendix A: Common Device Properties

Universal Properties

Property	Type	R/W	Description
On	0/1	R/W	Power state
Setting	Number	R/W	Target/display value
Mode	Integer	R/W	Operating mode
Lock	0/1	R/W	Lock state
Error	0/1	R	Error state
Power	Watts	R	Power consumption
PrefabHash	Integer	R	Device type hash

Atmosphere Properties

Property	Type	R/W	Description
Temperature	Kelvin	R	Gas temperature
Pressure	kPa	R	Total pressure
RatioOxygen	0-1	R	O2 ratio
RatioCarbonDioxide	0-1	R	CO2 ratio
RatioNitrogen	0-1	R	N2 ratio
RatioVolatiles	0-1	R	H2 ratio
RatioWater	0-1	R	Steam ratio
TotalMoles	Moles	R	Total gas quantity

Power Properties

Property	Type	R/W	Description
Charge	0-1	R	Battery charge ratio
PowerGeneration	Watts	R	Power output
PowerRequired	Watts	R	Power demand
SolarAngle	Degrees	R	Sun angle
Horizontal	Degrees	R/W	Panel horizontal
Vertical	Degrees	R/W	Panel vertical

Appendix B: Color Constants

Built-in color constants for lights and displays:

Name	Value	RGB Hex	Usage
Blue	0	#0000FF	light.Color = Blue
Gray	1	#808080	light.Color = Gray
Green	2	#00FF00	light.Color = Green
Orange	3	#FFA500	light.Color = Orange
Red	4	#FF0000	light.Color = Red
Yellow	5	#FFFF00	light.Color = Yellow
White	6	#FFFFFF	light.Color = White
Black	7	#000000	light.Color = Black
Brown	8	#8B4513	light.Color = Brown
Khaki	9	#F0E68C	light.Color = Khaki
Pink	10	#FFC0CB	light.Color = Pink
Purple	11	#800080	light.Color = Purple

Custom RGB Colors

For custom colors, use decimal RGB values:

```
# RGB to decimal: R*65536 + G*256 + B
DEFINE RED 16711680      # FF0000
DEFINE GREEN 65280       # 00FF00
DEFINE BLUE 255          # 0000FF
DEFINE YELLOW 16776960   # FFFF00
DEFINE CYAN 65535        # 00FFFF
DEFINE MAGENTA 16711935  # FF00FF
DEFINE WHITE 16777215    # FFFFFFFF

light.Color = RED
```

Slot Type Constants

For slot operations:

Name	Value	Description
Import	0	Input slot (also: Input)
Export	1	Output slot (also: Output)
Content	2	Content/storage slot
Fuel	3	Fuel slot